

FIGURE 7.1. Behavior of test sample and training sample error as the model complexity is varied. The light blue curves show the training error $\overline{\text{err}}$, while the light red curves show the conditional test error $\text{Err}_{\mathcal{T}}$ for 100 training sets of size 50 each, as the model complexity is increased. The solid curves show the expected test error Err and the expected training error $\text{E}[\overline{\text{err}}]$.

Test error, also referred to as generalization error, is the prediction error over an independent test sample

$$Err_{\mathcal{T}} = E[L(Y, \hat{f}(X))|\mathcal{T}]$$
(7.2)

where both X and Y are drawn randomly from their joint distribution (population). Here the training set \mathcal{T} is fixed, and test error refers to the error for this specific training set. A related quantity is the expected prediction error (or expected test error)

$$\operatorname{Err} = \operatorname{E}[L(Y, \hat{f}(X))] = \operatorname{E}[\operatorname{Err}_{\mathcal{T}}]. \tag{7.3}$$

Note that this expectation averages over everything that is random, including the randomness in the training set that produced \hat{f} .

Figure 7.1 shows the prediction error (light red curves) $Err_{\mathcal{T}}$ for 100 simulated training sets each of size 50. The lasso (Section 3.4.2) was used to produce the sequence of fits. The solid red curve is the average, and hence an estimate of Err.

Estimation of $Err_{\mathcal{T}}$ will be our goal, although we will see that Err is more amenable to statistical analysis, and most methods effectively estimate the expected error. It does not seem possible to estimate conditional