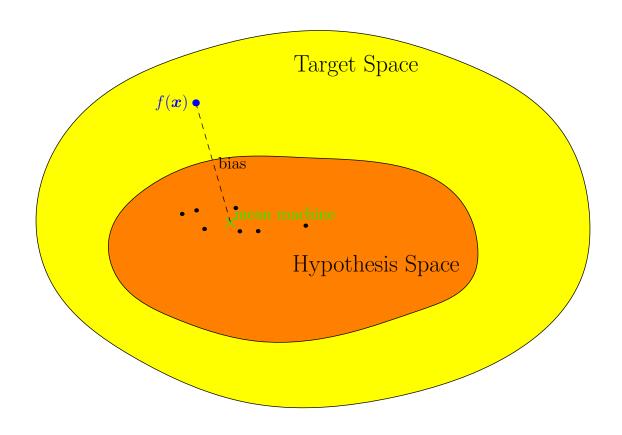
Advanced Machine Learning

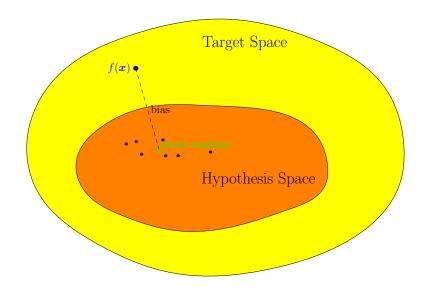
When Machine Learning Works



When ML Works, Bias Variance

Outline

- 1. What Makes a Good Learning Machine?
- 2. Bias-Variance Dilemma



- We want to understand why some machine learning techniques work well and other don't
- To understand why these works we need to understand what makes a good learning machine
- For this we have to get conceptual and think about generalisation performance

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- The problem can be over-constrained (i.e. we have conflicting data to deal with)
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- ullet We construct a learning machine that makes a prediction $\hat{f}(oldsymbol{x}|oldsymbol{ heta})$
- We typically choose the machine to minimise a *training loss*

$$L_T(\mathcal{D}) = \sum_{(\boldsymbol{x},y)\in\mathcal{D}} \left(\hat{f}(\boldsymbol{x}|\boldsymbol{\theta}) - y\right)^2$$

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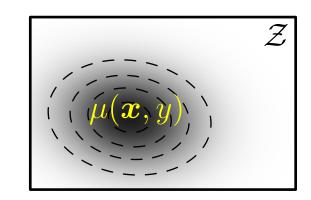
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ullet We call this machine $\hat{f}(oldsymbol{x}|oldsymbol{ heta}_{\mathcal{D}})$

Generalisation Error

• We want to minimise the generalisation loss which in this case is

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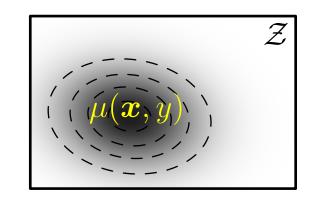
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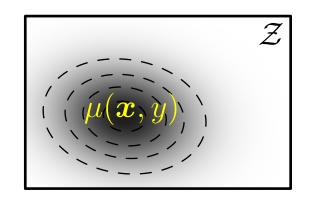
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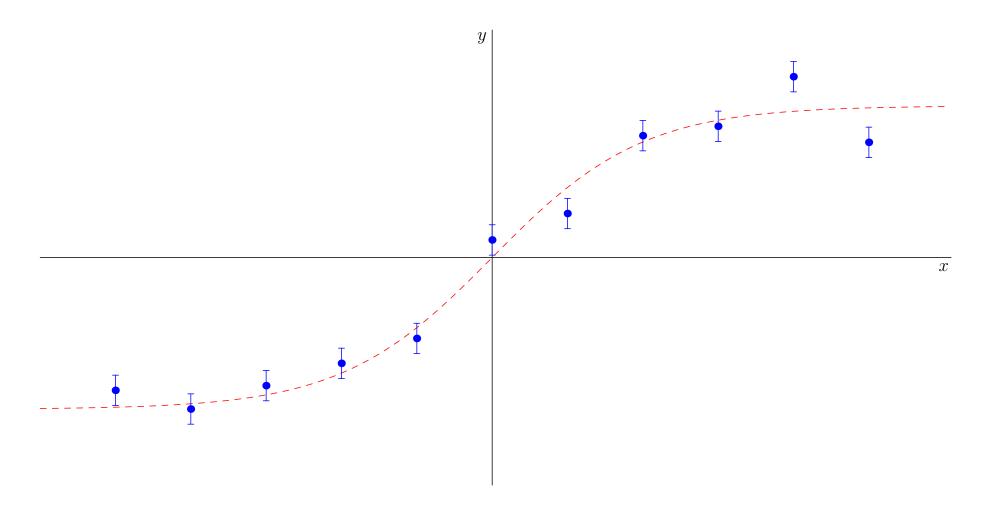
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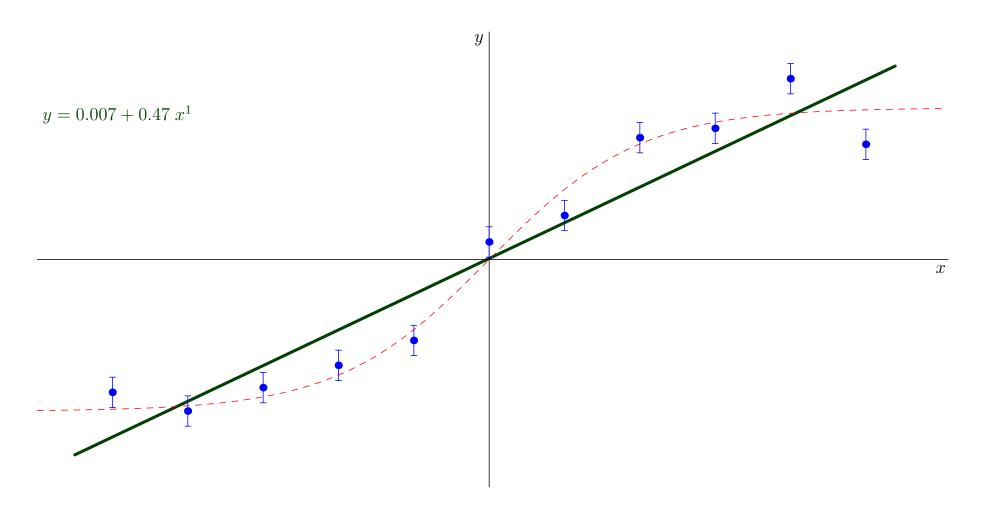
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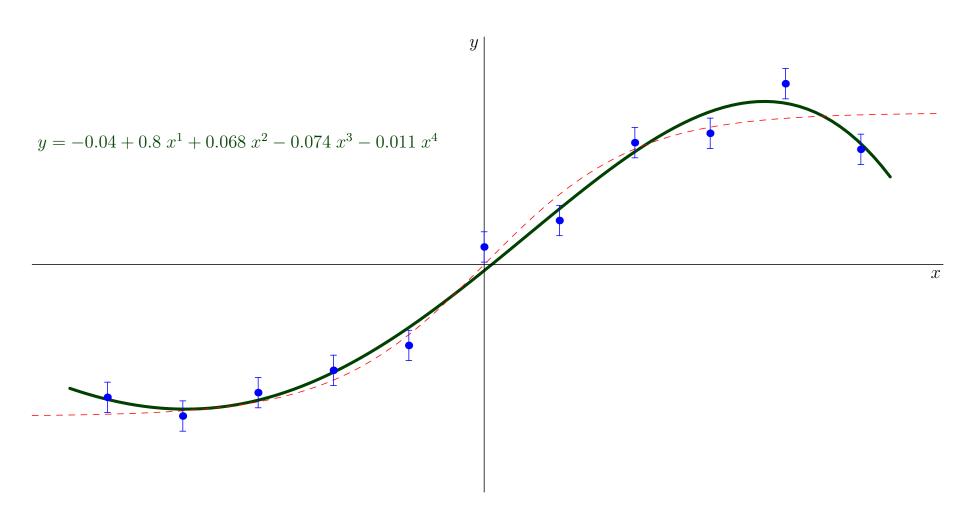


