

Algorithms and Analysis

Lesson 8: *Keep Trees Balanced*



AVL trees, red-black trees, TreeSet, TreeMap

Outline

1. **Deletion**
2. Balancing Trees
 - Rotations
3. AVL
4. Red-Black Trees
 - TreeSet
 - TreeMap



Recap

- Binary search trees are commonly used to store data because we need to only look down one branch to find any element
- We saw how to implement many methods of the binary search tree
 - ★ `find`
 - ★ `insert`
 - ★ `successor` (in outline)
- One method we missed was `remove`

Recap

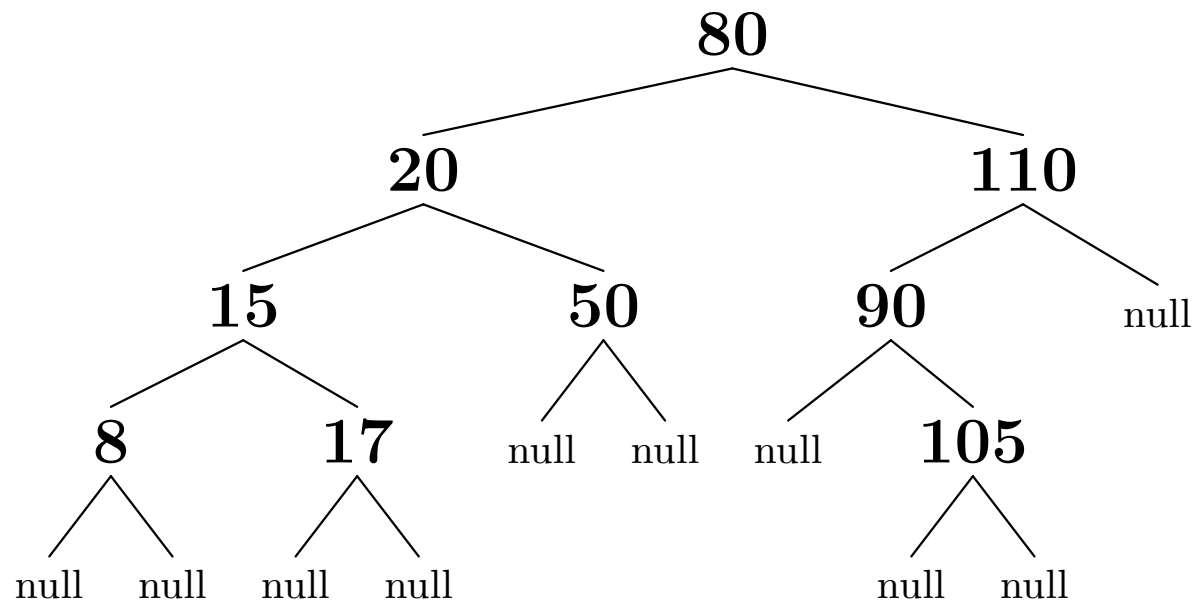
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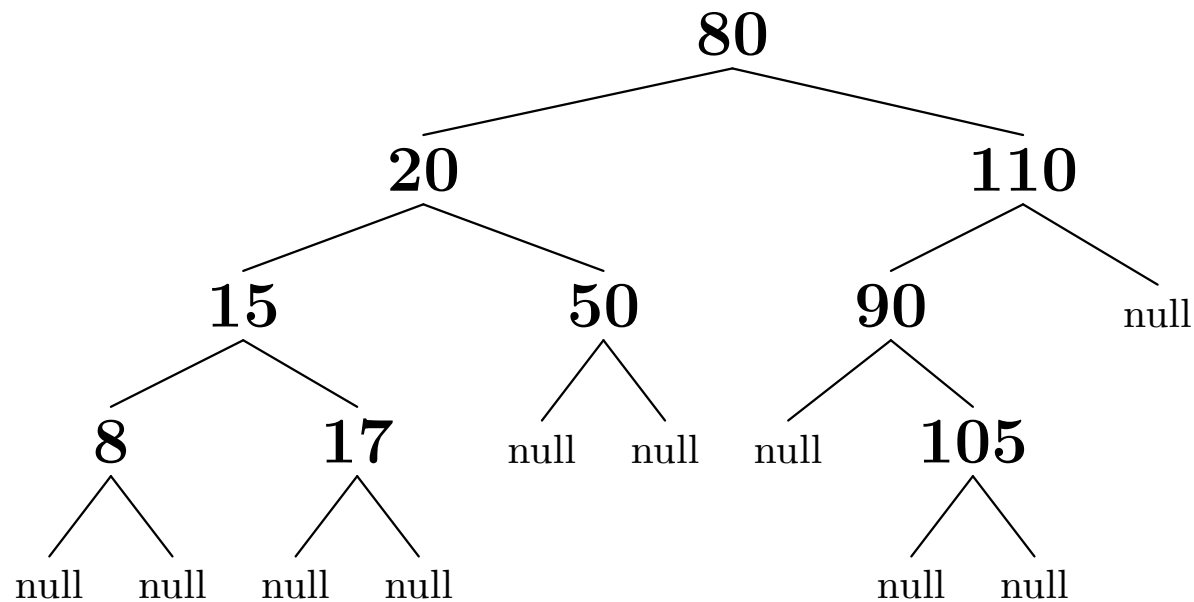
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- Suppose we want to delete some elements from a tree
- It is relatively easy if the element is a leaf node (e.g. 50)
- It is not so hard if the node has one child (e.g. 20)



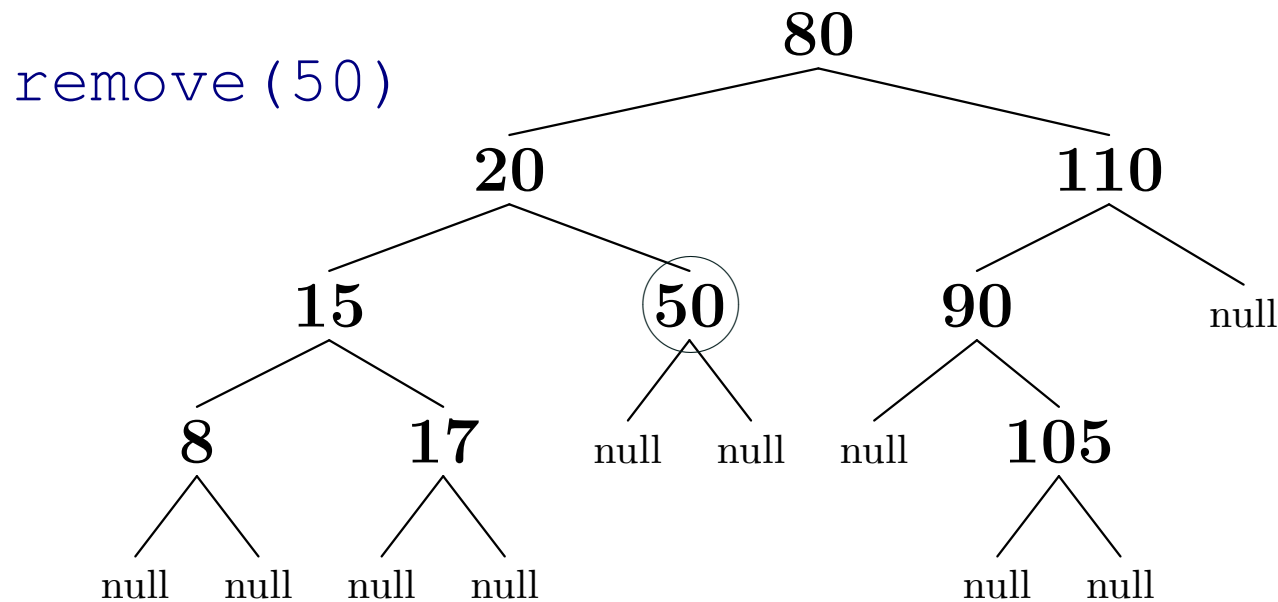
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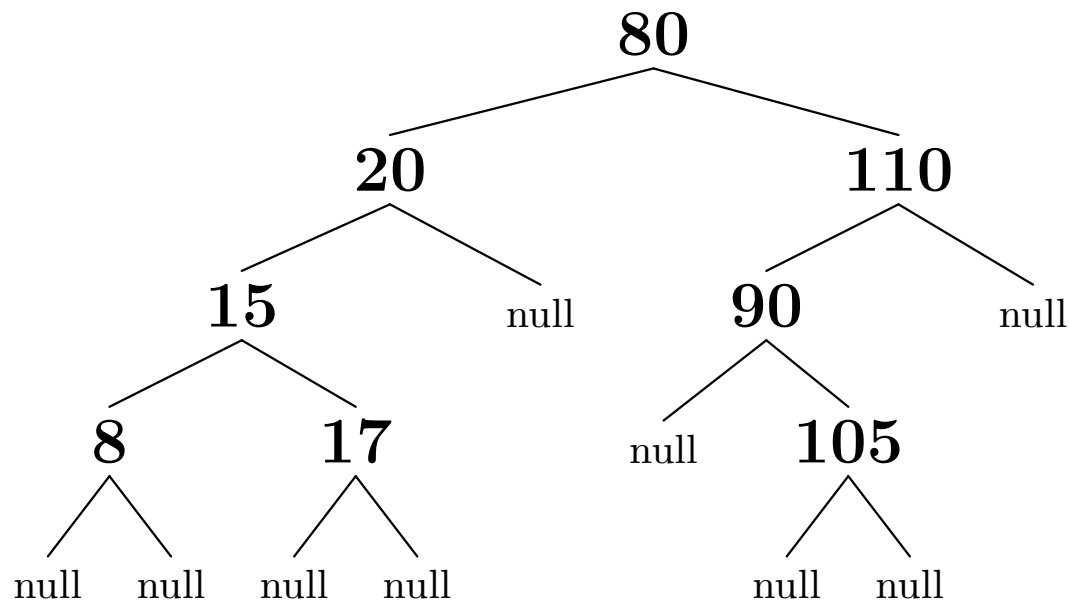
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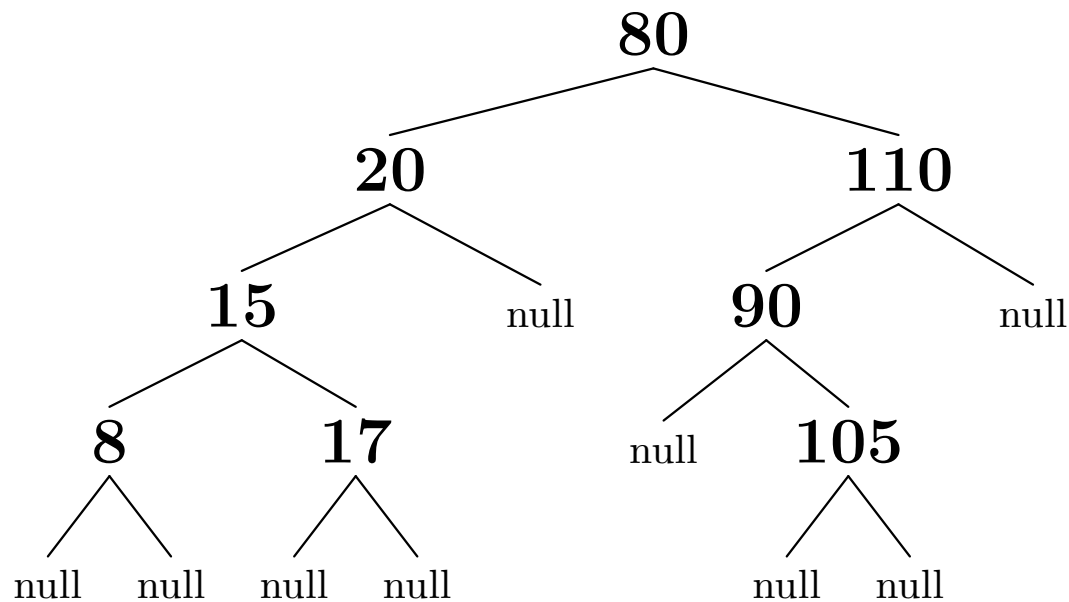
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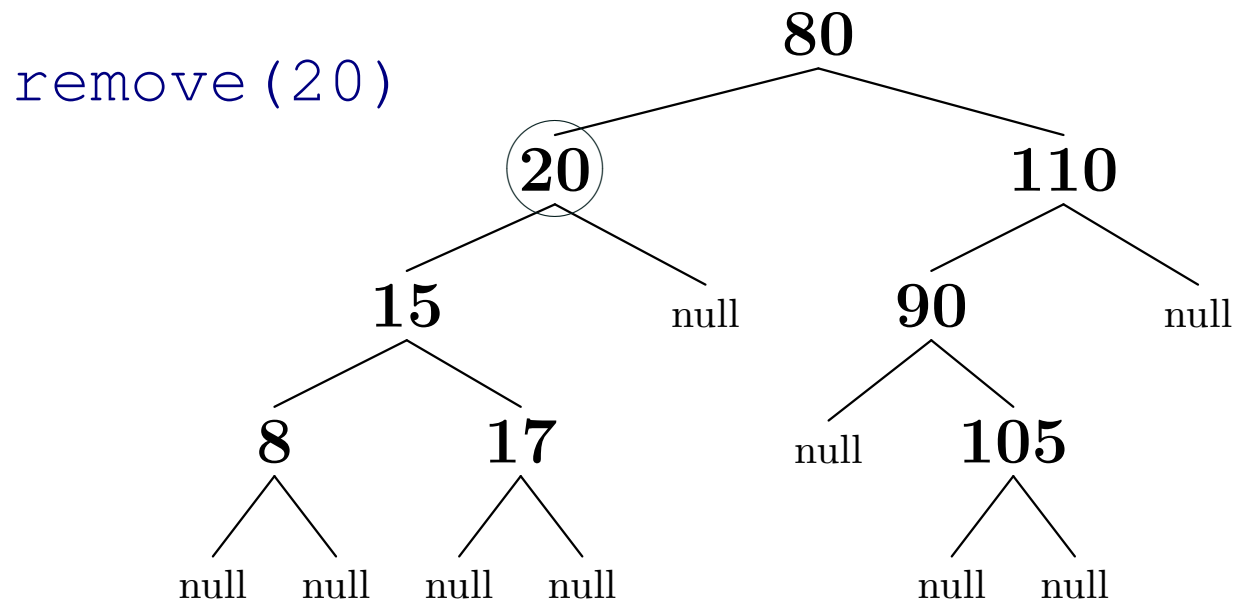
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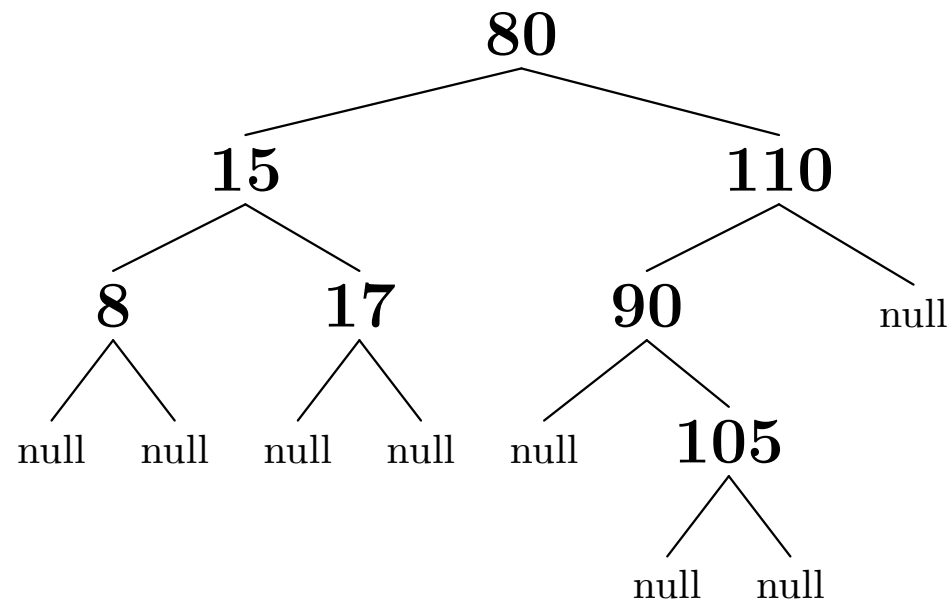
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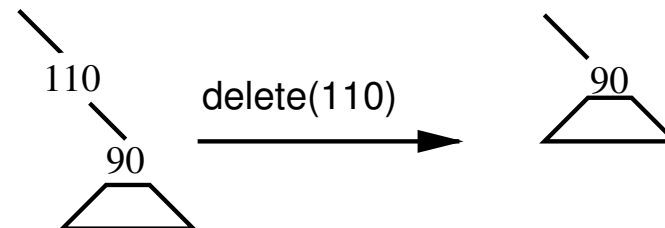
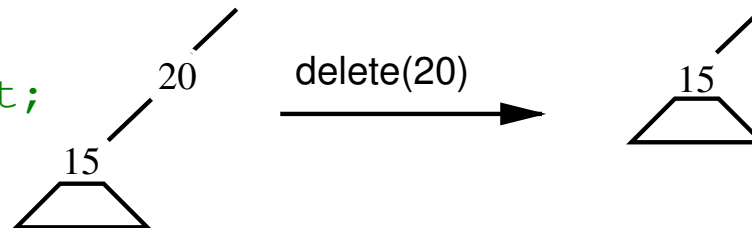
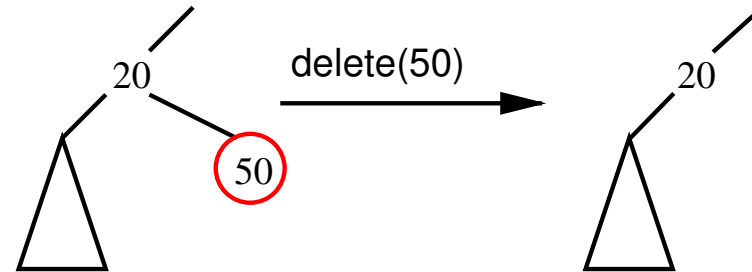
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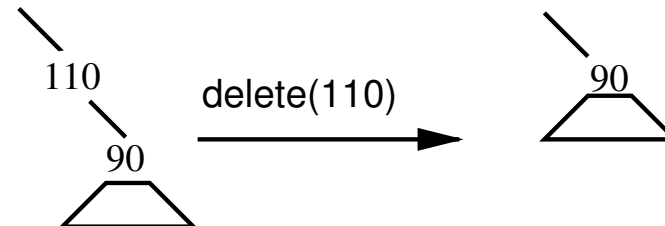
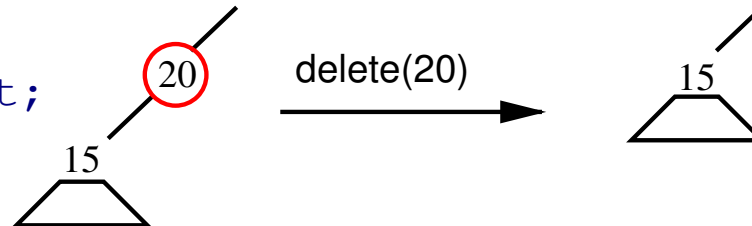
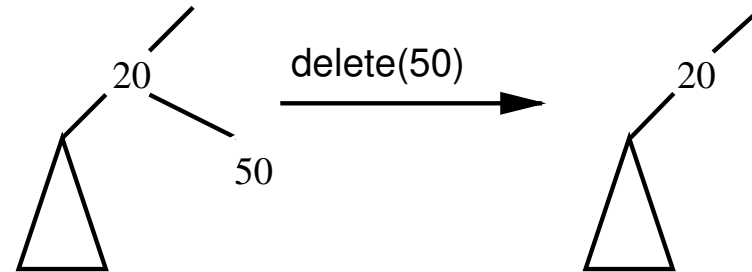
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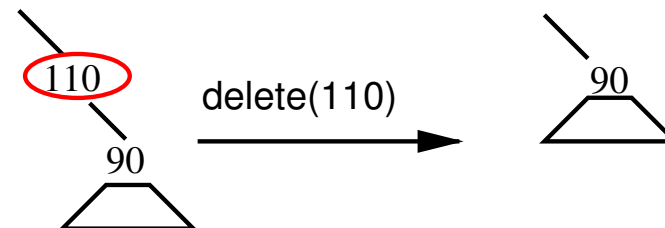
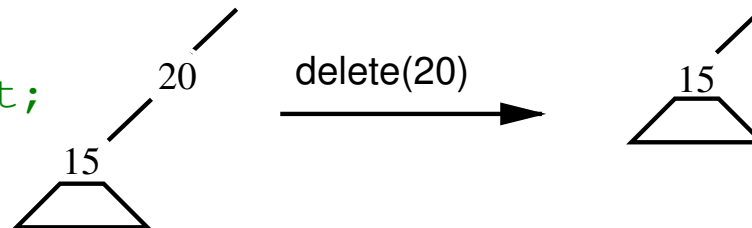
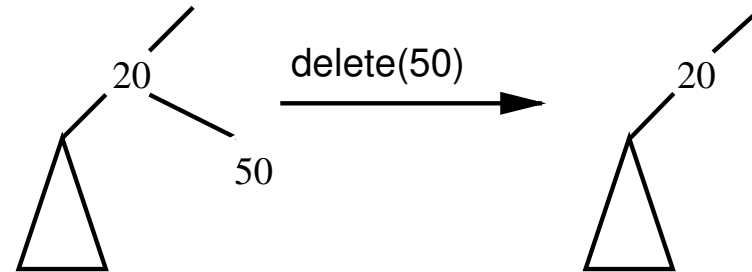
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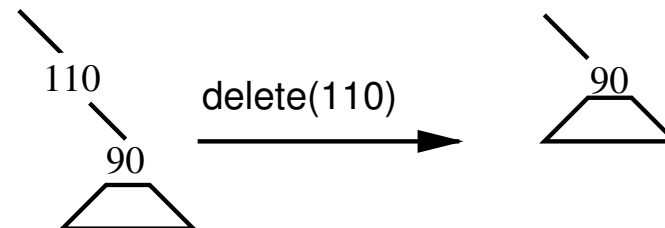
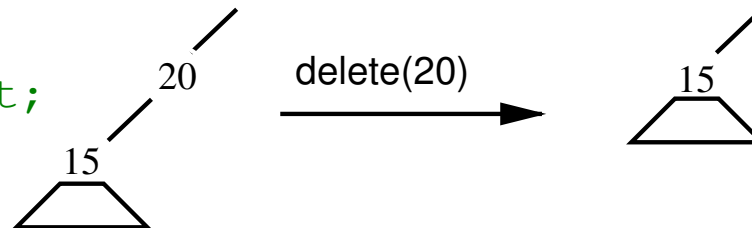
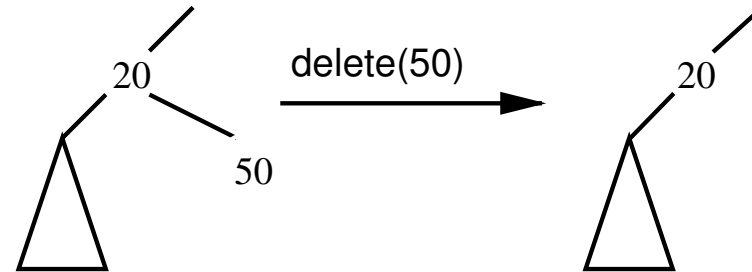
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Removing Element with Two Children

