

Advanced Machine Learning Subsidiary Notes

Lecture 1: When Machine Learning Works

Adam Prügel-Bennett

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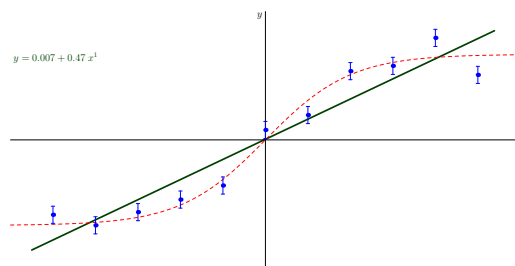
1 Keywords

- When ML Works, Bias Variance

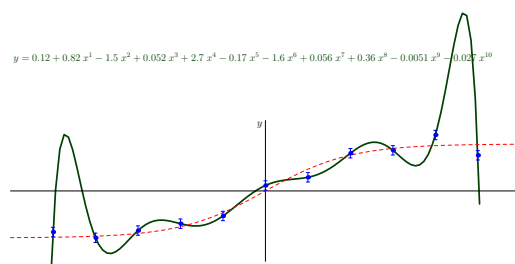
2 Main Points

2.1 Generalisation

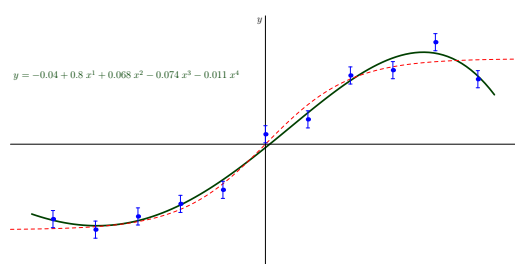
- We train our learning machines on a finite data set
- But we use our learning machines on unseen data
- If we have a too simple machine we might not be able to fit the training data and are unlikely to do well on unseen data



- If we have a too complicated machine we might be able to fit the training data almost perfectly, but we might have learnt a too complex rule that doesn't fit the test set



- Often there is a good compromise so that the learning machine learns a simple rule that fits the training data quite well but isn't too complicated



2.2 Bias-Variance Dilemmas

- We assume that we are trying to learn some function $f(\mathbf{x})$ where \mathbf{x} are feature vectors
- Our task is to learn a function $\hat{f}(\mathbf{x}|\mathcal{D})$ based on a training set \mathcal{D}
- We consider a scenario where we draw different training datasets \mathcal{D} from a distribution of training examples $p(\mathbf{x})$
- Each training set contains m independent examples
- We start from the definition of the *mean machine*

$$\hat{f}_m(\mathbf{x}) = \mathbb{E}_{\mathcal{D}} [\hat{f}(\mathbf{x}|\mathcal{D})]$$

- The mean machine makes a prediction by averaging the results of machines trained on all possible learning datasets (clearly this is a thought experiment and not something practical)
- Now the **bias** is equal to generalisation performance of mean machine

$$B = \sum_{\mathbf{x} \in \mathcal{X}} p(\mathbf{x}) \left(\hat{f}_m(\mathbf{x}) - f(\mathbf{x}) \right)^2$$

- We consider the expected generalisation loss for a randomly drawn dataset
 - For any particular dataset we might do better or worse than this expected generalisation loss

$$\begin{aligned} \bar{L}_G &\stackrel{(1)}{=} \mathbb{E}_{\mathcal{D}} [L_G(\mathcal{D})] \stackrel{(2)}{=} \mathbb{E}_{\mathcal{D}} \left[\sum_{\mathbf{x} \in \mathcal{X}} p(\mathbf{x}) \left(\hat{f}(\mathbf{x}|\mathcal{D}) - f(\mathbf{x}) \right)^2 \right] \\ &\stackrel{(3)}{=} \sum_{\mathbf{x} \in \mathcal{X}} p(\mathbf{x}) \mathbb{E}_{\mathcal{D}} \left[\left(\hat{f}(\mathbf{x}|\mathcal{D}) - f(\mathbf{x}) \right)^2 \right] \\ &\stackrel{(4)}{=} \sum_{\mathbf{x} \in \mathcal{X}} p(\mathbf{x}) \mathbb{E}_{\mathcal{D}} \left[\left(\left(\hat{f}(\mathbf{x}|\mathcal{D}) - \hat{f}_m(\mathbf{x}) \right) + \left(\hat{f}_m(\mathbf{x}) - f(\mathbf{x}) \right) \right)^2 \right] \\ &\stackrel{(5)}{=} \sum_{\mathbf{x} \in \mathcal{X}} p(\mathbf{x}) \left(\mathbb{E}_{\mathcal{D}} \left[\left(\hat{f}(\mathbf{x}|\mathcal{D}) - \hat{f}_m(\mathbf{x}) \right)^2 + \left(\hat{f}_m(\mathbf{x}) - f(\mathbf{x}) \right)^2 \right] \right. \\ &\quad \left. + 2 \mathbb{E}_{\mathcal{D}} \left[\left(\hat{f}(\mathbf{x}|\mathcal{D}) - \hat{f}_m(\mathbf{x}) \right) \left(\hat{f}_m(\mathbf{x}) - f(\mathbf{x}) \right) \right] \right) \end{aligned}$$

