

Contents

1 Basic	1	8 Geometry	17
1.1 vimrc	1	8.1 Basic	17
1.2 Fast Integer Input	1	8.2 KD Tree	18
1.3 Increase stack size	1	8.3 Delaunay Triangulation	18
1.4 Pragma optimization	1	8.4 Sector Area	19
2 Flow, Matching	2	8.5 Half Plane Intersection	19
2.1 Dinic's Algorithm	2	8.6 Rotating Sweep Line	19
2.2 Minimum-cost flow	2	8.7 Triangle Center	19
2.3 Gomory-Hu Tree	2	8.8 Polygon Center	19
2.4 Stoer-Wagner Minimum Cut	2	8.9 Maximum Triangle	19
2.5 Kuhn-Munkres Algorithm	3	8.10 Point in Polygon	20
2.6 Flow Model	3	8.11 Circle	20
3 Data Structure	3	8.12 Tangent of Circles and Points to Circle	20
3.1 <ext/pbds>	3	8.13 Area of Union of Circles	20
3.2 Li Chao Tree	4	8.14 Minimum Distance of 2 Polygons	21
3.3 Link-Cut Tree	4	8.15 2D Convex Hull	21
4 Graph	4	8.16 3D Convex Hull	22
4.1 Heavy-Light Decomposition	4	8.17 Minimum Enclosing Circle	22
4.2 Centroid Decomposition	5	8.18 Closest Pair	22
4.3 Minimum Mean Cycle	5	9 Miscellaneous	22
4.4 Minimum Steiner Tree	5	9.1 Bitwise Hack	22
4.5 Directed Minimum Spanning Tree	5	9.2 Hilbert's Curve (faster Mo's algorithm)	23
4.6 Maximum Matching on General Graph	6	9.3 Java	23
4.7 Maximum Weighted Matching on General Graph	6	9.4 Dancing Links	23
4.8 Maximum Clique	8	9.5 Offline Dynamic MST	23
4.9 Tarjan's Algorithm	8	9.6 Manhattan Distance MST	24
4.10 Dominator Tree	8	9.7 IOI 2016 Alien trick	24
4.11 Virtual Tree	9	1 Basic	
4.12 System of Difference Constraints	9	1.1 vimrc	
5 String	9	se nu rnu bs=2 ru mouse=a cin et ts=4 sw=4 sts=4	
5.1 Knuth-Morris-Pratt Algorithm	9	syn on	
5.2 Z Algorithm	9	colo desert	
5.3 Manacher's Algorithm	9	filetype indent on	
5.4 Aho-Corasick Automaton	9	inoremap {<CR> {<CR>}<Esc>0	
5.5 Suffix Automaton	10	1.2 Fast Integer Input	
5.6 Suffix Array	10	inline int gtx() {	
5.7 Lexicographically Smallest Rotation	11	const int N = 4096;	
6 Math	11	static char buffer[N];	
6.1 Fast Fourier Transform	11	static char *p = buffer, *end = buffer;	
6.2 Number Theoretic Transform	11	if (p == end) {	
6.2.1 NTT Prime List	12	if ((end = buffer + fread(buffer, 1, N, stdin)) == buffer)	
6.3 Polynomial Division	12	return EOF;	
6.4 Polynomial Square Root	12	p = buffer;	
6.5 Multipoint Evaluation	12	}	
6.6 Polynomial Interpolation	13	return *p++;	
6.7 Fast Walsh-Hadamard Transform	13	}	
6.7.1 XOR Convolution	13	template <typename T>	
6.7.2 OR Convolution	13	inline bool rit(T& x) {	
6.7.3 AND Convolution	13	char c = 0; bool flag = false;	
6.8 Simplex Algorithm	13	while (c = getchar(), (c < '0' && c != '-') c > '9') if (c	
6.8.1 Construction	13	== -1) return false;	
6.9 Schreier-Sims Algorithm	13	c == '-' ? (flag = true, x = 0) : (x = c - '0');	
6.10 Berlekamp-Massey Algorithm	14	while (c = getchar(), c >= '0' && c <= '9') x = x * 10 + c -	
6.11 Miller Rabin	14	'0';	
6.12 Pollard's Rho	14	if (flag) x = -x;	
6.13 Meissel-Lehmer Algorithm	15	return true;	
6.14 Discrete Logarithm	15	}	
6.15 Quadratic Residue	15		
6.16 Gaussian Elimination	15	1.3 Increase stack size	
6.17 μ function	15	const int size = 256 << 20;	
6.18 Partition Function	16	register long rsp asm("rsp");	
6.19 $\lfloor \frac{n}{i} \rfloor$ Enumeration	16	char *p = (char*)malloc(size) + size, *bak = (char*)rsp;	
6.20 De Bruijn Sequence	16	__asm__("movq %0, %%rsp\n:::r"(p));	
6.21 Extended GCD	16	// main	
6.22 Euclidean Algorithms	16	__asm__("movq %0, %%rsp\n:::r"(bak));	
6.23 Chinese Remainder Theorem	16	1.4 Pragma optimization	
6.24 Theorem	16	#pragma GCC optimize("Ofast", "no-stack-protector", "no-math-	
6.24.1 Kirchhoff's Theorem	16	errno", "unroll-loops")	
6.24.2 Tutte's Matrix	16	#pragma GCC target("sse,sse2,sse3,ssse3,sse4,sse4.2,popcnt,abm,	
6.24.3 Cayley's Formula	17	mmx,avx,tune=native,arch=core-avx2,tune=core-avx2")	
6.24.4 Erdős-Gallai Theorem	17	#pragma GCC ivdep	
6.25 Primes	17		
7 Dynamic Programming	17		
7.1 Dynamic Convex Hull	17		
7.2 1D/1D Convex Optimization	17		
7.3 Condition	17		
7.3.1 Totally Monotone (Concave/Convex)	17		
7.3.2 Monge Condition (Concave/Convex)	17		
7.3.3 Optimal Split Point	17		

2 Flow, Matching

2.1 Dinic's Algorithm

```
struct dinic {
    static const int inf = 1e9;
    struct edge {
        int to, cap, rev;
        edge(int d, int c, int r): to(d), cap(c), rev(r) {}
    };
    vector<edge> g[maxn];
    int qu[maxn], ql, qr;
    int lev[maxn];
    void init() {
        for (int i = 0; i < maxn; ++i)
            g[i].clear();
    }
    void add_edge(int a, int b, int c) {
        g[a].emplace_back(b, c, g[b].size() - 0);
        g[b].emplace_back(a, 0, g[a].size() - 1);
    }
    bool bfs(int s, int t) {
        memset(lev, -1, sizeof(lev));
        lev[s] = 0;
        ql = qr = 0;
        qu[qr++] = s;
        while (ql < qr) {
            int x = qu[ql++];
            for (edge &e : g[x]) if (lev[e.to] == -1 && e.cap > 0) {
                lev[e.to] = lev[x] + 1;
                qu[qr++] = e.to;
            }
        }
        return lev[t] != -1;
    }
    int dfs(int x, int t, int flow) {
        if (x == t) return flow;
        int res = 0;
        for (edge &e : g[x]) if (e.cap > 0 && lev[e.to] == lev[x] + 1) {
            int f = dfs(e.to, t, min(e.cap, flow - res));
            res += f;
            e.cap -= f;
            g[e.to][e.rev].cap += f;
        }
        if (res == 0) lev[x] = -1;
        return res;
    }
    int operator()(int s, int t) {
        int flow = 0;
        for (; bfs(s, t); flow += dfs(s, t, inf));
        return flow;
    }
};
```

2.2 Minimum-cost flow

```
struct mincost {
    struct edge {
        int dest, cap, w, rev;
        edge(int a, int b, int c, int d): dest(a), cap(b), w(c), rev(d) {}
    };
    vector<edge> g[maxn];
    int d[maxn], p[maxn], ed[maxn];
    bool inq[maxn];
    void init() {
        for (int i = 0; i < maxn; ++i) g[i].clear();
    }
    void add_edge(int a, int b, int c, int d) {
        g[a].emplace_back(b, c, +d, g[b].size() - 0);
        g[b].emplace_back(a, 0, -d, g[a].size() - 1);
    }
    bool spfa(int s, int t, int &f, int &c) {
        for (int i = 0; i < maxn; ++i) {
            d[i] = inf;
            p[i] = ed[i] = -1;
            inq[i] = false;
        }
        d[s] = 0;
        queue<int> q;
        q.push(s);
```

```
while (q.size()) {
    int x = q.front(); q.pop();
    inq[x] = false;
    for (int i = 0; i < g[x].size(); ++i) {
        edge &e = g[x][i];
        if (e.cap > 0 && d[e.dest] > d[x] + e.w) {
            d[e.dest] = d[x] + e.w;
            p[e.dest] = x;
            ed[e.dest] = i;
            if (!inq[e.dest]) q.push(e.dest), inq[e.dest] = true;
        }
    }
}
if (d[t] == inf) return false;
int dlt = inf;
for (int x = t; x != s; x = p[x]) dlt = min(dlt, g[p[x]][ed[x]].cap);
for (int x = t; x != s; x = p[x]) {
    edge &e = g[p[x]][ed[x]];
    e.cap -= dlt;
    g[e.dest][e.rev].cap += dlt;
}
f += dlt; c += d[t] * dlt;
return true;
}
pair<int, int> operator()(int s, int t) {
    int f = 0, c = 0;
    while (spfa(s, t, f, c));
    return make_pair(f, c);
}
```

2.3 Gomory-Hu Tree

```
int g[maxn];
vector<edge> GomoryHu(int n){
    vector<edge> rt;
    for(int i=1;i<=n;++i)g[i]=1;
    for(int i=2;i<=n;++i){
        int t=g[i];
        flow.reset(); // clear flows on all edge
        rt.push_back({i,t,flow(i,t)});
        flow.walk(i); // bfs points that connected to i (use edges not fully flow)
        for(int j=i+1;j<=n;++j){
            if(g[j]==t && flow.connect(j))g[j]=i; // check if i can reach j
        }
    }
    return rt;
}
```

