

Figure 14.3: The computational graph of the cost function for a denoising autoencoder, which is trained to reconstruct the clean data point  $\boldsymbol{x}$  from its corrupted version  $\tilde{\boldsymbol{x}}$ . This is accomplished by minimizing the loss  $L = -\log p_{\text{decoder}}(\boldsymbol{x} \mid \boldsymbol{h} = f(\tilde{\boldsymbol{x}}))$ , where  $\tilde{\boldsymbol{x}}$  is a corrupted version of the data example  $\boldsymbol{x}$ , obtained through a given corruption process  $C(\tilde{\boldsymbol{x}} \mid \boldsymbol{x})$ . Typically the distribution  $p_{\text{decoder}}$  is a factorial distribution whose mean parameters are emitted by a feedforward network g.

corrupted samples  $\tilde{\mathbf{x}}$ , given a data sample  $\mathbf{x}$ . The autoencoder then learns a **reconstruction distribution**  $p_{\text{reconstruct}}(\mathbf{x} \mid \tilde{\mathbf{x}})$  estimated from training pairs  $(\mathbf{x}, \tilde{\mathbf{x}})$ , as follows:

- 1. Sample a training example  $\boldsymbol{x}$  from the training data.
- 2. Sample a corrupted version  $\tilde{x}$  from  $C(\tilde{\mathbf{x}} \mid \mathbf{x} = x)$ .
- 3. Use  $(\boldsymbol{x}, \tilde{\boldsymbol{x}})$  as a training example for estimating the autoencoder reconstruction distribution  $p_{\text{reconstruct}}(\boldsymbol{x} \mid \tilde{\boldsymbol{x}}) = p_{\text{decoder}}(\boldsymbol{x} \mid \boldsymbol{h})$  with  $\boldsymbol{h}$  the output of encoder  $f(\tilde{\boldsymbol{x}})$  and  $p_{\text{decoder}}$  typically defined by a decoder  $g(\boldsymbol{h})$ .

Typically we can simply perform gradient-based approximate minimization (such as minibatch gradient descent) on the negative log-likelihood  $-\log p_{\rm decoder}(\boldsymbol{x}\mid\boldsymbol{h})$ . So long as the encoder is deterministic, the denoising autoencoder is a feedforward network and may be trained with exactly the same techniques as any other feedforward network.

We can therefore view the DAE as performing stochastic gradient descent on the following expectation:

$$- \mathbb{E}_{\mathbf{x} \sim \hat{p}_{\text{data}}(\mathbf{x})} \mathbb{E}_{\tilde{\mathbf{x}} \sim C(\tilde{\mathbf{x}} | \mathbf{x})} \log p_{\text{decoder}}(\mathbf{x} \mid \mathbf{h} = f(\tilde{\mathbf{x}}))$$
 (14.14)

where  $\hat{p}_{\text{data}}(\mathbf{x})$  is the training distribution.