

Accton

Making Partnership Work



Introduction to Simba High Level Architecture

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Training Purpose



- To understand the high level architecture of the Simba platform
- To understand the important infrastructure design of the Simba platform

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Outline



- Terminology
- Modularized Design
- System Operation Flow
- Loader and OS adopted in Simba
- Simba Runtime Layered Architecture
- Major System Components in Simba
- Generic Flow of a Forked Process

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Terminology



- CSC → Computer Software Component. A module which is designed for a specific feature. And it will contain OM and MGR.
- OM → Object Management. A.k.a. database.
- MGR → Manager. MGR APIs will perform transactions specific to features of the CSC.
- PMGR, POM → Provide wrapper functions for MGR OM APIs which will encapsulate **input arguments** into **request ipc msg** and convert **respond ipc msg** into **output arguments**.

N.B. OM which is created on shared memory does not have POM interface.

Modularized Design

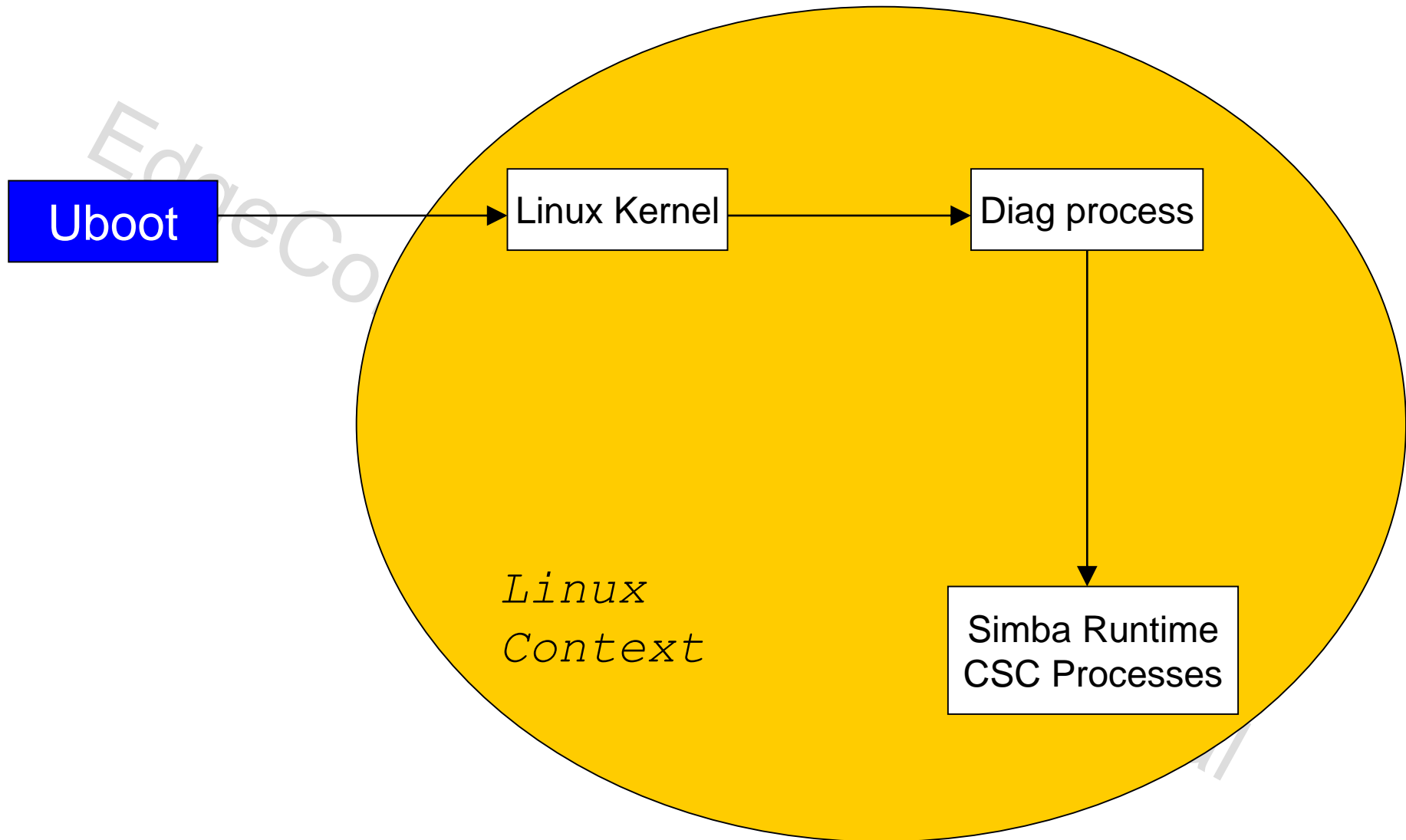


- For each CSC, there will be a corresponding constant defined in “sys_cpnt.h”. For example, the line shown below will add “web” into the build.

```
#define SYS_CPNT_WEB    TRUE
```

- The source code related to the CSC will be enclosed by “#if (SYS_CPNT_WEB==TRUE)” for the example shown above.

