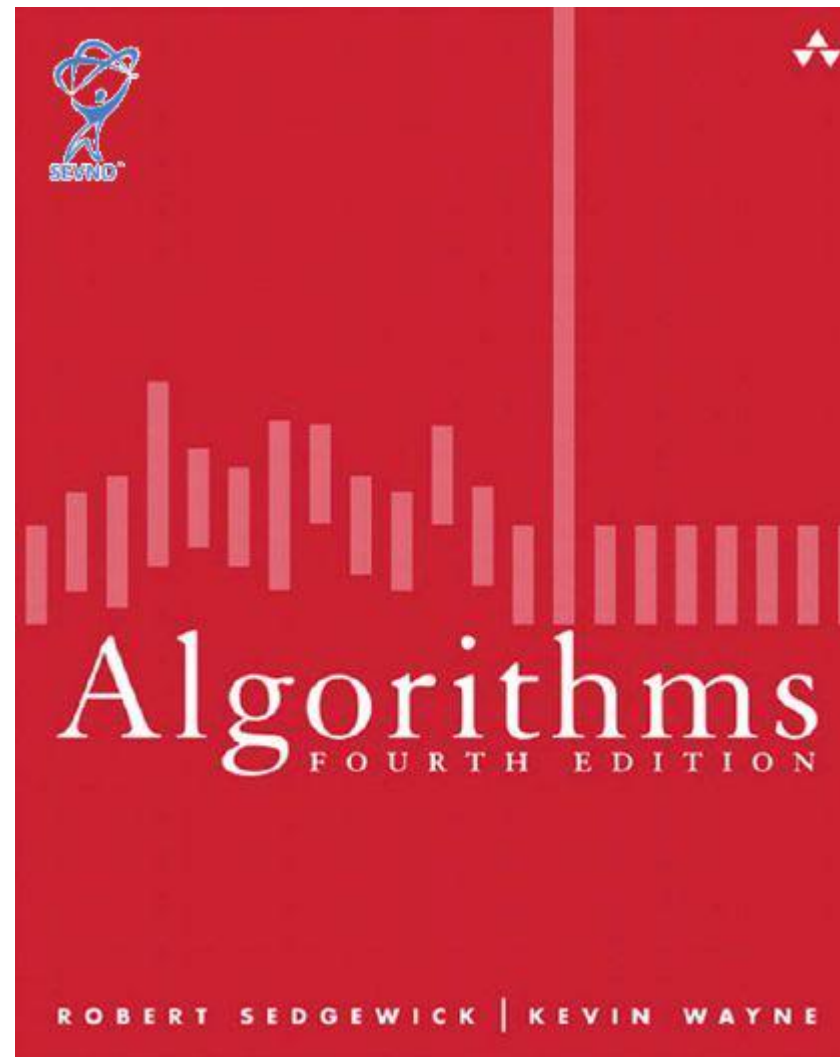


Introduction to Algorithms
*adapted from Kevin Wayne's slides @
Princeton Univ.*

Book

- Slide content mostly extracted from :

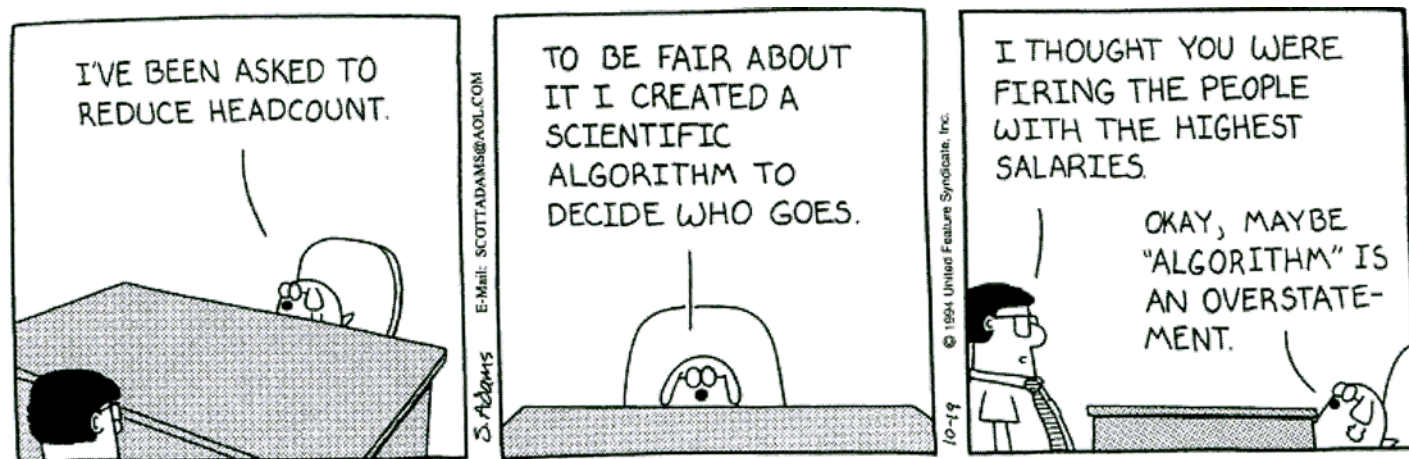


Agenda

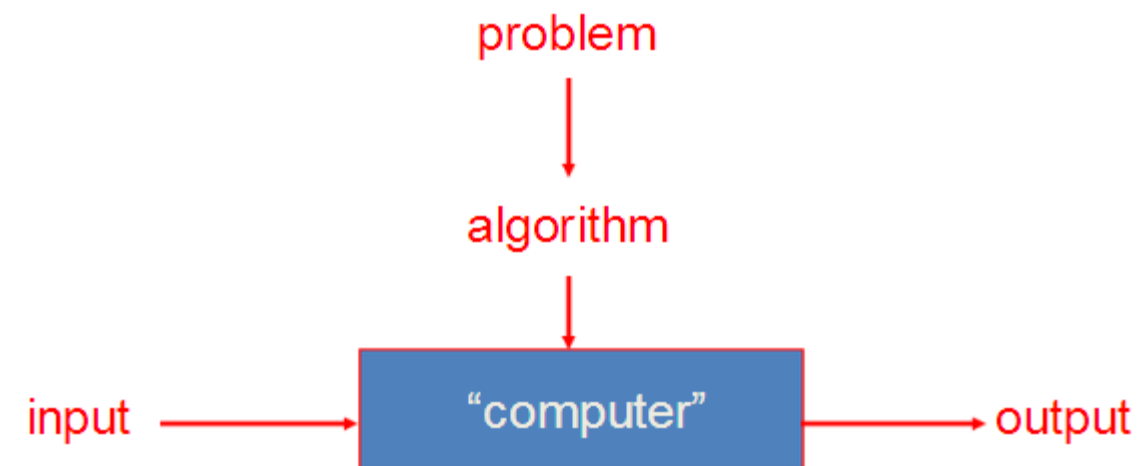
- Introduction to Algorithms
- Algorithm case study.
 - Model the problem.
 - Find an algorithm to solve it.
 - Fast enough? Fits in memory?
 - If not, figure out why.
 - Find a way to address the problem.
 - Iterate until satisfied.
- The scientific method.
- Mathematical analysis.

What's an Algorithm

- An algorithm is a sequence of **unambiguous instructions** for **solving a problem**, i.e., for obtaining a required output for any **legitimate input** in a **finite amount of time**.

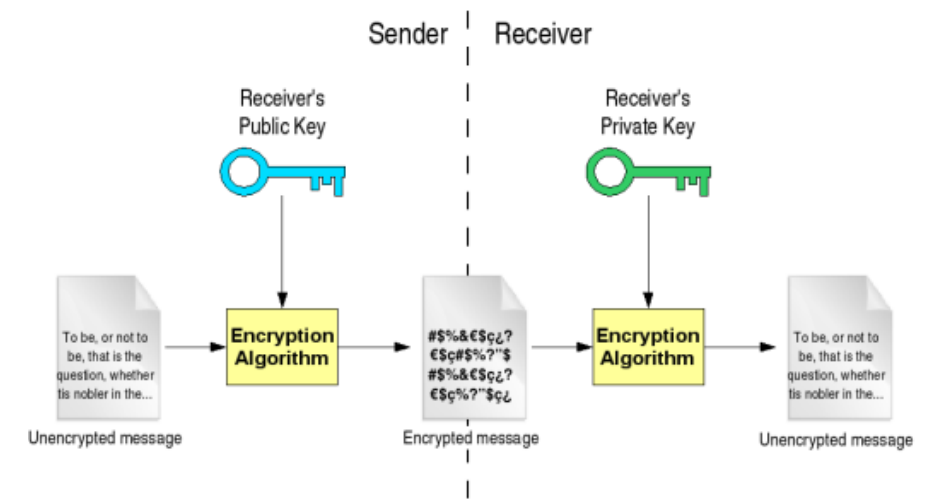
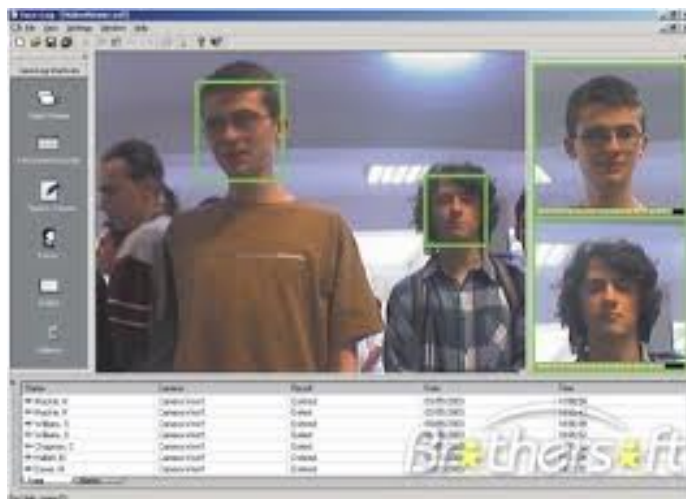


Dilbert by Scott Adams From the ClariNet electronic newspaper Redistribution prohibited info@clarinet.com



Why Algorithms

- Algorithms are everywhere...
 - Web Searching, packet routing, peer-to-peer/file sharing
 - Human genome project
 - Circuit layout on silicon
 - Multimedia Image and signal processing(e.g. MP3, divx...
 - Security and Encryption.
 - Biometrics(fingerprint scanning/face recognition)
 - ...



Why Algorithms

- *“For me, great algorithms are the poetry of computation. Just like verse, they can be terse, allusive, dense, and even mysterious. But once unlocked, they cast a brilliant new light on some aspect of computing.” — Francis Sullivan*
- [http://en.wikipedia.org/wiki/John G.F. Francis](http://en.wikipedia.org/wiki/John_G.F._Francis)
- You can have good “poems” and then you have better “poems”...

Why Algorithms

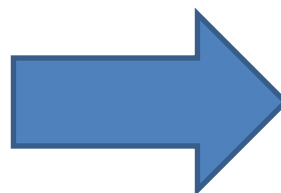
- “Algorithms: a common language for nature, human, and computer.” — Avi Wigderson

Mathematical Models

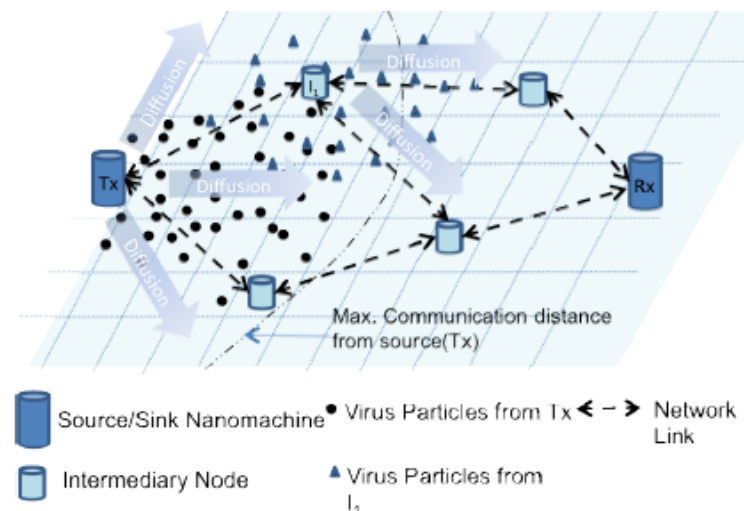
Fick's Law (Diffusion Equation) and solution

$$\frac{\delta V}{\delta t} = D \frac{\delta^2 V}{\delta r^2} - k_d V$$

$$c_{ij}(\tau_\eta) = \frac{Q}{4\pi D\tau} \exp\left(\frac{-r_{ij}^2}{4D\tau} - k_d\tau\right)$$



Computational Models (& Algorithms)



```
function [ out ] = instantPoint2D( r,t,Q,D )
%Calculates Concentration of particles at
%distance r at time t from release of instantaneous conc. Q at t=0
kd=3.34e-5;
a=Q/(4*pi*D*t);
b=exp((-r^2)/(4*D*t)-(kd*t));
out=a*b;
end
```

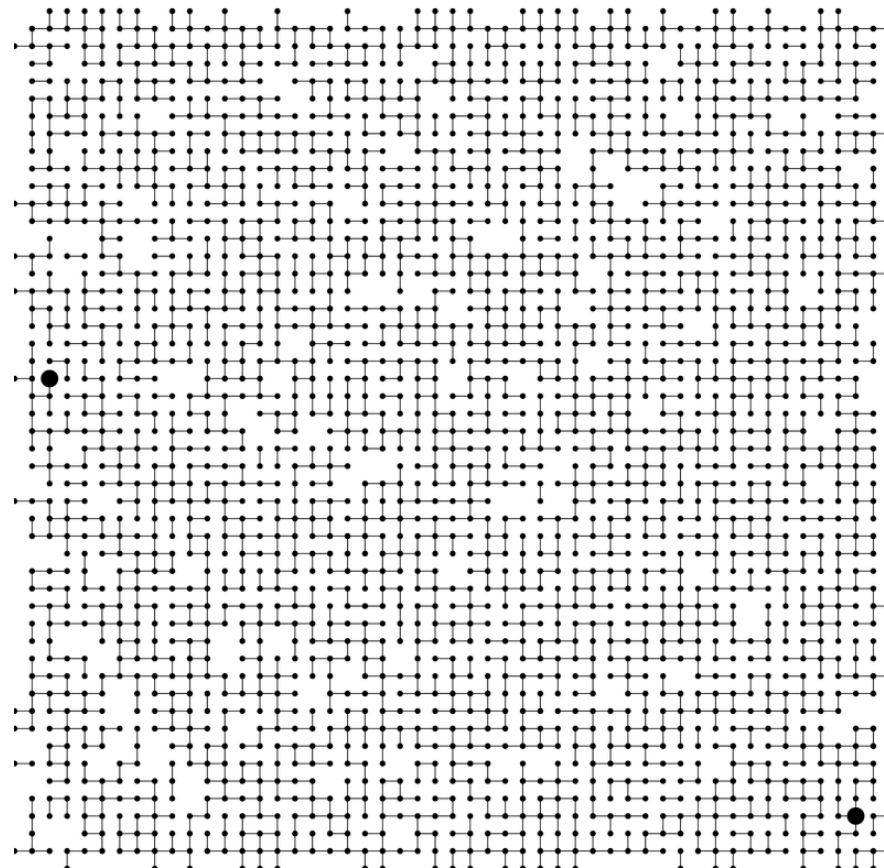

Historical Perspective

- Euclid's algorithm for finding the greatest common divisor dates back to 300bc (they've been around for a long time...)
- http://en.wikipedia.org/wiki/Greatest_common_divisor
- The name "Algorithm" is derived from Muhammad ibn Musa al-Khwarizmi – 9th century mathematician
- www.lib.virginia.edu/science/parshall/khwariz.html



Example Problems

- Network connectivity – “Can you get from a to b”



- Sort Class Results for Algorithms in ascending order:
 - *Input:* A sequence of n numbers $\langle a_1, a_2, \dots, a_n \rangle$
 - *Output:* A reordering of the input sequence $\langle a'_1, a'_2, \dots, a'_n \rangle$ so that $a'_i \leq a'_j$ whenever $i < j$
 - *Algorithms:* Selection Sort, Insertion Sort, Merge Sort...

