Algorithms and Analysis

Lesson 11: Use Heaps!



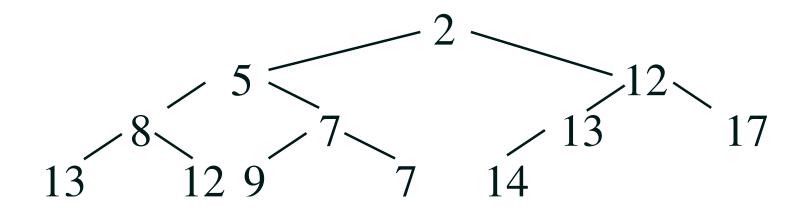
Heaps, Priority queues, Heap Sort, Other heaps

Outline

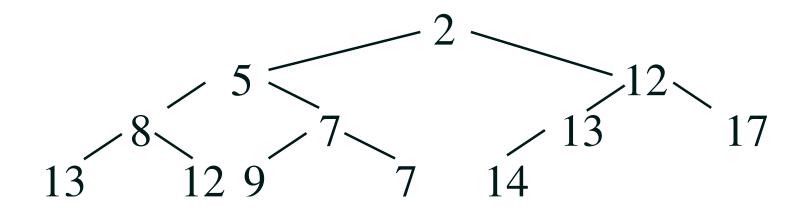
- 1. Heaps
- 2. Priority Queues
 - Array Implementation
- 3. Heap Sort
- 4. Other Heaps



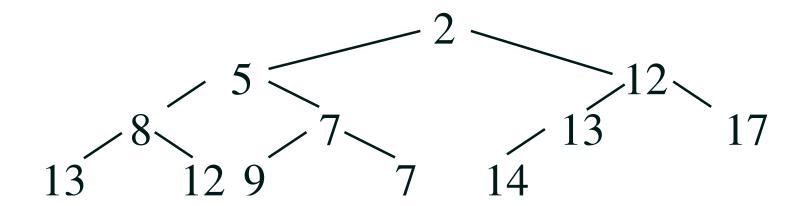
- A (min-)heap is (from one perspective) a binary tree
- It is a binary tree satisfying two constraints
 - ★ It is a complete tree
 - ★ Each child has a value 'greater than or equal to' its parent



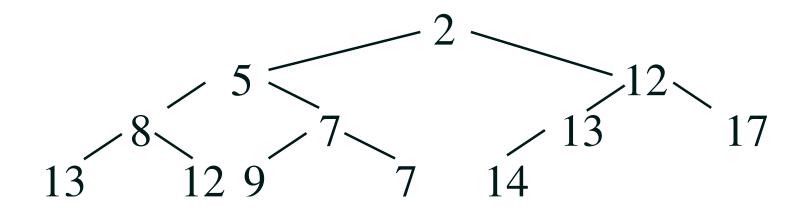
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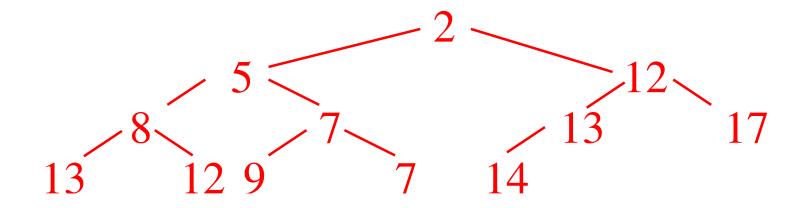
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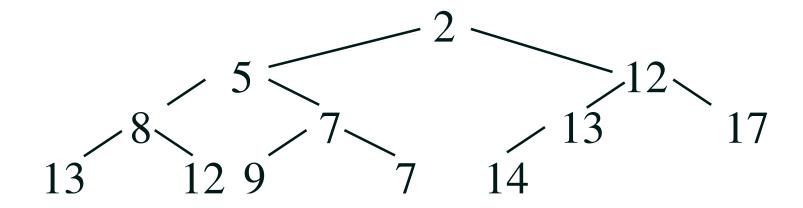
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- 1. Heaps
- 2. Priority Queues
 - Array Implementation
- 3. Heap Sort
- 4. Other Heaps



- One of the prime uses of heaps is to implement a priority queue
- A Priority Queue is a queue with priorities
- That is, we assign a priority to each element we add
- The head of the queue is the element with highest priority (smallest number)
- Used, for example, in simulating real time events
- Used to implement "greedy algorithms"

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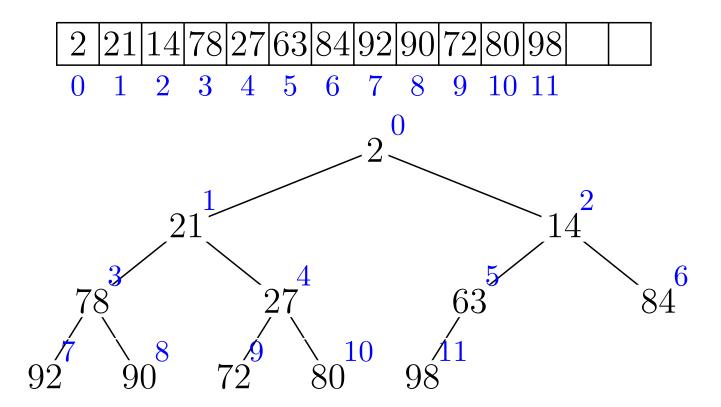
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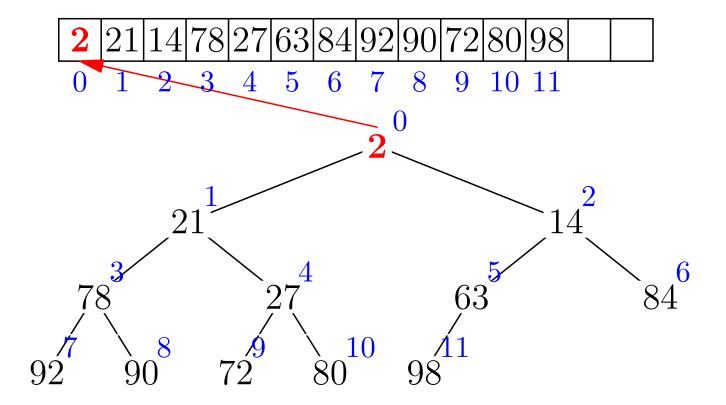
- A simple Priority Queue might include
 - * unsigned size() returning the the number of elements
 - ⋆ bool empty() returns true if empty
 - void push(T element, int priority) adds an
 element
 - ★ T top() returns head of queue
 - ⋆ void pop() dequeues head of queue

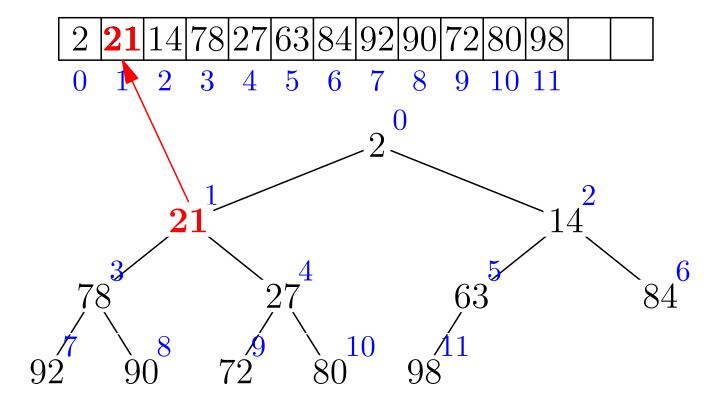
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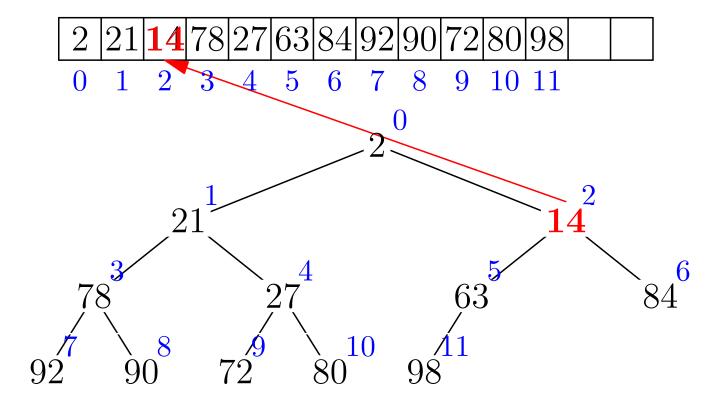
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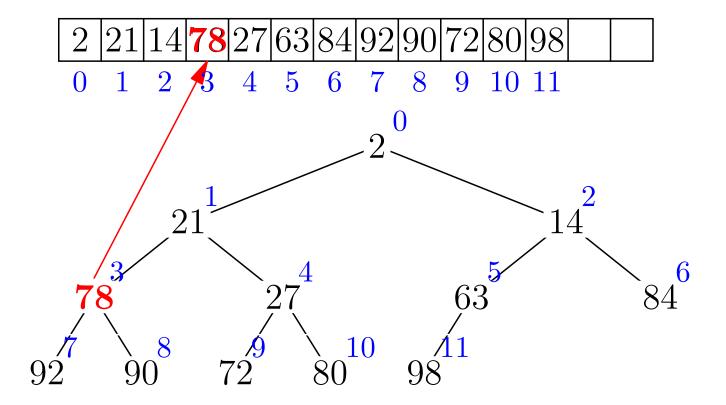
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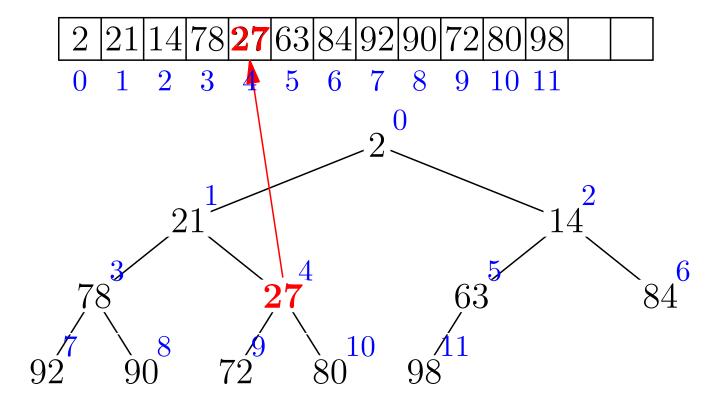