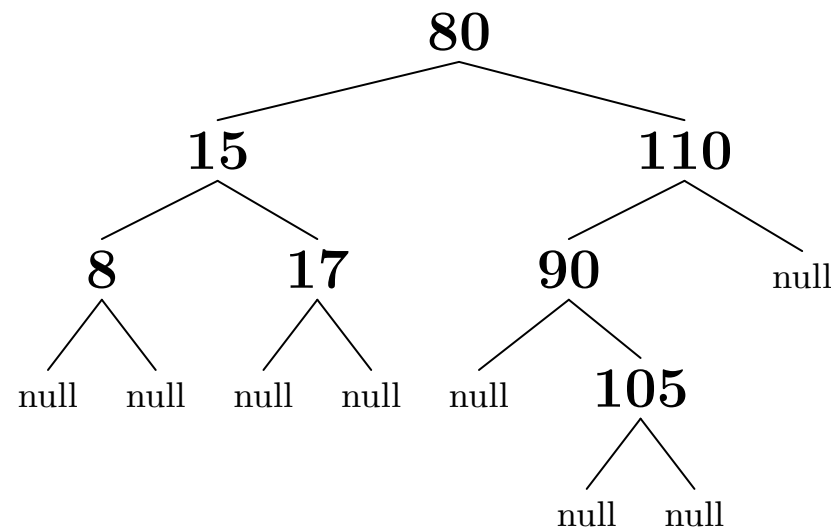
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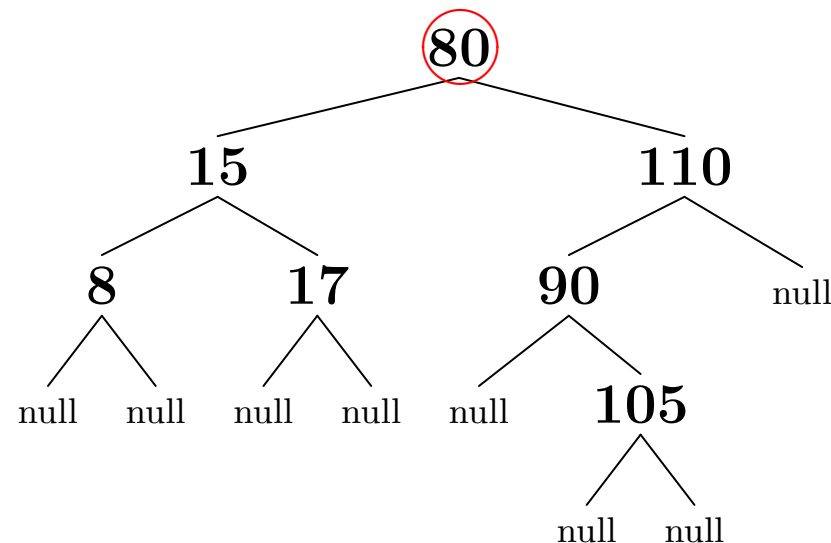
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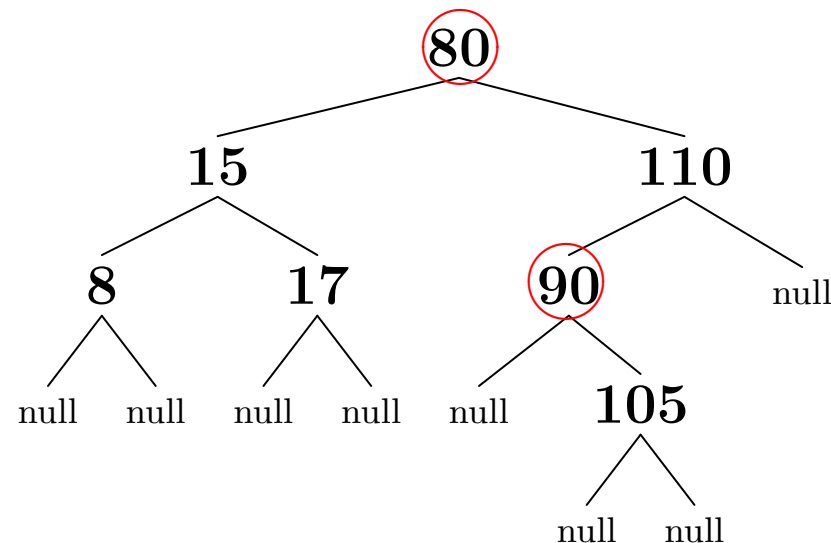
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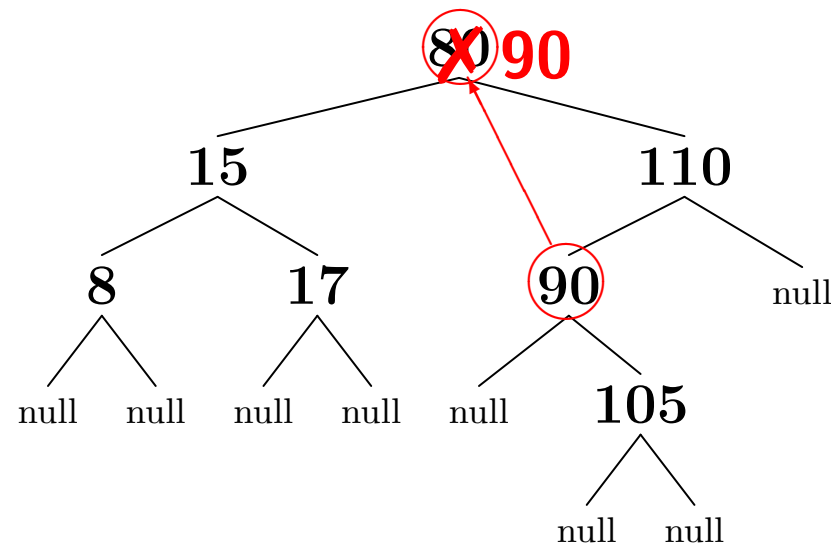
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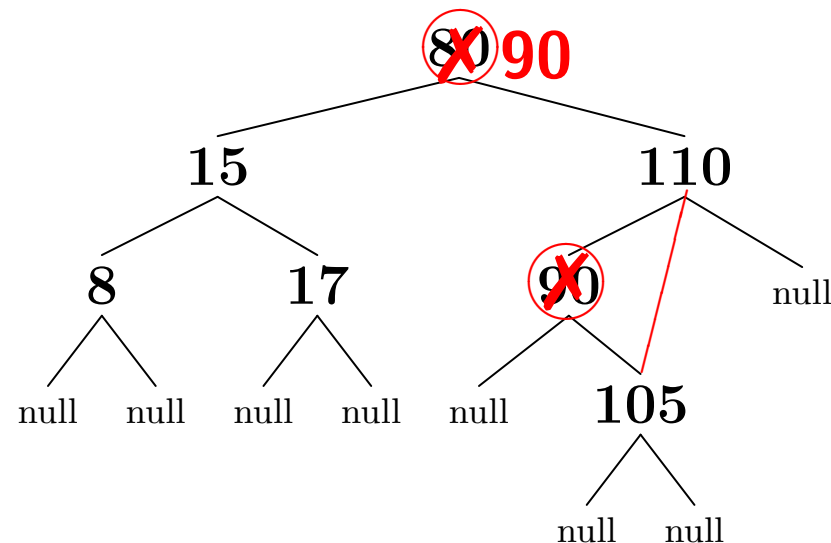
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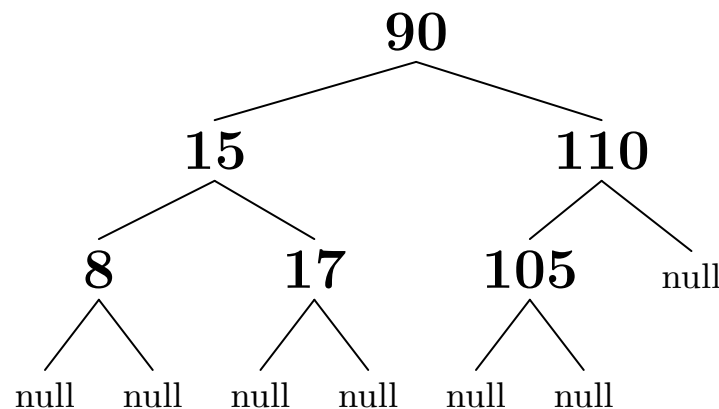
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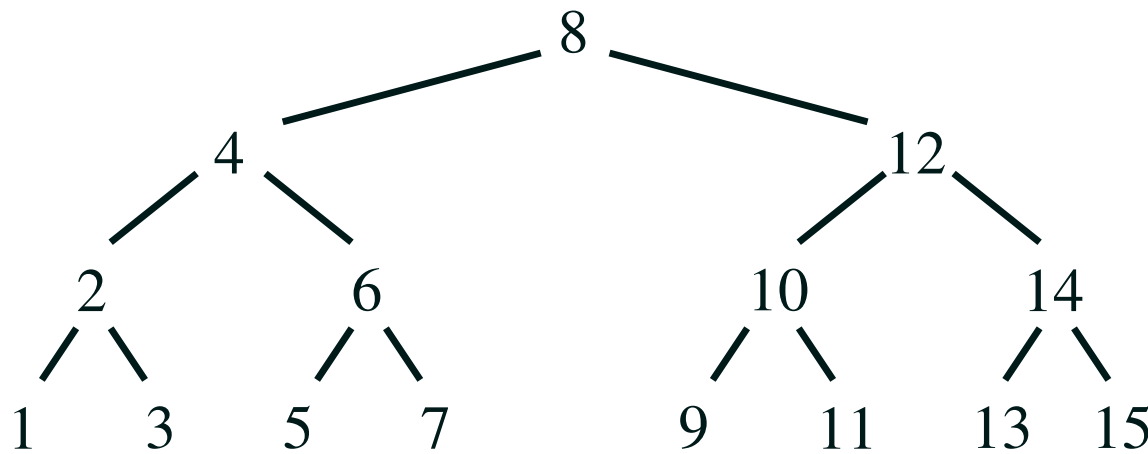
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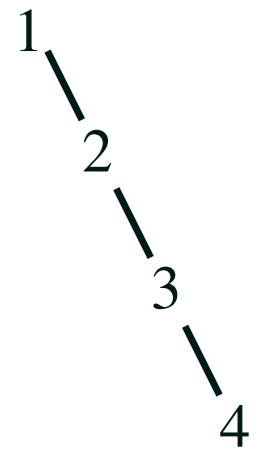


Why Balance Trees

- The number of comparisons to access an element depends on the depth of the node
- The average depth of the node depends on the shape of the tree



full tree

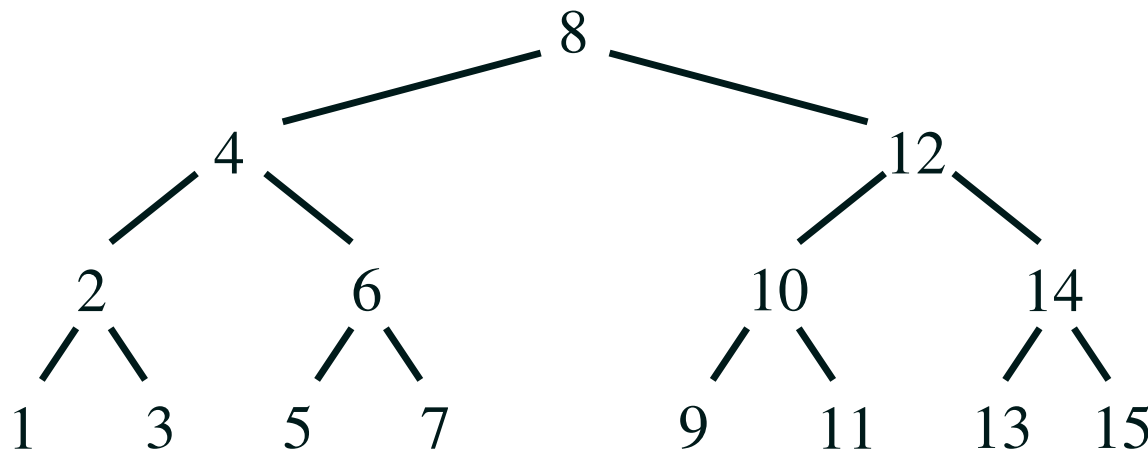


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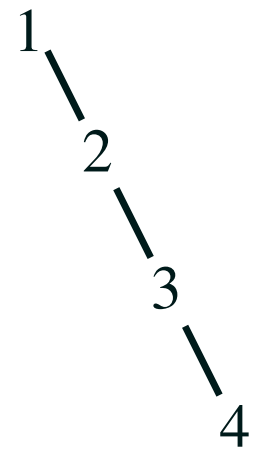
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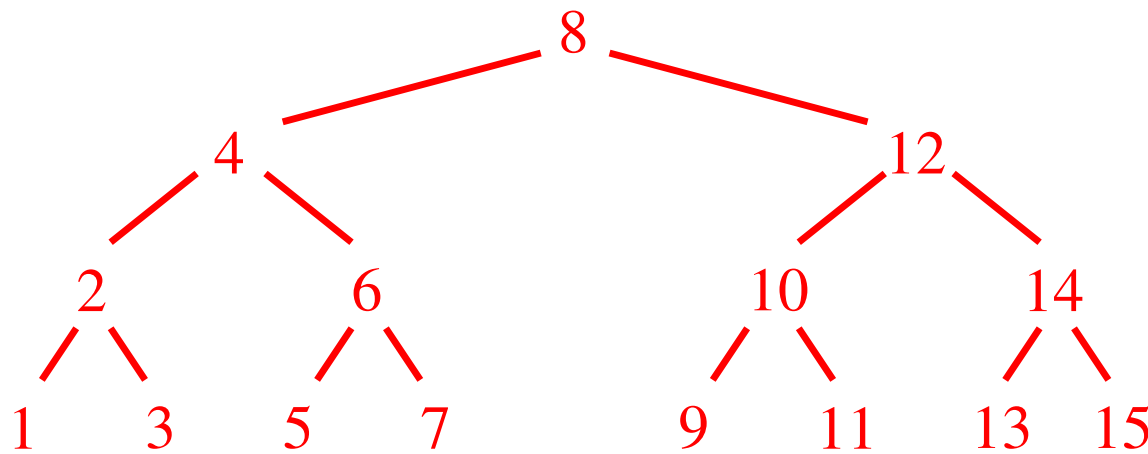


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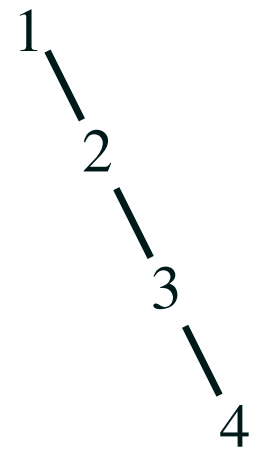
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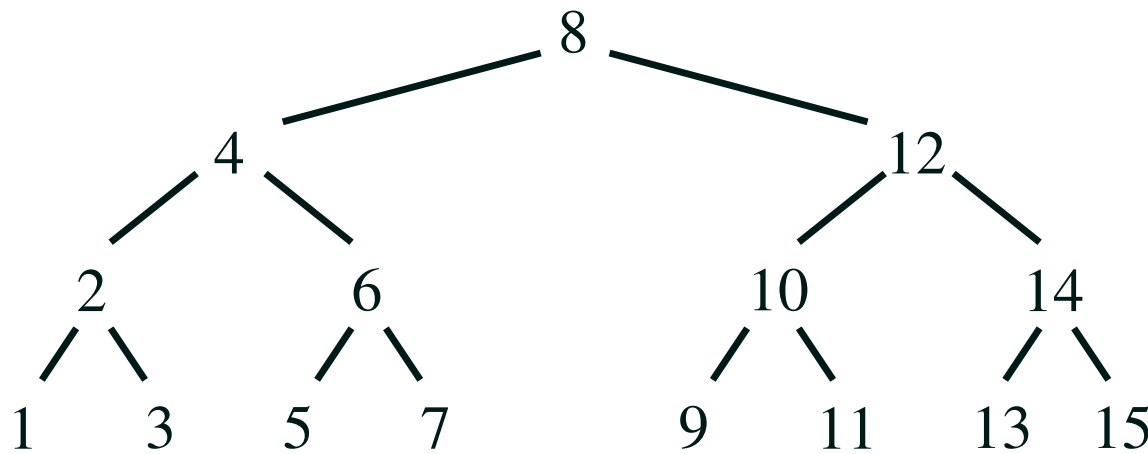


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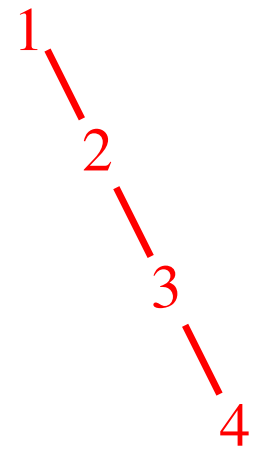
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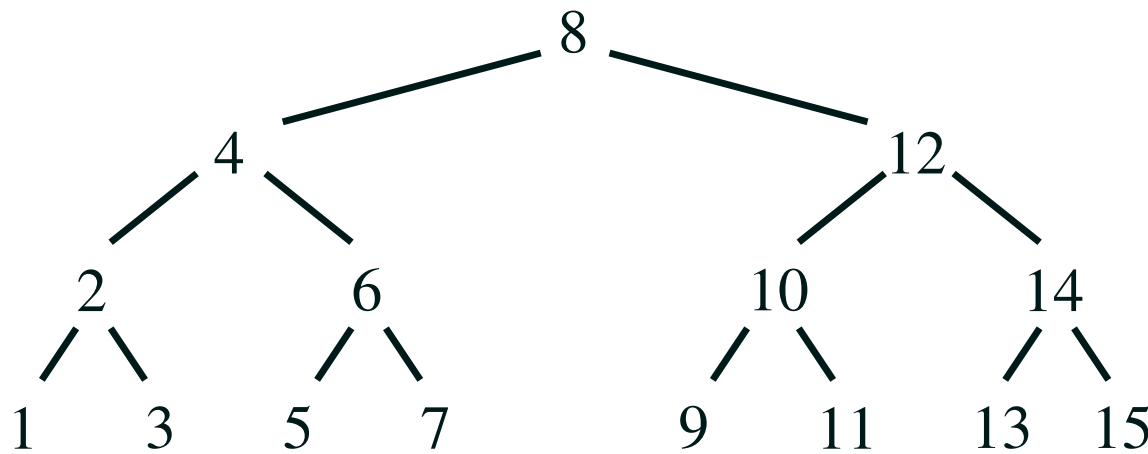


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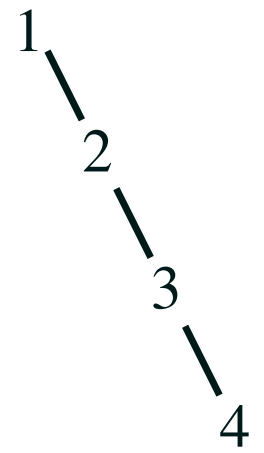
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Time Complexity

- In the best situation (a full tree) the number of elements in a tree is $n = \Theta(2^l)$ the depth is l so that the maximum depth is $\log_2(n)$
- It turns out for random sequences the average depth is $\Theta(\log(n))$
- In the worst case (when the tree is effectively a linked list), the average depth is $\Theta(n)$
- Unfortunately, the worst case happens when the elements are added *in order* (not a rare event)

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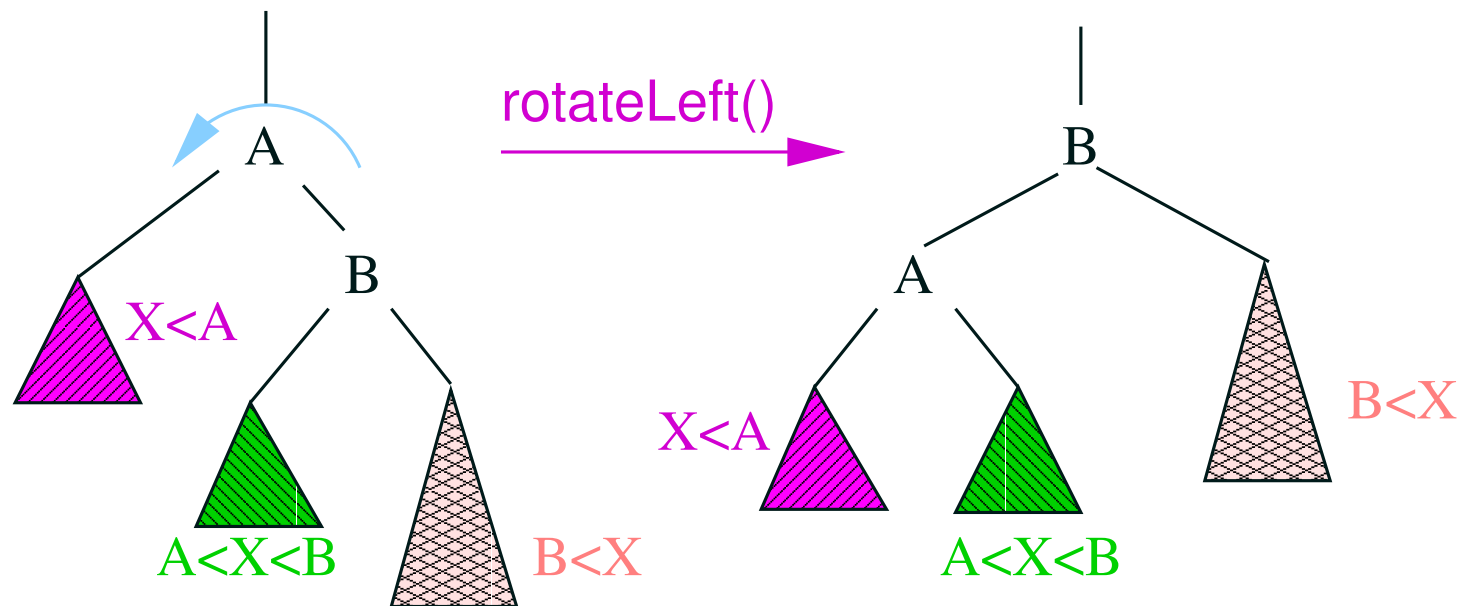
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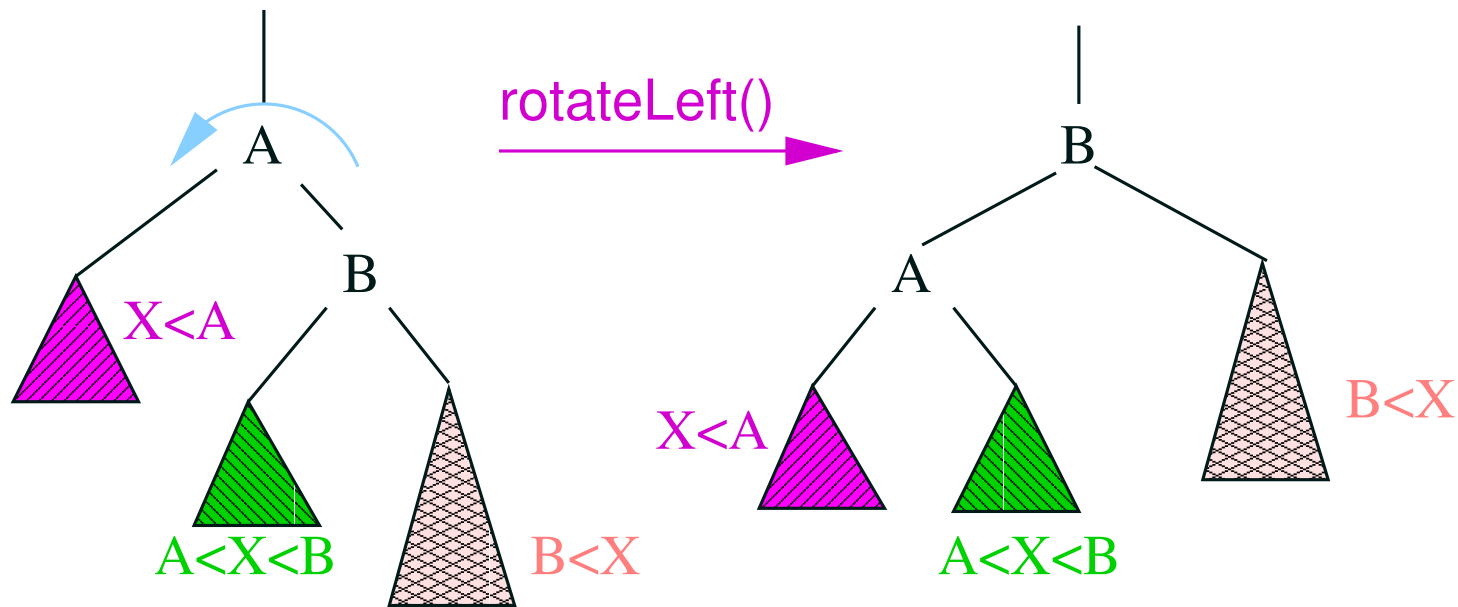
Rotations