Dynamic connectivity

- Given a set of objects
 - Union: connect two objects.
 - Connected: is there a path connecting the two objects?

more difficult problem: find the path

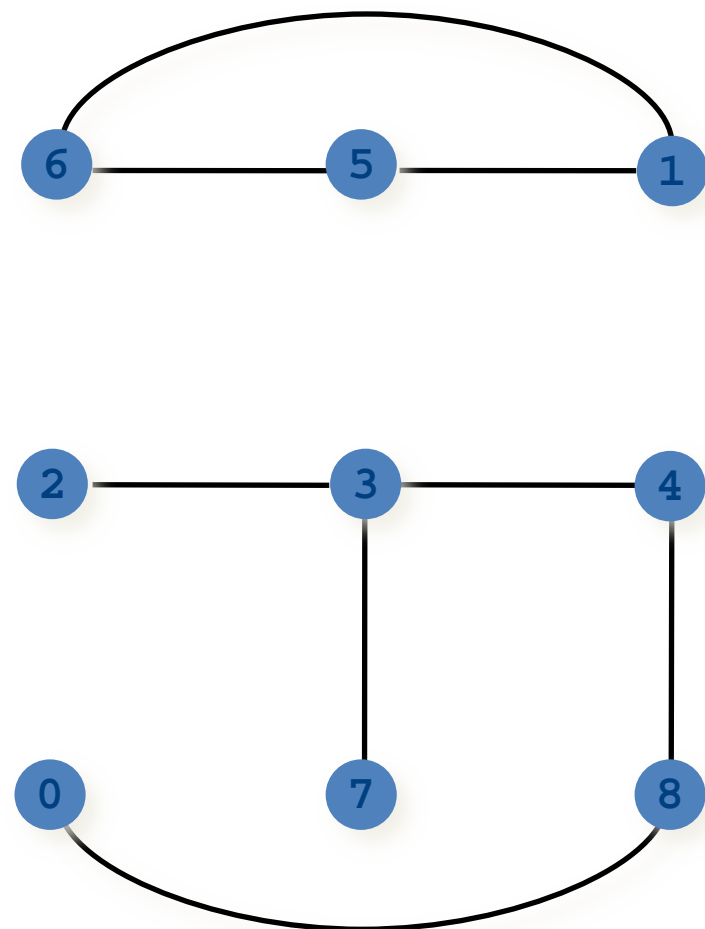
```
union(3, 4)
union(8, 0)
union(2, 3)
union(5, 6)
connected(0, 2)
connected(2, 4)
union(5, 1)
union(7, 3)
union(1, 6)
union(4, 8)
connected(0, 2)
connected(2, 4)
```

no

yes

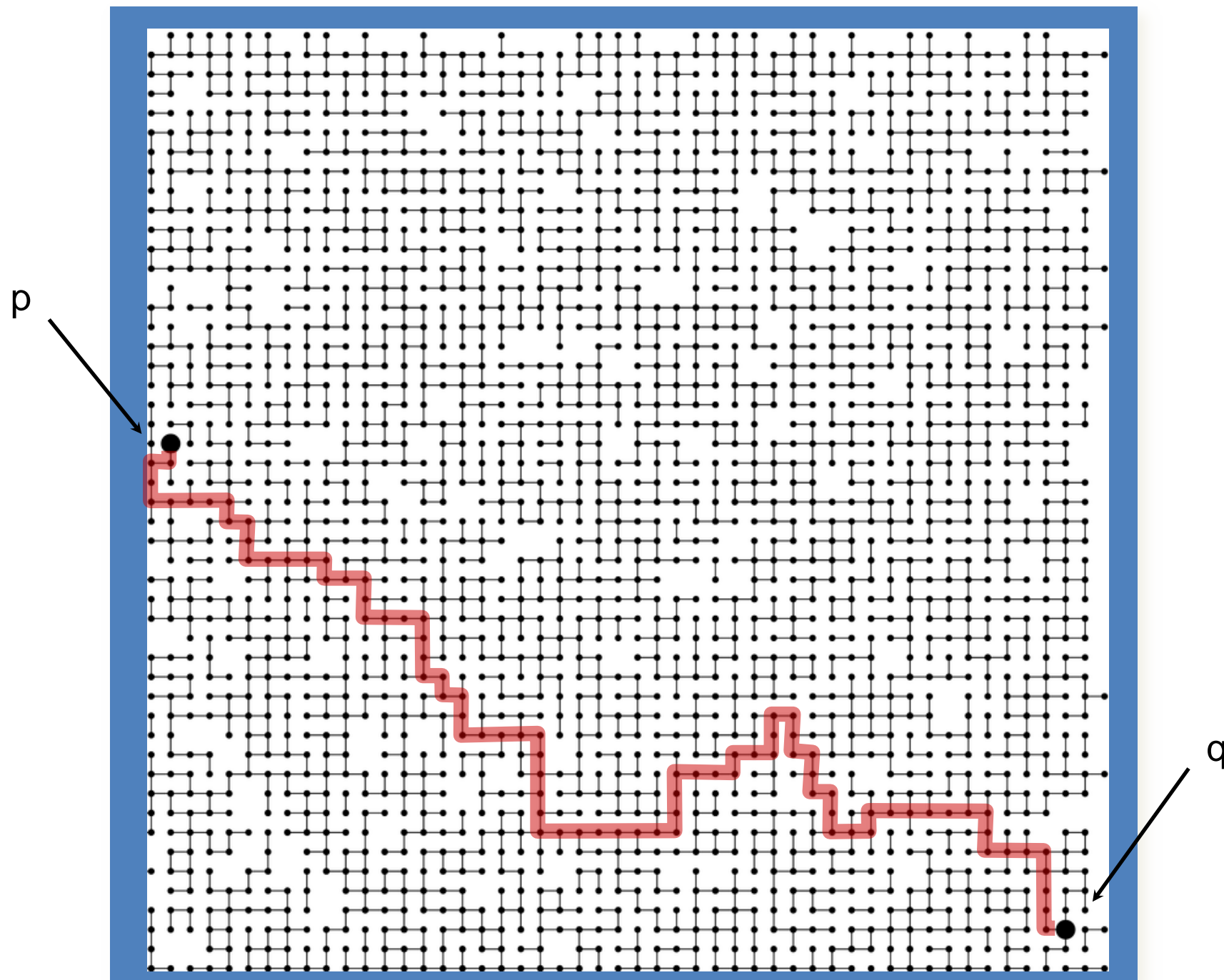
yes

yes



Connectivity example

Q. Is there a path from p to q ?



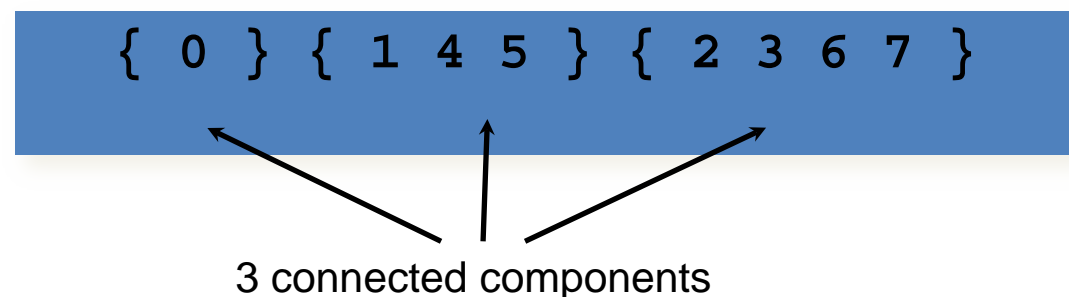
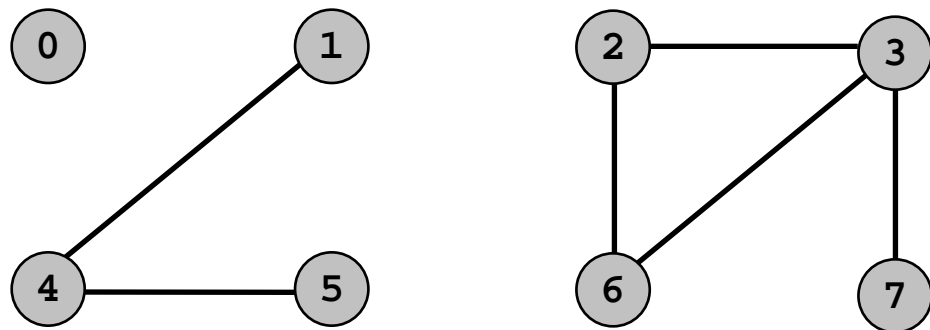
A. Yes.

Modeling the objects

- Dynamic connectivity applications involve manipulating objects of all types.
 - Pixels in a digital photo.
 - Computers in a network.
 - Friends in a social network.
 - Transistors in a computer chip.
 - Elements in a mathematical set.
 - Metallic sites in a composite system.
- When programming, convenient to name sites 0 to $N-1$.
 - Use integers as array index.
 - Suppress details not relevant to union-find.

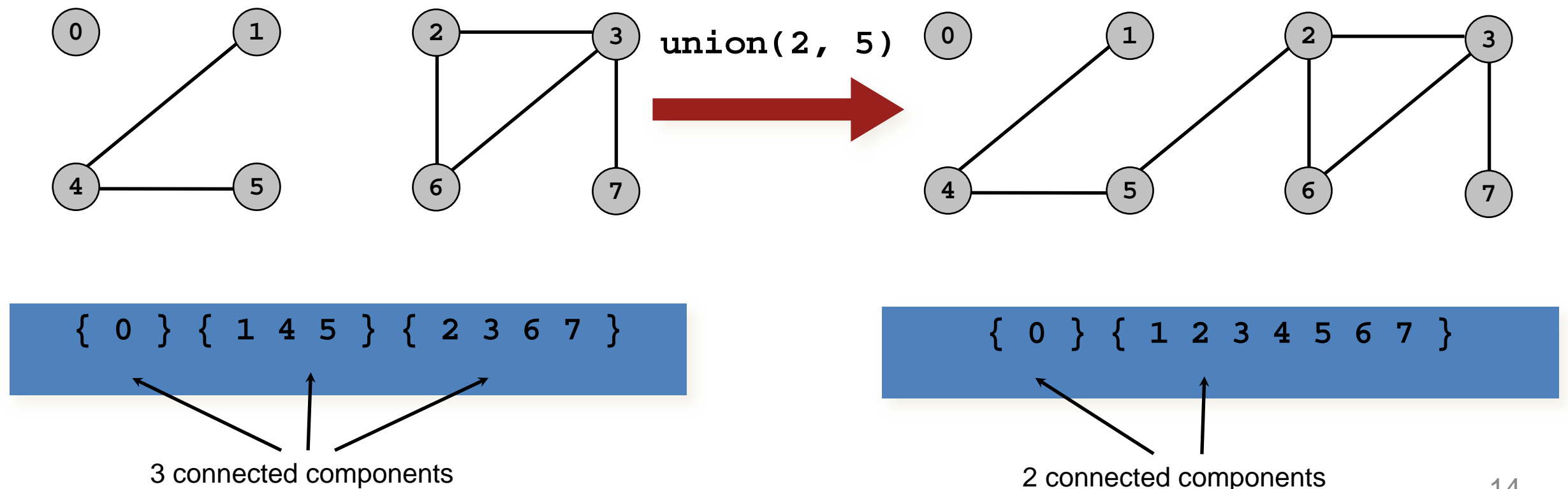
Modeling the connections

- We assume "is connected to" is an equivalence relation:
 - Reflexive: p is connected to p .
 - Symmetric: if p is connected to q , then q is connected to p .
 - Transitive: if p is connected to q and q is connected to r , then p is connected to r .
- Connected components. Maximal set of objects that are mutually connected.



Implementing the operations

- Connected query. Check if two objects are in the same component.
- Union command. Replace components containing two objects with their union.



