

Monte Carlo methods, MCMC, Variational Methods

Bayesian Inference Gets Hard

- We saw that in some cases if we had a simple likelihood (normal, binomial, Poisson, multinomial) you can choose a conjugate prior (gamma-normal/Wishart, beta, gamma, Dirichlet) so that the posterior has the same form as the prior
- Very often we are working with more complex models where no conjugate prior exists
- The posterior is not described by a known distribution
- We have to work a lot harder—particularly with multivariate distributions

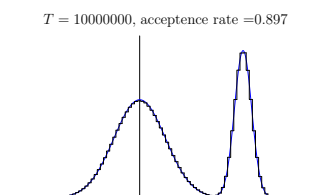
Histograms, Samples and Means

- We could represent our posterior as a histogram, although for multivariate distributions (i.e. when we are modelling more than one variable) a histogram can be unwieldy
- A sample from the posterior distribution is often sufficient e.g. in our topic models (LDA) a typical set of topics is what we are after
- However, when samples vary a lot, often the most useful quantities are expectation, e.g.

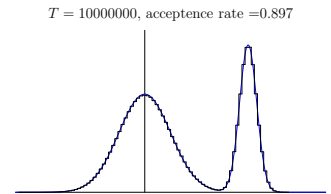
$$\begin{aligned} \mathbb{E}[\Theta] & \quad \mathbb{E}[\Theta_i^2] - \mathbb{E}[\Theta_i]^2 \\ \mathbb{E}[\Theta_i \Theta_j] - \mathbb{E}[\Theta_i] \mathbb{E}[\Theta_j] & \quad \mathbb{E}[\Theta \Theta^T] - \mathbb{E}[\Theta] \mathbb{E}[\Theta]^T \end{aligned}$$

Outline

1. Sampling
2. Random Number Generation
3. MCMC



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Bayesian Inference

- Recall our problem is that we are given some data \mathcal{D}
- Our posterior is given by

$$\mathbb{P}(\theta|\mathcal{D}) = \frac{\mathbb{P}(\mathcal{D}|\theta) \mathbb{P}(\theta)}{\mathbb{P}(\mathcal{D})} \quad \text{or} \quad f(\theta|\mathcal{D}) = \frac{f(\mathcal{D}|\theta) f(\theta)}{f(\mathcal{D})}$$

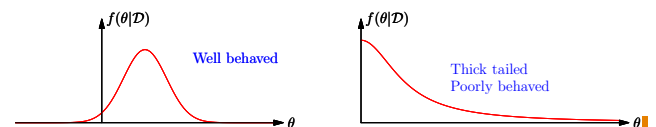
- Where θ are the parameters we are trying to infer
- But our likelihood (and/or prior) might be quite complicated
- Typically we don't have a closed form representation for our posterior distribution

Sample Estimation

- If we can draw independent deviates (aka variates), Θ_i , from our posterior distribution then we can obtain an estimate of our expectation

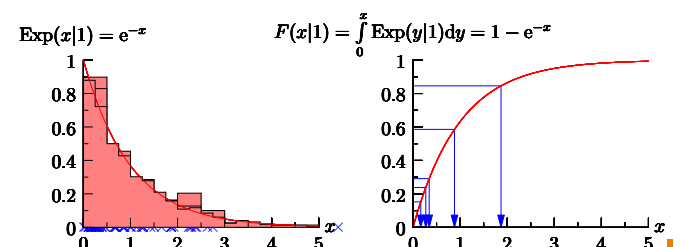
$$\mathbb{E}[g(\Theta)] \approx \frac{1}{n} \sum_{i=1}^n g(\Theta_i)$$

- Provided our posterior distribution is well behaved the relative error in our estimate will drop off as $1/\sqrt{n}$



Drawing Random Samples

- Drawing (pseudo) random variables from a distribution is known as Monte Carlo
- For some very simple distributions we can use the transformation methods to transform a uniform distribution



- The transformation method only works when we can easily compute the inverse *cumulative distribution function* (CDF)
- A more general technique is the **rejection method** where we generate deviates from $g_Y(y)$ such that $c g_Y(x) \geq f_X(x)$
- To draw deviates from $f_X(x)$ we draw a deviate $Y \sim g_Y$ and then accept the deviate with probability $f_X(Y)/(c g_Y(Y))$
- The expected rejection rate is $c - 1$
- Need to choose a good distribution $g_Y(y)$

