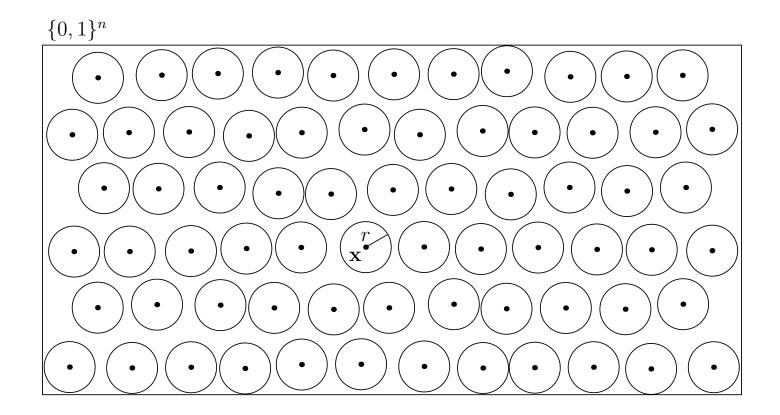
Advanced Machine Learning

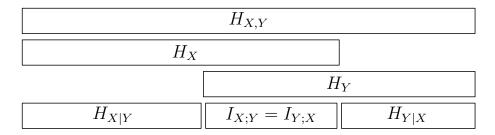
Information Theory



Information, KL-divergence, Minimum Description Length

Outline

- 1. Information Theory
- 2. KL-Divergence
- 3. Minimum Description Length
- 4. Variational Auto-Encoders



Communicating Via a Noisy Channel

Information theory considers communicating down a (noisy) channel

$$X \sim \mathbb{P}(X) \xrightarrow{\text{noisy channel}} Y \sim \mathbb{P}(Y \mid X)$$

- We send a message X (with probability $\mathbb{P}(X)$) and receive a message Y with probability $\mathbb{P}(Y\mid X)$
- ullet The uncertainty of the message sent, given we received a message y is

$$H_{X|Y=y} = -\sum_{x \in \mathcal{X}} \mathbb{P}(X = x \mid Y = y) \log(\mathbb{P}(X = x \mid Y = y))$$

• The expected uncertainty in the message sent is

$$H_{X|Y} = \sum_{y \in \mathcal{Y}} \mathbb{P}(Y = y) H_{X|Y=y} = -\sum_{x,y} \mathbb{P}(X = x, Y = y) \log(\mathbb{P}(X = x \mid Y = y))$$

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We can define the joint entropy

$$H_{X,Y} = -\sum_{x,y} P_{X,Y}(x,y) \log(P_{X,Y}(x,y))$$

- If the message we receive is independent of the message that is sent then $H_{X,Y}=H_X+H_Y$ (we saw this in the last lecture)
- This is different when X and Y are correlated
- Since $\mathbb{P}(X,Y) = \mathbb{P}(Y|X)\mathbb{P}(X) = \mathbb{P}(X|Y)\mathbb{P}(Y)$ if follows

$$H_{X,Y} = H_X + H_{Y|X} = H_Y + H_{X|Y}$$

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Mutual Information

- The amount of uncertainty about the message being sent, X, before receiving the message is $H_X = -\mathbb{E}_X[\log \mathbb{P}(X)]$
- Shannon define the $mutual\ information$ to be the expected loss in uncertainty when we receive a message

$$I_{X;Y} = H_X - H_{X|Y}$$

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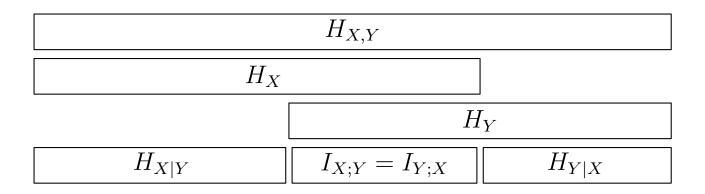
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Channel Capacity

