

# Hartree-Fock Stability and its Relation to Strong Correlation

Evan Curtin

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University of Illinois at Urbana-Champaign

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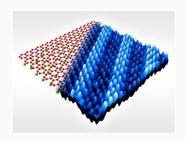
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- 3. Homogeneous Electron Gas
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- 5. Results
- 6. Future Directions

**Background Information** 

## We Have Trouble Calculating...

Polyradicals with degenerate triplet HOMO

Broken Symmetry Periodic Systems



#### The Electronic Structure Approach

The Molecular Electronic S.E. in the Born-Oppenheimer approximation

$$\left(\hat{T}_{elec} + \hat{V}_{elec-nuc} + \hat{V}_{elec-elec}\right)\Psi = E_{exact}\Psi$$

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the difference between the two energies is the correlation energy

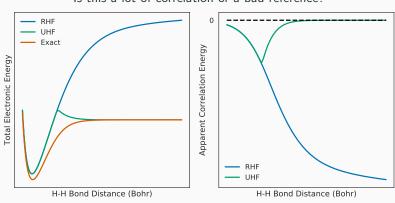
$$E_{corr} = E_{exact} - E_{HF}$$

#### Post-Hartree-Fock

- The correlation energy is recovered by post Hartree-Fock methods (CC, MBPT) which perform better the closer the HF solution is to the exact
- These methods may fail if the HF solution is far from the exact
- Can we remedy this by finding a better HF solution?
- To what extent are systems with large correlation energies insufficiently described by HF?

### Case Study: H<sub>2</sub> Dissociation

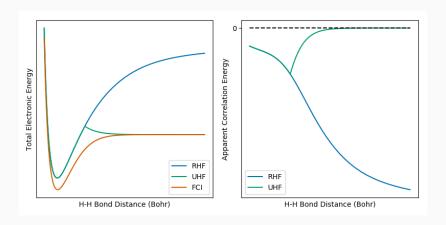
Is this a lot of correlation or a bad reference?



# Hartree-Fock Theory is Almost Always Restricted

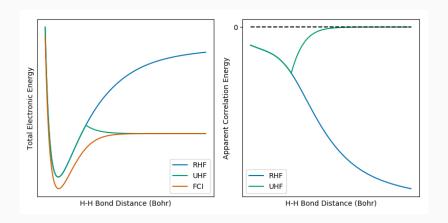
Method	Spinorbital	DoF	Eigenfunction of
Restricted	1 <u> </u>	N/2	$\hat{S}^2$ , $\hat{S}_z$
Unrestricted	1 1	N	$\hat{S}_z$
General	1 1	2N	Neither

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- Is this situation unique to H<sub>2</sub> or is it common?
- Can we identify when a better HF solution is necessary?

# Hartree-Fock Stability

 Solving the HF equations guarantees only that the energy is stationary.

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$$\begin{bmatrix} \mathbf{A} & \mathbf{B} \\ \mathbf{B}^* & \mathbf{A}^* \end{bmatrix} \begin{bmatrix} \mathbf{X} \\ \mathbf{Y} \end{bmatrix} = \omega \begin{bmatrix} \mathbf{X} \\ \mathbf{Y} \end{bmatrix}$$
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Where

$$A_{ia,jb} = \langle_i^a | H - E_0 |_j^b \rangle = (\epsilon_a - \epsilon_i) \, \delta_{ij} \delta_{ab} + \langle aj | | ib \rangle$$

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To determine instabilities, find the lowest eigenvalue

• The Matrix Equation Factorizes after spin integration

$$\begin{bmatrix} {}^{1}\mathbf{H} & \mathbf{0} \\ \mathbf{0} & {}^{3}\mathbf{H} \end{bmatrix} \begin{bmatrix} {}^{1}\mathbf{x} \\ {}^{3}\mathbf{x} \end{bmatrix} = \omega \begin{bmatrix} {}^{1}\mathbf{x} \\ {}^{3}\mathbf{x} \end{bmatrix}$$

- ${}^{1}$ **H** = Singlet Instability Matrix (RHF  $\rightarrow$  RHF)
- <sup>3</sup>H = Triplet Instability Matrix (RHF → UHF)
- If the lowest eigenvalue of either is negative, solution is unstable

Homogeneous Electron Gas

#### Why HEG?

- In finite systems with degenerate HOMO-LUMO, an RHF solution is always triplet unstable<sup>1</sup>
- Does this hold for infinite systems?
- Overhauser's theorem suggests that this always holds in 1D<sup>2</sup> HEG
- Can we show this and investigate 2D and 3D?