2.4 Stoer-Wagner Minimum Cut

```
const int maxn = 500 + 5;
int w[maxn][maxn], g[maxn];
bool v[maxn], del[maxn];
void add_edge(int x, int y, int c) {
    w[x][y] += c;
    w[y][x] += c;
}
pair<int, int> phase(int n) {
    memset(v, false, sizeof(v));
    memset(g, 0, sizeof(g));
    int s = -1, t = -1;
    while (true) {
        int c = -1;
        for (int i = 0; i < n; ++i) {
            if (del[i] || v[i]) continue;
            if (c == -1 || g[i] > g[c]) c = i;
        }
        if (c == -1) break;
        v[c] = true;
        s = t, t = c;
        for (int i = 0; i < n; ++i) {
            if (del[i] || v[i]) continue;
            g[i] += w[c][i];
        }
    }
    return make_pair(s, t);
}
int mincut(int n) {
```

```

int cut = 1e9;
memset(del, false, sizeof(del));
for (int i = 0; i < n - 1; ++i) {
    int s, t; tie(s, t) = phase(n);
    del[t] = true;
    cut = min(cut, g[t]);
    for (int j = 0; j < n; ++j) {
        w[s][j] += w[t][j];
        w[j][s] += w[j][t];
    }
}
return cut;
}

```

2.5 Kuhn–Munkres Algorithm

```

int w[maxn][maxn], lx[maxn], ly[maxn];
int match[maxn], slack[maxn];
bool vx[maxn], vy[maxn];
bool dfs(int x) {
    vx[x] = true;
    for (int i = 0; i < n; ++i) {
        if (vy[i]) continue;
        if (lx[x] + ly[i] > w[x][i]) {
            slack[i] = min(slack[i], lx[x] + ly[i] - w[x][i]);
            continue;
        }
        vy[i] = true;
        if (match[i] == -1 || dfs(match[i])) {
            match[i] = x;
            return true;
        }
    }
    return false;
}
int solve() {
    fill_n(match, n, -1);
    fill_n(lx, n, -inf);
    fill_n(ly, n, 0);
    for (int i = 0; i < n; ++i) {
        for (int j = 0; j < n; ++j) lx[i] = max(lx[i], w[i][j]);
    }
    for (int i = 0; i < n; ++i) {
        fill_n(slack, n, inf);
        while (true) {
            fill_n(vx, n, false);
            fill_n(vy, n, false);
            if (dfs(i)) break;
            int dlt = inf;
            for (int j = 0; j < n; ++j) if (!vy[j]) dlt = min(dlt, slack[j]);
            for (int j = 0; j < n; ++j) {
                if (vx[j]) lx[j] -= dlt;
                if (vy[j]) ly[j] += dlt;
                else slack[j] -= dlt;
            }
        }
    }
    int res = 0;
    for (int i = 0; i < n; ++i) res += w[match[i]][i];
    return res;
}

```

2.6 Flow Model

- Maximum/Minimum flow with lower/upper bound from s to t

- Construct super source S and sink T
- For each edge (x, y, l, u) , connect $x \rightarrow y$ with capacity $u - l$
- For each vertex v , denote $in(v)$ as the difference between the sum of incoming lower bounds and the sum of outgoing lower bounds
- If $in(v) > 0$, connect $S \rightarrow v$ with capacity $in(v)$, otherwise, connect $v \rightarrow T$ with capacity $-in(v)$
 - To maximize, connect $t \rightarrow s$ with capacity ∞ , and let f be the maximum flow from S to T . If $f \neq \sum_{v \in V, in(v) > 0} in(v)$, there's no solution. Otherwise, the maximum flow from s to t is the answer.
 - To minimize, let f be the maximum flow from S to T . Connect $t \rightarrow s$ with capacity ∞ and let the flow from S to T be f' . If $f + f' \neq \sum_{v \in V, in(v) > 0} in(v)$, there's no solution. Otherwise, f' is the answer.

- The solution of each edge e is $l_e + f_e$, where f_e corresponds to the flow on the graph

- Construct minimum vertex cover from maximum matching M on bipartite graph (X, Y)

- Redirect every edge $(y \rightarrow x$ if $(x, y) \in M$, $x \rightarrow y$ otherwise)
- DFS from unmatched vertices in X
- $x \in X$ is chosen iff x is unvisited
- $y \in Y$ is chosen iff y is visited

- Minimum cost cyclic flow

- Construct super source S and sink T
- For each edge (x, y, c) , connect $x \rightarrow y$ with $(cost, cap) = (c, 1)$ if $c > 0$, otherwise connect $y \rightarrow x$ with $(cost, cap) = (-c, 1)$
- For each edge with $c < 0$, sum these cost as K , then increase $d(y)$ by 1, decrease $d(x)$ by 1
- For each vertex v with $d(v) > 0$, connect $S \rightarrow v$ with $(cost, cap) = (0, d(v))$
- For each vertex v with $d(v) < 0$, connect $v \rightarrow T$ with $(cost, cap) = (0, -d(v))$
- Flow from S to T , the answer is the cost of the flow $C + K$

- Maximum density induced subgraph

- Binary search on answer, suppose we're checking answer T
- Construct a max flow model, let K be the sum of all weights
- Connect source $s \rightarrow v$, $v \in G$ with capacity K
- For each edge (u, v, w) in G , connect $u \rightarrow v$ and $v \rightarrow u$ with capacity w
- For $v \in G$, connect it with sink $v \rightarrow t$ with capacity $K + 2T - (\sum_{e \in E(v)} w(e)) - 2w(v)$
- T is a valid answer if the maximum flow $f < K|V|$

3 Data Structure

3.1 <ext/pbds>

```

#include <bits/stdc++.h>
#include <bits/extc++.h>
#include <ext/rope>
using namespace __gnu_pbds;
using namespace __gnu_cxx;
#include <ext/pb_ds/assoc_container.hpp>
typedef tree<int, null_type, std::less<int>, rb_tree_tag,
            tree_order_statistics_node_update> tree_set;
typedef cc_hash_table<int, int> umap;
typedef priority_queue<int> heap;

int main() {
    // rb tree
    tree_set s;
    s.insert(71); s.insert(22);
    assert(*s.find_by_order(0) == 22); assert(*s.find_by_order(1) == 71);
    assert(s.order_of_key(22) == 0); assert(s.order_of_key(71) == 1);
    s.erase(22);
    assert(*s.find_by_order(0) == 71); assert(s.order_of_key(71) == 0);
    // mergable heap
    heap a, b; a.join(b);
    // persistent
    rope<char> r[2];
    r[1] = r[0];
    std::string st = "abc";
    r[1].insert(0, st.c_str());
    r[1].erase(1, 1);
    std::cout << r[1].substr(0, 2) << std::endl;
    return 0;
}

```

3.2 Li Chao Tree

```
namespace lichao {
struct line {
    long long a, b;
    line(): a(0), b(0) {}
    line(long long a, long long b): a(a), b(b) {}
    long long operator()(int x) const { return a * x + b; }
};
line st[maxc * 4];
int sz, lc[maxc * 4], rc[maxc * 4];
int gnode() {
    st[sz] = line(1e9, 1e9);
    lc[sz] = -1, rc[sz] = -1;
    return sz++;
}
void init() {
    sz = 0;
}
void add(int l, int r, line tl, int o) {
    bool lcp = st[o](l) > tl(l);
    bool mcp = st[o]((l + r) / 2) > tl((l + r) / 2);
    if (mcp) swap(st[o], tl);
    if (r - l == 1) return;
    if (lcp != mcp) {
        if (lc[o] == -1) lc[o] = gnode();
        add(l, (l + r) / 2, tl, lc[o]);
    } else {
        if (rc[o] == -1) rc[o] = gnode();
        add((l + r) / 2, r, tl, rc[o]);
    }
}
long long query(int l, int r, int x, int o) {
    if (r - l == 1) return st[o](x);
    if (x < (l + r) / 2) {
        if (lc[o] == -1) return st[o](x);
        return min(st[o](x), query(l, (l + r) / 2, x, lc[o]));
    } else {
        if (rc[o] == -1) return st[o](x);
        return min(st[o](x), query((l + r) / 2, r, x, rc[o]));
    }
}
}
```

