

# Permutation Generation with Heap's Algorithm and the Steinhaus-Johnson-Trotter Algorithm

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## **Abstract**

A formal mathematical analysis of two algorithms – Heap's and Steinhaus-Johnson-Trotter – for generating permutations of a set. Implementation, execution and analysis of space and time performance of these two algorithms. Additional consideration is given to the nature of generating permutations and how these two algorithms differ in solving that problem.

Code and detailed test results for this project can be found at the URL below:  
<https://github.com/RyanLB/CS-350-Permutation-Generation-Algorithms>

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The application and study of algorithms in the field of combinatorics – particularly permutation generation – is an exciting area of theoretical study. Generating all distinct permutations of a set is NP hard; since there are  $n!$  possible permutations of an  $n$ -element set, even simply outputting each permutation will take  $n!$  steps. As such, no deterministic algorithm exists that can generate all permutations of a set in less than  $O(n!)$  time. The differences in the algorithms are wrinkles that allow for more space efficient computations, or that merely exist to show the cleverness of the designer with a novel application of a design pattern to the problem.

Algorithms for this problem fall into two camps: those that generate a unique permutation of a set and those that use exchange methods to generate *all* permutations of that set. Our first algorithm, Heap’s Algorithm, is a recursive twist on the exchange method. The second, Steinhaus-Johnson-Trotter, is an adjacent exchange method implemented iteratively with one loop structure, although this algorithm can be implemented recursively as well.

The intractable nature of this problem has lead to the discovery and refinement of more efficient combinatorial search optimization algorithms [4], many of which emphasize the use of backtracking and mathematical programming; perhaps most notable is the solution to the four coloring graph problem [3].

## 1 Heap’s Algorithm

Heap’s algorithm is a “divide-and-conquer” permutation generation algorithm [1]. It divides the set into subsets that all end with the same element and then generates all of the permutations that end with that element. It works by iterating from 1 to the cardinality of the set. Each iteration makes a new recursive call with  $(n - 1)$  as the new cardinality of the set. This recursion will continue until we have reached the case where  $n$  is equal to 1; it then outputs the current state of the set as a permutation. Between each recursive call, we check to see if  $n$  is odd. If so, we switch the first element of the set with the last element of the set. If  $n$  is even, we switch the  $i$ th element of the set with the last element of the set (where  $i$  the number of current iteration). This guarantees that each iteration will produce all the permutations that end with the element that has been moved into the last position in the set.

### 1.1 Pseudocode

```
//Algorithm Heaps(n, A):
//Outputs all the permutations of A using Heap’s algorithm
//Input: A is a set, n is the cardinality of the set A
//Output: The permutations of A
if n = 1 then
    output(A)
else
    for i <- 1 to n
        Heaps(n - 1, A)
        if n is odd then
            j <- 1
        else
            j <- i
        swap(A[j], A[n])
        i <- i + 1
```

### 1.2 Proof of Termination

At each step of Heap’s, we recurse and decrement  $n$  by 1. Eventually we reach the the base case of 1 element, as  $n$  must be a positive integer, so no infinite descent is possible.

### 1.3 Proof of Correctness

It is trivial to establish that this algorithm correctly outputs all distinct permutations of 1, 2, and 3-element sets. Since the algorithm works by recursively generating all  $(n - 1)$ -element sets, we can then use induction to show that it works for arbitrarily large values of  $n$ . However, because the algorithm behaves differently depending on whether  $n$  is even or odd, we'll need two separate inductive steps to prove correctness.

Based on observations made with small values of  $n$ , we can make two inductive hypotheses:

1. If  $n$  is odd, assume that Heap's algorithm correctly generates all  $n!$  permutations and that upon completion, the elements of  $S$  are in the same order as when the algorithm began
2. If  $n$  is even, assume that Heap's algorithm correctly generates all  $n!$  permutations and that upon completion, the elements of  $S$  have been rotated one space to the right (e.g. if the algorithm is run on the set  $(s_1, s_2, \dots, s_{n-1}, s_n)$ ,  $S$  is in the order  $(s_n, s_1, \dots, s_{n-2}, s_{n-1})$  when the algorithm terminates).

Assume that Heap's algorithm correctly generates all permutations of a  $k$ -element set  $S$ . We then have two cases to consider.

#### 1.3.1 $k$ is Odd

To correctly generate all permutations of a  $k + 1$  element set  $S$ , we can simply generate every permutation of each  $k$ -element subset and append the missing element to the end. To do this, we'll need to make  $n$  recursive calls, each time withholding a different element.