- (1) This is the definition of the expected generalisation loss, \bar{L}_G
- (2) The generalisation loss is the squared difference between the prediction of the learning machine, $\hat{f}(\mathbf{x}|\mathcal{D})$, and the true function, $f(\mathbf{x})$, averaged over all possible input feature vectors, \mathbf{x} , weighted by the probability of the input, $p(\mathbf{x})$
- (3) We exchange the sum and expectation
- (4) We add and subtract the prediction of the mean machine
- (5) We expand out the sum
- The cross term cancels

$$\begin{aligned} C &= \mathbb{E}_{\mathcal{D}} \left[\left(\hat{f}(\mathbf{x}|\mathcal{D}) - \hat{f}_m(\mathbf{x}) \right) \left(\hat{f}_m(\mathbf{x}) - f(\mathbf{x}) \right) \right] \\ &= \left(\mathbb{E}_{\mathcal{D}} [\hat{f}(\mathbf{x}|\mathcal{D})] - \hat{f}_m(\mathbf{x}) \right) \left(\hat{f}_m(\mathbf{x}) - f(\mathbf{x}) \right) \\ &= \left(\hat{f}_m(\mathbf{x}) - \hat{f}_m(\mathbf{x}) \right) \left(\hat{f}_m(\mathbf{x}) - f(\mathbf{x}) \right) = 0 \end{aligned}$$

- Note we use the following properties of expectations
 - (1) $\mathbb{E}[A + B] = \mathbb{E}[A] + \mathbb{E}[B]$
 - (2) $\mathbb{E}[cA] = c\mathbb{E}[A]$ where c doesn't depend on the random variable you are averaging over
 - (3) $\mathbb{E}[1] = 1$
- We are left with

$$\begin{aligned}\bar{L}_G &= \sum_{\mathbf{x} \in \mathcal{X}} p(\mathbf{x}) \mathbb{E}_{\mathcal{D}} \left[\left(\hat{f}(\mathbf{x}|\mathcal{D}) - \hat{f}_m(\mathbf{x}) \right)^2 + \left(\hat{f}_m(\mathbf{x}) - f(\mathbf{x}) \right)^2 \right] \\ &= \sum_{\mathbf{x} \in \mathcal{X}} p(\mathbf{x}) \mathbb{E}_{\mathcal{D}} \left[\left(\hat{f}(\mathbf{x}|\mathcal{D}) - \hat{f}_m(\mathbf{x}) \right)^2 \right] + \sum_{\mathbf{x} \in \mathcal{X}} p(\mathbf{x}) \left(\hat{f}_m(\mathbf{x}) - f(\mathbf{x}) \right)^2\end{aligned}$$

- Where we used the fact that the last term doesn't depend on the dataset
- The last term is equal to the bias, defined earlier as the generalisation performance of the mean machine
- The first term is known as the **variance**

$$V = \sum_{\mathbf{x} \in \mathcal{X}} p(\mathbf{x}) \mathbb{E}_{\mathcal{D}} \left[\left(\hat{f}(\mathbf{x}|\mathcal{D}) - \hat{f}_m(\mathbf{x}) \right)^2 \right]$$

- It measures how a single learning machine differs from the mean machine
- We therefore have $\bar{L}_G = B + V$ or

$$\text{Expected Generalisation Loss} = \text{Bias} + \text{Variance}$$

- The **Bias-Variance Dilemma** is that
 - Simple machines are likely to have high bias
 - * because any single machine can't represent the data well the mean machine won't be accurate
 - * this is true of the curve fitting example, but it is not true of decision trees where the average of many decision trees can learn a far more complex division boundary than a single machine
 - Complex machines are likely to have high variance
 - * Complex machines are likely to be sensitive to the training data whereas simpler machines (because of their lack of flexibility) aren't as sensitive
- A lot of this course will be looking at machines that cleverly resolve this dilemma

3 Experiments

Download the Jupyter Notebook

- This computes the training and generalisation loss as well as the bias and variance for arbitrary functions (at least approximately)
- We can do this because it is a 1-D function
- See if you can understand the code

3.1 Questions

- What is the effect of increasing the number of training points?
- What is the effect of using a more complex function, E.g. $e^{-x} \sin(x)$?