We can summarise these relationships diagrammatically



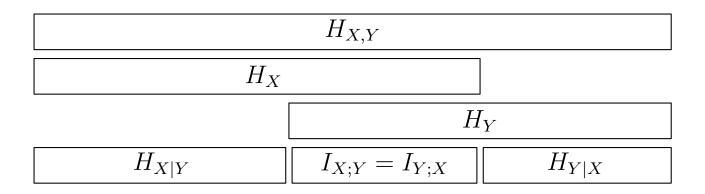
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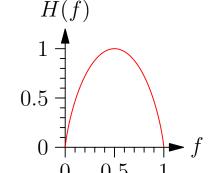
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Independent Noise

ullet The simplest model of a noisy channel is a binary channel where each symbol is corrupted independently with a probability f

$$\mathbb{P}(X = 1 | Y = 0) = \mathbb{P}(X = 0 | Y = 1) = f$$



An elementary calculations shows that

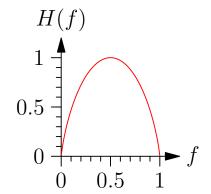
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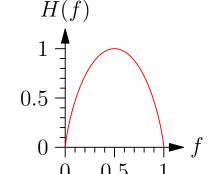
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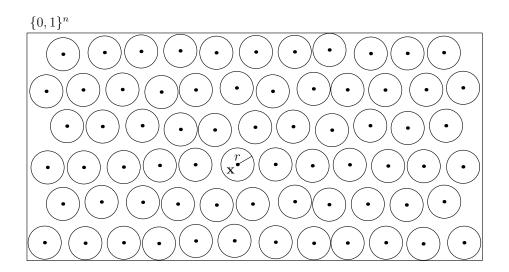
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Error Correcting Codes

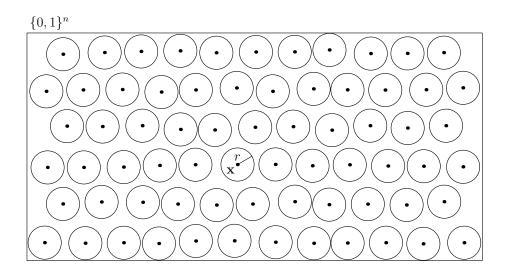
- To reduce the chance of misinterpreting a message we need to build an error correcting code
- We can do this dividing the space of binary messages into a set of Hamming balls



• A Hamming ball B(x,r) is the set of strings that differ from n-dimensional binary string, x, by at most r digits

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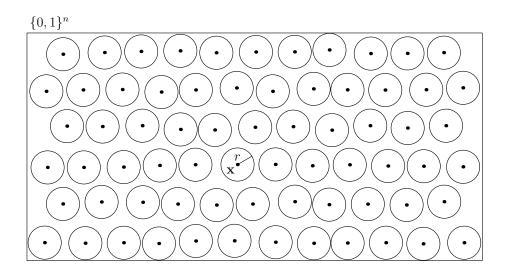
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- ullet The expected number of errors in a string of length n given an error rate of f is nf
- For sufficiently large n we would expect all errors are smaller that $(f+\epsilon)n$ (for $\epsilon>0$)
- If we make the radius of the Hamming ball $r = (f + \epsilon)n$ ($\epsilon > 0$) then we would expect no error for sufficiently large n
- ullet An upper bound on the number of code words we can send in a string of length n is

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- If f=0.1 then $C=I_{X;Y}=0.469 {
 m bits}$ so we need codes of just over twice as long to communicate accurately over a noisy channel with a 10% corruption rate
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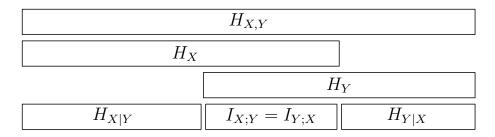
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- 2. KL-Divergence
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KL-Divergence

We have met the Kullback-Leiblier divergence

$$KL(p||q) = \mathbb{E}_{X \sim p(X)} \left[\log \left(\frac{p(X)}{q(X)} \right) \right]$$
$$= -\mathbb{E}_{X \sim p(X)} [\log(q(X))] - H_X$$