- To avoid unbalanced trees we would like to modify the shape
- This is possible as the shape of the tree is not uniquely defined (e.g. we could make any node the root)
- We can change the shape of a tree using **rotations**
- E.g. left rotation



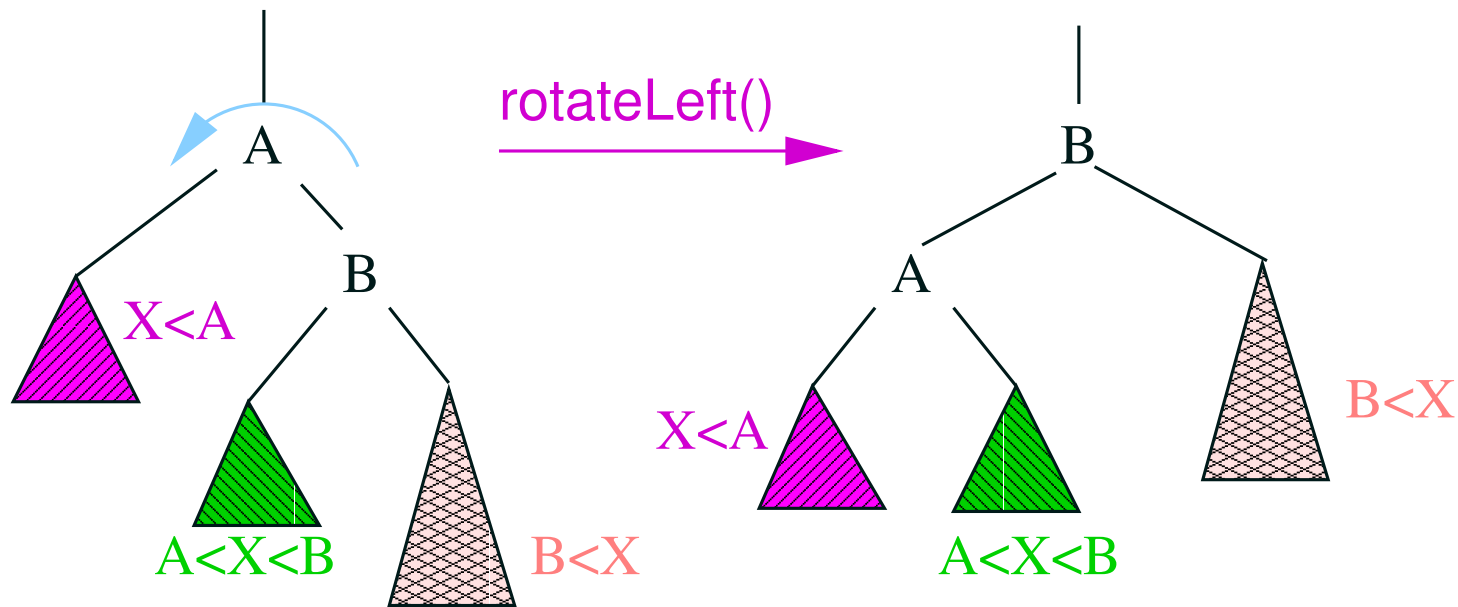
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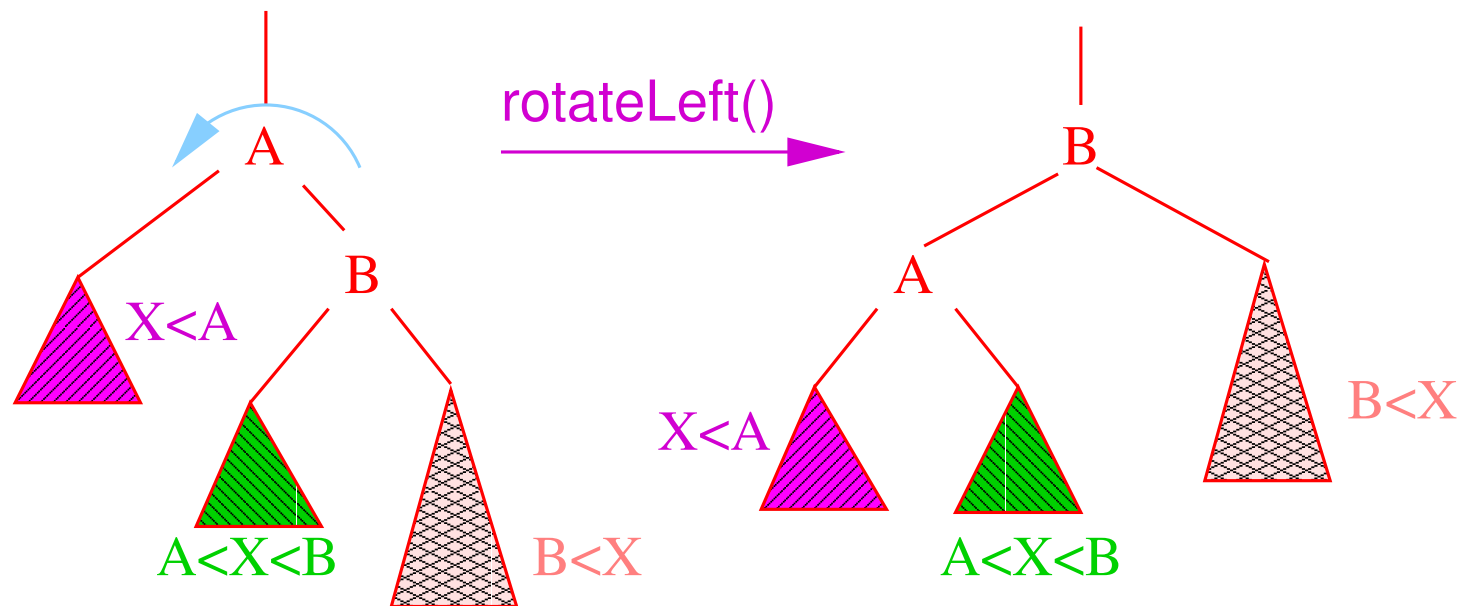
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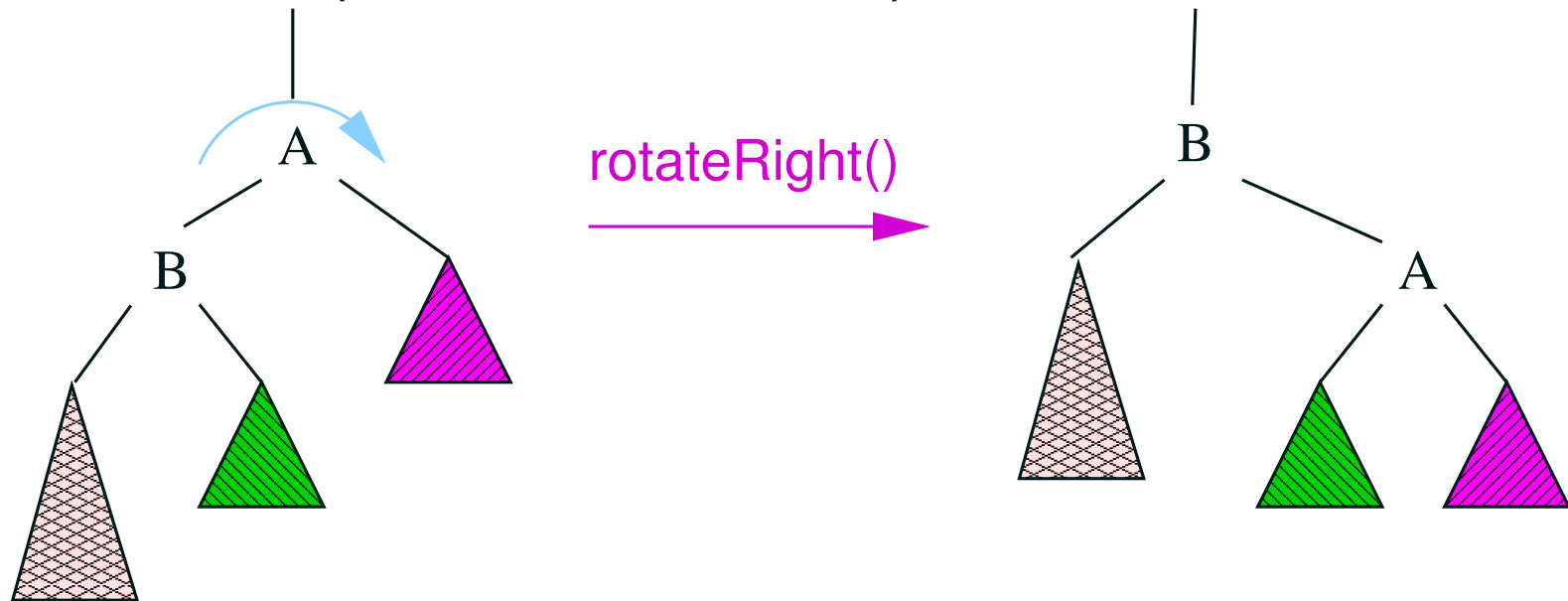
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Types of Rotations

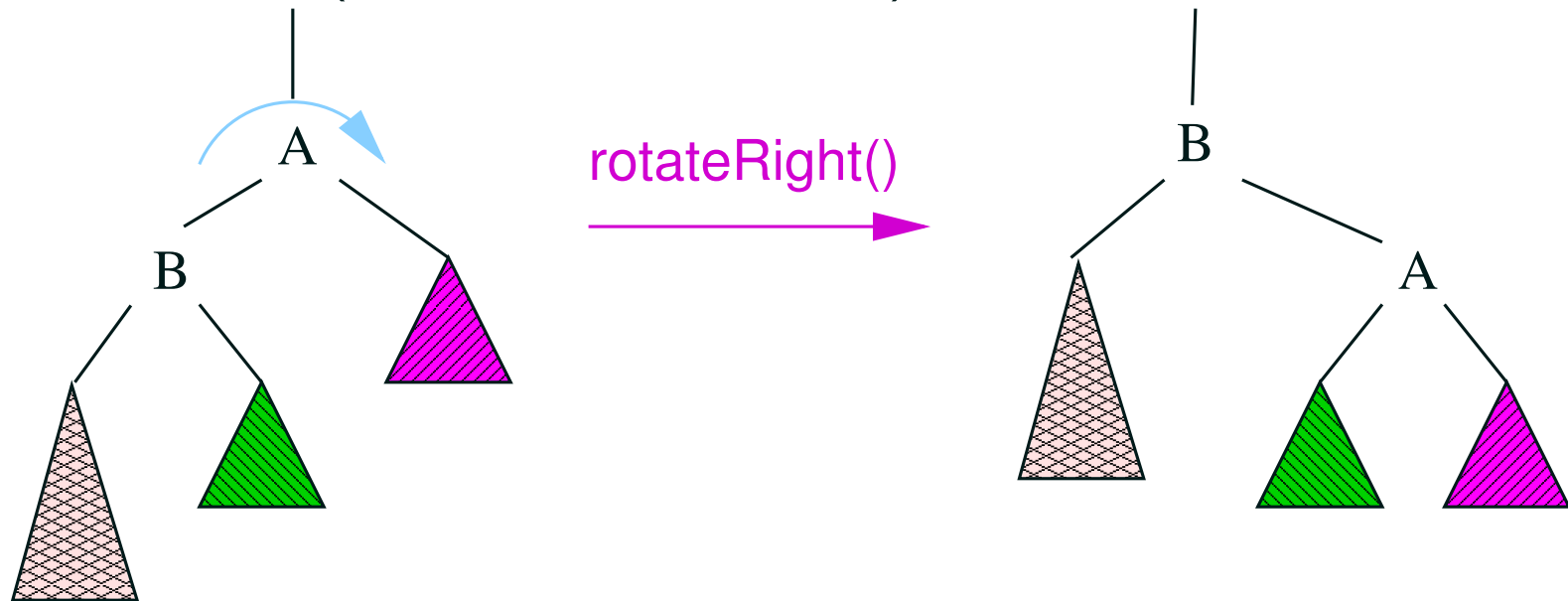
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 - ★ Left rotation (as above)
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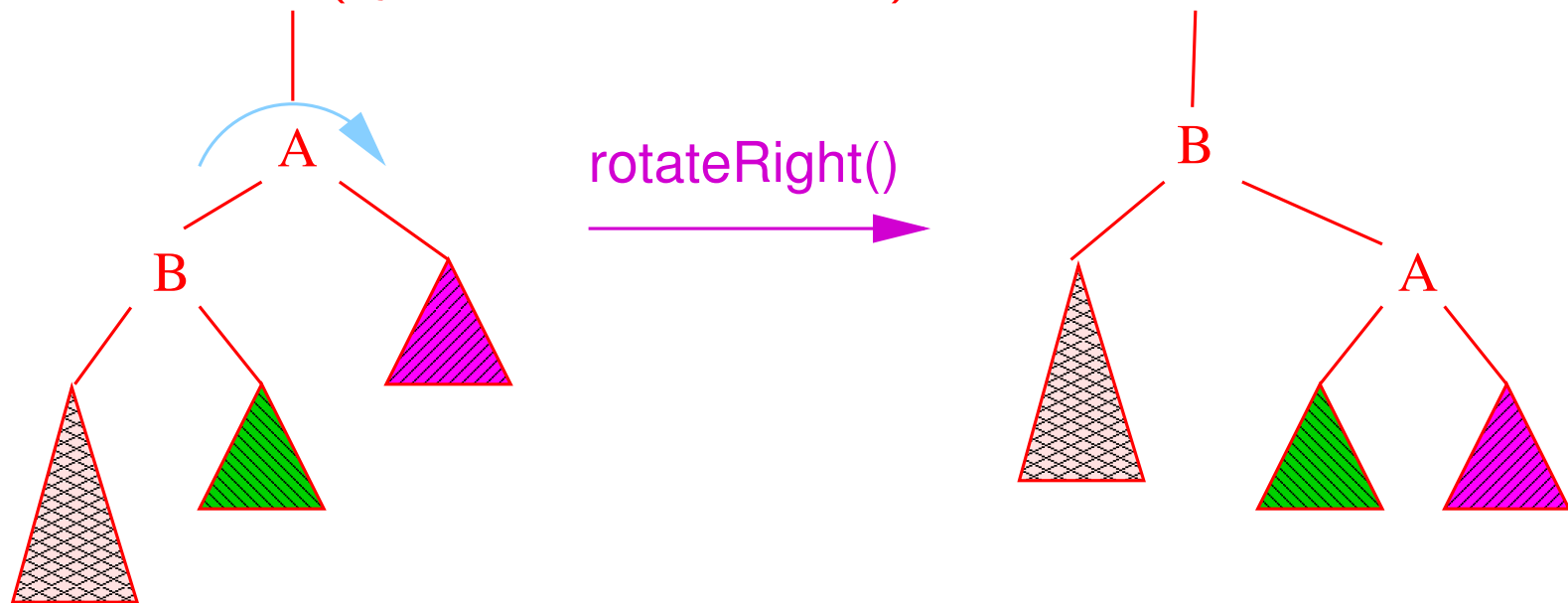
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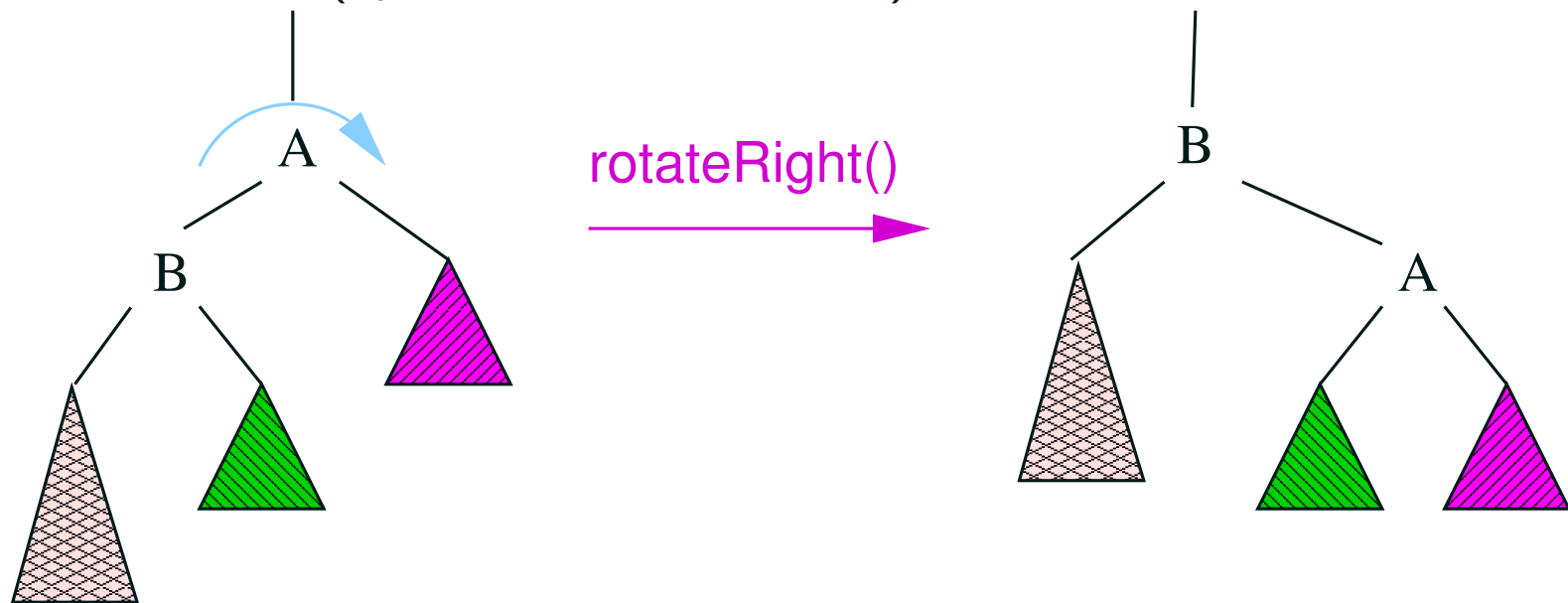
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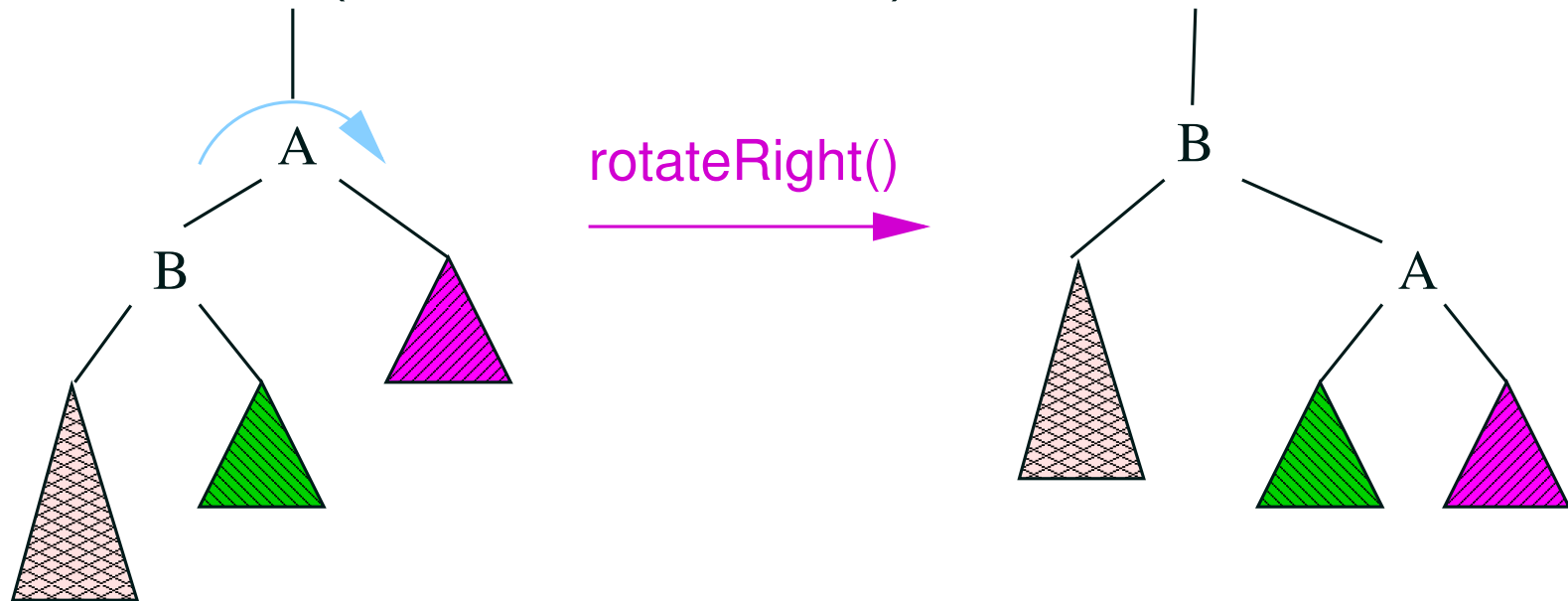
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Coding Rotations

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void rotateLeft(Node* e)
```