System Operation Flow



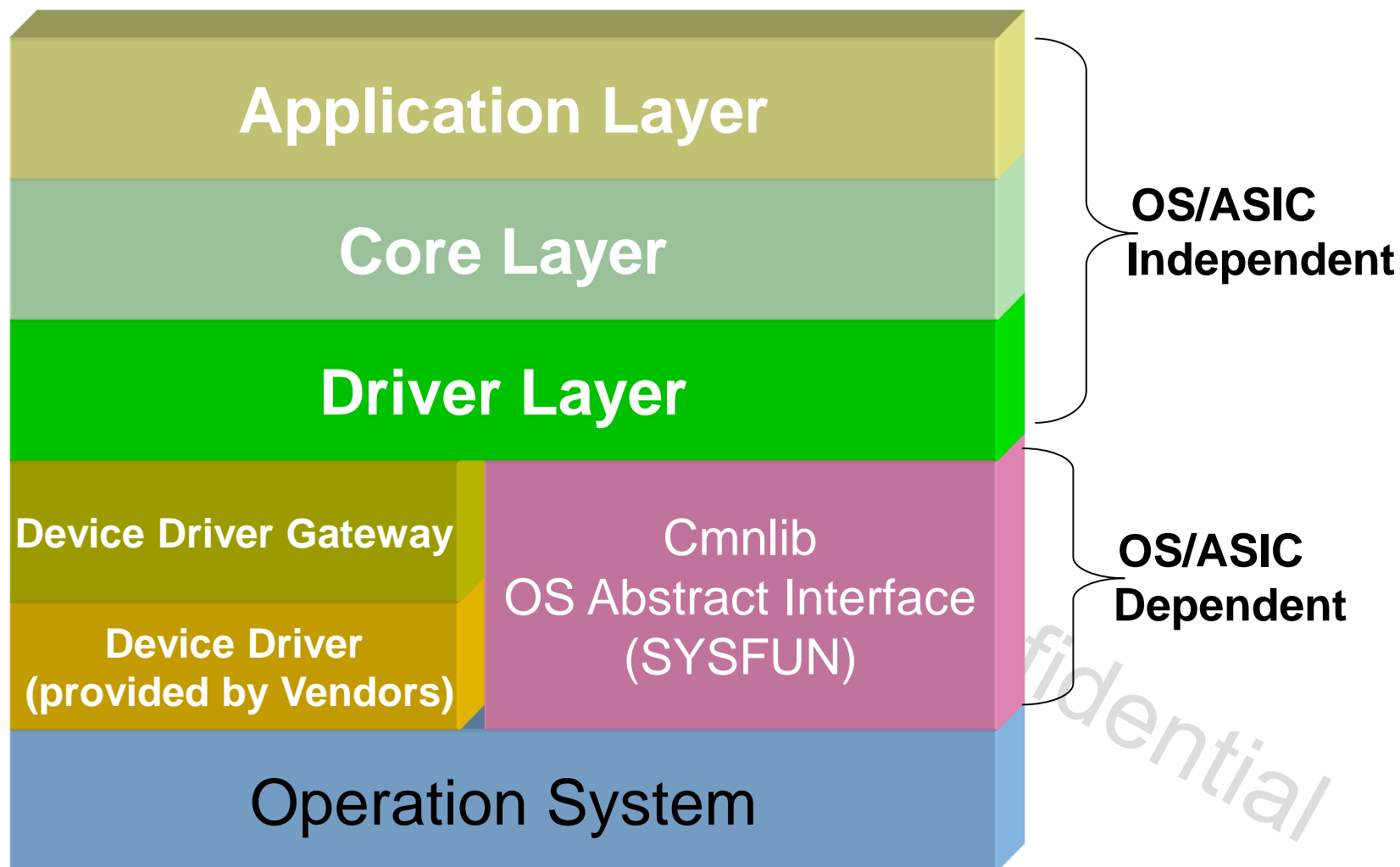
Loader and OS Adopted in Simba



- Loader: Uboot
- OS: Linux kernel
- C library: glibc

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Simba Runtime Layered Hierarchy



N.B. Partial of modules in Cmnlb is OS Independent (e.g. sorted list).