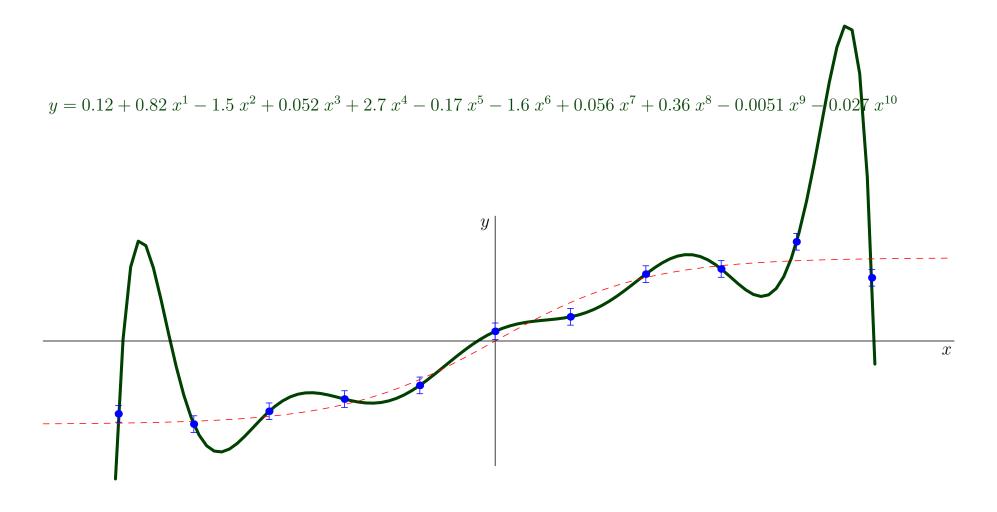
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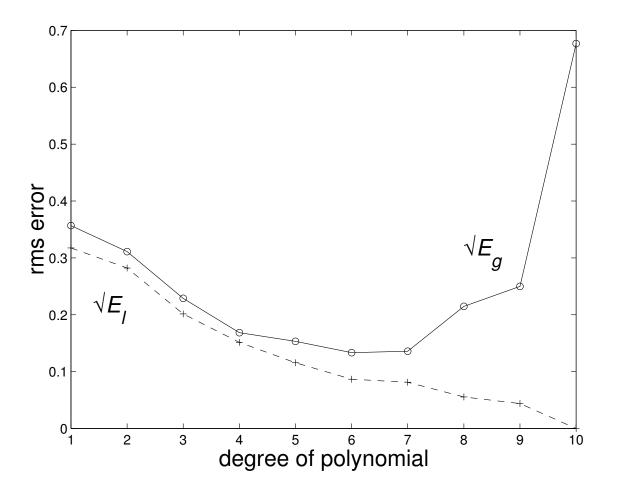






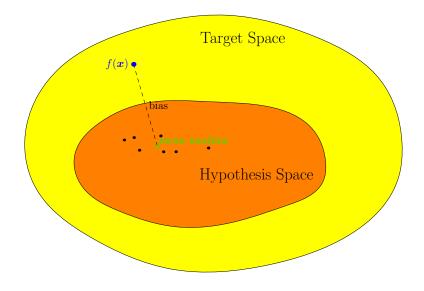
Measuring Generalisation Error for Regression

• Consider the regression example. The root mean squared error is



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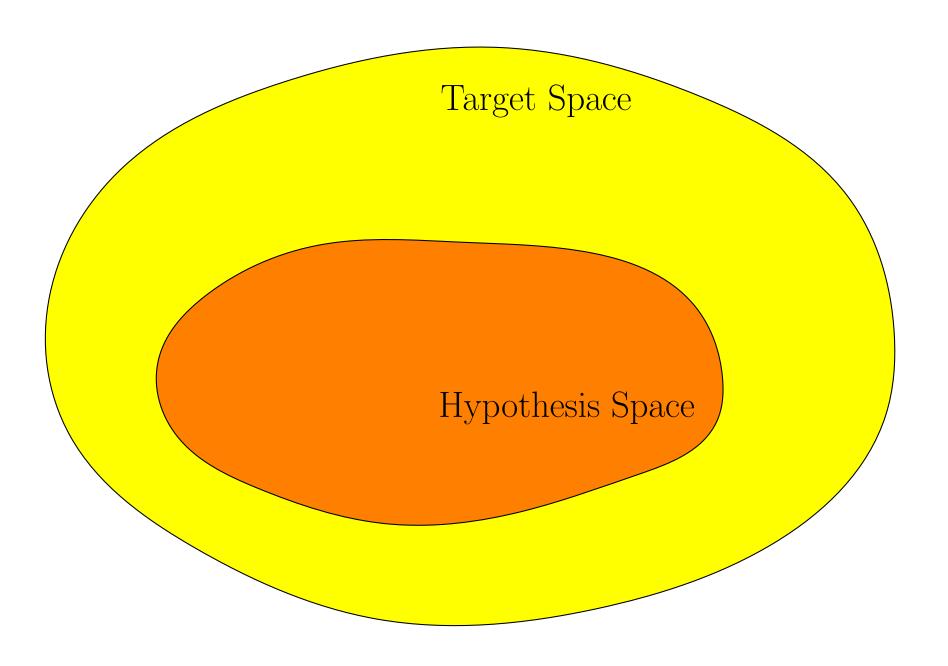