3.3 Link-Cut Tree

```
struct node {
    node *ch[2], *fa, *pfa;
    int sum, v, rev, id;
    node(int s, int id): id(id), v(s), sum(s), rev(0), fa(nullptr), pfa(nullptr) {
        ch[0] = nullptr;
        ch[1] = nullptr;
    }
    int relation() {
        return this == fa->ch[0] ? 0 : 1;
    }
    void push() {
        if (!rev) return;
        swap(ch[0], ch[1]);
        if (ch[0]) ch[0]->rev ^= 1;
        if (ch[1]) ch[1]->rev ^= 1;
        rev = 0;
    }
    void pull() {
        sum = v;
        if (ch[0]) sum += ch[0]->sum;
        if (ch[1]) sum += ch[1]->sum;
    }
    void rotate() {
        if (fa->fa) fa->fa->push();
        fa->push(), push(), swap(pfa, fa->pfa);
        int d = relation();
        node *t = fa;
        if (t->fa) t->fa->ch[t->relation()] = this;
        fa = t->fa, t->ch[d] = ch[d ^ 1];
        if (ch[d ^ 1]) ch[d ^ 1]->fa = t;
        ch[d ^ 1] = t, t->fa = this;
        t->pull(), pull();
    }
    void splay() {
        while (fa) {
            if (!fa->fa) {
                rotate();
                continue;
            }
            if (fa->relation() == fa->fa->relation()) fa->rotate(), rotate();
            else rotate(), rotate();
        }
        void evert() { access(), splay(), rev ^= 1; }
        void expose() {
            splay(), push();
            if (ch[1]) {
                ch[1]->fa = nullptr, ch[1]->pfa = this;
                ch[1] = nullptr, pull();
            }
        }
        bool splice() {
            splay();
            if (!pfa) return false;
            pfa->expose(), pfa->ch[1] = this, fa = pfa;
            pfa = nullptr, fa->pull();
            return true;
        }
        void access() {
            expose();
            while (splice());
        }
        int query() { return sum; }
    };
namespace lct {
node *sp[maxn];
void make(int u, int v) {
    // create node with id u and value v
    sp[u] = new node(v, u);
}
void link(int u, int v) {
    // u become v's parent
    sp[v]->evert();
    sp[v]->pfa = sp[u];
}
void cut(int u, int v) {
    // u was v's parent
    sp[u]->evert();
    sp[v]->access(), sp[v]->splay(), sp[v]->push();
    sp[v]->ch[0]->fa = nullptr;
    sp[v]->ch[0] = nullptr;
    sp[v]->pull();
}
void modify(int u, int v) {
    sp[u]->splay();
    sp[u]->v = v;
    sp[u]->pull();
}
int query(int u, int v) {
    sp[u]->evert(), sp[v]->access(), sp[v]->splay();
    return sp[v]->query();
}
int find(int u) {
    sp[u]->access();
    sp[u]->splay();
    node *p = sp[u];
    while (true) {
        p->push();
        if (p->ch[0]) p = p->ch[0];
        else break;
    }
    return p->id;
}
}
```

```

    }
    fa->fa->push(), fa->push();
    if (relation() == fa->relation()) fa->rotate(), rotate();
    else rotate(), rotate();
}
}
void evert() { access(), splay(), rev ^= 1; }
void expose() {
    splay(), push();
    if (ch[1]) {
        ch[1]->fa = nullptr, ch[1]->pfa = this;
        ch[1] = nullptr, pull();
    }
}
bool splice() {
    splay();
    if (!pfa) return false;
    pfa->expose(), pfa->ch[1] = this, fa = pfa;
    pfa = nullptr, fa->pull();
    return true;
}
void access() {
    expose();
    while (splice());
}
int query() { return sum; }
};
namespace lct {
node *sp[maxn];
void make(int u, int v) {
    // create node with id u and value v
    sp[u] = new node(v, u);
}
void link(int u, int v) {
    // u become v's parent
    sp[v]->evert();
    sp[v]->pfa = sp[u];
}
void cut(int u, int v) {
    // u was v's parent
    sp[u]->evert();
    sp[v]->access(), sp[v]->splay(), sp[v]->push();
    sp[v]->ch[0]->fa = nullptr;
    sp[v]->ch[0] = nullptr;
    sp[v]->pull();
}
void modify(int u, int v) {
    sp[u]->splay();
    sp[u]->v = v;
    sp[u]->pull();
}
int query(int u, int v) {
    sp[u]->evert(), sp[v]->access(), sp[v]->splay();
    return sp[v]->query();
}
int find(int u) {
    sp[u]->access();
    sp[u]->splay();
    node *p = sp[u];
    while (true) {
        p->push();
        if (p->ch[0]) p = p->ch[0];
        else break;
    }
    return p->id;
}
}
```

4 Graph

4.1 Heavy-Light Decomposition

```
void dfs(int x, int p) {
    dep[x] = ~p ? dep[p] + 1 : dep[x];
    sz[x] = 1;
    to[x] = -1;
    fa[x] = p;
    for (const int &u : g[x]) {
        if (u == p) continue;
        dfs(u, x);
        sz[x] += sz[u];
        if (to[x] == -1 || sz[to[x]] < sz[u]) to[x] = u;
    }
}
```

```

}
void hld(int x, int t) {
    static int tk = 0;
    fr[x] = t;
    dfn[x] = tk++;
    if (!to[x]) return;
    hld(to[x], t);
    for (const int &u : g[x]) {
        if (u == fa[x] || u == to[x]) continue;
        hld(u, u);
    }
}
vector<pair<int, int>> get(int x, int y) {
    int fx = fr[x], fy = fr[y];
    vector<pair<int, int>> res;
    while (fx != fy) {
        if (dep[fx] < dep[fy]) {
            swap(fx, fy);
            swap(x, y);
        }
        res.emplace_back(dfn[fx], dfn[x] + 1);
        x = fa[fx];
        fx = fr[x];
    }
    res.emplace_back(min(dfn[x], dfn[y]), max(dfn[x], dfn[y]) + 1);
    int lca = (dep[x] < dep[y] ? x : y);
    return res;
}

```

4.2 Centroid Decomposition

```

void get_center(int now) {
    v[now] = true; vtx.push_back(now);
    sz[now] = 1; mx[now] = 0;
    for (int u : G[now]) if (!v[u]) {
        get_center(u);
        mx[now] = max(mx[now], sz[u]);
        sz[now] += sz[u];
    }
}
void get_dis(int now, int d, int len) {
    dis[d][now] = cnt;
    v[now] = true;
    for (auto u : G[now]) if (!v[u.first]) {
        get_dis(u, d, len + u.second);
    }
}
void dfs(int now, int fa, int d) {
    get_center(now);
    int c = -1;
    for (int i : vtx) {
        if (max(mx[i], (int)vtx.size() - sz[i]) <= (int)vtx.size() / 2) c = i;
        v[i] = false;
    }
    get_dis(c, d, 0);
    for (int i : vtx) v[i] = false;
    v[c] = true; vtx.clear();
    dep[c] = d; p[c] = fa;
    for (auto u : G[c]) if (u.first != fa && !v[u.first]) {
        dfs(u.first, c, d + 1);
    }
}

```

4.3 Minimum Mean Cycle

```

// d[i][j] == 0 if {i,j} !in E
long long d[1003][1003], dp[1003][1003];

pair<long long, long long> MMWC() {
    memset(dp, 0x3f, sizeof(dp));
    for (int i = 1; i <= n; ++i) dp[0][i] = 0;
    for (int i = 1; i <= n; ++i) {
        for (int j = 1; j <= n; ++j) {
            for (int k = 1; k <= n; ++k) {
                dp[i][k] = min(dp[i-1][j] + d[j][k], dp[i][k]);
            }
        }
    }
    long long au = 1ll << 31, ad = 1;
    for (int i = 1; i <= n; ++i) {

```

```

        if (dp[n][i] == 0x3f3f3f3f3f3f3f3f) continue;
        long long u = 0, d = 1;
        for (int j = n - 1; j >= 0; --j) {
            if ((dp[n][i] - dp[j][i]) * d > u * (n - j)) {
                u = dp[n][i] - dp[j][i];
                d = n - j;
            }
        }
        if (u * ad < au * d) au = u, ad = d;
    }
    long long g = __gcd(ad, au);
    return make_pair(ad/g, au/g);
}

```

4.4 Minimum Steiner Tree

```

namespace steiner {
    // Minimum Steiner Tree - O(N * 3^K + N^2 * 2^K)
    // z[i] = the weight of the i-th vertex
    const int maxn = 64, maxk = 10;
    const int inf = 1e9;
    int w[maxn][maxn], z[maxn], dp[1 << maxk][maxn], off[maxn];
    void init(int n) {
        for (int i = 0; i < n; ++i) {
            for (int j = 0; j < n; ++j) w[i][j] = inf;
            z[i] = 0;
            w[i][i] = 0;
        }
    }
    void add_edge(int x, int y, int d) {
        w[x][y] = min(w[x][y], d);
        w[y][x] = min(w[y][x], d);
    }
    void build(int n) {
        for (int i = 0; i < n; ++i) {
            for (int j = 0; j < n; ++j) {
                w[i][j] += z[i];
                if (i != j) w[i][j] += z[j];
            }
        }
        for (int k = 0; k < n; ++k) {
            for (int i = 0; i < n; ++i) {
                for (int j = 0; j < n; ++j) w[i][j] = min(w[i][j], w[i][k] + w[k][j] - z[k]);
            }
        }
    }
    int solve(int n, vector<int> mark) {
        build(n);
        int k = (int)mark.size();
        assert(k < maxk);
        for (int s = 0; s < (1 << k); ++s) {
            for (int i = 0; i < n; ++i) dp[s][i] = inf;
        }
        for (int i = 0; i < n; ++i) dp[0][i] = 0;
        for (int s = 1; s < (1 << k); ++s) {
            if (__builtin_popcount(s) == 1) {
                int x = __builtin_ctz(s);
                for (int i = 0; i < n; ++i) dp[s][i] = w[mark[x]][i];
                continue;
            }
            for (int i = 0; i < n; ++i) {
                for (int sub = s & (s - 1); sub; sub = s & (sub - 1)) {
                    dp[s][i] = min(dp[s][i], dp[sub][i] + dp[s ^ sub][i] - z[i]);
                }
            }
            for (int i = 0; i < n; ++i) {
                off[i] = inf;
                for (int j = 0; j < n; ++j) off[i] = min(off[i], dp[s][j] + w[j][i] - z[j]);
            }
            for (int i = 0; i < n; ++i) dp[s][i] = min(dp[s][i], off[i]);
        }
        int res = inf;
        for (int i = 0; i < n; ++i) res = min(res, dp[(1 << k) - 1][i]);
        return res;
    }
}