Since we're generating permutations of the elements in positions  $1 \dots k$ , we can ensure that each recursive call acts on a distinct subset by placing a different element in position  $k + 1$  in each iteration. Since  $k$  is odd, the items in positions  $1 \dots k$  will be in the same order after each recursive call runs. Therefore, iterating from  $1 \dots k + 1$ , making a recursive call, and then swapping  $s_i$  with  $s_{k+1}$  will place each element of  $S$  in position  $k + 1$  once and only once. Since we assume that we're correctly generating permutations of  $k$ -element sets, this implies correctness.

Notice also that each element  $s_i$  for  $i \leq k$  will move one position to the right, since it will be swapped into position  $k + 1$  and then swapped back into position  $i + 1$  on the next iteration. The final iteration will swap the element in position  $k + 1$  with the element in position  $k + 1$ , meaning that we don't rotate all the way back to the starting condition. This confirms that the elements of  $S$  will be rotated one position to the right when the algorithm terminates (since  $k$  is odd,  $k + 1$  is even).

#### 1.3.2 $k$ is Even

Since  $k$  is even, each call made on a  $k + 1$  element set will rotate the items in positions  $1 \dots k$  one position to the right. This means that we no longer have to iterate across positions when swapping elements in and out of position  $k + 1$ ; we can let the rotation of the elements take care of this for us, swapping the elements in positions 1 and  $k + 1$  after each recursive call.

Since a call (and rotation) occur before the first swap, we can see that items  $s_1 \dots s_k$  will be swapped into location  $k + 1$  in reverse order; for the same reason, they will be swapped back into location 1 in reverse order as well. This means that the elements of  $S$  will maintain the same relative order when our algorithm terminates. We can also see that  $s_{k+1}$  is swapped into position 1 after the first recursive call. Since  $k$  recursive calls remain, it will then be rotated  $k$  times through  $k$  positions and return to location 1 after the final recursive call. The final swap will return it to location  $k + 1$ . Since elements are in the same relative order and  $s_{k+1}$  ends in position  $k + 1$ , this confirms that running our algorithm on sets with an odd number of elements leaves the order of the elements unchanged.

We have now proven that both inductive hypotheses are true. Since we have established base cases for both even and odd values of  $n$ , this proves the correctness of Heap's algorithm for all  $n \geq 1$ , regardless of whether  $n$  is even or odd.

## 1.4 Time Complexity

We'll analyze the running time of this algorithm in terms of swaps, comparisons, assignments, and processes. From the code above, we can count how many times each of these operations is performed, *not* including work done within the recursive calls.

Swaps ( $O(1)$ )

The swap operation appears only once in our implementation. This is never executed when  $n = 1$ ; if  $n > 1$ , the loop containing it executes  $n$  times.

Comparisons ( $O(1)$ )

A comparison appears before we enter our loop regardless of the current value of  $n$ . Another comparison appears within the loop, which executes  $n$  times for all  $n > 1$ . The second comparison also includes a division for modular arithmetic; we will also consider this an  $O(n)$  operation.

Assignments ( $O(1)$ )

Not counting the assignments that appear within the swaps, a single assignment occurs after the comparison that checks whether  $n$  is odd.

Processes/prints ( $O(n)$ )

We only process a permutation in the base case of our recursion, when  $n = 1$ . Thus we execute a process once when  $n = 1$  and 0 times in any other case.

### 1.4.1 Factoring In Recursion

Our total number of operations (not counting recursion) can be represented by the following table:

Input Size	1	2	3	4	5	$n > 1$
Swaps	0	2	3	4	5	$n$
Comparisons	1	3	4	5	6	$n + 1$
Assignments	0	2	3	4	5	$n$
Processes	1	0	0	0	0	0
Recursive calls	0	2	3	4	5	$n$

Looking only at the recursive calls, it becomes clear that the number of recursive calls made for an input of size  $n$  is 0 when  $n = 1$  and  $n$  for any  $n > 1$  (we can confirm this by looking at the loop in our code). It follows that if we wish to include operations executed within recursive calls, the total number of times that each operation will execute on an input of size  $n$  will be the number of times that this operation executes in the work function plus  $n$  times the number of times that operation is performed for an input of size  $n - 1$ .

