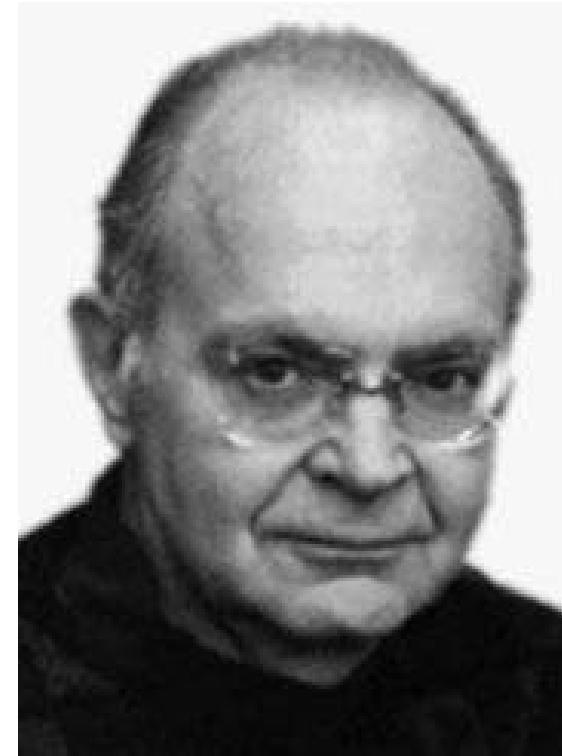
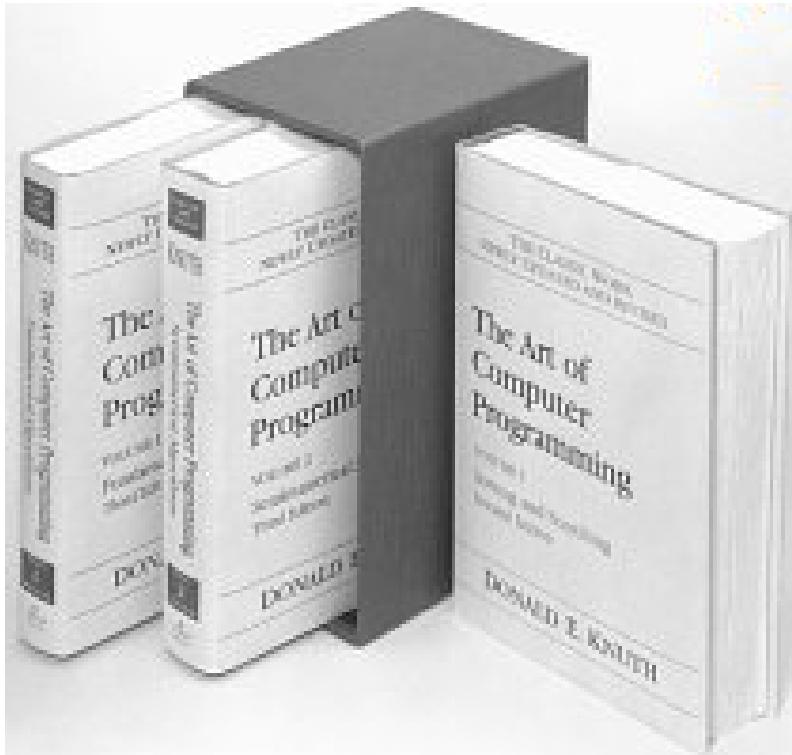


# Algorithms and Analysis

## Lesson 14: Analyse!



*Pseudo code, binary search, insertion sort, selection sort, lower bound complexity*

# Outline

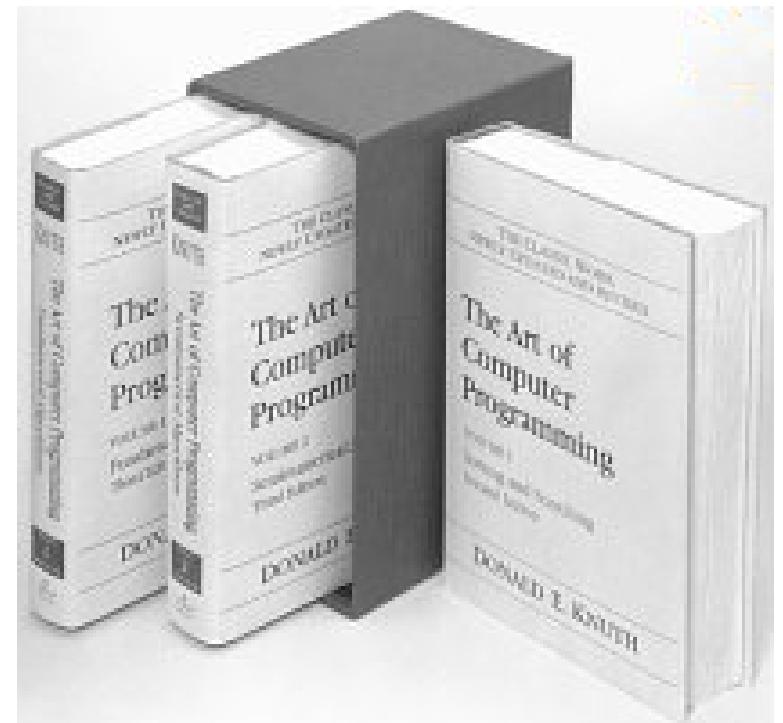
## 1. Algorithm Analysis

## 2. Search

## 3. Simple Sort

- Insertion Sort
- Selection Sort

## 4. Lower Bound



# Algorithm Analysis

- We've covered most of the basic data structures
- The rest of the course is going to focus more on algorithms
- We will look predominantly at
  - ★ Searching
  - ★ Sorting
  - ★ Graph Algorithms
- Emphasise general solution strategies

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# Code and Pseudo Code

- C++ code is often difficult to read—there are often programming details we don't care about
- It contains details such as throwing exception which are repetitive and often depends on who you are writing the code for
- Algorithms are not language dependent (data structures are a bit more language dependent)
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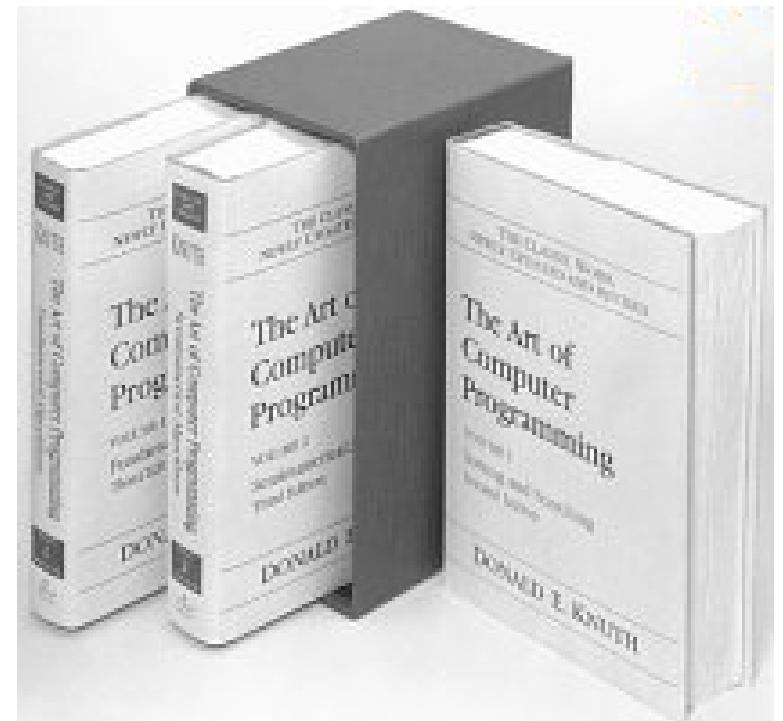
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# Dumb Search

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DUMBSEARCH (a, x)
{
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bool search(T a[], T x)  
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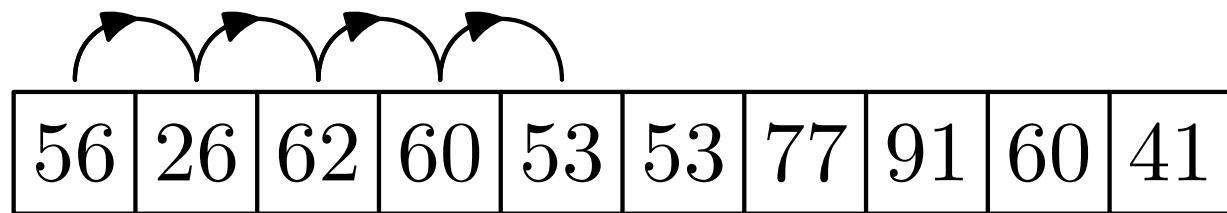
56	26	62	60	53	53	77	91	60	41
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$\text{find}(53) \rightarrow \text{true}$



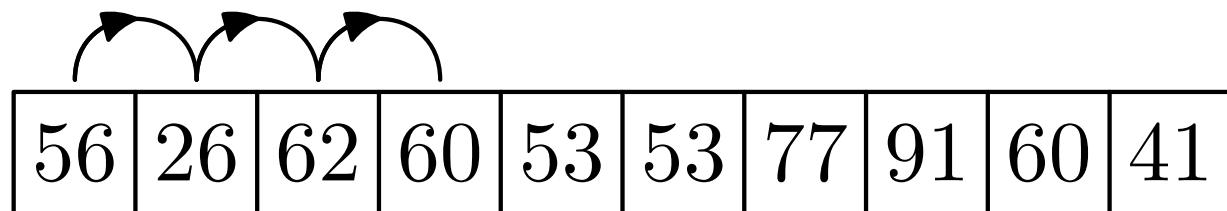
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$\text{find}(60) \rightarrow \text{true}$



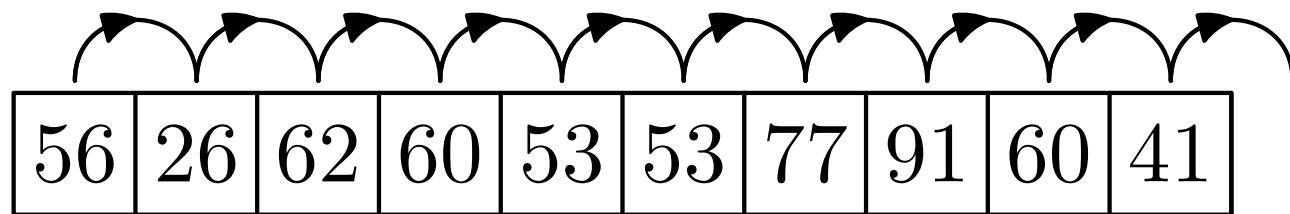
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$\text{find}(12) \rightarrow \text{false}$



# Time Complexity

- Worst case:
  - ★ The worst case for a successful search is when the element is in the last location in the array
  - ★ This takes  $n$  comparisons: worst case is  $\Theta(n)$
- Best case:
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- Average case:
  - ★ Assume every location is equally likely to hold the key

$$\frac{1 + 2 + \dots + n}{n} = \frac{1}{n} \sum_{i=1}^n i = \frac{1}{n} \times \frac{n(n+1)}{2} = \frac{n+1}{2}$$

- For an unsuccessful search  $n$  comparison are necessary

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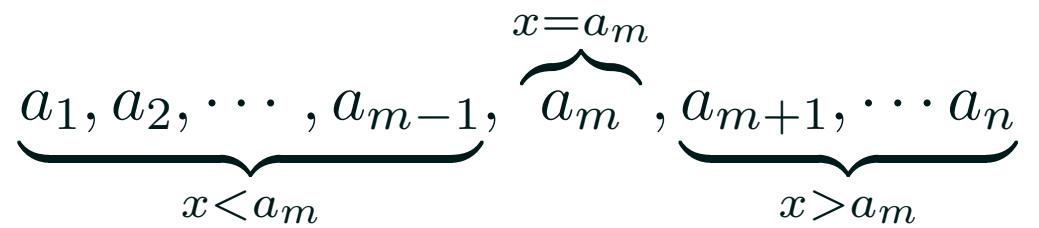
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- If the array is ordered we can do better
- At each step we bisect the array

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★ We check the middle of the array