- Recall $-\log(q(X=x))$ is the length of code need to send a message x with a probability q(X=x)
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- Often we have a parameterised distribution $q(X|\theta)$ and we have some complex distribution p(X)
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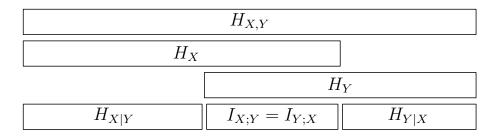
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- Alice wants to communicate y_i to Bob as efficiently as possible
- We suppose Alice & Bob have available a model $y = \hat{f}(\boldsymbol{x}|\boldsymbol{\theta})$
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Description Length

• The **description length** for $\{y_i \mid i=1,2,...,m\}$ is then the cost of transmitting θ plus the cost of transmitting the errors

$$L = \sum_{k=1}^{n} \ell(\theta_k) - \sum_{i=1}^{m} \log \left(p_{\delta} \left(y_i - \hat{f}(\boldsymbol{x}_i | \boldsymbol{\theta}) \right) \right) - \log(\Delta)$$

where $\ell(\theta_i)$ is the number of bits need to communicate θ_k (we get to choose the accuracy if is worth encoding the parameters)

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- Often it is the only principled method available
- It allows you to trade model accuracy against model complexity
- It can be fiddly as we need to determine the accuracy to which we should store the parameters of our model
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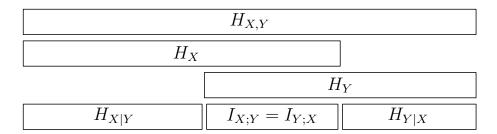
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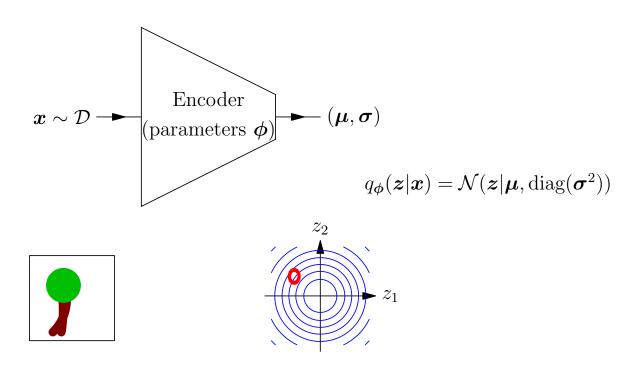
Outline

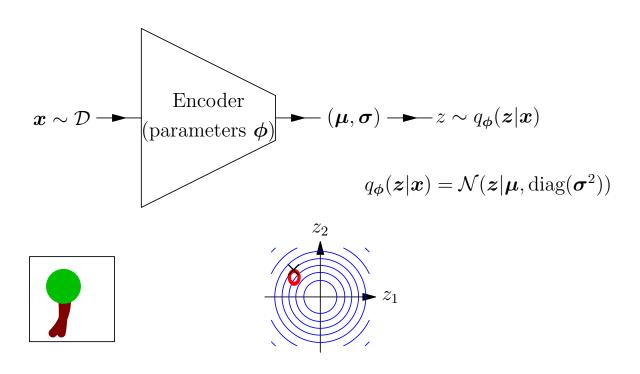
- 1. Information Theory
- 2. KL-Divergence
- 3. Minimum Description Length
- 4. Variational Auto-Encoders