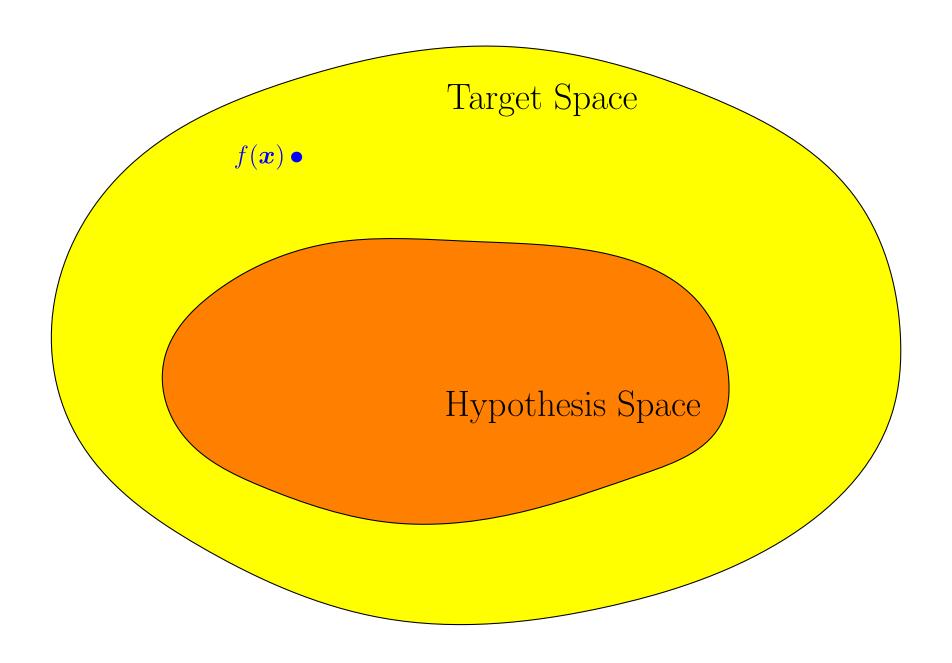
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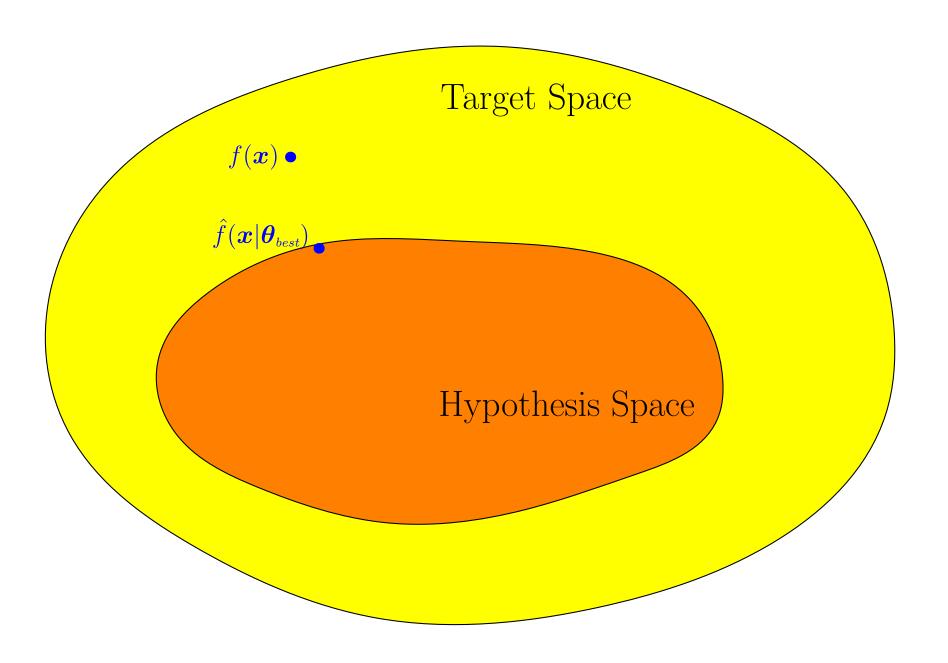
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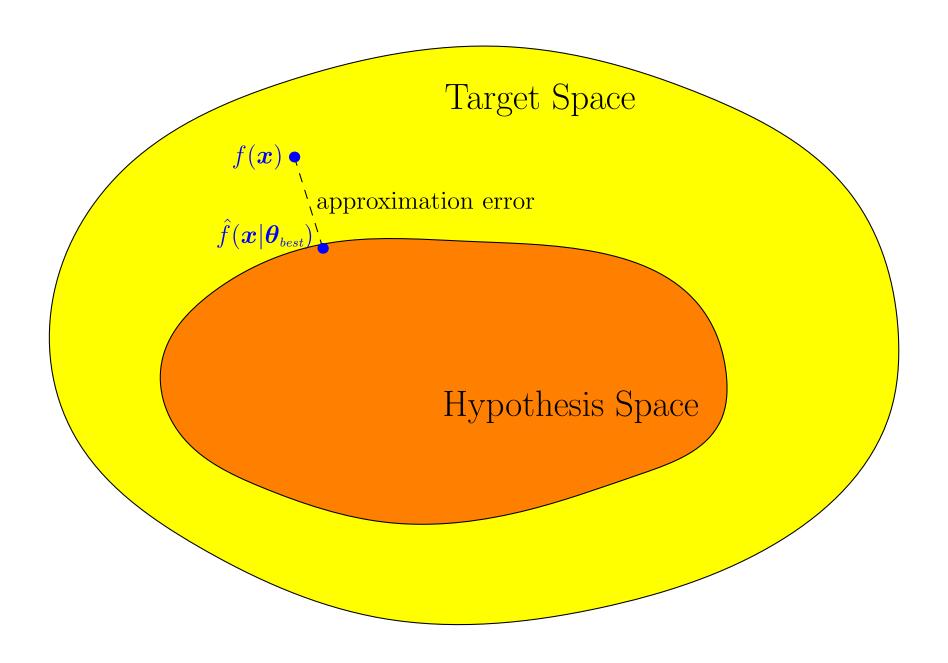
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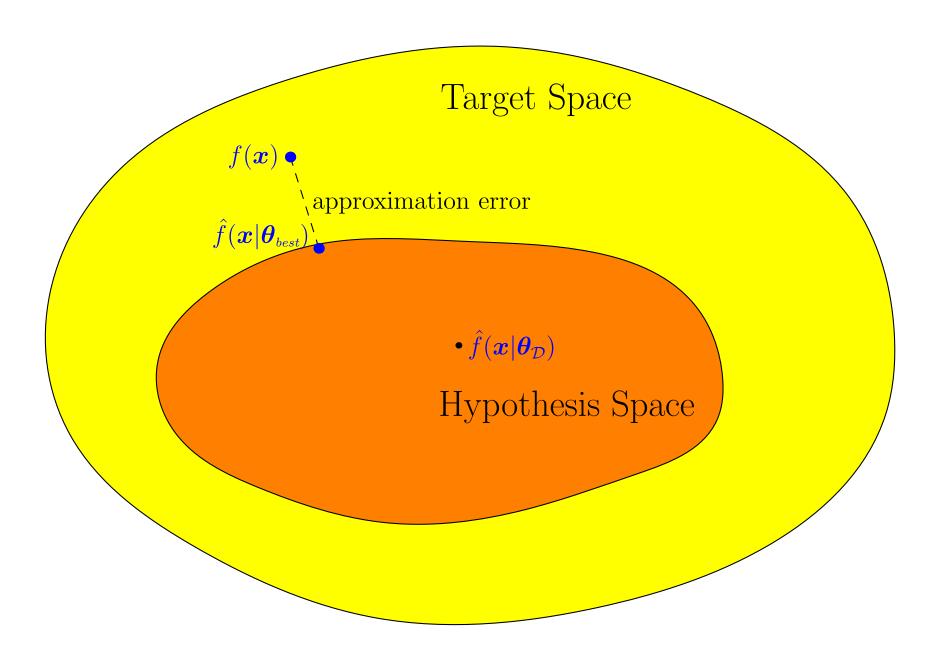
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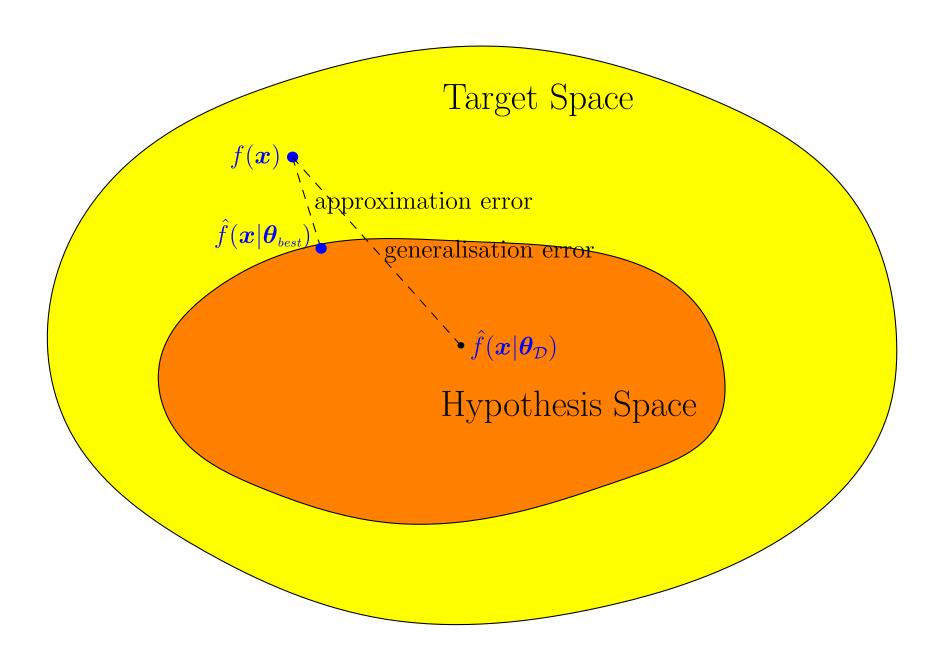


