

Design Automation Renegades

GLOBETROTTING DIVISION

Boilerplate Code: Data Structures and Algorithms for Design Automation

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REPORT ON
Common Data Structures and Algorithms
Found in Boilerplate Code for
Design Automation Software

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Abstract

This report describes the design and implementation of common data structures and algorithms, as well as “computational engines” that are found in electronic design automation (EDA) software.

Data structures and algorithms for digital VLSI and cyber-physical system design include: binary decision diagrams (BDDs), AND-inverter graphs (AIGs), and their associated algorithms for optimization, traversal, and other operations (such as graph matching). Common computational engines for digital systems would include: optimization and verification engines for deterministic and nondeterministic finite state machines; decision procedures for the boolean satisfiability problem (SAT solvers) and satisfiability modulo theories (SMT solvers); quantified boolean formula (QBF) solvers; and SAT and SMT solvers for maximum satisfiability (i.e., Max-SAT and Max-SMT solvers).

Regarding EDA problems that require numerical computation (in digital, analog, or mixed-signal VLSI design), the data structures and algorithms for circuit simulation based on sparse graph would be required. In addition, techniques for model order reduction shall be implemented.

Computational engines for statistical and probabilistic analyses or stochastic modeling can include data structures and algorithms for partially observable Markov decision processes (POMDPs) and Markov chains. Tools for analyses of queueing systems (based on queueing theory) should be included.

Regarding cyber-physical systems and mixed-signal circuits, hybrid automata can be used to represent these circuits and systems.

Optimization engines for EDA include: solvers for different types of mathematical programming, such as linear programming (LP), integer linear programming (ILP), mixed-integer linear programming (MILP), quadratic programming (QP), convex programming (CP), geometric programming (GP), and second-order conic programming (SOCP); solvers for pseudo-boolean optimization (PBO solvers) and weighted-boolean optimization (WBO); and meta-heuristics (e.g., evolutionary algorithms, simulated annealing, and ant colony optimization).

Algorithms shall be implemented using parallel programming, in a scalable style. In addition, considerations shall be given to the use of constraint programming.

More stuff to be included...

Revision History

Revision History:

1. Version 0.1, December 23, 2014. Initial copy of the report.
2. Version 0.1.1, September 16, 2015. Added sections for mathematics and statistics, and the abstract.

Contents

Revision History	i
1 Algorithms	1
2 Data Structures	2
2.1 Graphs	2
2.1.1 Directed Graphs	2
2.1.2 Undirected Graphs	2
3 Mathematics	3
4 Statistics	5
5 C++ Resources	6
5.1 Computational Complexity of C++ Containers	10
6 Questions	11
6.1 Unresolved C++ Questions	11
6.2 Resolved C++ Questions	11
Acknowledgments	14
Bibliography	18

Chapter 1

Algorithms

This section documents algorithms that I have implemented for my C++ -based boilerplate code repository.

A template for typesetting algorithms is shown in PROCEDURE 1.

NAME OF THE ALGORITHM(*ARGUMENTS*)

```
// Input ARGUMENT #1: Definition1
// Input ARGUMENT #2: Definition2
1 BODY OF THE PROCEDURE
  // A while loop.
2 while [condition]
3   [Something]
  // A for loop.
4 for Var = [initial value] to [final value]
5   [Something]
  // An if-elseif-else block.
6 if [Condition1]
7   Blah...
8 elseif [Condition2]
9   Blah...
10 elseif [Condition3]
11   Blah...
12 else
13   Blah...
  // A variable assignment.
14 blah = A[j]
  // This is indented with a tab.
  // What is the output of this procedure?
15 return
```

Chapter 2

Data Structures

2.1 Graphs

2.1.1 Directed Graphs

2.1.1.1 Functions that need to be implemented

2.1.1.2 Binary Decision Diagrams (BDDs)

2.1.1.3 AND-Inverter Graphs (AIGs)

2.1.2 Undirected Graphs

Chapter 3

Mathematics

Math symbols that I use frequently:

1. \mathbb{N}
2. $\sum_{i=1}^n$
3. $f(x) = \lim_{n \rightarrow \infty} \frac{f(x)}{g(x)}$
4. \emptyset
5. q

A 3×3 matrix: $\begin{pmatrix} 11 & 12 & 13 \\ 21 & 22 & 23 \\ 31 & 32 & 33 \end{pmatrix}$

Here is an equation:

$$\iint_{\Sigma} \nabla \times \mathbf{F} \cdot d\mathbf{\Sigma} = \oint_{\partial\Sigma} \mathbf{F} \cdot d\mathbf{r}. \quad (3.1)$$

Here is an equation that is not numbered.

$$\nabla \times \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t}$$

Here is the set of Maxwell's equations that is numbered.

$$\nabla \cdot \mathbf{E} = \frac{\rho}{\epsilon_0} \quad (3.2)$$

$$\nabla \cdot \mathbf{B} = 0 \quad (3.3)$$

$$\nabla \times \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t} \quad (3.4)$$

$$\nabla \times \mathbf{B} = \mu_0 \left(\mathbf{J} + \epsilon_0 \frac{\partial \mathbf{E}}{\partial t} \right) \quad (3.5)$$

$$\begin{array}{l} \text{minimize} \sum_{i=1}^c c_i \cdot x_i \\ \underline{x} \in S \\ \text{subject to :} \\ x_1 + x_4 = 0 \\ x_3 + 7 \cdot x_4 + 2 \cdot x_9 = 0 \end{array}$$

$$f(n) = \begin{cases} case - 1 & : n \text{ is odd} \\ case - 2 & : n \text{ is even} \end{cases} \tag{3.6}$$

Proof. This is a proof for BLAH ... □

Theorem 3.1. *TITLE of theorem. My theorem is...*

Axiom 3.1. *TITLE of axiom. Blah...*

Cases of putting a bracket/parenthesis on the right side of the equation.

$$\left. \begin{array}{l} B' = -\partial \times E, \\ E' = \partial \times B - 4\pi j, \end{array} \right\} \text{Maxwell's equations}$$

Labeling an arrow: $\overset{ewq}{\longrightarrow}$

Chapter 4

Statistics

Chapter 5

C++ Resources

Some C++ and C++ STL resources are:

1. [28]: http://www.tutorialspoint.com/cplusplus/cpp_stl_tutorial.htm
2. [8] and CplusplusCom2015: <http://www.cplusplus.com/reference/stl/>
3. <http://en.cppreference.com/w/cpp/container>
4. <http://www.cs.wustl.edu/~schmidt/PDF/stl4.pdf>
5. Pointers to functions: <http://www.cplusplus.com/doc/tutorial/pointers/>

C++ topics:

1. Function objects:
 - (a) [https://en.wikipedia.org/wiki/Functional_\(C%2B%2B\)](https://en.wikipedia.org/wiki/Functional_(C%2B%2B))
 - (b) <http://stackoverflow.com/questions/356950/c-functors-and-their-uses>
 - (c) <http://www.cprogramming.com/tutorial/functors-function-objects-in-c++.html>
2. Strings:
 - (a) [49], Chp 23
 - (b) [48], Chp 23
 - (c) [15], Chp 18
 - (d) [3], Chp 19
 - (e) [10], Chp 1
3. IO Streams:
 - (a) [10], Chp 2
 - (b) [12], Chp 12. See all of [12–14].
 - (c) [49], Chp 10-11
 - (d) [48], Chp 10-11
 - (e) [31], Chp 16
 - (f) [51], Chp 10
 - (g) [46], Chp 21
 - (h) [3], Chp 28
 - (i) [15], Chp 12
 - (j) [36], Chp 17
 - (k) [26], Chp 8
4. Templates:
 - (a) [10], Chp 3
 - (b) [9], Chp 16

- (c) [49], Chp 19
- (d) [48], Chp 19
- (e) [31], Chp 24
- (f) [51], Chp 6
- (g) [2], book; typelist - Chp 3
- (h) [46], Chp 18
- (i) [50], book
- (j) [1], book
- (k) [3], Chp 29
- (l) [15], Chp 11,21
- (m) [26], Chp 16