Problems with Rejection

- The rejection method is very general and often the method of choice (although for normal deviates there is a clever transformation method which is faster)
- However, for complicated probability distributions it can be difficult to find a good proposal distribution $g_Y(y)$
- This is particular true for multivariate distributions
- If the proposal distribution is poor c might be very high and the number of rejections is stupidly high

Detailed Balance

- Suppose we have a set of states \mathcal{S} and want to draw sample from a probability distribution $\pi = (\pi_i | i \in \mathcal{S})$
- We invent a dynamical system with a transition probability M_{ij} from state j to state i such that

$$M_{ij}\pi_j = M_{ji}\pi_i$$

- This is known as **detailed balance**
- Summing both sides over j

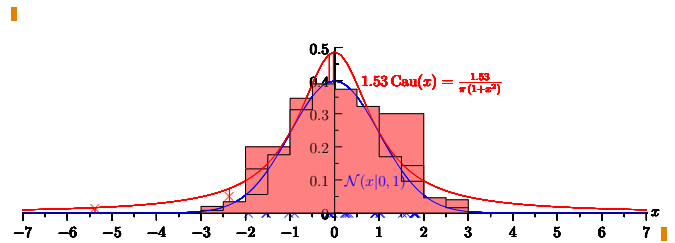
$$\sum_j M_{ij}\pi_j = \sum_j M_{ji}\pi_i = \pi_i \quad \mathbf{M}\pi = \pi$$

Metropolis Algorithm

- A very easy way to achieve detailed balance is starting from state j choose a “neighbouring” state, i with equal probability
- We accept the move if either
 - $\pi_i > \pi_j$ or
 - we make the move with a probability π_i/π_j
- If $\pi_i > \pi_j$ then $M_{ij} = 1$ and $M_{ji} = \pi_j/\pi_i$. Thus

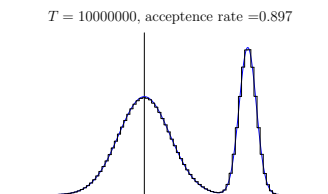
$$M_{ij}\pi_j = \pi_j \quad M_{ji}\pi_i = \frac{\pi_j}{\pi_i}\pi_i = \pi_j$$

- Note that we require the state i to have the same number of neighbours as state j so that detailed balance is satisfied



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Convergence of MCMC

- Suppose we start from a state $x(0) = \sum_i c_i v^{(i)}$ where the $v^{(i)}$'s are an eigenvectors of the transition matrix \mathbf{M} with eigenvalues λ_i
- If I apply \mathbf{M} many times then

$$x(t) = \mathbf{M}^t x(0) = \mathbf{M}^t \sum_i c_i v^{(i)} = \sum_i \lambda_i^t c_i v^{(i)}$$

- And $\lim_{t \rightarrow \infty} x(t) = v^*$ where v^* is the eigenvector with the maximum eigenvalue
- Now $\|\mathbf{M}v\|_1 \leq \|\mathbf{M}\|_1 \|v\|_1 = \|v\|_1$ so the maximum eigenvalue is 1 with eigenvector π (\mathbf{M} is known as a **stochastic matrix**)

Continuous Variables

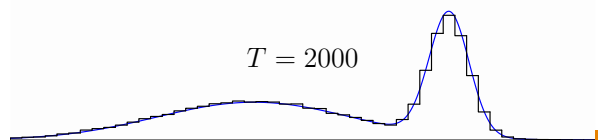
- If we are working with continuous variables θ then the equation for detailed balance for the transition probability $W(\theta \rightarrow \theta')$ is

$$W(\theta \rightarrow \theta')\pi(\theta) = W(\theta' \rightarrow \theta)\pi(\theta')$$

- where $\pi(\theta)$ is the probability distribution we wish to sample from
- The update rule is to choose a nearby value θ' , compute $r = \pi(\theta')/\pi(\theta)$ and accept the update with probability $\min(1, r)$
- We require that the probability of choosing θ from θ' is the same as the reverse

- Because we are free to choose where we move (and choose close by neighbours) $\pi(\theta') \approx \pi(\theta)$ so that moves are not too infrequent
- Also very importantly the updates depend only on the ratio $\pi(\theta')/\pi(\theta)$
- We only need to know our probabilities up to a multiplicative scaling factor
- For sampling from the posterior we only need to know the likelihood and prior $\mathbb{P}(\mathcal{D}|\theta)\mathbb{P}(\theta)$ (or $f(\mathcal{D}|\theta)f(\theta)$)
- We don't need to know $\mathbb{P}(\mathcal{D})$ which we generally don't know