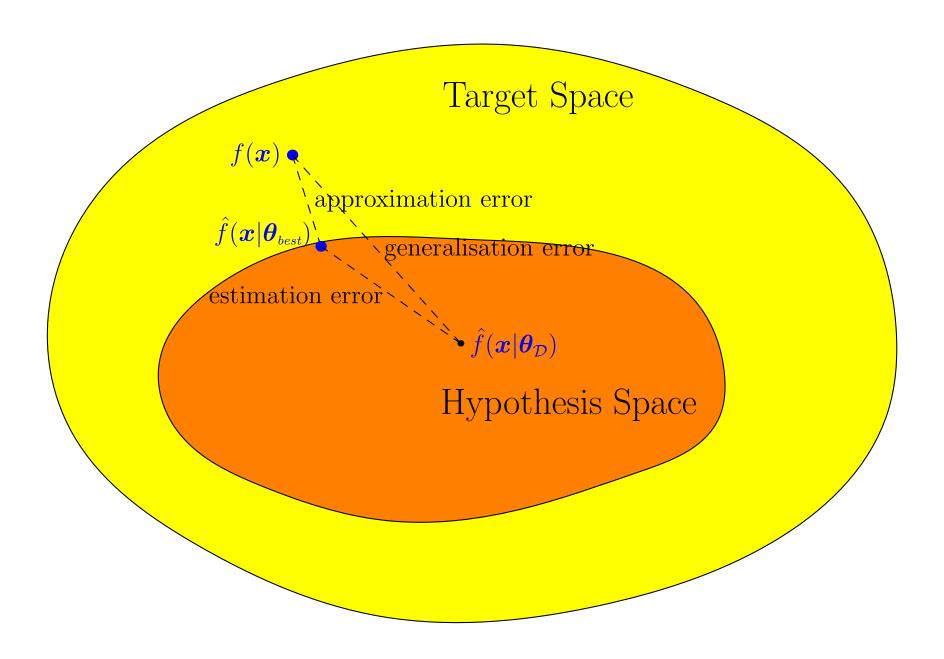


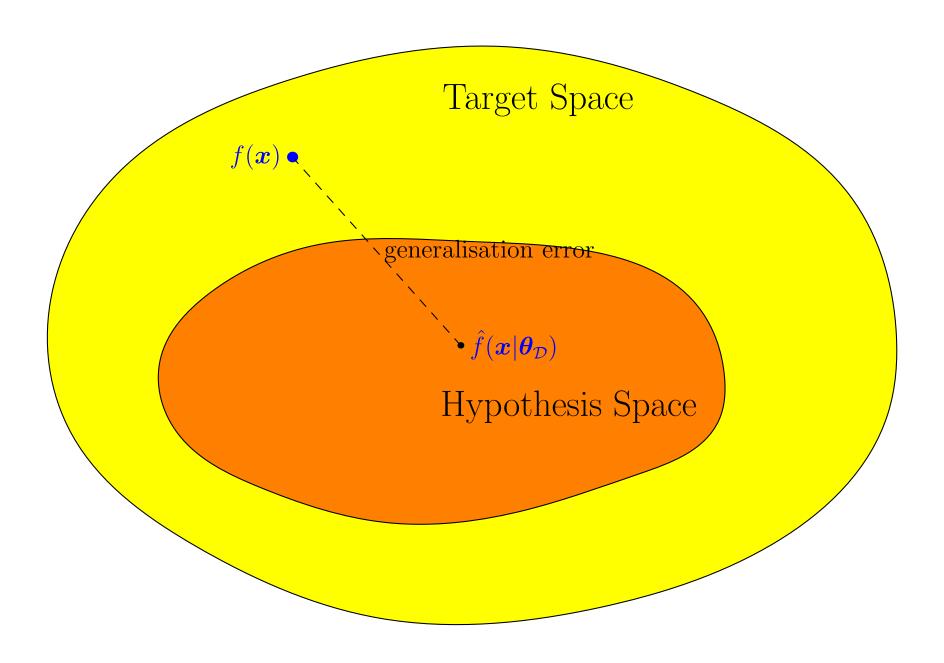


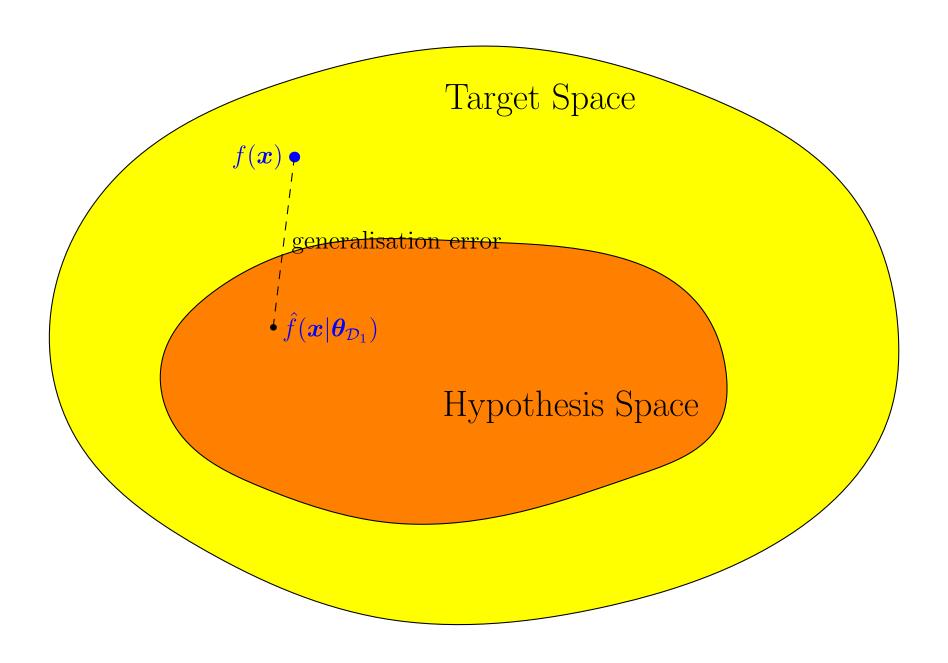


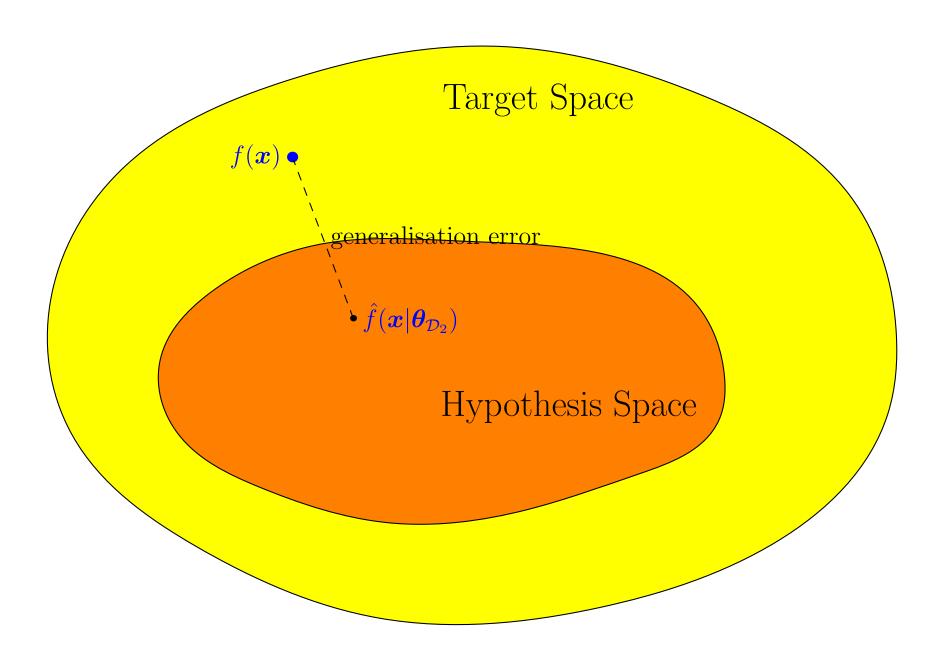


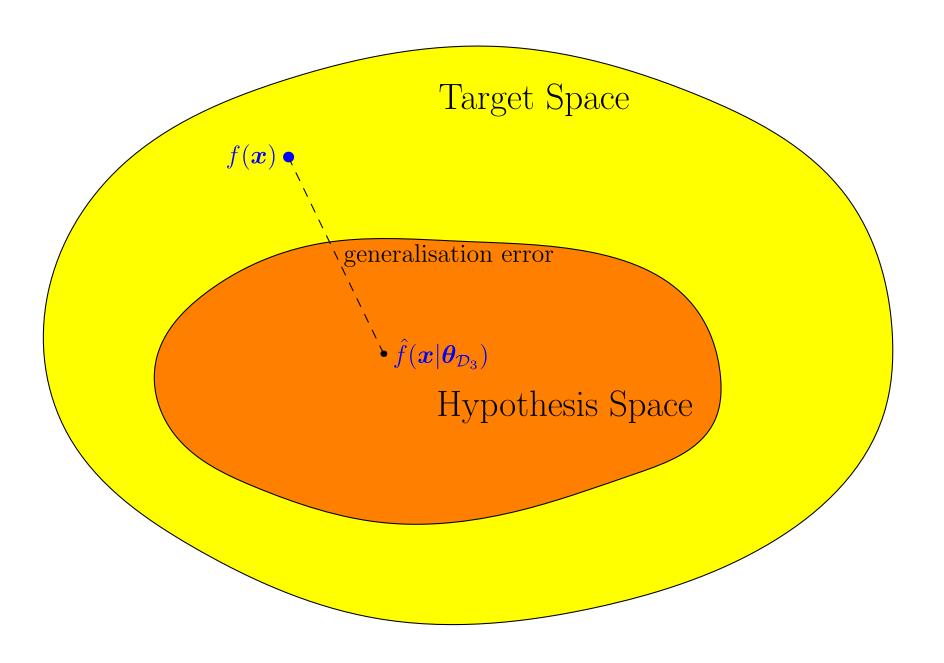


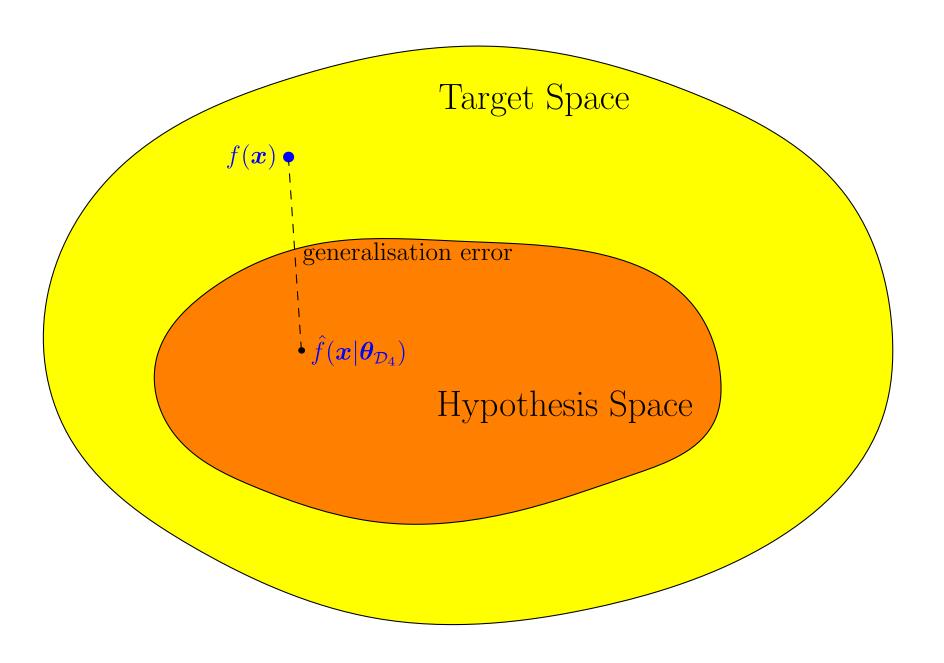