This means that with recursion factored in, the total number of swaps, assignments, and recursive calls can be expressed as follows [5]:

$$\begin{aligned}
 T(n) &= n \cdot T(n-1) + n \\
 \frac{T(n)}{n!} &= \frac{T(n-1)}{(n-1)!} + \frac{1}{(n-1)!} && \text{Divide by } n! \\
 &= \sum_{i=1}^n \frac{1}{(i-1)!} && \text{Since } T(1) = 0 \\
 &= \sum_{i=1}^{n-1} \frac{1}{i!} \\
 T(n) &= n! \cdot \sum_{i=1}^{n-1} \frac{1}{i!} && \text{Multiply by } n!
 \end{aligned}$$

Because comparisons have  $n + 1$  comparisons before recursion, we can use a similar process to discover that the total number of comparisons can be expressed as:

$$n! \cdot \sum_{i=1}^{n-1} \frac{1}{i!} + n! \cdot \sum_{i=1}^n \frac{1}{i!} = 2! \cdot \sum_{i=1}^{n-1} \frac{1}{i!} + 1$$

Combining this with the time complexity of each operation, the overall time complexity is therefore as follows:

$$\begin{aligned} & 2 \cdot \left( n! \cdot \sum_{i=1}^{n-1} \frac{1}{i!} \right) + \left( 2n! \cdot \sum_{i=1}^{n-1} \frac{1}{i!} + 1 \right) + n \\ &= n! \cdot \left( 4 \cdot \sum_{i=1}^{n-1} \frac{1}{i!} \right) + 1 + n \end{aligned}$$

## 1.5 Space Complexity

Looking at the code above, we can see that we use the same set object throughout the series of recursive calls. Beyond that, since our recursion decrements  $n$  each time and stops at 1, we will have at most  $n$  (constant-size) stack-frames at any given time.

The space complexity of Heap's algorithm is therefore  $O(n)$ .

## 2 The Steinhaus-Johnson-Trotter Algorithm

The Steinhaus-Johnson-Trotter algorithm is an example of a minimal change/decrease by one algorithmic approach to the permutation problem [2]. It is based on the observation that all permutations of  $n$  elements can be generated by taking the element  $a_n$  and placing it in every possible position in each permutation of  $n - 1$  elements.

This behavior is induced by assigning each element a direction; the direction of each element is initialized to be left. We call an element mobile if and only if it points to a smaller element. As long as our set contains a mobile element, we take the largest mobile element  $a_\ell$  and swap it with the element to which it points; at this point, we reverse the direction of every element larger than  $a_\ell$ .

### 2.1 Pseudocode

```
//Algorithm: Steinhaus-Johnson-Trotter(A[n])
//Input      : Array of sorted integers
//Output     : All permutations of A[n]

initialize D = [<- <- <- ... <-] (from 1 to n)

while there exists a mobile element
    k <- the largest mobile integer in A
    swap k and the element it points to
    reverse the direction of all elements in A larger than k
```

### 2.2 Proof of Termination and Correctness

By induction on  $n$ , the validity of the above algorithm is proven as follows. As a base case, we can easily verify that the algorithm is true for sets of two elements. Initially  $a_n$  is active and being the largest element moves left

through all positions until it is not pointing to a smaller element. Now  $a_n$  is immobile and at an extreme position. Assuming that the algorithm works for  $n - 1$  integers, the next permutation of  $n - 1$  elements is generated, with  $n$  playing no part. At this point,  $a_n$  becomes mobile again and passes unobstructed to the opposite extreme. The process continues, with  $a_n$  reversing direction for each permutation of  $n - 1$  elements, until the last permutation of  $n - 1$  elements is generated, leaving all but  $a_n$  immobile. After the final traversal of  $n$ , it also immobilized and the algorithm terminates. Thus each of the  $n!$  permutations is generated once and only once, and this algorithm will terminate in finite time.

## 2.3 Time Complexity

Our proof of correctness shows that this algorithm correctly generates all  $n!$  permutations of an  $n$ -element set; this means that our loop will run  $n!$  times. However, unlike Heap's algorithm, this loop will not perform the same number of steps every time. Each loop iteration will perform:

- A search for the largest mobile element, which is broken into  $n$  mobility checks and  $c$  comparisons against the current largest mobile element (where  $c$  is the sum of the numbers of mobile elements for each iteration)
- A single  $O(n)$  process
- Some number of  $O(1)$  direction reversals
- One  $O(1)$  swap (except for the last iteration, in which no swaps occur)