Major System Components in Simba



- SYSFUN Message
- SYSFUN Event
- SYSINIT
- Callback Design
- CSC Group
- Communications among CSC Groups
- Rules about CSC Groups

SYSFUN Message (1/2)



- Two types of message
 - Synchronous message
 - The request message is **handled by the message receiver** and a **response message** is sent back to the message originator.
 - Asynchronous message
 - The asynchronous message **just be enqueued** to the message receiver's queue.

```
UI32_T SYSFUN_SendRequestMsg(UI32_T msgq_handle, SYSFUN_Msg_T *  
req_msg_p, UI32_T wait_time, UI32_T event, UI32_T res_msg_size,  
SYSFUN_Msg_T* res_msg_p);
```

SYSFUN Message (2/2)



- Two types of message queue
 - Uni-direction message queue(Rcv only)
 - Only support **asynchronous** messages.
 - Bi-direction message queue(Rcv and Respond)
 - Support both **synchronous** and **asynchronous** messages.

```
UI32_T SYSFUN_CreateMsgQ(UI32_T msgq_key, UI32_T msgq_type, UI32_T  
    *msgq_handle_p);
```

```
msgq_type :  
    SYSFUN_MSGQ_UNIDIRECTIONAL/SYSFUN_MSGQ_BIDIRECTIONAL
```

Sysfun Event (1/2)



- Event is a bitmap with data type unsigned long(32 bits)
- Each thread can define the events it needs.
- SYSFUN_SendEvent(UI32_T tid, UI32_T event)
 - SYSFUN API to send event to the given tid.

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Sysfun Event (2/2)



- SYSFUN_RecvEvent(UI32_T wait_event, UI32_T flags, int timeout, UI32_T *received_event)
 - SYSFUN API for each thread to receive the event that had been sent to it.
 - The caller of the API can choose to wait on all of the events in wait_event or just any one of the events in wait_event.
 - The caller of the API can determine the longest time to wait for a event by the argument “timeout”. It is also possible to perform unblocked operation (i.e. no wait).

SYSFUN_SendEvent Example



```
#define AMTRDRV_MGR_EVENT_ADDRESS_OPERATION  
(1<<2)  
  
BOOL_T AMTRDRV_MGR_DeleteAllAddr(void)  
{  
    AMTR_TYPE_BlockedCommand_T * blocked_command_p ;  
    blocked_command_p =  
AMTRDRV_OM_GetBlockCommand(0);  
    blocked_command_p->blocked_command =  
AMTR_TYPE_COMMAND_DELETE_ALL;  
    SYSFUN_SendEvent(AMTRDRV_OM_GetAsicComTaskId(),  
AMTRDRV_MGR_EVENT_ADDRESS_OPERATION);  
    ...  
}
```

```

static void AMTRDRV_ASIC_COMMAND_TASK_Main(void)
{
    ...
    SYSFUN_PeriodicTimer_Start(amtrdrv_asic_command_task_tmid,
                               amtr_update_addr_table_ticks,
                               AMTRDRV_MGR_EVENT_TIMER);

    events = 0;
    while(TRUE)
    {
        /* wait event
         */
        SYSFUN_ReceiveEvent ((AMTRDRV_MGR_EVENT_TIMER |
                               AMTRDRV_MGR_EVENT_ENTER_TRANSITION_MODE |
                               AMTRDRV_MGR_EVENT_ADDRESS_OPERATION),
                              SYSFUN_EVENT_WAIT_ANY,
                              (events!=0)? SYSFUN_TIMEOUT_NOWAIT:
                               SYSFUN_TIMEOUT_WAIT_FOREVER,
                              &pending_events);
        events |= pending_events;

        if (events & AMTRDRV_MGR_EVENT_ADDRESS_OPERATION)
            ...
    }
    ...
}