Union-find data type (API)

- Goal. Design efficient data structure for union-find.
 - Number of objects N can be huge.
 - Number of operations M can be huge.
 - Find queries and union commands may be intermixed.

public class UF		
	UF(int N)	initialize union-find data structure with N objects (0 to N-1)
void	union(int p, int q)	add connection between p and q
boolean	connected(int p, int q)	are p and q in the same component?
int	find(int p)	component identifier for p (0 to N-1)
int	count()	number of components

Dynamic-connectivity client

- Read in number of objects N from standard input.
- Repeat:
 - read in pair of integers from standard input
 - write out pair if they are not already connected

```
public static void main(String[] args)
{
    int N = StdIn.readInt();
    UF uf = new UF(N);
    while (!StdIn.isEmpty())
    {
        int p = StdIn.readInt();
        int q = StdIn.readInt();
        if (uf.connected(p, q)) continue;
        uf.union(p, q);
        StdOut.println(p + " " + q);
    }
}
```

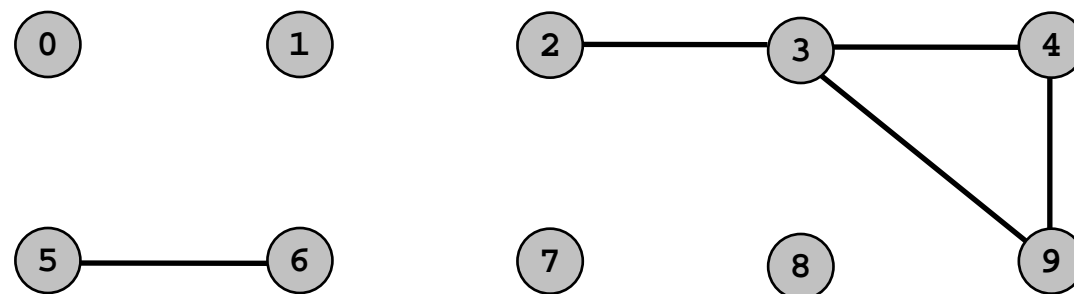
```
% more tiny.txt
10
4 3
3 8
6 5
9 4
2 1
8 9
5 0
7 2
6 1
1 0
6 7
```

Quick-find [eager approach]

- Data structure.

- Integer array `id[]` of size `N`.
- Interpretation: p and q in same component iff they have the same id.

<code>i</code>	0	1	2	3	4	5	6	7	8	9
<code>id[i]</code>	0	1	9	9	9	6	6	7	8	9



5 and 6 are connected
2, 3, 4, and 9 are connected

Quick-find [eager approach]

- Data structure.
 - Integer array $id[]$ of size N .
 - Interpretation: p and q in same component iff they have the same id.

i	0	1	2	3	4	5	6	7	8	9
$id[i]$	0	1	9	9	9	6	6	7	8	9

5 and 6 are connected

2, 3, 4, and 9 are connected

$id[3] = 9; id[6] = 6$

3 and 6 in different components

- Find. Check if p and q have the same id.

Quick-find [eager approach]

- Data structure.

- Integer array $id[]$ of size N .
- Interpretation: p and q in same component iff they have the same id.

i	0	1	2	3	4	5	6	7	8	9
$id[i]$	0	1	9	9	9	6	6	7	8	9

5 and 6 are connected
2, 3, 4, and 9 are connected

- Find. Check if p and q have the same id.

$id[3] = 9; id[6] = 6$
3 and 6 in different components

i	0	1	2	3	4	5	6	7	8	9
$id[i]$	0	1	6	6	6	6	6	7	8	6

problem: many values can change

union of 3 and 6
2, 3, 4, 5, 6, and 9 are connected

- Union. To merge sets containing p and q , change all entries with $id[p]$ to $id[q]$.

Quick-find example

		id[]									
p	q	0	1	2	3	4	5	6	7	8	9
4	3	0	1	2	3	4	5	6	7	8	9
		0	1	2	3	3	5	6	7	8	9
3	8	0	1	2	3	3	5	6	7	8	9
		0	1	2	8	8	5	6	7	8	9
6	5	0	1	2	8	8	5	6	7	8	9
		0	1	2	8	8	5	5	7	8	9
9	4	0	1	2	8	8	5	5	7	8	9
		0	1	2	8	8	5	5	7	8	8
2	1	0	1	2	8	8	5	5	7	8	8
		0	1	1	8	8	5	5	7	8	8
8	9	0	1	1	8	8	5	5	7	8	8
5	0	0	1	1	8	8	5	5	7	8	8
		0	1	1	8	8	0	0	7	8	8
7	2	0	1	1	8	8	0	0	7	8	8
		0	1	1	8	8	0	0	1	8	8
6	1	0	1	1	8	8	0	0	1	8	8
		1	1	1	8	8	1	1	1	8	8
1	0	1	1	1	8	8	1	1	1	8	8
6	7	1	1	1	8	8	1	1	1	8	8

id[p] and id[q] differ, so
union() changes entries equal
to id[p] to id[q] (in red)

id[p] and id[q]
match, so no change

Quick-find: Java implementation

```
public class QuickFindUF
{
    private int[] id;

    public QuickFindUF(int N)
    {
        id = new int[N];
        for (int i = 0; i < N; i++)
            id[i] = i;
    }

    public boolean connected(int p, int q)
    { return id[p] == id[q]; }

    public void union(int p, int q)
    {
        int pid = id[p];
        int qid = id[q];
        for (int i = 0; i < id.length; i++)
            if (id[i] == pid) id[i] = qid;
    }
}
```

← set id of each object to itself
(N array accesses)

← check whether **p** and **q**
are in the same component
(2 array accesses)

← change all entries with **id[p]** to **id[q]**
(linear number of array accesses)

Quick-find is too slow

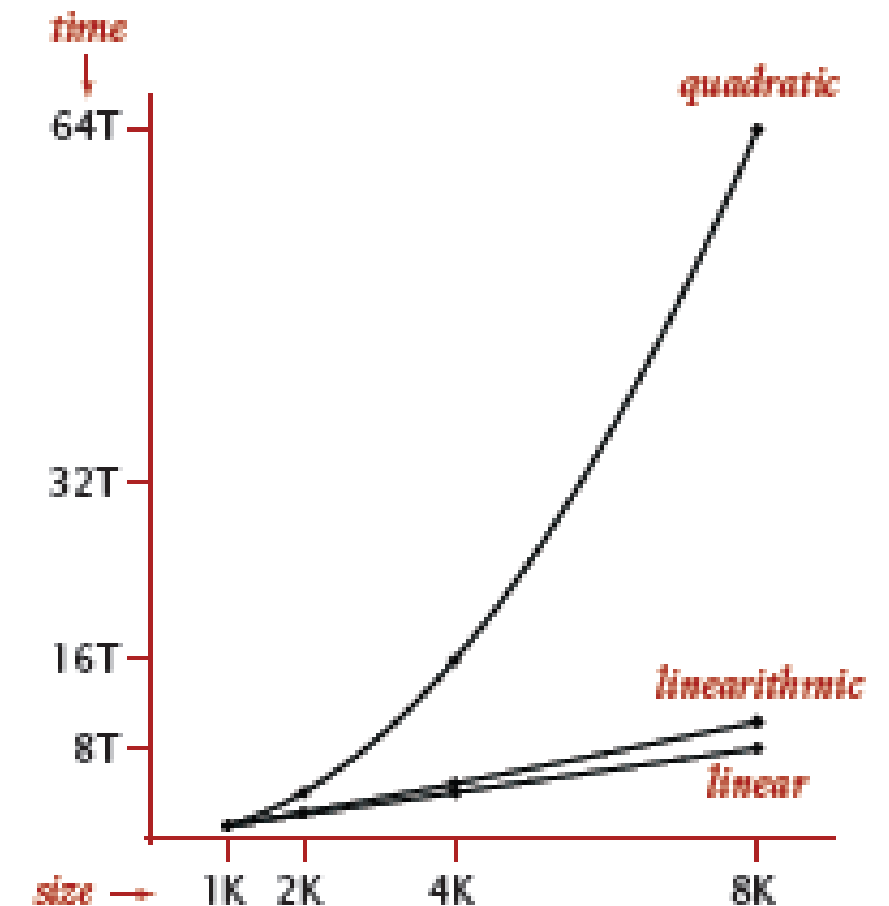
- Cost model. Number of array accesses (for read or write).

algorithm	init	union	find
quick-find	N	N	1

- Quick-find defect.
 - Union too expensive.
 - Trees are flat, but too expensive to keep them flat.
 - Ex. Takes N^2 array accesses to process sequence of N union commands on N objects.

Quadratic Algorithms

- Currently, a computer can do:
 - 10^9 operations per second.
 - 10^9 “words” in main memory.
- Therefore can “touch” every memory location in 1 second!
- For Quick-Find
 - 10^9 union commands on 10^9 objects = 10^{18} operations. Prize for whoever can tell me how long this will take...

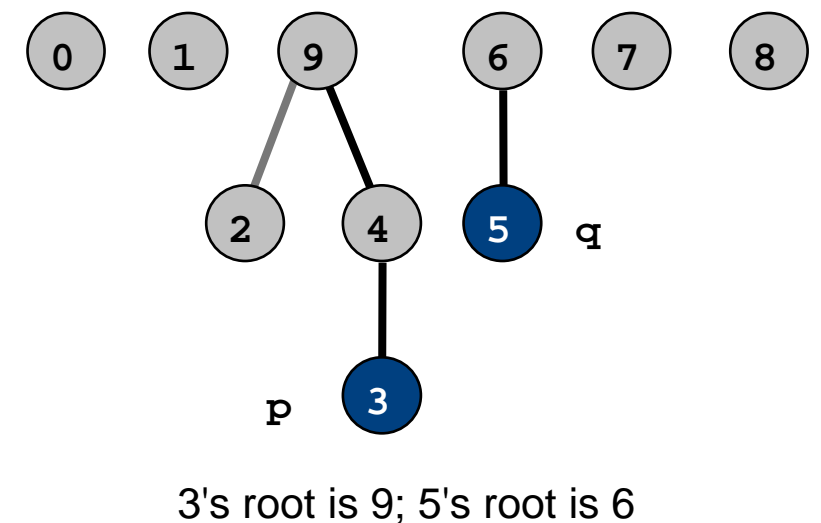


Quick-union [lazy approach]

- Data structure.

- Integer array $id[]$ of size N .
- Interpretation: $id[i]$ is parent of i .
- Root of i is $id[id[id[...id[i]...]]]$. keep going until it doesn't change

i	0	1	2	3	4	5	6	7	8	9
$id[i]$	0	1	9	4	9	6	6	7	8	9

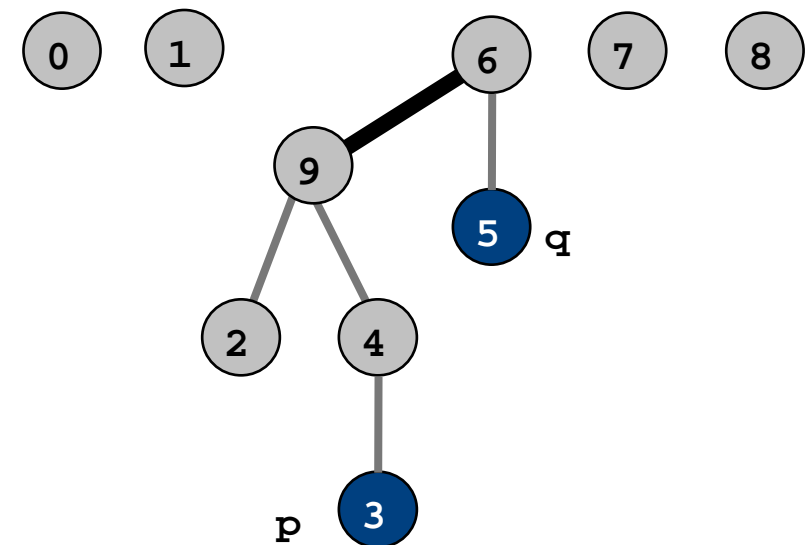


Quick-union [lazy approach]

- Find. Check if p and q have the same root.
- Union. To merge sets containing p and q , set the id of p 's root to the id of q 's root.

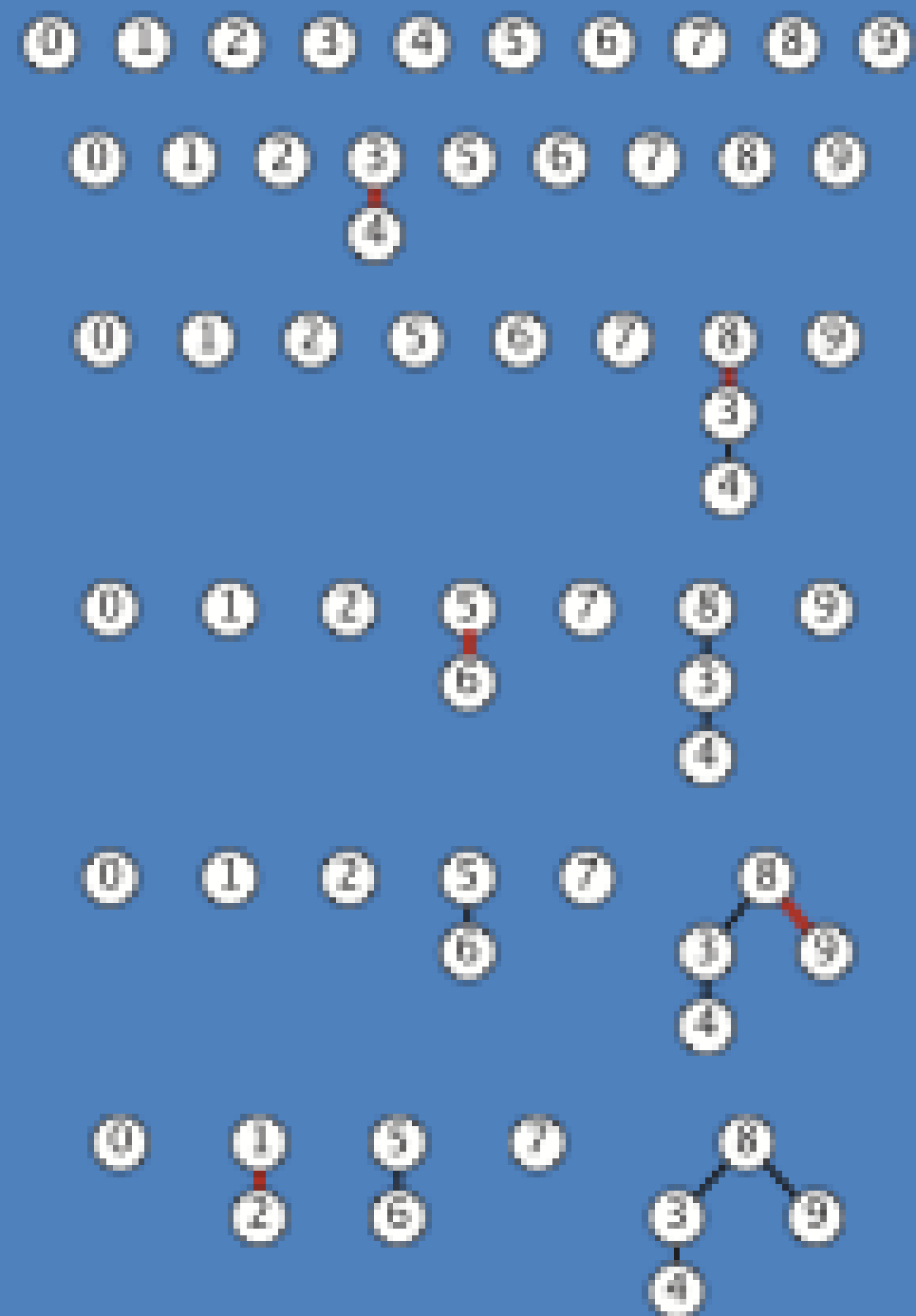
i	0	1	2	3	4	5	6	7	8	9
id[i]	0	1	9	4	9	6	6	7	8	6

