White Paper on Obstacle Detection via a Stereoscopic Camera System, Using Deep Learning

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1 Section 1

There are a significant amount of references for helping people to learn L^AT_EX [1–29] and related information/technologies.

2 Alternate Plan

lat=20&lng=0&z=1.5

Data sets to use in lieu of poor, failed, and/or untimely data acquisition, and preprocessing of data set:

- 1. Manuela Chessa's GENUA PESTO GENoa hUman Active fixation database: PEripersonal space STereoscopic images and grOund truth disparity: https://www.manuelachessa.it/sample-page/benchmarking-datasets-2/
- 2. The KITTI Vision Benchmark Suite: http://www.cvlibs.net/datasets/kitti/eval_object.php
- php
 3. Mapillary Vistas Dataset: https://www.mapillary.com/dataset/vistas?pKey=cc5dEAyQECBFF9MN3Mbd
- 4. ApolloScape: http://apolloscape.auto/
- $5. \ \, BDD100K \ self-driving \ dataset: url https://www.therobotreport.com/uc-berkeley-opens-self-driving-dataset-bdd100k/$
- 6. Cityscapes Dataset: https://www.cityscapes-dataset.com/

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