```

4.5 Directed Minimum Spanning Tree

```

template <typename T> struct DMST {
    T g[maxn][maxn], fw[maxn];
    int n, fr[maxn];
    bool vis[maxn], inc[maxn];
    void clear() {
        for(int i = 0; i < maxn; ++i) {
            for(int j = 0; j < maxn; ++j) g[i][j] = inf;
            vis[i] = inc[i] = false;
        }
    }
    void addedge(int u, int v, T w) {
        g[u][v] = min(g[u][v], w);
    }
    T operator()(int root, int _n) {
        n = _n;
        if (dfs(root) != n) return -1;
        T ans = 0;
        while (true) {
            for (int i = 1; i <= n; ++i) fw[i] = inf, fr[i] = i;
            for (int i = 1; i <= n; ++i) if (!inc[i]) {
                for (int j = 1; j <= n; ++j) {
                    if (!inc[j] && i != j && g[j][i] < fw[i]) {
                        fw[i] = g[j][i];
                        fr[i] = j;
                    }
                }
            }
            int x = -1;
            for (int i = 1; i <= n; ++i) if (i != root && !inc[i]) {
                int j = i, c = 0;
                while (j != root && fr[j] != i && c <= n) ++c, j = fr[j];
            }
            if (j == root || c > n) continue;
            else { x = i; break; }
            if (!x) {
                for (int i = 1; i <= n; ++i) if (i != root && !inc[i])
                    ans += fw[i];
                return ans;
            }
            int y = x;
            for (int i = 1; i <= n; ++i) vis[i] = false;
            do { ans += fw[y]; y = fr[y]; vis[y] = inc[y] = true; }
            while (y != x);
            inc[x] = false;
            for (int k = 1; k <= n; ++k) if (vis[k]) {
                for (int j = 1; j <= n; ++j) if (!vis[j]) {
                    if (g[x][j] > g[k][j]) g[x][j] = g[k][j];
                    if (g[j][k] < inf && g[j][k] - fw[k] < g[j][x]) g[j][x] = g[j][k] - fw[k];
                }
            }
        }
        return ans;
    }
    int dfs(int now) {
        int r = 1;
        vis[now] = true;
        for (int i = 1; i <= n; ++i) if (g[now][i] < inf && !vis[i])
            r += dfs(i);
        return r;
    }
};

tk++;
x = find(x), y = find(y);
for (; ; swap(x, y)) {
    if (x != n) {
        if (v[x] == tk) return x;
        v[x] = tk;
        x = find(pre[match[x]]);
    }
}
}
void blossom(int x, int y, int l) {
    while (find(x) != l) {
        pre[x] = y;
        y = match[x];
        if (s[y] == 1) {
            q.push(y);
            s[y] = 0;
        }
        if (fa[x] == x) fa[x] = l;
        if (fa[y] == y) fa[y] = l;
        x = pre[y];
    }
}
bool bfs(int r, int n) {
    for (int i = 0; i <= n; ++i) {
        fa[i] = i;
        s[i] = -1;
    }
    while (!q.empty()) q.pop();
    q.push(r);
    s[r] = 0;
    while (!q.empty()) {
        int x = q.front(); q.pop();
        for (int u : g[x]) {
            if (s[u] == -1) {
                pre[u] = x;
                s[u] = 1;
                if (match[u] == n) {
                    for (int a = u, b = x, last; b != n; a = last, b = pre[a])
                        last = match[b], match[b] = a, match[a] = b;
                    return true;
                }
                q.push(match[u]);
                s[match[u]] = 0;
            } else if (!s[u] && find(u) != find(x)) {
                int l = lca(u, x, n);
                blossom(x, u, l);
                blossom(u, x, l);
            }
        }
    }
    return false;
}
int solve(int n) {
    int res = 0;
    for (int x = 0; x < n; ++x) {
        if (match[x] == n) res += bfs(x, n);
    }
    return res;
}
}
}

```

4.6 Maximum Matching on General Graph

```

namespace matching {
    int fa[maxn], pre[maxn], match[maxn], s[maxn], v[maxn];
    vector<int> g[maxn];
    queue<int> q;
    void init(int n) {
        for (int i = 0; i <= n; ++i) match[i] = pre[i] = n;
        for (int i = 0; i < n; ++i) g[i].clear();
    }
    void add_edge(int u, int v) {
        g[u].push_back(v);
        g[v].push_back(u);
    }
    int find(int u) {
        if (u == fa[u]) return u;
        return fa[u] = find(fa[u]);
    }
    int lca(int x, int y, int n) {
        static int tk = 0;

```

4.7 Maximum Weighted Matching on General Graph

```

struct WeightGraph {
    static const int inf = INT_MAX;
    static const int maxn = 514;
    struct edge {
        int u, v, w;
        edge(){}
        edge(int u, int v, int w): u(u), v(v), w(w) {}
    };
    int n, n_x;
    edge g[maxn * 2][maxn * 2];
    int lab[maxn * 2];
    int match[maxn * 2], slack[maxn * 2], st[maxn * 2], pa[maxn * 2];
    int flo_from[maxn * 2][maxn + 1], S[maxn * 2], vis[maxn * 2];
    vector<int> flo[maxn * 2];
    queue<int> q;
    int e_delta(const edge &e) {
        return lab[e.u] + lab[e.v] - g[e.u][e.v].w * 2;
    }
};

```



```

}
void update_slack(int u, int x) {
    if (!slack[x] || e_delta(g[u][x]) < e_delta(g[slack[x]][x]))
        slack[x] = u;
}
void set_slack(int x) {
    slack[x] = 0;
    for (int u = 1; u <= n; ++u)
        if (g[u][x].w > 0 && st[u] != x && S[st[u]] == 0)
            update_slack(u, x);
}
void q_push(int x) {
    if (x <= n) q.push(x);
    else for (size_t i = 0; i < flo[x].size(); ++i) q.push(flo[x][i]);
}
void set_st(int x, int b) {
    st[x] = b;
    if (x > n) for (size_t i = 0; i < flo[x].size(); ++i)
        set_st(flo[x][i], b);
}
int get_pr(int b, int xr) {
    int pr = find(flo[b].begin(), flo[b].end(), xr) - flo[b].begin();
    if (pr % 2 == 1) {
        reverse(flo[b].begin() + 1, flo[b].end());
        return (int)flo[b].size() - pr;
    }
    return pr;
}
void set_match(int u, int v) {
    match[u] = g[u][v].v;
    if (u <= n) return;
    edge e = g[u][v];
    int xr = flo_from[u][e.u], pr = get_pr(u, xr);
    for (int i = 0; i < pr; ++i) set_match(flo[u][i], flo[u][i ^ 1]);
    set_match(xr, v);
    rotate(flo[u].begin(), flo[u].begin() + pr, flo[u].end());
}
void augment(int u, int v) {
    for (; ; ) {
        int xnv = st[match[u]];
        set_match(u, v);
        if (!xnv) return;
        set_match(xnv, st[pa[xnv]]);
        u = st[pa[xnv]], v = xnv;
    }
}
int get_lca(int u, int v) {
    static int t = 0;
    for (++t; u || v; swap(u, v)) {
        if (u == 0) continue;
        if (vis[u] == t) return u;
        vis[u] = t;
        u = st[match[u]];
        if (u) u = st[pa[u]];
    }
    return 0;
}
void add_blossom(int u, int lca, int v) {
    int b = n + 1;
    while (b <= n_x && st[b]) ++b;
    if (b > n_x) ++n_x;
    lab[b] = 0, S[b] = 0;
    match[b] = match[lca];
    flo[b].clear();
    flo[b].push_back(lca);
    for (int x = u, y; x != lca; x = st[pa[y]])
        flo[b].push_back(x), flo[b].push_back(y = st[match[x]]),
        q_push(y);
    reverse(flo[b].begin() + 1, flo[b].end());
    for (int x = v, y; x != lca; x = st[pa[y]])
        flo[b].push_back(x), flo[b].push_back(y = st[match[x]]),
        q_push(y);
    set_st(b, b);
    for (int x = 1; x <= n_x; ++x) g[b][x].w = g[x][b].w = 0;
    for (int x = 1; x <= n; ++x) flo_from[b][x] = 0;
    for (size_t i = 0; i < flo[b].size(); ++i) {
        int xs = flo[b][i];
        for (int x = 1; x <= n_x; ++x)
            if (g[b][x].w == 0 || e_delta(g[xs][x]) < e_delta(g[b][x]))
                g[b][x] = g[xs][x], g[x][b] = g[x][xs];
        for (int x = 1; x <= n; ++x)
            if (flo_from[xs][x]) flo_from[b][x] = xs;
    }
    set_slack(b);
}
void expand_blossom(int b) {
    for (size_t i = 0; i < flo[b].size(); ++i)
        set_st(flo[b][i], flo[b][i]);
    int xr = flo_from[b][g[b][pa[b]].u], pr = get_pr(b, xr);
    for (int i = 0; i < pr; i += 2) {
        int xs = flo[b][i], xns = flo[b][i + 1];
        pa[xs] = g[xns][xs].u;
        S[xs] = 1, S[xns] = 0;
        slack[xs] = 0, set_slack(xns);
        q_push(xns);
    }
    S[xr] = 1, pa[xr] = pa[b];
    for (size_t i = pr + 1; i < flo[b].size(); ++i) {
        int xs = flo[b][i];
        S[xs] = -1, set_slack(xs);
    }
    st[b] = 0;
}
bool on_found_edge(const edge &e) {
    int u = st[e.u], v = st[e.v];
    if (S[v] == -1) {
        pa[v] = e.u, S[v] = 1;
        int nu = st[match[v]];
        slack[v] = slack[nu] = 0;
        S[nu] = 0, q_push(nu);
    } else if (S[v] == 0) {
        int lca = get_lca(u, v);
        if (!lca) return augment(u, v), augment(v, u), true;
        else add_blossom(u, lca, v);
    }
    return false;
}
bool matching() {
    memset(S + 1, -1, sizeof(int) * n_x);
    memset(slack + 1, 0, sizeof(int) * n_x);
    q = queue<int>();
    for (int x = 1; x <= n_x; ++x)
        if (st[x] == x && !match[x]) pa[x] = 0, S[x] = 0, q.push(x);
    if (q.empty()) return false;
    for (; ; ) {
        while (q.size()) {
            int u = q.front(); q.pop();
            if (S[st[u]] == 1) continue;
            for (int v = 1; v <= n; ++v)
                if (g[u][v].w > 0 && st[u] != st[v]) {
                    if (e_delta(g[u][v]) == 0) {
                        if (on_found_edge(g[u][v])) return true;
                    } else update_slack(u, st[v]);
                }
        }
        int d = inf;
        for (int b = n + 1; b <= n_x; ++b)
            if (st[b] == b && S[b] == 1) d = min(d, lab[b] / 2);
        for (int x = 1; x <= n_x; ++x)
            if (st[x] == x && slack[x]) {
                if (S[x] == -1) d = min(d, e_delta(g[slack[x]][x]));
                else if (S[x] == 0) d = min(d, e_delta(g[slack[x]][x]) / 2);
            }
        for (int u = 1; u <= n; ++u) {
            if (S[st[u]] == 0) {
                if (lab[u] <= d) return 0;
                lab[u] -= d;
            } else if (S[st[u]] == 1) lab[u] += d;
        }
        for (int b = n + 1; b <= n_x; ++b)
            if (st[b] == b) {
                if (S[st[b]] == 0) lab[b] += d * 2;
                else if (S[st[b]] == 1) lab[b] -= d * 2;
            }
        q = queue<int>();
        for (int x = 1; x <= n_x; ++x)
            if (st[x] == x && slack[x] && st[slack[x]] != x &&
                e_delta(g[slack[x]][x]) == 0)
                if (on_found_edge(g[slack[x]][x])) return true;
        for (int b = n + 1; b <= n_x; ++b)
            if (st[b] == b && S[b] == 1 && lab[b] == 0)
                expand_blossom(b);
    }
    return false;
}
pair<long long, int> solve() {