only one value changes



Quick-union example

		id[]										
p	q	0	1	2	3	4	5	6	7	8	9	
4	3	0	1	2	3	4	5	6	7	8	9	
		0	1	2	3	3	5	6	7	8	9	
3	8	0	1	2	3	3	5	6	7	8	9	
		0	1	2	8	3	5	6	7	8	9	
6	5	0	1	2	8	3	5	6	7	8	9	
		0	1	2	8	3	5	5	7	8	9	
9	4	0	1	2	8	3	5	5	7	8	9	
		0	1	2	8	3	5	5	7	8	8	
2	1	0	1	2	8	3	5	5	7	8	8	
		0	1	1	8	3	5	5	7	8	8	



id[]

p	q	0	1	2	3	4	5	6	7	8	9
---	---	---	---	---	---	---	---	---	---	---	---

8	9	0	1	1	8	3	5	5	7	8	8
---	---	---	---	---	---	---	---	---	---	---	---

5	0	0	1	1	8	3	5	5	7	8	8
---	---	---	---	---	---	---	---	---	---	---	---

		0	1	1	8	3	0	5	7	8	8
--	--	---	---	---	---	---	---	---	---	---	---

7	2	0	1	1	8	3	0	5	7	8	8
---	---	---	---	---	---	---	---	---	---	---	---

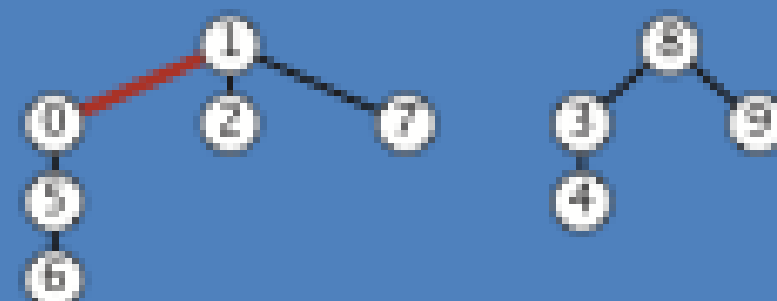
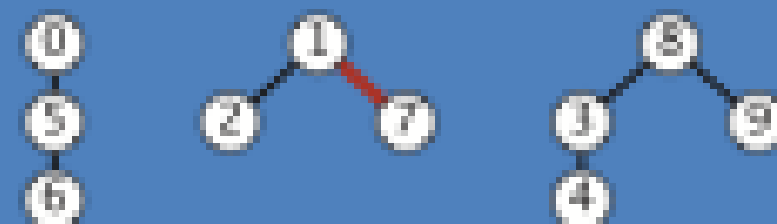
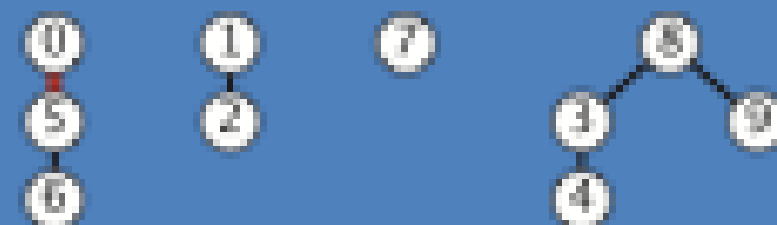
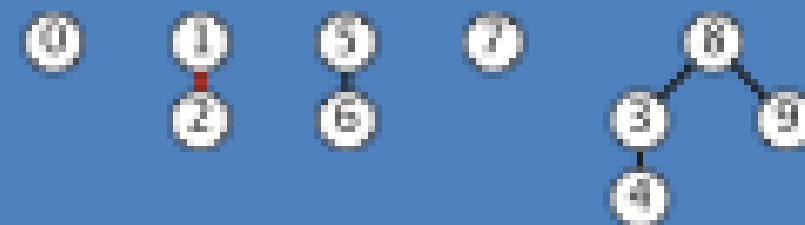
		0	1	1	8	3	0	5	1	8	8
--	--	---	---	---	---	---	---	---	---	---	---

6	1	0	1	1	8	3	0	5	1	8	8
---	---	---	---	---	---	---	---	---	---	---	---

		1	1	1	8	3	0	5	1	8	8
--	--	---	---	---	---	---	---	---	---	---	---

1	0	1	1	1	8	3	0	5	1	8	8
---	---	---	---	---	---	---	---	---	---	---	---

6	7	1	1	1	8	3	0	5	1	8	8
---	---	---	---	---	---	---	---	---	---	---	---



Quick-union: Java implementation

```
public class QuickUnionUF{
private int[] id;

public QuickUnionUF(int N)    {
    id = new int[N];
    for (int i = 0; i < N; i++) id[i] = i;
}

private int root(int i)    {
    while (i != id[i]) i = id[i];
    return i;
}

public boolean connected(int p, int q)    {
return root(p) == root(q);
}

public void union(int p, int q)    {
    int i = root(p), j = root(q);
    id[i] = j;    }
}
```

← set id of each object to itself
(N array accesses)

← chase parent pointers until reach root
(depth of i array accesses)

← check if p and q have same root
(depth of p and q array accesses)

← change root of p to point to root of q
(depth of p and q array accesses)

Quick-union is also too slow

- Cost model. Number of array accesses (for read or write).

algorithm	init	union	find
quick-find	N	N	1
quick-union	N	N^\dagger	N

\dagger includes cost of finding root

← worst case

- Quick-find defect.

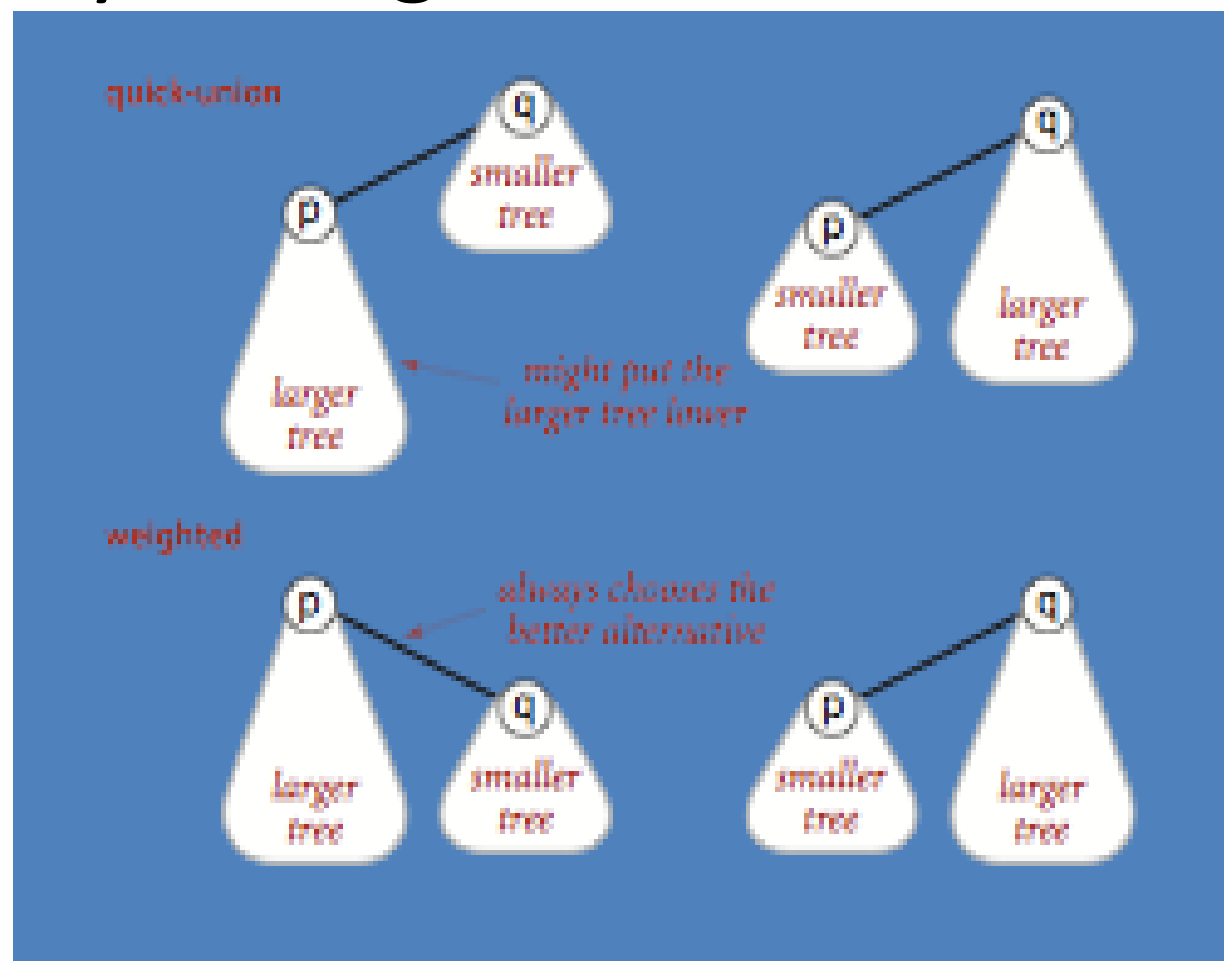
- Union too expensive (N array accesses).
- Trees are flat, but too expensive to keep them flat.

- Quick-union defect.

- Trees can get tall.
- Find too expensive (could be N array accesses).

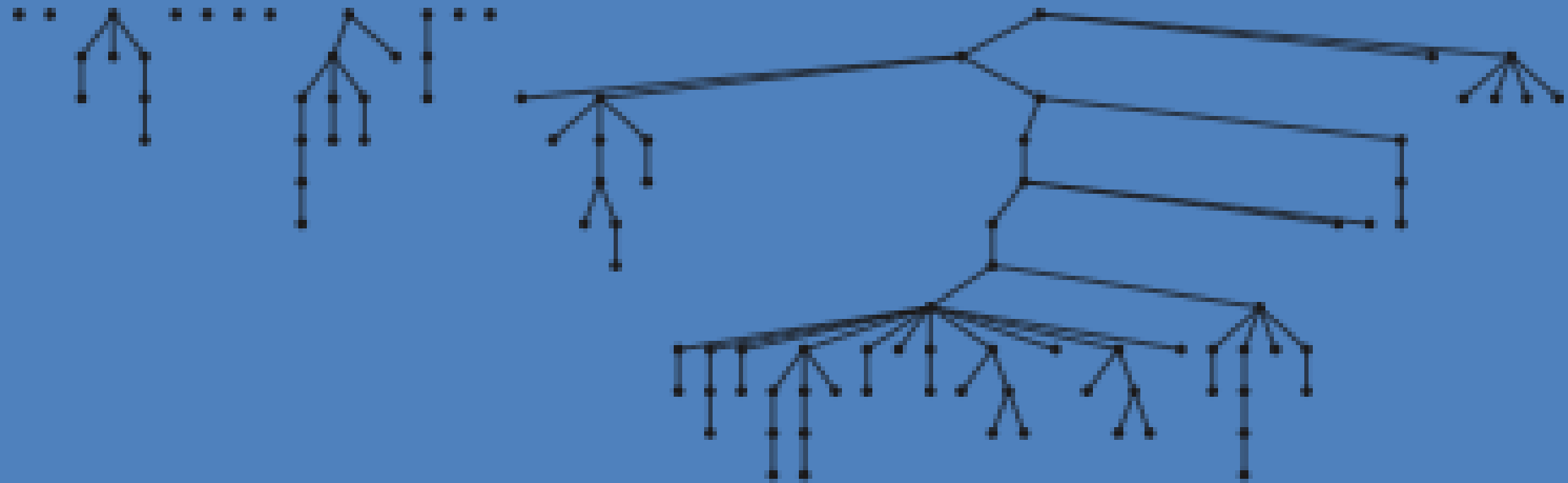
Improvement 1: weighting

- Weighted quick-union.
 - Modify quick-union to avoid tall trees.
 - Keep track of size of each tree (number of objects).
 - Balance by linking small tree below large one.



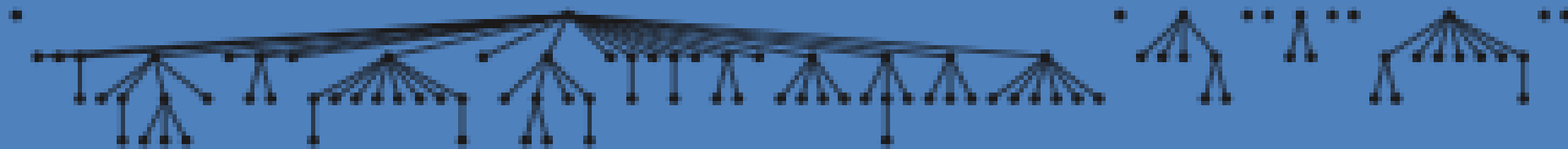
Quick-union and weighted quick-union example

quick-union



average distance to root 3.11

weighted



average distance to root 1.52

Quick-union and weighted quick-union (100 sites, 88 union() operations)

Weighted quick-union: Java implementation

- Data structure. Same as quick-union, but maintain extra array `sz[i]` to count number of objects in the tree rooted at `i`.