★ Based on a recursive idea

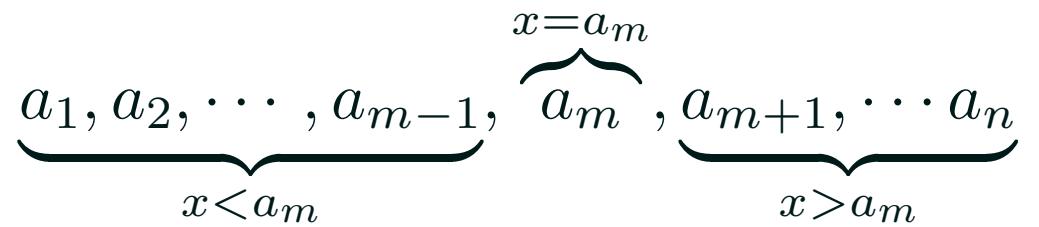
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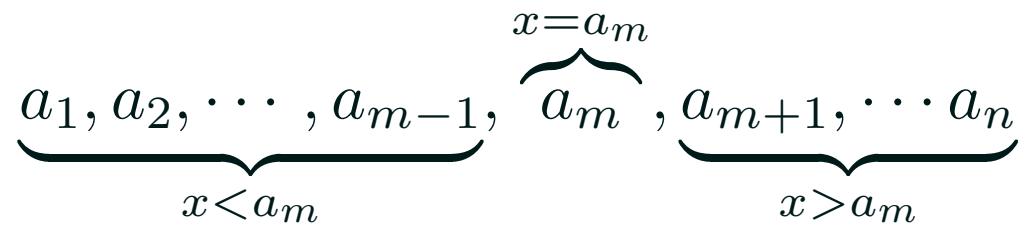
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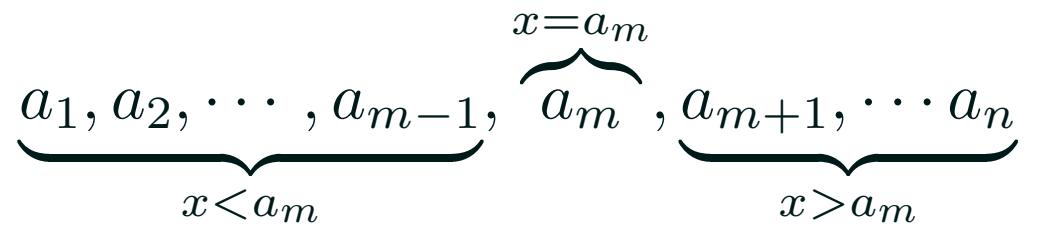
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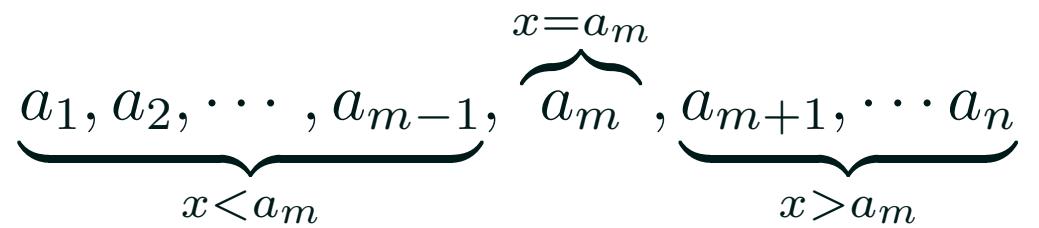
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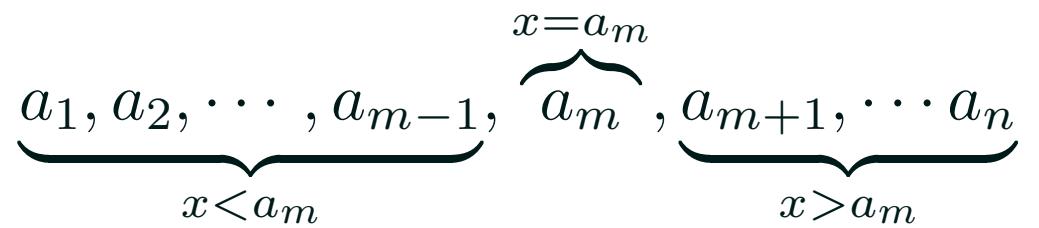
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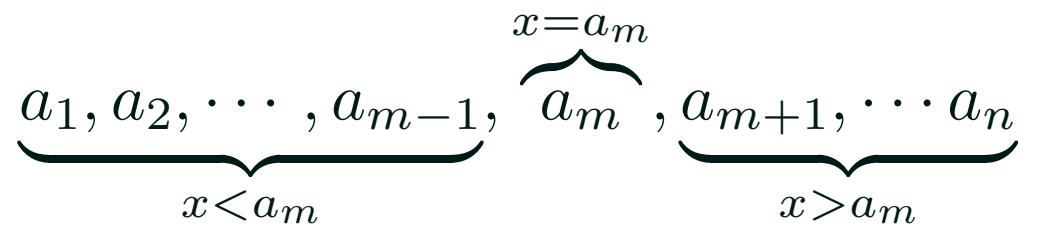
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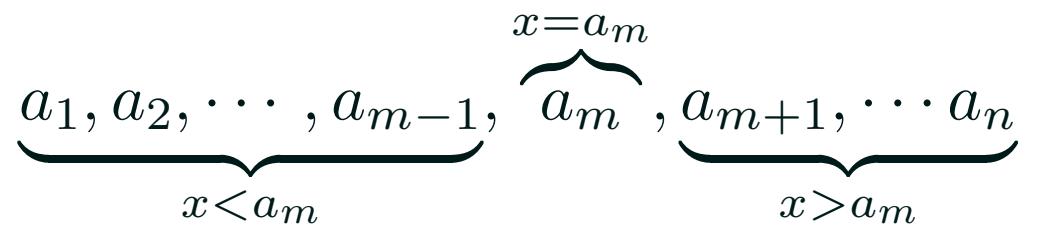
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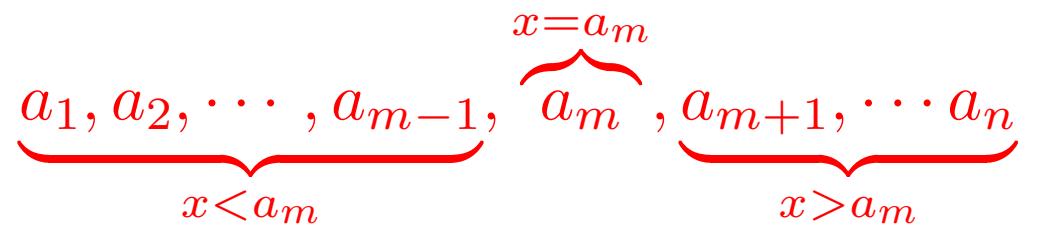
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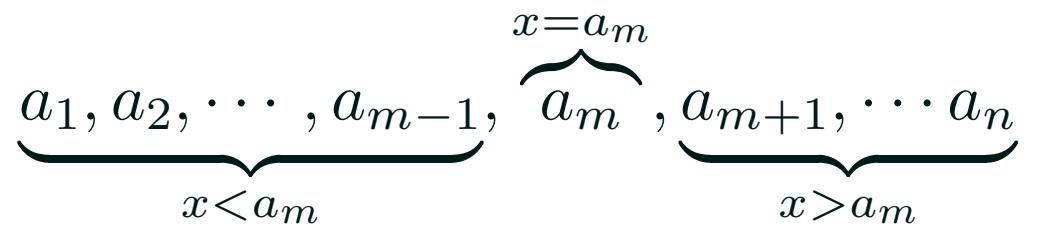
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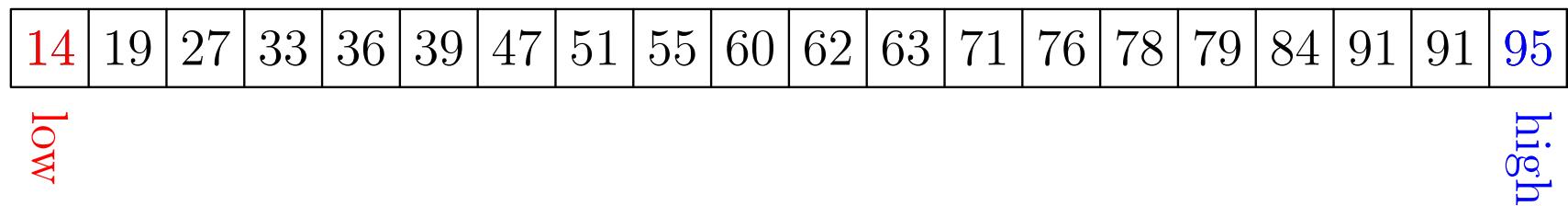
★ Based on a recursive idea

# Binary Search in Action

14	19	27	33	36	39	47	51	55	60	62	63	71	76	78	79	84	91	91	95
----	----	----	----	----	----	----	----	----	----	----	----	----	----	----	----	----	----	----	----

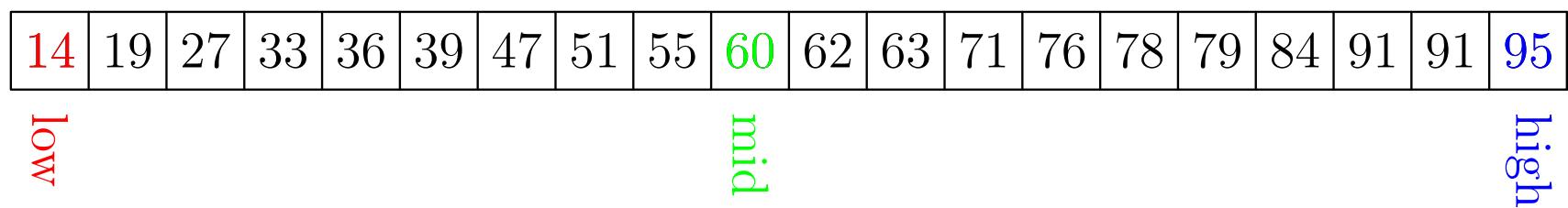
# Binary Search in Action

BINARYSEARCH(**a**, 27)



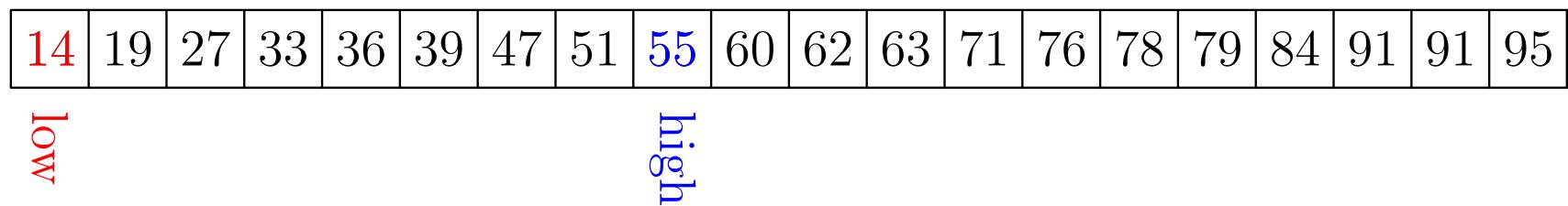
# Binary Search in Action

BINARYSEARCH(**a**, 27)



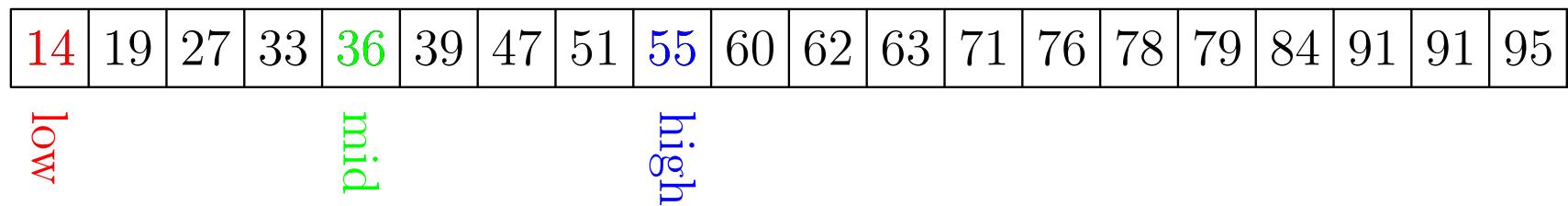
# Binary Search in Action

BINARYSEARCH(**a**, 27)



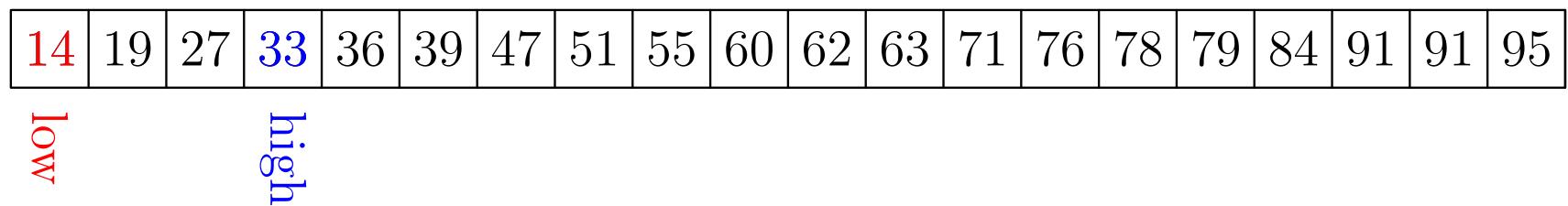
# Binary Search in Action

BINARYSEARCH(**a**, 27)



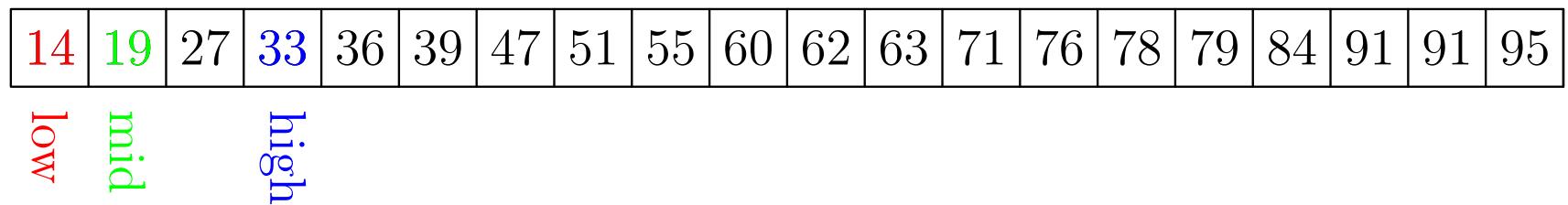
# Binary Search in Action

BINARYSEARCH(**a**, 27)



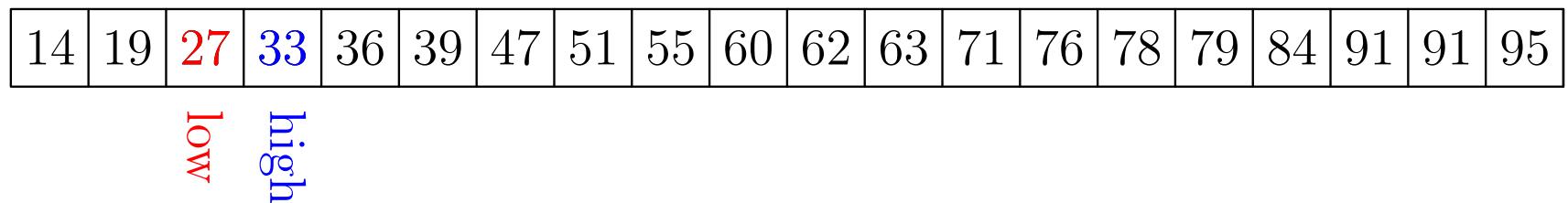
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BINARYSEARCH(**a**, 27)



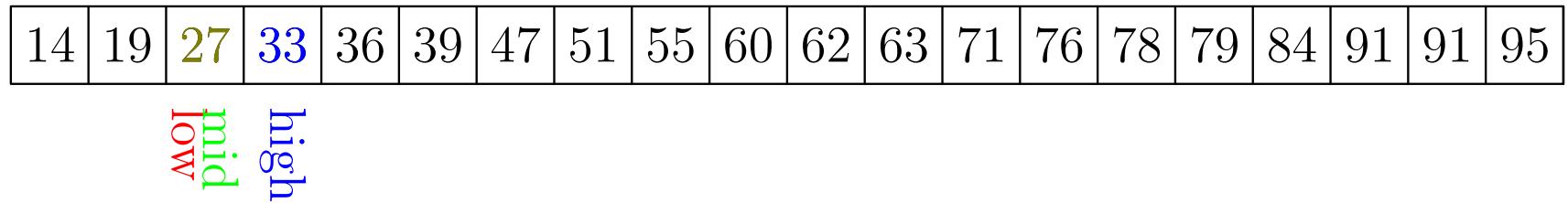
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BINARYSEARCH(**a**, 27)