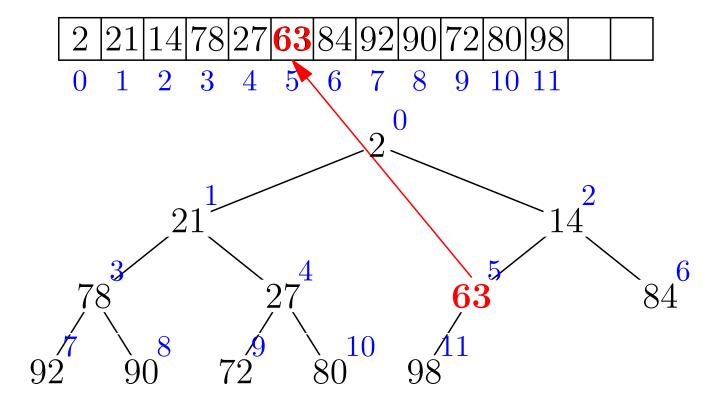


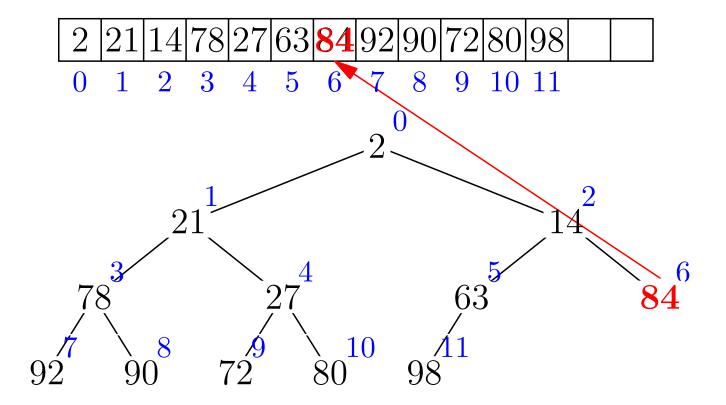


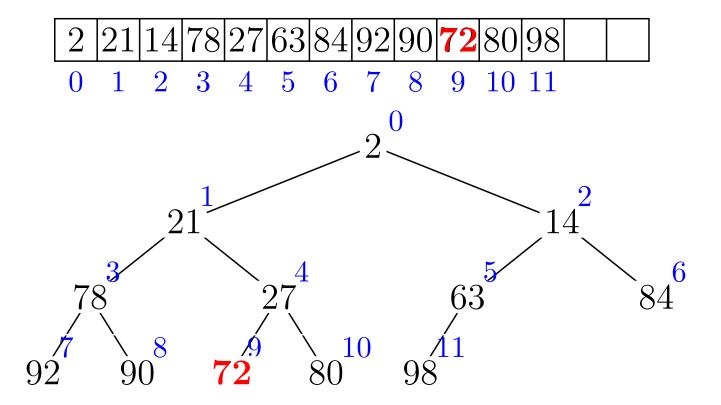


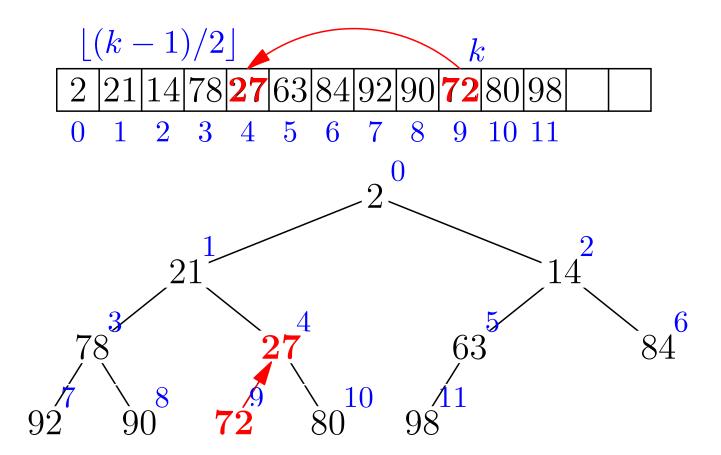


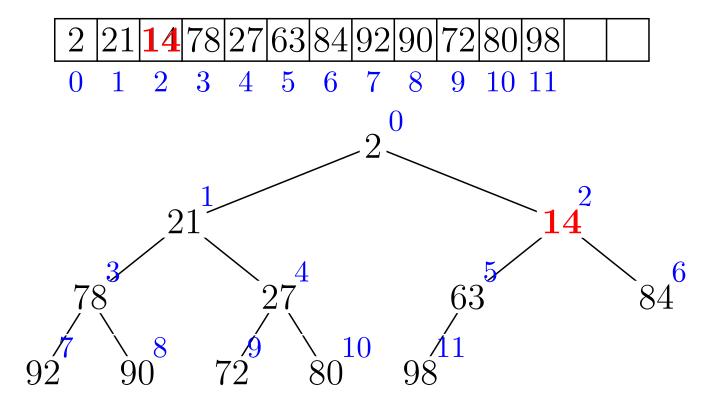


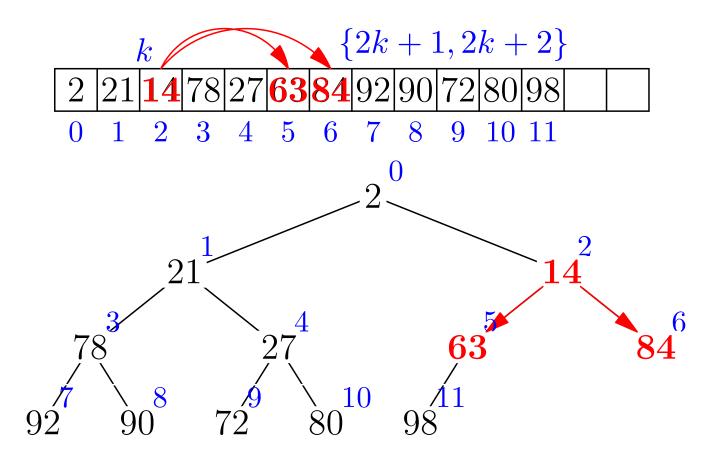












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#include <vector>
using namespace std;

template <typename T, typename P>
class heapPQ {
private:
   vector<pair<T, P> > array;
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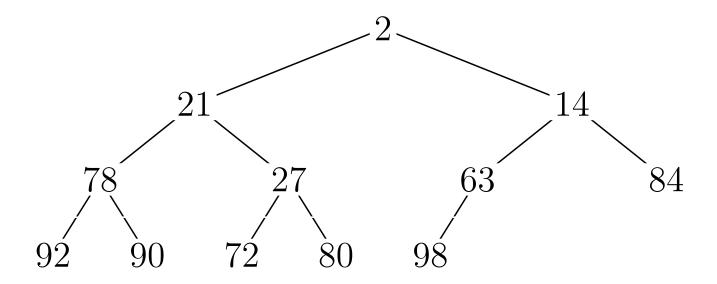
template <typename T, typename P>
class heapPQ {
private:
   vector<pair<T, P> > array;

