Embedded reconfiguration of TSN: Dual reconfiguration with dropping and reclaiming

Álex Gracia, Alitzel G. Torres-Macías, Juan Segarra, José L. Briz. Antonio Ramírez-Treviño, Héctor Blanco-Alcaine







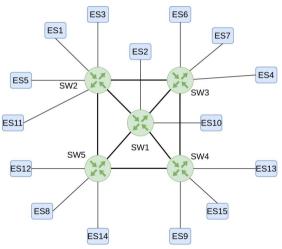
37th Euromicro Conference on Real-Time Systems **Brussels, July 8-11, 2025**



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1 Introduction



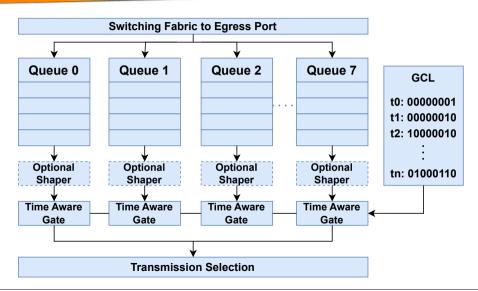
Challenge:

- > 241 mixed criticality streams
- 8 potentially failing links
- Reroute and reschedule upon link failures
 - NP-complete problem

Tested solution:

- Mixed Integer Linear Programming models for scheduling
- Incremental + global reconfiguration
- Time Aware Shaper for all streams

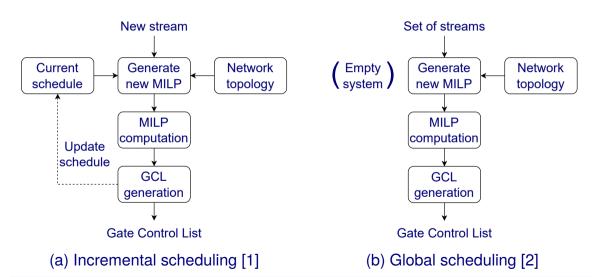
1.1 Time Aware Shaper



2 Proposed procedure

- 1. Detect faulty link
- 2. Get ordered sublist of disposable (affected) schedules and purge them
 - > DROP policy until reschedule
- 3. Incremental stage: schedule and deploy stream-by-stream
 - Schedule streams one-by-one on an existing schedule
 - Faster, one-by-one optimal (no heuristics)
 - [1] A. Galilea Torres-Macías et al. Optimal and Fast IEEE802.1Qbv Incremental Scheduling. Submitted to Computer Networks.
- 4. Global stage, if needed (not needed for the use case)
 - Schedule several streams together on an empty system
 - > Slower, better schedulability, globaly optimized, with heuristics
 - [2] A. Galilea Torres-Macías et al. Fast IEEE802.1Qbv gate scheduling through integer linear programming. IEEE Access, 12:111239–111250, 2024.

2.1 Scheduling by MILP models



2.2 Incremental stage

Process streams one by one:

- 1: **for all** stream in disposableStreamList **do**
- 2: $pathList \leftarrow Get ordered list of possible paths to reschedule <math>stream$
- 3: **for all** path in pathList, shortest first **do** // Single iteration suffices!
- 4: Generate MILP model [1] to schedule *stream* on *path*
- 5: Solve model
- 6: **if** schedulable **then**
- 7: Deploy schedule for *stream*
- 8: Exit loop on pathList

2.3 Global stage

Process set of streams together; maximize its size with binary search:

- 1: while not satisfied with the schedule do
- 2: Generate MILP model [2] to schedule a *set of streams* (shortest paths)
- 3: Solve model
- 4: **if** schedulable **then**
- 5: Purge system and Deploy
- 6: **if** scheduled *set of streams* contains all streams **then**
- 7: The system is optimized; exit
- 8: **else**
- 9: Add streams to the *set of streams*
- 10: **else**
- 11: Remove streams from the set of streams
- 12: **if** the *set of streams* has already been tested **then**
- 13: The system cannot be further improved; exit

3 Experiments

- Intel Xeon Gold 5120 CPU: 28 cores (56 total threads), released on 2017
- Frame isolation supported but not addressed (TC7 streams isolated)
- > 1 ms frame processing time; 0.5 ms clock skew

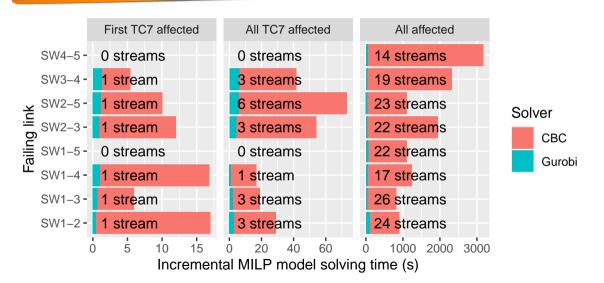
Experiment 1. Network dimmensioning (consecutive link failures)

✓ Adequate: all reschedulable with 3 failing links

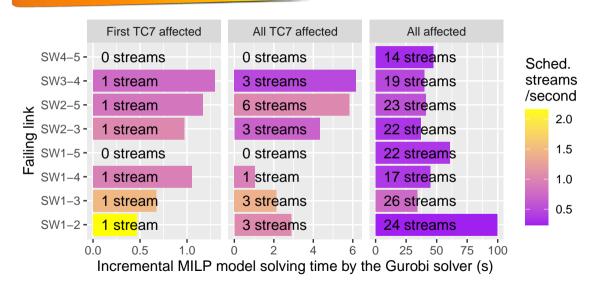
Experiment 2. Rescheduling times (single link failure)

- × Remove streams affected by link failure and lower priority working ones
 - Rescheduling working schedules is not worth
 - ✓ Reschedule streams affected by link failure only
- X Get valid schedules (not necessarily optimal)
 - Faster for the first streams, but globaly slower
 - ✓ Get optimal schedules always

3.1 Rescheduling times (single link failure)



3.1 Rescheduling times (single link failure) (II)



4 Conclusions and future work

For the considered use case:

- ➤ Recovery time (Gurobi): from 0.5 s (TC7) to 1-2 min. (all streams)
- Incremental (one-by-one) rescheduling [1] suffices
- Hints for rescheduling:
 - Rescheduling working low-criticality streams is globally slower
 - Computing optimal schedules is globaly faster than just valid ones

Work in progress:

- Speed-up solving times through heuristics
- Fault tolerance by CNC-managed frame replication
- Alternative implementations of the Gate Control List of TAS

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