```
{
```

```
    Node* r = e->right;
```

```
    e->right = r->left;
```

```
    if (r->left != 0)
```

```
        r->left->parent = e;
```

```
    r->parent = e->parent;
```

```
    if (e->parent == 0)
```

```
        root = r;
```

```
    else if (e->parent->left == e)
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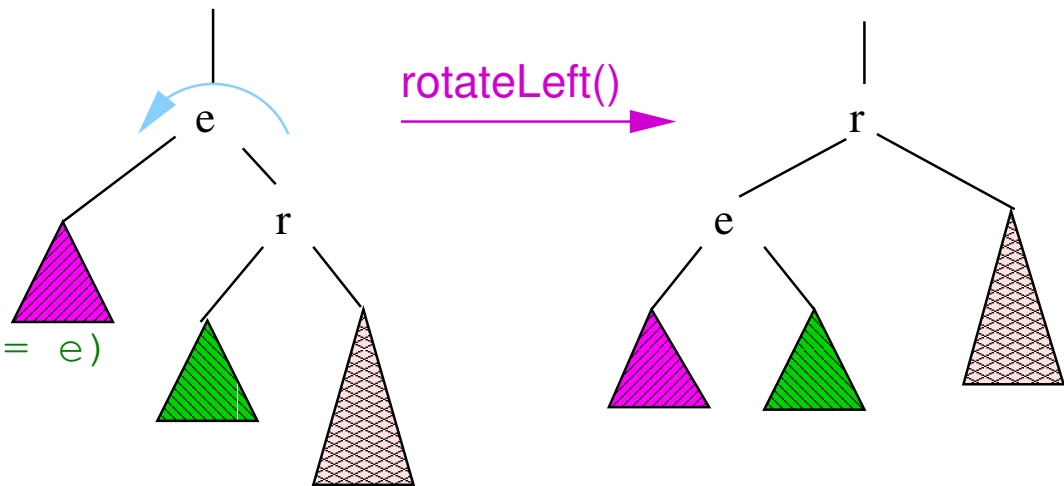
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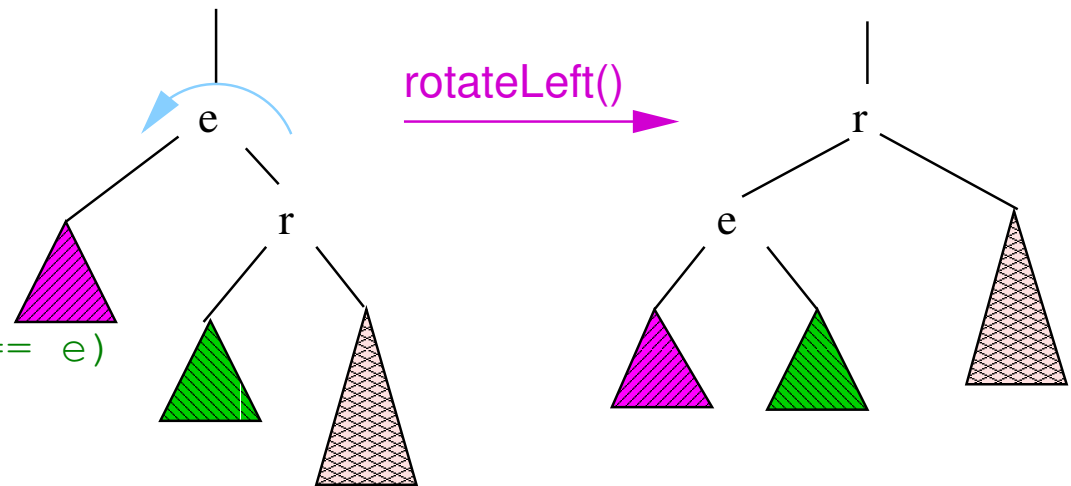
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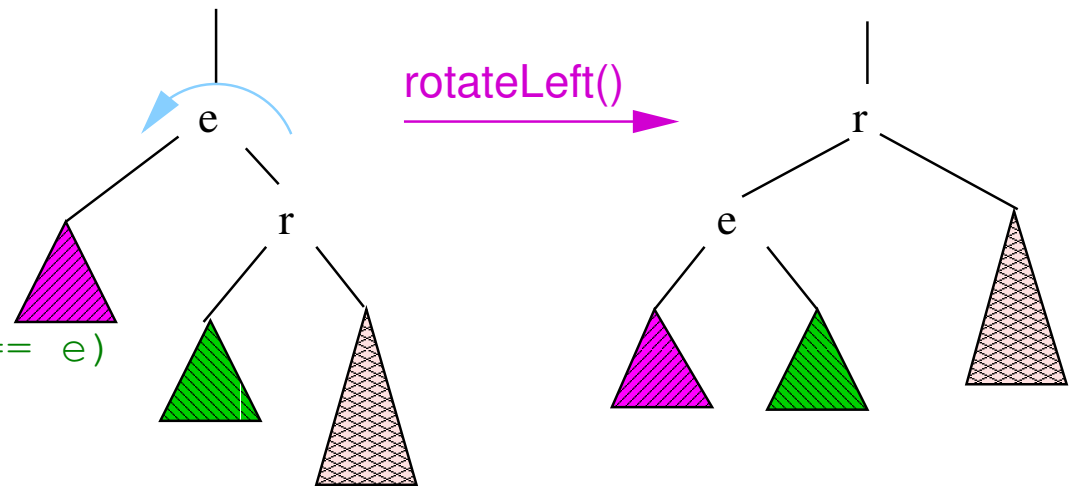
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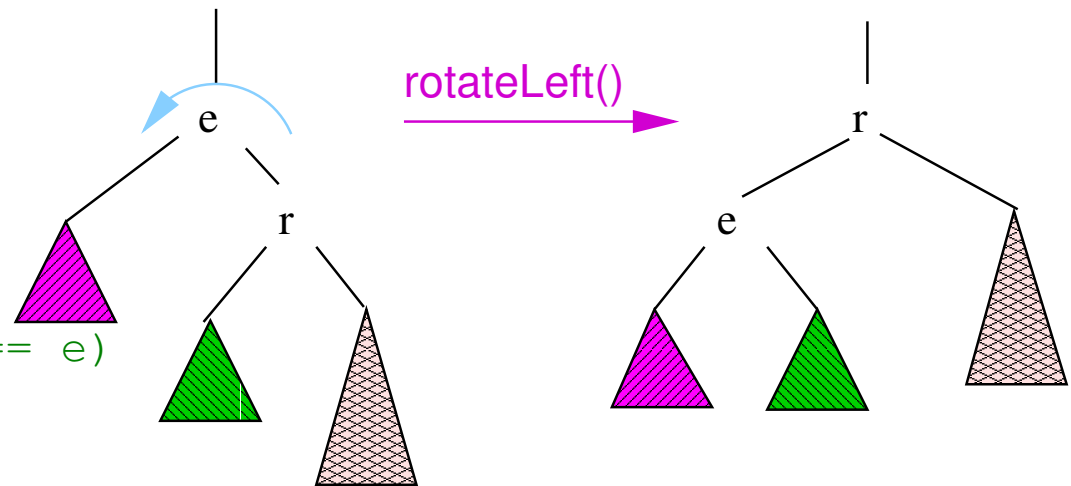
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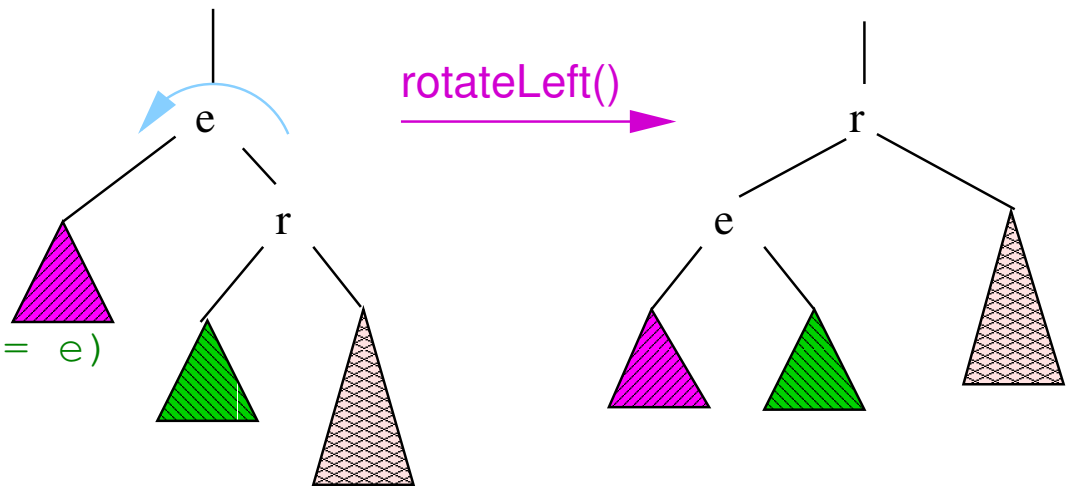
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    if (r->left != 0)
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    r->parent = e->parent;
    if (e->parent == 0)
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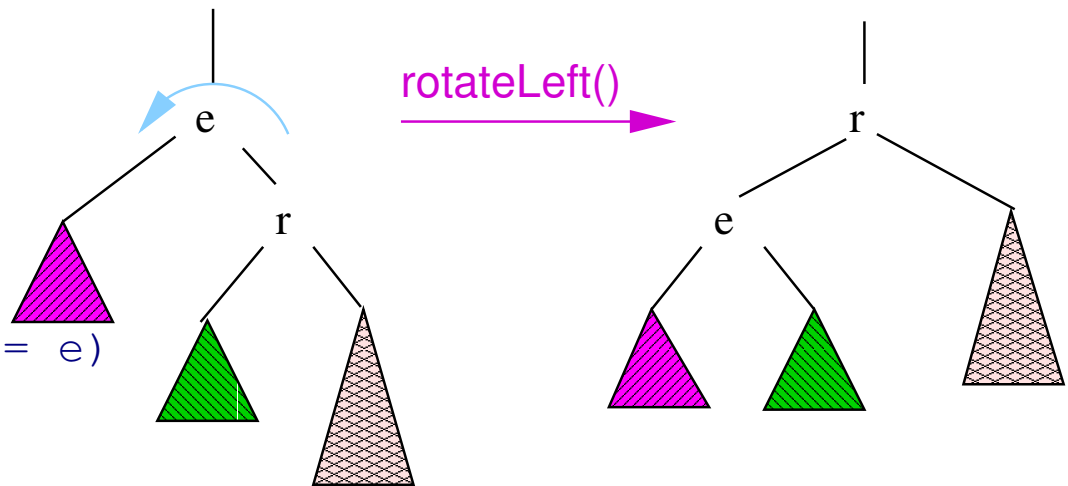
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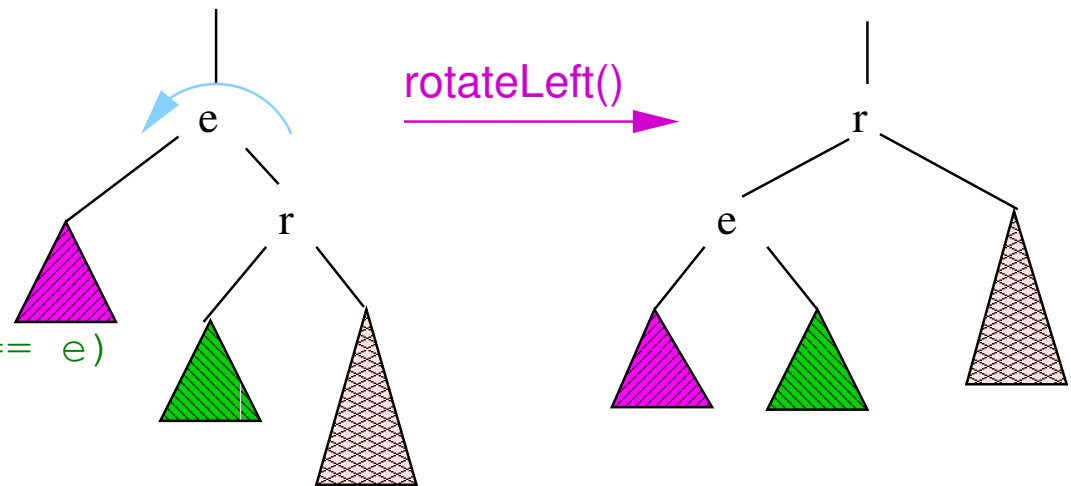
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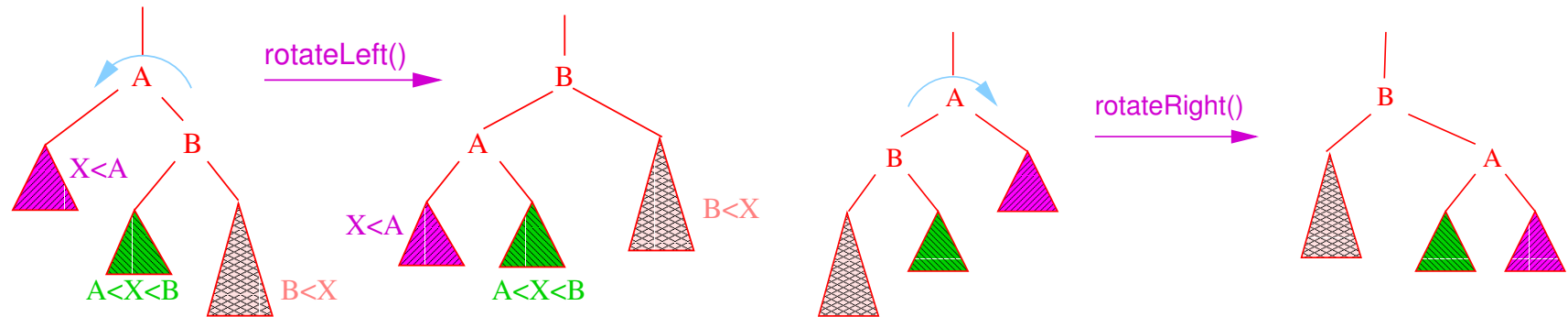
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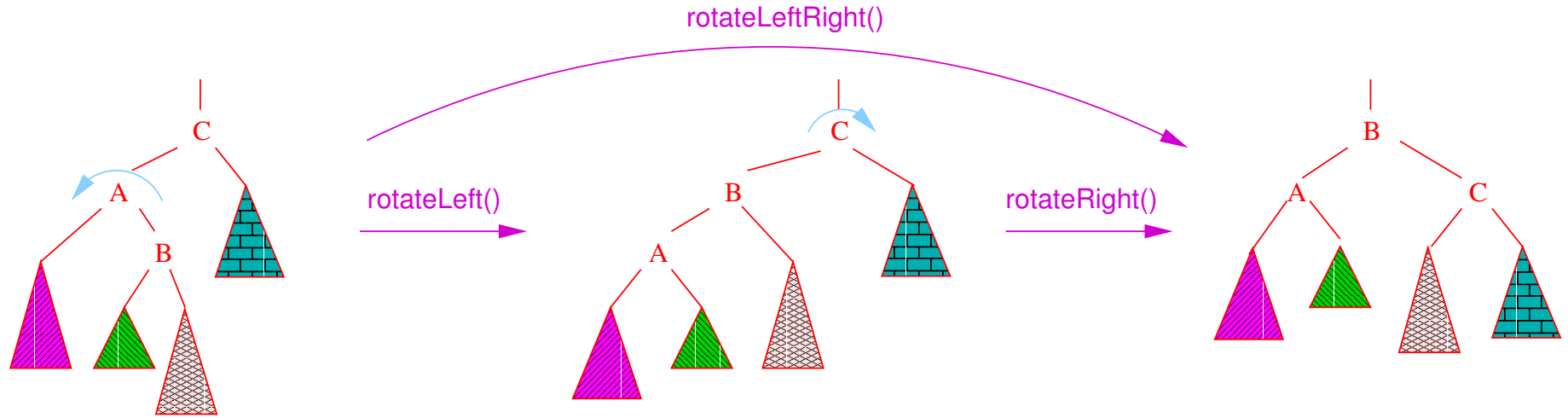
When Single Rotations Work

- Single rotations balance the tree when the unbalanced subtree is on the outside



Double Rotations

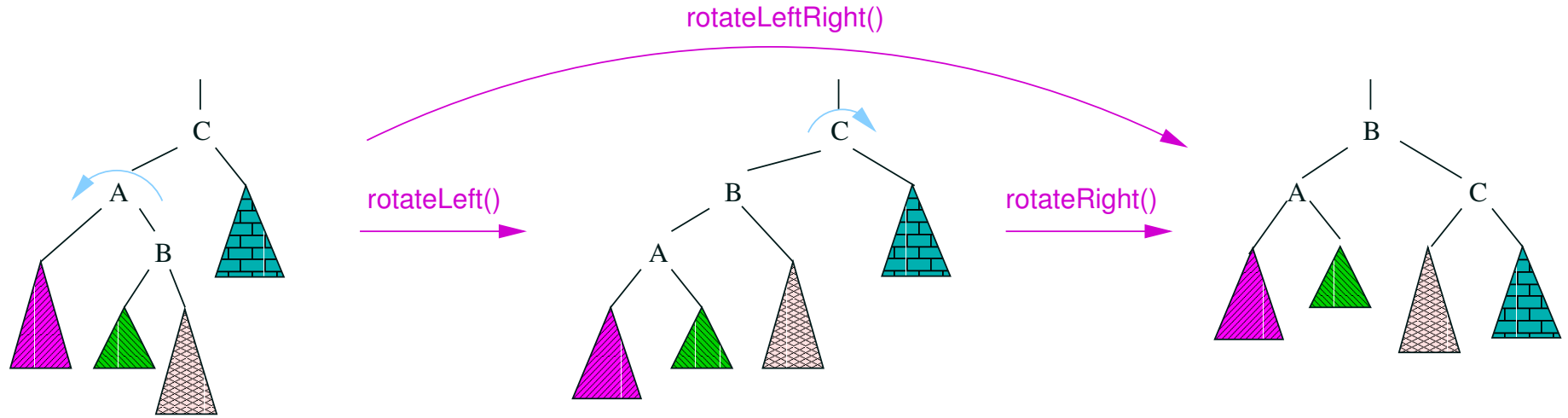
- If the unbalanced subtree is on the inside we need a double rotation



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Outline

1. Deletion
2. Balancing Trees
 - Rotations
3. **AVL**
4. Red-Black Trees
 - TreeSet
 - TreeMap



Balancing Trees

- There are different strategies for using rotations for balancing trees
- The three most popular are
 - ★ AVL-trees
 - ★ Red-black trees
 - ★ Splay trees
- They differ in the criteria they use for doing rotations

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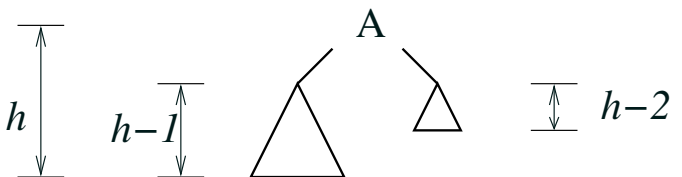
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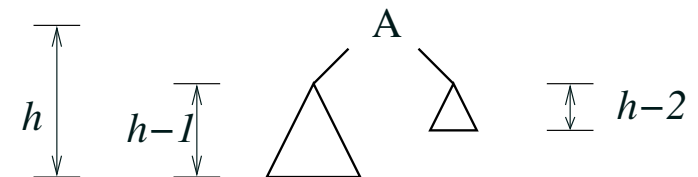
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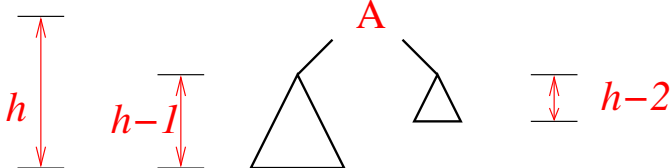
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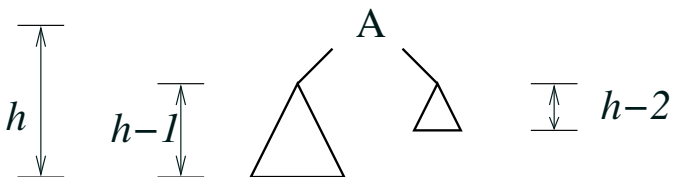
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Implementing AVL Trees

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add(16)

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16 0

Implementing AVL Trees

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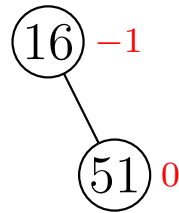
add(51)

16 0

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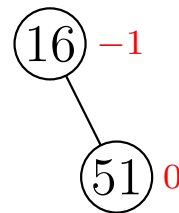


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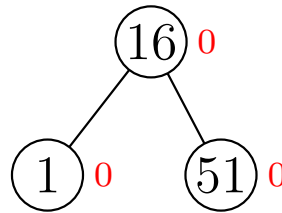
add(1)



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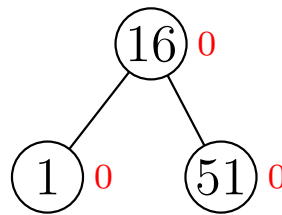


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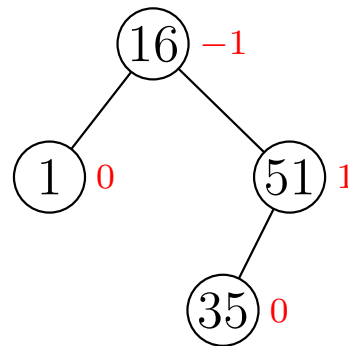
add(35)



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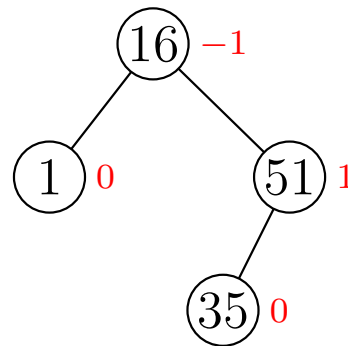


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add(23)

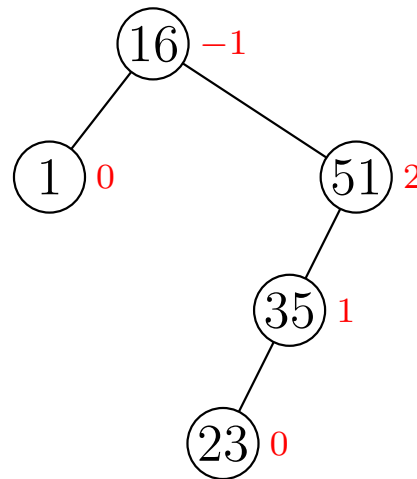


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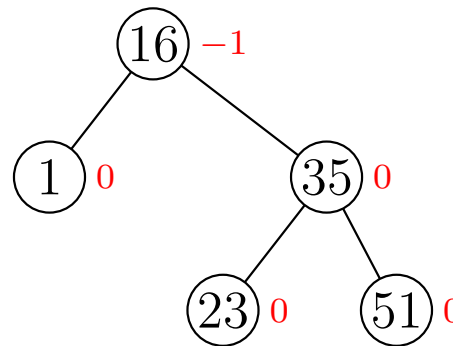
RotateRight



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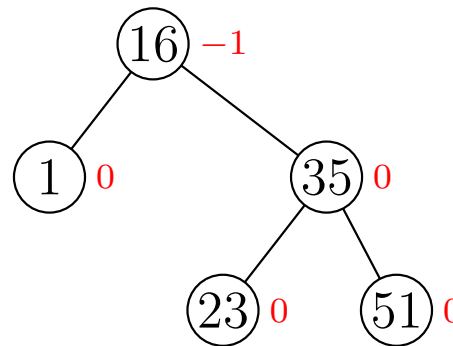


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add(45)

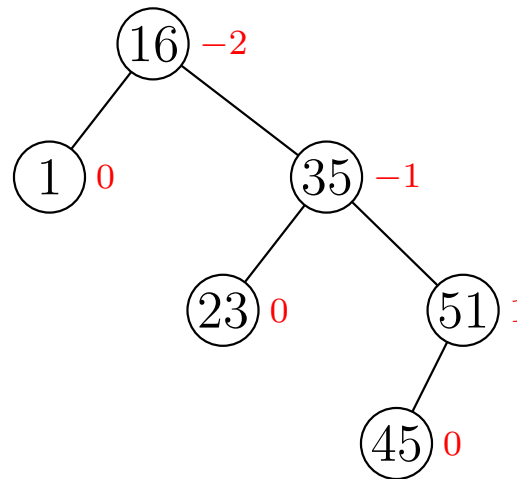


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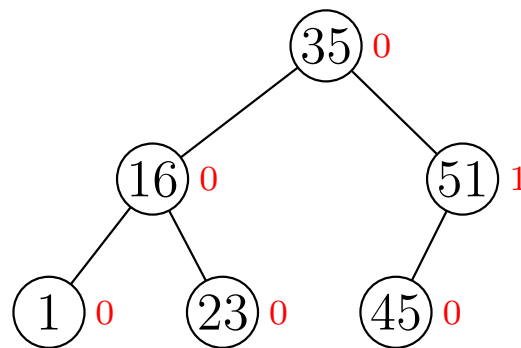
RotateLeft



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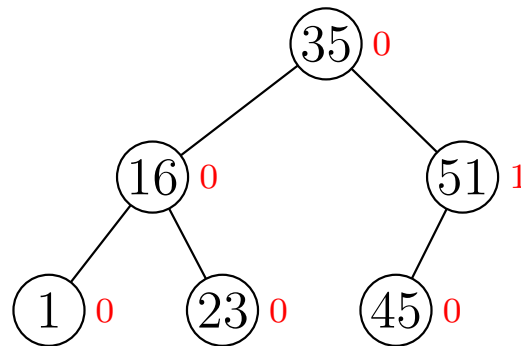