5. Debugging:

- (a) [10], Chp 11 (especially memory management problems, pp. 533)

6. STL containers:

- (a) [10], Chp 4
- (b) [47], Chp 8
- (c) [31], Chp 25
- (d) [51], Chp 7
- (e) [37], book
- (f) [3], Chp 18
- (g) [15], Chp 15-16
- (h) [36], Chp 16
- (i) [26], Chp 9,11
- (j) [11]:
 - i. `vector<int> v(10);` // Create an int vector of size 10.
 - ii. `v[5] = 10;` // Target of this assignment is the return value of operator[].

7. STL algorithms:

- (a) [10], Chp 5
- (b) [31], Chp 25
- (c) [51], Chp 7
- (d) [37], book
- (e) [3], Chp 18
- (f) [15], Chp 15,17
- (g) [36], Chp 16
- (h) [26], Chp 10

8. Function addresses:

- (a) [9], Chp 3, pp. 213
- (b) [49], Chp 8
- (c) [48], Chp 8

9. Dynamic memory management problems:

- (a) [9], Chp 6,13
- (b) [12], Chp 13. See all of [12–14].
- (c) [27], Chp 2-4
- (d) [46], Chp 29
- (e) [3], Chp 14

- (f) [15], Chp 10,22
 - (g) [36], Chp 9,12
 - (h) [26], Chp 12,13
10. Function overloading:
- (a) [9], Chp 7
 - (b) [12], Chp 6. See all of [12–14].
 - (c) [49], Chp 8
 - (d) [48], Chp 8
 - (e) [46], Chp 14
11. Operator overloading:
- (a) [9], Chp 12
 - (b) [31], Chp 18
 - (c) [46], Chp 15
 - (d) [26], Chp 14
12. Constants:
- (a) [9], Chp 8
13. Functions and pointers:
- (a) [9], Chp 11:
 - i. use const at the end of accessor functions
 - ii. Do not use pointers as instance variables
 - (b) [49], Chp 8:
 - i. Pass-by-reference: e.g., void init(vector<double> &v)
 - ii. Pass-by-const-reference: e.g., void print(const vector<double> &v)
 - iii. Pass-by-value: e.g., void fn(int x)
 - (c) [48], Chp 8
 - (d) [31], Chp 15,20
 - (e) [3], Chp 12-13
 - (f) [36], Chp 7-8
 - (g) [26], Chp 6
 - (h) Elsewhere:
 - i. You cannot call a non-const method from a const method. That would 'discard' the const qualifier.:
 - A. <http://stackoverflow.com/questions/2382834/discards-qualifiers-error>
 - ii. Pointer to constant data: *const type* variable*; and *type const * variable*;
 - A. http://www.cprogramming.com/reference/pointers/const_pointers.html
 - iii. Pointer with constant memory address: *type * const variable = some-memory-address*;
 - A. http://www.cprogramming.com/reference/pointers/const_pointers.html
 - iv. Constant data with a constant pointer: *const type * const variable = some-memory-address*; and *type const * const variable = some-memory-address*;
 - A. http://www.cprogramming.com/reference/pointers/const_pointers.html
 - v. <http://stackoverflow.com/questions/1143262/what-is-the-difference-between-const->[29]:
 - A. Read it backwards; the first *const* can be on either side of the type.
 - B. "Read pointer declarations right-to-left."
 - C. From the answer of Ted Dennison, July 17, 2009. **Rule: The "const" goes after the thing it applies to. Putting const at the very front (e.g., const int *) is an exception to the rule.**

