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1  #include <stdio.h>
2  #include <stdlib.h>
3  #include <math.h>
4
5  enum
6  {
7      NOSYS = 0,
8      SYS = 1,
9  };
10
11 // начальные аргументы
12 const double e = 2.7182818284;
13 double nosys_args[2] = {0., 3.};
14 double sys_args[3] = {0., 1., 0.25,};
15
16 double f1(double x, double y);
17 double f1_exac(double x, double y);
18 double test2(double x, double y);
19 double test2_exac(double x, double y);
20 double test3(double x, double y);
21 double test3_exac(double x, double y);
22
23 double f1_sys(double x, double y, double z);
24 double f2_sys(double x, double y, double z);
25
26
27 void runge_kutta_2(double (*f)(double, double), double *x, double *y, double
h, int n, FILE *out);
28 void runge_kutta_4(double (*f)(double, double), double *x, double *y, double
h, int n, FILE *out);
29 void runge_kutta_sys_2(double (*f)(double, double, double), double (*g)
(double, double, double), double *x, double *y, double *z, double h, int n,
FILE *out);
30 void runge_kutta_sys_4(double (*f)(double, double, double), double (*g)
(double, double, double), double *x, double *y, double *z, double h, int n,
FILE *out);
31
32 int main(int argc, char **argv)
33 {
34     int mode, accur;
35     sscanf(argv[1], "%d", &mode);
36     sscanf(argv[2], "%d", &accur);
37
38     printf("Enter [a, b] and n:\n");
39     double a, b; int n;
40     scanf("%lf%lf%d", &a, &b, &n);
41     double h = (b - a) / n;
42
43     char name[128];
44     sprintf(name, "table_%d_%d.txt", mode, accur);
45     // файл для записи сетки и построения графика
46     FILE *out = fopen(name, "w");
47
48     // аргументы сетки сохраняются
49     double *x = calloc(n + 1, sizeof(double));
50     double *y = calloc(n + 1, sizeof(double));
51     double *z = calloc(n + 1, sizeof(double));
52
53     if (mode == NOSYS) {
54         x[0] = nosys_args[0];
55         y[0] = nosys_args[1];
56
57         if (accur == 2)
58             runge_kutta_2(&f1, x, y, h, n, out);
59         if (accur == 4)
60             runge_kutta_4(&f1, x, y, h, n, out);
61     }
62
63     if (mode == SYS) {

