

$f'(x - \epsilon) < 0$  and  $f'(x + \epsilon) > 0$  for small enough  $\epsilon$ . In other words, as we move right, the slope begins to point uphill to the right, and as we move left, the slope begins to point uphill to the left. Thus, when  $f'(x) = 0$  and  $f''(x) > 0$ , we can conclude that  $x$  is a local minimum. Similarly, when  $f'(x) = 0$  and  $f''(x) < 0$ , we can conclude that  $x$  is a local maximum. This is known as the **second derivative test**. Unfortunately, when  $f''(x) = 0$ , the test is inconclusive. In this case  $x$  may be a saddle point, or a part of a flat region.

In multiple dimensions, we need to examine all of the second derivatives of the function. Using the eigendecomposition of the Hessian matrix, we can generalize the second derivative test to multiple dimensions. At a critical point, where  $\nabla_{\mathbf{x}} f(\mathbf{x}) = 0$ , we can examine the eigenvalues of the Hessian to determine whether the critical point is a local maximum, local minimum, or saddle point. When the Hessian is positive definite (all its eigenvalues are positive), the point is a local minimum. This can be seen by observing that the directional second derivative in any direction must be positive, and making reference to the univariate second derivative test. Likewise, when the Hessian is negative definite (all its eigenvalues are negative), the point is a local maximum. In multiple dimensions, it is actually possible to find positive evidence of saddle points in some cases. When at least one eigenvalue is positive and at least one eigenvalue is negative, we know that  $\mathbf{x}$  is a local maximum on one cross section of  $f$  but a local minimum on another cross section. See figure 4.5 for an example. Finally, the multidimensional second derivative test can be inconclusive, just like the univariate version. The test is inconclusive whenever all of the non-zero eigenvalues have the same sign, but at least one eigenvalue is zero. This is because the univariate second derivative test is inconclusive in the cross section corresponding to the zero eigenvalue.

In multiple dimensions, there is a different second derivative for each direction at a single point. The condition number of the Hessian at this point measures how much the second derivatives differ from each other. When the Hessian has a poor condition number, gradient descent performs poorly. This is because in one direction, the derivative increases rapidly, while in another direction, it increases slowly. Gradient descent is unaware of this change in the derivative so it does not know that it needs to explore preferentially in the direction where the derivative remains negative for longer. It also makes it difficult to choose a good step size. The step size must be small enough to avoid overshooting the minimum and going uphill in directions with strong positive curvature. This usually means that the step size is too small to make significant progress in other directions with less curvature. See figure 4.6 for an example.

This issue can be resolved by using information from the Hessian matrix to guide