(1) Yamada, T.; Hirata, S. J. Chem. Phys. 2015, 143 (11), 114112. (2) Overhauser, A. W. Phys. Rev. Lett. 1960, 4 (9), 462465.

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- The total charge is constrained to be neutral,

$$V_{bg}(\mathbf{r}) = \sum_{i} \frac{-Ze^2}{|\mathbf{r} - \mathbf{R_i}|} \to -e^2 \int \frac{d\mathbf{r}'}{|\mathbf{r} - \mathbf{r}'|},\tag{3}$$

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and the background and coulomb terms cancel exactly,

$$V_{ee} = e^2 \int \frac{d\mathbf{r}'}{|\mathbf{r} - \mathbf{r}'|}.$$
 (4)

The discretized solutions are given by,

$$\epsilon_{\vec{k}} = \frac{\hbar^2 k^2}{2m} - \sum_{\vec{k'}}^{|\vec{k'}| < k_f} \langle \vec{k}, \vec{k'} | \vec{k'}, \vec{k} \rangle \tag{5}$$

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Where the 2D and 3D two electron integral is given by

$$\langle \vec{k}, \vec{k}' | \vec{k}'', \vec{k}''' \rangle = \begin{cases} \frac{\pi}{V} \frac{2^{D-1}}{|\vec{k} - \vec{k}''|^{D-1}} & \vec{k}''' = \vec{k} + \vec{k}' - \vec{k}'' \\ 0 & \text{else} \end{cases}$$

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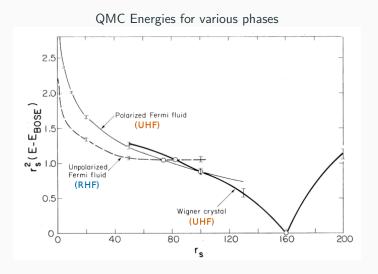
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• In 1D, if  $V(r_{12}) = V_0 \delta(r_{12})$ ,

$$\langle k, k' | k'', k''' \rangle = \begin{cases} V_0 ; & k''' = k + k' - k'' \\ 0 ; & \text{else} \end{cases}$$
 (6)

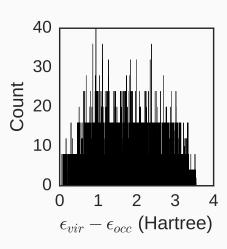
# **Energies of Some Phases are Known Exactly**



Implementation

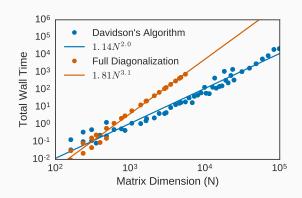
# **Technical Challenges**

- H Too big to construct or diagonalize
- Spectrum is dense, leading to numerical issues



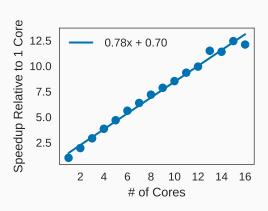
# Implementation Solutions 1: Davidson's Algorithm

- Only need the lowest eigenvalue
- Davidson requires no explicit matrix storage
- Careful choice of initial guess circumvents numerical issues
- Still slow for large N



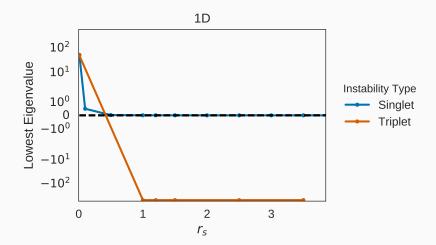
### **Implementation Solutions 2: Parallelization**