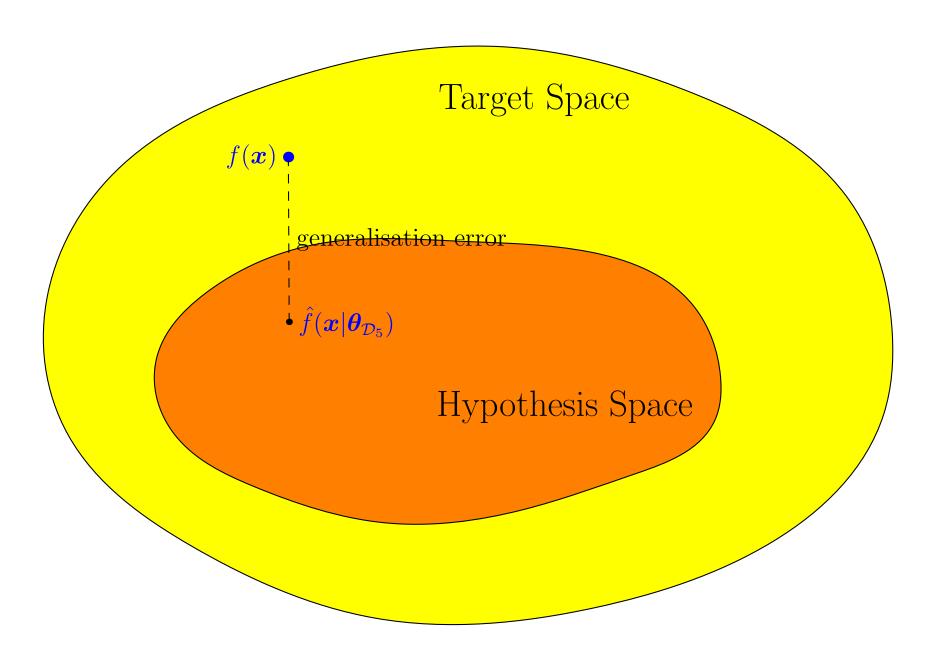


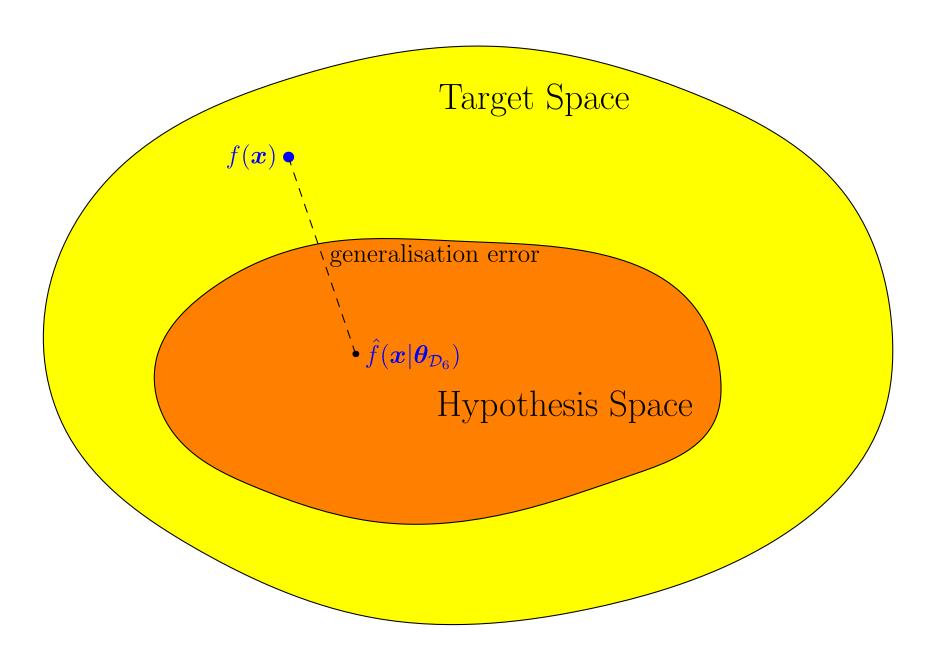


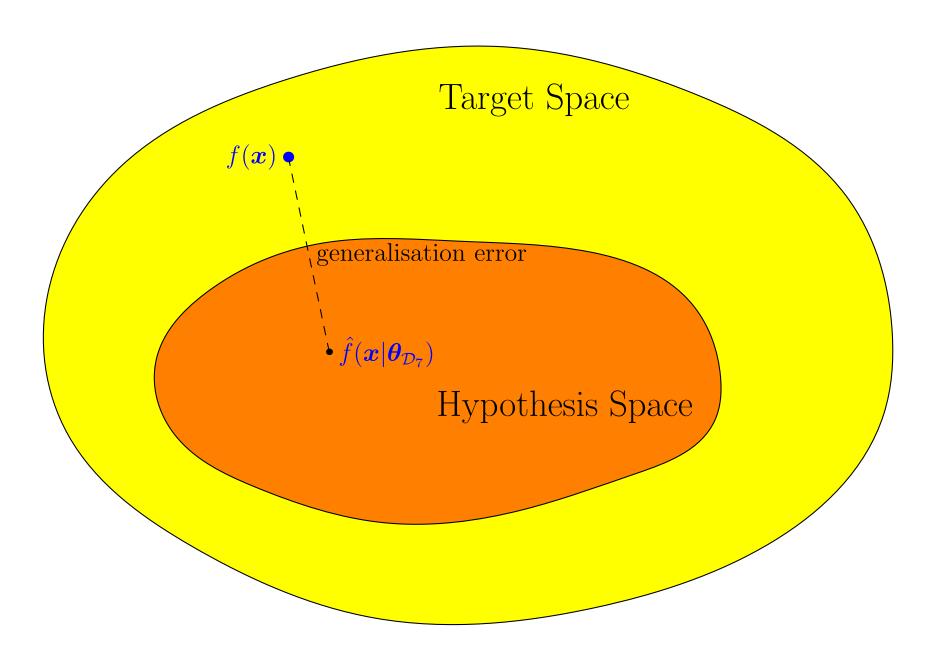


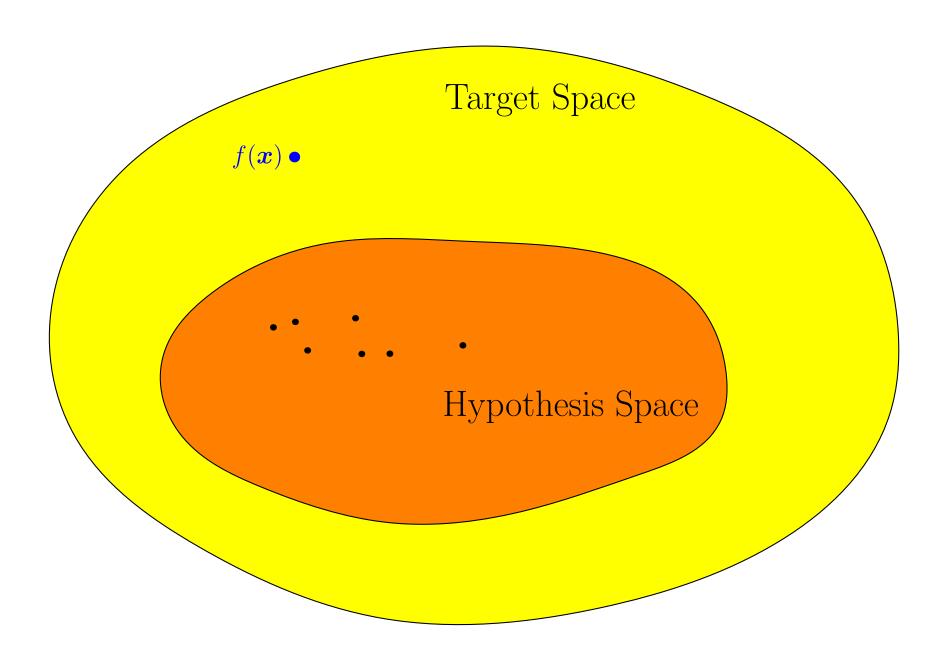


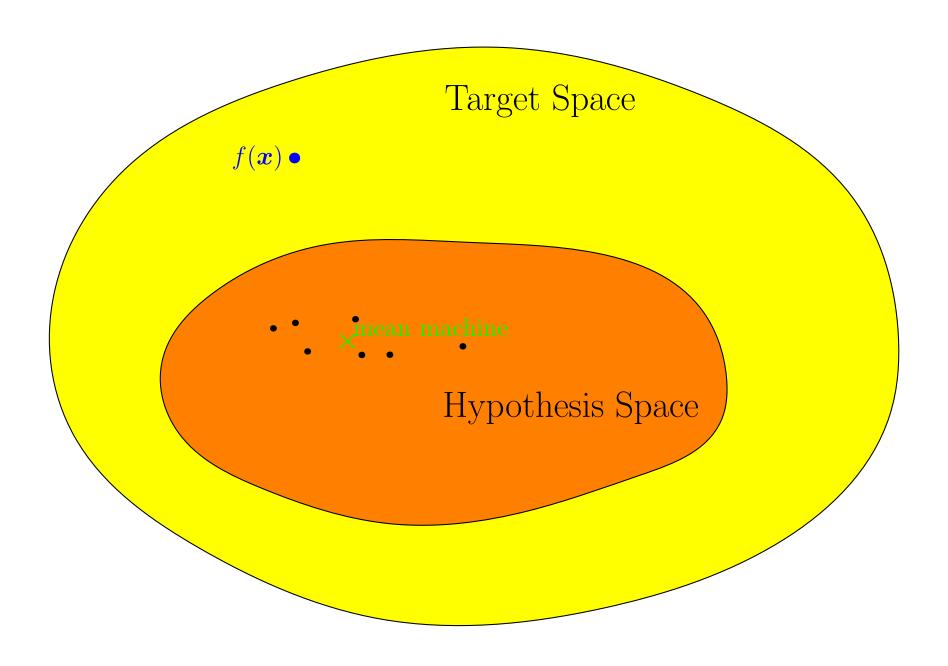


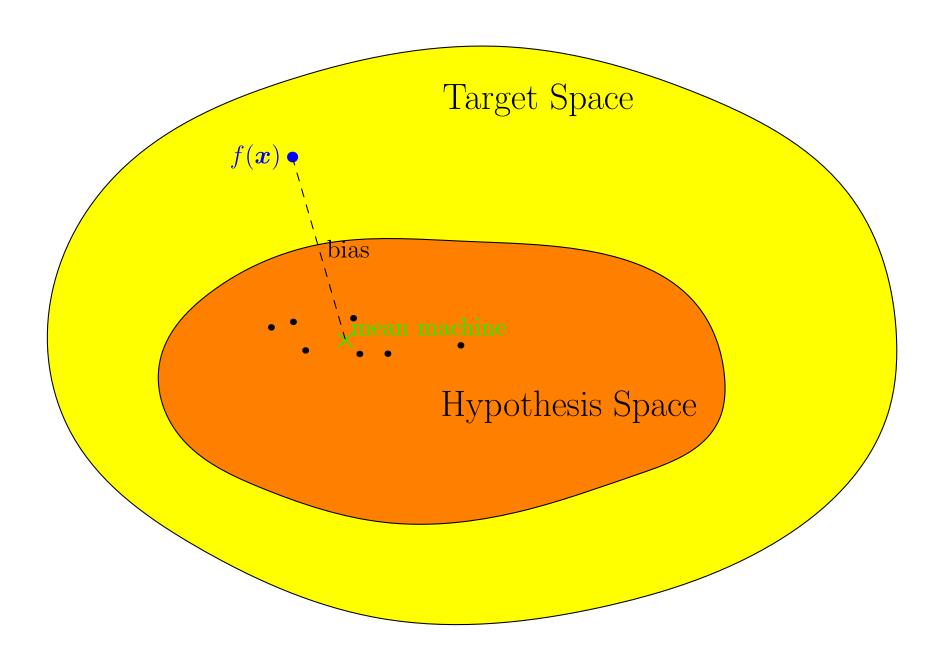