How can we determine the number of direction reversals? The key lies in our definition of mobility and the following fact: for each case in which item  $a_i$  is the largest mobile element (LME), we will perform a reversal for each item  $a_j > a_i$  in our set. We can therefore define the total number of reversals across *all* iterations as follows:

$$R_{\text{total}} = \sum_{i=1}^n ((\text{number of times } a_i \text{ is the LME}) \cdot (n - i))$$

### 2.3.1 Solving for Largest Mobile Element Counts

We say that an element is mobile if and only if it points to a smaller element. Based on this definition, I propose the following axioms:

**Axiom 2.1** *Since  $a_n$  is the largest element in the set, this means that any time it is mobile, it will be the largest mobile element.*

**Axiom 2.2** *Furthermore,  $a_n$  will only be immobile if it points at an edge. At this point, if another mobile element exists,  $a_n$  will reverse direction; otherwise, no mobile elements exist and our loop terminates. Since we are sweeping  $a_n$  back and forth across all  $(n - 1)$ -element permutations, it will point to an edge and lose mobility once for each of these.*

**Axiom 2.3** *An element  $a_i$  can be mobile in an  $n$ -element permutation  $\pi$  if and only if it would be mobile in the  $i$ -element permutation  $\pi - a_j$  for all  $j > i$ .*

Extending axiom 2.3, we can see the following: since we're assuming that each possible permutation of an  $(n - 1)$ -element set appears  $n$  times in permutations of an  $n$ -element set, any  $(n - 1)$ -element permutation  $\pi_{n-1}$  in which  $a_{n-1}$  is the LME will appear  $n$  times in permutations of  $n$  elements. Of these,  $a_n$  will be the LME in any case where it is mobile by axiom 2.1. Since  $a_n$  will be mobile for all but one of the  $n$  repetitions of  $\pi_{n-1}$ . In this permutation  $\pi$ ,  $a_{n-1}$  is the LME of  $\pi - a_n$  and  $a_n$  is immobile. Therefore,  $a_{n-1}$  is the LME in  $\pi$ .

We can therefore conclude that in permutations of  $n$  elements,  $a_{n-1}$  is the LME exactly once for every  $(n - 1)$ -element permutation for which  $a_{n-1}$  is the LME. By axiom 2.1, this is any  $(n - 1)$ -element permutation in which  $a_{n-1}$  is mobile.

Axiom 2.2 tells us that  $a_n$  loses mobility exactly once for each  $(n - 1)$ -element permutation, of which there are  $(n - 1)!$ . Therefore, the number of times  $a_n$  is the largest mobile element in a permutation of  $m$  elements for all  $m \geq n$  is equal to exactly  $n! - (n - 1)!$ .

Substituting this back into our equation for  $R_{\text{total}}$ , we get the following result:

$$R_{\text{total}} = \sum_{i=1}^{n-1} ((i! - (i - 1)!) \cdot (n - i))$$

### 2.3.2 Mobility Counts

We can solve for mobility counts in a similar fashion. Every  $(n - 1)$ -element permutation appears  $n$  times in the set of  $n$ -elements. Element  $a_n$  will be swept across each position in  $\pi_{n-1}$ . The combination of these two facts tells us that if an element  $a_i$  is mobile in  $\pi_{n-1}$ , it will be mobile in every  $n$ -element permutation that extends  $\pi_{n-1}$  except for the one case in which  $a_n$  is between  $a_i$  and the (smaller) element that  $a_i$  points to.

We know that  $a_n$  is mobile in  $(n! - (n - 1)!)$  of the  $n$ -element permutations in which it first appears. By this reasoning, it will now be mobile in  $n \cdot (n! - (n - 1)!)$  permutations of  $n + 1$  elements,  $(n + 1) \cdot n \cdot (n! - (n - 1)!)$  permutations of  $n + 2$  elements, and so on.

We can therefore solve for the total number of mobile elements across all iterations (which is also the total number of comparisons made to find the largest mobile element in each iteration) as follows:

$$C_{\text{total}} = \sum_{i=1}^n \left( (i! - (i - 1)!) \cdot \frac{(n - 1)!}{(i - 1)!} \right)$$

The overall time complexity of the Steinhaus-Johnson-Trotter algorithm is therefore:

$$n! \cdot (2n + 1) + \sum_{i=1}^{n-1} \left( (i! - (i - 1)!) \cdot \frac{(n - 1)!}{(i - 1)!} \right) + \sum_{i=1}^n ((i! - (i - 1)!) \cdot (n - i))$$

## 2.4 Space Complexity

Since this is an iterative algorithm, we can accomplish everything within a single stack frame (while we've divided our code with function calls, the number of simultaneously active stack frames remains constant with respect to  $n$ ). This algorithm needs only an  $n$ -element array to hold its elements and another  $n$ -element array to hold the direction in which each element points.