- Enables utilization of Blue Waters
- Depending on # of cores, 400-1000 fold speedup compared to serial
- This enabled me to compute 3D results

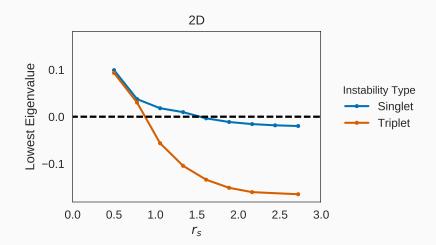


# Results

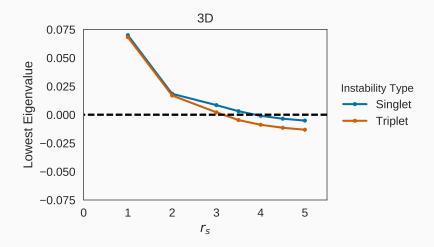
#### **Stability Curves Show Clear Transition**



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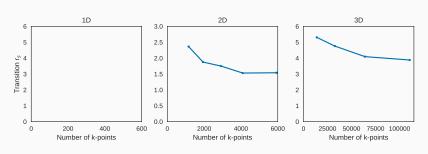


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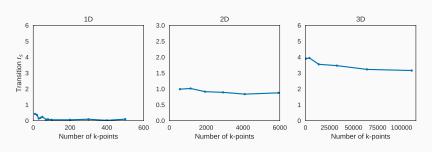
# Stability Onset Converges With k-points

#### Singlet Instabilities



# Stability Onset Converges With k-points

#### Triplet Instabilities



#### **Transitions are Consistent with Others**

# Dimensions	Instability $r_s$	Phase Boundary $r_s$
1	0.(1)	01
2	0.8(7)	0.82
3	3.(2)	$3.0^{3}$

(1) Overhauser, A. W. Phys. Rev. 1962, 128 (3), 14371452.

(3) Baguet, L.; Delyon, F.; Bernu, B.; Holzmann, M. Phys. Rev. B 2014, 90 (16), 165131.

<sup>(2)</sup> Bernu, B.; Delyon, F.; Holzmann, M.; Baguet, L. Phys. Rev. B 2011, 84 (11), 115115.

# **Concluding Remarks**

- Paramagnetic HEG instabilities are successfully reproduced by the MO hessian approach
- HF Stability analysis can show when restrictions should be lifted
- It is feasible that even stable HF are not global minimum...

# **Future Directions**

Find the lowest energy GHF solution

<sup>(1)</sup> Ohno, K. Chem. Rec. 2016, 16 (5), 21982218. (2) Supady, A.; Blum, V.; Baldauf, C. J. Chem. Inf. Model. 2015, 55 (11), 23382348.

- Find the lowest energy GHF solution
- Use algorithms inspired by similar problems (atomic configuration)

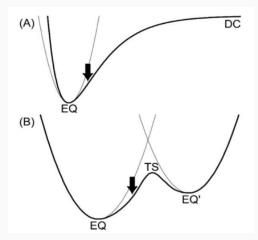
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- Genetic Algorithm<sup>2</sup>

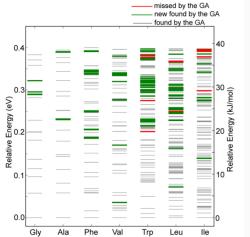
#### **Anharmonic Downard Distortion**



Replace atomic coordinates with MO coefficients and vibrational information with MO eigenvalues/vectors

# **Genetic Algorithm**

Genetic Algorithm promising in finding many low energy solutions



# **Proposal: Genetic Algorithm**

- Use as the gene the density matrix / MO coefficients
- Less human input
- Less dependence on underlying PES structure
- How the HF solution gets found is irrelevant

# Acknowledgements

- Advisor: So Hirata
- Group Members:
  - Misha Salim
  - Jacob Faucheaux
  - Alex Doran
  - Cole Johnson
  - Punit Jha
  - Alexander Kunitsa
  - Jun Zhang
- Libraries:
  - PETSc
  - SLEPc
- And the Blue Waters / NCSA Support Staff