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BINARYSEARCH(**a**, 27)



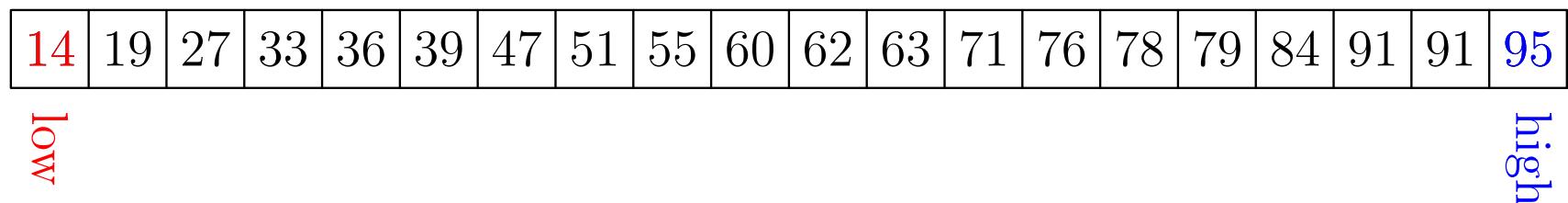
# Binary Search in Action

BINARYSEARCH(**a**, 27)      found

14	19	27	33	36	39	47	51	55	60	62	63	71	76	78	79	84	91	91	95
LOW	mid	high																	

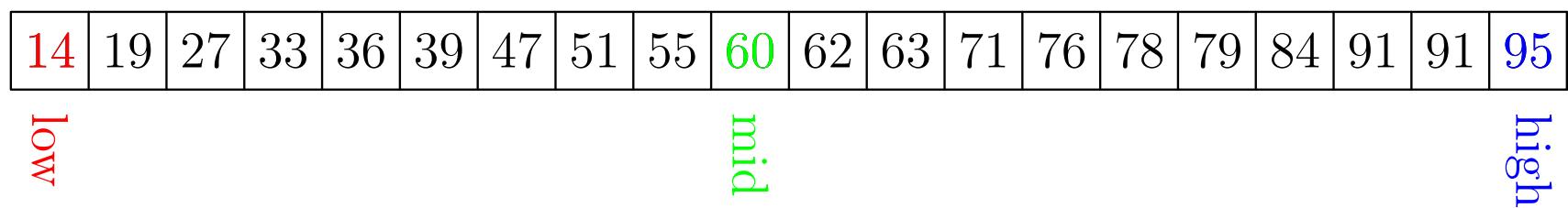
# Binary Search in Action

BINARYSEARCH(**a**, 20)



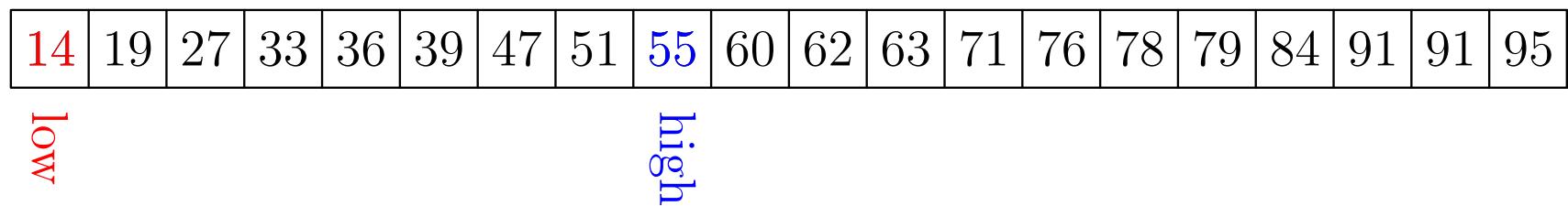
# Binary Search in Action

BINARYSEARCH(**a**, 20)



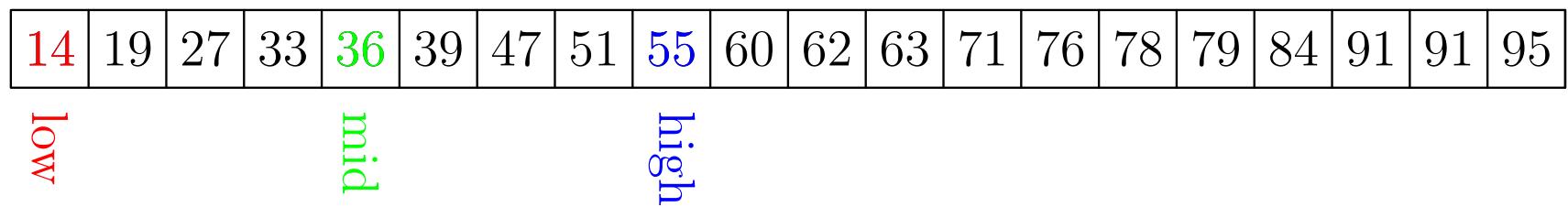
# Binary Search in Action

BINARYSEARCH(**a**, 20)



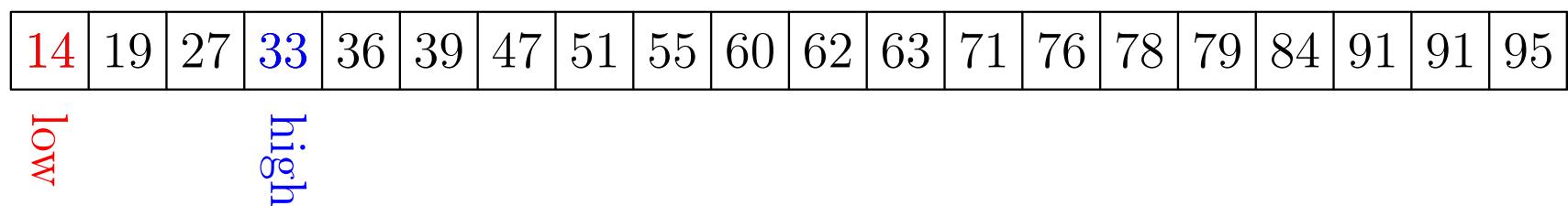
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BINARYSEARCH(**a**, 20)



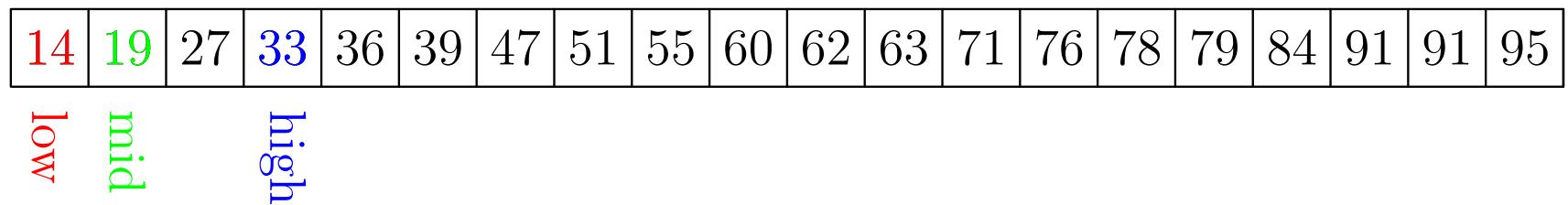
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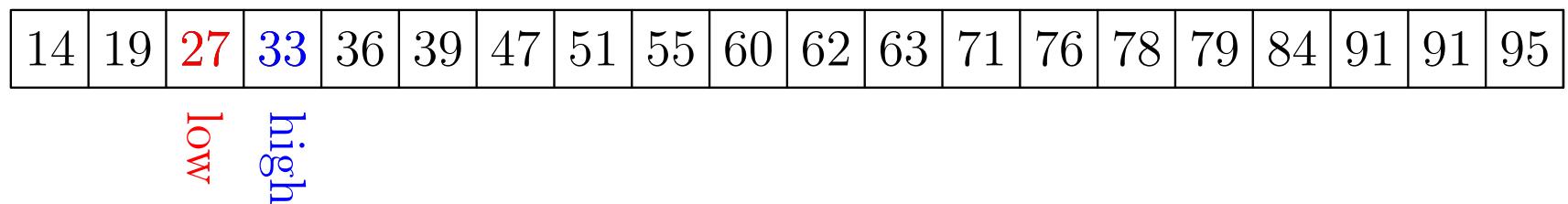
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BINARYSEARCH(**a**, 20)



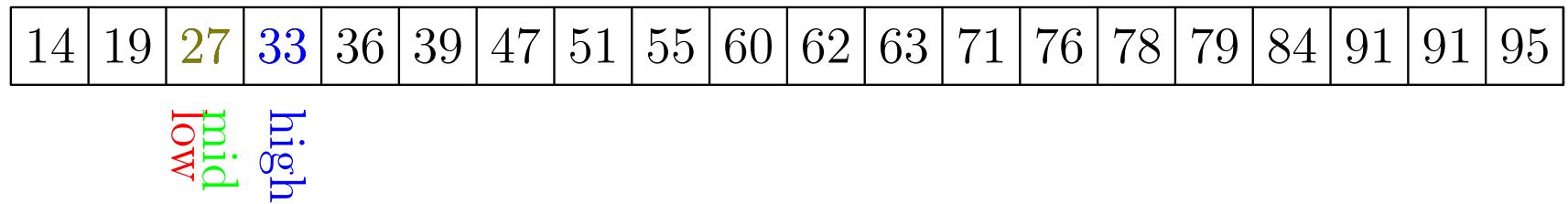
# Binary Search in Action

BINARYSEARCH(**a**, 20)



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BINARYSEARCH(**a**, 20)



# Binary Search in Action

BINARYSEARCH(**a**, 20)

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		high										low							

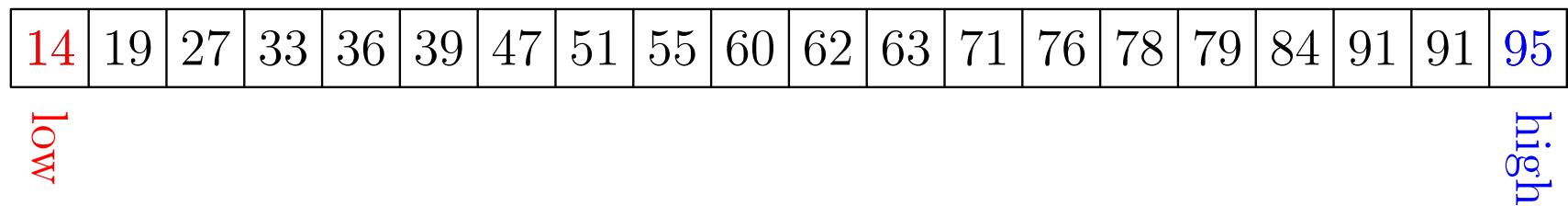
# Binary Search in Action

BINARYSEARCH( $\mathbf{a}$ , 20)      not found

14	19	27	33	36	39	47	51	55	60	62	63	71	76	78	79	84	91	91	95
		high										low							

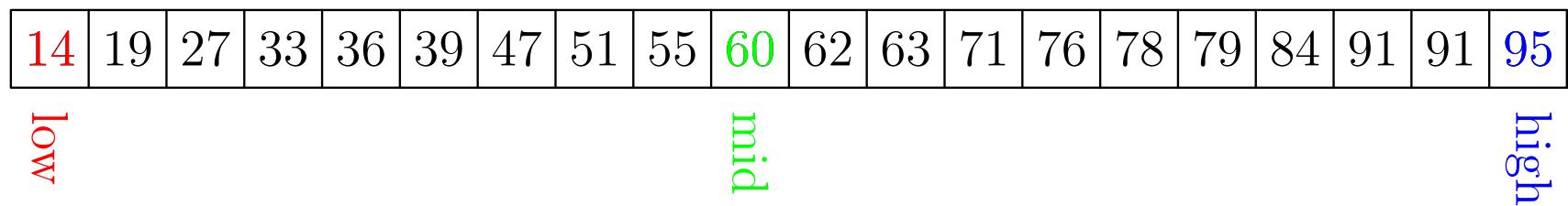
# Binary Search in Action

BINARYSEARCH(**a**, 84)



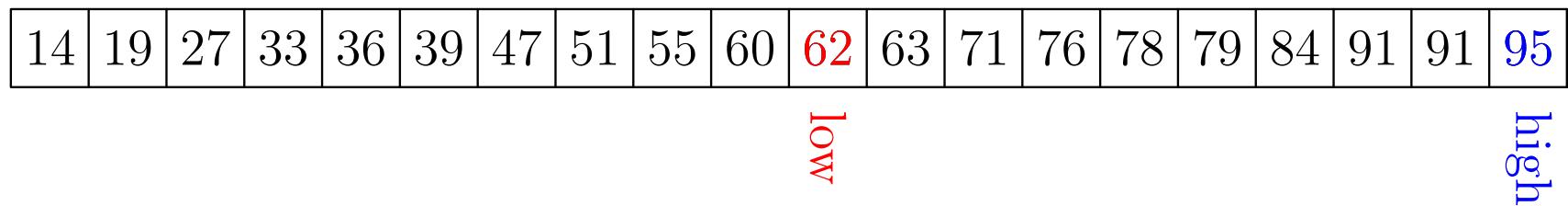
# Binary Search in Action

BINARYSEARCH(**a**, 84)



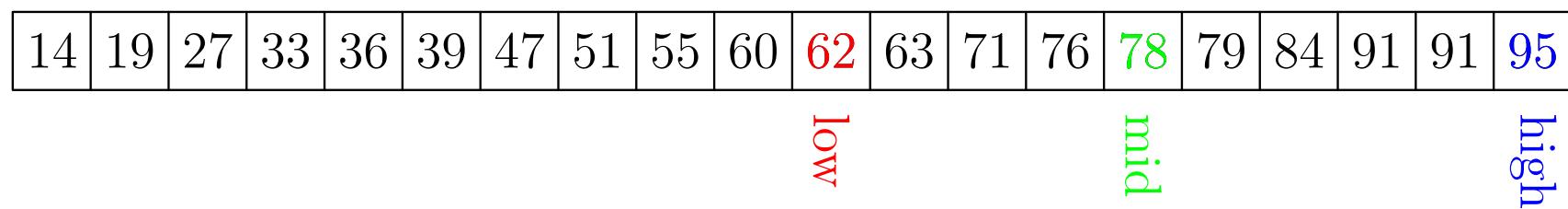
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BINARYSEARCH(**a**, 84)