```

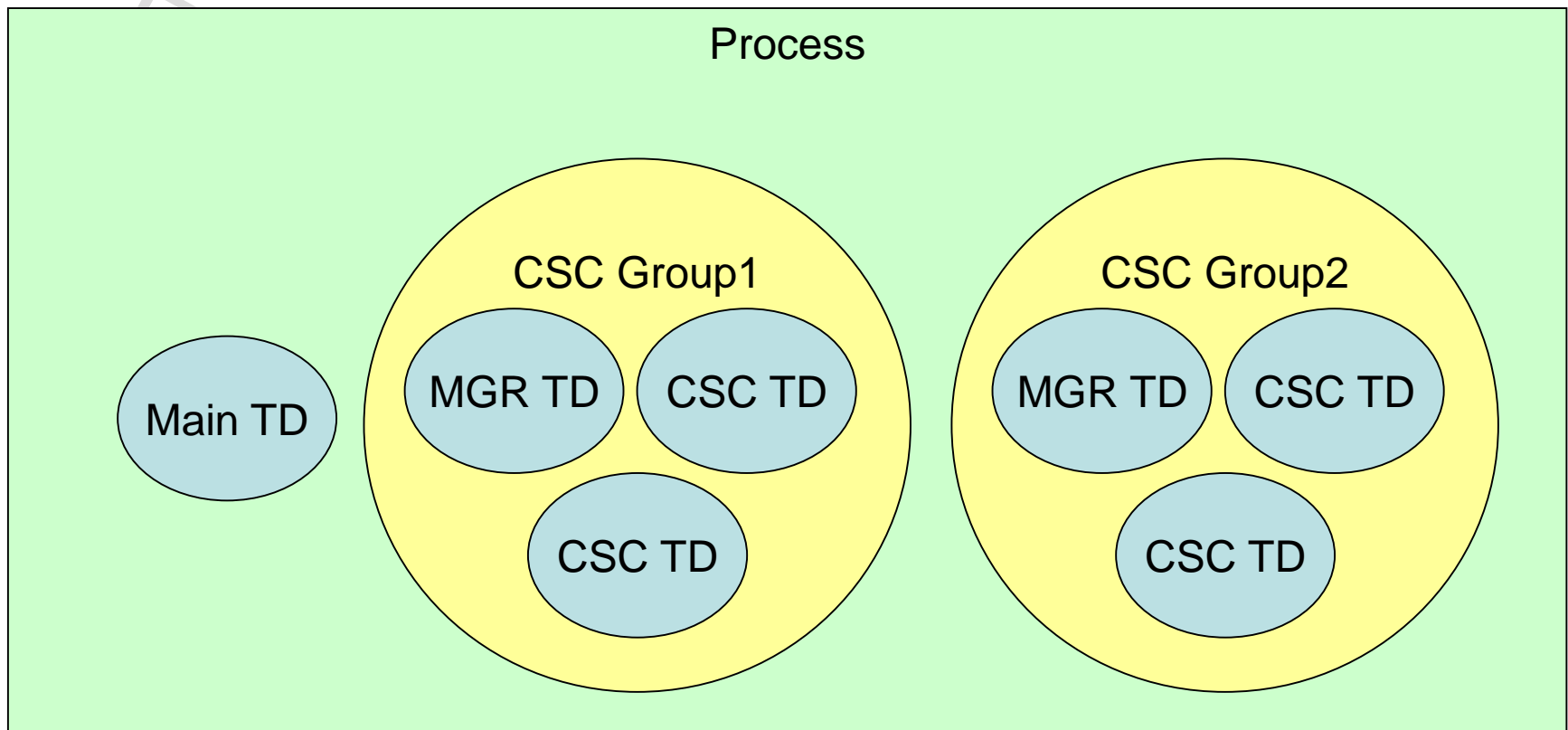
SYSINIT



- SYSINIT is a program that is executed before any CSC processes spawns.
- SYSINIT will initialize system-wised resources (shared memory, semaphore) which will be used by CSCs.

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Concept of a CSC Group



TD means "thread".

Communications among CSC Groups



- Communications among CSC Groups are done through **Synchronous/Asynchronous** message queues.
- Each **mgr thread** in a CSC group **owns a message queue** which is assigned a pre-defined specific id. The mgr thread is **responsible** for handling all of the IPC request messages belong to the **CSCs in the CSC group**.
- All threads in the system are able to **get** the message queue **handle** by the **pre-defined specific id**.

Rules about CSC Group (1/3)



- The **main thread** is responsible for **handling POM IPC** messages if needed.
- Each CSC group **must have a mgr thread** to handle the IPC messages.
- Message queues will be used in **communications among CSC groups**.

