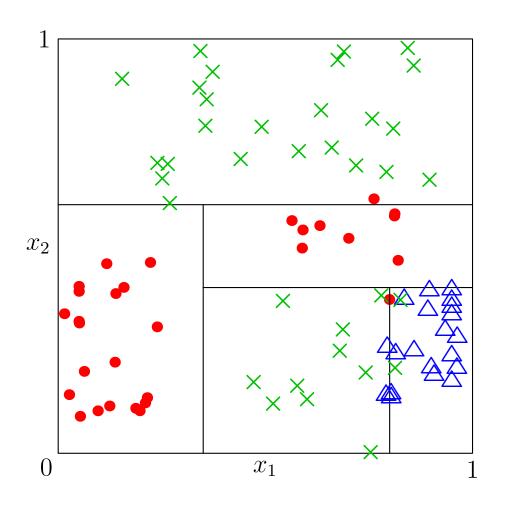
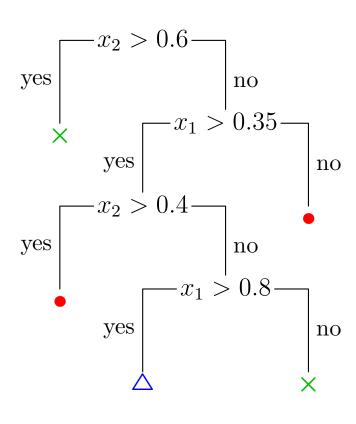
Advanced Machine Learning

Ensemble Methods



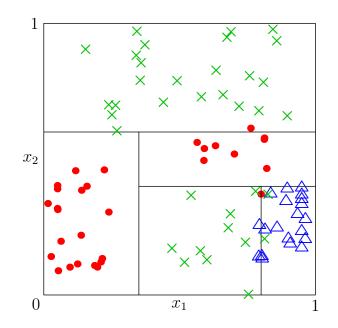


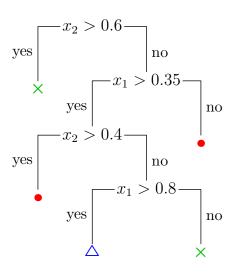
Decision Trees, Averaging, Bagging

Outline

1. Decision Trees

2. Bagging





- We can reduce the variance and hence improve our generalisation error by averaging over different learning machines
- There are a number of different techniques for doing this that go by the name of ensemble methods or ensemble learning
- This trick can be used with many different learning machines, but is clearly most practical for machine that can be trained quickly

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- This trick can be used with many different learning machines, but is clearly most practical for machine that can be trained quickly
- (nevertheless, even for deep learning taking the average response of many machines is usually done to win competitions)

- One set of algorithms where ensembling are common place are decision trees
- These are particularly good for handling messy data
 - ★ categorical data
 - ★ mixture of data types
 - ★ missing data
 - ★ large data sets
 - multiclass
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- A decision trees builds a binary tree to partition the data, $\mathcal{D} = \{(\boldsymbol{x}_i, y_i) | i = 1, ..., m\}$, into the leaves of the tree
- Each decision rule depends on a single feature
- ullet At each step the rule is chosen that maximise the "purity" of the leaf nodes
- Decisions can be made on numerical values or categories

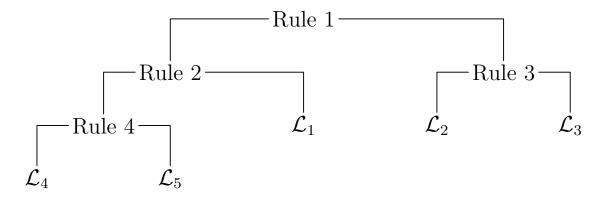
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- The data is partitioned by the tree into leaves