public:
   heapPQ(unsigned capacity=11) {
      array.reserve(capacity);
   }
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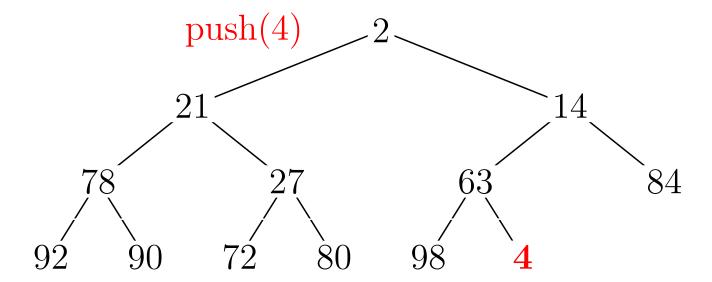
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  unsigned size() {return array.size();}
  bool empty() {return array.empty();}
  const T& top() {return array[0].first;}
```

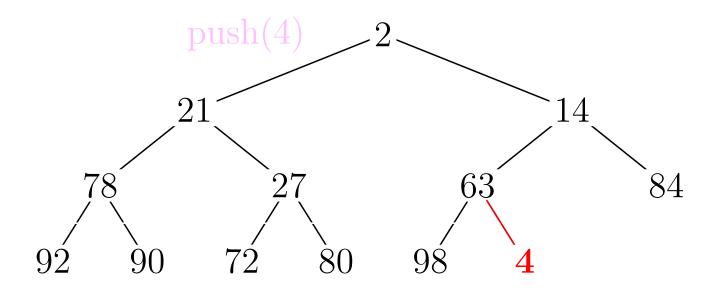
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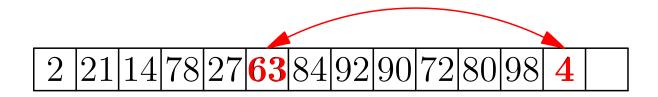


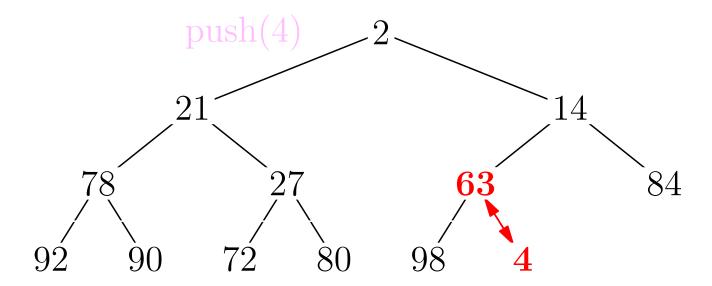
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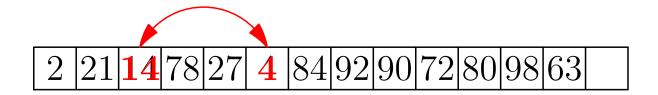


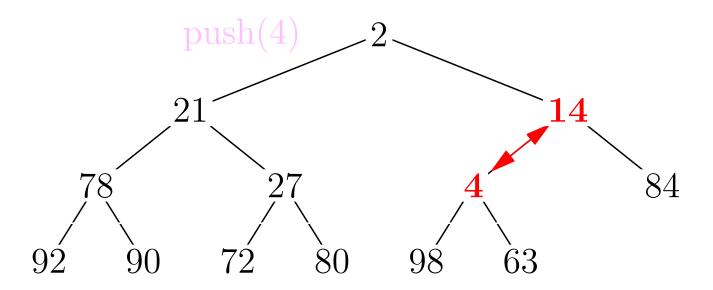
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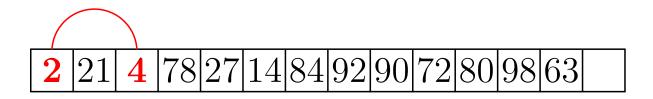


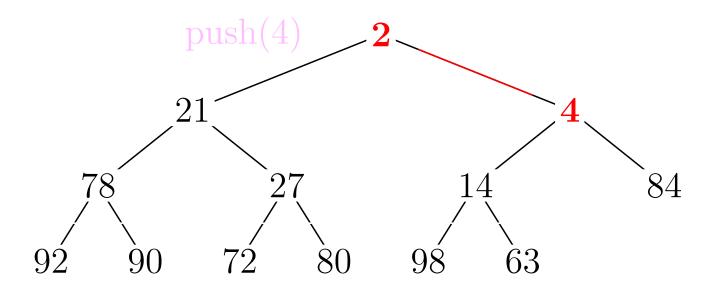












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void push(T value, P priority) {
  pair<T,P> tmp(value, priority);
  array.push_back(tmp);
  unsigned child = size() - 1;
  /* Percolate Up */
  while (child!=0) {
    unsigned parent = (child-1) >> 1; // floor((child-1)/2)
    if (array[parent].second < array[child].second)</pre>
      return;
    array[child] = array[parent];
    array[parent] = tmp;
    child = parent;
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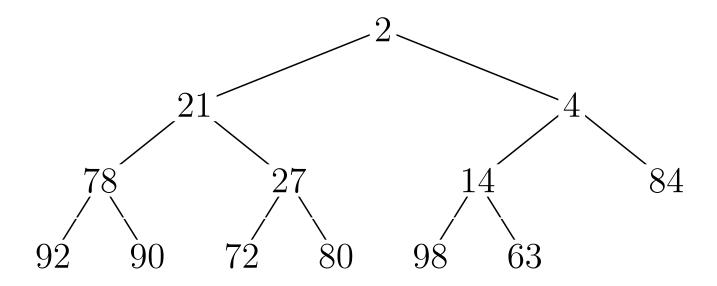
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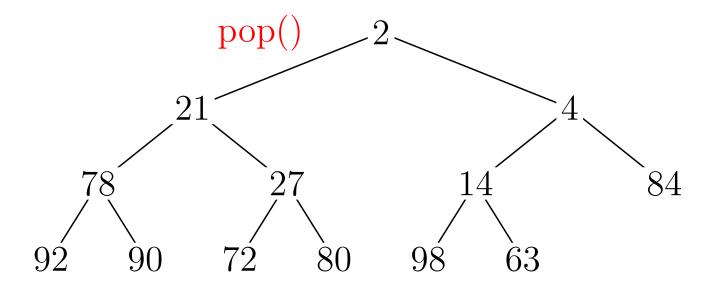
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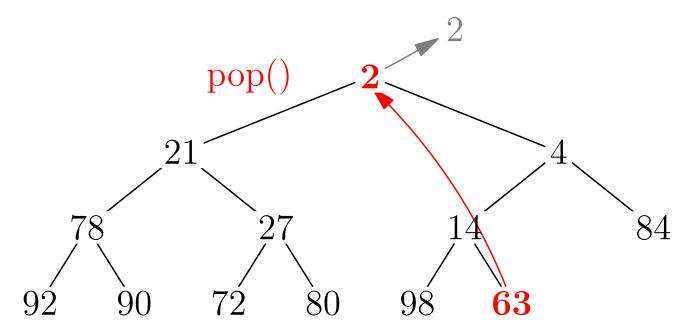
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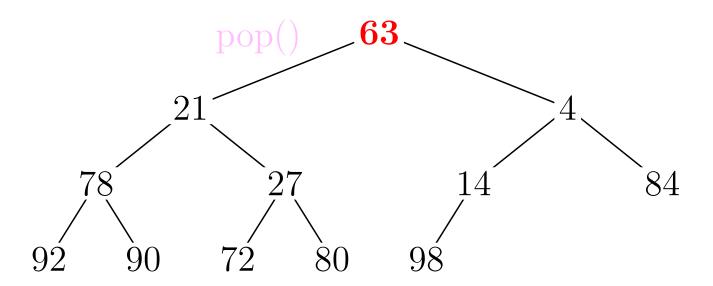
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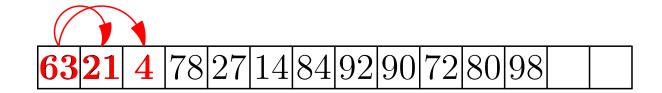


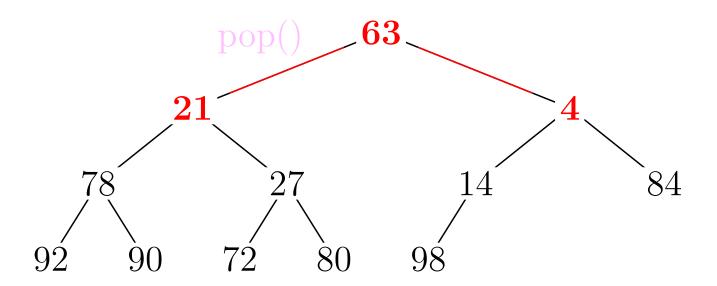
2 21 4 78 27 14 84 92 90 72 80 98 **63**

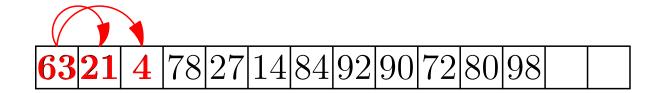


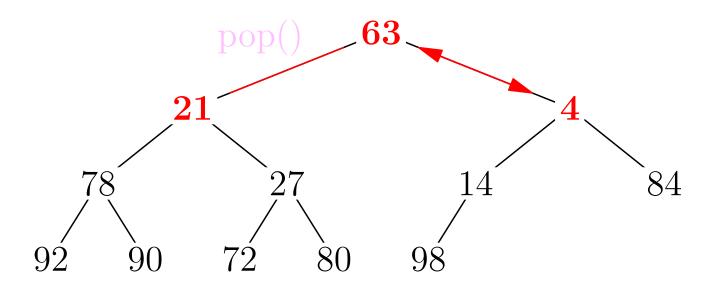
63 21 4 78 27 14 84 92 90 72 80 98



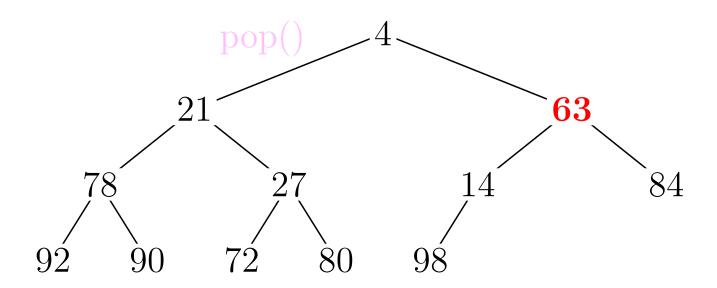




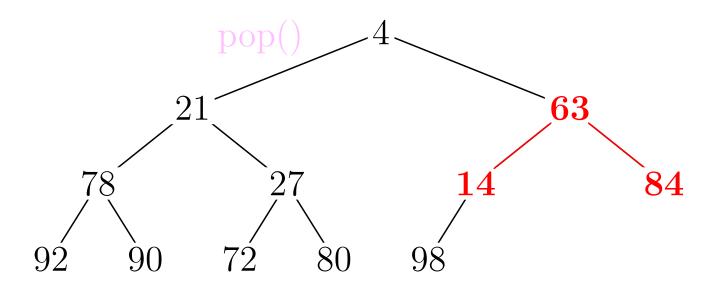




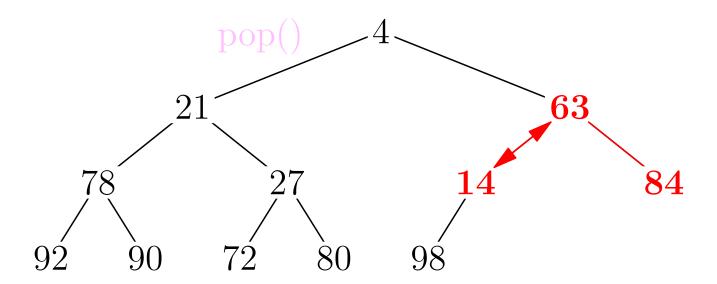
4 | 21 | 63 | 78 | 27 | 14 | 84 | 92 | 90 | 72 | 80 | 98 |

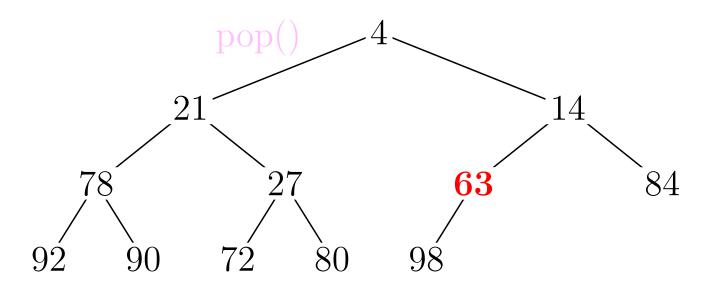


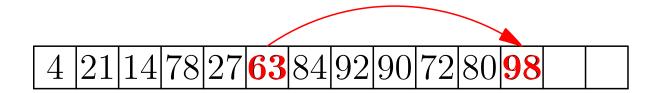


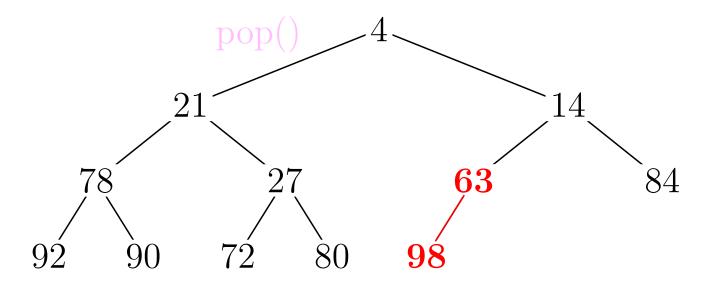










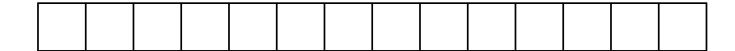


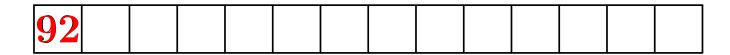
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void pop() {
unsigned parent = 0;
pair<T, P> tmp = array.back();
array[0] = tmp;
array.pop_back();
```

```
void pop() {
unsigned parent = 0;
pair<T, P> tmp = array.back();
array[0] = tmp;
array.pop_back();
unsigned child = 1;

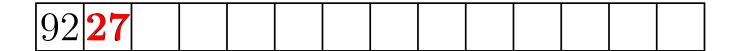
/* Percolate down */
while(child<size()) {</pre>
```