- D. `int*` – pointer to `int`
- E. `int const *` == `const int *` – pointer to `const int`
- F. `int * const` – `const` pointer to `int`
- G. `int const * const` == `const int * const` – `const` pointer to `const int`
- H. `int **` – pointer to pointer to `int`
- I. `int ** const` – A `const` pointer to a pointer to an `int`
- J. `int * const *` – A pointer to a `const` pointer to an `int`
- K. `int const **` – A pointer to a pointer to a `const int`
- L. `int * const * const` – A `const` pointer to a `const` pointer to an `int`
- vi. For the following [29], let: `int var0 = 0;`
 - A. `const int &ptr1 = var0;` // Constant reference
 - B. `int * const ptr2 = &var0;` // Constant pointer
 - C. `int const * ptr3 = &var0;` // Pointer to `const`
 - D. `const int * const ptr4 = &var0;` // `Const` pointer to a `const`
- vii. A pointer is dereferenced

14. OOD and inheritance:

- (a) [9], Chp 14,15
- (b) [12], Chp 13,14,15. See all of [12–14].
- (c) [49], Chp 9
- (d) [48], Chp 9
- (e) [31], Chp 13-14,21
- (f) [51], Chp 3-4,8
- (g) [3], Chp 24-26
- (h) [15], Chp 4-9
- (i) [36], Chp 10-11,13,14,15
- (j) [26], Chp 7,15,18,19

15. SW engineering issues:

- (a) [3], Chp 21
- (b) [15], Chp 24-26

16. multi-threading:

- (a) [47], Chp 3

17. graphs:

- (a) [47], Chp 7

18. typedef:

- (a) In the sandbox, use the *Make* target *make typedef* to study an example of how *typedef* can be used. When the *header file* defines/specifies the *typedef*, and is included in the *C++ implementation file* and other *C++ implementation files* that instantiates those objects, it can be used subsequently without additional definition/specification. October 6, 2015.

Books to classify:

1. C++ programming: [18, 24, 25, 34, 35, 40, 41, 43–45]
2. C++ STL: [5–7, 16, 17, 21, 22, 38, 39]
3. C++ -based MPI programming: [23]
4. scientific computing: [32]
5. Boost C++: [30, 33, 42]

5.1 Computational Complexity of C++ Containers

Table 5.1 shows a tabulated summary of containers in the C++ Standard Template Library (STL) and the computational complexity for each of their common operations: `add(element e)`, `remove(element e)`, `search(element e)`, `size()`, `empty()`, `begin()`, and `end()`.

Table 5.1: Computational Complexity of Basic Operations of Containers from the C++ STL.

Container \ Complexity	add	remove	search	size	empty	begin	end
vector	$O(1)$	$O(n)$	$O(n)$	$O(1)$	$O(1)$	$O(1)$	$O(1)$
list	$O(1)$	$O(n)$	$O(n)$	$O(1)$	$O(1)$	$O(1)$	$O(1)$
queue	$O(1)$ amortized	$O(1)$	$O(n)$	$O(1)$	$O(1)$	$O(1)$	$O(1)$
priority queue	$O(\log n)$	$O(\log n)$	$O(n)$	$O(1)$	$O(1)$	$O(1)$???
set	$O(\log n)$	$O(\log n)$	$O(\log n)$	$O(1)$	$O(1)$	$O(1)$	$O(1)$
multi-set	$O(\log n)$???	$O(\log n)$	$O(1)$	$O(1)$	$O(1)$	$O(1)$
map	$O(\log n)$	$O(\log n)$	$O(\log n)$	$O(1)$	$O(1)$	$O(1)$	$O(1)$
multi-map	$O(\log n)$???	$O(\log n)$	$O(1)$	$O(1)$	$O(1)$	$O(1)$
stack	$O(1)$	$O(1)$	$O(n)$	$O(1)$	$O(1)$	$O(1)$	$O(1)$

To conclude, we can get some facts about each data structure:

1. `std::list` is very very slow to iterate through the collection due to its very poor spatial locality.
2. `std::vector` and `std::deque` perform always faster than `std::list` with very small data
3. `std::list` handles very well large elements
4. `std::deque` performs better than a `std::vector` for inserting at random positions (especially at the front, which is constant time)
5. `std::deque` and `std::vector` do not support very well data types with high cost of copy/assignment

This draw simple conclusions on usage of each data structure [4, 20]:

1. Number crunching: use `std::vector` or `std::deque`
2. Linear search: use `std::vector` or `std::deque`
3. Random Insert/Remove:
4. Small data size: use `std::vector`
5. Large element size: use `std::list` (unless if intended principally for searching)
6. Non-trivial data type: use `std::list` unless you need the container especially for searching. But for multiple modifications of the container, it will be very slow.
7. Push to front: use `std::deque` or `std::list`

Chapter 6

Questions

6.1 Unresolved C++ Questions

Questions about C++:

1.