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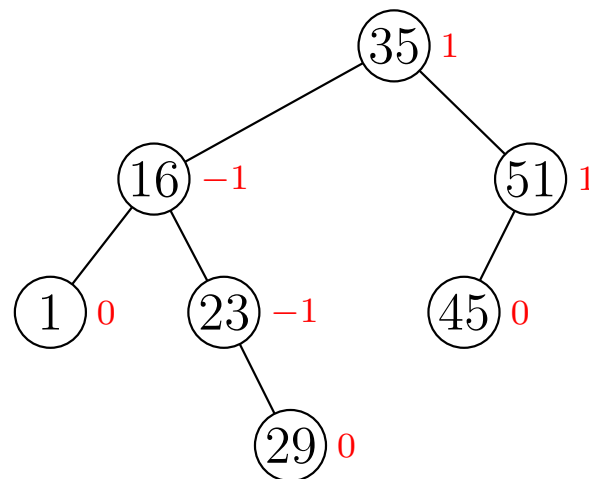
add(29)



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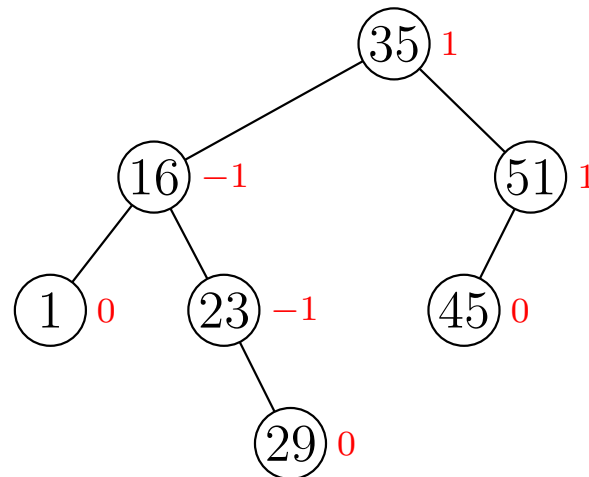


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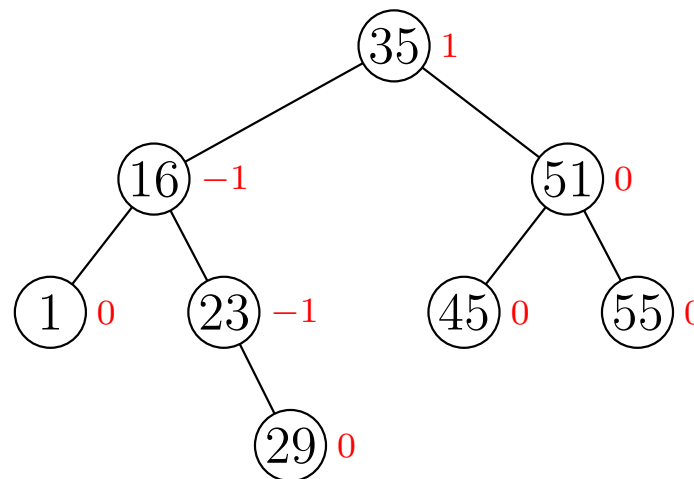
add(55)



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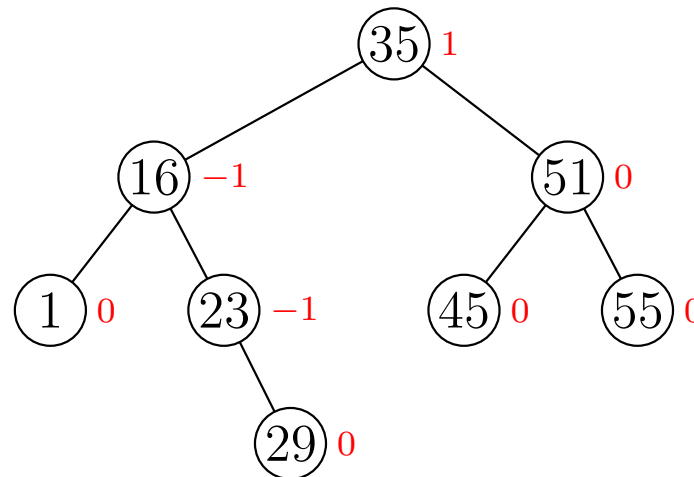


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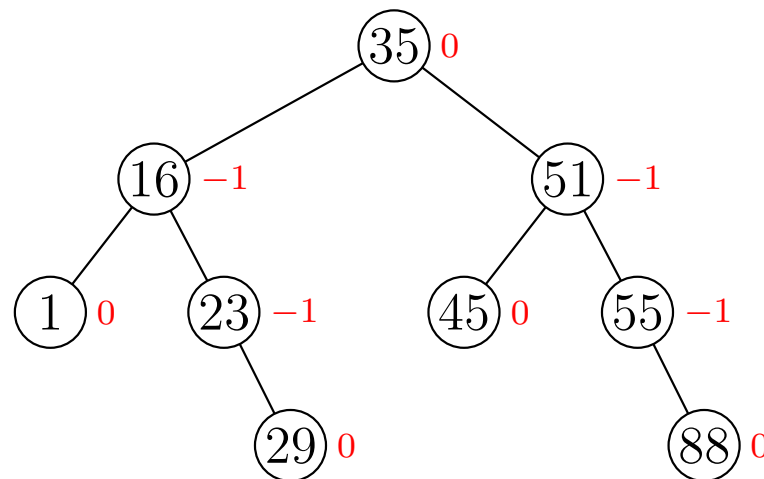
add(88)



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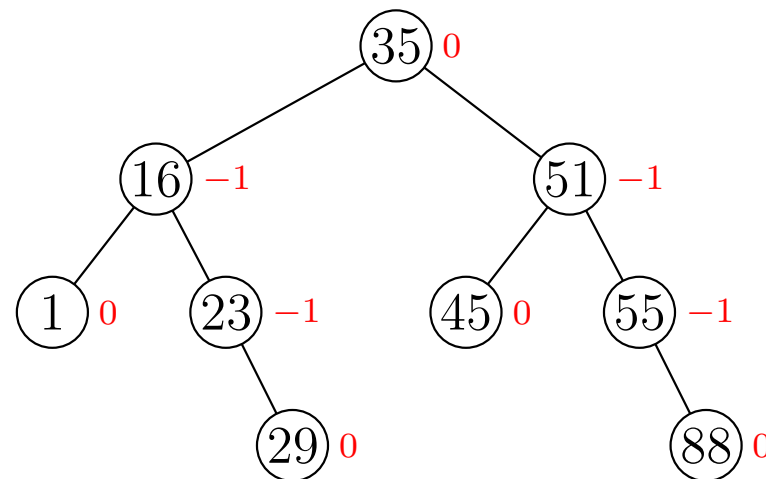


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add(91)

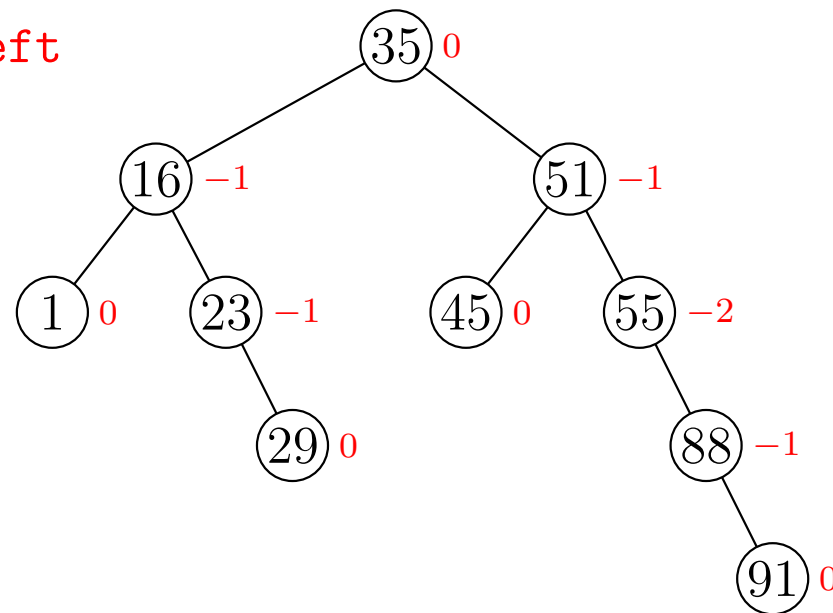


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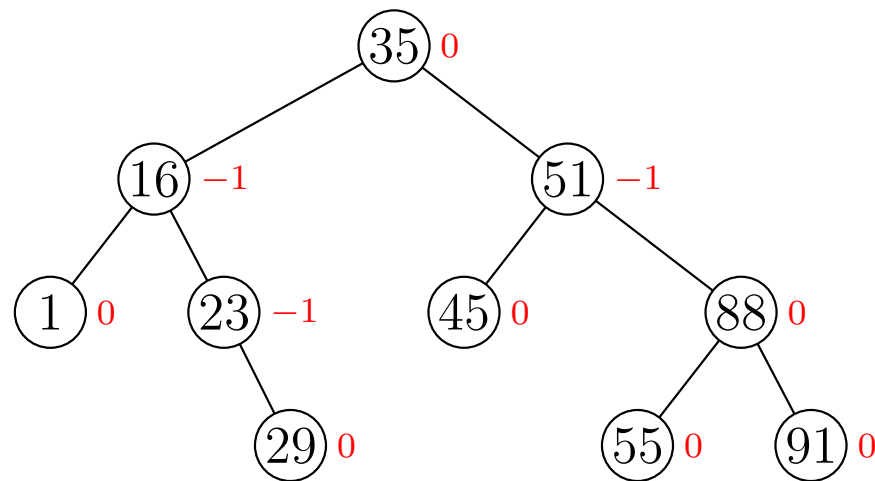
RotateLeft



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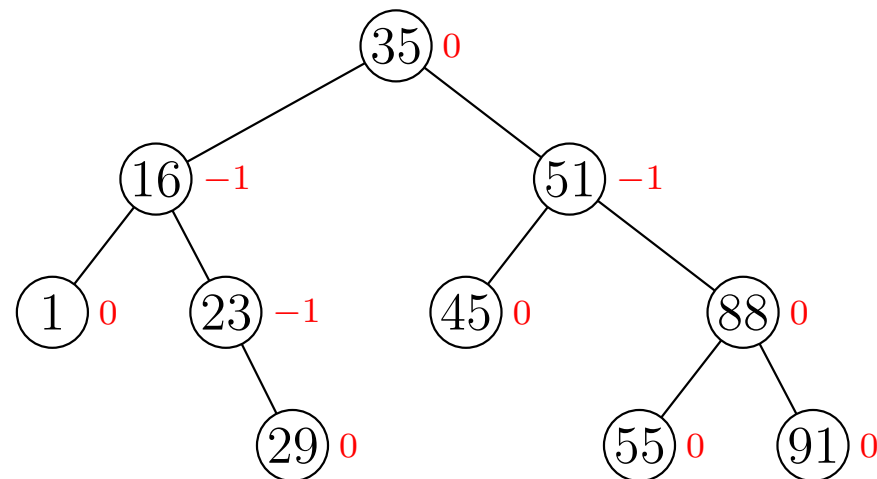


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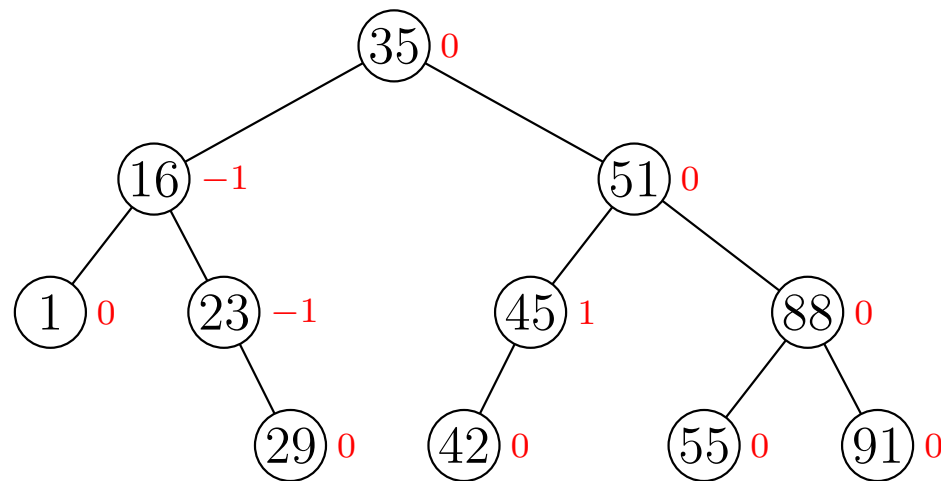
add(42)



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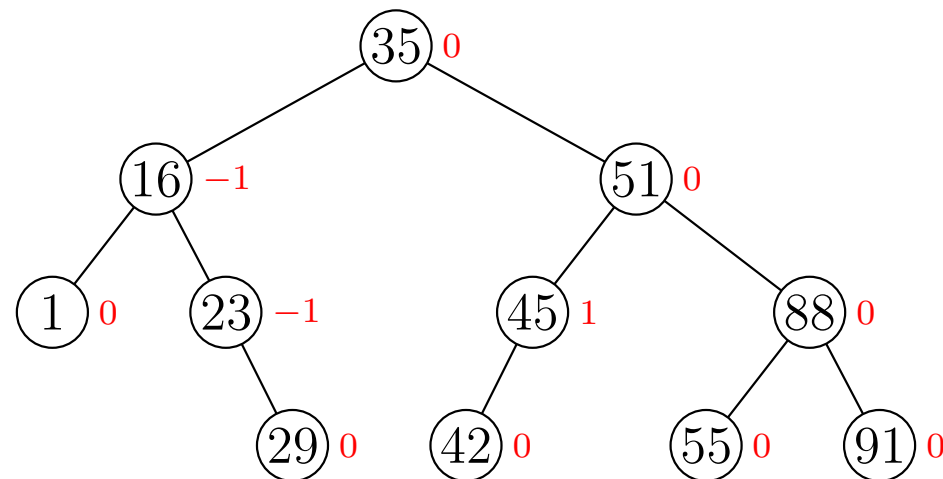


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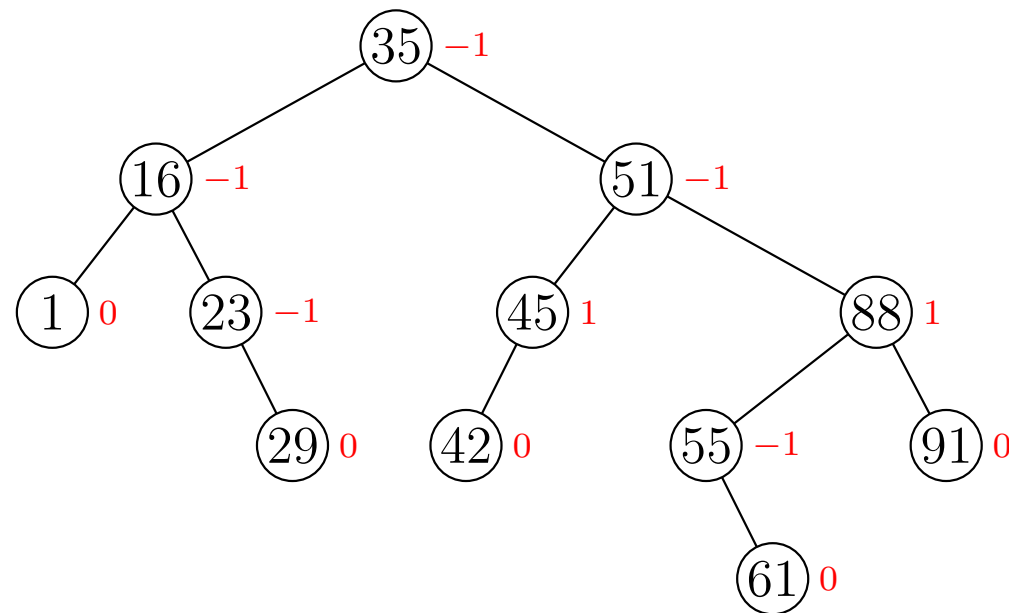
add(61)



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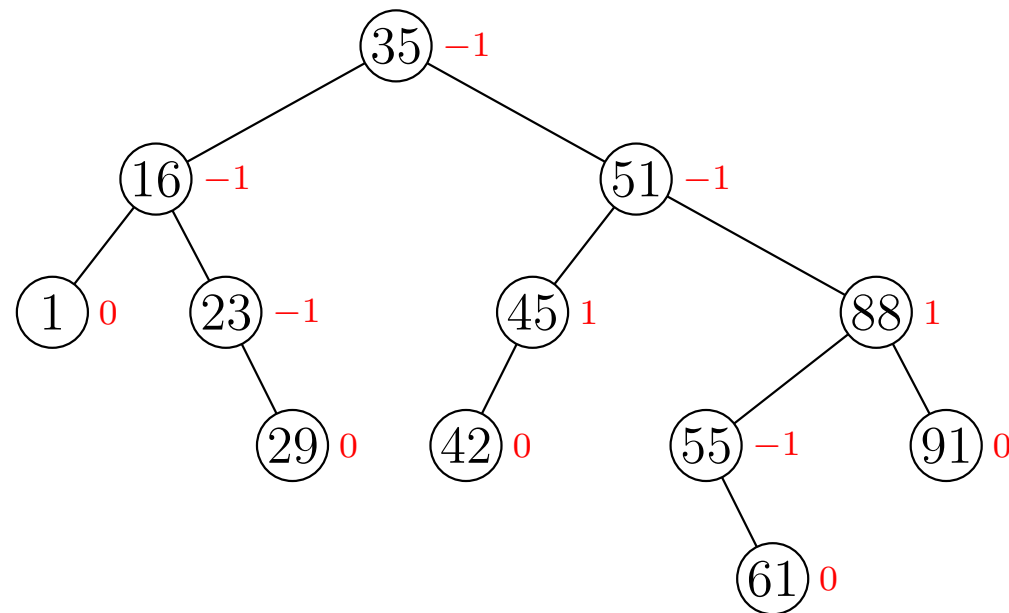


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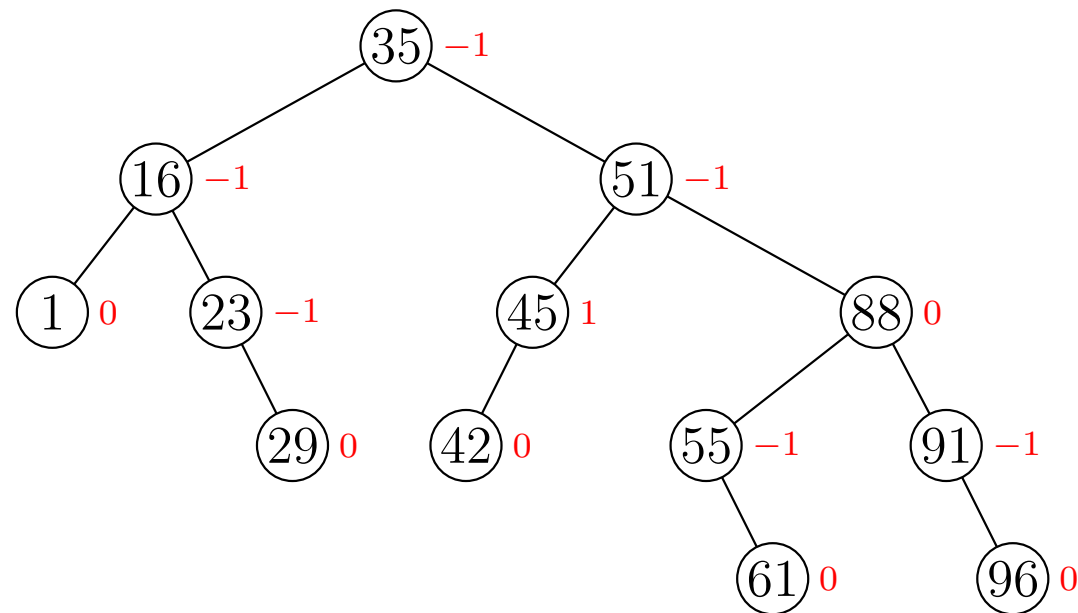
add(96)



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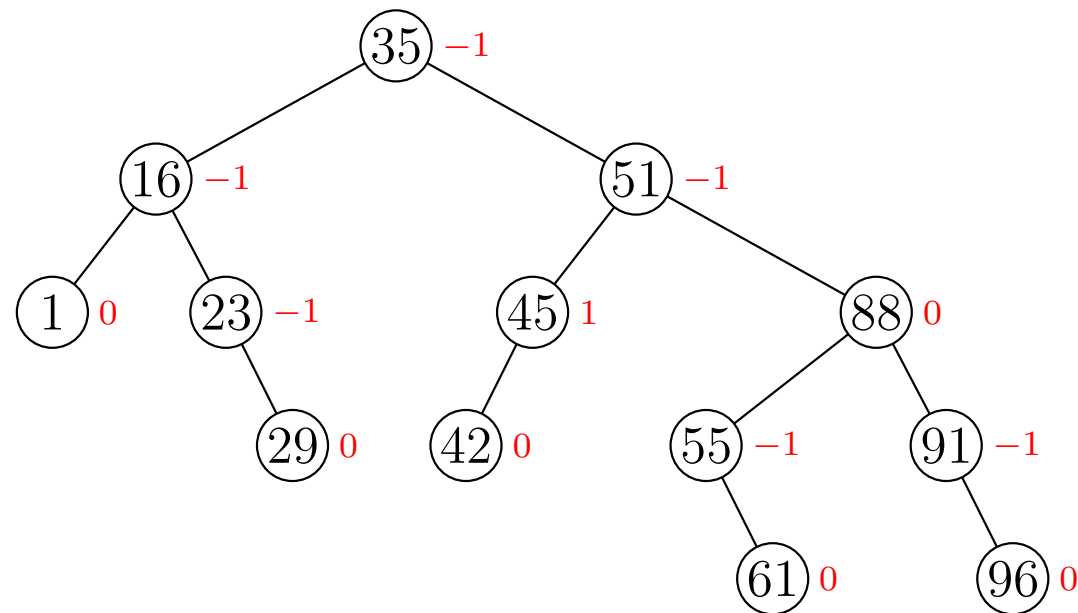