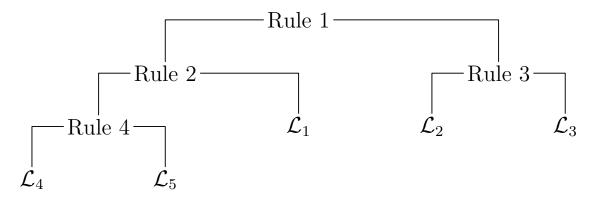
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$$p_c(\mathcal{L}) = \frac{1}{|\mathcal{L}|} \sum_{(\boldsymbol{x}, y) \in \mathcal{L}} [y = c]$$

where $[\![y=c]\!]=1$ if y=c and 0 otherwise

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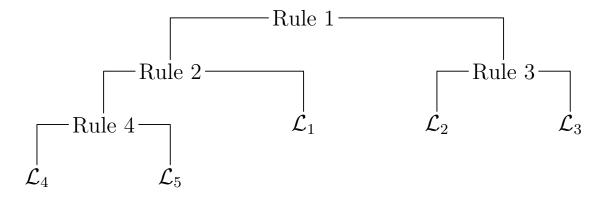
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Leaf Purity

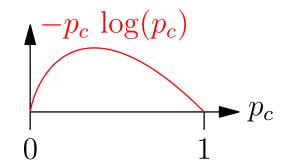
- Two different purity measures, $Q_m(\mathcal{L})$, for a leaf node \mathcal{L} are commonly used
 - ★ Gini index

$$Q_m^g(\mathcal{L}) = \sum_{c \in \mathcal{C}} p_c(\mathcal{L}) (1 - p_c(\mathcal{L}))$$

 $\begin{array}{c|c}
 & p_c (1 - p_c) \\
\hline
 & p_c \\
\hline
 & 1
\end{array}$

Cross-entropy

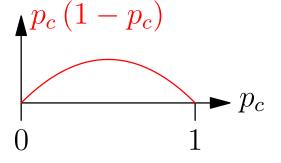
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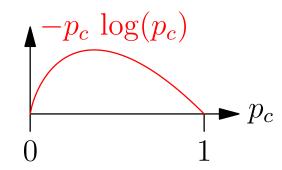
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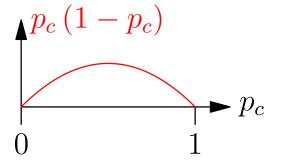
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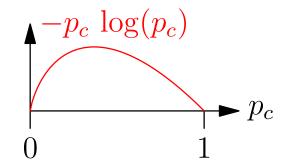
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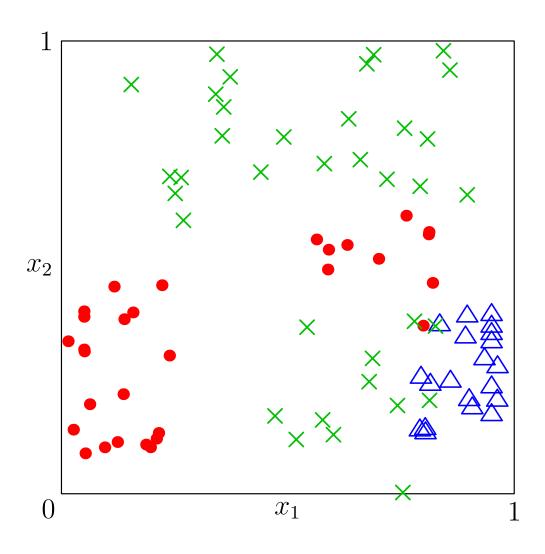
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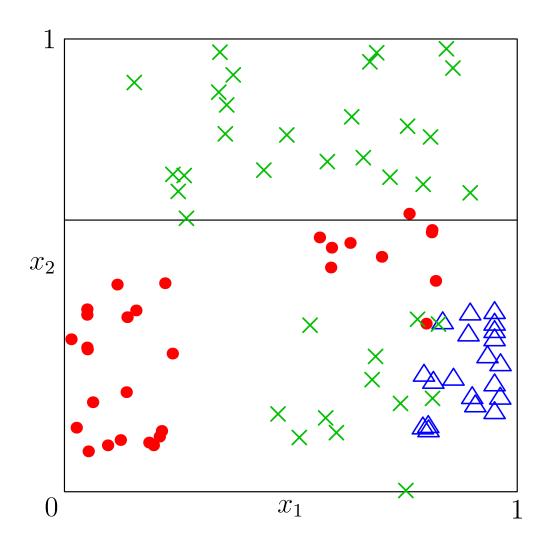