6.2 Resolved C++ Questions

Difference between pointers and references:

1. Yusuf Kemal Özcan (“BFaceCoder”), “Is there any difference between pointers and references? [duplicate],” Stack Exchange Inc., New York, NY, April 18, 2013. Available online from *Stack Exchange Inc.: Programmers Stack Exchange: Questions* at: <http://programmers.stackexchange.com/questions/195337/is-there-any-difference-between-pointers-and-references>; October 6, 2015 was the last accessed date.
 - (a)
2. Macneil Shonle and Programmers Stack Exchange contributors, “What’s a nice explanation for pointers? [closed],” Stack Exchange Inc., New York, NY, July 30, 2015. Available online from *Stack Exchange Inc.: Programmers Stack Exchange: Questions* at: <http://programmers.stackexchange.com/questions/17898/whats-a-nice-explanation-for-pointers>; October 6, 2015 was the last accessed date.
 - (a) Answer from Kevin, November 10, 2010: <http://programmers.stackexchange.com/a/17919> and <http://programmers.stackexchange.com/questions/17898/whats-a-nice-explanation-for-pointers/17919#17919>. “A pointer is a variable that contains an address to a variable. A pointer is both defined and dereferenced (yielding the value stored at the memory location that it points to) with the “*” operator; the expression is mnemonic.” ... `char (*(x())[])()`
 - (b) Answer from Barfield, November 10, 2010: <http://programmers.stackexchange.com/a/18087> and <http://programmers.stackexchange.com/questions/17898/whats-a-nice-explanation-for-pointers/18087#18087>. “Pointer[s] are a bit like the application shortcuts on your desktop.”
 - (c) Answer from Gulshan, November 10, 2010: <http://programmers.stackexchange.com/a/17915> and <http://programmers.stackexchange.com/questions/17898/whats-a-nice-explanation-for-pointers/17915#17915>. Pointers point to instance and static variables. A pointer can point to different variables during the execution of the program, but must point to one variable at any instance (i.e., point in time) during execution. Also, the pointer must point to variables of the same type. Associate a pointer with a variable via the reference to the variable; e.g., `int *pointer; pointer = & variable;` ... According to *Ptolemy*, December 2,

2010: <http://programmers.stackexchange.com/a/23016>. `int *pointer = & variable;` creates a pointer to the variable. ... Dereference the pointer (add `*` as a prefix) to store the value of an expression (based on variables, strings, or constants). According to *Ptolemy*, `&variable` is the “address of the variable” and it “represents the literal value for” the pointer. “The pointer” refers to the data that the pointer points to, or something “pointed to by” the pointer.