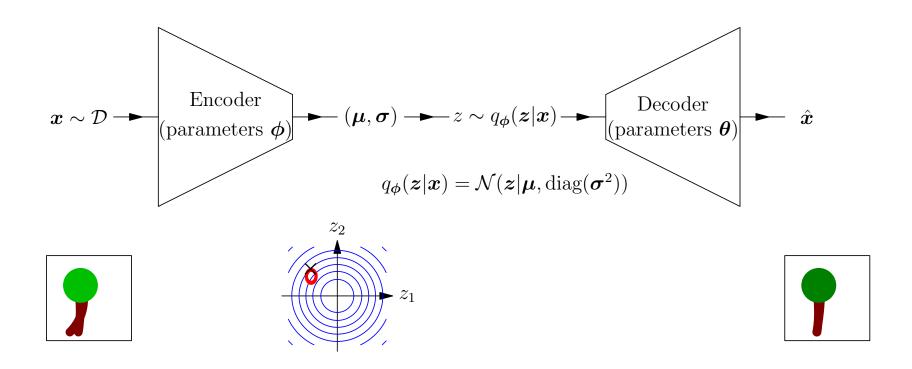


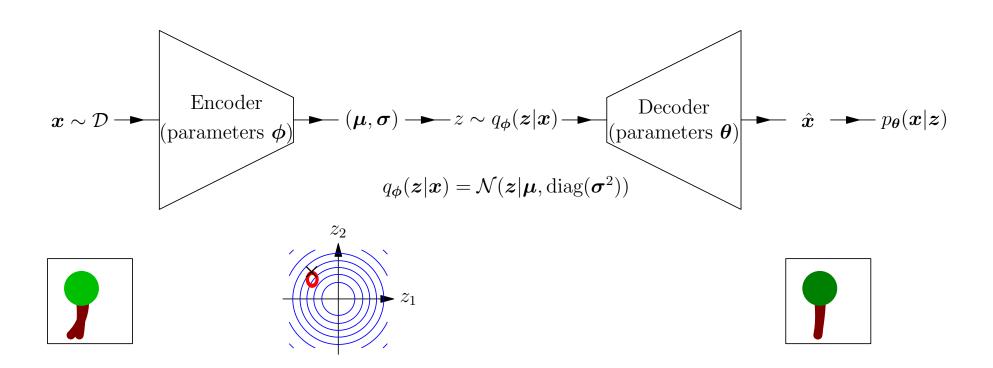
 $oldsymbol{x} \sim \mathcal{D}$

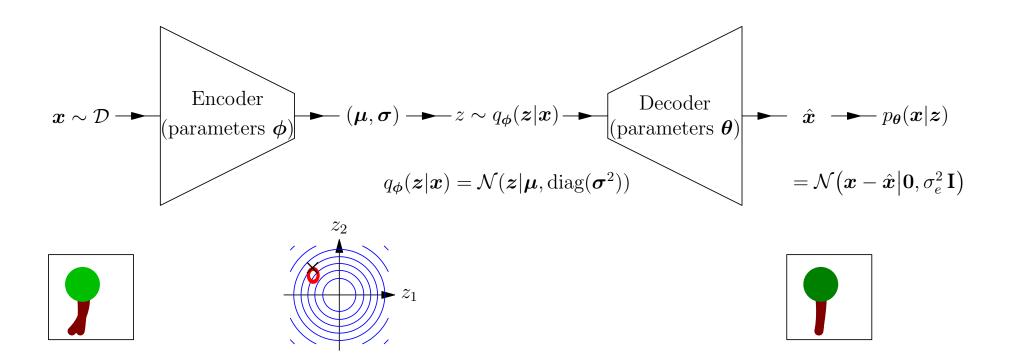


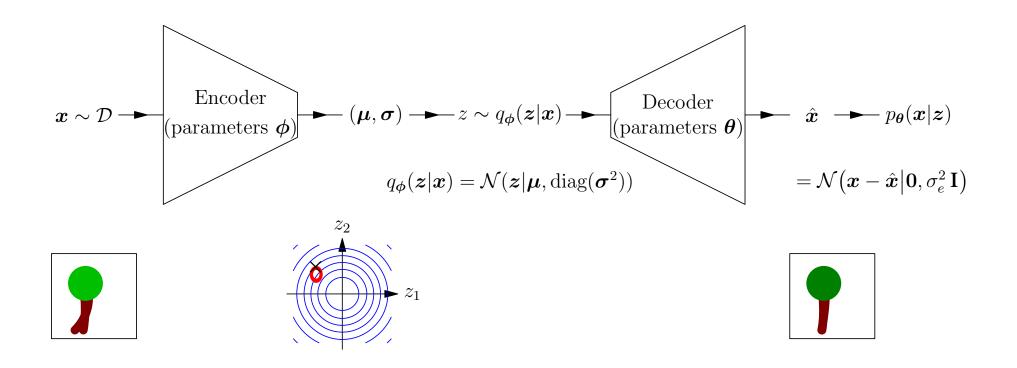






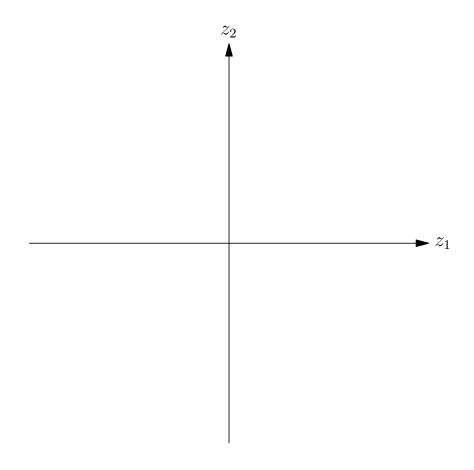




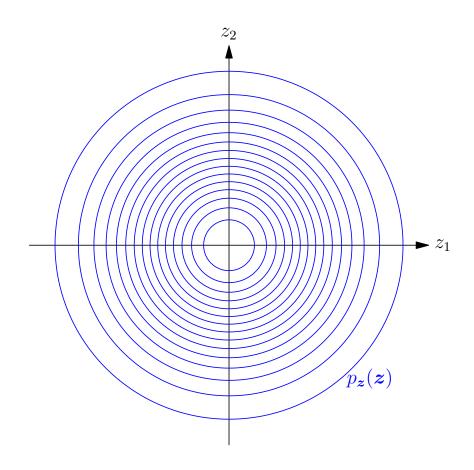


$$\mathcal{L} = \mathbb{E}_{\boldsymbol{x} \sim \mathcal{D}} \left[\text{KL} \left(q_{\boldsymbol{\theta}}(\boldsymbol{z} | \boldsymbol{x}) \middle| | \mathcal{N}(\boldsymbol{0}, \boldsymbol{I}) \right) - \log(p_{\boldsymbol{\theta}}(\boldsymbol{x} | \boldsymbol{z}(\boldsymbol{x}))) \right]$$