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64     x[0] = sys_args[0];
65     y[0] = sys_args[1];
66     z[0] = sys_args[2];
67     printf("here\n");
68     if (accur == 2)
69         runge_kutta_sys_2(&f1_sys, &f2_sys, x, y, z, h, n, out);
70     if (accur == 4)
71         runge_kutta_sys_4(&f1_sys, &f2_sys, x, y, z, h, n, out);
72 }
73 return 0;
74 }
75
76 void runge_kutta_2(double (*f)(double, double), double *x, double *y, double
h, int n, FILE *out)
77 {
78     for(int i = 0; i < n; i++) {
79         fprintf(out, "%9.3lf %9.3lf ", x[i], y[i]);
80         fprintf(out, "%9.3lf\n", f1_exac(x[i], y[i]));
81         double k1 = (*f)(x[i], y[i]);
82         double k2 = (*f)(x[i] + h, y[i] + h * k1); // пересчет tilda <y>
83         y[i + 1] = y[i] + h * (k1 + k2) / 2; // добавка с полусуммой
84         x[i + 1] = x[i] + h;
85     }
86     fprintf(out, "%9.3lf %9.3lf\n", x[n], y[n]);
87     return;
88 }
89
90 void runge_kutta_4(double (*f)(double, double), double *x, double *y, double
h, int n, FILE *out)
91 {
92     for(int i = 0; i < n; i++) {
93         fprintf(out, "%9.3lf %9.3lf ", x[i], y[i]);
94         fprintf(out, "%9.3lf\n", f1_exac(x[i], y[i]));
95         double k1 = (*f)(x[i], y[i]);
96         double k2 = (*f)(x[i] + h / 2, y[i] + h * k1 / 2);
97         double k3 = (*f)(x[i] + h / 2, y[i] + h * k2 / 2);
98         double k4 = (*f)(x[i] + h, y[i] + h * k3);
99         y[i + 1] = y[i] + (h / 6) * (k1 + 2 * k2 + 2 * k3 + k4);
100        x[i + 1] = x[i] + h;
101    }
102    fprintf(out, "%9.3lf %9.3lf\n", x[n], y[n]);
103    return;
104 }
105
106 void runge_kutta_sys_2(double (*f)(double, double, double), double (*g)
(double, double, double), double *x, double *y, double *z, double h, int n,
FILE *out)
107 {
108     for(int i = 0; i < n; i++) {
109         fprintf(out, "%9.3lf %9.3lf %9.3lf\n", x[i], y[i], z[i]);
110         double k1 = (*f)(x[i], y[i], z[i]);
111         double m1 = (*g)(x[i], y[i], z[i]);
112         double k2 = (*f)(x[i] + h, y[i] + h * k1, z[i] + h * m1);
113         double m2 = (*g)(x[i] + h, y[i] + h * k1, z[i] + h * m1);
114         y[i + 1] = y[i] + h * (k1 + k2) / 2;
115         z[i + 1] = z[i] + h * (m1 + m2) / 2;
116         x[i + 1] = x[i] + h;
117     }
118     fprintf(out, "%9.3lf %9.3lf %9.3lf\n", x[n], y[n], z[n]);
119     return;
120 }
121
122 void runge_kutta_sys_4(double (*f)(double, double, double), double (*g)
(double, double, double), double *x, double *y, double *z, double h, int n,
FILE *out)
123 {
124     for(int i = 0; i < n; i++) {
125         fprintf(out, "%9.3lf %9.3lf %9.3lf\n", x[i], y[i], z[i]);
126         double k1 = (*f)(x[i], y[i], z[i]);

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127     double m1 = (*g)(x[i], y[i], z[i]);
128     double k2 = (*f)(x[i] + h / 2, y[i] + h * k1 / 2, z[i] + h * m1 / 2);
129     double m2 = (*g)(x[i] + h / 2, y[i] + h * k1 / 2, z[i] + h * m1 / 2);
130     double k3 = (*f)(x[i] + h / 2, y[i] + h * k2 / 2, z[i] + h * m2 / 2);
131     double m3 = (*g)(x[i] + h / 2, y[i] + h * k2 / 2, z[i] + h * m2 / 2);
132     double k4 = (*f)(x[i] + h, y[i] + h * k3, z[i] + h * m3);
133     double m4 = (*g)(x[i] + h, y[i] + h * k3, z[i] + h * m3);
134     y[i + 1] = y[i] + (h / 6) * (k1 + 2 * k2 + 2 * k3 + k4);
135     z[i + 1] = z[i] + (h / 6) * (m1 + 2 * m2 + 2 * m3 + m4);
136     x[i + 1] = x[i] + h;
137 }
138 fprintf(out, "%9.3lf %9.3lf %9.3lf\n", x[n], y[n], z[n]);
139 return;
140 }
141
142 double f1(double x, double y) { return (y - y*y) * x; } //(0, 3)
143
144 double f1_exac(double x, double y)
145 {
146     double proc = x*x / 2;
147     return pow(e, proc) / (pow(e, proc) - 2./3);
148 }
149
150 double f1_sys(double x, double y, double z) { return 2.4 * z - y; }
151
152 double f2_sys(double x, double y, double z) { return pow(e, -1. * y) - x +
153 2.2 * z; }
154
155 double test2(double x, double y) { return 3 - y - x; } // (0, 0)
156
157 double test2_exac(double x, double y) { return 4 - x - 4*pow(e, -1. * x); }
158
159 double test3(double x, double y) { return -1.*y - x*x; } // (0, 10)
160
161 double test3_exac(double x, double y) {return -1.*x*x +2*x - 2 + 12*pow(e,
162 -1.*x);}

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