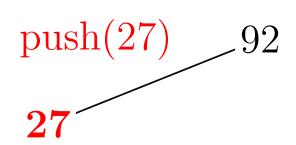
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void pop() {
unsigned parent = 0;
pair<T, P> tmp = array.back();
array[0] = tmp;
array.pop_back();
unsigned child = 1;
/* Percolate down */
while (child<size()) {</pre>
  if (child+1<=size() && array[child+1].second < array[child].second)</pre>
    ++child;
  if (array[child].second > array[parent].second)
    return;
  array[parent] = array[child];
  array[child] = tmp;
  parent = child;
  child = 2*parent + 1;
```

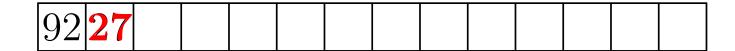




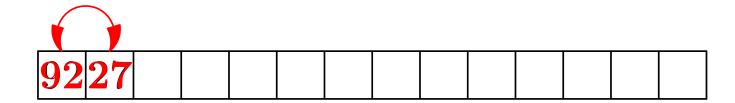
push(92) **92**

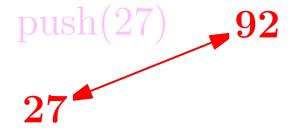




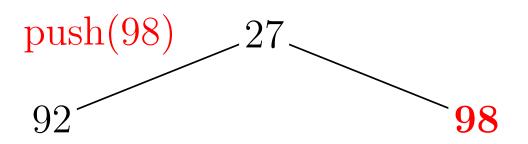




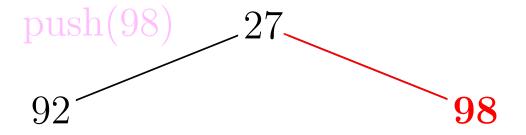




| 27 92 9 | 98 | | | |
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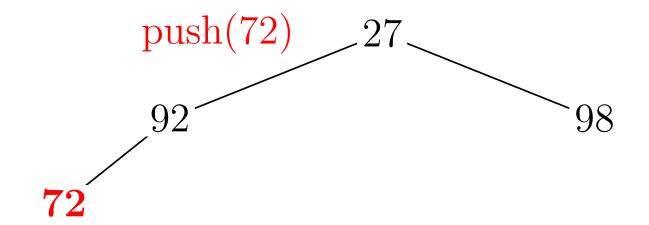
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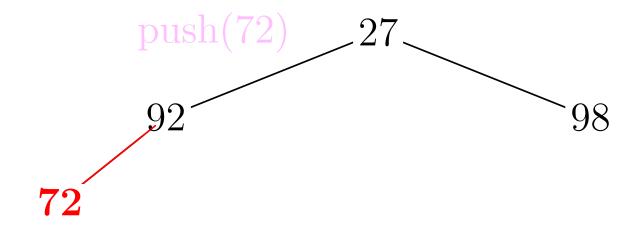


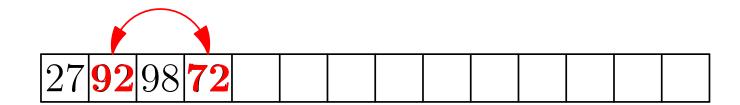


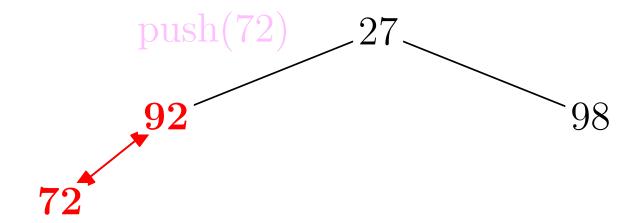


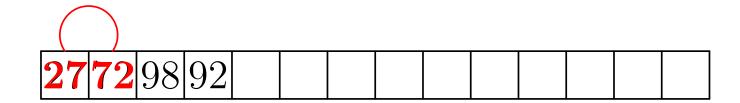


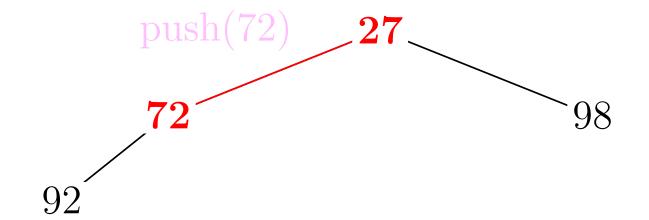




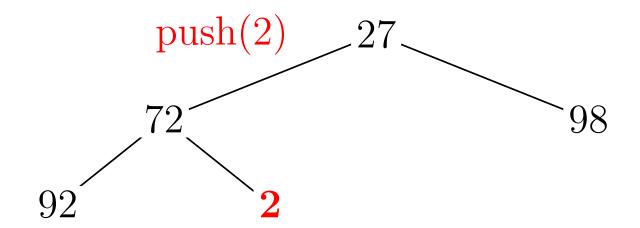




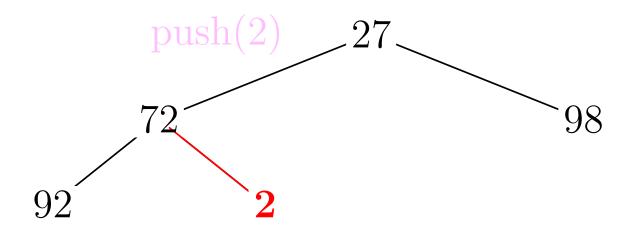


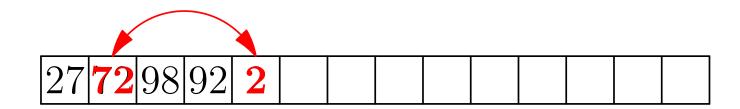


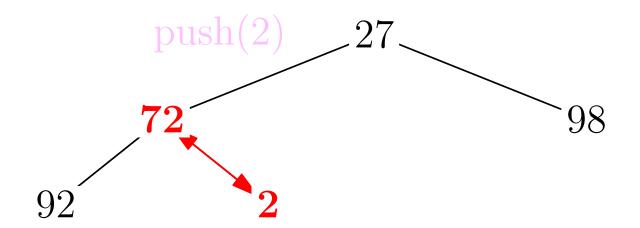


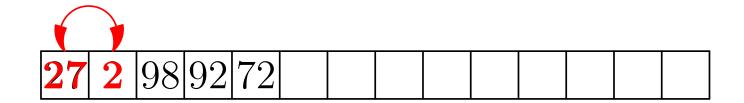


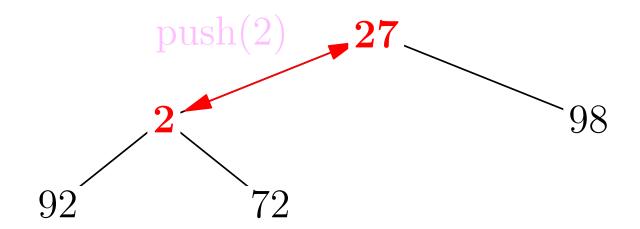


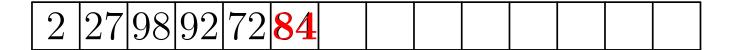


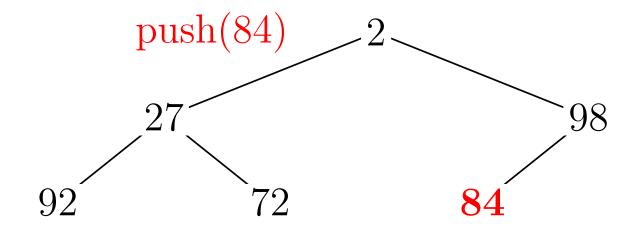




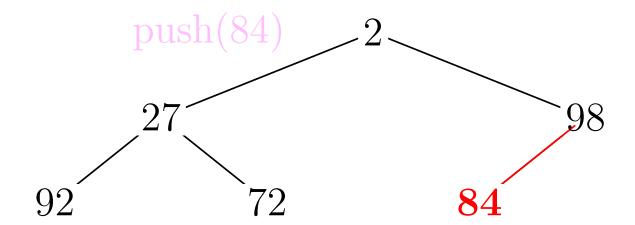


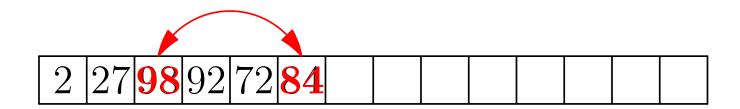


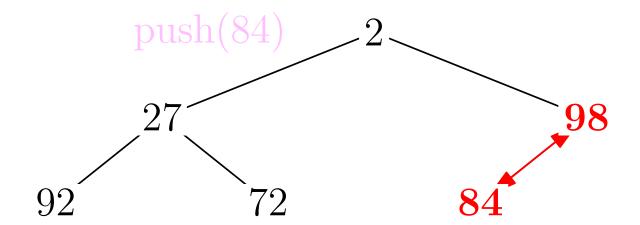


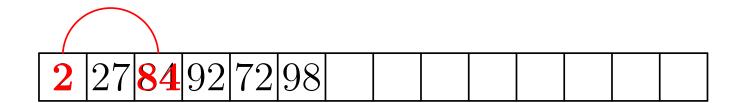


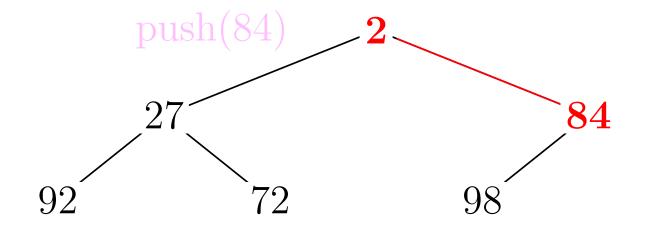




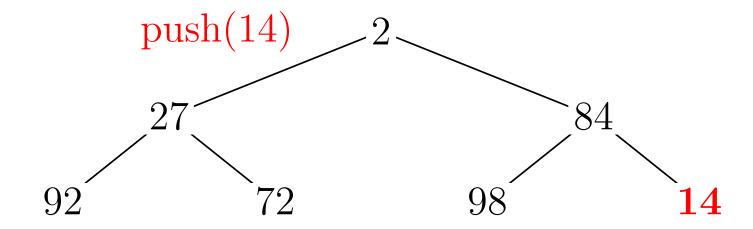




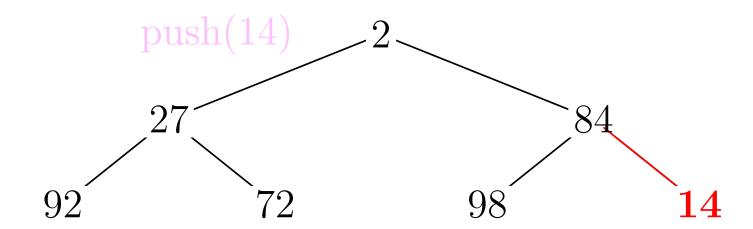


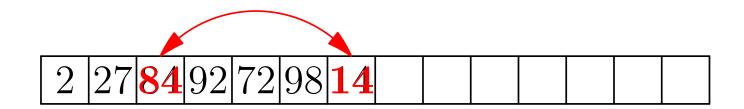


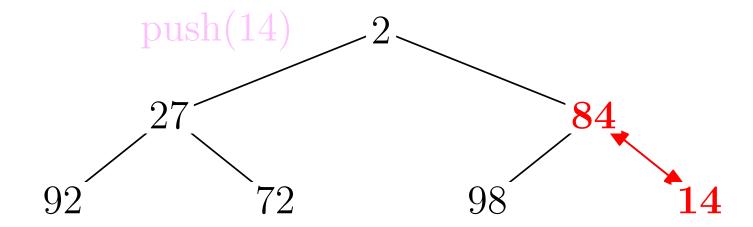


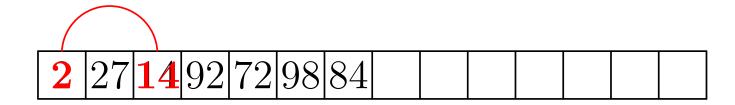


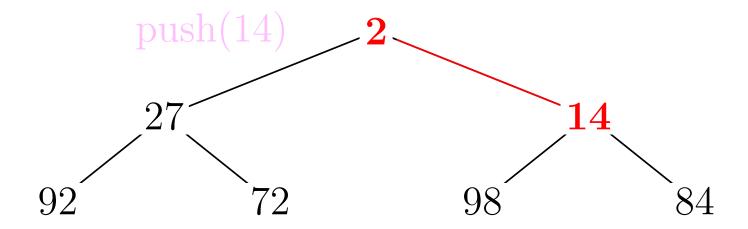


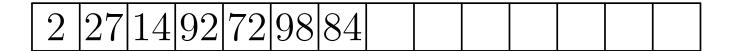


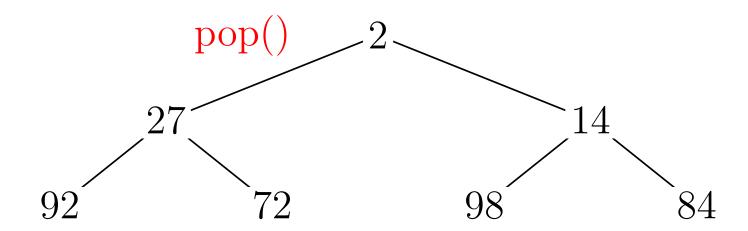




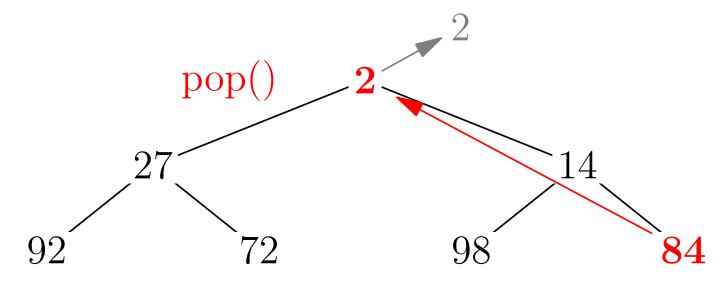


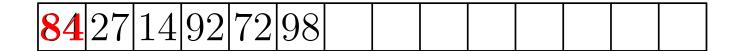


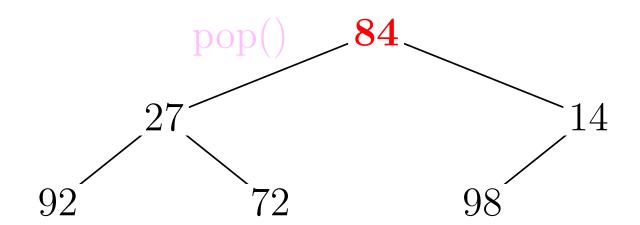




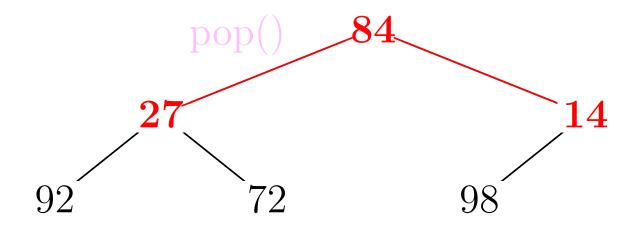




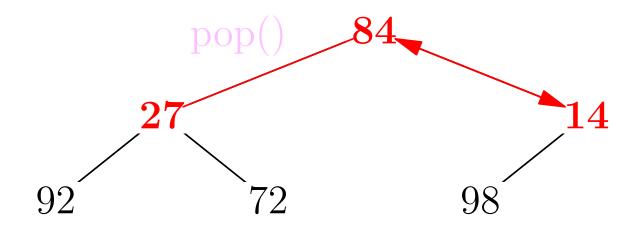




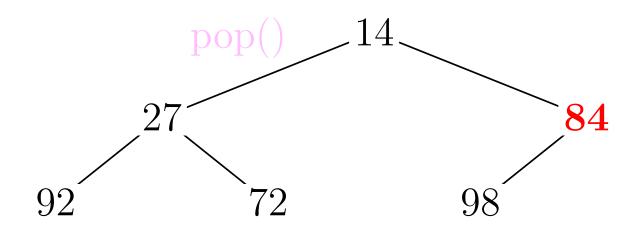


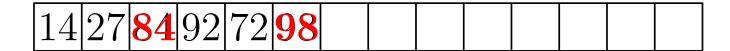


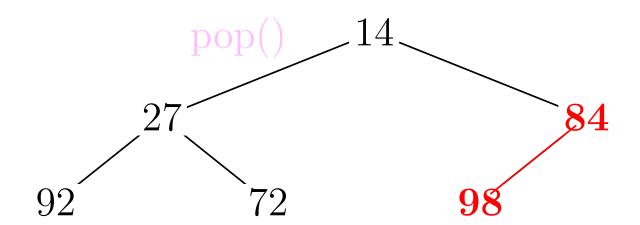




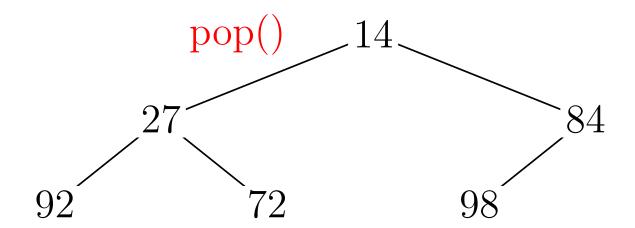




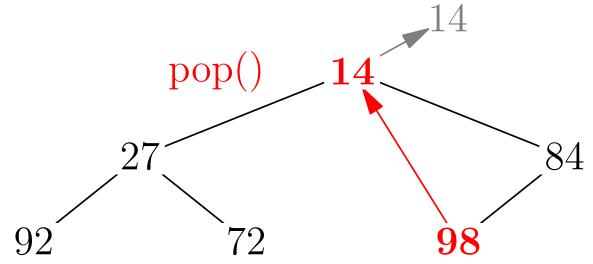


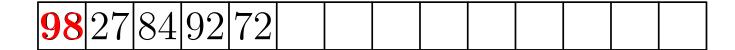


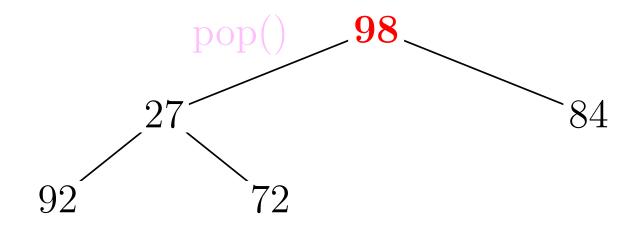




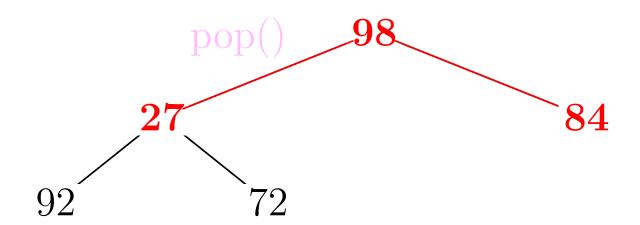