- Find. Identical to quick-union.

```
return root(p) == root(q);
```

- Union. Modify quick-union to:
 - Merge smaller tree into larger tree.
 - Update the `sz[]` array.

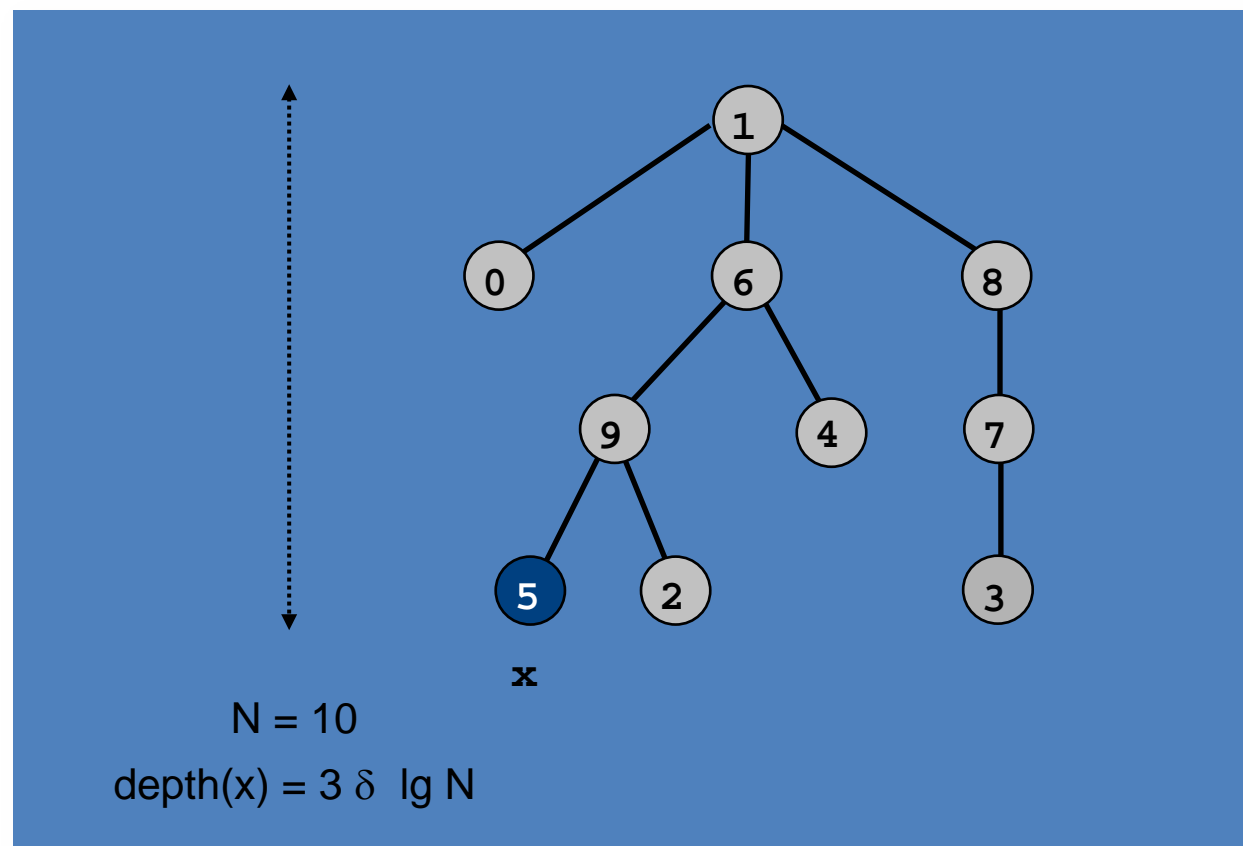
```
int i = root(p);
int j = root(q);
if (sz[i] < sz[j]) { id[i] = j; sz[j] += sz[i]; }
else                { id[j] = i; sz[i] += sz[j]; }
```

Weighted quick-union analysis

- Running time.

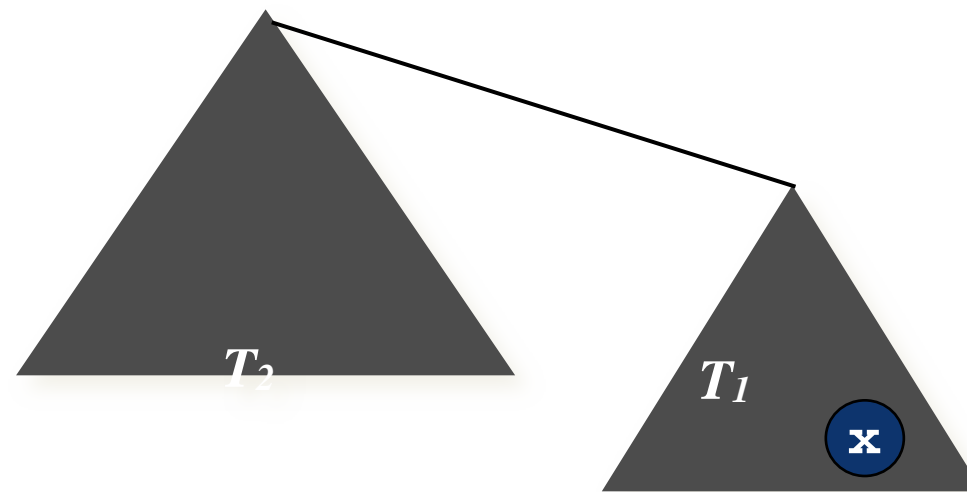
- Find: takes time proportional to depth of p and q .
- Union: takes constant time, given roots.

- Proposition. Depth of any node x is at most $\lg N$.



Weighted quick-union analysis

- Running time.
 - Find: takes time proportional to depth of p and q .
 - Union: takes constant time, given roots.
- Proposition. Depth of any node x is at most $\lg N$.
- Pf. When does depth of x increase?
- Increases by 1 when tree T_1 containing x is merged into another tree T_2 .
 - The size of the tree containing x at least doubles since $|T_2| > |T_1|$.
 - Size of tree containing x can double at most $\lg N$ times. Why?



Weighted quick-union analysis

- Running time.

- Find: takes time proportional to depth of p and q .
- Union: takes constant time, given roots.


- Proposition. Depth of any node x is at most $\lg N$.

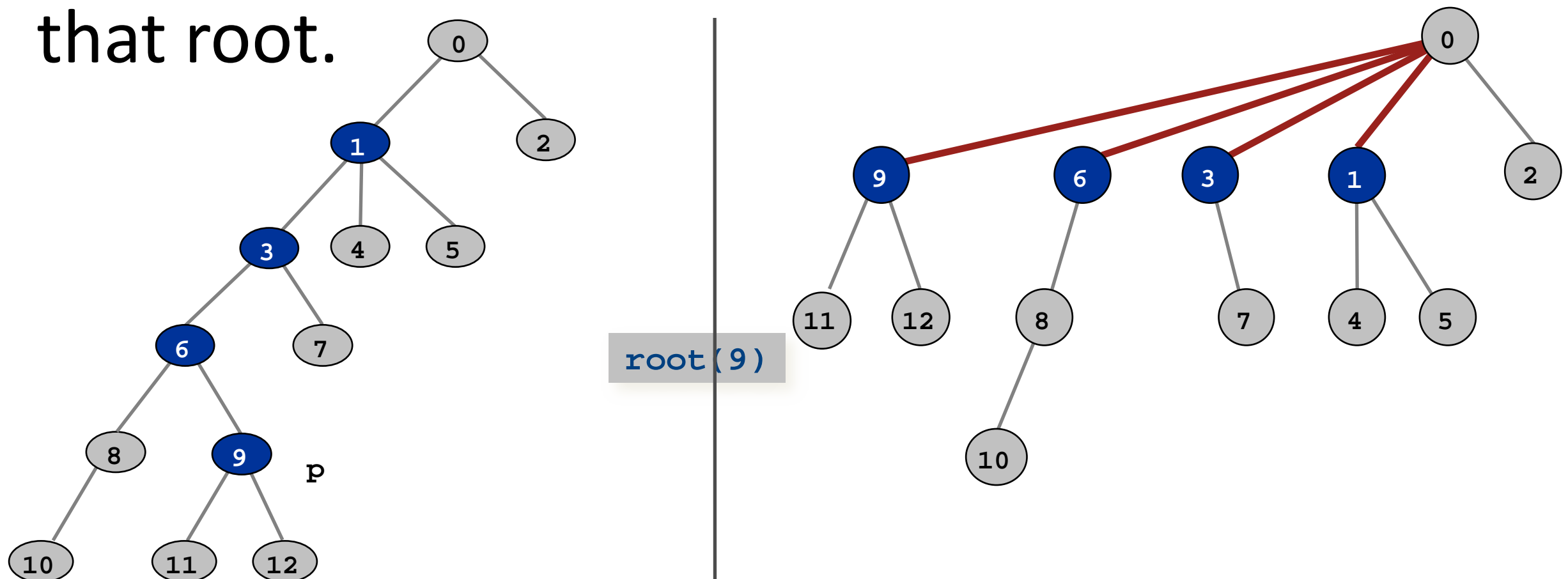
algorithm	init	union	find
quick-find	N	N	1
quick-union	N	N^\dagger	N
weighted QU	N	$\lg N^\dagger$	$\lg N$

\dagger includes cost of finding root

- Q. Stop at guaranteed acceptable performance?
- A. No, easy to improve further.

Improvement 2: path compression

- Quick union with path compression. Just after computing the root of p ,
 - set the id of each examined node to point to that root.
- 



Path compression: Java implementation

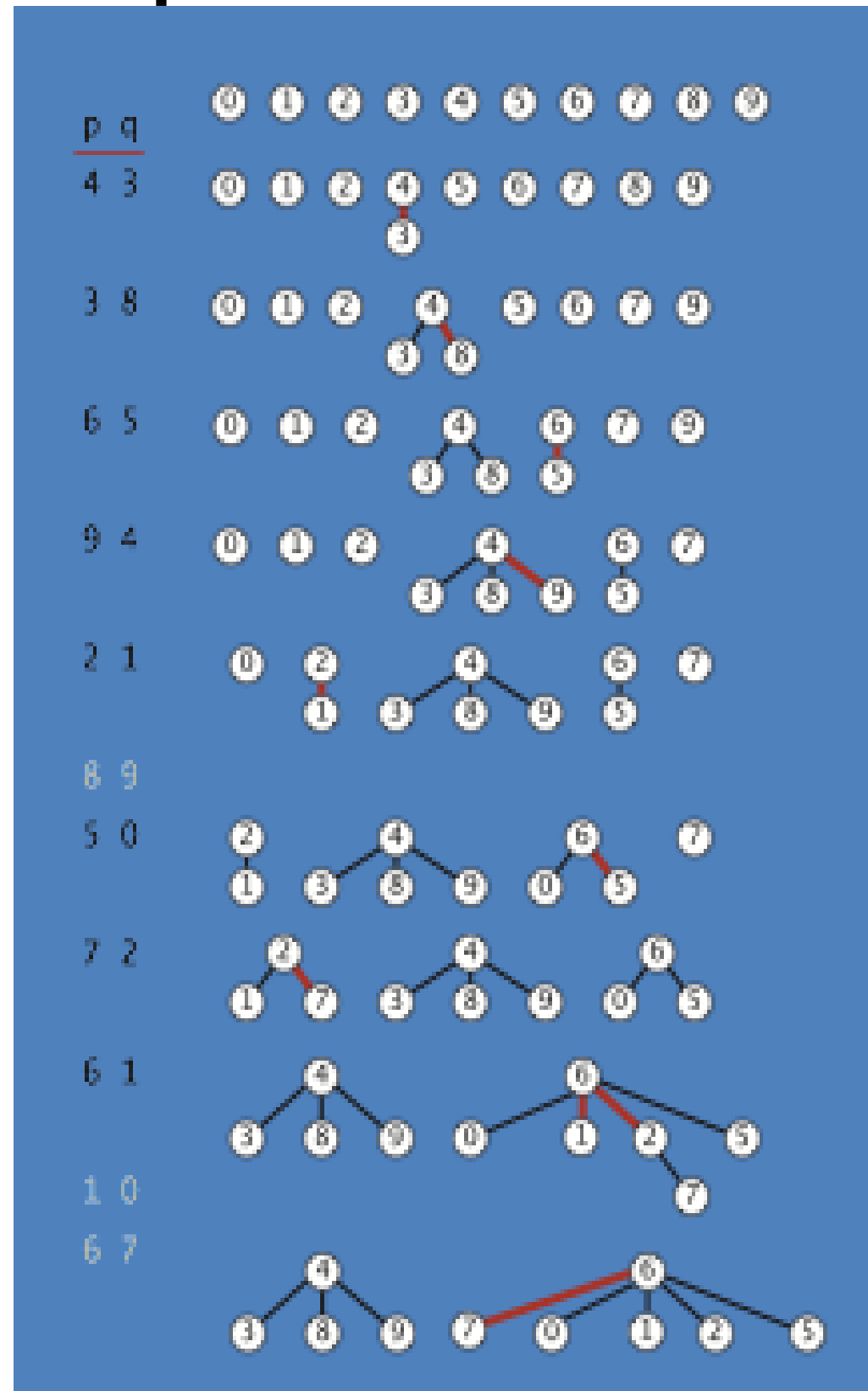
- Standard implementation: add second loop to `find()` to set the `id[]` of each examined node to the root.
- Simpler one-pass variant: halve the path length by making every other node in path point to its grandparent.

```
public int root(int i)
{
    while (i != id[i])
    {
        id[i] = id[id[i]];
        i = id[i];
    }
    return i;
}
```

← only one extra line of code !