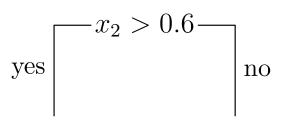
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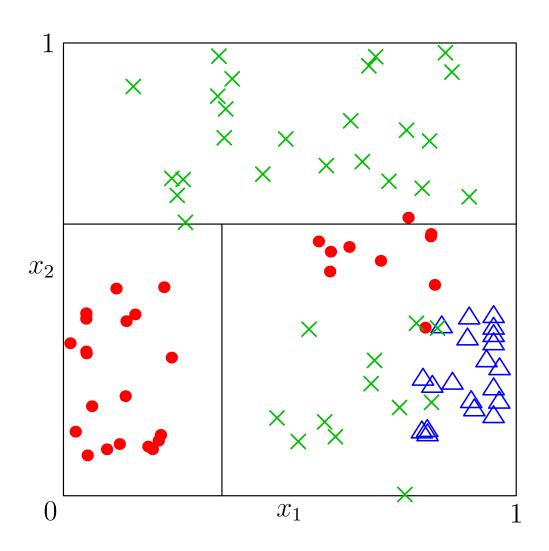
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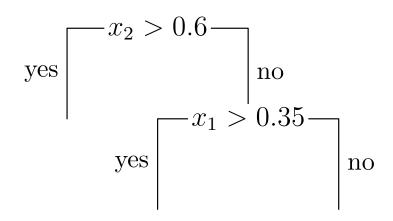


