ensemble to make partially independent errors.

Model averaging is an extremely powerful and reliable method for reducing generalization error. Its use is usually discouraged when benchmarking algorithms for scientific papers, because any machine learning algorithm can benefit substantially from model averaging at the price of increased computation and memory. For this reason, benchmark comparisons are usually made using a single model.

Machine learning contests are usually won by methods using model averaging over dozens of models. A recent prominent example is the Netflix Grand Prize (Koren, 2009).

Not all techniques for constructing ensembles are designed to make the ensemble more regularized than the individual models. For example, a technique called **boosting** (Freund and Schapire, 1996b,a) constructs an ensemble with higher capacity than the individual models. Boosting has been applied to build ensembles of neural networks (Schwenk and Bengio, 1998) by incrementally adding neural networks to the ensemble. Boosting has also been applied interpreting an individual neural network as an ensemble (Bengio et al., 2006a), incrementally adding hidden units to the neural network.

7.12 Dropout

Dropout (Srivastava et al., 2014) provides a computationally inexpensive but powerful method of regularizing a broad family of models. To a first approximation, dropout can be thought of as a method of making bagging practical for ensembles of very many large neural networks. Bagging involves training multiple models, and evaluating multiple models on each test example. This seems impractical when each model is a large neural network, since training and evaluating such networks is costly in terms of runtime and memory. It is common to use ensembles of five to ten neural networks—Szegedy et al. (2014a) used six to win the ILSVRC—but more than this rapidly becomes unwieldy. Dropout provides an inexpensive approximation to training and evaluating a bagged ensemble of exponentially many neural networks.

Specifically, dropout trains the ensemble consisting of all sub-networks that can be formed by removing non-output units from an underlying base network, as illustrated in figure 7.6. In most modern neural networks, based on a series of affine transformations and nonlinearities, we can effectively remove a unit from a network by multiplying its output value by zero. This procedure requires some slight modification for models such as radial basis function networks, which take