- In practice. No reason not to! Keeps tree almost completely flat.

Weighted quick-union with path compression example



1 linked to 6 because of
path compression

7 linked to 6 because of
path compression

Weighted quick-union with path compression: amortized analysis

- Proposition. Starting from an empty data structure,
- any sequence of M union–find operations on N objects makes at most proportional to $N + M \lg^* N$ array accesses.
 - Proof is very difficult.
 - Can be improved to $N + M \langle (M, N) \rangle$.
 - But the algorithm is still simple!

- Linear-time algorithm for M union-find ops on N objects
 - Cost within constant factor of reading in the data.
 - In theory, WQUPC is not quite linear.
 - In practice, WQUPC is linear.

because $\lg^* N$ is a constant in this universe

N	$\lg^* N$
1	0
2	1
4	2
16	3
65536	4
2^{65536}	5

\lg^* function

- Amazing fact. No linear-time algorithm exists.

in "cell-probe" model of computation

Summary

- Bottom line. WQUPC makes it possible to solve problems that could not otherwise be addressed.

algorithm	worst-case time
quick-find	$M N$
quick-union	$M N$
weighted QU	$N + M \log N$
QU + path compression	$N + M \log N$
weighted QU + path compression	$N + M \lg^* N$

M union–find operations on a set of N objects

- Ex. [10^9 unions and finds with 10^9 objects]
 - WQUPC reduces time from 30 years to 6 seconds.
 - Supercomputer won't help much; good algorithm enables solution.

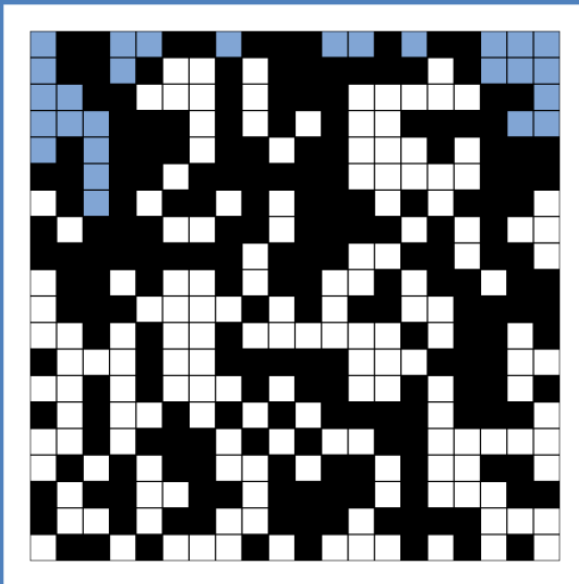
Percolation

- A model for many physical systems:
 - N -by- N grid of sites.
 - Each site is open with probability p (or blocked with

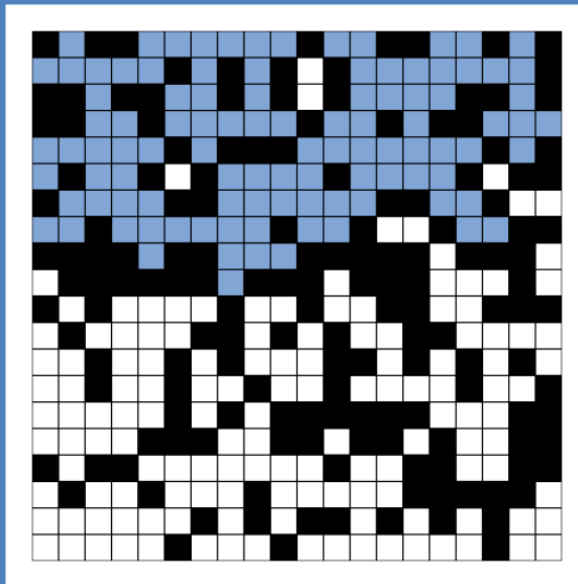
model	system	vacant site	occupied site	percolates
electricity	material	conductor	insulated	conducts
fluid flow	material	empty	blocked	porous
social interaction	population	person	empty	communicates

Likelihood of percolation

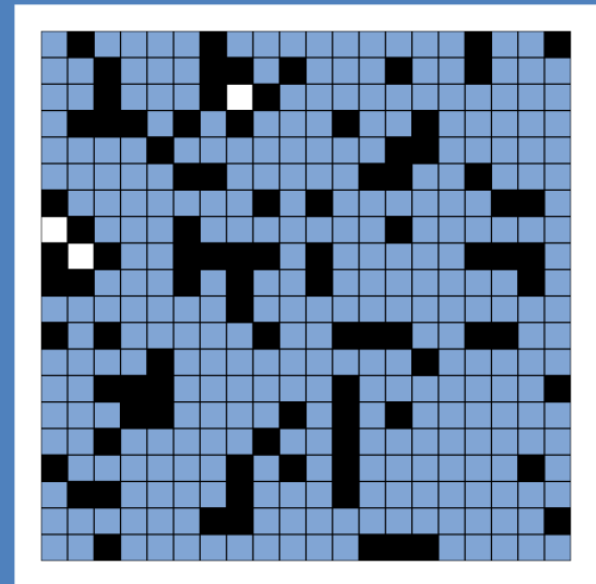
• D



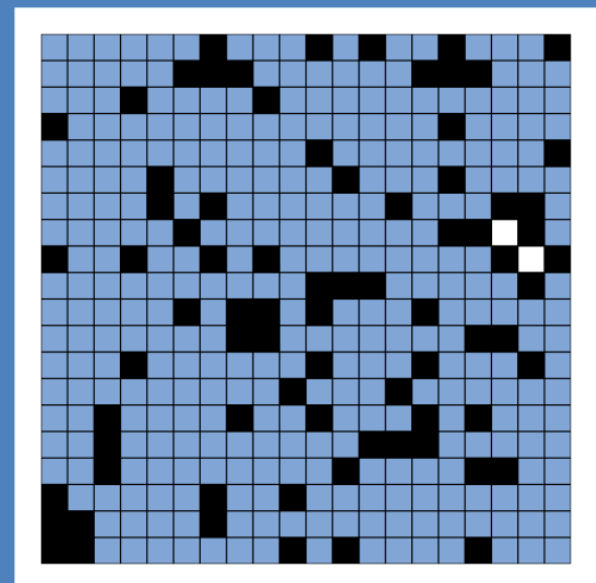
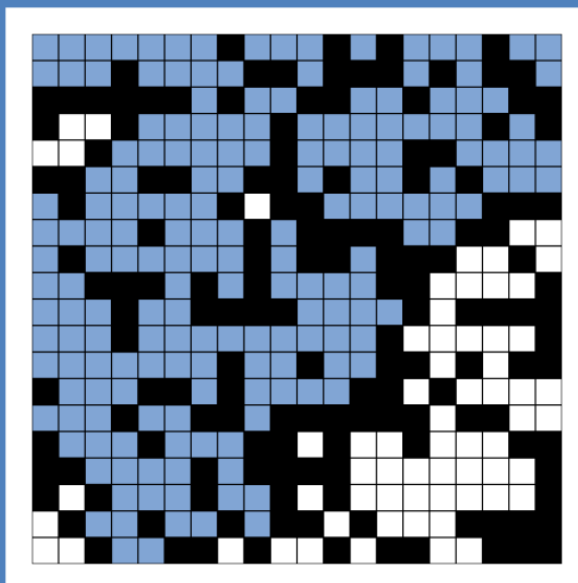
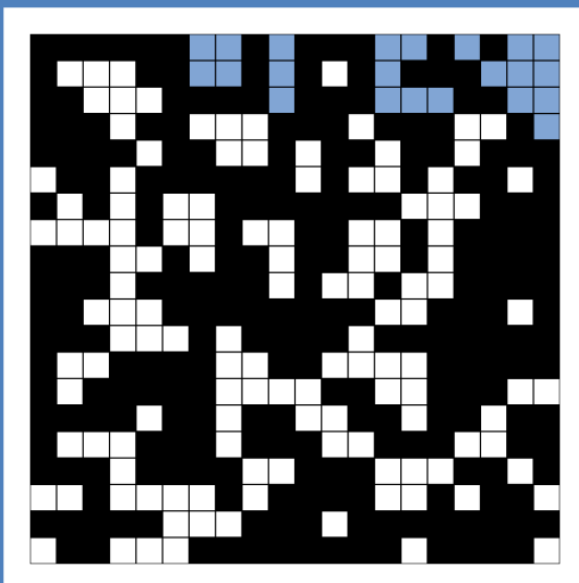
p low (0.4)
does not percolate



p medium (0.6)
percolates?



p high (0.8)
percolates



Percolation phase transition

- When N is large, theory guarantees a sharp threshold p^* .

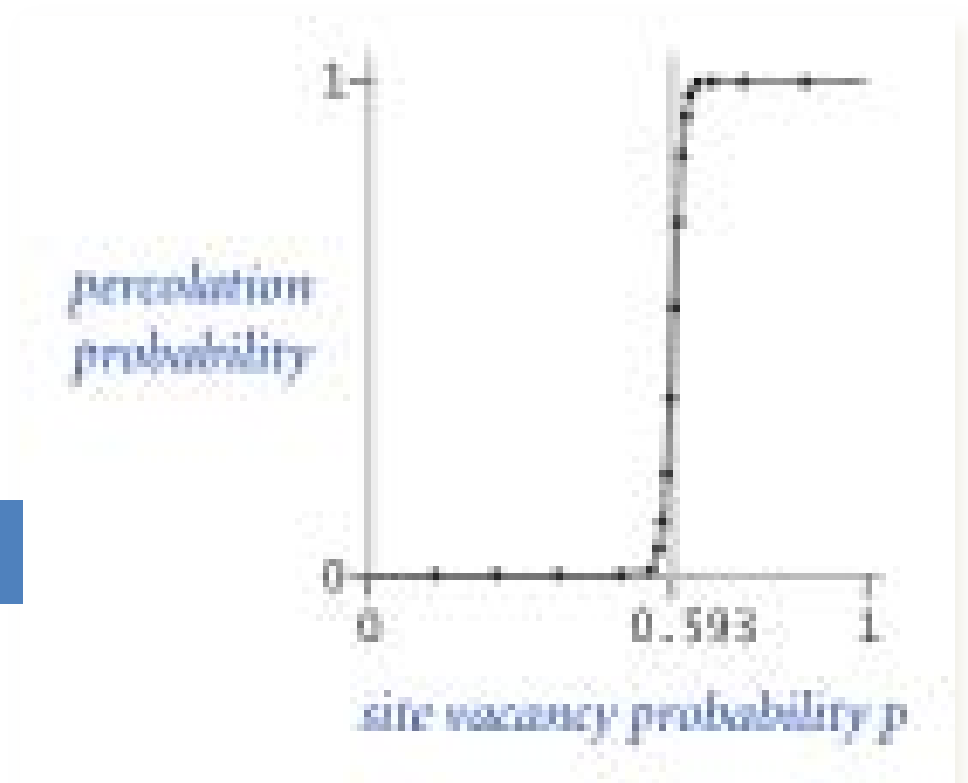
- $p > p^*$: almost certainly percolates.

- $p < p^*$: almost certainly does not percolate.

- Q. What is the value of p^* ?

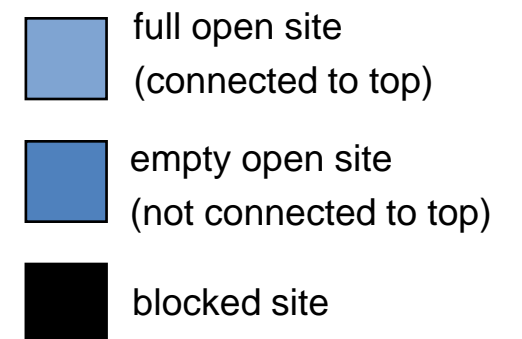
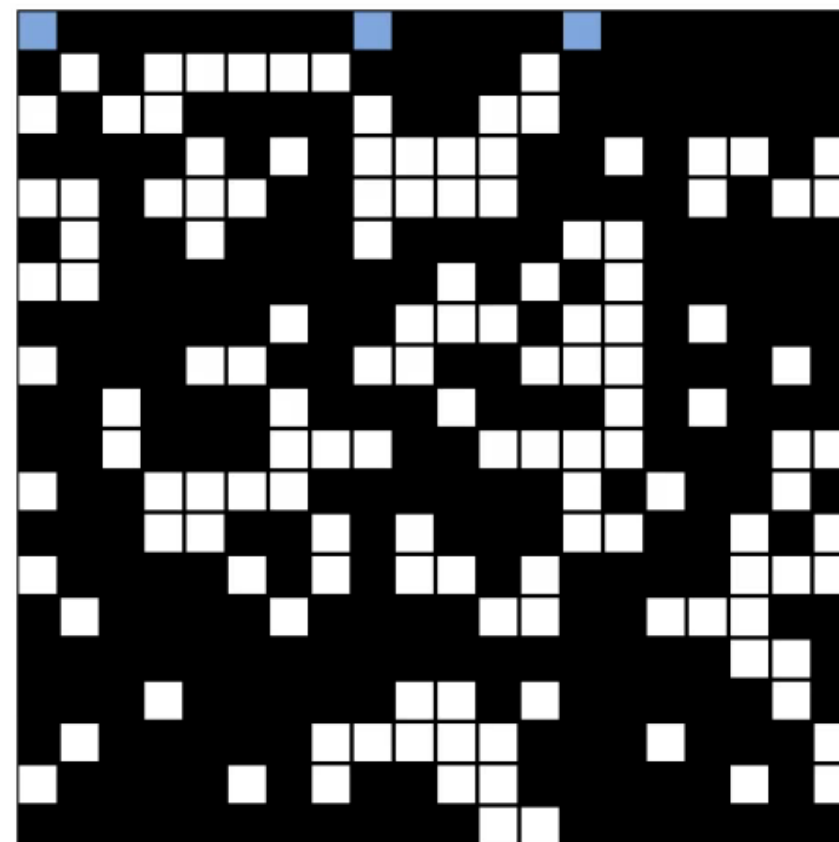
$N = 100$

p^*



Monte Carlo simulation

- Initialize N -by- N whole grid to be blocked.
- Declare random sites open until top connected to bottom.
- Vacancy percentage estimates p^* .