```

```

memset(match + 1, 0, sizeof(int) * n);
n_x = n;
int n_matches = 0;
long long tot_weight = 0;
for (int u = 0; u <= n; ++u) st[u] = u, flo[u].clear();
int w_max = 0;
for (int u = 1; u <= n; ++u)
    for (int v = 1; v <= n; ++v) {
        flo_from[u][v] = (u == v ? u : 0);
        w_max = max(w_max, g[u][v].w);
    }
for (int u = 1; u <= n; ++u) lab[u] = w_max;
while (matching()) ++n_matches;
for (int u = 1; u <= n; ++u)
    if (match[u] && match[u] < u)
        tot_weight += g[u][match[u]].w;
return make_pair(tot_weight, n_matches);
}
void add_edge(int ui, int vi, int wi) {
    g[ui][vi].w = g[vi][ui].w = wi;
}
void init(int _n) {
    n = _n;
    for (int u = 1; u <= n; ++u)
        for (int v = 1; v <= n; ++v)
            g[u][v] = edge(u, v, 0);
}
};

```

4.8 Maximum Clique

```

struct MaxClique {
    // change to bitset for n > 64.
    int n, deg[maxn];
    uint64_t adj[maxn], ans;
    vector<pair<int, int>> edge;
    void init(int n_) {
        n = n_;
        fill(adj, adj + n, 0ull);
        fill(deg, deg + n, 0);
        edge.clear();
    }
    void add_edge(int u, int v) {
        edge.emplace_back(u, v);
        ++deg[u], ++deg[v];
    }
    vector<int> operator()() {
        vector<int> ord(n);
        iota(ord.begin(), ord.end(), 0);
        sort(ord.begin(), ord.end(), [&](int u, int v) { return deg[u] < deg[v]; });
        vector<int> id(n);
        for (int i = 0; i < n; ++i) id[ord[i]] = i;
        for (auto e : edge) {
            int u = id[e.first], v = id[e.second];
            adj[u] |= (1ull << v);
            adj[v] |= (1ull << u);
        }
        uint64_t r = 0, p = (1ull << n) - 1;
        ans = 0;
        dfs(r, p);
        vector<int> res;
        for (int i = 0; i < n; ++i) {
            if (ans >> i & 1) res.push_back(ord[i]);
        }
        return res;
    }
#define pcount __builtin_popcountll
    void dfs(uint64_t r, uint64_t p) {
        if (p == 0) {
            if (pcount(r) > pcount(ans)) ans = r;
            return;
        }
        if (pcount(r | p) <= pcount(ans)) return;
        int x = __builtin_ctzll(p & -p);
        uint64_t c = p & ~adj[x];
        while (c > 0) {
            // bitset._Find_first(); bitset._Find_next();
            x = __builtin_ctzll(c & -c);
            r |= (1ull << x);
            dfs(r, p & adj[x]);
            r &= ~(1ull << x);
            p &= ~(1ull << x);
            c ^= (1ull << x);
        }
    }
};

```

```

    }
}
};

```

4.9 Tarjan's Algorithm

```

void dfs(int x, int p) {
    dfn[x] = low[x] = tk++;
    int ch = 0;
    st.push(x); // bridge
    for (auto e : g[x]) if (e.first != p) {
        if (!ins[e.second]) { // articulation point
            st.push(e.second);
            ins[e.second] = true;
        }
        if (~dfn[e.first]) {
            low[x] = min(low[x], dfn[e.first]);
            continue;
        }
        dfs(e.first, x);
        if (low[e.first] >= low[x]) { // articulation point
            cut[x] = true;
            while (true) {
                int z = st.top(); st.pop();
                bcc[z] = sz;
                if (z == e.second) break;
            }
            sz++;
        }
    }
    if (ch == 1 && p == -1) cut[x] = false;
    if (dfn[x] == low[x]) { // bridge
        while (true) {
            int z = st.top(); st.pop();
            bcc[z] = sz;
            if (z == x) break;
        }
    }
}
}

```

4.10 Dominator Tree

```

namespace dominator {
    vector<int> g[maxn], r[maxn], rdom[maxn];
    int dfn[maxn], rev[maxn], fa[maxn], sdom[maxn], dom[maxn], val[
        maxn], rp[maxn], tk;
    void init(int n) {
        // vertices are numbered from 0 to n - 1
        fill(dfn, dfn + n, -1);
        fill(rev, rev + n, -1);
        fill(fa, fa + n, -1);
        fill(val, val + n, -1);
        fill(sdom, sdom + n, -1);
        fill(rp, rp + n, -1);
        fill(dom, dom + n, -1);
        tk = 0;
        for (int i = 0; i < n; ++i)
            g[i].clear();
    }
    void add_edge(int x, int y) {
        g[x].push_back(y);
    }
    void dfs(int x) {
        rev[dfn[x] = tk] = x;
        fa[tk] = sdom[tk] = val[tk] = tk;
        tk++;
        for (int u : g[x]) {
            if (dfn[u] == -1) dfs(u), rp[dfn[u]] = dfn[x];
            r[dfn[u]].push_back(dfn[x]);
        }
    }
    void merge(int x, int y) {
        fa[x] = y;
    }
    int find(int x, int c = 0) {
        if (fa[x] == x) return c ? -1 : x;
        int p = find(fa[x], 1);
        if (p == -1) return c ? fa[x] : val[x];
        if (sdom[val[x]] > sdom[val[fa[x]]]) val[x] = val[fa[x]];
        fa[x] = p;
        return c ? p : val[x];
    }
}

```



```
vector<int> build(int s, int n) {
    // return the father of each node in the dominator tree
    // p[i] = -2 if i is unreachable from s
    dfs(s);
    for (int i = tk - 1; i >= 0; --i) {
        for (int u : r[i]) sdom[i] = min(sdom[i], sdom[find(u)]);
        if (i) rdom[sdom[i]].push_back(i);
        for (int &u : rdom[i]) {
            int p = find(u);
            if (sdom[p] == i) dom[u] = i;
            else dom[u] = p;
        }
        if (i) merge(i, rp[i]);
    }
    vector<int> p(n, -2);
    p[s] = -1;
    for (int i = 1; i < tk; ++i) if (sdom[i] != dom[i]) dom[i] = dom[dom[i]];
    for (int i = 1; i < tk; ++i) p[rev[i]] = rev[dom[i]];
    return p;
}
```

4.11 Virtual Tree

```
void VirtualTree(vector<int> v) {
    static int stk[kn];
    int sz = 0;
    sort(v.begin(), v.end(), [&](int i, int j) { return dfn[i] < dfn[j]; });
    stk[sz++] = 0;
    for (int u : v) {
        if (u == 0) continue;
        int p = LCA(u, stk[sz - 1]);
        if (p != stk[sz - 1]) {
            while (sz >= 2 && dfn[p] < dfn[stk[sz - 2]]) {
                AddEdge(stk[sz - 2], stk[sz - 1]);
                --sz;
            }
            if (sz >= 2 && dfn[p] > dfn[stk[sz - 2]]) {
                AddEdge(p, stk[sz - 1]);
                stk[sz - 1] = p;
            } else {
                AddEdge(p, stk[--sz]);
            }
        }
        stk[sz++] = u;
    }
    for (int i = 0; i < sz - 1; ++i) AddEdge(stk[i], stk[i + 1]);
}
```

4.12 System of Difference Constraints

Given m constraints on n variables x_1, x_2, \dots, x_n of form $x_i - x_j \leq w$ (resp. $x_i - x_j \geq w$), connect $i \rightarrow j$ with weight w . Then connect $0 \rightarrow i$ for all i with weight 0 and find the shortest path (resp. longest path) on the graph. $dis(i)$ will be the maximum (resp. minimum) solution to x_i .