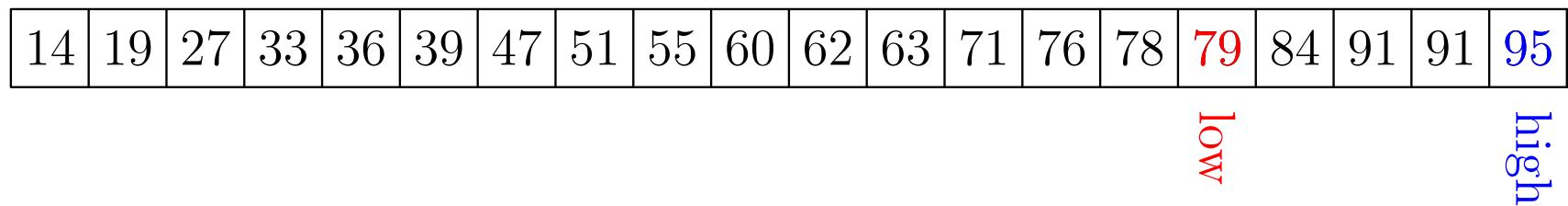
# Binary Search in Action

BINARYSEARCH(a, 84)



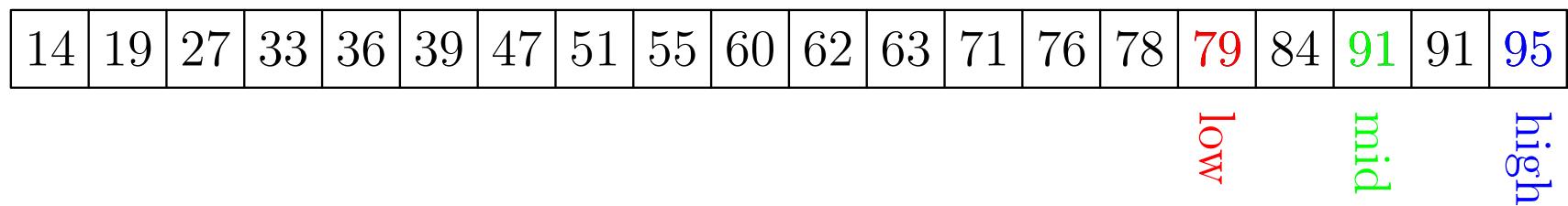
# Binary Search in Action

BINARYSEARCH(**a**, 84)



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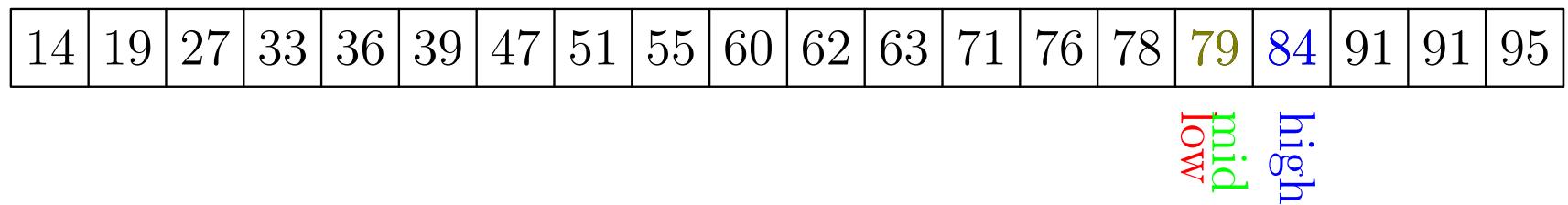


# Binary Search in Action

BINARYSEARCH(a, 84)

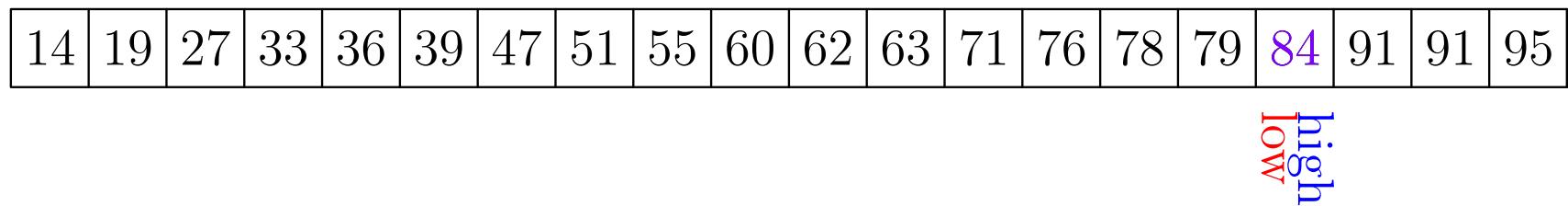
# Binary Search in Action

BINARYSEARCH(**a**, 84)



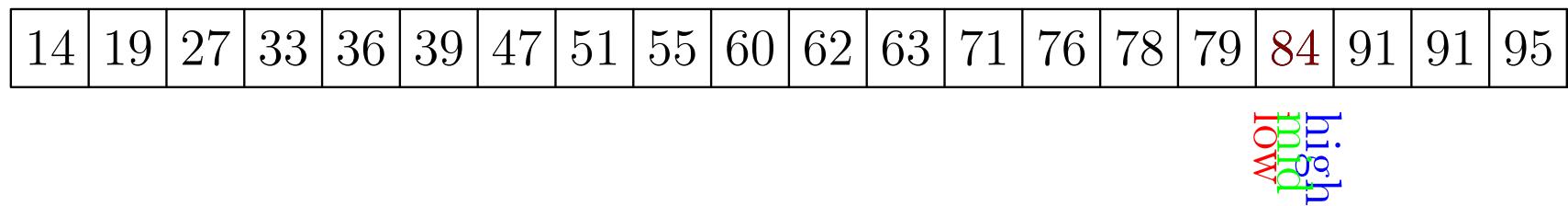
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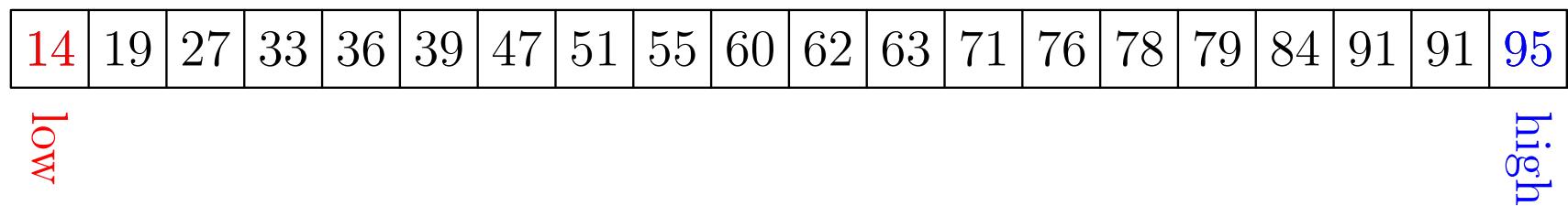
# Binary Search in Action

BINARYSEARCH(**a**, 84)                  found

14	19	27	33	36	39	47	51	55	60	62	63	71	76	78	79	84	91	91	95
																low	high		

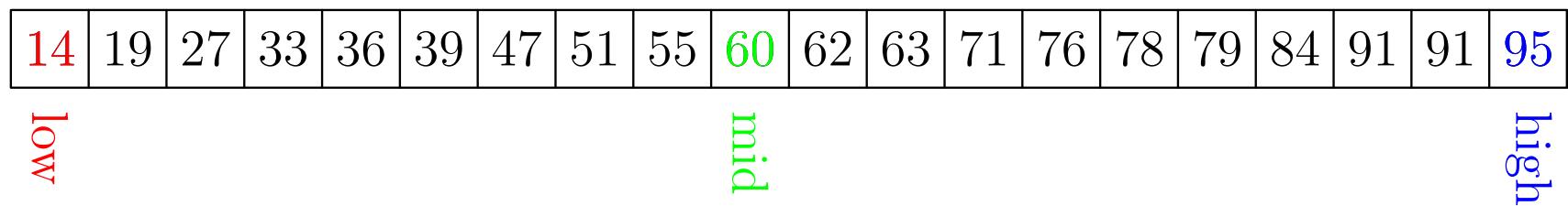
# Binary Search in Action

BINARYSEARCH(**a**, 99)



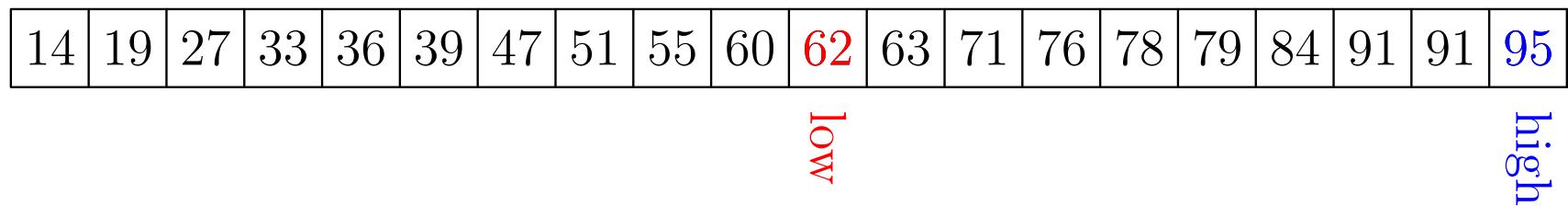
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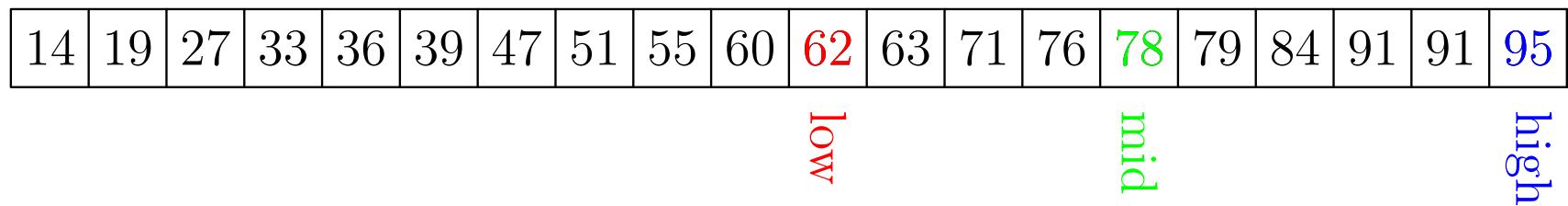
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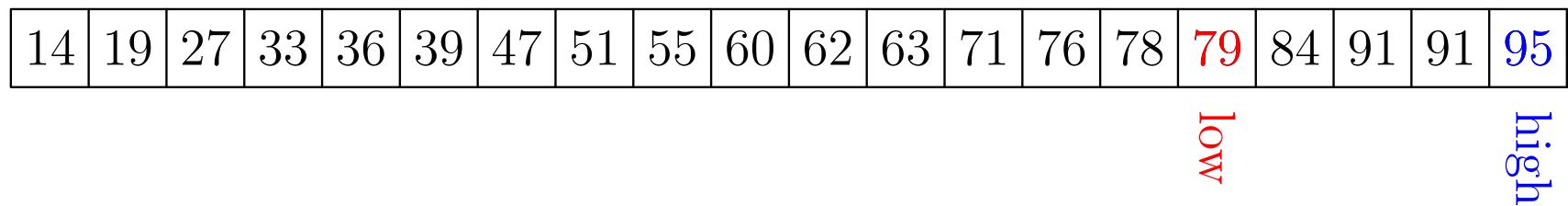
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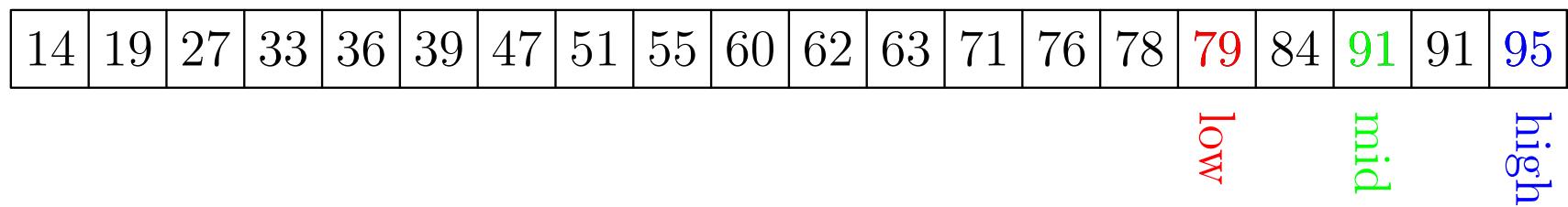
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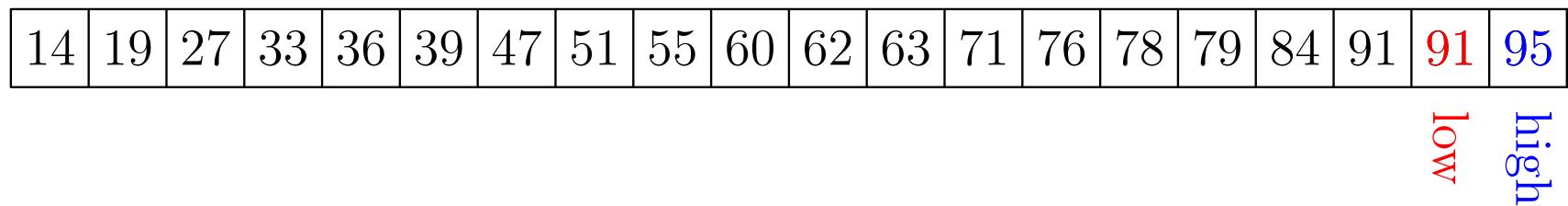
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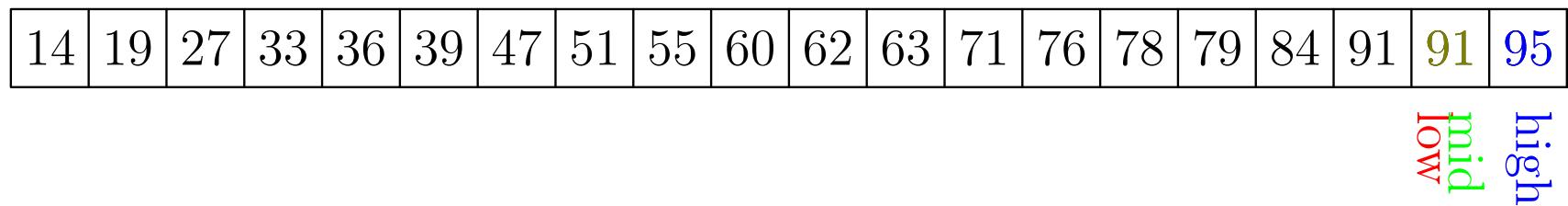
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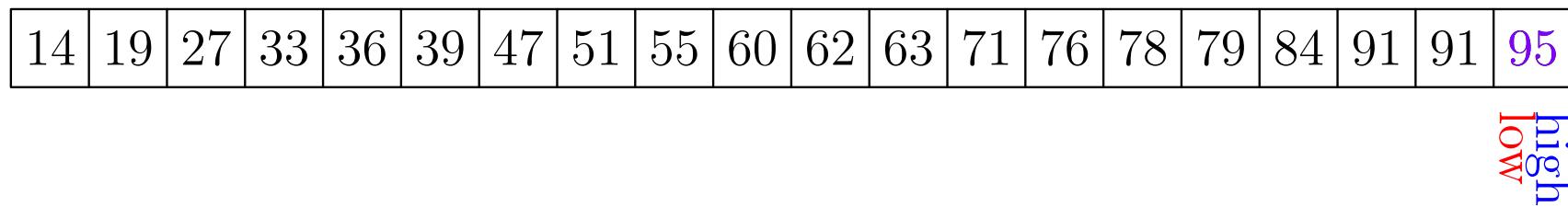
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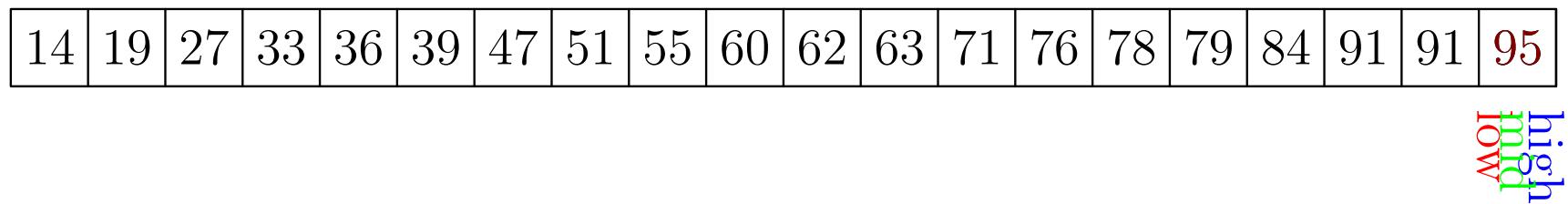
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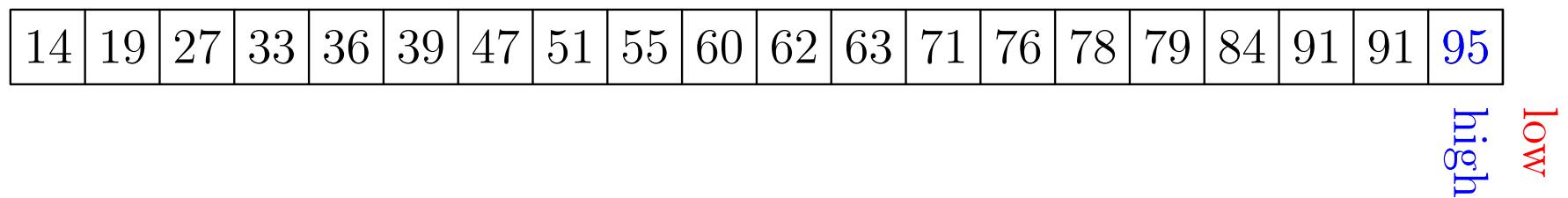
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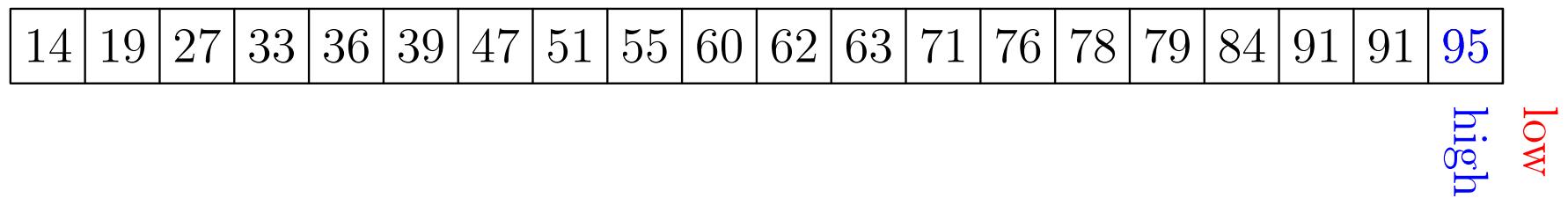
# Binary Search in Action