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and to first order in  $\rho_{ai}$ , the elements of the density matrix are ,

$$\rho_{ai} = C_{ai}, \quad \rho_{ia} = C_{ai}^*. \tag{10}$$

The TDHF EoM becomes,

$$i\hbar \frac{dC_{ai}(t)}{dt} = (\epsilon_{a} - \epsilon_{i}) + \sum_{j}^{occ} \sum_{b}^{vir} \left[ \langle aj || ib \rangle C_{bj}(t) + \langle ab || ij \rangle C_{bj}^{*}(t) \right]. (11)$$

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$$(\epsilon_{a} - \epsilon_{i}) Y_{ai} + \sum_{i}^{occ} \sum_{b}^{vir} \left[ \langle aj || ib \rangle X_{bj} + \langle ab || ij \rangle Y_{bj} \right] = -\hbar \omega Y_{ai}. \quad (13)$$

Thouless, D. J. The Quantum Mechanics of Many-Body Systems, 2nd ed.; Dover: 1972. (p. 114)

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These are the equations of the Random Phase Approximation (RPA)

Thouless, D. J. The Quantum Mechanics of Many-Body Systems, 2nd ed.; Dover: 1972. (p. 114)

#### **Matrix Factorizations**

$$\begin{bmatrix} \mathbf{A} & \mathbf{B} \\ \mathbf{B}^* & \mathbf{A}^* \end{bmatrix} \begin{bmatrix} \mathbf{d} \\ \mathbf{d}^* \end{bmatrix} = 2E_2 \begin{bmatrix} \mathbf{d} \\ \mathbf{d}^* \end{bmatrix}$$

We can now apply the similarity transform defined by the Unitary matrix

$$\mathbf{U} = \frac{1}{\sqrt{2}} \begin{bmatrix} \mathbf{I} & -\mathbf{I} \\ \mathbf{I} & \mathbf{I} \end{bmatrix}$$

after which the transformed eigenvalue problem has the form

$$\frac{1}{2} \begin{bmatrix} \mathbf{A} + \mathbf{B} + \mathbf{A}^* + \mathbf{B}^* & -\mathbf{A} + \mathbf{A}^* + \mathbf{B} - \mathbf{B}^* \\ -\mathbf{A} + \mathbf{A}^* - \mathbf{B} + \mathbf{B}^* & \mathbf{A}^* + \mathbf{A} - \mathbf{B} - \mathbf{B}^* \end{bmatrix} \begin{bmatrix} \mathbf{d} + \mathbf{d}^* \\ \mathbf{d} - \mathbf{d}^* \end{bmatrix} = 2E_2 \begin{bmatrix} \mathbf{d} + \mathbf{d}^* \\ -\mathbf{d} + \mathbf{d}^* \end{bmatrix}$$

$$= 2E_2 \begin{bmatrix} \mathbf{Re}(\mathbf{d}) \\ \mathbf{Im}(\mathbf{d}) \end{bmatrix}$$

If  $\boldsymbol{A}$  and  $\boldsymbol{B}$  are both real,  $\boldsymbol{A}=\boldsymbol{A}^*$  and  $\boldsymbol{B}=\boldsymbol{B}^*$  and the above simplifies to

$$\begin{bmatrix} A + B & 0 \\ 0 & A - B \end{bmatrix} \begin{bmatrix} Re(d) \\ Im(d) \end{bmatrix} = 2E_2 \begin{bmatrix} Re(d) \\ Im(d) \end{bmatrix}$$

# **Correlation Energy Increases at Small Gap**

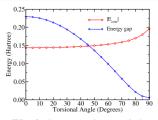


FIG. 6: Correlation energy and energy gap for the twisted ethylene  $C_2H_4$  as a function of the torsion angle around the C=C double bond.

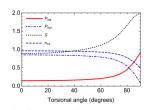


FIG. 7: Correlation curves for ethylene. P<sub>eta</sub> and P<sub>elyn</sub> as well as the occupancy of the highest occupien natural spin-orbital and the von Neumann entropy S are plotted as functions of the torsion angle around the C=C double bond.

Figure reproduced from: Benavides-Riveros, C. L.; Lathiotakis, N. N.; Marques, M. A. L. 2017, 111.

