the SVD is more generally applicable. Every real matrix has a singular value decomposition, but the same is not true of the eigenvalue decomposition. For example, if a matrix is not square, the eigendecomposition is not defined, and we must use a singular value decomposition instead.

Recall that the eigendecomposition involves analyzing a matrix A to discover a matrix V of eigenvectors and a vector of eigenvalues λ such that we can rewrite A as

$$\mathbf{A} = \mathbf{V}\operatorname{diag}(\lambda)\mathbf{V}^{-1}.\tag{2.42}$$

The singular value decomposition is similar, except this time we will write A as a product of three matrices:

$$\mathbf{A} = \mathbf{U}\mathbf{D}\mathbf{V}^{\top}.\tag{2.43}$$

Suppose that \boldsymbol{A} is an $m \times n$ matrix. Then \boldsymbol{U} is defined to be an $m \times m$ matrix, \boldsymbol{D} to be an $m \times n$ matrix, and \boldsymbol{V} to be an $n \times n$ matrix.

Each of these matrices is defined to have a special structure. The matrices U and V are both defined to be orthogonal matrices. The matrix D is defined to be a diagonal matrix. Note that D is not necessarily square.

The elements along the diagonal of D are known as the **singular values** of the matrix A. The columns of U are known as the **left-singular vectors**. The columns of V are known as as the **right-singular vectors**.

We can actually interpret the singular value decomposition of \boldsymbol{A} in terms of the eigendecomposition of functions of \boldsymbol{A} . The left-singular vectors of \boldsymbol{A} are the eigenvectors of $\boldsymbol{A}\boldsymbol{A}^{\top}$. The right-singular vectors of \boldsymbol{A} are the eigenvectors of $\boldsymbol{A}^{\top}\boldsymbol{A}$. The non-zero singular values of \boldsymbol{A} are the square roots of the eigenvalues of $\boldsymbol{A}^{\top}\boldsymbol{A}$. The same is true for $\boldsymbol{A}\boldsymbol{A}^{\top}$.

Perhaps the most useful feature of the SVD is that we can use it to partially generalize matrix inversion to non-square matrices, as we will see in the next section.

2.9 The Moore-Penrose Pseudoinverse

Matrix inversion is not defined for matrices that are not square. Suppose we want to make a left-inverse B of a matrix A, so that we can solve a linear equation

$$Ax = y \tag{2.44}$$