BINARYSEARCH(**a**, 99)



# Binary Search in Action

BINARYSEARCH(**a**, 99)      not found



# Analysis

- We count the number of comparisons (counting each `if/else if` statement as a single comparison)
- Let  $C(n)$  be the number of comparisons needed to search in an array of size  $n$
- After one comparison we are left (in the worst case) with having to search an array not larger than  $\lfloor n/2 \rfloor$ , thus

$$C(n) < C(\lfloor n/2 \rfloor) + 1$$

- We've seen this relation before (lesson on Recursion)
- Easy to show  $C(n) < \lfloor \log_2(n) \rfloor + 1 = O(\log(n))$

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# Outline

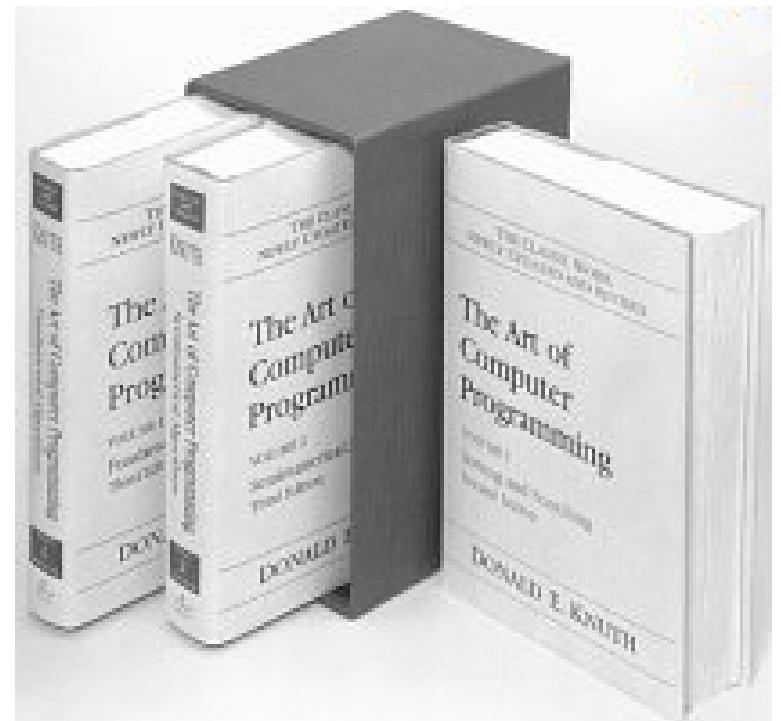
1. Algorithm Analysis

2. Search

3. Simple Sort

- Insertion Sort
- Selection Sort

4. Lower Bound



# Sort Characteristics

- Sort is one of the best studied algorithms. We care about stability, space and time complexity
- A sort algorithm is said to be **stable** if it does not change the order of elements that have the same value
- Space Complexity. Sort is said to be
  - ★ **In-place** if the memory used is  $O(1)$
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  - ★ Worst case
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# Insertion Sort

- In insertion sort we keep a subsequence of elements on the left in sorted order
- This subsequence is increased by *inserting* the next element into its correct position

```
INSERTIONSORT (a)
{
    for i $\leftarrow$ 2 to n
        v $\leftarrow$ ai
        j $\leftarrow$ i-1
        while j  $\geq$  1 and aj $>$ v
            aj+1 $\leftarrow$ aj
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66	37	23	69	74	90	39	84	69	50
----	----	----	----	----	----	----	----	----	----

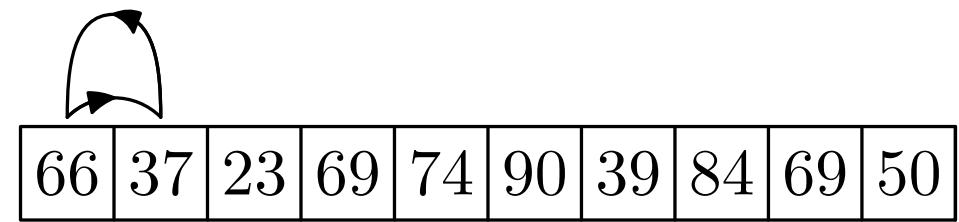
sorted

unsorted

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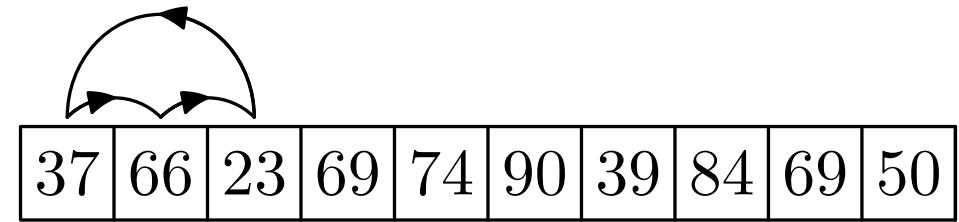
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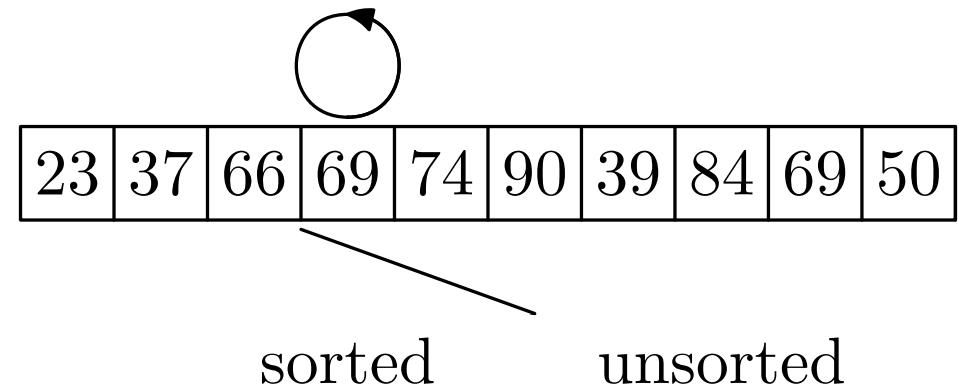
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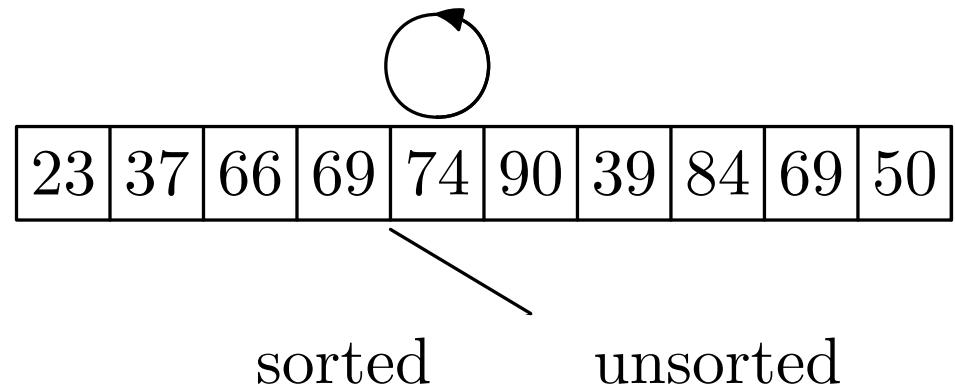
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- In insertion sort we keep a subsequence of elements on the left in sorted order
- This subsequence is increased by *inserting* the next element into its correct position

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INSERTIONSORT (a)
{
    for i $\leftarrow$ 2 to n
        v $\leftarrow$ ai
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        while j  $\geq$  1 and aj>v
            aj+1 $\leftarrow$ aj
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        endwhile
        aj+1 $\leftarrow$ v
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}
```