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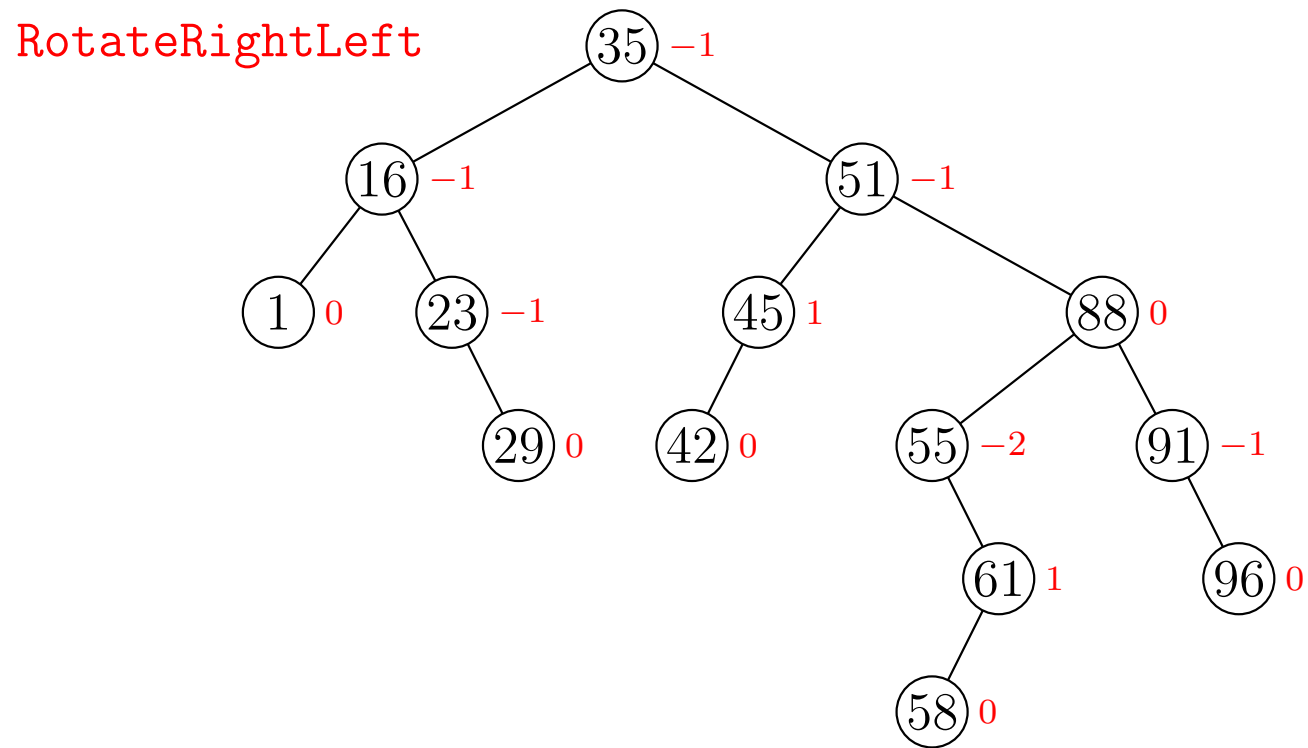
add(58)



Implementing AVL Trees

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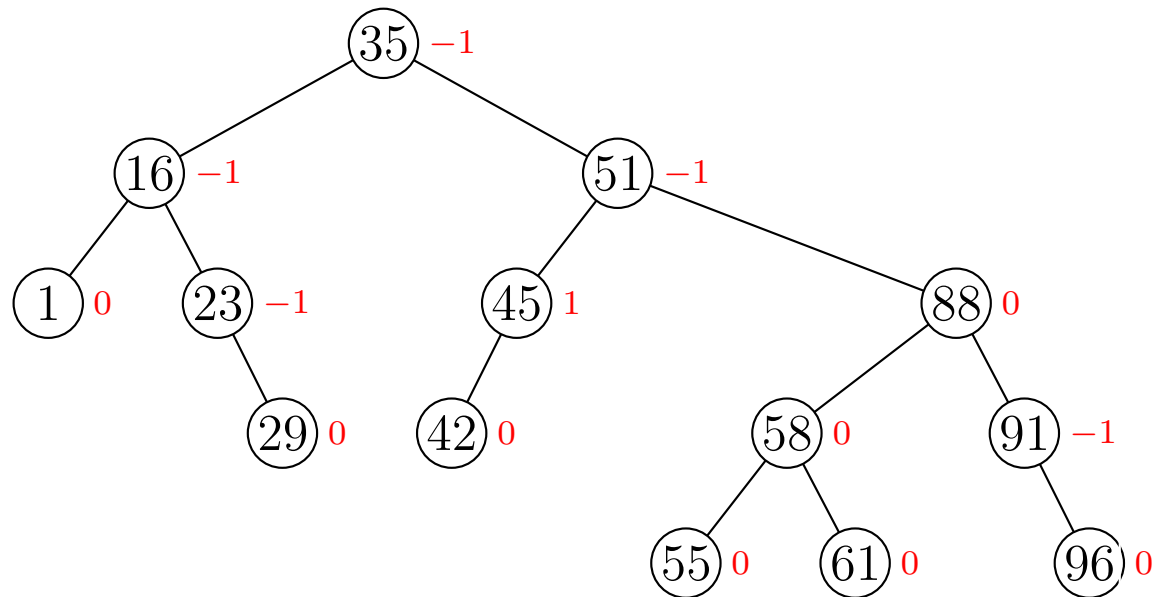
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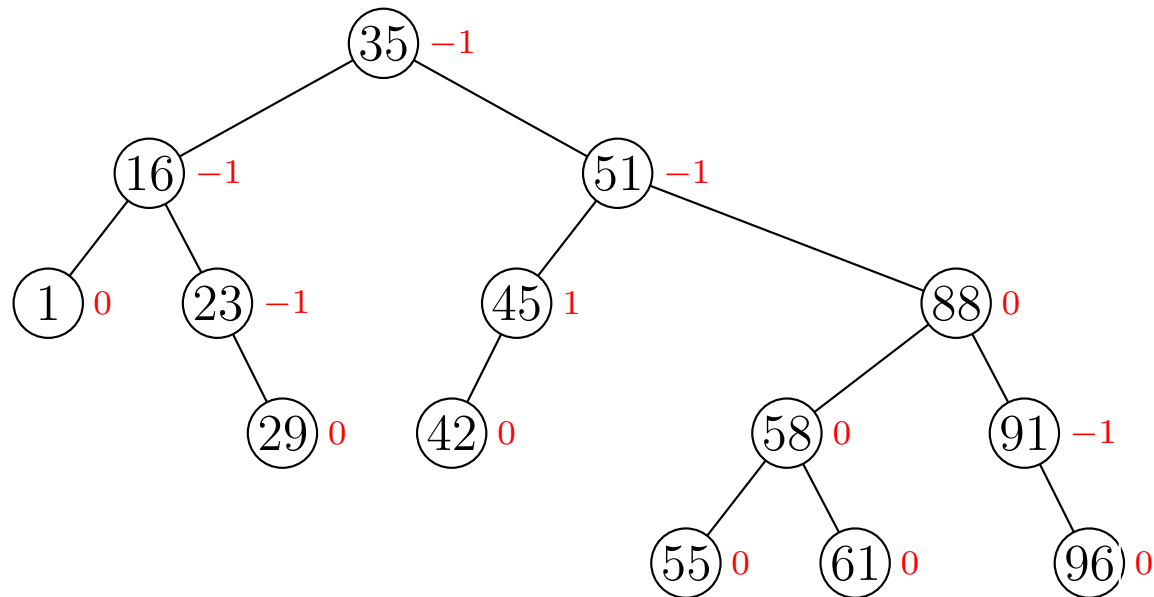


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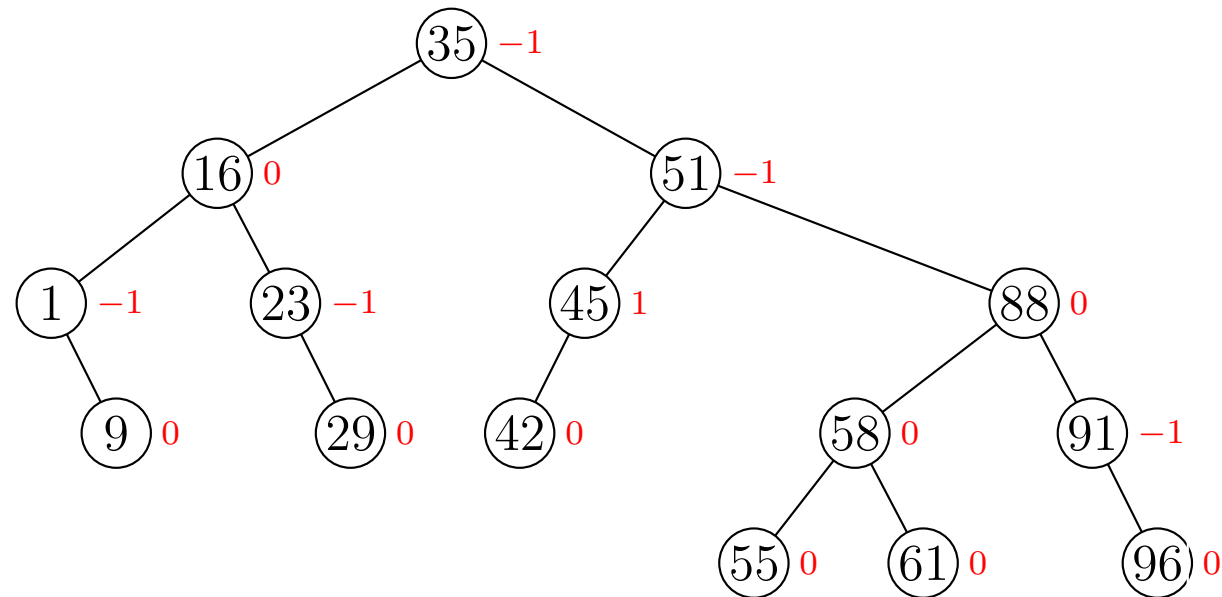
add(9)



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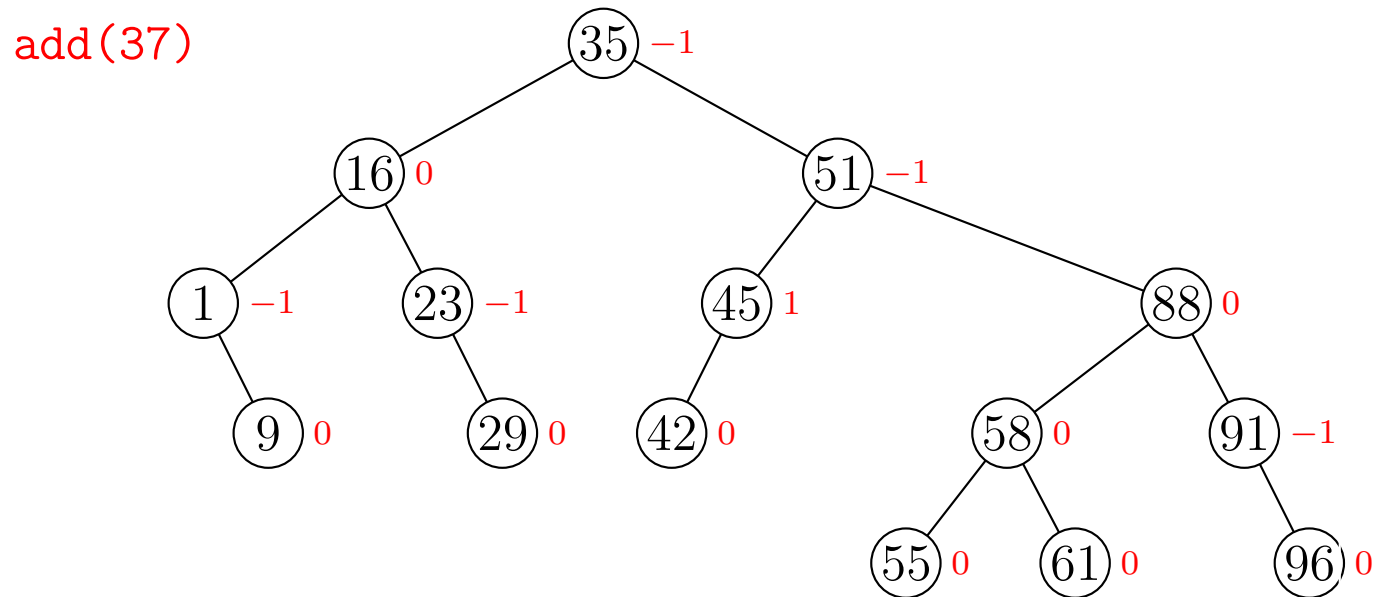
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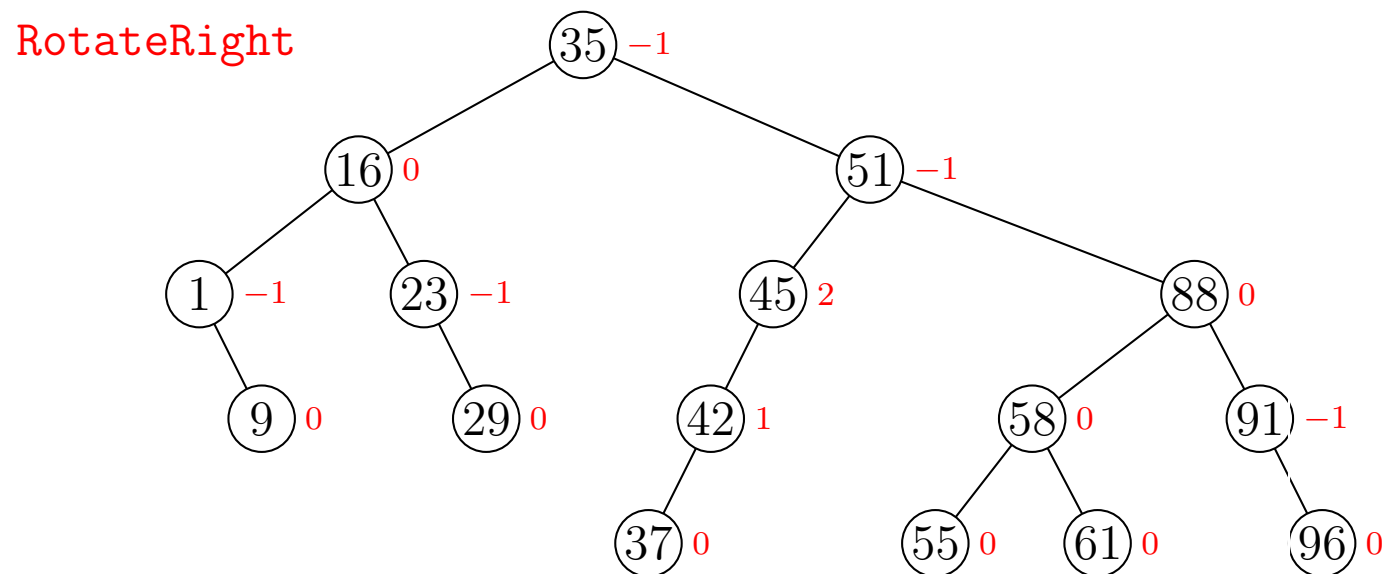
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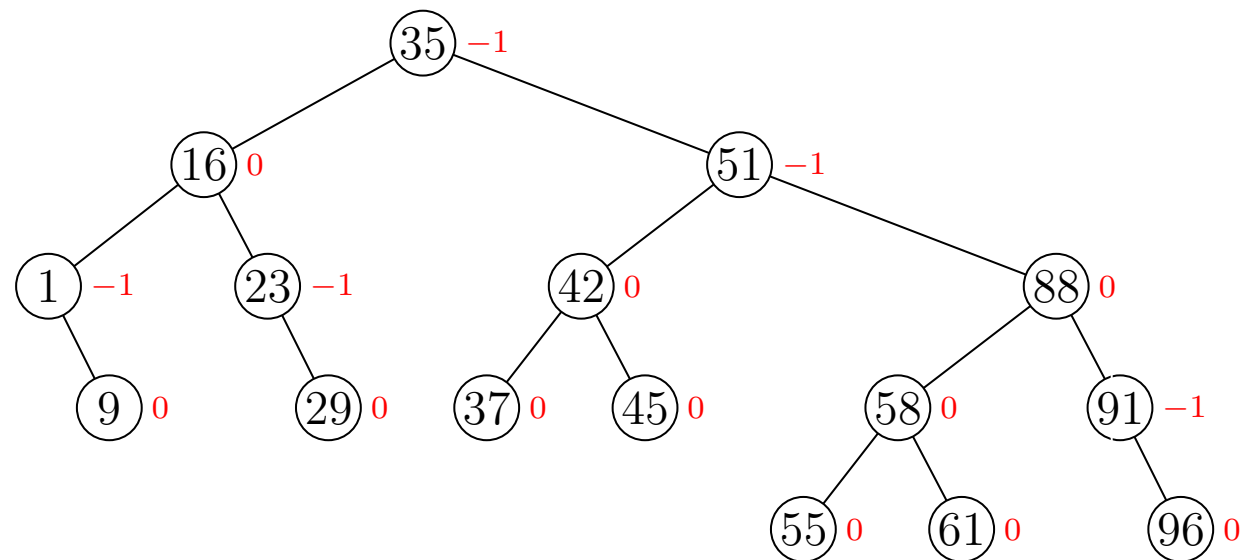
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Implementing AVL Trees

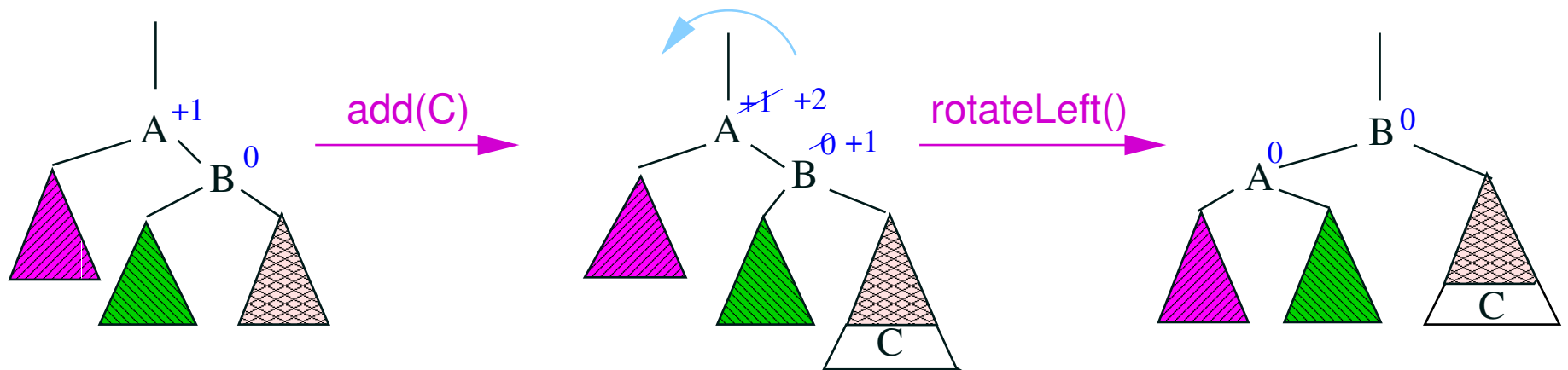
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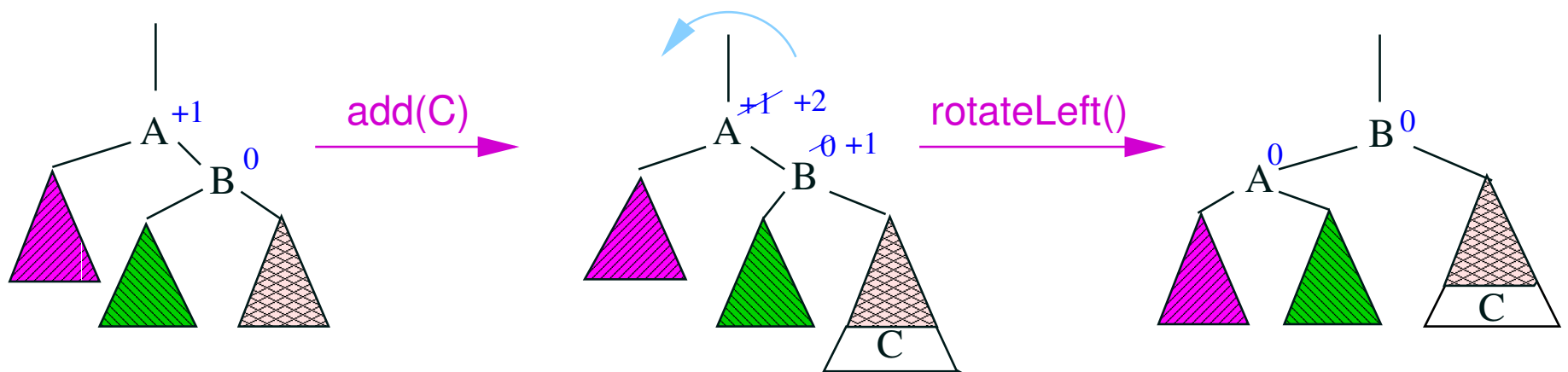
Balancing AVL Trees