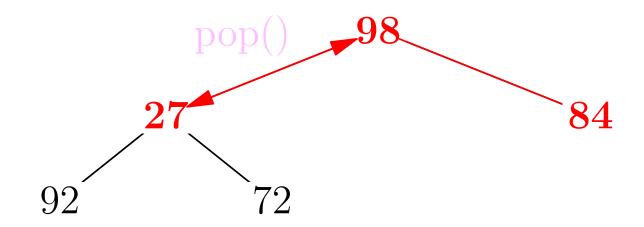




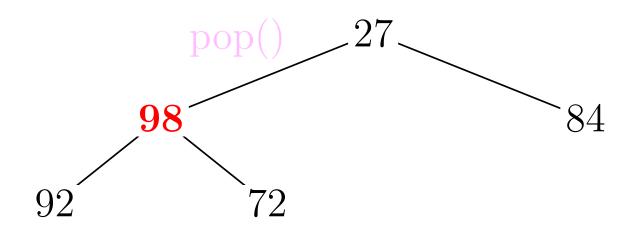




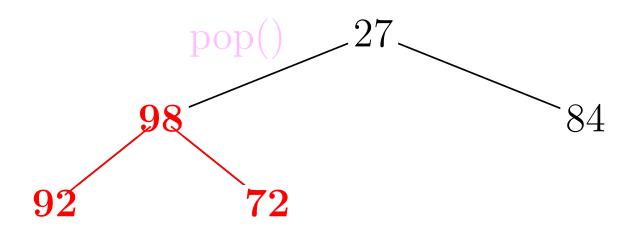


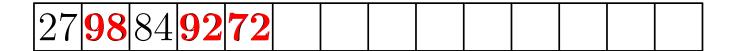


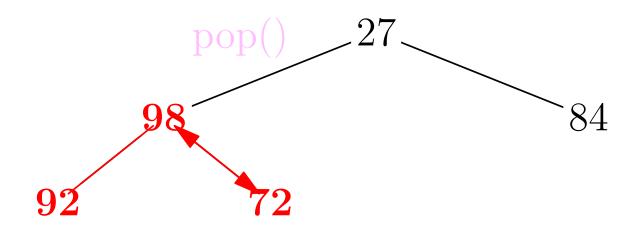




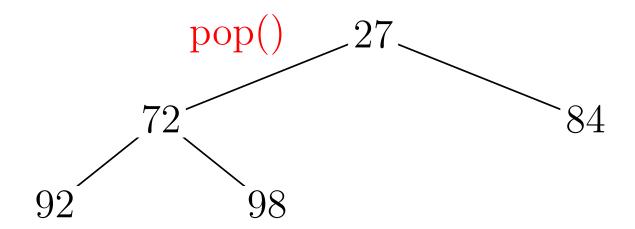


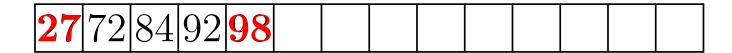


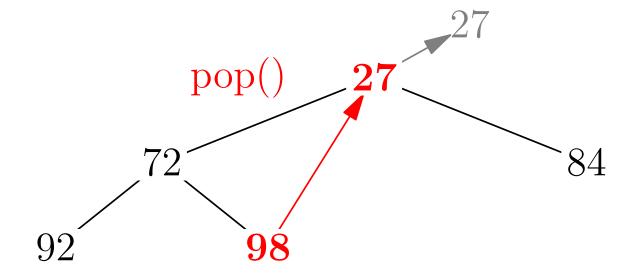


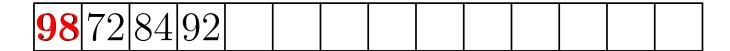


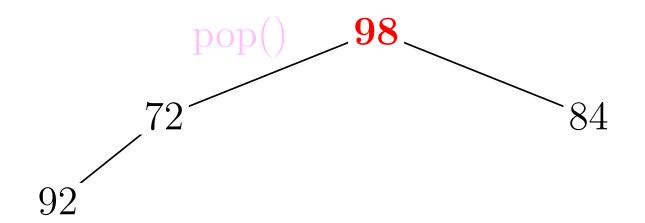
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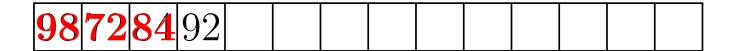


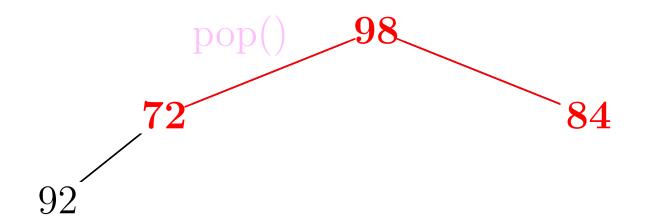


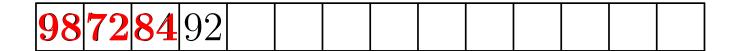


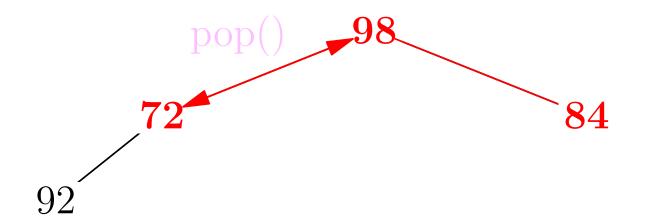




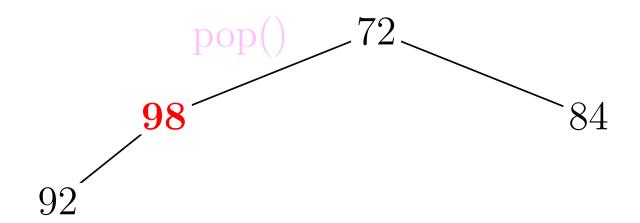




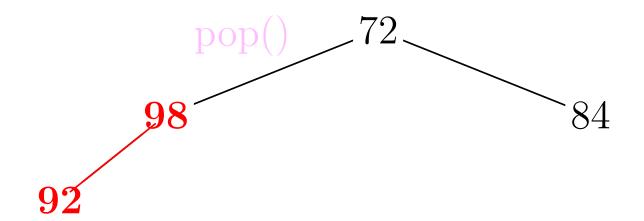




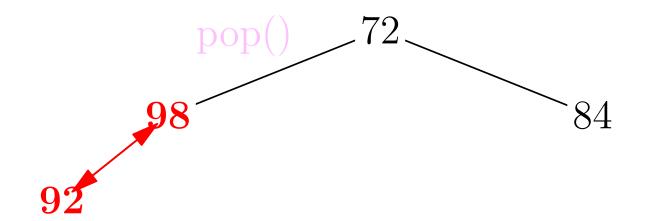




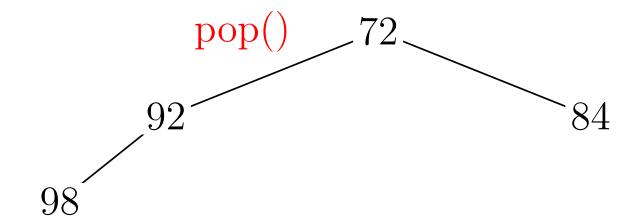




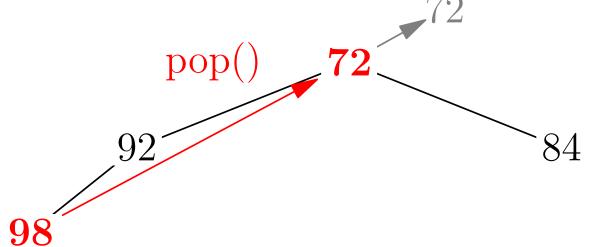


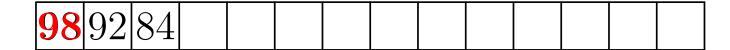


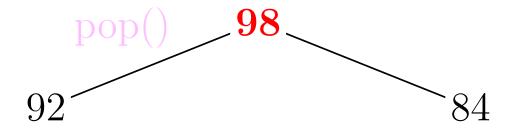




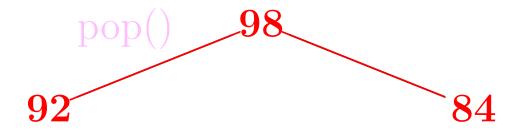




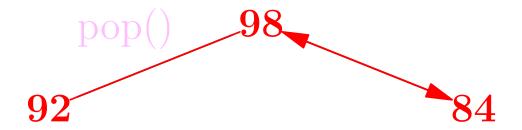




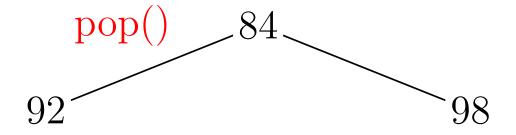
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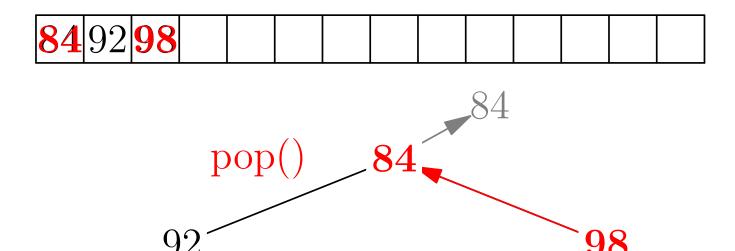


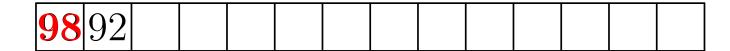
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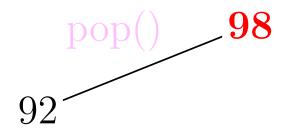


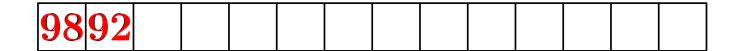
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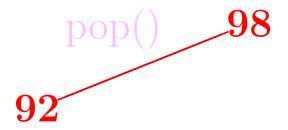


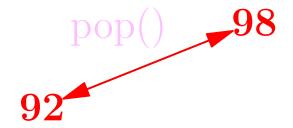


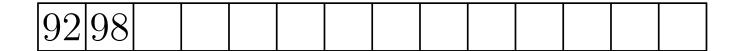


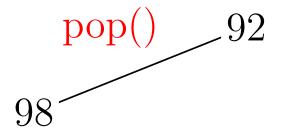


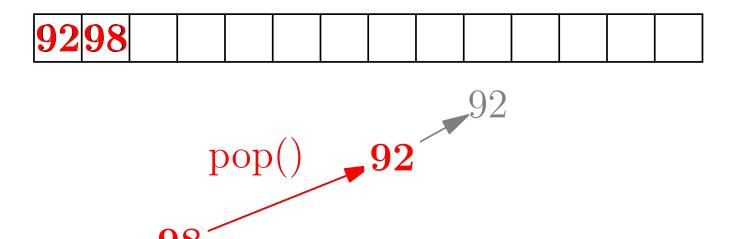






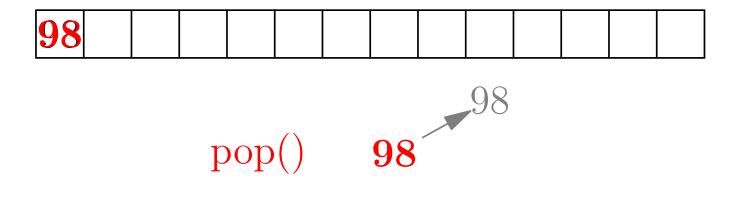








pop() 98



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- These both either percolating an element up the tree or percolating an element down the tree
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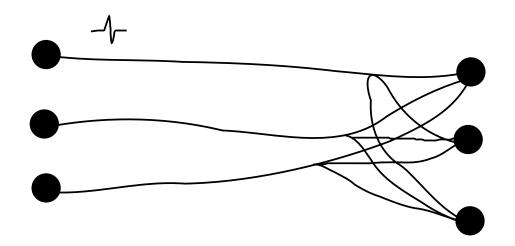
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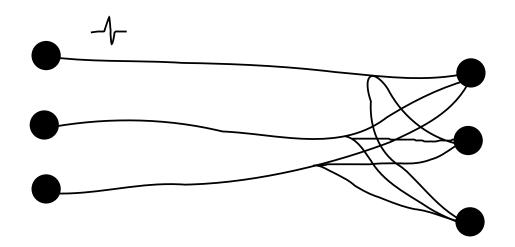
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 fact that it would take different times for the receiving neurons to
 feel the pulse (due to the different lengths of the axons)
- A famous Israeli group had "proved" this couldn't happen
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Outline

- 1. Heaps
- 2. Priority Queues
 - Array Implementation
- 3. Heap Sort
- 4. Other Heaps



Heap Sort

- A priority queue suggests a very simple way of performing sort
- We simply add elements to a heap and then take them off again