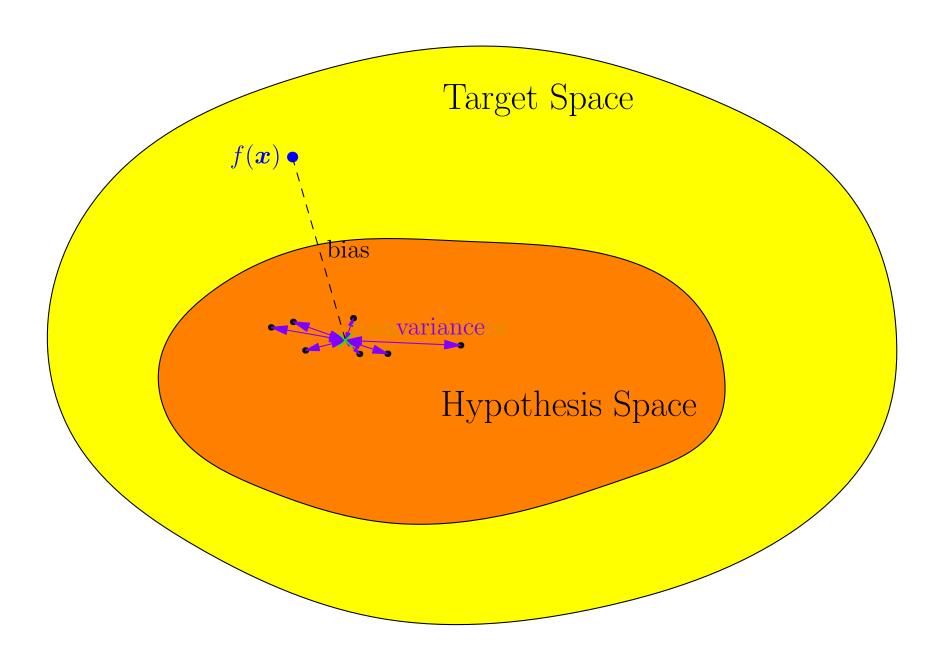












Mean Machine

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$$\hat{f}_m(oldsymbol{x}) = \mathbb{E}_{\mathcal{D}} \Big[\hat{f}(oldsymbol{x} | oldsymbol{ heta}_{\mathcal{D}}) \Big]$$