- When adding an element to an AVL tree
 - ★ Find the location where it is to be inserted
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 - ★ **If** the balance factor exceeds ± 1 then re-balance the tree and stop
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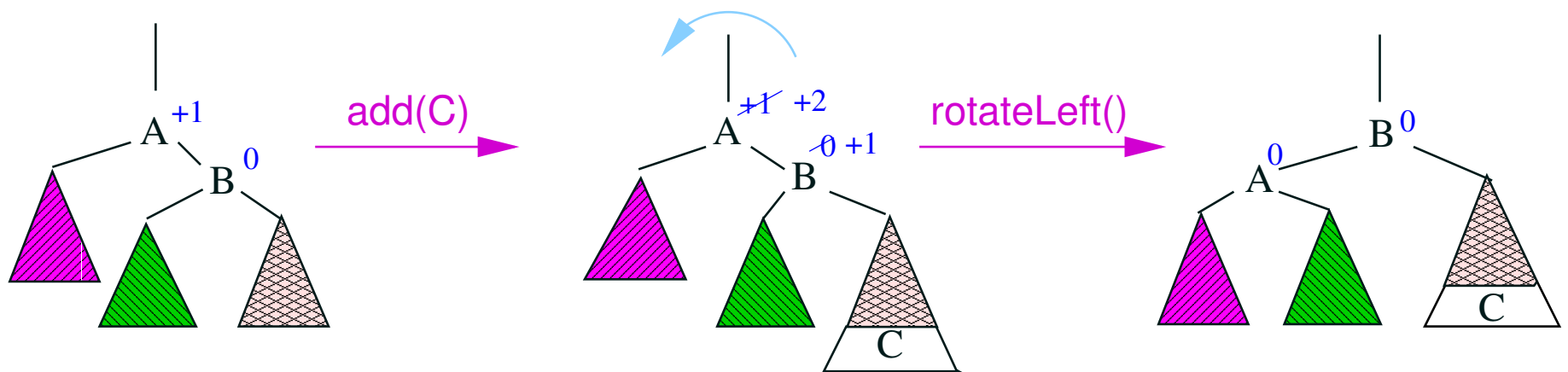
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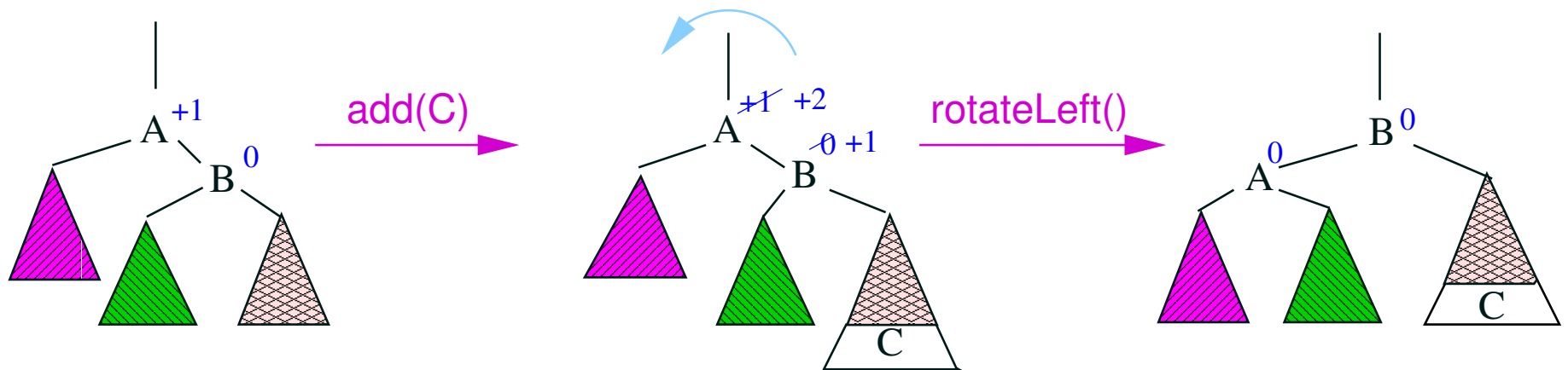
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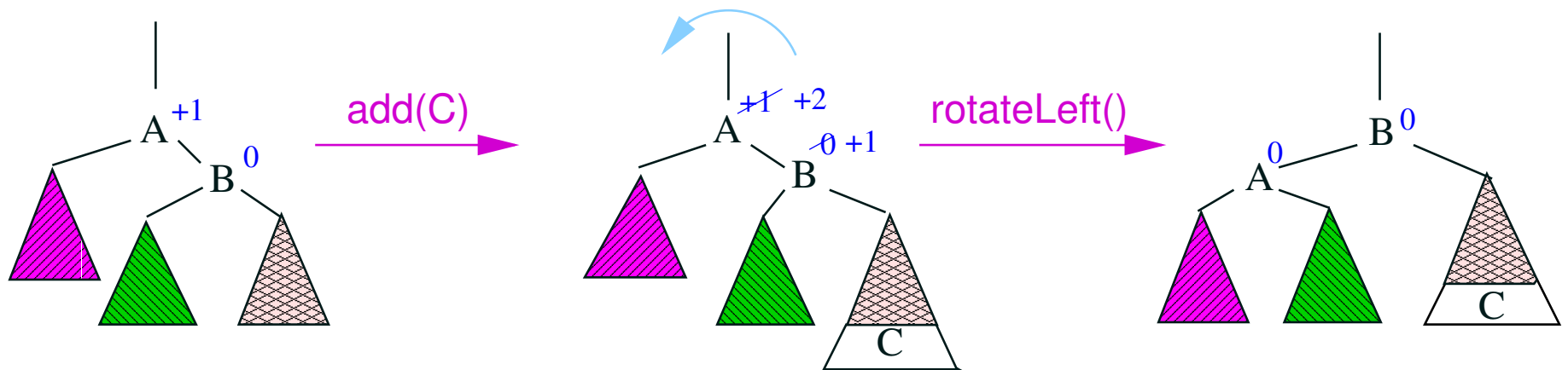
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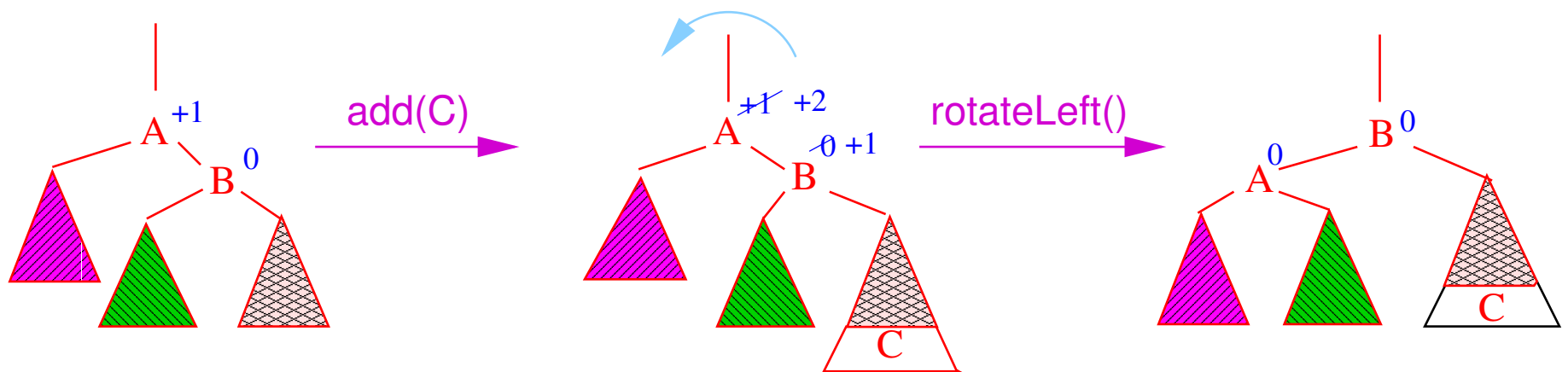
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AVL Deletions

- AVL deletions are similar to AVL insertions
- One difference is that after performing a rotation the tree may still not satisfy the AVL criteria so higher levels need to be examined
- In the worst case $\Theta(\log(n))$ rotations may be necessary
- This may be relatively slow—but in many applications deletions are rare

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AVL Tree Performance

- Insertion, deletion and search in AVL trees are, at worst, $\Theta(\log(n))$
- The height of an average AVL tree is $1.44 \log_2(n)$
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Outline

1. Deletion
2. Balancing Trees
 - Rotations
3. AVL
4. **Red-Black Trees**
 - TreeSet
 - TreeMap

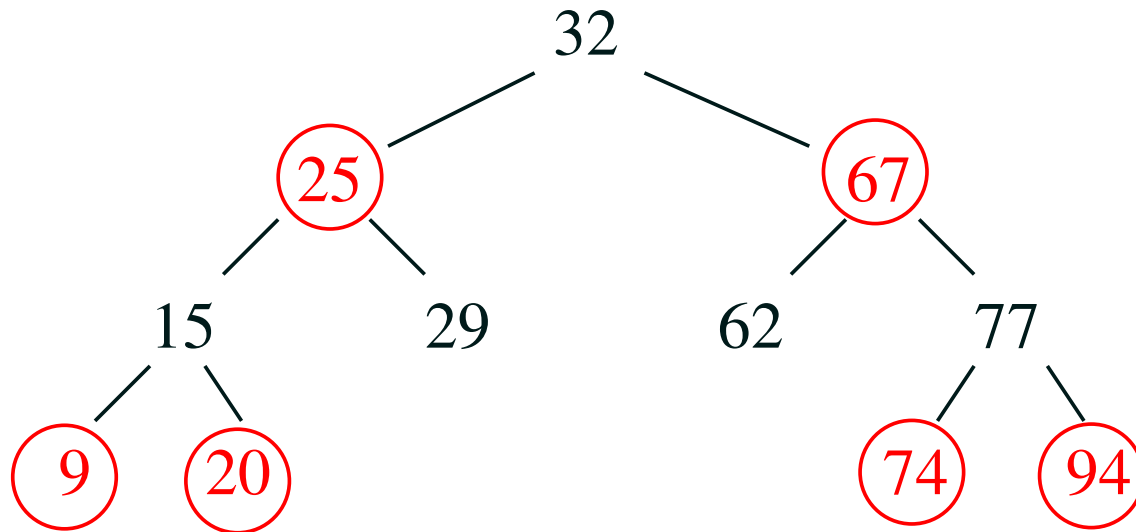


Red-Black Trees

- Red-black trees are another strategy for balancing trees
- Nodes are either *red* or *black*
- Two rules are imposed

Red Rule: the children of a red node must be black

Black Rule: the number of black elements must be the same in all paths from the root to elements with no children or with one child

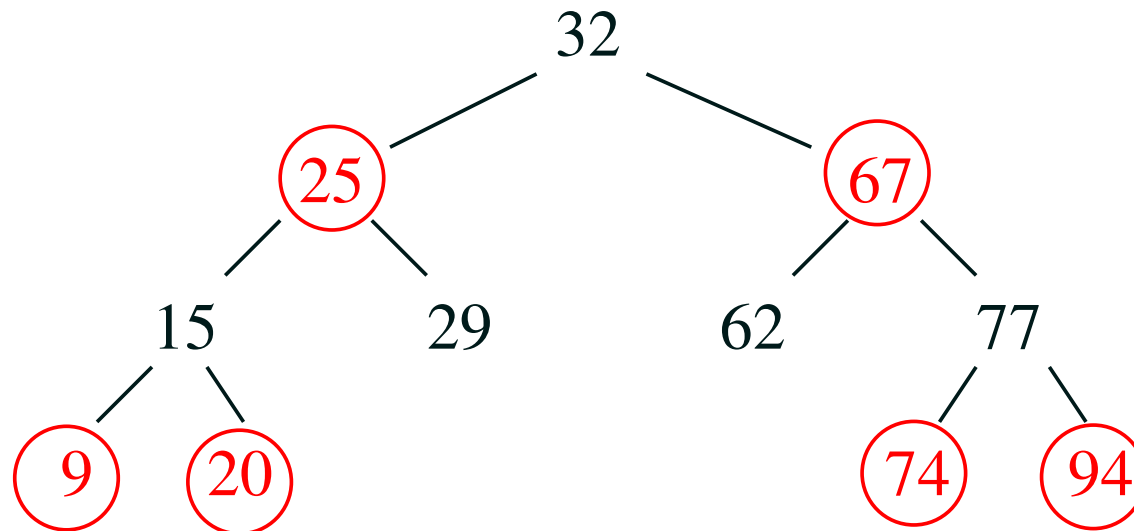


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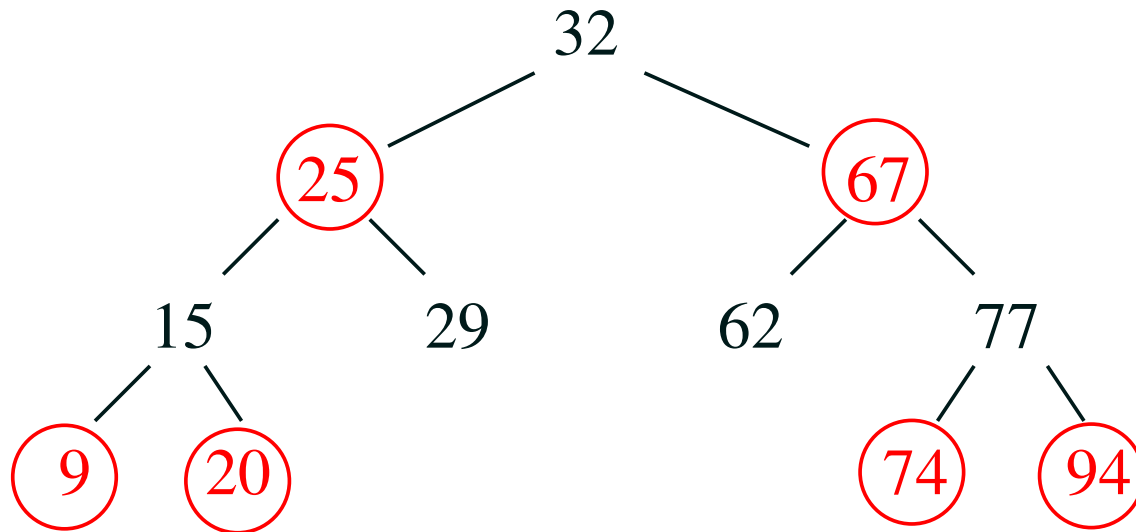


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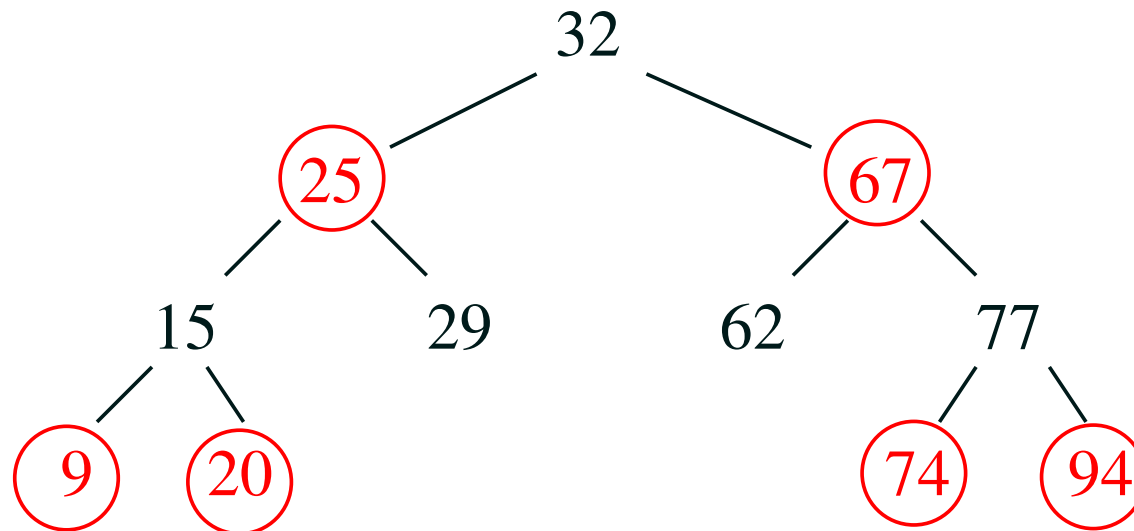


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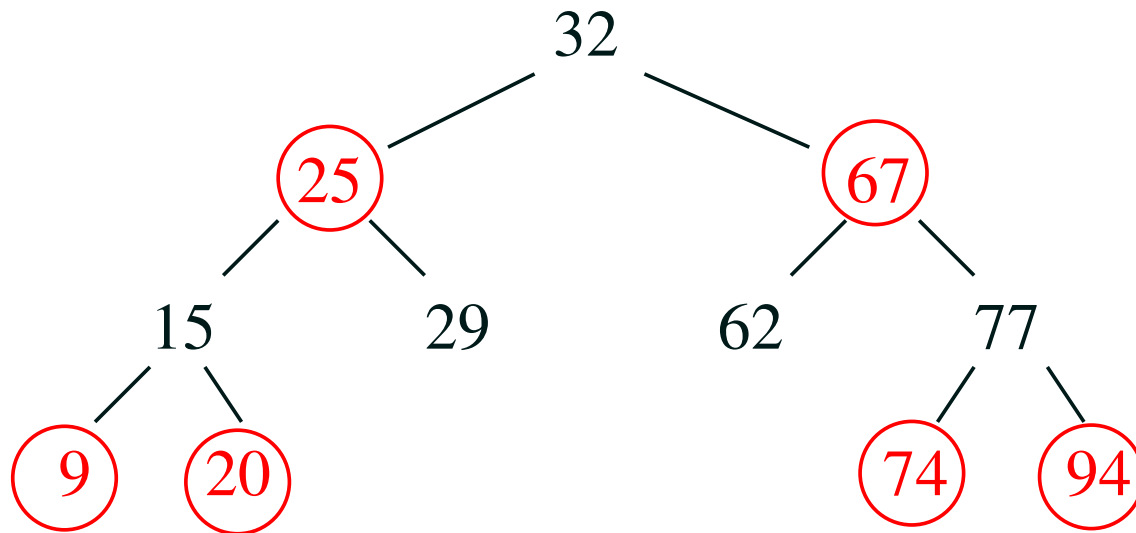


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- When inserting a new element we first find its position
- If it is the root we colour it black otherwise we colour it red
- If its parent is red we must either relabel or restructure the tree