```
template <typename T>
void sort(vector<T> aList)
{
    HeapPQ<T> aHeap = new HeapPQ<T>(aList.size());
    for (T element: aList)
        aHeap.push(element, element);

aList.clear();
while(aHeap.size() > 0) {
    aList.push_back(aHeap.top());
    aHeap.pop();
    }
}
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 Note that this is not an in-place sort algorithm (i.e. it uses lots of memory)

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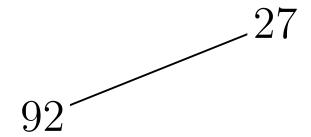
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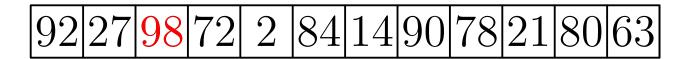
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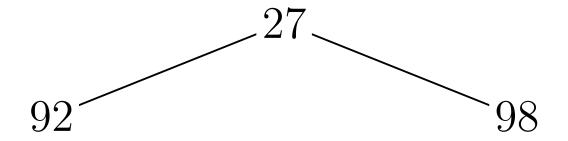
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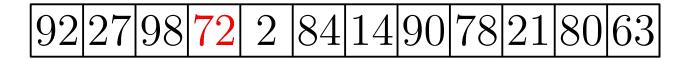
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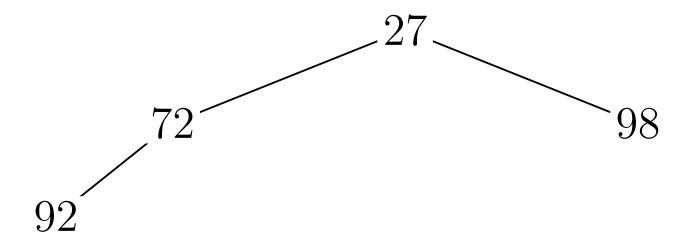
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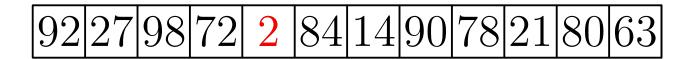


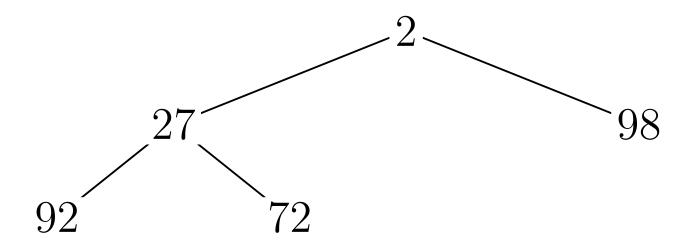




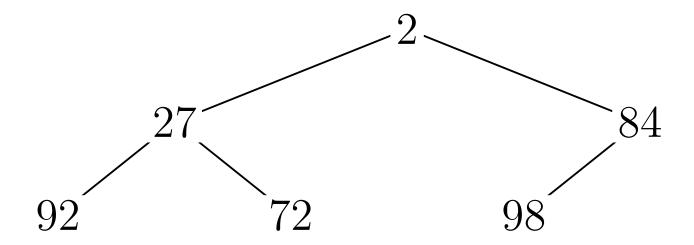




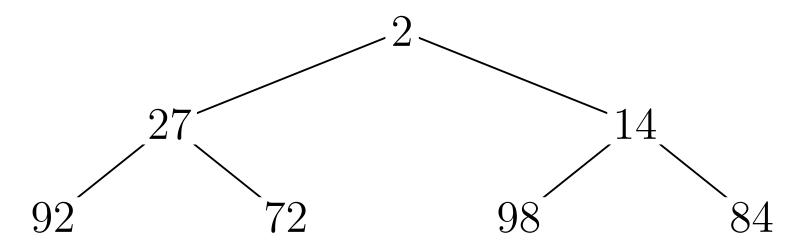


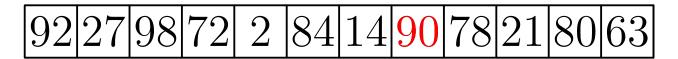


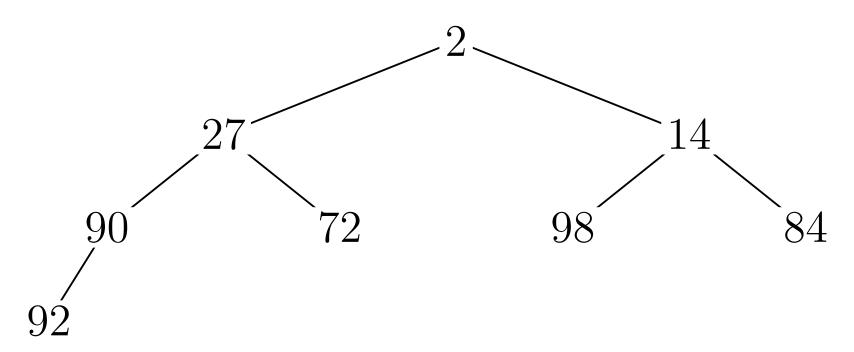
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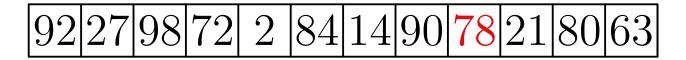