5 String

5.1 Knuth–Morris–Pratt Algorithm

```
vector<int> kmp(const string &s) {
    vector<int> f(s.size(), 0);
    // f[i] = length of the longest prefix (excluding s[0:i])
    // such that it coincides with the suffix of s[0:i] of the
    // same length
    // i + 1 - f[i] is the length of the smallest recurring
    // period of s[0:i]
    int k = 0;
    for (int i = 1; i < (int)s.size(); ++i) {
        while (k > 0 && s[i] != s[k]) k = f[k - 1];
        if (s[i] == s[k]) ++k;
        f[i] = k;
    }
    return f;
}

vector<int> search(const string &s, const string &t) {
    // return 0-indexed occurrence of t in s
    vector<int> f = kmp(t), res;
    int k = 0;
    for (int i = 0; i < (int)s.size(); ++i) {
        while (k > 0 && (k == (int)t.size() || s[i] != t[k])) k = f[k - 1];
        if (s[i] == t[k]) ++k;
        if (k == (int)t.size()) res.push_back(i - t.size() + 1);
    }
    return res;
}
```

5.2 Z Algorithm

```
int z[maxn];
// z[i] = LCP of suffix i and suffix 0
void z_function(const string& s) {
    memset(z, 0, sizeof(z));
    z[0] = (int)s.length();
    int l = 0, r = 0;
    for (int i = 1; i < s.length(); ++i) {
        z[i] = max(0, min(z[i - l], r - i + 1));
        while (i + z[i] < s.length() && s[z[i]] == s[i + z[i]]) {
            ++z[i];
        }
    }
}
```

5.3 Manacher's Algorithm

```
int z[maxn];
int manacher(const string& s) {
    string t = ".";
    for (int i = 0; i < s.length(); ++i) t += s[i], t += '.';
    int l = 0, r = 0;
    for (int i = 1; i < t.length(); ++i) {
        z[i] = (r > i ? min(z[2 * l - i], r - i) : 1);
        while (i - z[i] >= 0 && i + z[i] < t.length() && t[i - z[i]] == t[i + z[i]]) ++z[i];
        if (i + z[i] > r) r = i + z[i], l = i;
    }
    int ans = 0;
    for (int i = 1; i < t.length(); ++i) ans = max(ans, z[i] - 1);
    return ans;
}
```

5.4 Aho–Corasick Automaton

```
struct AC {
    static const int maxn = 1e5 + 5;
    int sz, ql, qr, root;
    int cnt[maxn], q[maxn], ed[maxn], el[maxn], ch[maxn][26], f[
        maxn];
    int gnode() {
        for (int i = 0; i < 26; ++i) ch[sz][i] = -1;
        f[sz] = -1;
        ed[sz] = 0;
        cnt[sz] = 0;
        return sz++;
    }
    void init() {
        sz = 0;
        root = gnode();
    }
    int add(const string &s) {
        int now = root;
        for (int i = 0; i < s.length(); ++i) {
            if (ch[now][s[i] - 'a'] == -1) ch[now][s[i] - 'a'] = gnode();
            now = ch[now][s[i] - 'a'];
        }
        ed[now] = 1;
        return now;
    }
    void build_fail() {
        ql = qr = 0; q[qr++] = root;
        while (ql < qr) {
            int now = q[ql++];
            for (int i = 0; i < 26; ++i) if (ch[now][i] != -1) {
                int p = ch[now][i], fp = f[now];
                f[p] = (fp == -1 ? root : f[fp]);
                ed[p] = ed[now] || (ch[fp][i] != -1);
            }
        }
    }
}
```

```

    while (fp != -1 && ch[fp][i] == -1) fp = f[fp];
    int pd = fp != -1 ? ch[fp][i] : root;
    f[p] = pd;
    el[p] = ed[pd] ? pd : el[pd];
    q[qr++] = p;
}
}
}
void build(const string &s) {
    build_fail();
    int now = root;
    for (int i = 0; i < s.length(); ++i) {
        while (now != -1 && ch[now][s[i] - 'a'] == -1) now = f[
now];
        now = now != -1 ? ch[now][s[i] - 'a'] : root;
        ++cnt[now];
    }
    for (int i = qr - 1; i >= 0; --i) cnt[f[q[i]]] += cnt[q[i]
];
}
long long solve(int n) {
    build_fail();
    vector<vector<long long>> dp(sz, vector<long long>(n + 1,
0));
    for (int i = 0; i < sz; ++i) dp[i][0] = 1;
    for (int i = 1; i <= n; ++i) {
        for (int j = 0; j < sz; ++j) {
            for (int k = 0; k < 2; ++k) {
                if (ch[j][k] != -1) {
                    if (!ed[ch[j][k]])
                        dp[j][i] += dp[ch[j][k]][i - 1];
                } else {
                    int z = f[j];
                    while (z != root && ch[z][k] == -1) z = f[z];
                    int p = ch[z][k] == -1 ? root : ch[z][k];
                    if (ch[z][k] == -1 || !ed[ch[z][k]]) dp[j][i] += dp
[p][i - 1];
                }
            }
        }
    }
    return dp[0][n];
}
};

```

5.5 Suffix Automaton

```

struct SAM {
    static const int maxn = 5e5 + 5;
    int nxt[maxn][26], to[maxn], len[maxn];
    int root, last, sz;
    int gnode(int x) {
        for (int i = 0; i < 26; ++i) nxt[sz][i] = -1;
        to[sz] = -1;
        len[sz] = x;
        return sz++;
    }
    void init() {
        sz = 0;
        root = gnode(0);
        last = root;
    }
    void push(int c) {
        int cur = last;
        last = gnode(len[last] + 1);
        for (; ~cur && nxt[cur][c] == -1; cur = to[cur]) nxt[cur][c
] = last;
        if (cur == -1) return to[last] = root, void();
        int link = nxt[cur][c];
        if (len[link] == len[cur] + 1) return to[last] = link, void
();
        int tlink = gnode(len[cur] + 1);
        for (; ~cur && nxt[cur][c] == link; cur = to[cur]) nxt[cur
][c] = tlink;
        for (int i = 0; i < 26; ++i) nxt[tlink][i] = nxt[link][i];
        to[tlink] = to[link];
        to[link] = tlink;
        to[last] = tlink;
    }
    void add(const string &s) {
        for (int i = 0; i < s.size(); ++i) push(s[i] - 'a');
    }
    bool find(const string &s) {
        int cur = root;

```

```

        for (int i = 0; i < s.size(); ++i) {
            cur = nxt[cur][s[i] - 'a'];
            if (cur == -1) return false;
        }
        return true;
    }
    int solve(const string &t) {
        int res = 0, cnt = 0;
        int cur = root;
        for (int i = 0; i < t.size(); ++i) {
            if (~nxt[cur][t[i] - 'a']) {
                ++cnt;
                cur = nxt[cur][t[i] - 'a'];
            } else {
                for (; ~cur && nxt[cur][t[i] - 'a'] == -1; cur = to[cur
]);
                if (~cur) cnt = len[cur] + 1, cur = nxt[cur][t[i] - 'a'
];
                else cnt = 0, cur = root;
            }
            res = max(res, cnt);
        }
        return res;
    }
};

```

5.6 Suffix Array

```

namespace sfxarray {
    bool t[maxn * 2];
    int hi[maxn], rev[maxn];
    int _s[maxn * 2], sa[maxn * 2], c[maxn * 2], x[maxn], p[maxn],
q[maxn * 2];
    // sa[i]: sa[i]-th suffix is the i-th lexicographically smallest
    // suffix.
    // hi[i]: longest common prefix of suffix sa[i] and suffix sa[i
- 1].
    void pre(int *sa, int *c, int n, int z) {
        memset(sa, 0, sizeof(int) * n);
        memcpy(x, c, sizeof(int) * z);
    }
    void induce(int *sa, int *c, int *s, bool *t, int n, int z) {
        memcpy(x + 1, c, sizeof(int) * (z - 1));
        for (int i = 0; i < n; ++i) if (sa[i] && !t[sa[i] - 1]) sa[x[
s[sa[i] - 1]]++] = sa[i] - 1;
        memcpy(x, c, sizeof(int) * z);
        for (int i = n - 1; i >= 0; --i) if (sa[i] && t[sa[i] - 1])
sa[--x[sa[i] - 1]] = sa[i] - 1;
    }
    void sais(int *s, int *sa, int *p, int *q, bool *t, int *c, int
n, int z) {
        bool uniq = t[n - 1] = true;
        int nn = 0, nmzx = -1, *nsa = sa + n, *ns = s + n, last = -1;
        memset(c, 0, sizeof(int) * z);
        for (int i = 0; i < n; ++i) if (sa[i] && !t[sa[i] - 1]) sa[x[
s[sa[i] - 1]]++] = sa[i] - 1;
        for (int i = 0; i < z - 1; ++i) c[i + 1] += c[i];
        if (uniq) {
            for (int i = 0; i < n; ++i) sa[--c[s[i]]] = i;
            return;
        }
        for (int i = n - 2; i >= 0; --i) t[i] = (s[i] == s[i + 1] ? t
[i + 1] : s[i] < s[i + 1]);
        pre(sa, c, n, z);
        for (int i = 1; i <= n - 1; ++i) if (t[i] && !t[i - 1]) sa[
--x[s[i]]] = p[q[i] = nn++] = i;
        induce(sa, c, s, t, n, z);
        for (int i = 0; i < n; ++i) if (sa[i] && t[sa[i]] && !t[sa[i]
- 1]) {
            bool neq = last < 0 || memcmp(s + sa[i], s + last, (p[q[sa[
i]] + 1] - sa[i]) * sizeof(int));
            ns[q[last = sa[i]]] = nmzx += neq;
        }
        sais(ns, nsa, p + nn, q + n, t + n, c + z, nn, nmzx + 1);
        pre(sa, c, n, z);
        for (int i = nn - 1; i >= 0; --i) sa[--x[s[p[nsa[i]]]]] = p[
nsa[i]];
        induce(sa, c, s, t, n, z);
    }
    void build(const string &s) {
        for (int i = 0; i < (int)s.size(); ++i) _s[i] = s[i];
        _s[(int)s.size()] = 0; // s shouldn't contain 0
        sais(_s, sa, p, q, t, c, (int)s.size() + 1, 256);
        for (int i = 0; i < (int)s.size(); ++i) sa[i] = sa[i + 1];
        for (int i = 0; i < (int)s.size(); ++i) rev[sa[i]] = i;
    }
}