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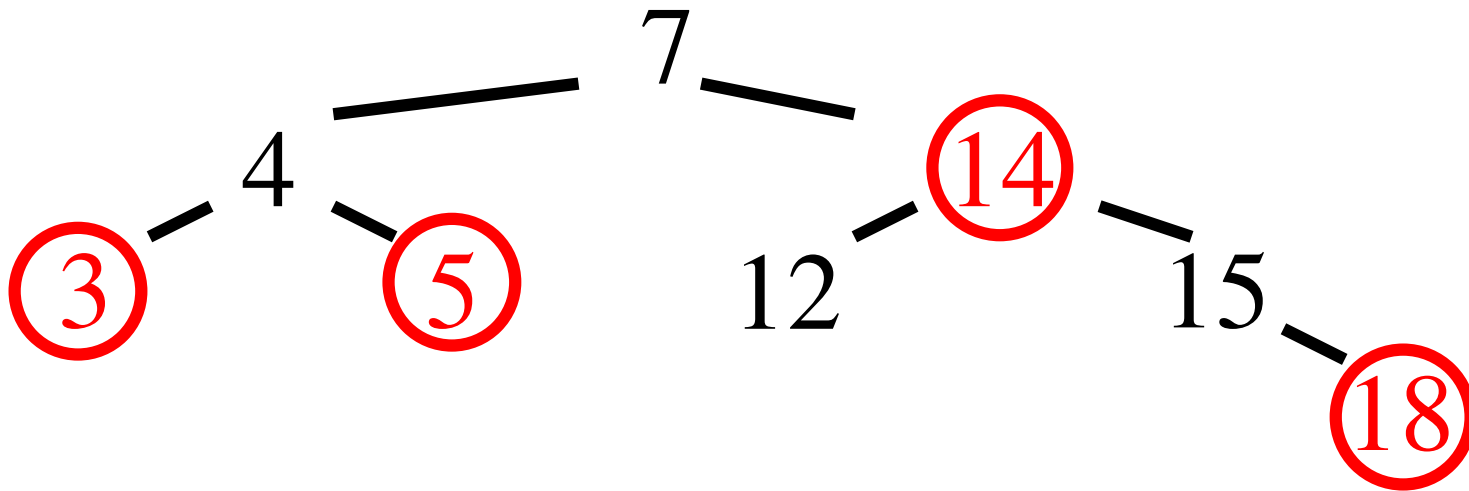
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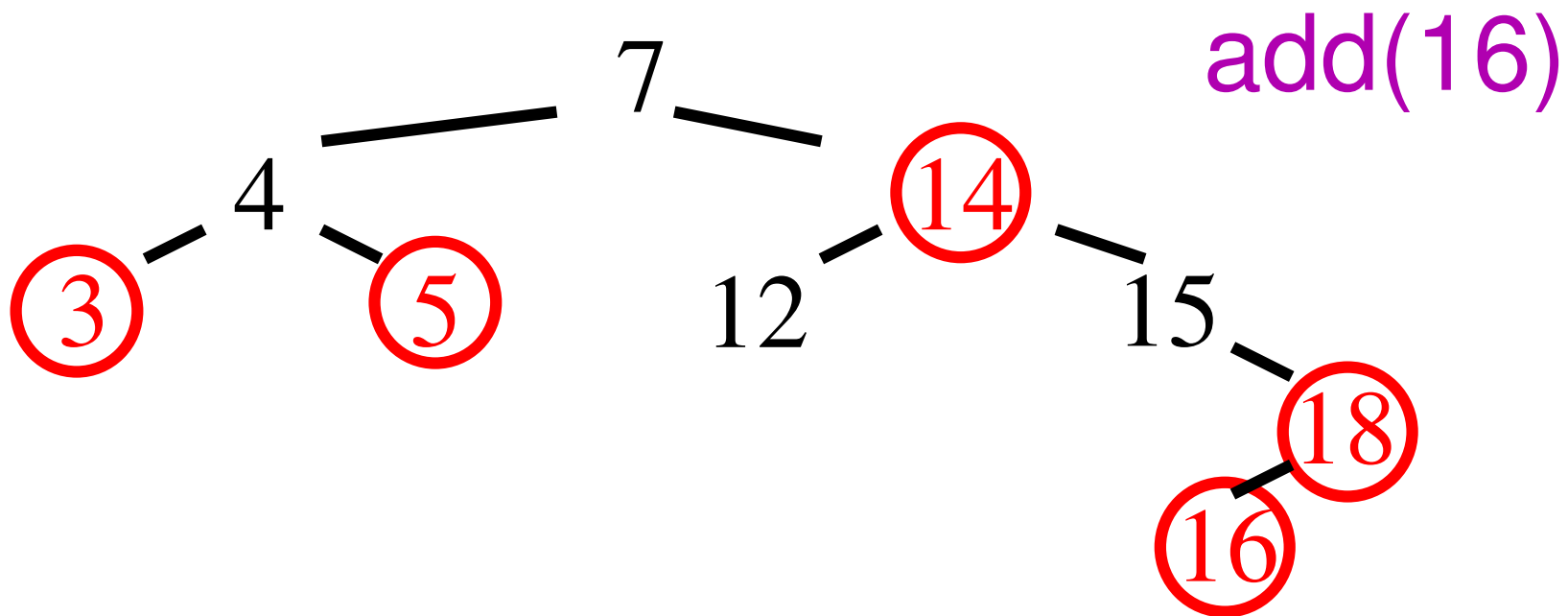
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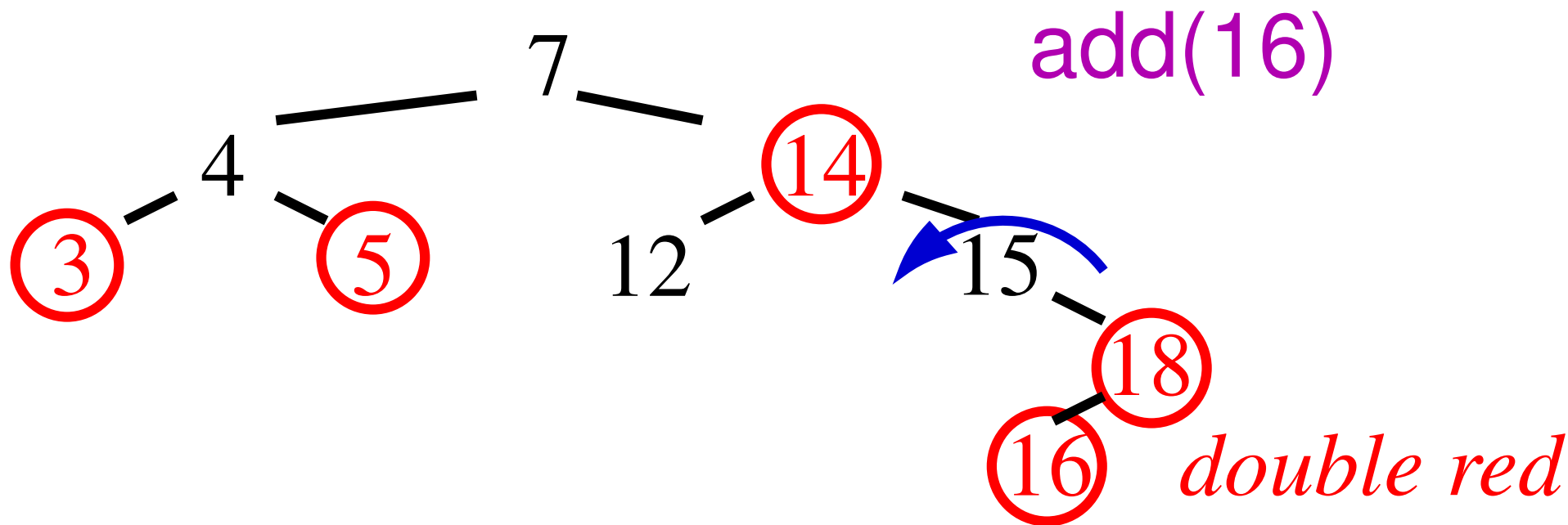
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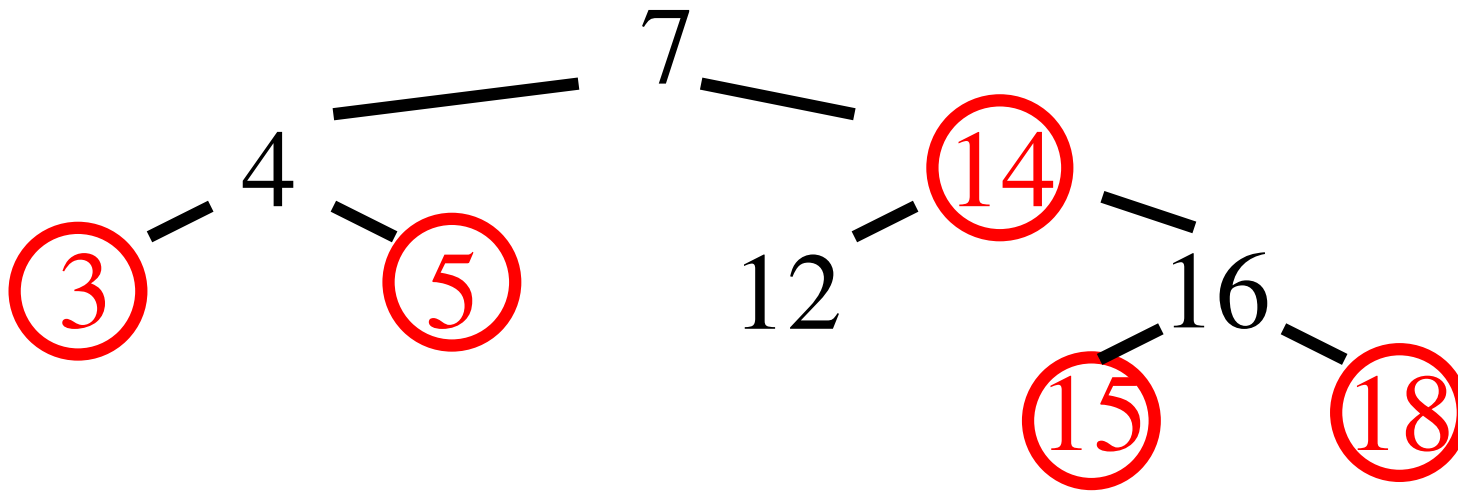
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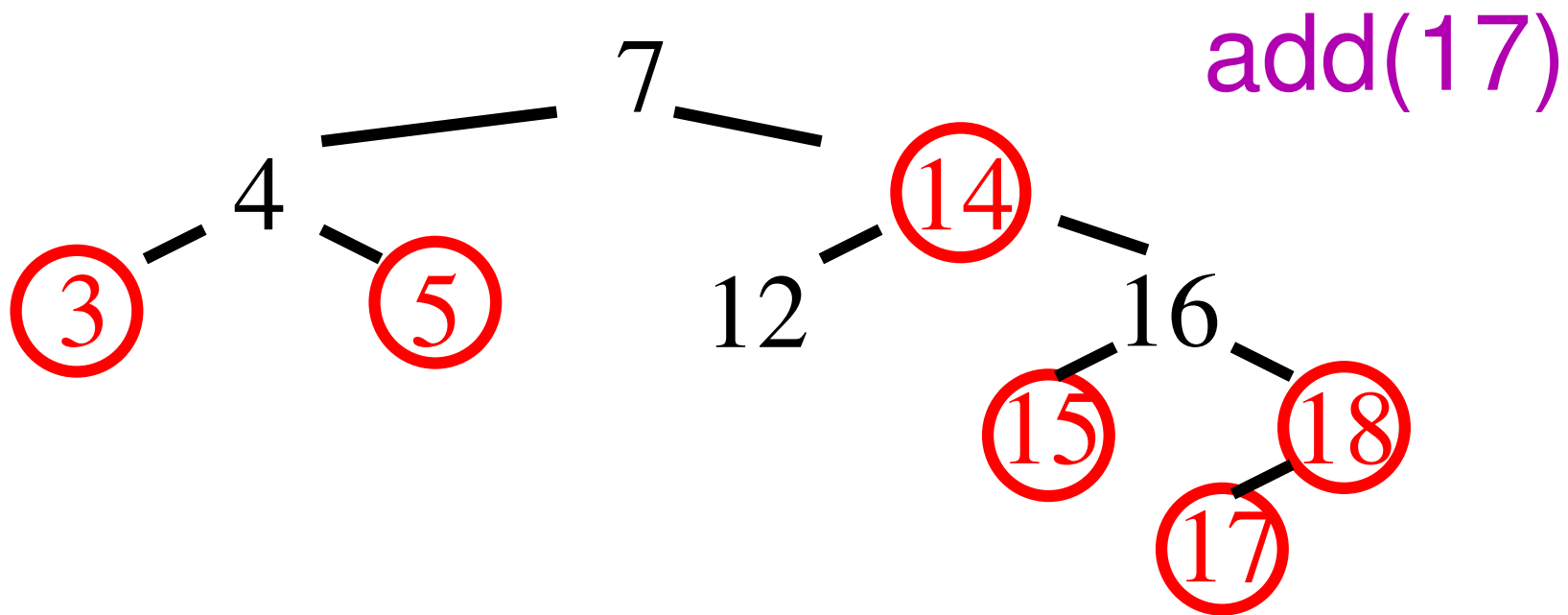
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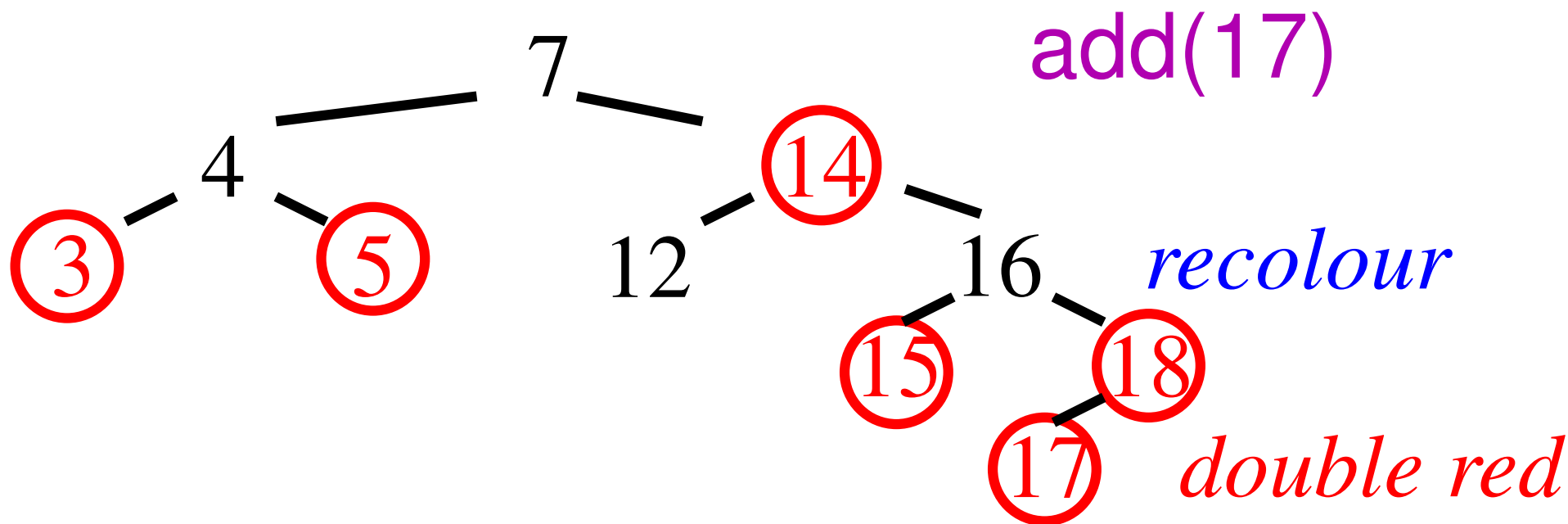
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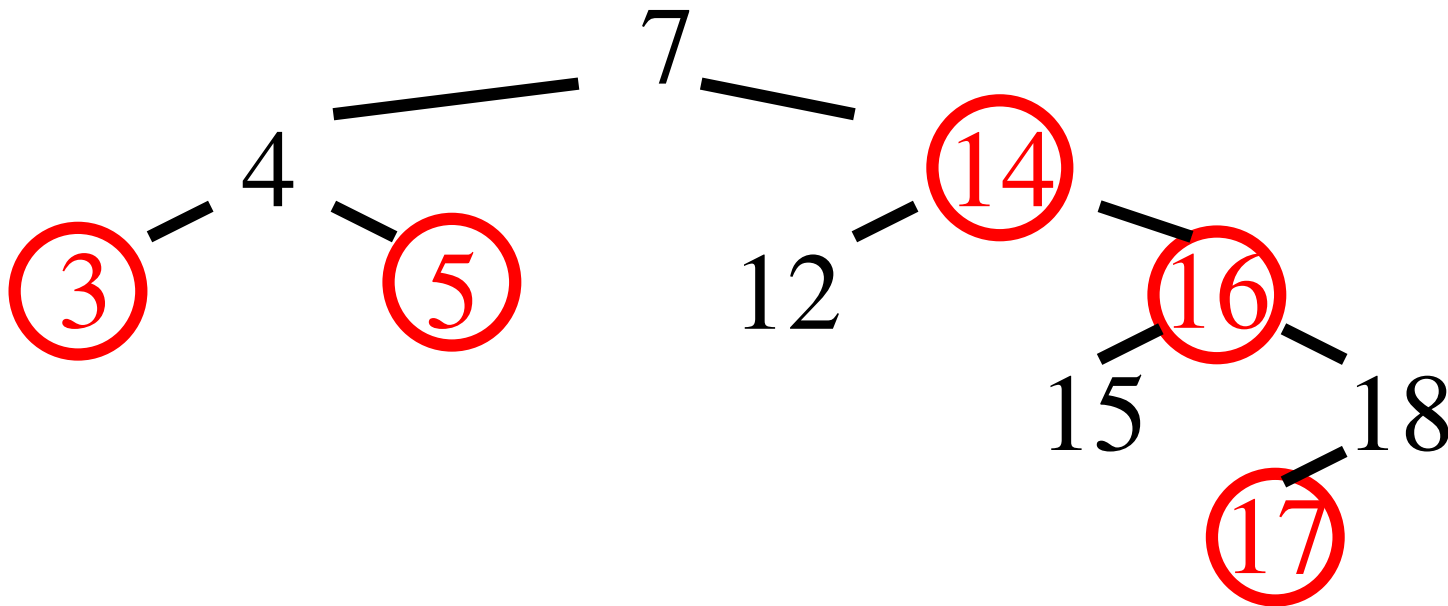
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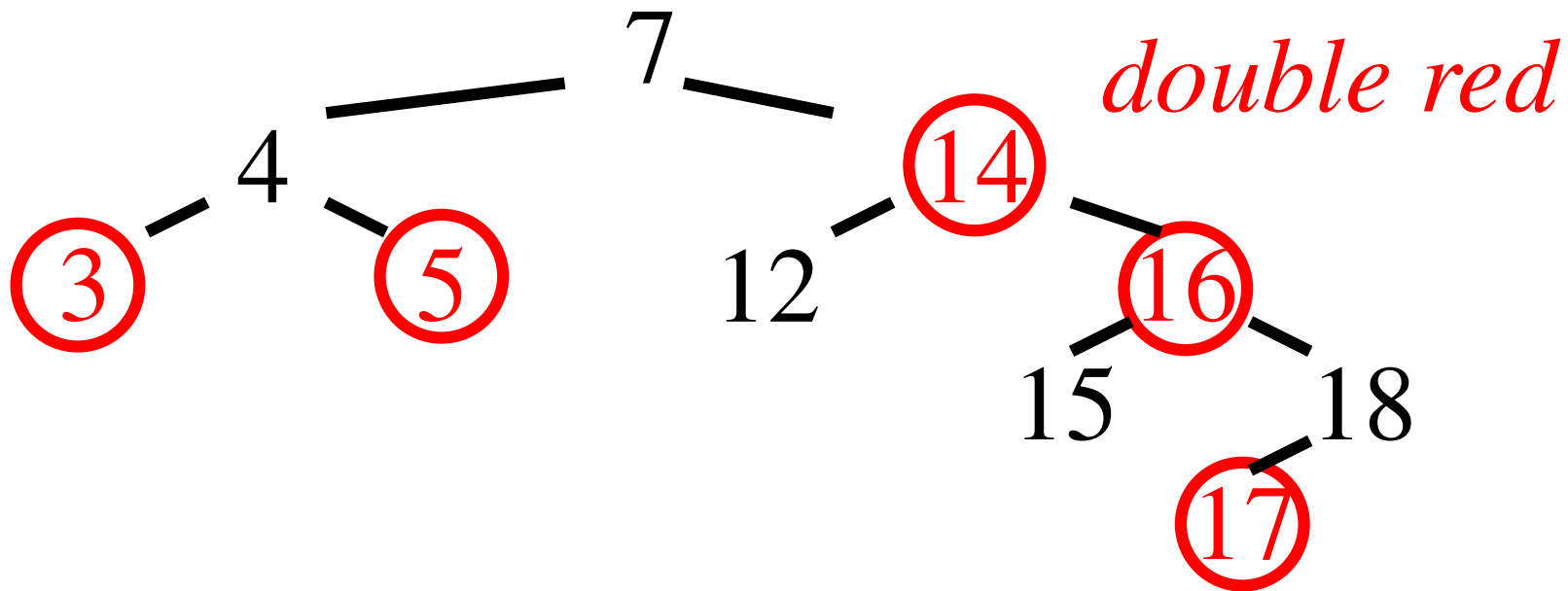
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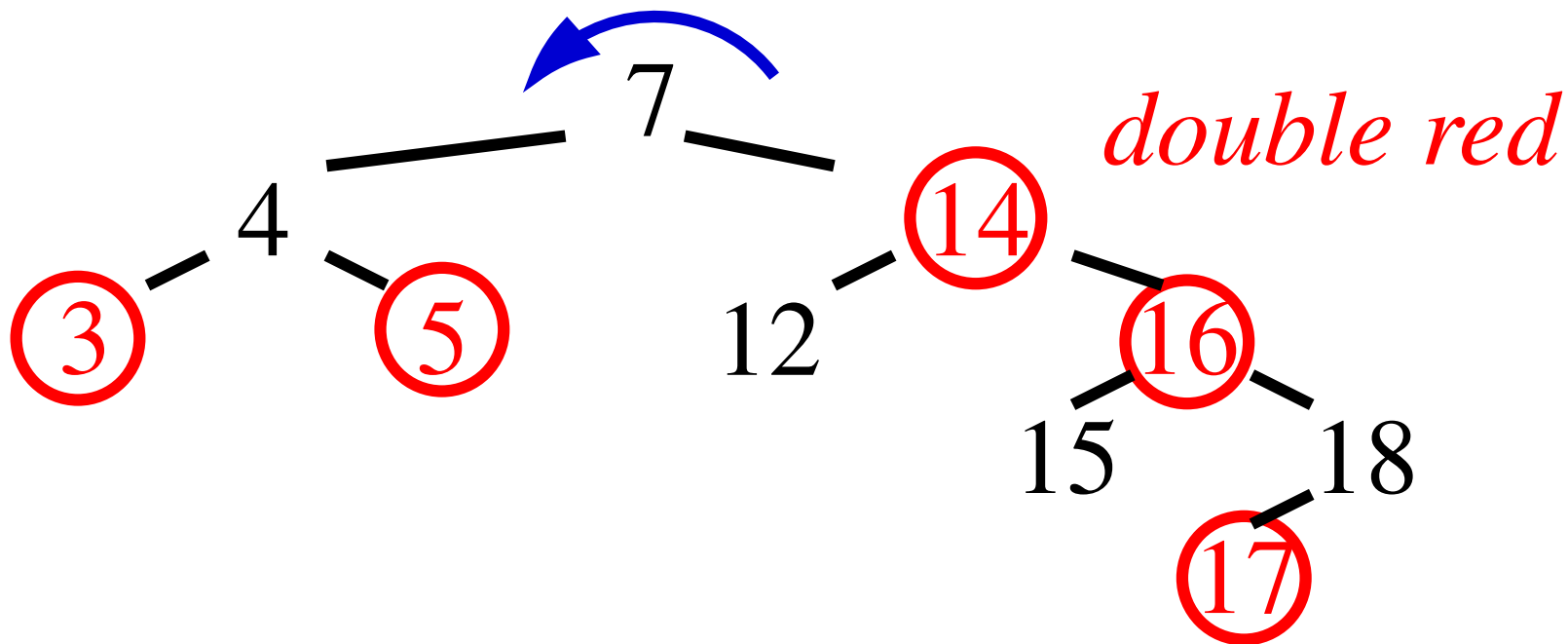
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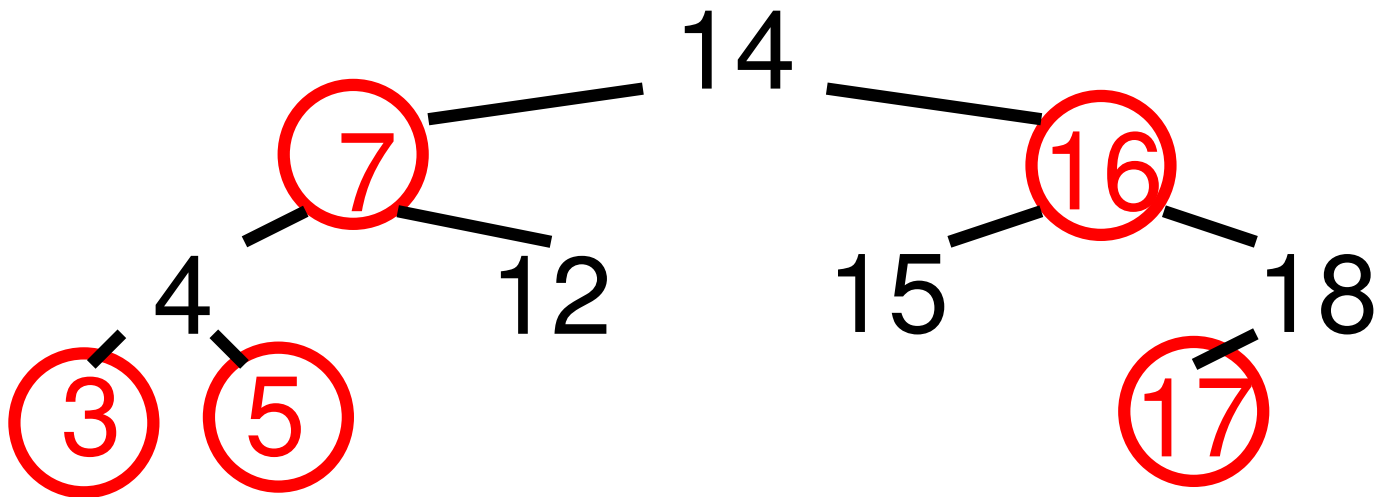
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- Red-black trees are slightly more complicated to code than AVL trees
- Red-black trees tend to be slightly less compact than AVL trees
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- It also has a `std::unordered_set<T>` class (which uses a hash table covered later)
- As well as `std::multiset<T>` that implements a multiset (i.e. a set, but with repetitions)
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Maps

- One major abstract data type (ADT) we have not encountered is the map class
- The map class `std::map<Key, V>` contain key-value pairs `pair<Key, V>`
 - ★ The first element of type `Key` is the **key**
 - ★ The second element of type `V` is the **value**
- Maps work as content addressable arrays

```
map<string, int> students;
student["John_Smith"] = 89;
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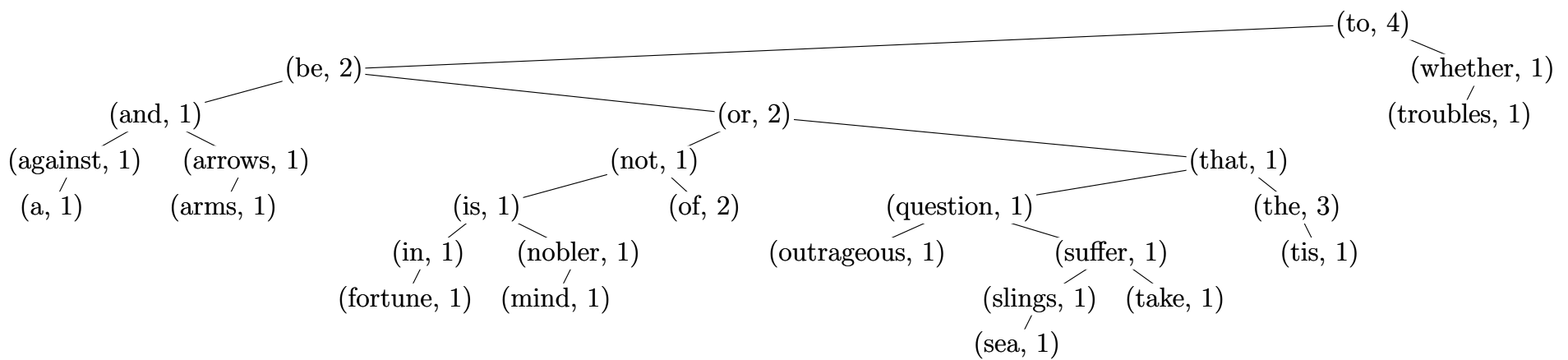
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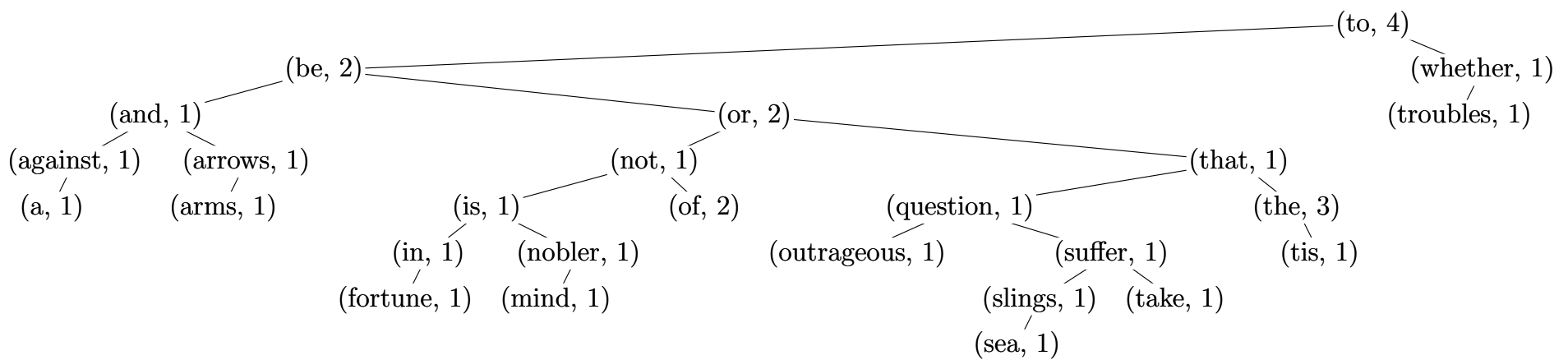


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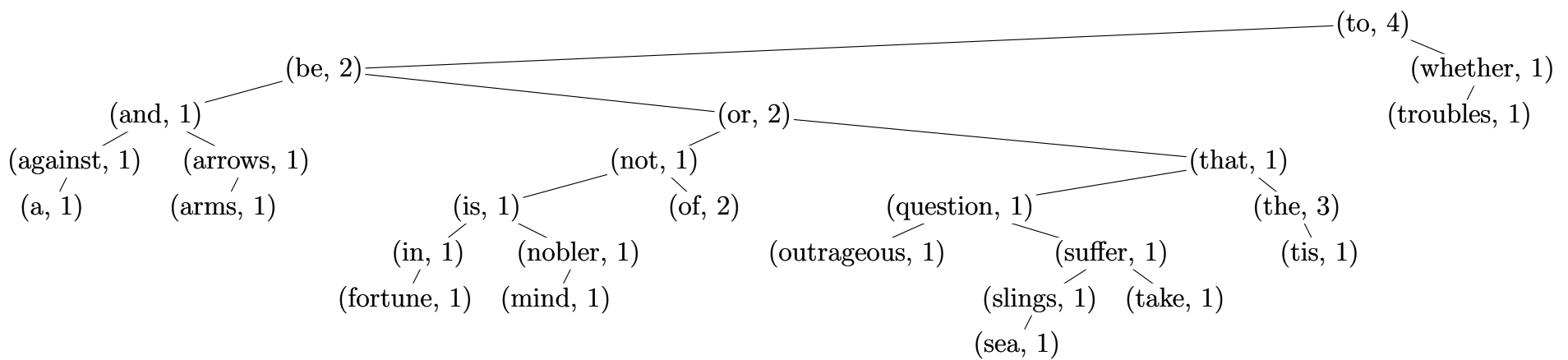


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