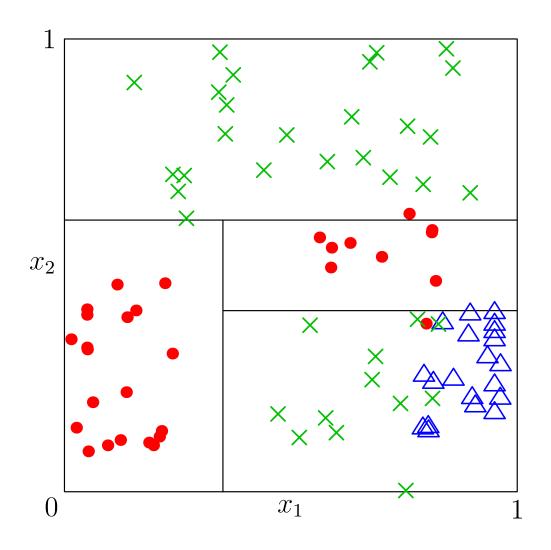


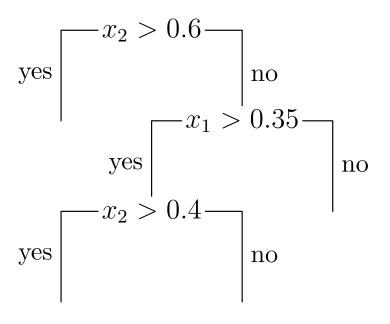


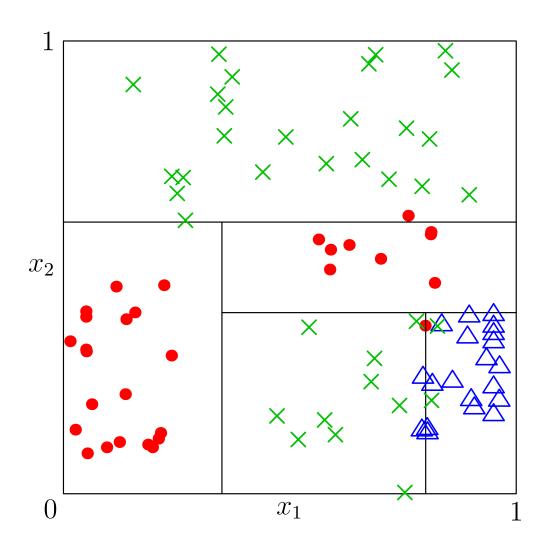


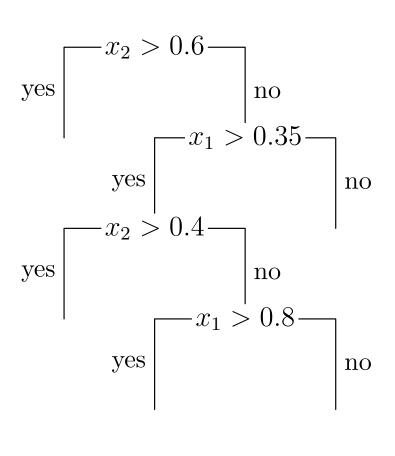


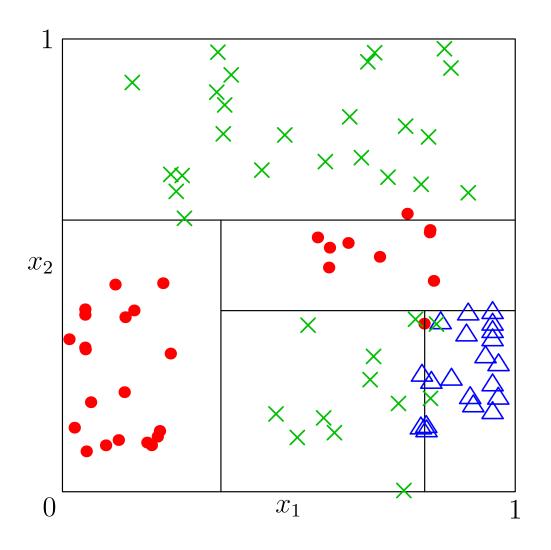


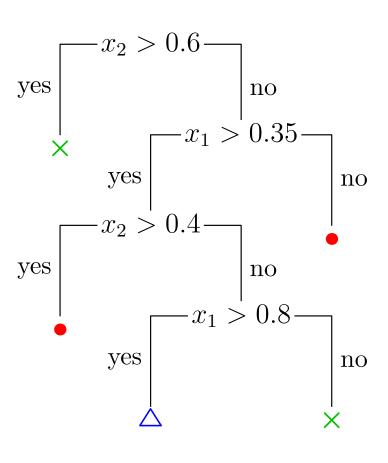












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- Decision trees can also be used for regression problems
 - * Approximate function by a series of rules
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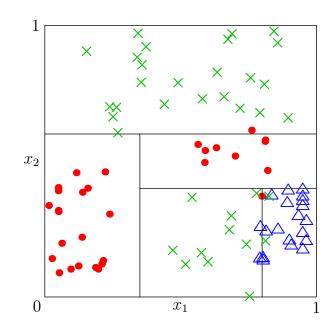
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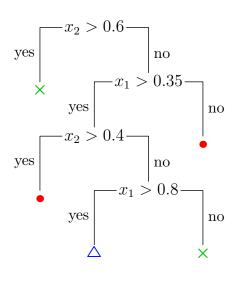
Observations

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 - * Approximate function by a series of rules
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- CART is a classic implementation that builds Classification And Regression Trees
- Decision trees depend strongly on the early decisions and so vary a lot for slightly different data sets—high variance

