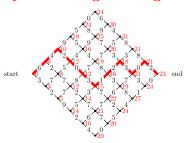
# **Algorithms and Analysis**

## Outline

## Lesson 23: Dynamic Programming



 $\label{eq:continuous} Dynamic\ programming,\ line\ breaking,\ edit\ distance,\ Dijkstra,\ TSP$ 

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### **Dynamic Programming**

- One of the most powerful strategies for solving optimisation problems is **dynamic programming**!
  - ★ Build a set of optimal partial solutions
  - ⋆ Increase the size of the partial solutions until you have a full solution
  - ★ Each step uses the set of optimal partial solutions found in the previous step!
- Developed by Richard Bellman in the early 1950's
- The name is unfortunate as it doesn't have much to do with programming!

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### **Brute Force**

- The obvious brute force strategy is to try every path
- For a problem with n steps we require n/2 to be diagonally up and n/2 to be diagonally down!
- The total number of paths is

$$\binom{n}{n/2} \approx \sqrt{\frac{2}{\pi\,n}}\,2^n {\rm I}$$

- $\bullet$  For the problem shown above with n=8 there are 70 paths!
- $\bullet$  For a problem with n=100 there are  $1.01\times 10^{29}$  paths!

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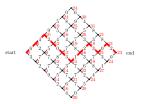
### Forward Algorithm

- ullet Suppose we know the optimal costs for all the edge in column i
- ullet Our task is to find the optimal cost at column i+1
- If we consider the sites in the lattice then the optimal cost will be

$$c_{(i+1,j)} = \min \left( c_{(i,j+1)} + w_{(i,j+1)(i+1,j)}, \ c_{(i,j-1)} + w_{(i,j-1)(i+1,j)} \right) \mathbf{I}$$

- This is the defining equation in dynamic programming
- We have to treat the boundary sites specially, but this is just book-keeping

- 1. Dynamic Programming
- 2. Applications
  - Line Breaks
  - Edit Distance
  - Dijkstra's Algorithm
- 3. Limitation

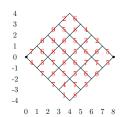


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## A Toy Problem

 Consider the problem of find a minimum cost path from point (0,0) to (8,0) on the lattice



- The costs of traversing each link is shown in red
- The cost of a path is the sum of weights on each link!

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### **Building a Solution**

- We can solve this problem efficiently using dynamic programming by considering optimal paths of shorter length
- $\bullet$  Let  $c_{(i,j)}$  denote the cost of the optimal path to node (i,j)
- $\bullet$  We denote the weights between two points on the lattice by  $w_{(i,j)(i+1,j\pm 1)}$

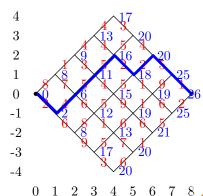


• Clearly  $c_{(0,0)} = 0$ 

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# Example



# **Backward Algorithm**

- $\bullet$  Having found the optimal costs  $c_{(i,j)}$  we can find the optimal path starting from  $(n,0) {\rm I\!I}$
- At each step we have a choice of going up or down
- We choose the direction which satisfies the constraint

$$c_{(i,j)} = c_{(i-1,j\pm 1)} + w_{(i-1,j\pm 1)(i,j)}$$

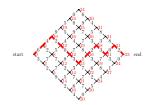
 If both directions satisfy the constraint we have more than one optimal path

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### **Using Dynamic Programming**

- The challenge is recognising that you can use dynamic programming and representing the problem right
- Learn this from examples
- Consider writing a word processor that splits paragraphs up into lines
- You want to choose the line breaks so that the lines are all roughly the same length
- This is a global optimisation task
  minimise the total number of spaces left at the end of each
  line

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### **Real Word Breaking**

- In advanced word processing you care about hyphenation, large gaps at the end of lines, etc.
- These all affect the way you would assign costs
- Dynamic programming is used in LATEX to produce nice line breaks
- A similar algorithm is used to produce nice page breaks

# **Time Complexity**

- In our dynamic programming solution we had to compute the cost  $c_{(i,j)}$  at each lattice point!
- There were  $(\frac{n+1}{2})^2$  lattice point
- It took constant time to compute each cost so the total time to perform the forward algorithm was  $\Theta(n^2)$
- ullet The time complexity of the backward algorithm was  $\Theta(n)$
- This compares with  $\exp(\Theta(n))$  for the brute force algorithm

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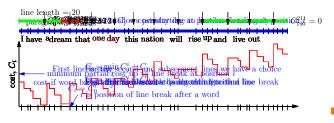
# Applications of Dynamic Programming

- Dynamic programming is used in a vast number of applications
  - ★ String matching algorithms
  - ⋆ Shape matching in images
  - ★ Dynamical time-warping in speech
  - \* Hidden Markov Models in machine learning
- Unlike greedy algorithms the idea is readily extended to many different applications

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## **Using Dynamic Programming**

• I have a dream that one day this nation will rise up and live out the. . .