```

```

int ind = 0; hi[0] = 0;
for (int i = 0; i < (int)s.size(); ++i) {
    if (!rev[i]) {
        ind = 0;
        continue;
    }
    while (i + ind < (int)s.size() && s[i + ind] == s[sa[rev[i]
- 1] + ind]) ++ind;
    hi[rev[i]] = ind ? ind-- : 0;
}
}
}

```

5.7 Lexicographically Smallest Rotation

```

string rotate(const string &s) {
    int n = s.length();
    string t = s + s;
    int i = 0, j = 1;
    while (i < n && j < n) {
        int k = 0;
        while (k < n && t[i + k] == t[j + k]) ++k;
        if (t[i + k] <= t[j + k]) j += k + 1;
        else i += k + 1;
        if (i == j) ++j;
    }
    int pos = (i < n ? i : j);
    return t.substr(pos, n);
}

```

6 Math

6.1 Fast Fourier Transform

```

namespace fft {
struct cplx {
    double re, im;
    cplx(): re(0), im(0) {}
    cplx(double r, double i): re(r), im(i) {}
    cplx operator+(const cplx &rhs) const { return cplx(re + rhs.
re, im + rhs.im); }
    cplx operator-(const cplx &rhs) const { return cplx(re - rhs.
re, im - rhs.im); }
    cplx operator*(const cplx &rhs) const { return cplx(re * rhs.
re - im * rhs.im, re * rhs.im + im * rhs.re); }
    cplx conj() const { return cplx(re, -im); }
};
const double pi = acos(-1);
cplx omega[maxn + 1];
void prefft() {
    for (int i = 0; i <= maxn; ++i)
        omega[i] = cplx(cos(2 * pi * i / maxn), sin(2 * pi * i /
maxn));
}
void bitrev(vector<cplx> &v, int n) {
    int z = __builtin_ctz(n) - 1;
    for (int i = 0; i < n; ++i) {
        int x = 0;
        for (int j = 0; (1 << j) < n; ++j) x ^= (i >> j & 1) << (z
- j);
        if (x > i) swap(v[x], v[i]);
    }
}
void fft(vector<cplx> &v, int n) {
    bitrev(v, n);
    for (int s = 2; s <= n; s <= 1) {
        int z = s >> 1;
        for (int i = 0; i < n; i += s) {
            for (int k = 0; k < z; ++k) {
                cplx x = v[i + z + k] * omega[maxn / s * k];
                v[i + z + k] = v[i + k] - x;
                v[i + k] = v[i + k] + x;
            }
        }
    }
}
void ifft(vector<cplx> &v, int n) {
    fft(v, n);
    reverse(v.begin() + 1, v.end());
    for (int i = 0; i < n; ++i) v[i] = v[i] * cplx(1. / n, 0);
}
}

```

```

vector<long long> convolution(const vector<int> &a, const
vector<int> &b) {
    // Should be able to handle N <= 10^5, C <= 10^4
    int sz = 1;
    while (sz < a.size() + b.size() - 1) sz <= 1;
    vector<cplx> v(sz);
    for (int i = 0; i < sz; ++i) {
        double re = i < a.size() ? a[i] : 0;
        double im = i < b.size() ? b[i] : 0;
        v[i] = cplx(re, im);
    }
    fft(v, sz);
    for (int i = 0; i <= sz / 2; ++i) {
        int j = (sz - i) & (sz - 1);
        cplx x = (v[i] + v[j].conj()) * (v[i] - v[j].conj()) * cplx
(0, -0.25);
        if (j != i) v[j] = (v[j] + v[i].conj()) * (v[j] - v[i].conj
()) * cplx(0, -0.25);
        v[i] = x;
    }
    ifft(v, sz);
    vector<long long> c(sz);
    for (int i = 0; i < sz; ++i) c[i] = round(v[i].re);
    return c;
}
vector<int> convolution_mod(const vector<int> &a, const vector<
int> &b, int p) {
    int sz = 1;
    while (sz < (int)a.size() + (int)b.size() - 1) sz <= 1;
    vector<cplx> fa(sz), fb(sz);
    for (int i = 0; i < (int)a.size(); ++i)
        fa[i] = cplx(a[i] & ((1 << 15) - 1), a[i] >> 15);
    for (int i = 0; i < (int)b.size(); ++i)
        fb[i] = cplx(b[i] & ((1 << 15) - 1), b[i] >> 15);
    fft(fa, sz), fft(fb, sz);
    double r = 0.25 / sz;
    cplx r2(0, -1), r3(r, 0), r4(0, -r), r5(0, 1);
    for (int i = 0; i <= (sz >> 1); ++i) {
        int j = (sz - i) & (sz - 1);
        cplx a1 = (fa[i] + fa[j].conj());
        cplx a2 = (fa[i] - fa[j].conj()) * r2;
        cplx b1 = (fb[i] + fb[j].conj()) * r3;
        cplx b2 = (fb[i] - fb[j].conj()) * r4;
        if (i != j) {
            cplx c1 = (fa[j] + fa[i].conj());
            cplx c2 = (fa[j] - fa[i].conj()) * r2;
            cplx d1 = (fb[j] + fb[i].conj()) * r3;
            cplx d2 = (fb[j] - fb[i].conj()) * r4;
            fa[i] = c1 * d1 + c2 * d2 * r5;
            fb[i] = c1 * d2 + c2 * d1;
        }
        fa[j] = a1 * b1 + a2 * b2 * r5;
        fb[j] = a1 * b2 + a2 * b1;
    }
    fft(fa, sz), fft(fb, sz);
    vector<int> res(sz);
    for (int i = 0; i < sz; ++i) {
        long long a = round(fa[i].re);
        long long b = round(fb[i].re);
        long long c = round(fa[i].im);
        res[i] = (a + ((b % p) << 15) + ((c % p) << 30)) % p;
    }
    return res;
}
}

```

6.2 Number Theoretic Transform

```

template <long long mod, long long root>
struct NTT {
    vector<long long> omega;
    NTT() {
        omega.resize(maxn + 1);
        long long x = fpow(root, (mod - 1) / maxn);
        omega[0] = 1ll;
        for (int i = 1; i <= maxn; ++i)
            omega[i] = omega[i - 1] * x % mod;
    }
    void bitrev(vector<long long> &v, int n) {
        int z = __builtin_ctz(n) - 1;
        for (int i = 0; i < n; ++i) {
            int x = 0;
            for (int j = 0; j <= z; ++j) x ^= (i >> j & 1) << (z - j)
;
            if (x > i) swap(v[x], v[i]);
        }
    }
}

```

```

    }
}
void ntt(vector<long long> &v, int n) {
    bitrev(v, n);
    for (int s = 2; s <= n; s <= 1) {
        int z = s >> 1;
        for (int i = 0; i < n; i += s) {
            for (int k = 0; k < z; ++k) {
                long long x = v[i + k + z] * omega[maxn / s * k] %
mod;
                v[i + k + z] = (v[i + k] + mod - x) % mod;
                (v[i + k] += x) %= mod;
            }
        }
    }
}
void intt(vector<long long> &v, int n) {
    ntt(v, n);
    for (int i = 1; i < n / 2; ++i) swap(v[i], v[n - i]);
    long long inv = fpow(n, -1);
    for (int i = 0; i < n; ++i) (v[i] *= inv) %= mod;
}
vector<long long> operator()(vector<long long> a, vector<long
long> b) {
    int sz = 1;
    while (sz < a.size() + b.size() - 1) sz <= 1;
    while (a.size() < sz) a.push_back(0);
    while (b.size() < sz) b.push_back(0);
    ntt(a, sz), ntt(b, sz);
    vector<long long> c(sz);
    for (int i = 0; i < sz; ++i) c[i] = a[i] * b[i] % mod;
    intt(c, sz);
    return c;
}
};
vector<long long> convolution(vector<long long> a, vector<long
long> b) {
    NTT<mod1, root1> conv1;
    NTT<mod2, root2> conv2;
    vector<long long> pa(a.size()), pb(b.size());
    for (int i = 0; i < (int)a.size(); ++i) pa[i] = (a[i] % mod1
+ mod1) % mod1;
    for (int i = 0; i < (int)b.size(); ++i) pb[i] = (b[i] % mod1
+ mod1) % mod1;
    vector<long long> c1 = conv1(pa, pb);
    for (int i = 0; i < (int)a.size(); ++i) pa[i] = (a[i] % mod2
+ mod2) % mod2;
    for (int i = 0; i < (int)b.size(); ++i) pb[i] = (b[i] % mod2
+ mod2) % mod2;
    vector<long long> c2 = conv2(pa, pb);
    long long x = conv2.fpow(mod1, -1);
    long long y = conv1.fpow(mod2, -1);
    long long prod = mod1 * mod2;
    vector<long long> res(c1.size());
    for (int i = 0; i < c1.size(); ++i) {
        long long z = ((ull)fmul(c1[i] * mod2 % prod, y, prod) +
(ull)fmul(c2[i] * mod1 % prod, x, prod)) % prod;
        if (z >= prod / 2) z -= prod;
        res[i] = z;
    }
    return res;
}
}

```

6.2.1 NTT Prime List

Prime	Root	Prime	Root
7681	17	167772161	3
12289	11	104857601	3
40961	3	985661441	3
65537	3	998244353	3
786433	10	1107296257	10
5767169	3	2013265921	31
7340033	3	2810183681	11
23068673	3	2885681153	3
469762049	3	605028353	3