## 3 Testing Methodology

### 3.1 Correctness Tests

To test for correctness we randomly generated sets of zero to six elements and then feed these into our algorithms. The output of the algorithms was then cross checked against the Python's standard library permutation generation algorithm, which we assume is correct, if both outputs matched then we can assume our permutation generation algorithm is correct. (Or at least as correct as Python's standard library permutation generation algorithm.)

### 3.2 Time Complexity Profiling

In order to ensure that our time complexities were correct, basic operations (e.g. swaps, comparisons, assignments, and the like) were factored out into their own functions. Python's `cProfile` framework was then used to count the number of times each function was called.



### 3.2.1 Direct Comparisons and Hypotheses

By breaking down our functions into swaps, comparisons, assignments, and recursive calls, we can directly compare the running time of the two algorithms for an input of size  $n$ . For the purposes of comparison, we consider each direction reversal in SJT to be comprised of a comparison and an assignment and each mobility check to be comprised of two comparisons.

	Heap's	SJT	Larger
Swaps	$n! \cdot \sum_{i=1}^{n-1} \frac{1}{i!}$	$n! - 1$	Heap's
Compares	$2n! \sum_{i=1}^{n-1} \frac{1}{i!} + 1$	$n \cdot n! + 2 \sum_{i=1}^n \left( (i! - (i-1)!) \cdot \frac{(n-1)!}{(i-1)!} \right) + \sum_{i=1}^n ((i! - (i-1)!) \cdot (n-i))$	SJT
Assigns	$n! \cdot \sum_{i=1}^{n-1} \frac{1}{i!}$	$\sum_{i=1}^n ((i! - (i-1)!) \cdot (n-i))$	Heap's
Processes	$n!$	$n!$	Tie
Calls	$n! \cdot \sum_{i=1}^{n-1} \frac{1}{i!}$	0	Heap's

With this in mind, we expect Heap's algorithm to have the longest real-world running time. To test this, each algorithm was run for inputs of sizes 5, 6, 7, and 8 100 times. The clock times for these 100 tests were then averaged and compared. While clock time is not the sole measurement of computing efficiency, it is the standard by which most end users judge the performance of their software.

## 4 Test Results

### 4.1 Correctness Results

Both algorithms passed the correctness check without issue.

### 4.2 Time Complexity Results

Average Running Times Across 100 Tests				
Input Size	5	6	7	8
Heap's Average Running Time (seconds)	0.00439	0.0279	0.21779	1.85517
SJT Average Running Time (seconds)	0.00118	0.00988	0.08201	0.70469

## 5 Conclusions

The Steinhaus-Johnson-Trotter algorithm noticeably outperformed Heap's algorithm for each of the input sizes tested. This is not the result reached by Robert Sedgewick in his 1977 paper "Permutation Generation Methods". Sedgewick concluded that Heap's algorithm was, at the time, the fastest method for generating permutations [4]. However, he did this by hand-writing assembly code in a pseudo-assembly language that he developed himself.

In cases where the data is not originally sorted, this may not be the case, as the Steinhaus-Johnson-Trotter algorithm relies on the positions and relative values of elements to induce correct behavior with its definitions of mobility. If the data is not sorted (or if elements are types such as strings, where comparisons may take a disproportionately long time compared to other operations), though, the algorithm can be adapted to generate permutations of element indices instead. This will generate the same permutations, but will increase the cost of **process** operations by  $n$  additional dereferences.

It is the conclusion of this group that if both algorithms are implemented reasonably in a high-level programming language (e.g. Python), the Steinhaus-Johnson-Trotter algorithm will yield better overall performance.

## References

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- [4] Sedgewick, Robert (1977), “Permutation generation methods”, ACM Computer Survey 9 (2): 137?164, doi:10.1145/356689.356692
- [5] Homework solutions from Eric Breimer’s Analysis of Algorithms course at Siena College. While homework solutions may not be the most rigorously peer-reviewed sources, this did give me the idea to divide the total number of swaps by  $n!$ , which was essential to finding the time complexity of Heap’s algorithm.  
<http://www.cs.siena.edu/~ebreimer/courses/csis-385-s04/homework/text5>