23	37	66	69	74	90	39	84	69	50
----	----	----	----	----	----	----	----	----	----

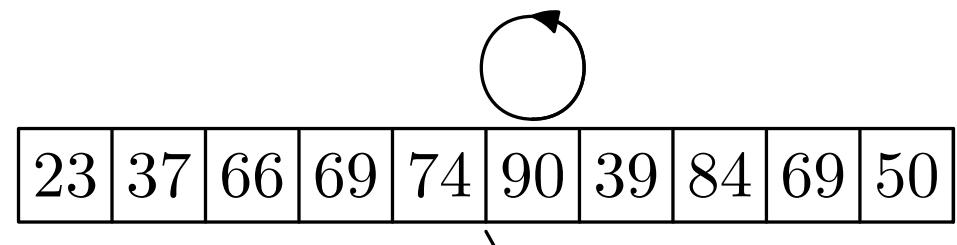
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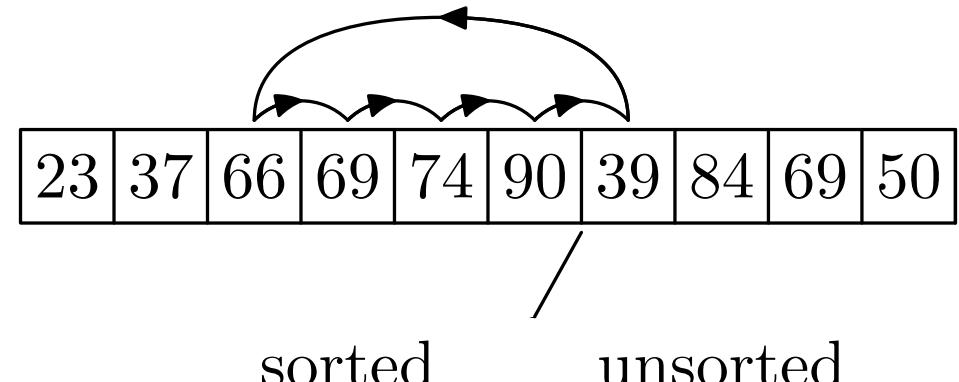
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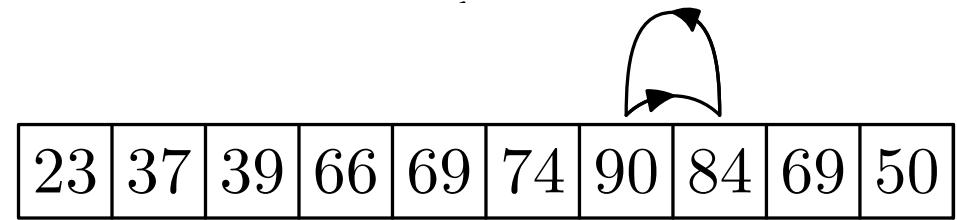
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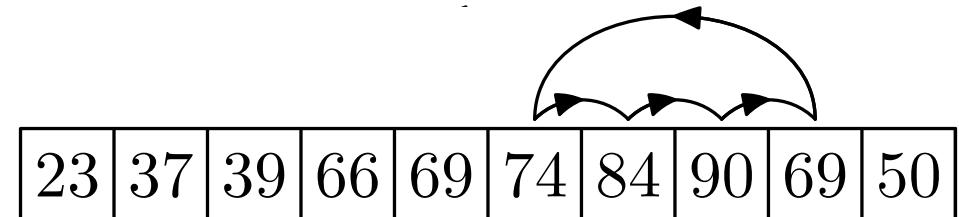
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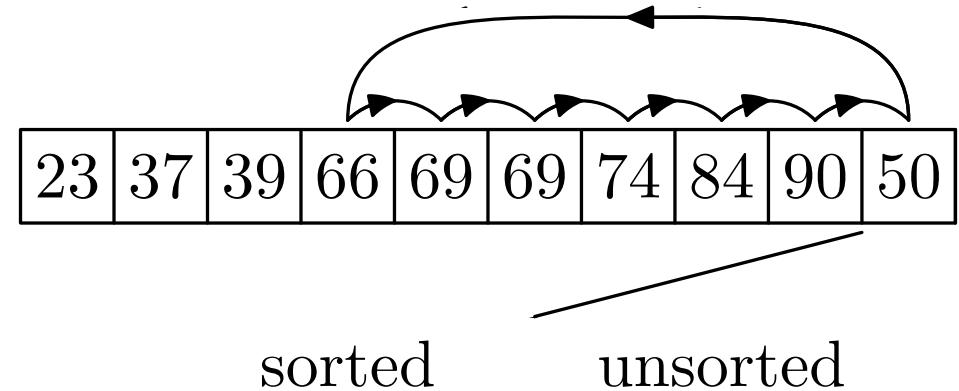
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# Properties of Insertion Sort

- Insertion sort is **stable**. We only swap the ordering of two elements if one is strictly less than the other
- It is **in-place**
- Worst time complexity
  - ★ Occurs when the array is in inverse order
  - ★ Every element has to be moved to front of the array
  - ★ Number of comparisons for an array of size  $C_w(n)$

$$C_w(n) = \sum_{i=2}^n (i - 1) = 1 + 2 + \dots + n - 1 = \frac{n(n - 1)}{2} \in \Theta(n^2)$$

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# Time Complexity

- Average Time Complexity

- ★ On average we can expect that each new element being sorted moves half the way down sorted list
- ★ This gives us an average time complexity,  $C_a(n)$  of half the worst time

$$C_a(n) = \frac{n(n - 1)}{4} \in \Theta(n^2)$$

- Best Time Complexity

- ★ This occurs if the array is already sorted
- ★ In this case we only need  $C_b(n) = n - 1 \in \Theta(n)$  comparisons
- Insertion sort is a good sort for small arrays because it is stable, in-place and is efficient when the arrays are almost sorted