 We can define the bias to be generalisation performance of the mean machine

$$B = \sum_{\boldsymbol{x} \in \mathcal{X}} \mu(\boldsymbol{x}, y) \left(\hat{f}_m(\boldsymbol{x}) - y \right)^2$$

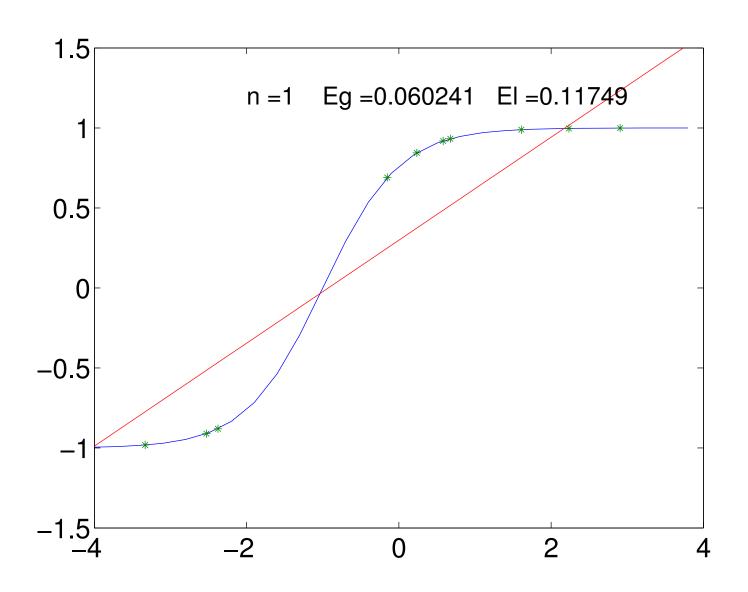
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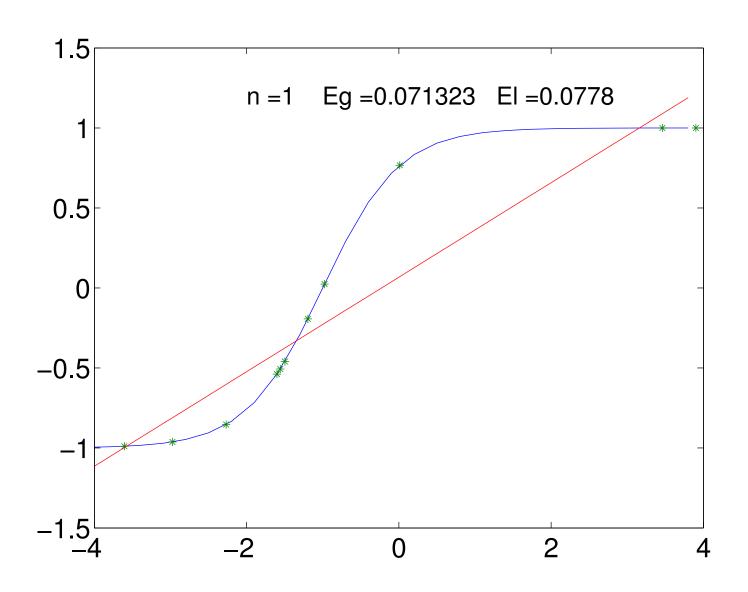
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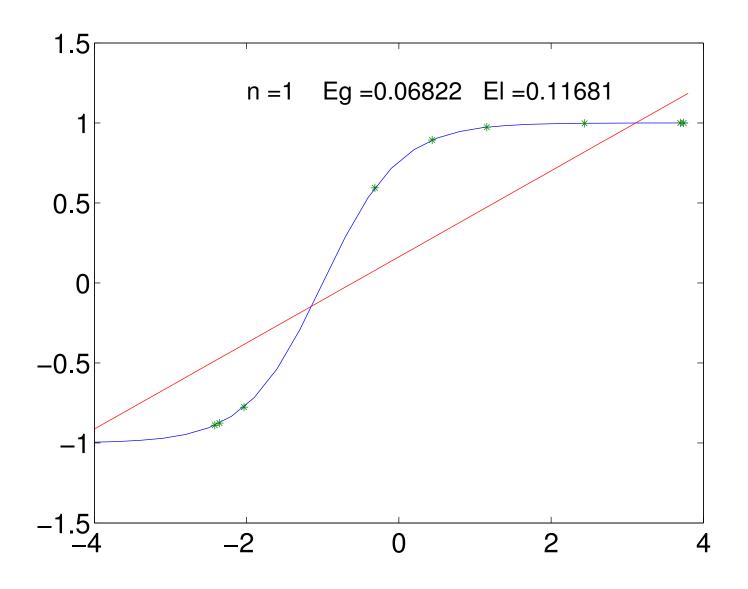
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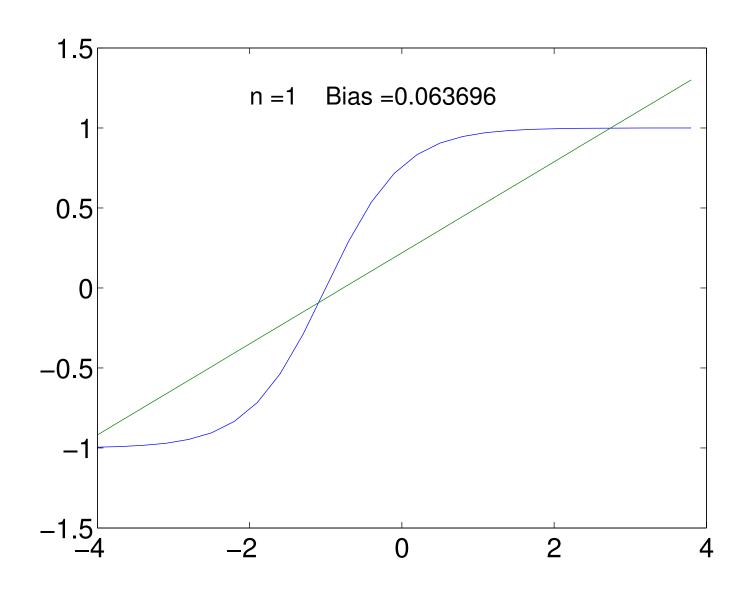
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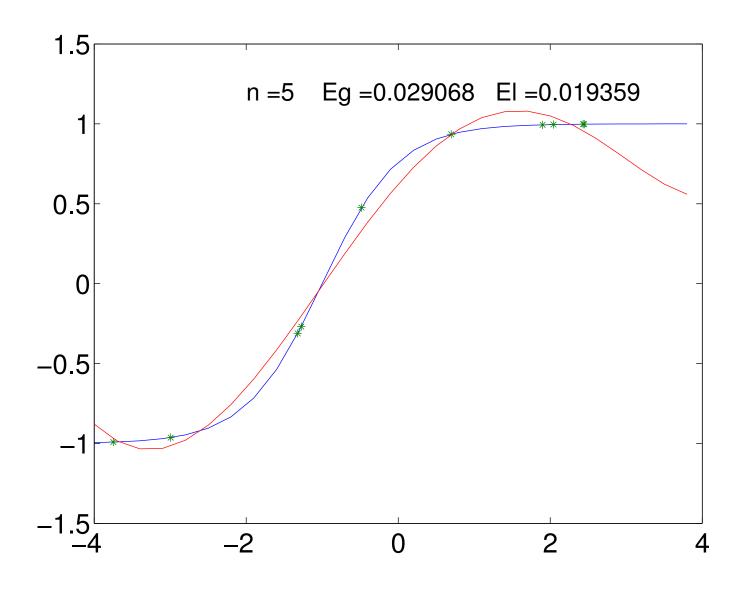
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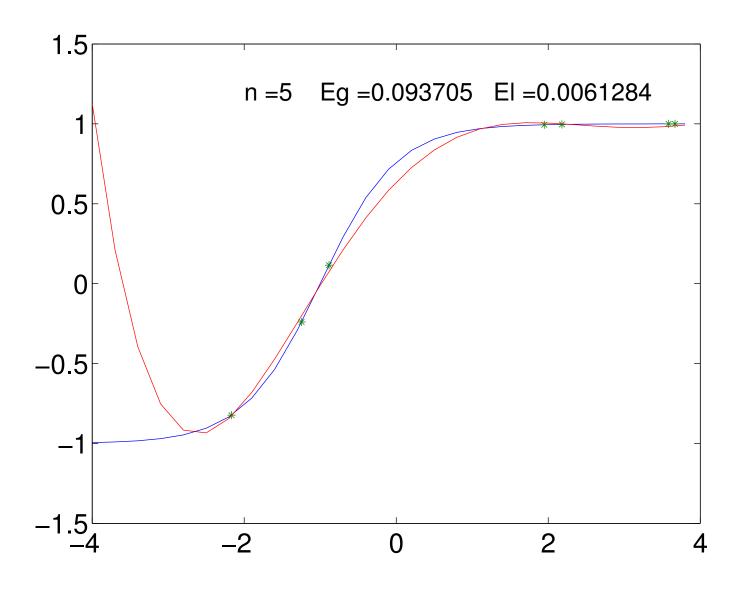