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Rules about CSC Group (2/3)



- A CSC **may** call **MGR APIs** of the other CSCs which **belong to the same CSC group**.
- A CSC has to **call PMGR APIs** of the other CSCs which belong to the CSC group **different from the calling CSC**.

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Rules about CSC Group (3/3)



- A CSC is **allowed to call OM APIs(read operations only)** of the other CSCs which belong to **the same process**.
- A CSC **needs to call POM APIs(read operations only)** of the other CSCs which belong to the **process different from the calling CSC**.

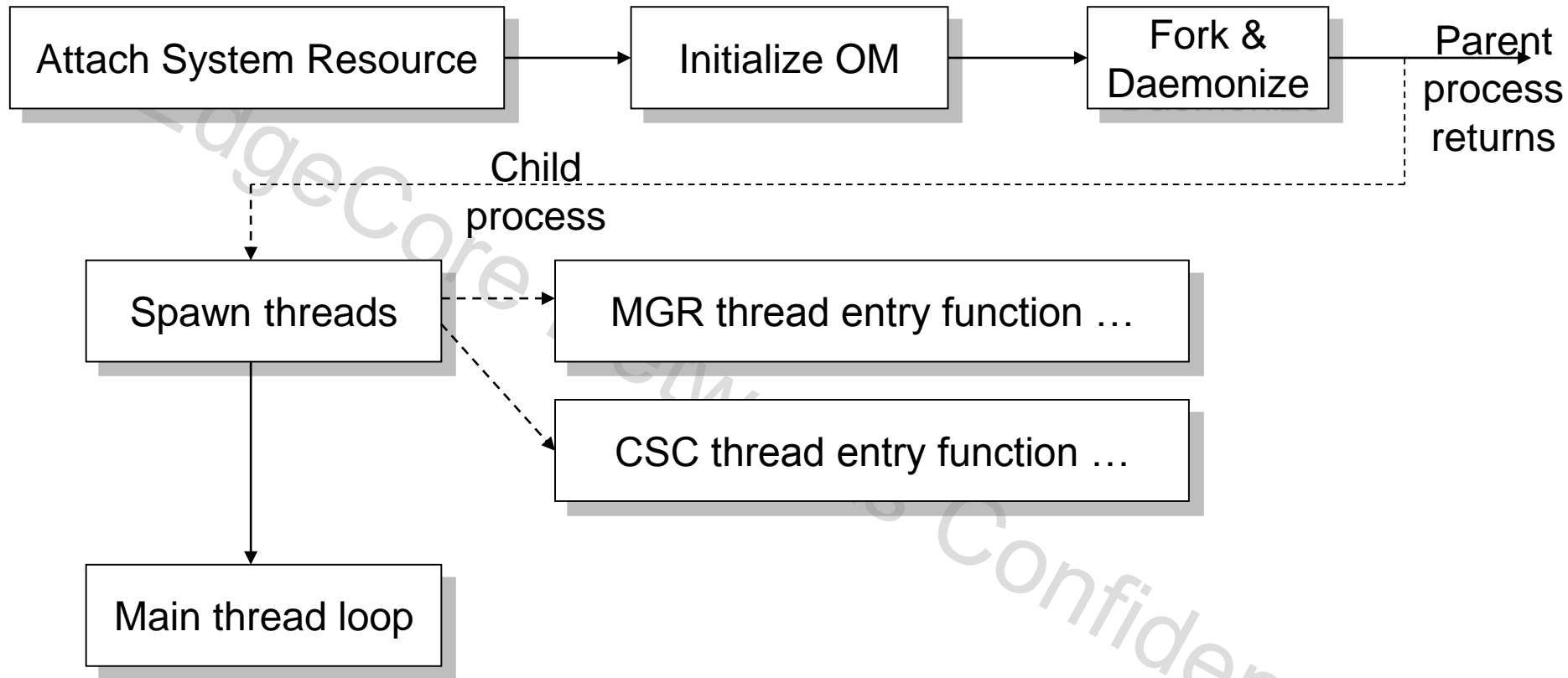
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Callback Design



- Callbacks **within the same** CSC group
 - Direct function calls
- Callbacks to CSCs in **the other** CSC groups
 - Through SYS_CALLBACK_MGR
- SYS_CALLBACK_MGR provides APIs to handle the delivery of **asynchronous SYSFUN message** to CSC groups that need to receive.

Generic Flow of a Forked Process





Q&A

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Thank you for your attention



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