Outline

- 1. Decision Trees
- 2. Bagging

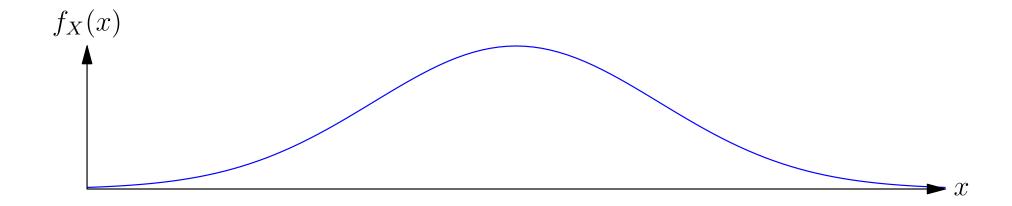




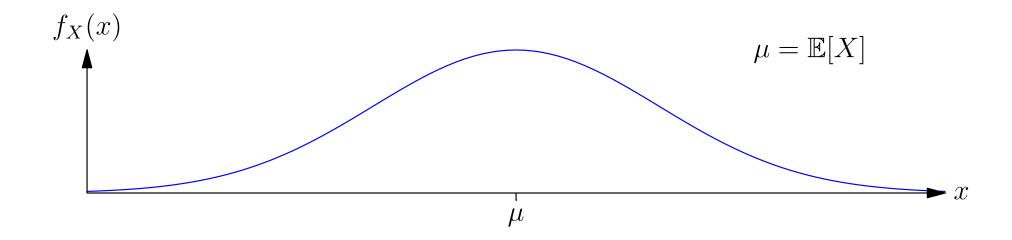
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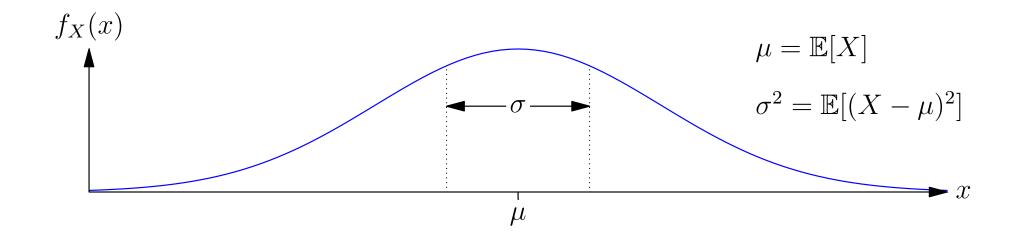
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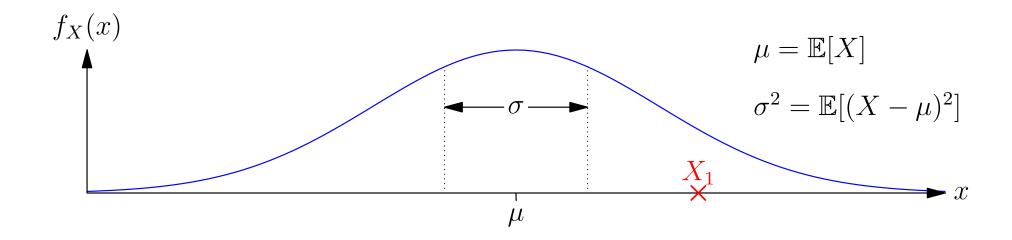
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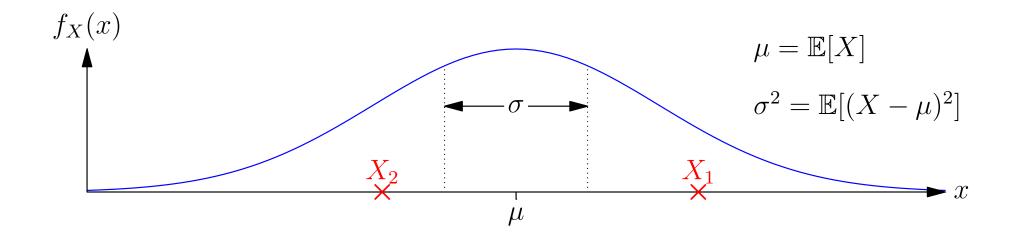
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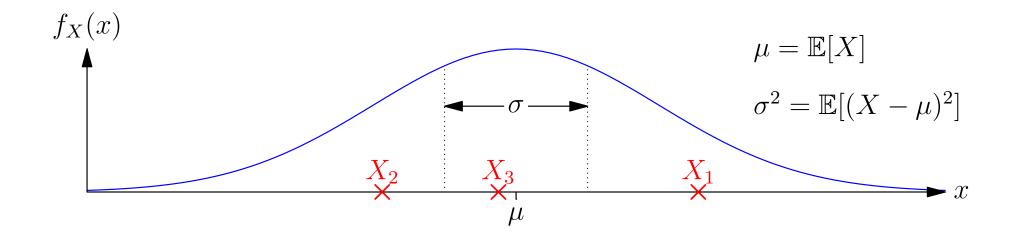
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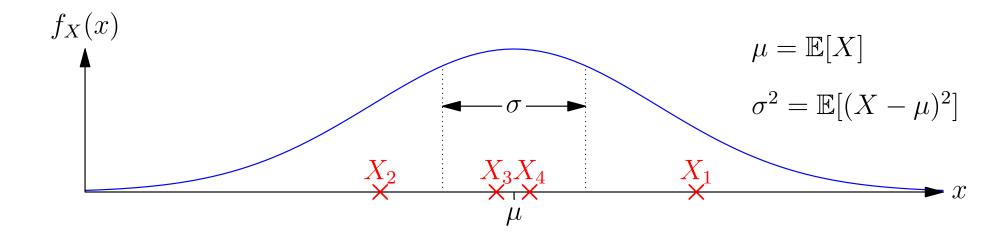
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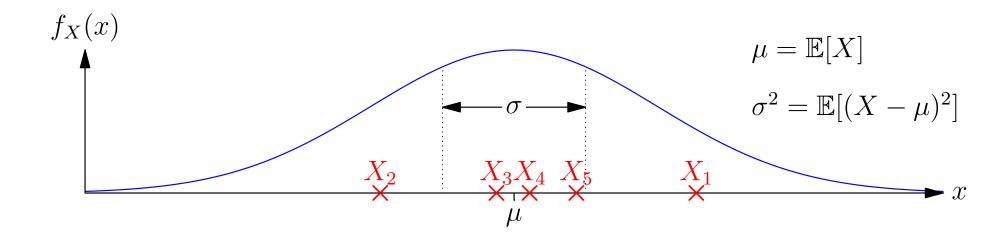