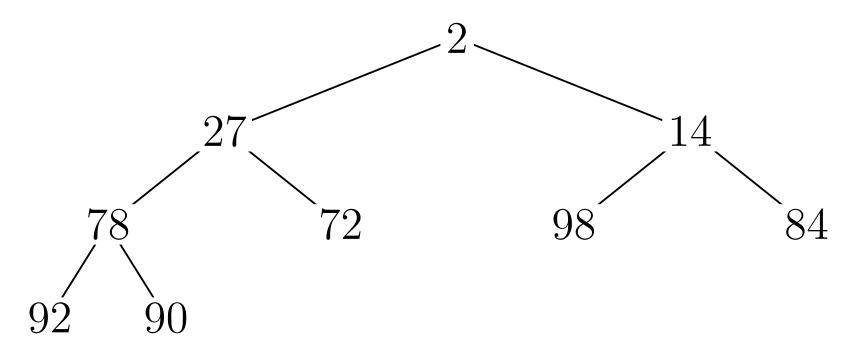


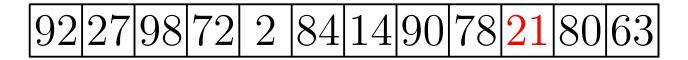


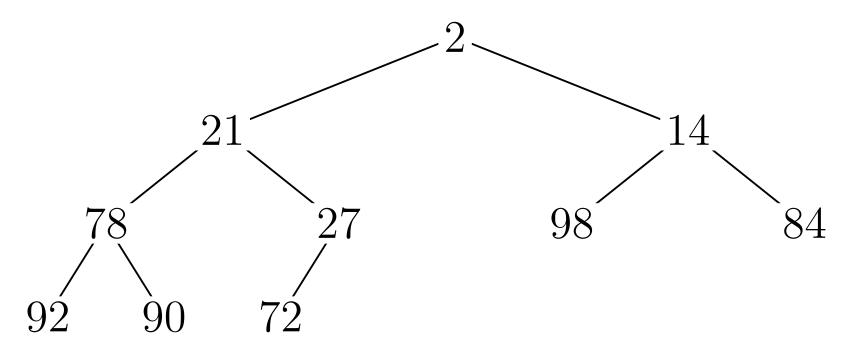


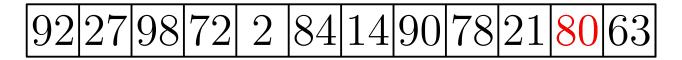


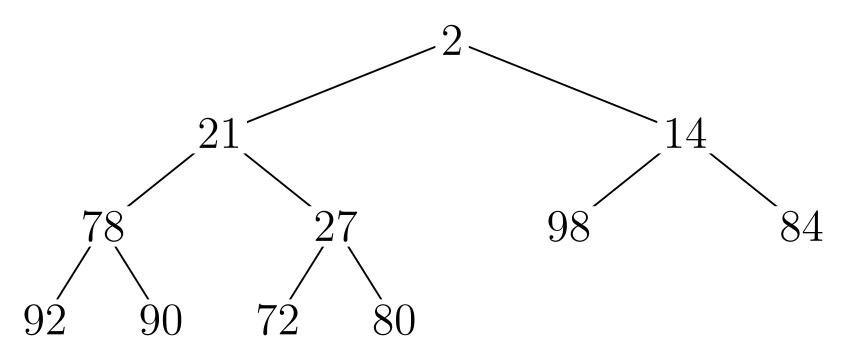


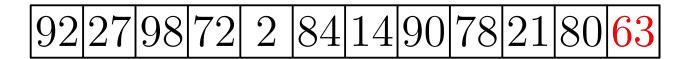


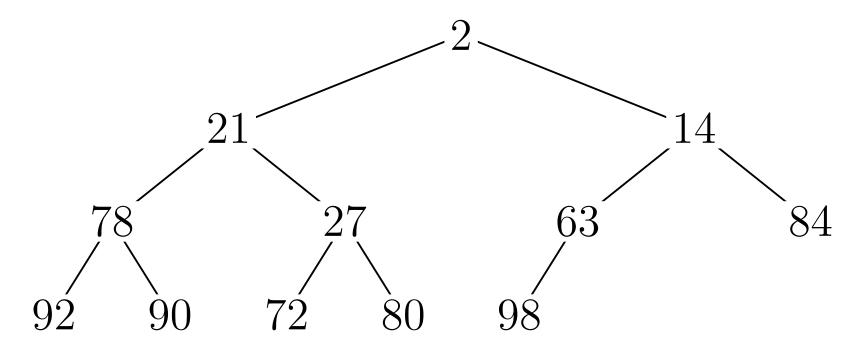


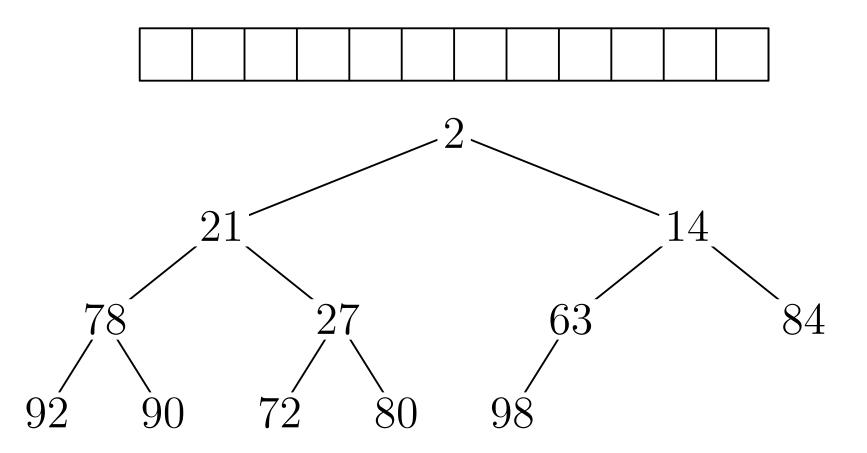


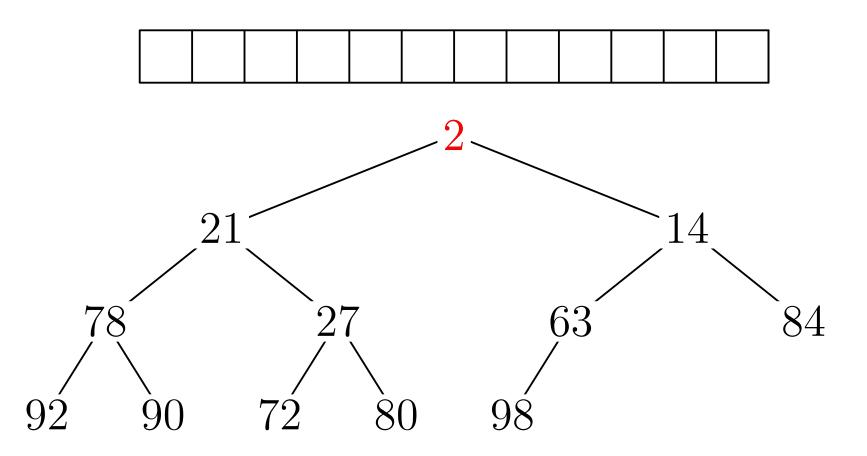


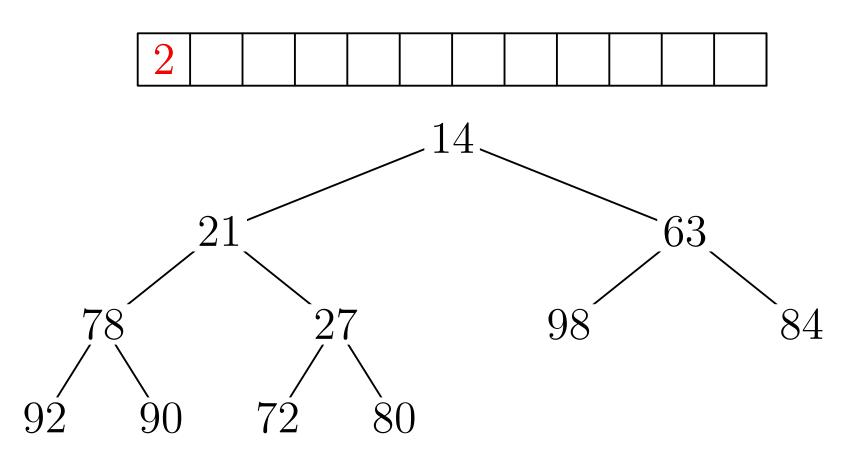


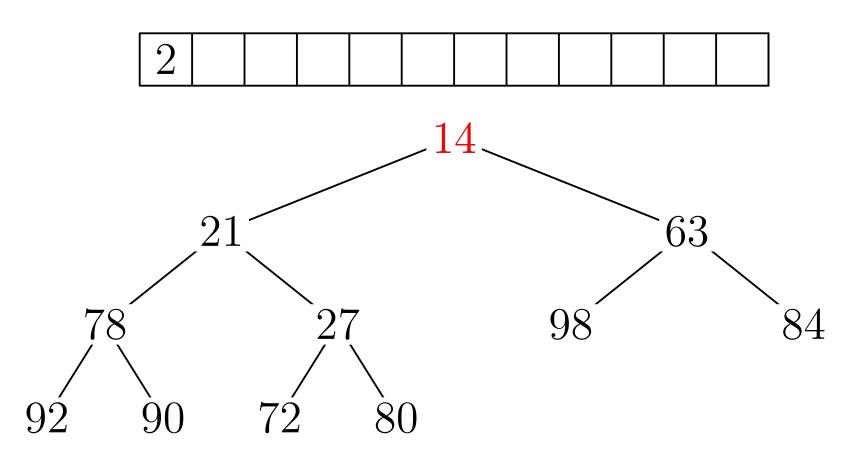


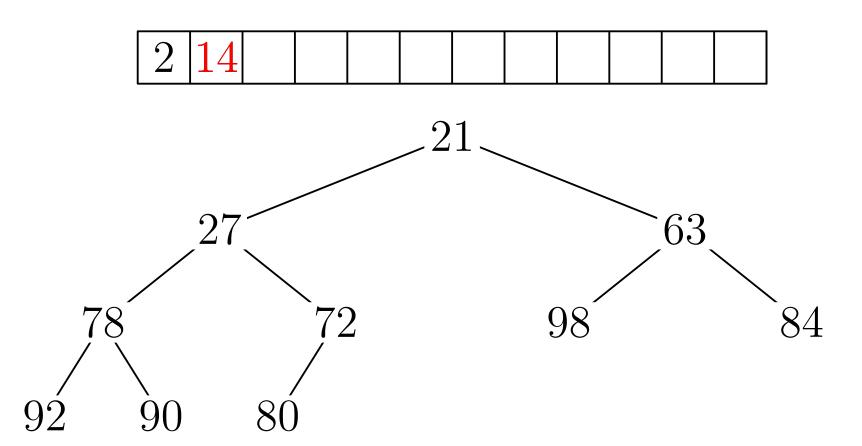


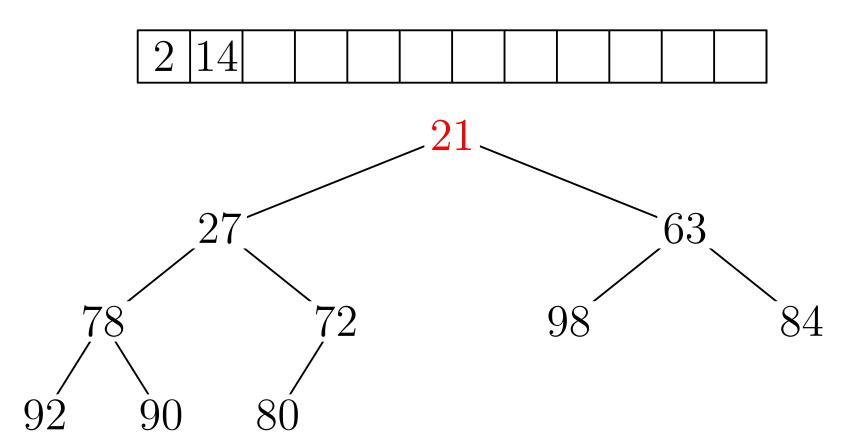


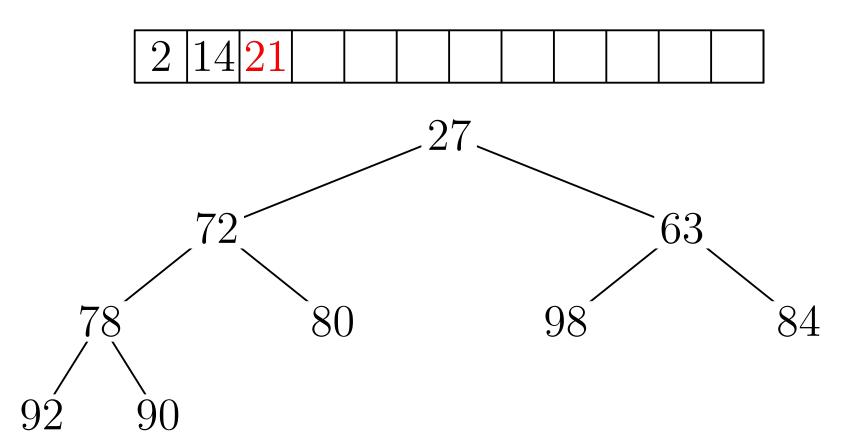


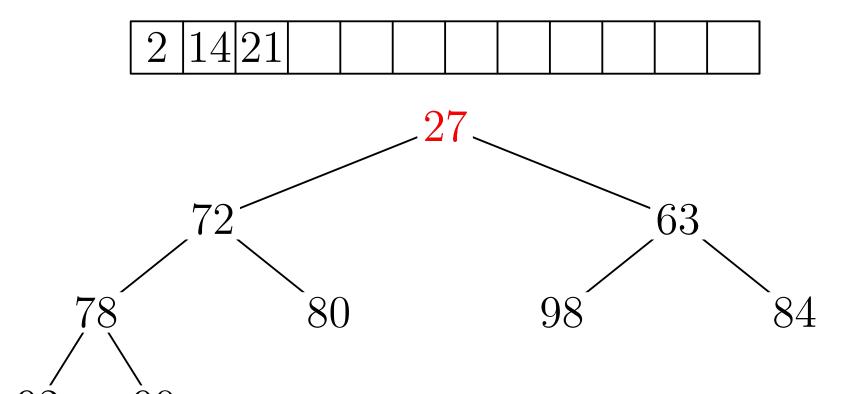


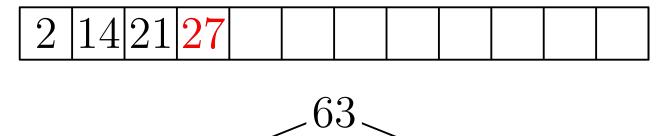


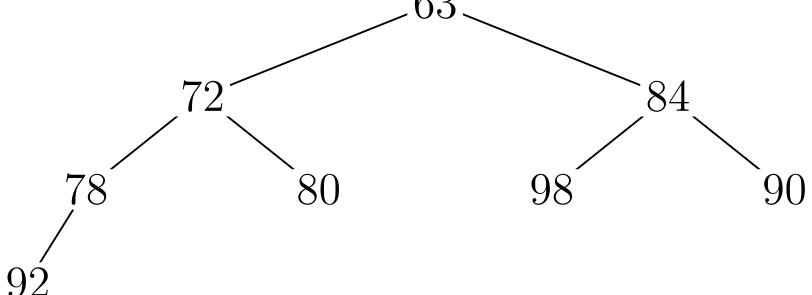




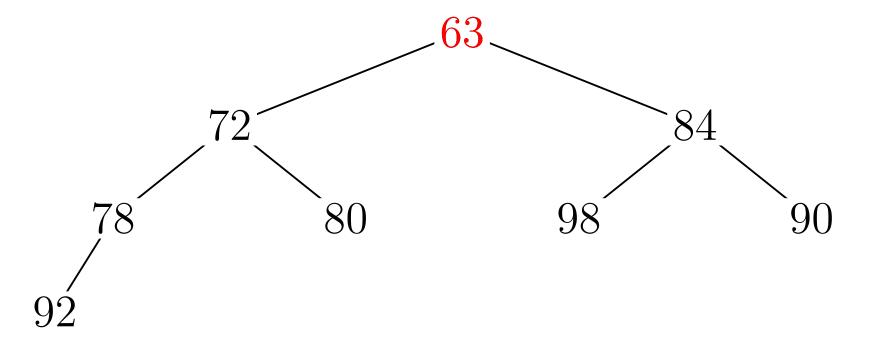


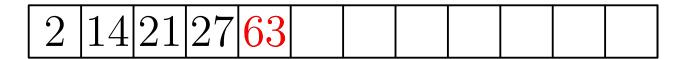


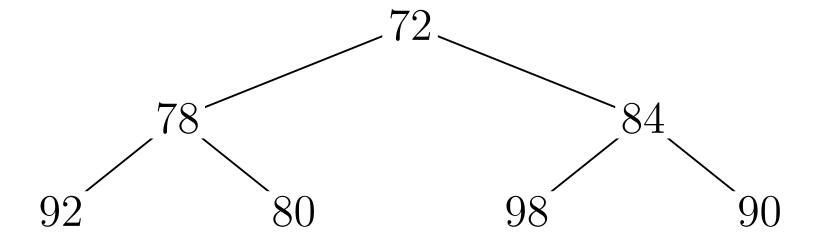




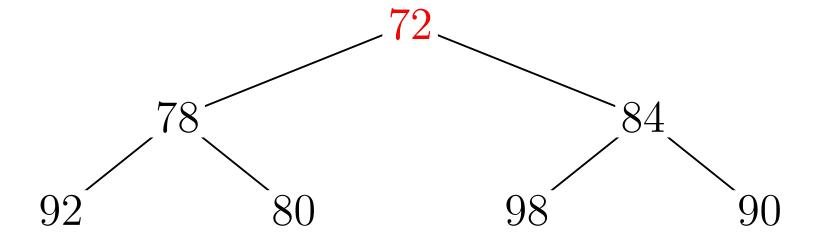




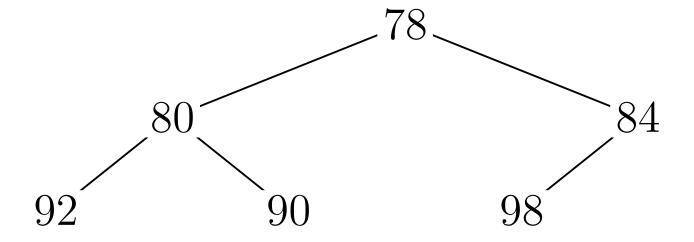


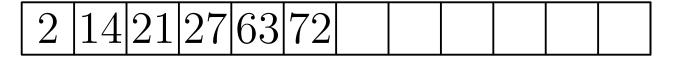


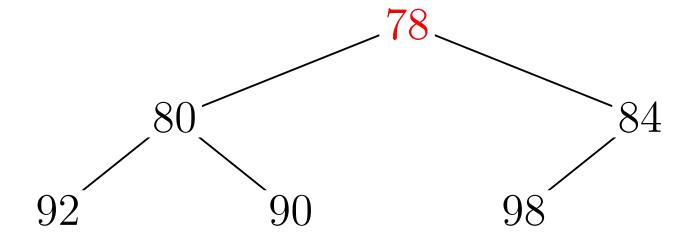




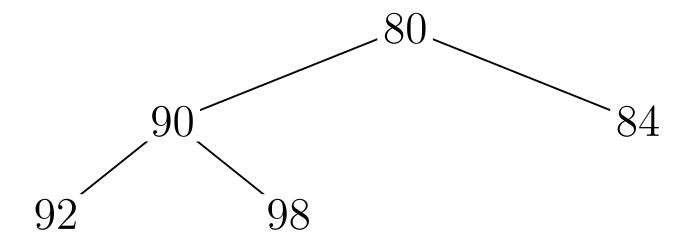


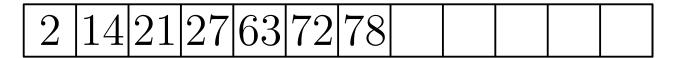


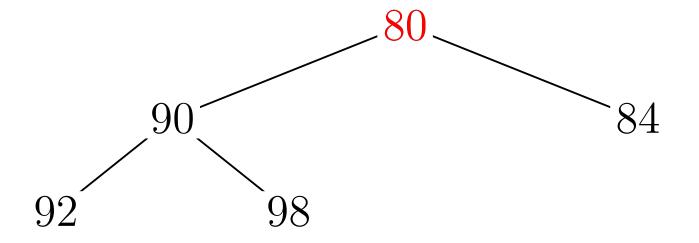


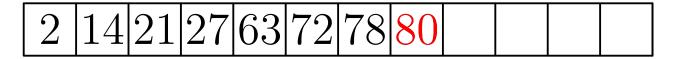


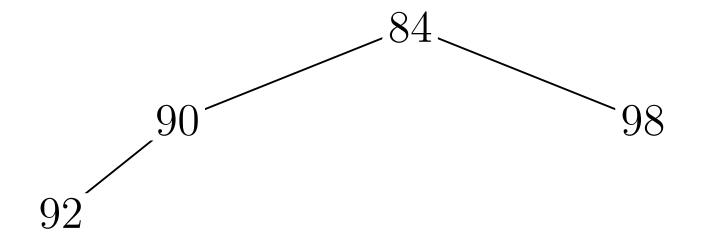


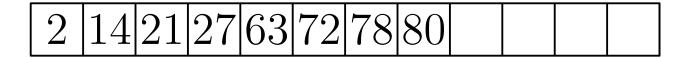


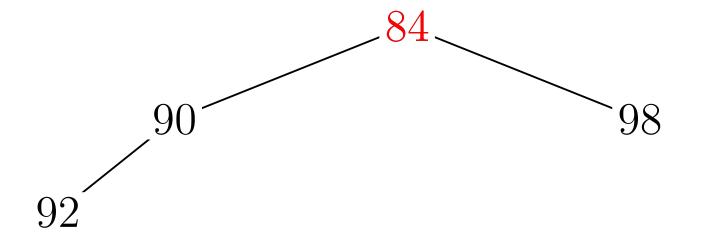


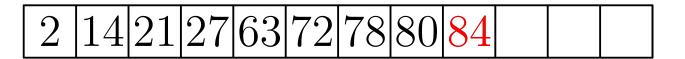


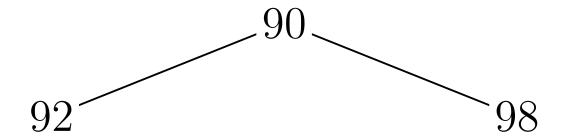


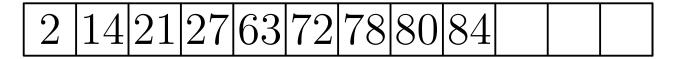


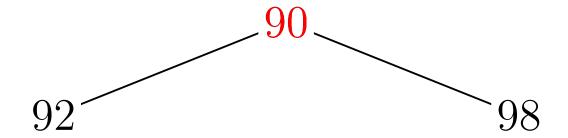




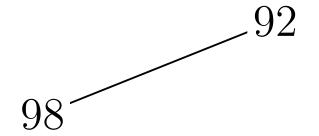




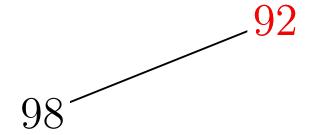




2 | 14 | 21 | 27 | 63 | 72 | 78 | 80 | 84 | 90 |



2 14 21 27 63 72 78 80 84 90



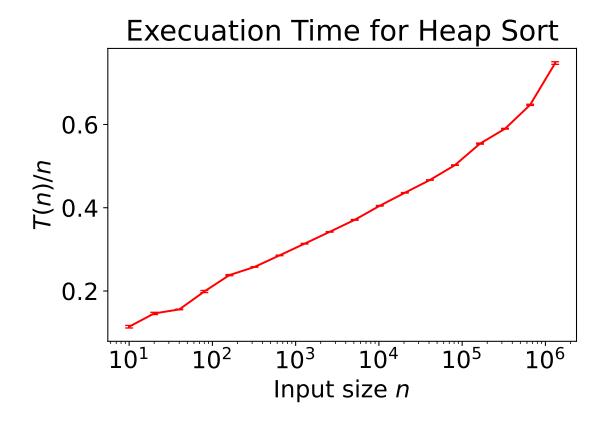
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2 | 14 | 21 | 27 | 63 | 72 | 78 | 80 | 84 | 90 | 92 | 98

Complexity of Heap Sort

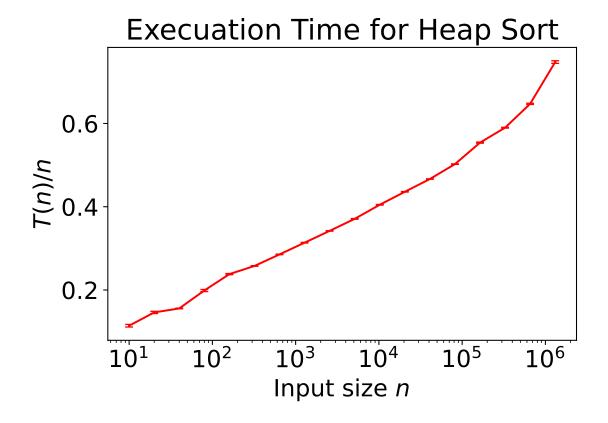