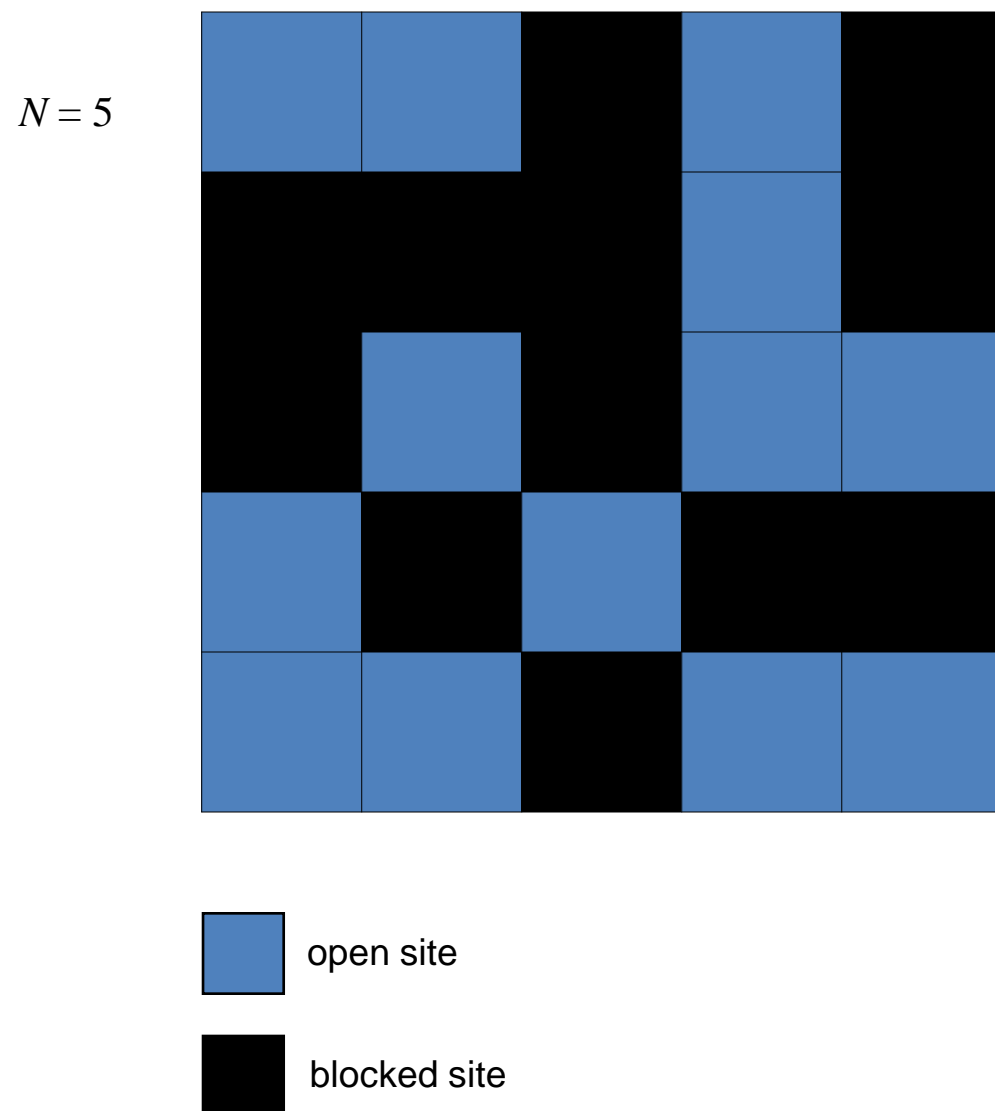


$N = 20$

135 open sites

Dynamic connectivity solution to estimate percolation threshold

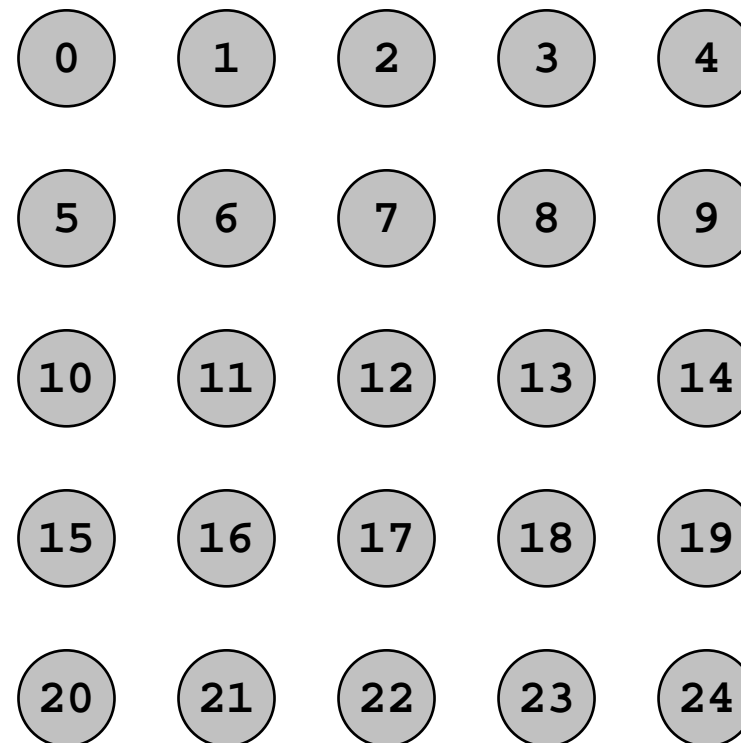
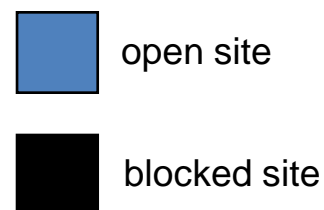
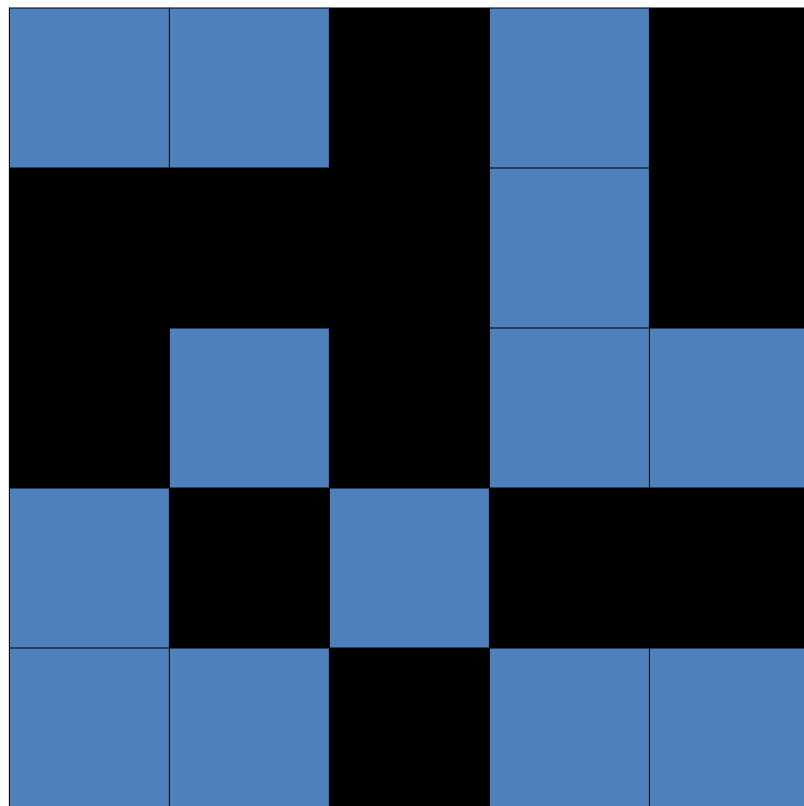
- Q. How to check whether an N -by- N system percolates?



Dynamic connectivity solution to estimate percolation threshold

- Q. How to check whether an N -by- N system percolates?
 - Create an object for each site and name them 0 to $N^2 - 1$.

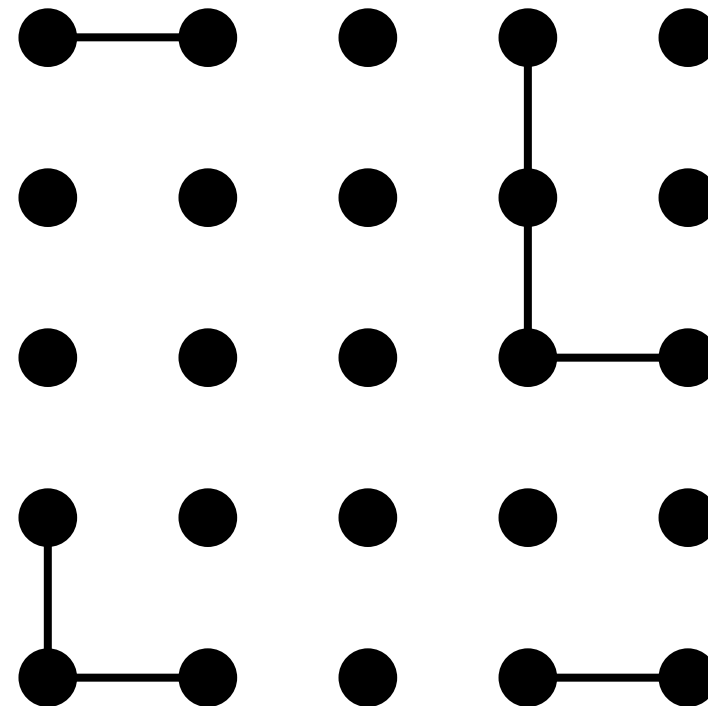
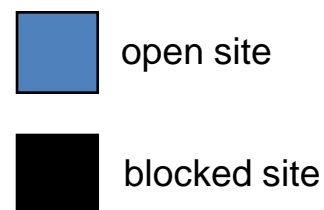
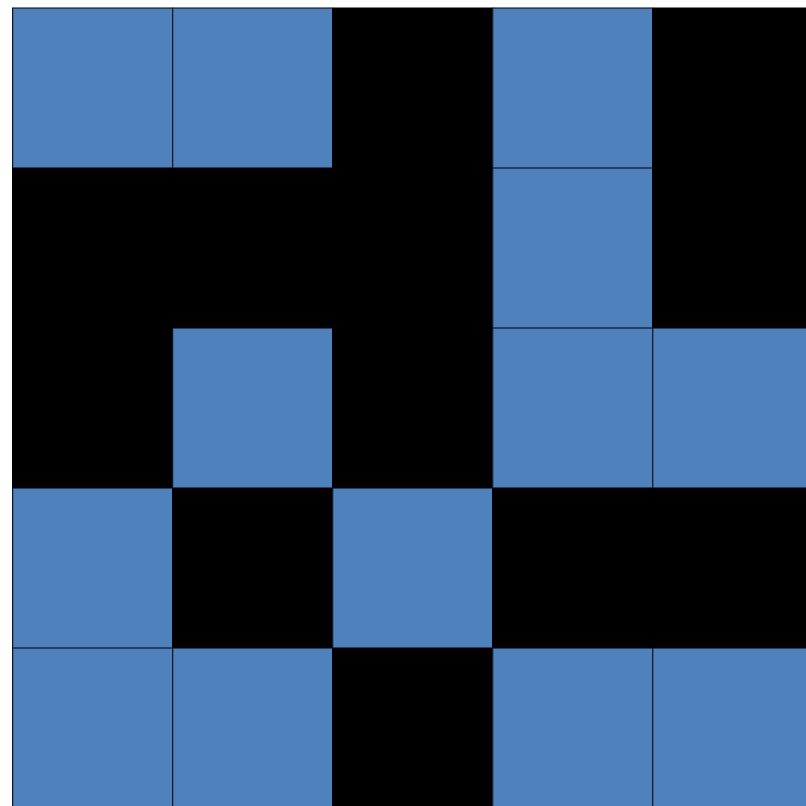
$N = 5$



Dynamic connectivity solution to estimate percolation threshold

- Q. How to check whether an N -by- N system percolates?
 - Create an object for each site and name them 0 to $N^2 - 1$.
 - Sites are in same set if connected by open sites.

