by left-multiplying each side to obtain

$$x = By. (2.45)$$

Depending on the structure of the problem, it may not be possible to design a unique mapping from A to B.

If A is taller than it is wide, then it is possible for this equation to have no solution. If A is wider than it is tall, then there could be multiple possible solutions.

The Moore-Penrose pseudoinverse allows us to make some headway in these cases. The pseudoinverse of A is defined as a matrix

$$\boldsymbol{A}^{+} = \lim_{\alpha \searrow 0} (\boldsymbol{A}^{\top} \boldsymbol{A} + \alpha \boldsymbol{I})^{-1} \boldsymbol{A}^{\top}. \tag{2.46}$$

Practical algorithms for computing the pseudoinverse are not based on this definition, but rather the formula

$$\boldsymbol{A}^{+} = \boldsymbol{V} \boldsymbol{D}^{+} \boldsymbol{U}^{\top}, \tag{2.47}$$

where U, D and V are the singular value decomposition of A, and the pseudoinverse  $D^+$  of a diagonal matrix D is obtained by taking the reciprocal of its non-zero elements then taking the transpose of the resulting matrix.

When A has more columns than rows, then solving a linear equation using the pseudoinverse provides one of the many possible solutions. Specifically, it provides the solution  $x = A^+ y$  with minimal Euclidean norm  $||x||_2$  among all possible solutions.

When  $\boldsymbol{A}$  has more rows than columns, it is possible for there to be no solution. In this case, using the pseudoinverse gives us the  $\boldsymbol{x}$  for which  $\boldsymbol{A}\boldsymbol{x}$  is as close as possible to  $\boldsymbol{y}$  in terms of Euclidean norm  $||\boldsymbol{A}\boldsymbol{x}-\boldsymbol{y}||_2$ .

## 2.10 The Trace Operator

The trace operator gives the sum of all of the diagonal entries of a matrix:

$$Tr(\mathbf{A}) = \sum_{i} \mathbf{A}_{i,i}.$$
 (2.48)

The trace operator is useful for a variety of reasons. Some operations that are difficult to specify without resorting to summation notation can be specified using