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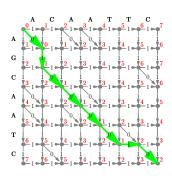
### **Inexact Matching**

- A second example of dynamic programming is to find inexact matches
- The edit distance between two strings is the number of changes needed to move from one string to another
- The exact metric depends on the application, but might include number of substitutions, insertions and deletions.
- This has many applications, e.g. in genomics to see what DNA strings (or proteins) are related

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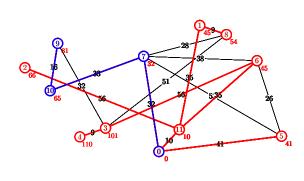
## **Edit Distance**

 What is the minimum edit distance between ACAATTC and AGCAATCI



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# Going from Node 0 to Node 9



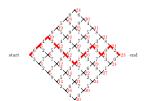
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- The use of transposition tables and refutation tables in computer chess
- The Viterbi algorithm (used for hidden Markov models)
- The Earley algorithm (a type of chart parser)
- The Needleman–Wunsch and other algorithms used in bioinformatics, including sequence alignment, structural alignment, RNA structure prediction
- Floyd's all-pairs shortest path algorithm
- Optimizing the order for chain matrix multiplication
- Pseudo-polynomial time algorithms for the subset sum and knapsack and partition problems
- The dynamic time warping algorithm for computing the global distance between two time series
- The Selinger (a.k.a. System R) algorithm for relational database query optimization
- De Boor algorithm for evaluating B-spline curves
- Duckworth–Lewis method for resolving the problem when games of cricket are interrupted

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# Outline

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# Dijkstra's Algorithm

- We saw early Dijkstra's algorithm for find the minimum distance between a source and destination node!
- We grouped this with the greedy algorithms as we choose the next node to add to the minimum-distance spanning tree to be the closest node to the source we could access!
- However, we should perhaps more rightly identify it as using a dynamic programming strategy as we are building up the cost of getting of the partial solution to reach a nodel
- We use the greedy strategy to ensure that we always find the shorter paths first

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# **Uses of Dynamic Programming**

- · Recurrent solutions to lattice models for protein-DNA binding
- Backward induction as a solution method for finite-horizon discrete-time dynamic optimization problems
- Method of undetermined coefficients can be used to solve the Bellman equation in infinite-horizon, discrete-time, discounted, time-invariant dynamic optimization problems
- Many string algorithms including longest common subsequence, longest increasing subsequence, longest common substring, Levenshtein distance (edit distance)
- Many algorithmic problems on graphs can be solved efficiently for graphs of bounded treewidth or bounded clique-width by using dynamic programming on a tree decomposition of the graph.
- The Cocke–Younger–Kasami (CYK) algorithm which determines whether and how a given string can be generated by a given context-free grammar
- Knuth's word wrapping algorithm that minimizes raggedness when word wrapping text

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- The value iteration method for solving Markov decision processes
- Some graphic image edge following selection methods such as the "magnet" selection tool in Photoshop
- Some methods for solving interval scheduling problems
- Some methods for solving word wrap problems
- Some methods for solving the travelling salesman problem, either exactly (in exponential time) or approximately (e.g. via the bitonic tour)
- Recursive least squares method
- Beat tracking in music information retrieval
- Adaptive-critic training strategy for artificial neural networks
- Stereo algorithms for solving the correspondence problem used in stereo vision
- Seam carving (content aware image resizing)
- $\bullet$  The Bellman–Ford algorithm for finding the shortest distance in a graph
- Some approximate solution methods for the linear search problem
- Kadane's algorithm for the maximum subarray problem

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#### When You Can't Use It

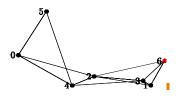
- Not all problems can be split neatly to make dynamic programming possible
- Dynamic programming works on problems with some natural ordering
- We need this to build up a list of optimum cost of partial solutions—these have to depend on the cost of previous partial solutions
- Sometime no natural ordering exists

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# **Travelling Salesman Problem**

- For TSP we can find a dynamic programming solution by considering optimal sub-tours (paths) involving sets of k cities
- If we know the optimal sub-tour through all sets of cities of size k (starting and finishing at each possible pair in the set) then we can quickly compute the optimal sub-tour between set of size k+1



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## Conclusions

- Dynamic programming is one of the most powerful strategies for solving hard optimisation problems
- It works by iteratively building up costs for partial solutions using the costs of smaller partial solutions
- When it works it is great and there are hosts of practical algorithms which use DPI
- However, it doesn't always work

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## **Travelling Salesman Problem**

- The problem is there are  $\binom{n}{k}$  subsets consisting of k cities out of a possible  $n\mathbf{l}$
- The total number of subsets that need to be considered is

$$\sum_{k=0}^{n} \binom{n}{k} = 2^{n}$$

• The time complexity of the DP solution is  $n^2\,2^n$  which is better than n! and is currently the fastest known exact algorithm for TSP, but it ain't very useful in practice!

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