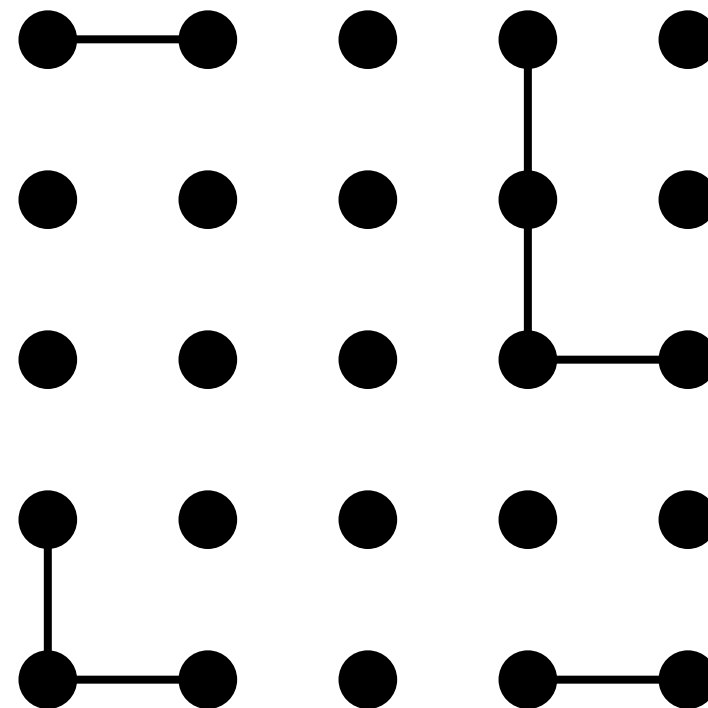
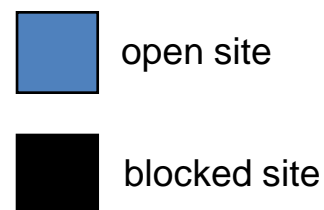
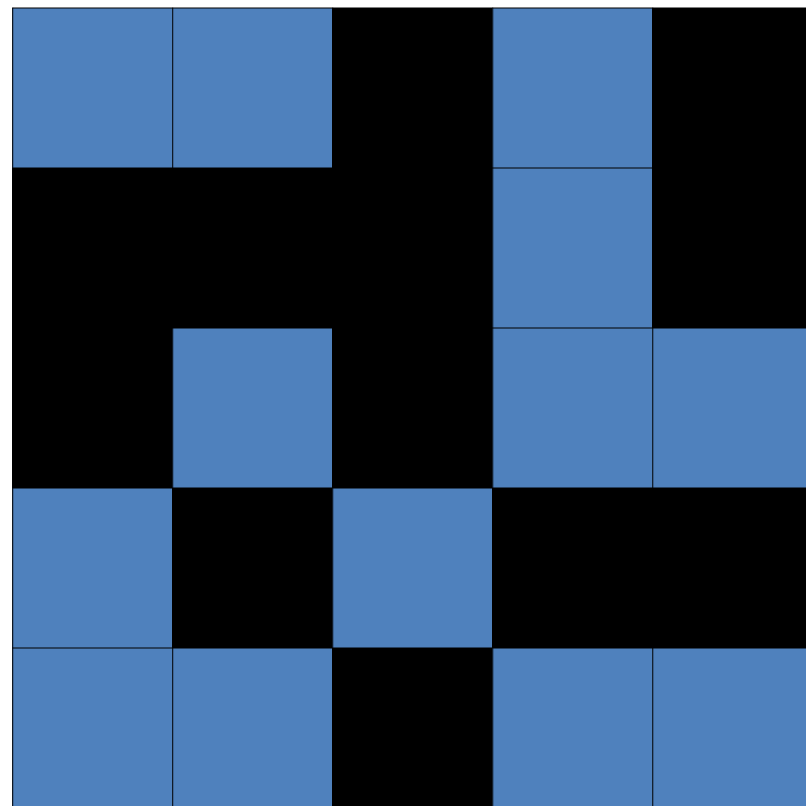
$N = 5$



Dynamic connectivity solution to estimate percolation threshold

- Q. How to check whether an N -by- N system percolates?
 - Create an object for each site and name them 0 to $N^2 - 1$.
 - Sites are in same set if connected by open sites.
 - Percolates iff any site on bottom row is connected to site on top row.

$N = 5$

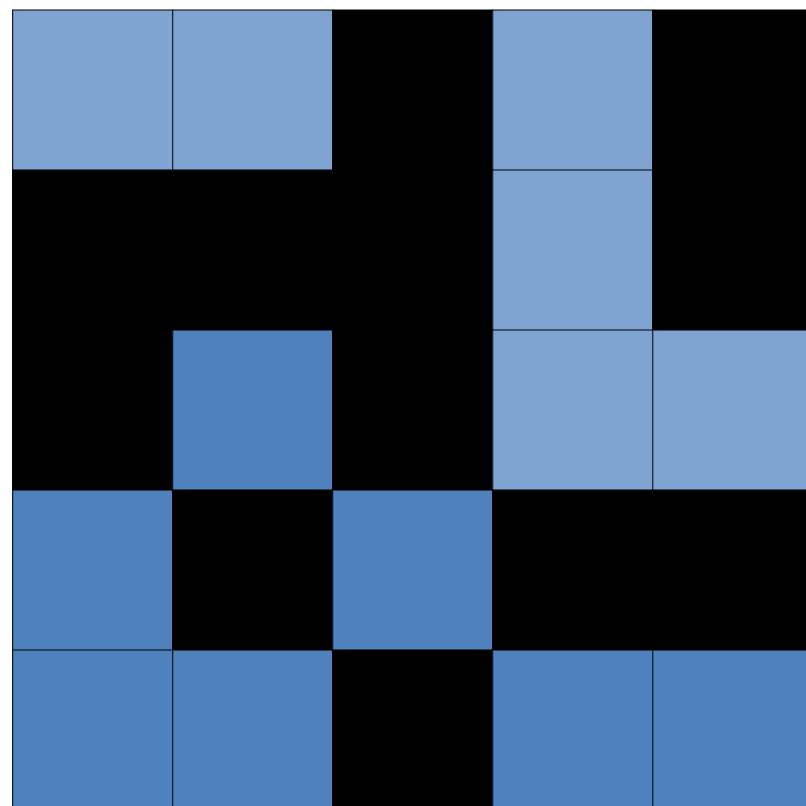



brute-force algorithm: N^2 calls to `connected()`


Dynamic connectivity solution to estimate percolation threshold

- Clever trick. Introduce two virtual sites (and connections to top and bottom).
 - Percolates iff virtual top site is connected to virtual bottom site.
 - Open site is full iff connected to virtual top site.

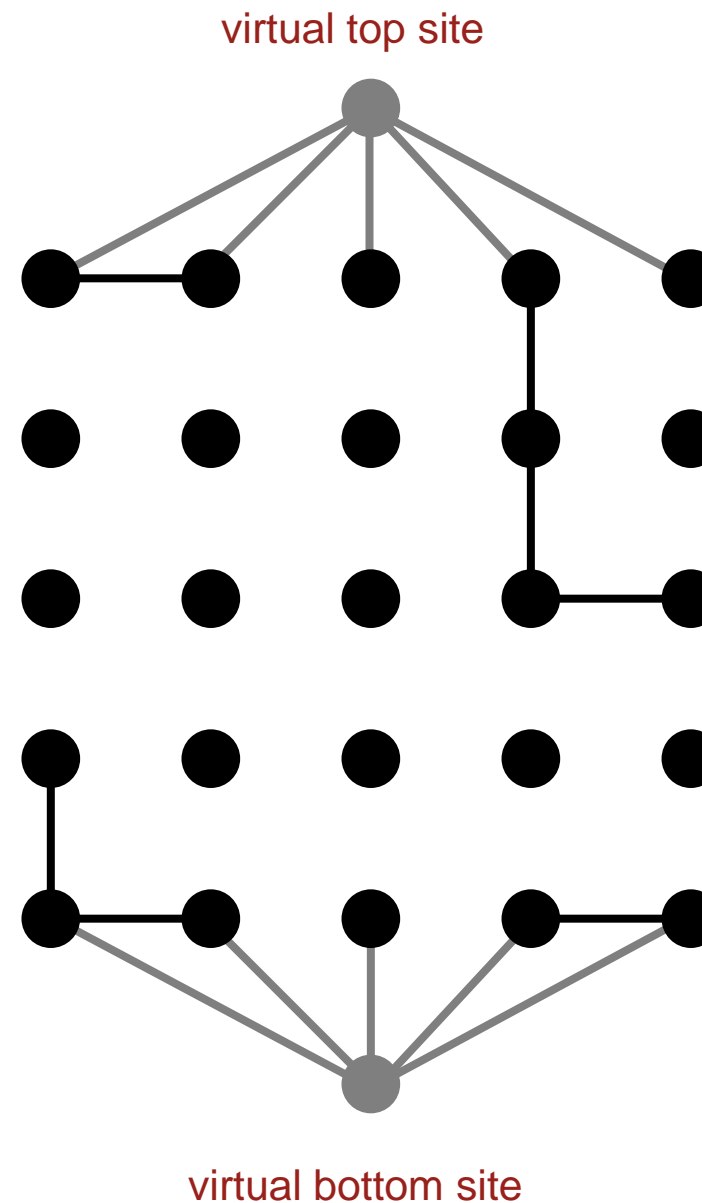
$N = 5$



 empty open site
(not connected to top)

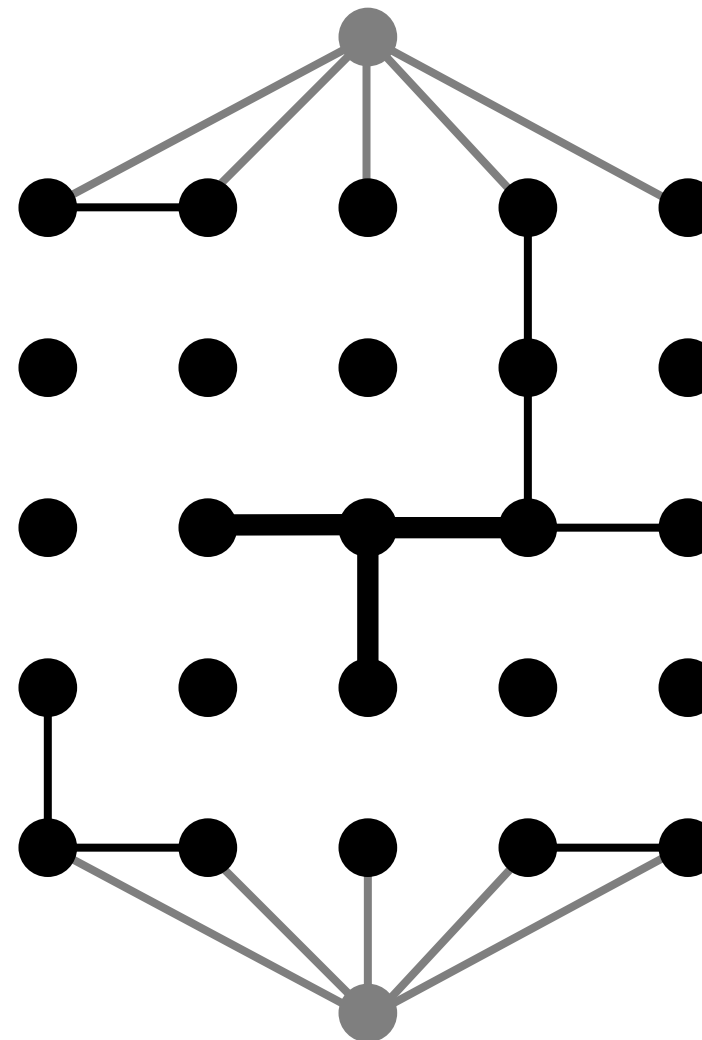
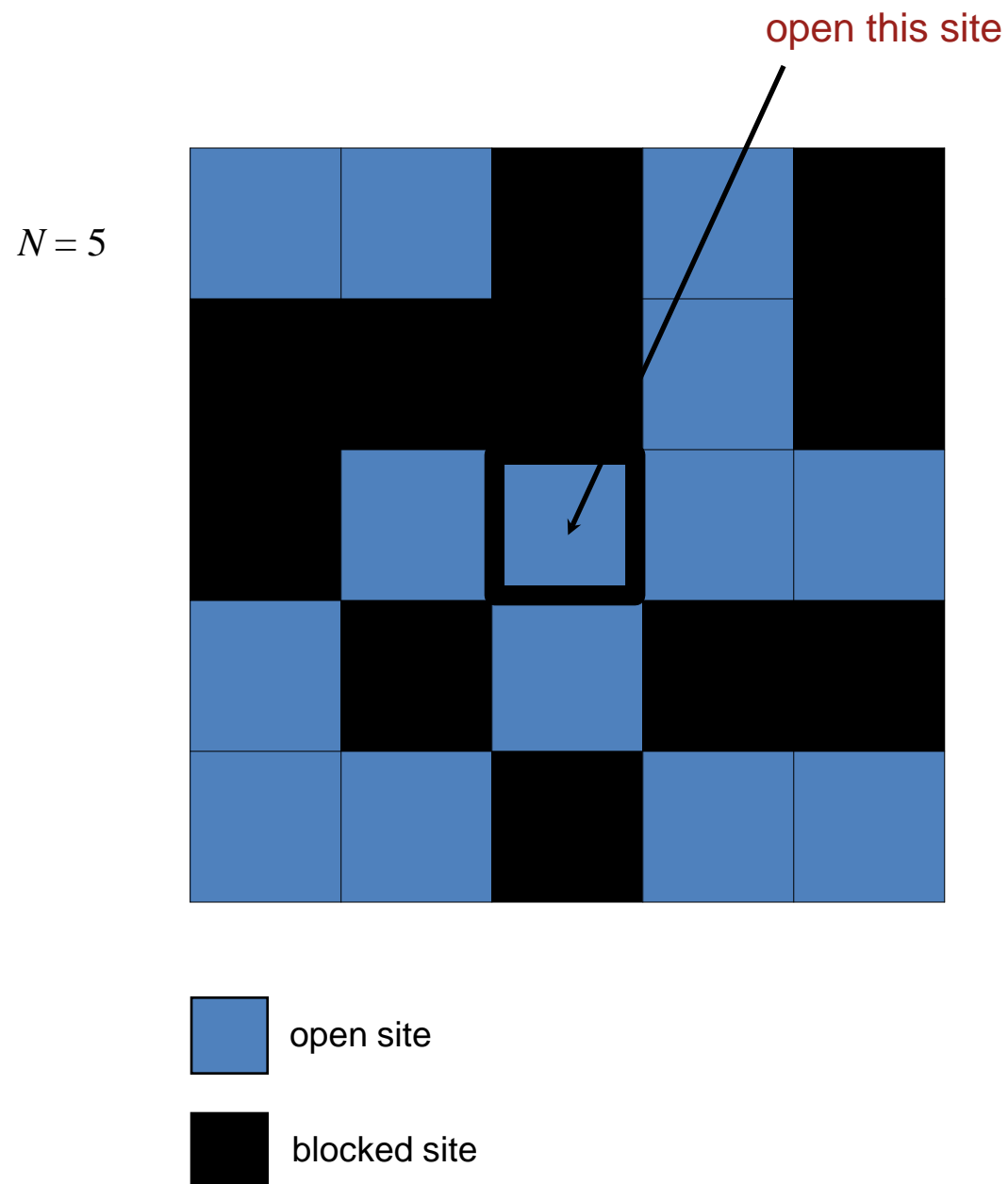
 full open site
(connected to top)

 blocked site



Dynamic connectivity solution to estimate percolation threshold

- Q. How to model as dynamic connectivity problem when opening a new site?
- A. Connect new site to all of its adjacent open sites.



Subtext of today's lecture (and this course)

- Steps to developing a usable algorithm.
 - Model the problem.
 - Find an algorithm to solve it.
 - Fast enough? Fits in memory?
 - If not, figure out why.
 - Find a way to address the problem.
 - Iterate until satisfied.
- The scientific method.
- Mathematical analysis.