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# Selection Sort

- A more direct **brute force** method is to find the least element iteratively
- We can make this an in-place method by swapping the least element with the first element, the second least element with the second element, etc.

```
SELECTIONSORT(a)
{
    for i  $\leftarrow$  1 to n-1
        min  $\leftarrow$  i
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41	82	30	83	58	84	40	33	83	63
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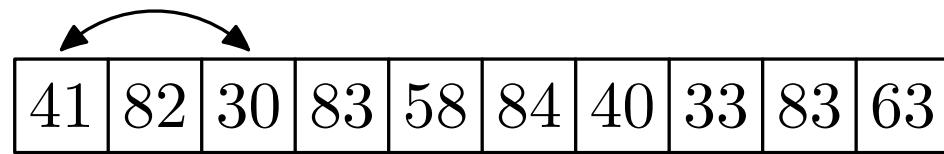
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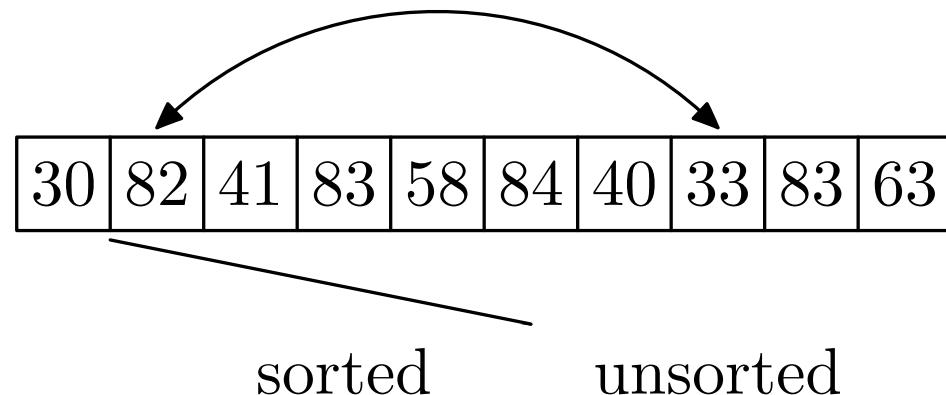
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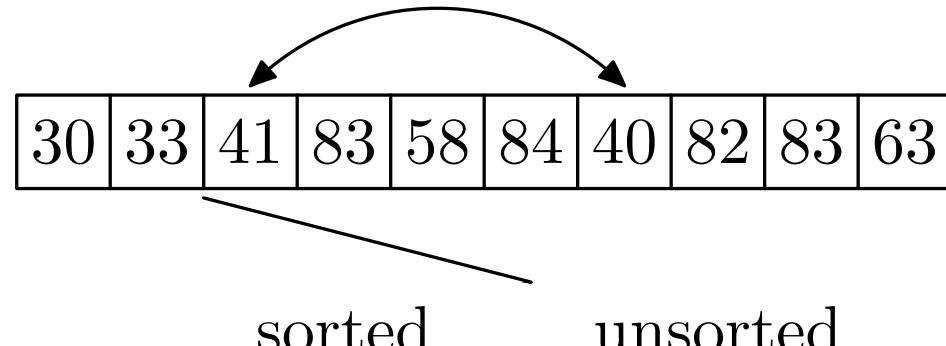
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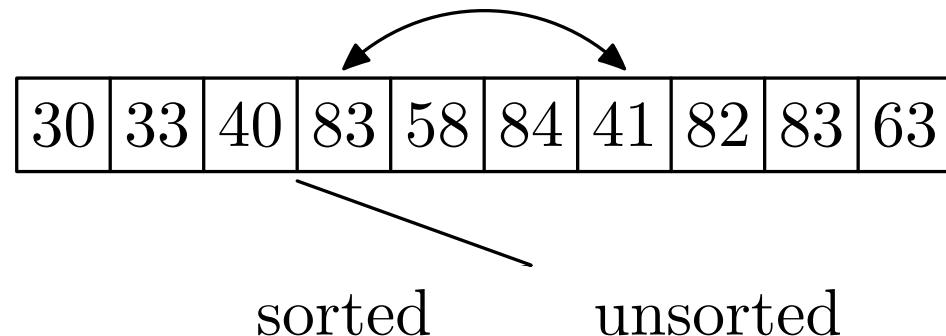
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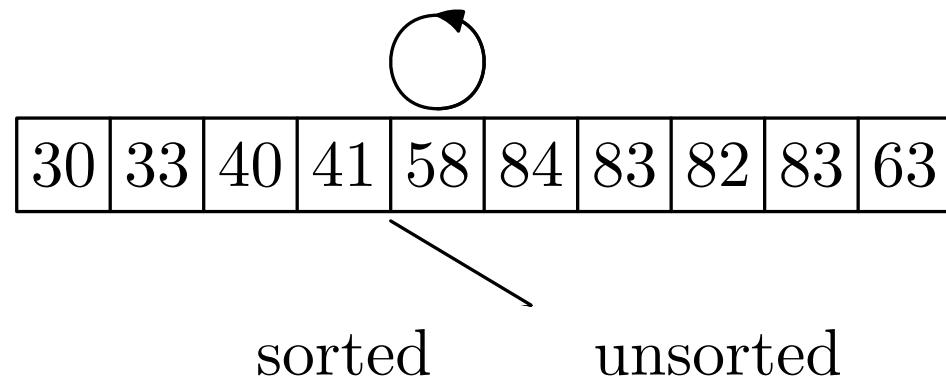
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unsorted

# Selection Sort

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30	33	40	41	58	84	83	82	83	63
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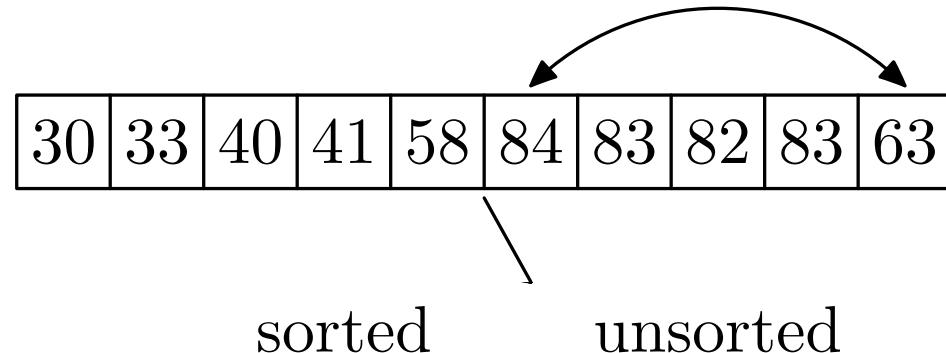
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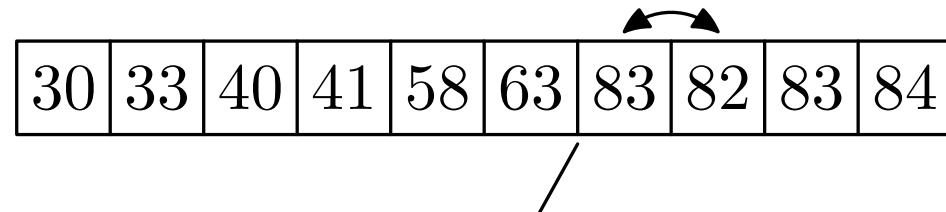
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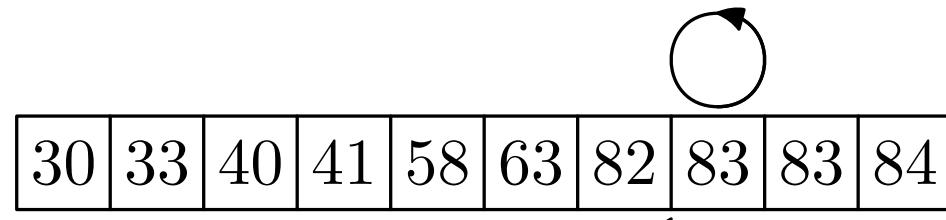
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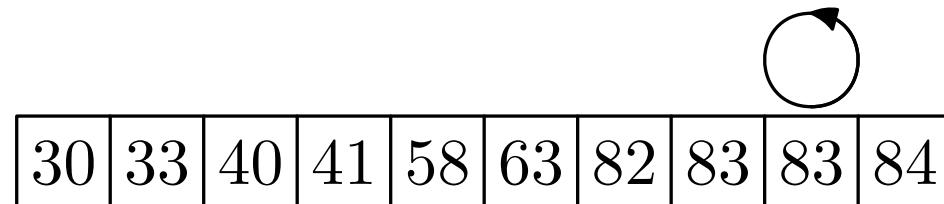
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# Analysis of Selection Sort

- Selection sort is in-place
- It isn't stable



- Selection sort always requires  $n(n - 1)/2$  comparisons so has the same worst case, but worse average case and best case complexity as insertion sort
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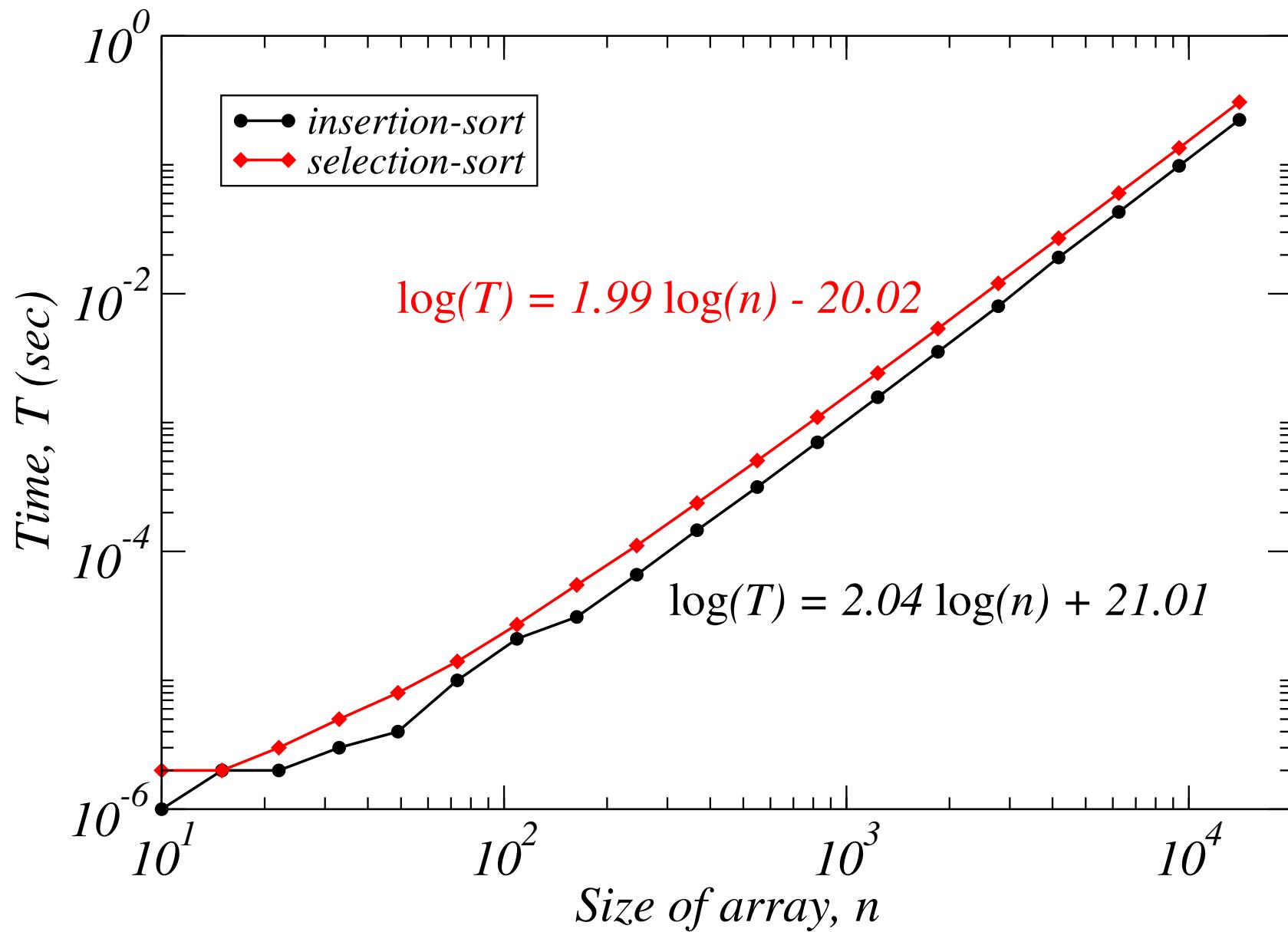
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# Insertion versus Selection Sort



# Bubble Sort

- There are many other simple sort strategies
- One popular one is bubble sort—keep on swapping neighbours until the array is sorted
- It is stable and in-place
- This again has  $O(n^2)$  complexity
- This isn't bad for a simple sort, but it does do more work than insertion sort and selection sort
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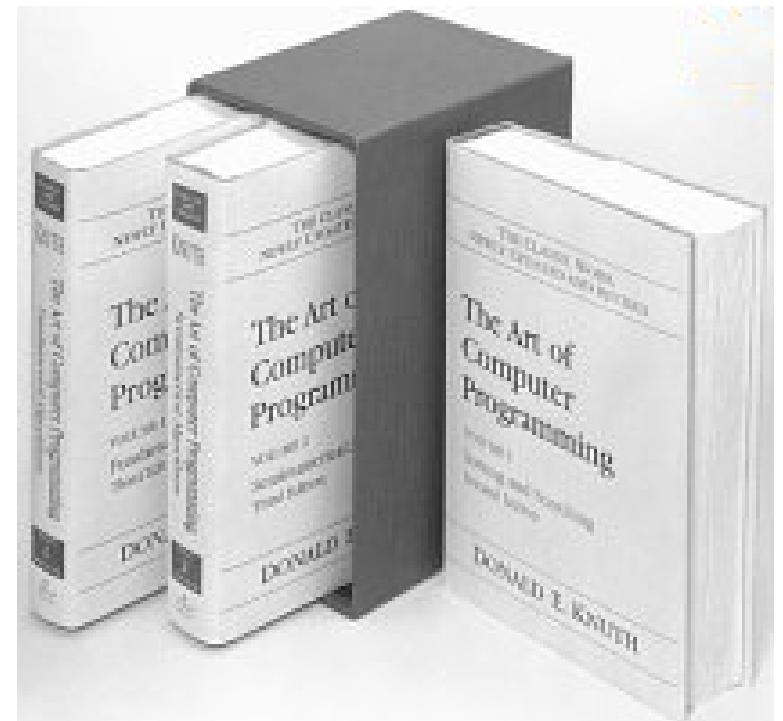
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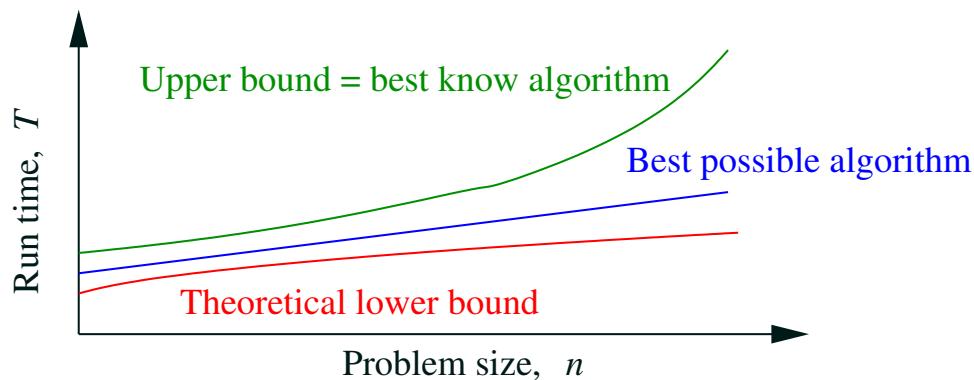
# Outline

1. Algorithm Analysis
2. Search
3. Simple Sort
  - Insertion Sort
  - Selection Sort
4. Lower Bound



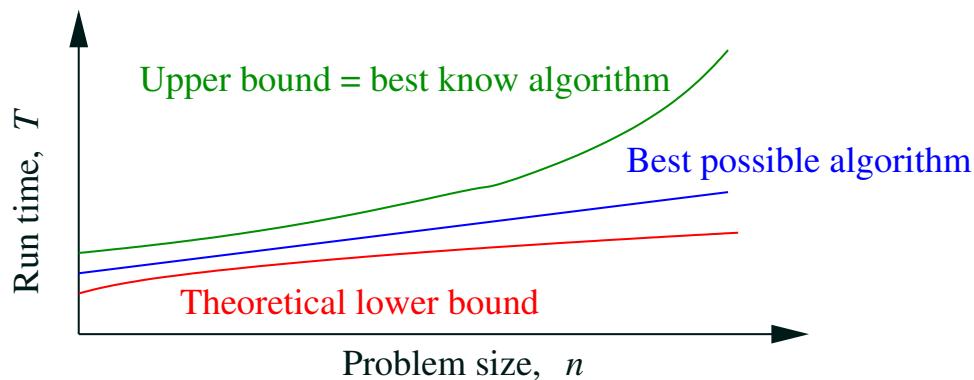
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- Given a problem we would like to know what is the time complexity of the best possible program
- Usually there is no way of knowing this
- We can get an upper bound—if we know the time complexity of any algorithm that solves the problem we have an upper bound
- Lower bounds are far trickier
- A lower bound of  $f(n)$  is a guarantee that we spend at least  $f(n)$  operations to solve the problem



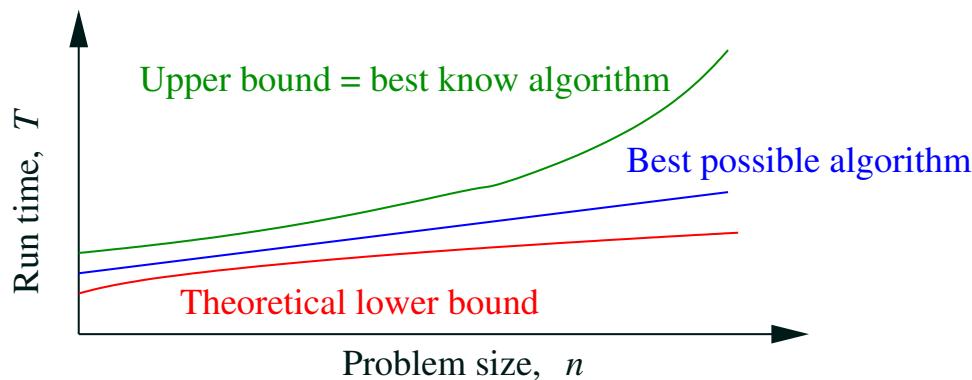
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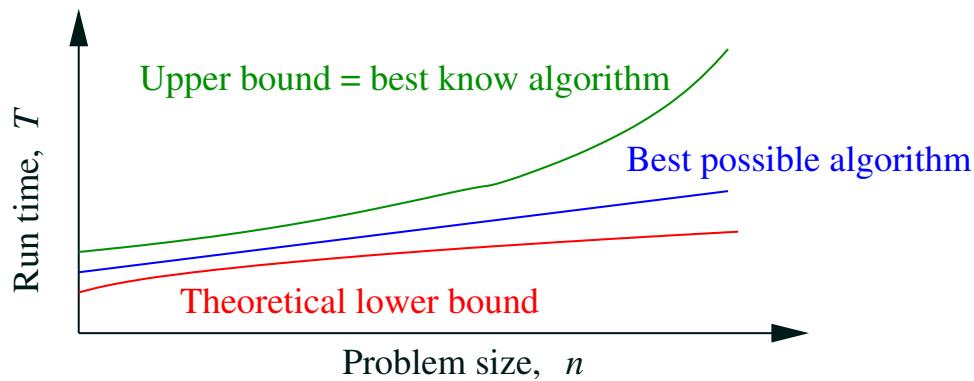
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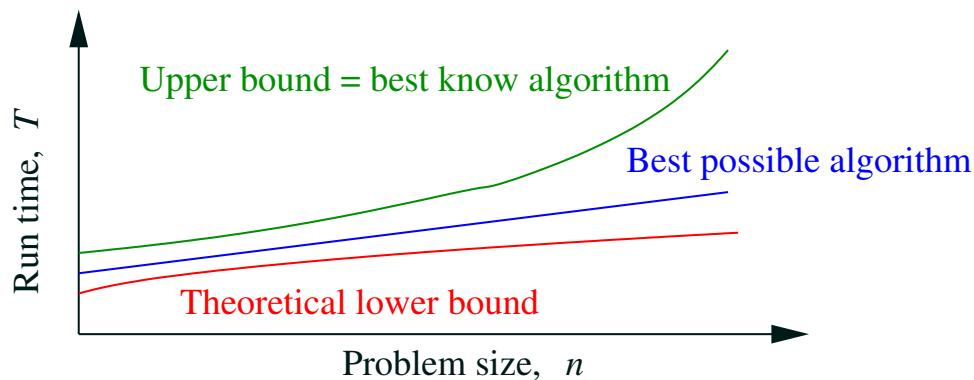
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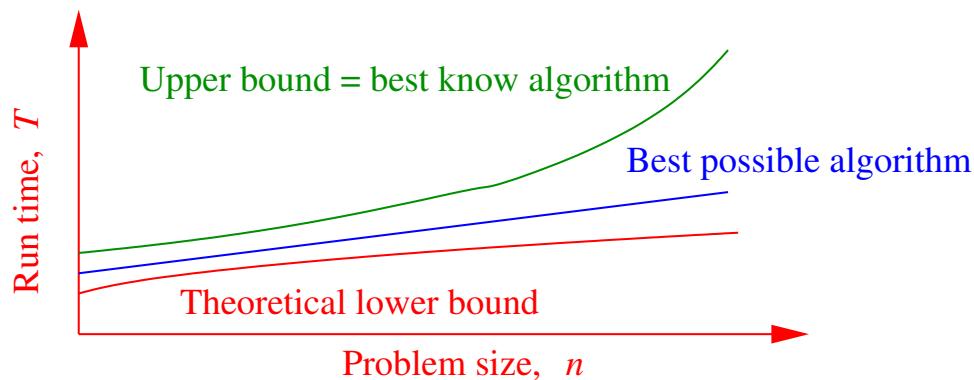
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- Decision trees are a way to visualise (at least, in principle) many algorithms
