1. Gaussian elimination = LU factorization

$$A = LU$$
.

where L is a unit lower triangular matrix and U a upper triangular matrix.

2. Not all matrices have the LU factorization. For example,

$$A = \left[\begin{array}{ccc} 0 & 1 & 0 \\ 0 & 2 & 1 \\ 2 & 3 & 1 \end{array} \right] \neq LU.$$

3. A permutation matrix P is an identity matrix with permuted rows.

Let P, P_1, P_2 be $n \times n$ permutation matrices, and X be an $n \times n$ matrix. Then

- $P^TP = I$, i.e., $P^{-1} = P^T$.
- $\det(P) = \pm 1$.
- P_1P_2 is also a permutation matrix.
- PX is the same as X with its rows permuted.
- XP is the same as X with its columns permuted.
- P_1XP_2 reorders both rows and columns of X.
- 4. The need of pivoting, mathematically

The LU factorization can fail on nonsingular matrices, see the above example. But by exchanging the first and third rows, we get

$$PA = \begin{bmatrix} 2 & 3 & 1 \\ 0 & 2 & 1 \\ 0 & 1 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & \frac{1}{2} & 1 \end{bmatrix} \begin{bmatrix} 2 & 3 & 1 \\ 0 & 2 & 1 \\ 0 & 0 & -\frac{1}{2} \end{bmatrix} := LU.$$

5. The above simple observation is the basis for LU factorization with pivoting.

Theorem. If A is nonsingular, then there exist permutations P, a unit lower triangular matrix L, and a nonsingular upper triangular matrix U such that

$$PA = LU$$
.

- 6. Function lutx.m
- 7. Solving Ax = b using the LU factorization
 - 1. Factorize A into PA = LU
 - 2. Permute the entries of b: b := Pb.
 - 3. Solve L(Ux) = b for Ux by forward substitution: $Ux = L^{-1}b$.
 - 4. Solve $Ux = L^{-1}b$ for x by back substitution: $x = U^{-1}(L^{-1}b)$.

- 8. Function bslashx0.m
- 9. The need for pivoting, numerically

Let us apply LU factorization without pivoting to

$$A = \begin{bmatrix} .0001 & 1 \\ 1 & 1 \end{bmatrix} = \begin{bmatrix} 10^{-4} & 1 \\ 1 & 1 \end{bmatrix} = LU = \begin{bmatrix} 1 \\ l_{21} & 1 \end{bmatrix} \begin{bmatrix} u_{11} & u_{12} \\ & u_{22} \end{bmatrix}$$

in three decimal-digit floating point arithmetic. We obtain

$$L = \begin{bmatrix} 1 & 0 \\ fl(1/10^{-4}) & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 10^4 & 1 \end{bmatrix},$$

$$U = \begin{bmatrix} 10^{-4} & 1 \\ fl(1-10^4 \cdot 1) \end{bmatrix} = \begin{bmatrix} 10^{-4} & 1 \\ & -10^4 \end{bmatrix},$$

so

$$LU = \begin{bmatrix} 1 & 0 \\ 10^4 & 1 \end{bmatrix} \begin{bmatrix} 10^{-4} & 1 \\ & -10^4 \end{bmatrix} = \begin{bmatrix} 10^{-4} & 1 \\ 1 & 0 \end{bmatrix} \not\approx A,$$

where the original a_{22} has been entirely "lost" from the computation by subtracting 10^4 from it. In fact, we would have gotten the same LU factors whether a_{22} had been 1, 0, -2, or any number such that $fl(a_{22} - 10^4) = -10^4$. Since the algorithm proceeds to work only with L and U, it will get the same answer for all these different a_{22} , which correspond to completely different A and so completely different $x = A^{-1}b$; there is no way to guarantee an accurate answer. This is called numerical instability. L and U are not the exact factors of a matrix close to A.

Let us see what happens when we go on to solve $Ax = [1,2]^T$ for x using this LU factorization. The correct answer is $x \approx [1,1]^T$. Instead we get the following. Solving

$$Ly = \begin{bmatrix} 1 \\ 2 \end{bmatrix} \Rightarrow y_1 = \text{fl}(1/1) = 1 \text{ and } y_2 = \text{fl}(2 - 10^4 \cdot 1) = -10^4.$$

Note that the value 2 has been "lost" by subtracting 10^4 from it. Solving

$$Ux = y = \begin{bmatrix} 1 \\ -10^4 \end{bmatrix} \Rightarrow \hat{x}_2 = \text{fl}((-10^4)/(-10^4)) = 1 \text{ and } \hat{x}_1 = \text{fl}((1-1)/10^{-4}) = 0,$$

a completely erroneous solution.

On the other hand, the LU factorization with partial pivoting would have reversed the order of the two equations before proceeding. You can confirm that we get

$$PA = LU$$
,

where

$$P = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}, L = \begin{bmatrix} 1 & 0 \\ \text{fl}(.0001/1) & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ .0001 & 1 \end{bmatrix},$$

and

$$U = \begin{bmatrix} 1 & 1 \\ & \text{fl}(1 - .0001 \cdot 1) \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ & 1 \end{bmatrix}.$$

The computed LU approximates A very accurately. As a result, the computed solution x is also perfect!