- (d) Answer from Sridhar Iyer, November 11, 2010: <http://programmers.stackexchange.com/a/18529> and <http://programmers.stackexchange.com/questions/17898/whats-a-nice-explanation-for-18529#18529>. A “pointer is a variable that store[s] the address of another variable (or just any variable). `*` is used to get the value at the memory location that is stored in the pointer variable. `&` operator gives the address of a memory location.”
- (e) Answer from *rwong*, November 2, 2010: <http://programmers.stackexchange.com/a/18054> and <http://programmers.stackexchange.com/questions/17898/whats-a-nice-explanation-for-18054#18054>. Each pointer, which is a special type of variable, must point to only one variable. Variables that are not pointers must not point to anything; however, such variables can be pointed to by any number of pointers.
- (f) Answer from *back2dos*, November 10, 2010: <http://programmers.stackexchange.com/a/18092> and <http://programmers.stackexchange.com/questions/17898/whats-a-nice-explanation-for-18092#18092>. The pointer [variable] interprets the value of the pointer [variable] as the address of another variable that it points to. Hence, the value of the pointer [variable] refers to a specific location in memory (specified by the address), and is called the reference. Dereferencing is the process of accessing the value of the memory location that it points/refers to. That is, `*v` dereferences the value of `v`, and provides the value at the memory location referred to by the address in `v`. `&v` provides a reference (or the address of the memory location for `v`) to the variable `v`.
- (g) Answer from *Ptolemy*, December 2, 2010: <http://programmers.stackexchange.com/a/23016> and <http://programmers.stackexchange.com/questions/17898/whats-a-nice-explanation-for-23016#23016>. At a low level, the concept of memory can be viewed as a massive array. “Any position in the array” can be accessed “by its index location.” “Passing the index location rather than copying the entire memory” is more efficient in terms of performance and memory usage. Hence, “pointers are useful.” “For [a] method to store the index location [of] where all the data [in the array] is stored,” “a memory index location” can be passed in as a parameter. Pointers can be chained indefinitely; “keep track of how many times [I] need to look at the addresses to find the actual data object.” While pointers to heap memory are safe, “pointers to stack memory are dangerous when passed outside the method.”
- (h) Also, see <http://www.udel.edu/CIS/105/pconrad/03F/2003.fall.doc> by “P. Conrad.”

3. [19, pp. 15, second last paragraph]

- (a) “The value of a pointer is the address to which it points”; or, the “the value of a pointer is the address.”

4. [11]

- (a) “pointers use the `*` and `->` operators, references use `.`”
- (b) “Both pointers and references let you refer to other objects indirectly.”
- (c) “there is no such thing as a null reference”
- (d) “A reference must always refer to some object.”
- (e) **“As a result, if you have a variable whose purpose is to refer to another object, but it is possible that there might not be an object to refer to, you should make the variable a pointer, because then you can set it to null.”**

- (f) “On the other hand, if the variable must always refer to an object, i.e., if your design does not allow for the possibility that the variable is null, you should probably make the variable a reference.”
- (g) “Because a reference must refer to an object, C++ requires that references be initialized.” ... Pointers do not have to be initialized; i.e., pointers can be uninitialized. However, “uninitialized pointers” are “valid but risky.”
- (h) Since null references do not exist, references can be used more efficiently than pointers. This is because the validity of a reference does not have to be tested prior to usage.
- (i) Before using pointers, they should be tested against null (i.e., check the validity of a reference prior to usage).
- (j) “Pointers may be reassigned to refer to different objects.” “A reference ... always refer to the object with which it is initialized.”
- (k) “You should use a pointer whenever you need to take into account the possibility that there’s nothing to refer to (in which case you can set the pointer to null) or whenever you need to be able to refer to different things at different times (in which case you can change where the pointer points).”
- (l) “You should use a reference whenever you know there will always be an object to refer to and you also know that once you’re referring to that object, you’ll never want to refer to anything else.”
- (m) “There is one other situation in which you should use a reference, and that’s when you’re implementing certain operators. The most common example is operator[]. This operator typically needs to return something that can be used as the target of an assignment.”
- (n) “References, then, are the feature of choice when you know you have something to refer to, when you’ll never want to refer to anything else, and when implementing operators whose syntactic requirements make the use of pointers undesirable. In all other cases, stick with pointers.”

5. Prakash Rajendran, Rob φ , Sudhanshu Aggarwal, lpapp, Alf, Deduplicator, Sam, and Siddhant Saraf, “What are the differences between a pointer variable and a reference variable in C++?,” Stack Exchange Inc., New York, NY, March 2, 2015. Available online from *Stack Exchange Inc.: Stack Overflow: Questions* at: <http://stackoverflow.com/questions/57483/what-are-the-differences-between-a-pointer-variable-and-a-reference-variable-in-c> October 8, 2015 was the last accessed date.

6. (a)
 7. (a)
 8. (a)
 9. (a)
 10. (a)
 11. (a)
 12. (a)
 13. (a)
 14. (a)
 15. (a)
 16. (a)

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