# **Physicist's Strong Correlation**

However, because all repulsive short-range interactions renormalize towards the Fermi surface, their presence does not destroy the underlying free-particle picture of a Fermi Liquid. That is, the interactions can be integrated out, leaving behind renormalized electron or quasi-particle states. Hence, in a Fermi liquid there is a simple principle that can be invoked to lay plain that free electrons are the propagating degrees of freedom. Without the assumption of a Fermi surface, no principle exists that allows us to smooth away the interactions. We refer to such problems as being strongly correlated, namely those in which no obvious principle, ... exists that governs the renormalization of the electron-electron interactions.

**Iterative Subspace Eigenvalue** 

Methods

# Davidson's Algorithm

$$\begin{array}{lll} \mathbf{A}\mathbf{x} = \lambda\mathbf{x} & & \text{Eigenvalue Problem} \\ \mathbf{V} = [\mathbf{v_1}, \mathbf{v_2}, ..., \mathbf{v_M}] & & \text{Guess vectors} \\ \mathbf{\tilde{A}} = \mathbf{V}^\dagger \mathbf{A} \mathbf{V} & & \text{Transform into subspace} \\ \mathbf{\tilde{A}} \mathbf{\tilde{x}} = \tilde{\lambda} \mathbf{\tilde{x}} & & \text{Solve the subspace problem} \\ \mathbf{x_i} \approx \mathbf{x}_i^R = \mathbf{V} \mathbf{\tilde{x}}_i & & \text{Approximate eigenvectors} \\ \lambda_i \approx \lambda_i^R = \tilde{\lambda}_i & & \text{Approximate eigenvalues} \\ \mathbf{r}_i = (\mathbf{A} - \lambda_i \mathbf{I}) \, \mathbf{x}_i^R & & \text{Calculate the residue} \\ \delta_i = c_i \mathbf{r}_i & & \text{Correction vectors} \\ c_i = \frac{1}{\lambda_i \mathbf{I} - \mathbf{D}} & & \text{Diagonal Precondition} \\ \mathbf{V} = [\mathbf{v_1}, \mathbf{v_2}, ..., \mathbf{v_M}, \delta_1, \delta_2, ..., \delta_I] & & \text{Append to guess and restart} \\ \mathbf{V} = orthonormalized(\mathbf{V}) & & \text{Ensure orthonormal projection} \\ \end{array}$$

Eigenvalue Problem Guess vectors Transform into subspace Solve the subspace problem Approximate eigenvectors Approximate eigenvalues Calculate the residue Correction vectors Diagonal Precondition Append to guess and restart

<sup>1.</sup> Saad, Y. Numerical Methods for Large Eigenvalue Problems; SIAM, 2011.

<sup>2.</sup> Davidson, E. R. J. Comput. Phys. 1975, 17 (1), 8794.

• The convergence of these subspace algorithms depends on:

Saad, Y. Numerical Methods for Large Eigenvalue Problems; SIAM, 2011.
 Li, R.-C.; Zhang, L.-H. Convergence of Block Lanczos Method for Eigenvalue Clusters; 2013.

- The convergence of these subspace algorithms depends on:
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- My recommendation for guess eigenvectors is

$$v_j^{(i)} = normalize\left(\frac{1}{|A_{ii} - A_{ii}| + 1}\right). \tag{14}$$

# Orthogonalization

• The condition number,  $\kappa$ , is bound from below by

$$\kappa \ge \frac{Max(A_{ii})}{Min(A_{jj})} \tag{15}$$

• The Gram-Schmidt procedure has numerical issues,

$$||\mathbf{I} - \mathbf{Q}^{\mathsf{T}} \mathbf{Q}|| \le \frac{\alpha \kappa^2}{1 - \beta \kappa^2}.$$
 (16)

Modified Gram-Schmidt is better, but not perfect,

$$||\mathbf{I} - \mathbf{Q}^{\mathsf{T}}\mathbf{Q}|| \le \frac{\gamma\kappa}{1 - \eta\kappa}$$
 (17)

May need multiple orthogonalization steps