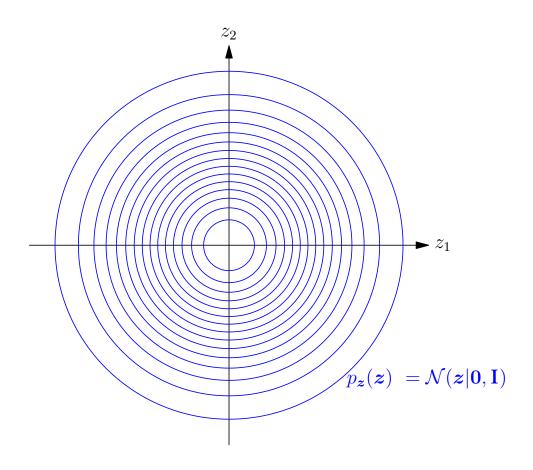
Latent Space



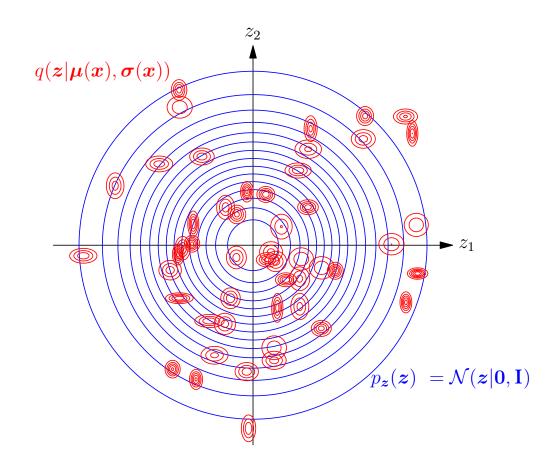
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- This is difficult to understand (at least, for me)
- It has a very natural explanation in terms of minimum description length
- Alice wants to communicate the images to Bob
- Alice uses the encoder to derive a (latent) code $q(\boldsymbol{z}|\boldsymbol{x})$ which she communicates to Bob
- ullet She also communicates the errors $oldsymbol{\delta} = x ar{x}$
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