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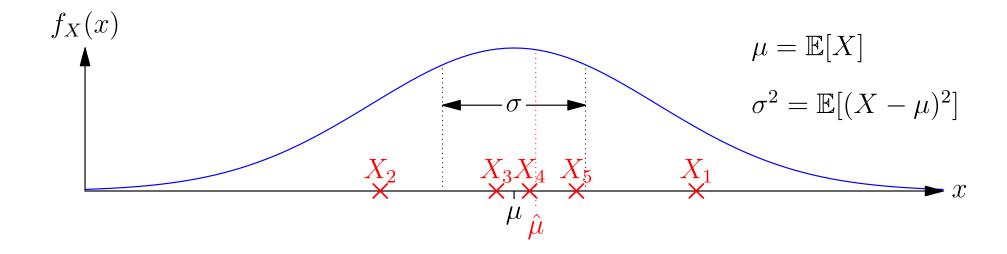
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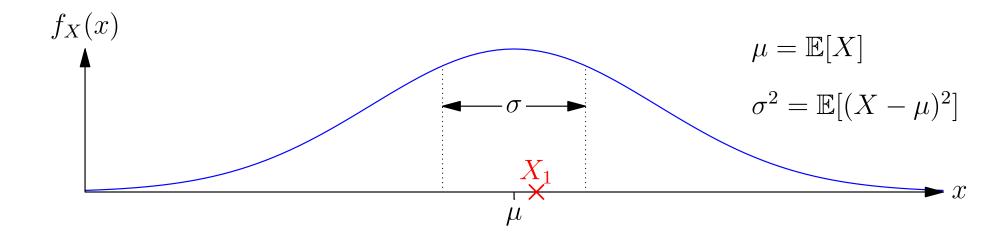
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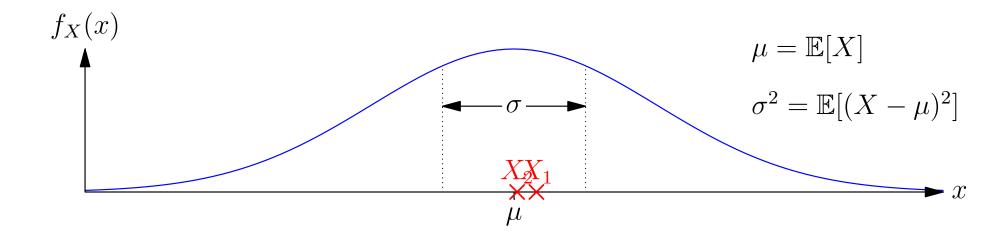
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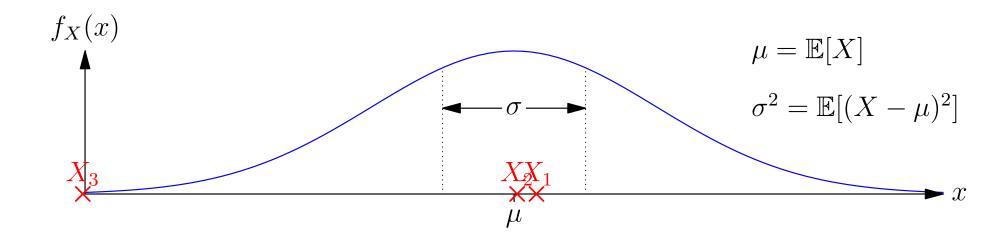
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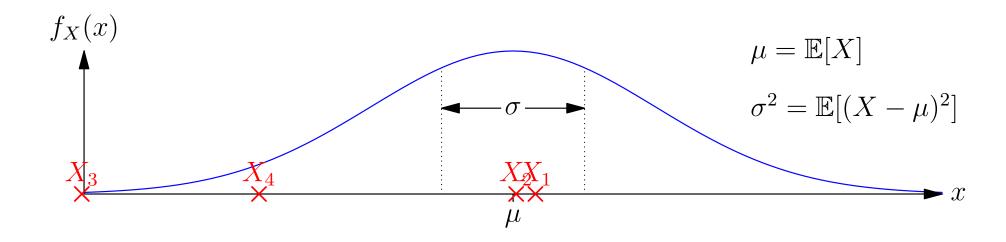
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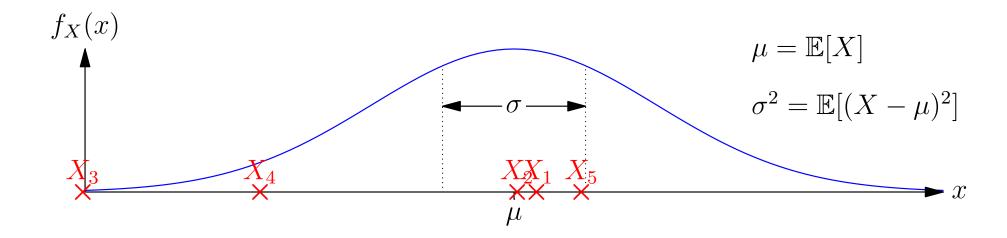
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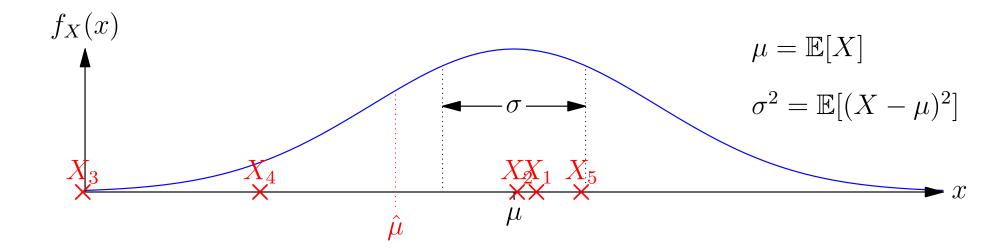
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- For regression we can average the prediction of different machines
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- However, we can usually do better using Boosting
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Variance of Positive Correlated Variables

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$$\frac{1}{n^2} \mathbb{E}\left[\left(\sum_{i=1}^n X_i - \mu\right)^2\right] = \rho \sigma^2 + \frac{1-\rho}{n} \sigma^2$$

$$(\rho = \mathbb{E}[(X_i - \mu)(X_j - \mu)]/\sigma^2)$$

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- To do this for each tree we choose a subset of $p' \ll p$ of the features on which to split the tree
- Typically p' can range from 1 to \sqrt{p}
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