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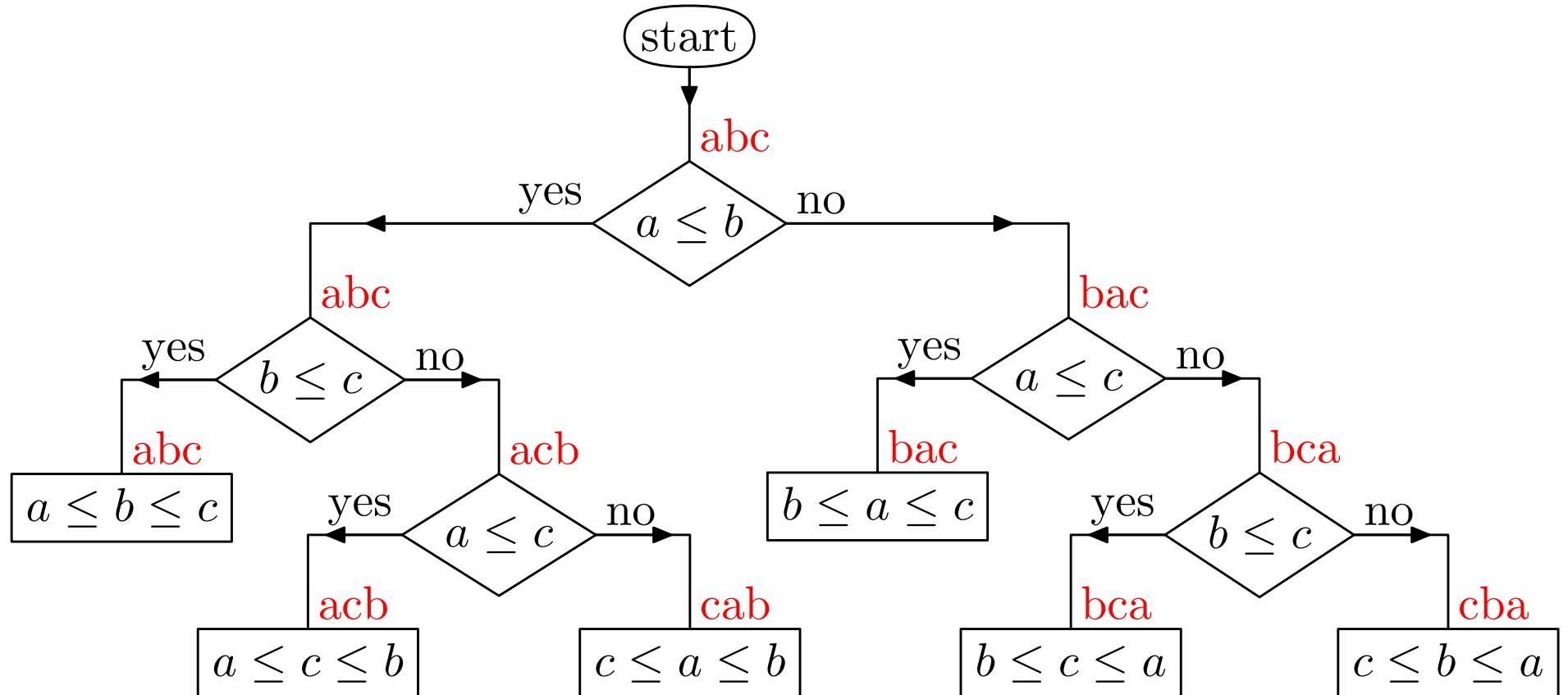
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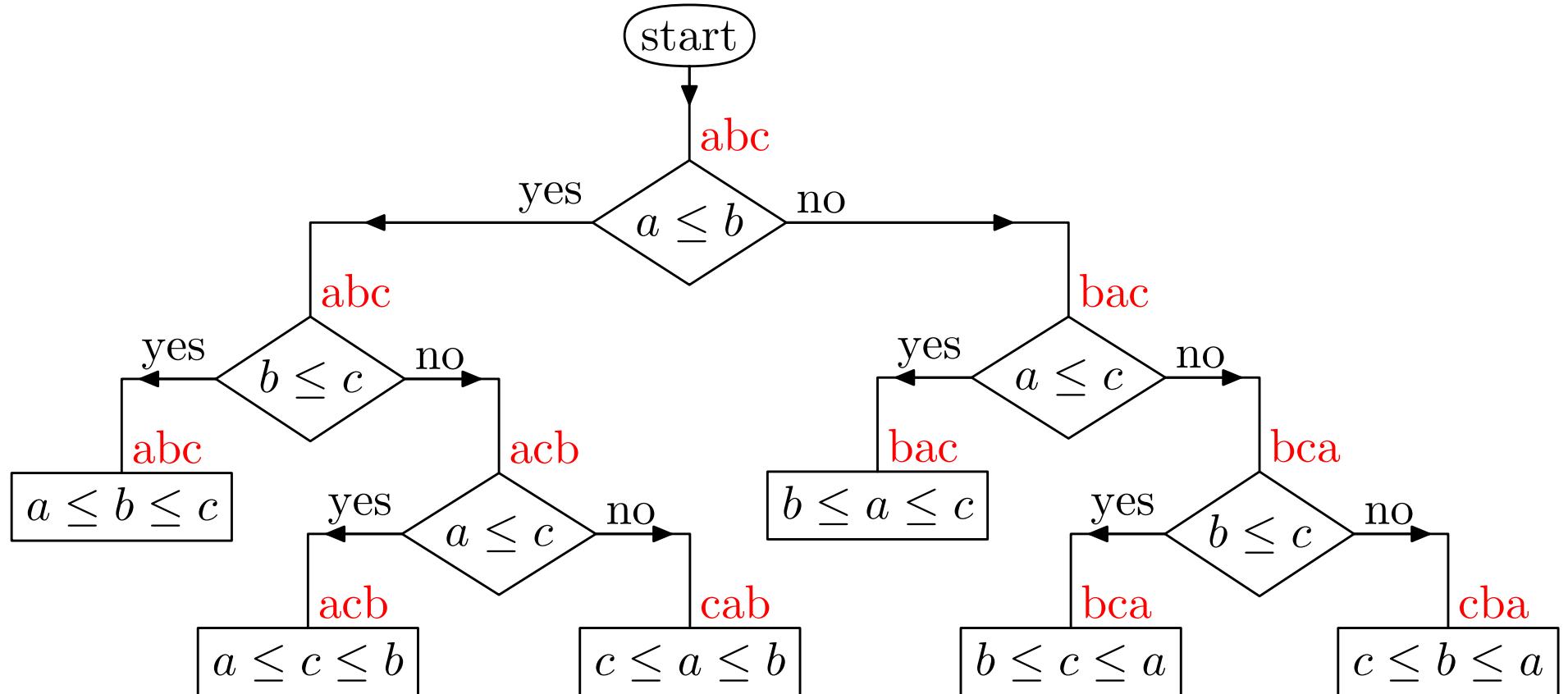
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# Decision Tree for Insertion Sort



- Note there is one leaf for every possible way of sorting the list

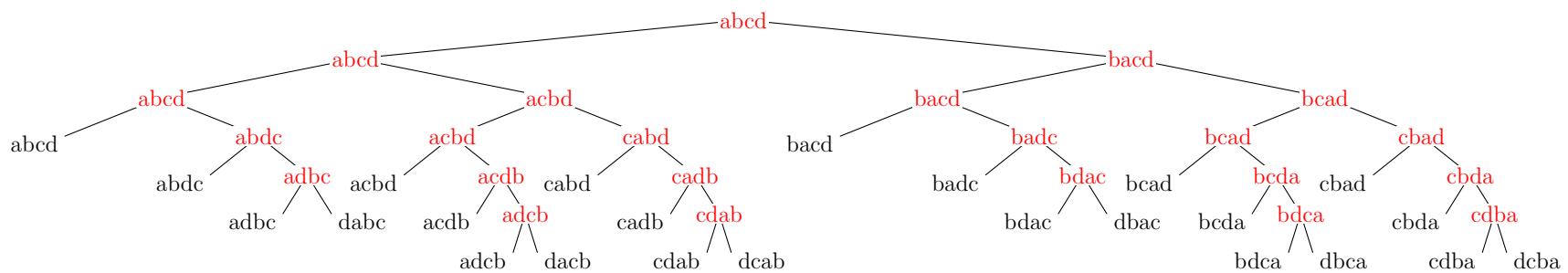
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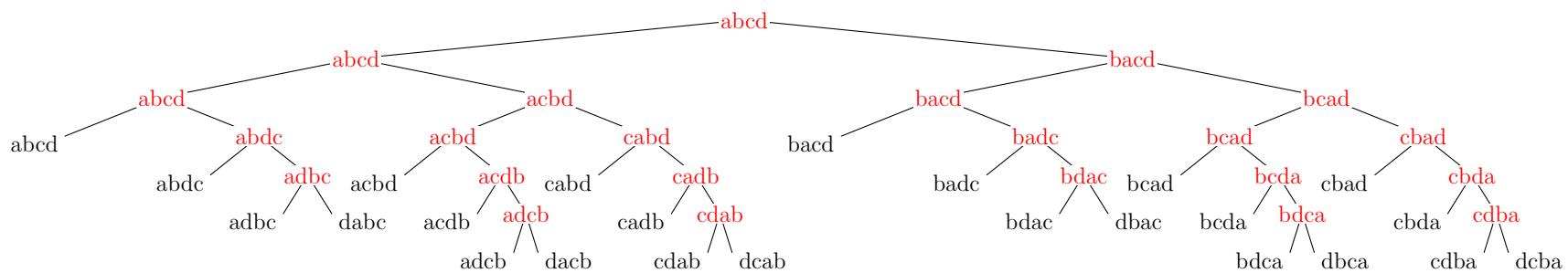
# Decision Trees and Time Complexity

- The time taken to complete the task is the depth of the tree at which we finish (i.e. the leaf nodes)
- We can thus read off the time complexity
  - ★ worst case time: depth of the deepest of leaf
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- Different sort strategies will have different decision trees
- Decision trees are usually far too large to write out ☹



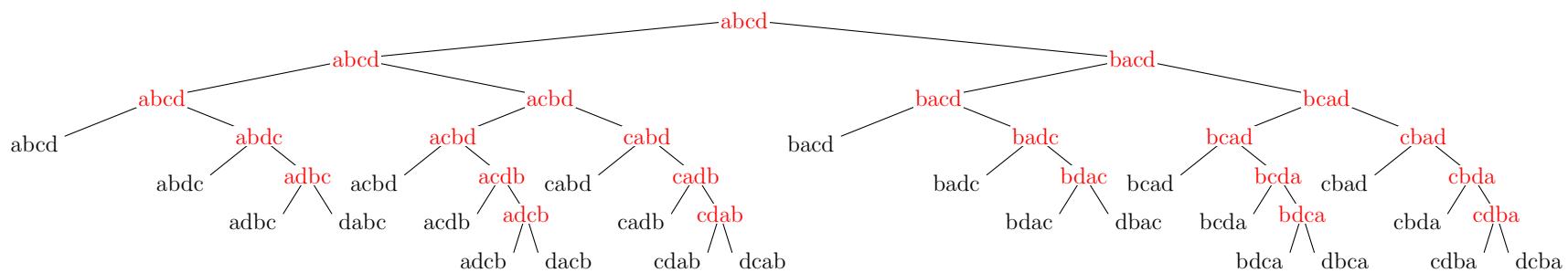
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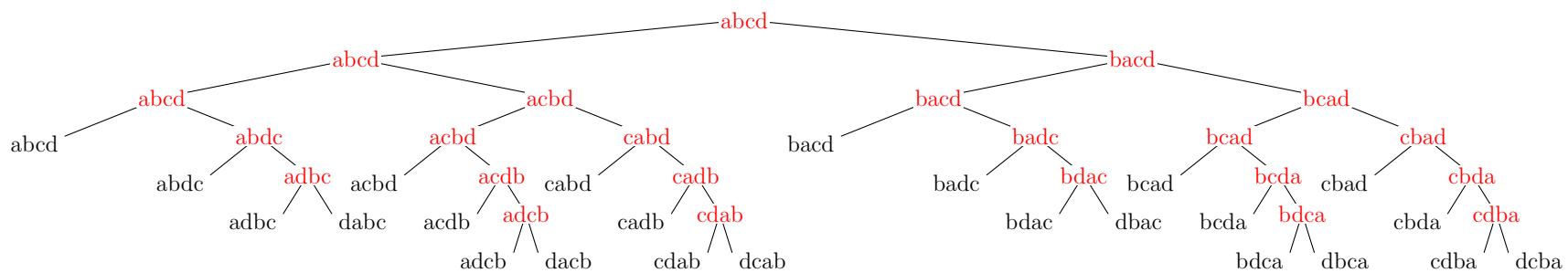
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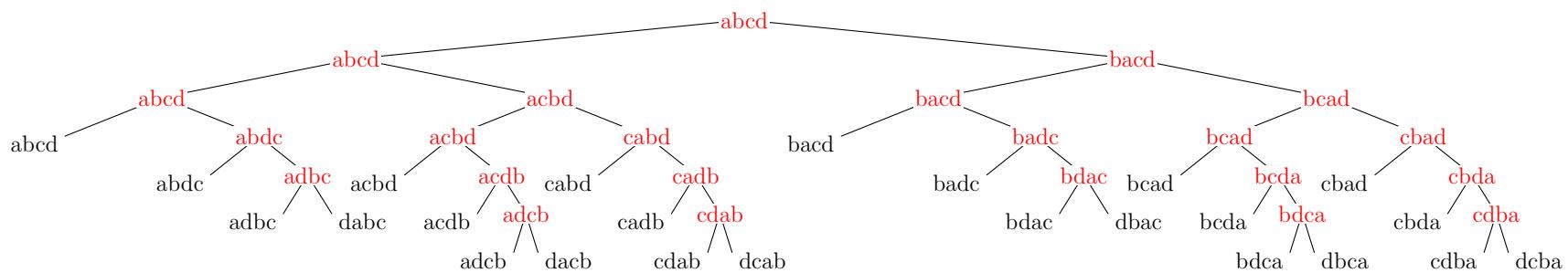
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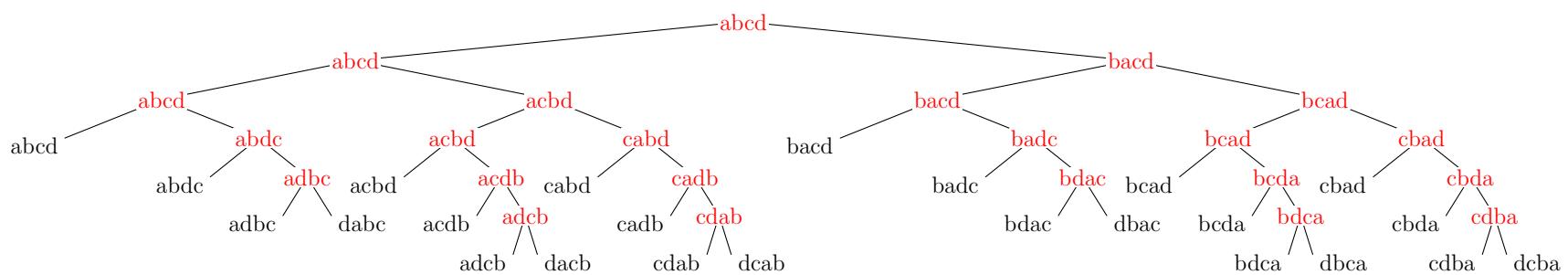
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- Any sort based on binary comparisons must have a leaf of the tree for every possible way of sorting the list
- The array  $[a, b, c]$  must be arranged differently for all combinations

$[1, 2, 3], [1, 3, 2], [2, 1, 3], [2, 3, 1], [3, 1, 2], [3, 2, 1]$

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# Minimum Number of Leaves

- There must be, at least, one leaf node of the decision tree for each possible permutation of the list
- How many permutations are there of a list of size  $n$ ?
- Start with a sequence  $(a_1, a_2, \dots, a_n)$
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- We can choose any of the remaining  $n - 1$  elements of the list as the second element of the permutation
- The total number of permutation is  
$$n \times (n - 1) \times (n - 2) \times \cdots \times 2 \times 1 = n!$$

# Lower Bound Time Complexity for Sorting

- Any sort algorithm using binary comparisons must have a decision tree with at least  $n!$  leaf nodes
- This will be a binary tree with some depth  $d$
- The number of leaves at depth  $d$  is  $2^d$
- Thus the smallest depth tree must have a depth  $d$  such that  $2^d \geq n!$
- That is, the depth of the decision tree satisfies  $d \geq \log_2(n!)$
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# How Big is $\log_2(n!)$

- We showed in the second lecture that

$$\left(\frac{n}{2}\right)^{n/2} < n! < n^n$$

- It is not too difficult to show that asymptotically (i.e. as  $n \rightarrow \infty$ ) that  $n!$  approaches  $\sqrt{2\pi n} \left(\frac{n}{e}\right)^n$ —this is known as **Stirling's approximation**
- Thus

$$\begin{aligned}\log_2(n!) &\approx n \log_2(n) - n \log_2(e) + \frac{\log_2(n)}{2} + \frac{\log_2(2\pi)}{2} \\ &= \Theta(n \log_2(n))\end{aligned}$$

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- We therefore have a lower bound on the time complexity of  $\Omega(n \log(n))$
- This is true for any sort using binary comparisons
- We will see in the next lecture there exists algorithms with time complexity  $O(n \log(n))$
- This means our lower bound is tight—i.e. it is the true cost of the best algorithm
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# Lessons

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