• As we have to add n elements and then remove n elements the time complexity is log-linear, i.e. $O(n \log(n))$



• This is actually a very efficient algorithm

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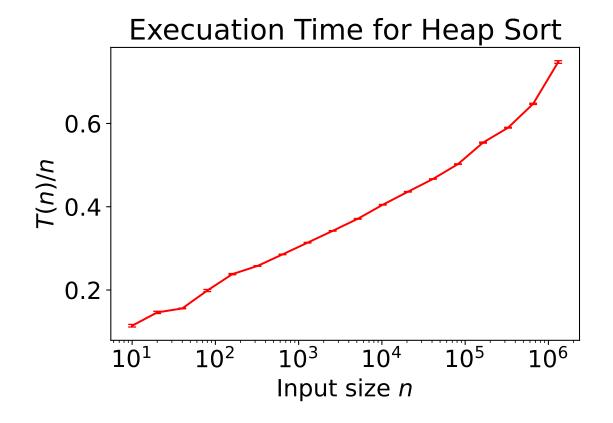
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Outline

- 1. Heaps
- 2. Priority Queues
 - Array Implementation
- 3. Heap Sort
- 4. Other Heaps



- Binary Heaps are so useful that other types of heaps have been developed
- The simplest enhancement is to combine a binary heap with a map which maintains a pointer to each element
- The map has to be updated every time elements are moved in the heap (fortunately only $O(\log(n))$ elements are move each time the heap is updated)
- The advantage of this heap is that the priorities of elements can be changed (involving percolating elements up or down the tree)

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- One common demand on a heaps is to merge two heaps
- Unfortunately binary heaps are not efficiently merged
- There are a variety of different heaps (leftist heaps, skew heaps, binomial queues, . . .) designed to be merged
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Other Operations

- All other operations are achieved by merging
 - * Adding an element is achieved by merging the current heap with a heap of one element
 - * Removing the minimum element is achieved by removing the root and merging the left and right tree
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- Heaps are binary trees that can be implemented as arrays
- Priority queue have many (often surprising uses)
 - ★ They are used when you need a queue with priorities, e.g. in operating systems
 - ★ They can be used to perform pretty efficient sort
 - ★ They are often used for implementing greedy type algorithms
 - ★ One important application is in real time simulations
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