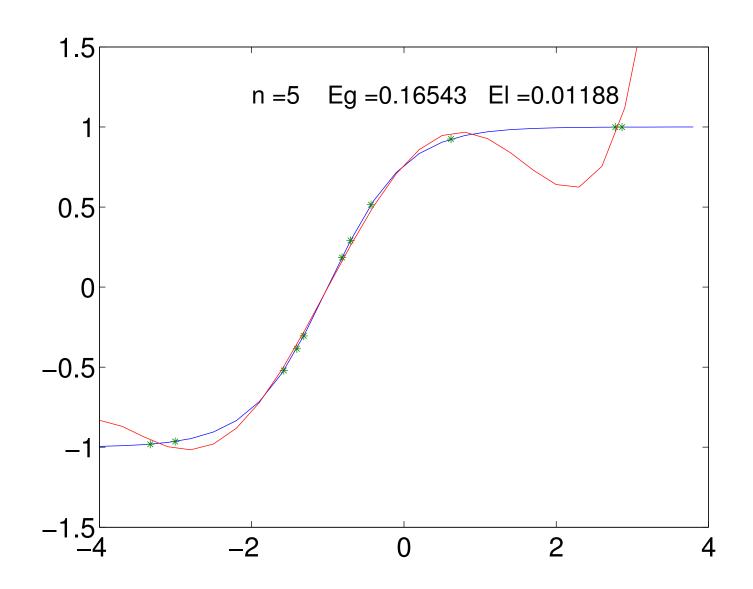


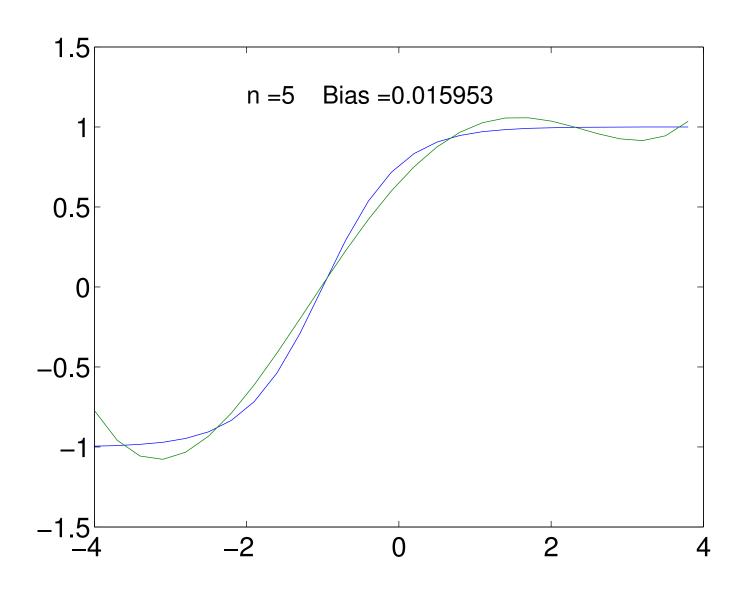












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$$+ 2\mathbb{E}_{\mathcal{D}}\left[\left(\hat{f}(\boldsymbol{x}|\boldsymbol{\theta}_{\mathcal{D}}) - \hat{f}_{m}(\boldsymbol{x})\right)\left(\hat{f}_{m}(\boldsymbol{x}) - y\right)\right]\right)$$

$$C = \mathbb{E}_{\mathcal{D}}\left[\left(\hat{f}(\boldsymbol{x}|\boldsymbol{\theta}_{\mathcal{D}}) - \hat{f}_{m}(\boldsymbol{x})\right)\left(\hat{f}_{m}(\boldsymbol{x}) - y\right)\right]$$

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$$= \Big(\hat{f}_{m}(\boldsymbol{x}) - \hat{f}_{m}(\boldsymbol{x}) \Big) \Big(\hat{f}_{m}(\boldsymbol{x}) - y \Big) = 0$$

Cross Term

The cross term vanishes

$$C = \mathbb{E}_{\mathcal{D}} \left[\left(\hat{f}(\boldsymbol{x}|\boldsymbol{\theta}_{\mathcal{D}}) - \hat{f}_{m}(\boldsymbol{x}) \right) \left(\hat{f}_{m}(\boldsymbol{x}) - y \right) \right]$$

$$= \mathbb{E}_{\mathcal{D}} \left[\left(\hat{f}(\boldsymbol{x}|\boldsymbol{\theta}_{\mathcal{D}}) - \hat{f}_{m}(\boldsymbol{x}) \right) \right] \left(\hat{f}_{m}(\boldsymbol{x}) - y \right)$$

$$= \left(\mathbb{E}_{\mathcal{D}} \left[\hat{f}(\boldsymbol{x}|\boldsymbol{\theta}_{\mathcal{D}}) \right] - \hat{f}_{m}(\boldsymbol{x}) \right) \left(\hat{f}_{m}(\boldsymbol{x}) - y \right)$$

$$= \left(\hat{f}_{m}(\boldsymbol{x}) - \hat{f}_{m}(\boldsymbol{x}) \right) \left(\hat{f}_{m}(\boldsymbol{x}) - y \right) = 0$$

Thus

$$\bar{L}_G = \sum_{\boldsymbol{x} \in \mathcal{X}} \mu(\boldsymbol{x}, y) \mathbb{E}_{\mathcal{D}} \left[\left(\hat{f}(\boldsymbol{x} | \boldsymbol{\theta}_{\mathcal{D}}) - \hat{f}_m(\boldsymbol{x}) \right)^2 + \left(\hat{f}_m(\boldsymbol{x}) - y \right)^2 \right]$$

Bias and Variance

We can write the expected generalisation loss as

$$\mathbb{E}_{\mathcal{D}}[L_G(\mathcal{D})] = \sum_{\boldsymbol{x} \in \mathcal{X}} \mu(\boldsymbol{x}, y) \mathbb{E}_{\mathcal{D}} \left[\left(\hat{f}(\boldsymbol{x} | \boldsymbol{\theta}_{\mathcal{D}}) - \hat{f}_m(\boldsymbol{x}) \right)^2 \right]$$
$$+ \sum_{\boldsymbol{x} \in \mathcal{X}} \mu(\boldsymbol{x}, y) \left(\hat{f}_m(\boldsymbol{x}) - y \right)^2 = V + B$$

ullet Where B is the bias and V is the variance defined by

$$V = \sum_{\boldsymbol{x} \in \mathcal{X}} \mu(\boldsymbol{x}, y) \mathbb{E}_{\mathcal{D}} \left[\left(\hat{f}(\boldsymbol{x} | \boldsymbol{\theta}_{\mathcal{D}}) - \hat{f}_{m}(\boldsymbol{x}) \right)^{2} \right]$$

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- The bias measure the generalisation performance of the mean machine and is large if the machine is too simple to capture the changes in the function we want to learn
- The variance measures the variation in the prediction of the machines as we change the data set we train on

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- Which one to use will depend on the data set
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