Burn-In



Traffic Rate

- Consider monitoring the flow of traffic where we have data

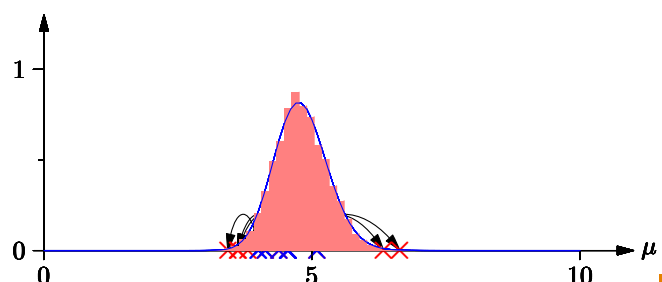
$$\mathcal{D} = (N_1, N_2, \dots, N_n)$$

where N_i is the number of car that past on day i

- We assume $N_i \sim \text{Poi}(\mu)$ and want to infer μ
- The Poisson distribution has a beta conjugate prior
- We don't have any prior knowledge on μ so we use a non-informative prior $\text{Gam}(\mu|0,0) = 1/\mu$
- Note that we can solve this problem exactly—however, lets compare with MCMC

MCMC in Practice

$$\mathcal{D} = \{4, 4, 6, 4, 2, 2, 5, 9, 5, 4, 3, 2, 5, 4, 4, 11, 6, 2, 3, 11\}$$



- It can take a long time until our states occur with the probability π (i.e. we have forgotten our initial state)
- We don't even know how long we have to wait
- Even when we have reached this *equilibration time* each sample is correlated with the previous sample
- To get a good approximation to the posterior expectation requires running for many times the equilibration time
- Note, if we are just finding sample averages then we can use all samples after equilibrating even if they are not independent

Proposals and Metropolis-Hastings

- We have some freedom in choosing a new proposal θ' from our current position θ —a good choice can increase the acceptance rate making the MCMC more efficient
- We define the proposal distribution $p(\theta'|\theta)$
- For the standard Metropolis algorithm to work we require $p(\theta'|\theta) = p(\theta|\theta')$
- In some cases (e.g when $\theta_i \geq 0$) this can be hard to achieve
- We can modify our update rule to accept a move with probability

$$\min\left(1, \frac{p(\theta|\theta')f(\mathcal{D}|\theta')f(\theta')}{p(\theta'\theta)f(\mathcal{D}|\theta)f(\theta)}\right)$$

Proposal Distribution

- If we can choose our proposal distribution $p(\mu'|\mu)$ to be close to the posterior distribution then our acceptance rate would be close to 1
- We choose $p(\mu'|\mu) = \text{Gam}(\mu'|\mu, \mu^2)$ which has $\mathbb{E}[\mu'] = \mu$ and variance 1
- We update with probability $\min(1, r)$ where

$$r = \frac{\text{Gam}(\mu|\mu'^2, \mu') \frac{1}{\mu'} \prod_{i=1}^n \text{Poi}(N_i|\mu')}{\text{Gam}(\mu'|\mu^2, \mu) \frac{1}{\mu} \prod_{i=1}^n \text{Poi}(N_i|\mu)}$$

$$= \frac{\mu \text{Gam}(\mu|\mu'^2, \mu')}{\mu' \text{Gam}(\mu'|\mu^2, \mu)} e^{-n(\mu' - \mu) + \sum_{i=1}^n N_i \log\left(\frac{\mu'}{\mu}\right)}$$

MCMC Details

- To compute correct histograms you need to count samples where no move is made multiple times
- On modern computers its quite quick to compute millions of samples
- The code is not very difficult to write (although care is need to get everything correct)
- This can be used on complicated problems such as topic models (LDA) with thousands of parameters
- The accuracy of MCMC is slow if it takes a long time to sample the posterior distribution

- MCMC provides a means to accurately sample from very complex models
- There have been many advanced techniques developed to improve MCMC performance
- E.g. hybrid MCMC simulates a dynamics to find good proposals with similar probability far from the starting point
- Often it seems that MCMC is complicated because there are so many optimisations, but often simple implementations are sufficient

- As soon as we use complex models we are no longer able to compute the posterior in closed form
- Monte Carlo techniques and particularly MCMC are a very general method for computing samples from the posterior
- These techniques have been highly developed, but very frequently even simple implementations are sufficient to do good inference
- Variational methods provide an approximate closed form solution to problems with complex likelihoods
- Variational methods are mathematically challenging, but are potentially far faster to compute than MCMC