6.3 Polynomial Division

```

vector<int> inverse(const vector<int> &v, int n) {
    vector<int> q(1, fpow(v[0], mod - 2));
    for (int i = 2; i <= n; i <= 1) {
        vector<int> fv(v.begin(), v.begin() + i);
        vector<int> fq(q.begin(), q.end());
        fv.resize(2 * i), fq.resize(2 * i);
        ntt(fq, 2 * i), ntt(fv, 2 * i);
    }
}

```

```

    for (int j = 0; j < 2 * i; ++j) {
        fv[j] = fv[j] * 11l * fq[j] % mod * 11l * fq[j] % mod;
    }
    intt(fv, 2 * i);
    vector<int> res(i);
    for (int j = 0; j < i; ++j) {
        res[j] = mod - fv[j];
        if (j < (i >> 1)) (res[j] += 2 * q[j] % mod) %= mod;
    }
    q = res;
}
return q;
}
vector<int> divide(const vector<int> &a, const vector<int> &b)
{
    // leading zero should be trimmed
    int n = (int)a.size(), m = (int)b.size();
    int k = 2;
    while (k < n - m + 1) k <= 1;
    vector<int> ra(k), rb(k);
    for (int i = 0; i < min(n, k); ++i) ra[i] = a[n - i - 1];
    for (int i = 0; i < min(m, k); ++i) rb[i] = b[m - i - 1];
    vector<int> rbi = inverse(rb, k);
    vector<int> res = convolution(rbi, ra);
    res.resize(n - m + 1);
    reverse(res.begin(), res.end());
    return res;
}
}

```

6.4 Polynomial Square Root

```

// Find G(x) such that G^2(x) = F(x) (mod x^{N+1})
vector<int> solve(vector<int> b, int n) {
    if (n == 1) return {sqr[b[0]]};
    vector<int> h = solve(b, n >> 1); h.resize(n);
    vector<int> c = inverse(h, n);
    h.resize(n << 1); c.resize(n << 1);
    vector<int> res(n << 1);
    conv.ntt(h, n << 1);
    for (int i = n; i < (n << 1); ++i) b[i] = 0;
    conv.ntt(b, n << 1);
    conv.ntt(c, n << 1);
    for (int i = 0; i < (n << 1); ++i) res[i] = 11l * (h[i] + 11l
* c[i] * b[i] % mod) % mod * inv2 % mod;
    conv.intt(res, n << 1);
    for (int i = n; i < (n << 1); ++i) res[i] = 0;
    return res;
}
}

```

6.5 Multipoint Evaluation

```

struct MultiEval {
    MultiEval *lc, *rc;
    vector<int> p, ml;
    // v is the points to be queried
    MultiEval(const vector<int> &v, int l, int r) : lc(nullptr),
rc(nullptr) {
        if (r - l <= 64) {
            p = vector<int>(v.begin() + l, v.begin() + r);
            ml.resize(1, 1);
            for (int x : p) ml = Multiply(ml, {kMod - x, 1});
            return;
        }
        int m = (l + r) >> 1;
        lc = new MultiEval(v, l, m), rc = new MultiEval(v, m, r);
        ml = Multiply(lc->ml, rc->ml);
    }
    // poly is the polynomial to be evaluated
    void Query(const vector<int> &poly, vector<int> &res, int l,
int r) const {
        if (r - l <= 64) {
            for (int x : p) {
                int s = 0, bs = 1;
                for (int i = 0; i < poly.size(); ++i) {
                    (s += 11L * bs * poly[i] % kMod) %= kMod;
                    bs = 11L * bs * x % kMod;
                }
                res.push_back(s);
            }
            return;
        }
        auto pol = Modulo(poly, ml);
    }
}

```

```

    int m = (l + r) >> 1;
    lc->Query(pol, res, l, m), rc->Query(pol, res, m, r);
}
};

```

6.6 Polynomial Interpolation

```

vector<int> Interp(const vector<int> &x, const vector<int> &y)
{
    vector<vector<vector<int>>> v;
    int n = x.size();
    v.emplace_back(n);
    for (int i = 0; i < n; ++i) v[0][i] = {{kMod - x[i], 1}};
    while (v.back().size() > 1) {
        int n2 = v.back().size();
        vector<vector<int>> f((n2 + 1) >> 1);
        for (int i = 0; i < (n2 >> 1); ++i) f[i] = Multiply(v.back()
            [2 * i], v.back()[2 * i + 1]);
        if (n2 & 1) f.back() = v.back().back();
        v.push_back(f);
    }
    vector<int> df(v.back()[0].size() - 1);
    for (int i = 0; i < df.size(); ++i) df[i] = 1LL * v.back()
        [0][i + 1] * (i + 1) % kMod;
    vector<int> s;
    MultiEval(x, 0, n).Query(df, s, 0, n);
    vector<vector<int>> res(n);
    for (int i = 0; i < n; ++i) res[i] = {1LL * y[i] * fpow(s[i],
        kMod - 2) % kMod};
    for (int p = 1; p < v.size(); ++p) {
        int n2 = v[p - 1].size();
        vector<vector<int>> f((n2 + 1) >> 1);
        for (int i = 0; i < (n2 >> 1); ++i) {
            auto a = Multiply(res[i * 2], v[p - 1][2 * i + 1]);
            auto b = Multiply(res[i * 2 + 1], v[p - 1][2 * i]);
            assert(a.size() == b.size());
            f[i].resize(a.size());
            for (int j = 0; j < a.size(); ++j) f[i][j] = (a[j] + b[j]
                ) % kMod;
        }
        if (n2 & 1) f.back() = res.back();
        res = f;
    }
    return res[0];
}

```

6.7 Fast Walsh-Hadamard Transform

6.7.1 XOR Convolution

- $tf(A) = (tf(A_0) + tf(A_1), tf(A_0) - tf(A_1))$
- $utf(A) = (utf(\frac{A_0+A_1}{2}), utf(\frac{A_0-A_1}{2}))$

6.7.2 OR Convolution

- $tf(A) = (tf(A_0), tf(A_0) + tf(A_1))$
- $utf(A) = (utf(A_0), utf(A_1) - utf(A_0))$

6.7.3 AND Convolution

- $tf(A) = (tf(A_0) + tf(A_1), tf(A_1))$
- $utf(A) = (utf(A_0) - utf(A_1), utf(A_1))$

6.8 Simplex Algorithm

```

namespace simplex {
// maximize c^T x under Ax <= B
// return vector<double>(n, -inf) if the solution doesn't exist
// return vector<double>(n, +inf) if the solution is unbounded
const double eps = 1e-9;
const double inf = 1e+9;
int n, m;
vector<vector<double>> d;
vector<int> p, q;
void pivot(int r, int s) {
    double inv = 1.0 / d[r][s];
    for (int i = 0; i < m + 2; ++i) {

```

```

        for (int j = 0; j < n + 2; ++j) {
            if (i != r && j != s) d[i][j] -= d[r][j] * d[i][s] * inv;
        }
    }
    for (int i = 0; i < m + 2; ++i) if (i != r) d[i][s] *= -inv;
    for (int j = 0; j < n + 2; ++j) if (j != s) d[r][j] *= +inv;
    d[r][s] = inv;
    swap(p[r], q[s]);
}
bool phase(int z) {
    int x = m + z;
    while (true) {
        int s = -1;
        for (int i = 0; i <= n; ++i) {
            if (!z && q[i] == -1) continue;
            if (s == -1 || d[x][i] < d[x][s]) s = i;
        }
        if (d[x][s] > -eps) return true;
        int r = -1;
        for (int i = 0; i < m; ++i) {
            if (d[i][s] < eps) continue;
            if (r == -1 || d[i][n + 1] / d[i][s] < d[r][n + 1] / d[r]
                [s]) r = i;
        }
        if (r == -1) return false;
        pivot(r, s);
    }
}
vector<double> solve(const vector<vector<double>> &a, const
    vector<double> &b, const vector<double> &c) {
    m = b.size(), n = c.size();
    d = vector<vector<double>>(m + 2, vector<double>(n + 2));
    for (int i = 0; i < m; ++i) {
        for (int j = 0; j < n; ++j) d[i][j] = a[i][j];
    }
    p.resize(m), q.resize(n + 1);
    for (int i = 0; i < m; ++i) p[i] = n + i, d[i][n] = -1, d[i][
        n + 1] = b[i];
    for (int i = 0; i < n; ++i) q[i] = i, d[m][i] = -c[i];
    q[n] = -1, d[m + 1][n] = 1;
    int r = 0;
    for (int i = 1; i < m; ++i) if (d[i][n + 1] < d[r][n + 1]) r
        = i;
    if (d[r][n + 1] < -eps) {
        pivot(r, n);
        if (!phase(1) || d[m + 1][n + 1] < -eps) return vector<
            double>(n, -inf);
        for (int i = 0; i < m; ++i) if (p[i] == -1) {
            int s = min_element(d[i].begin(), d[i].end() - 1) - d[i].
                begin();
            pivot(i, s);
        }
    }
    if (!phase(0)) return vector<double>(n, inf);
    vector<double> x(n);
    for (int i = 0; i < m; ++i) if (p[i] < n) x[p[i]] = d[i][n +
        1];
    return x;
}
}

```

6.8.1 Construction

Standard form: maximize $\sum_{1 \leq i \leq n} c_i x_i$ such that for all $1 \leq j \leq m$, $\sum_{1 \leq i \leq n} A_{ji} x_i \leq b_j$ and $x_i \geq 0$ for all $1 \leq i \leq n$.

1. In case of minimization, let $c'_i = -c_i$
2. $\sum_{1 \leq i \leq n} A_{ji} x_i \geq b_j \rightarrow \sum_{1 \leq i \leq n} -A_{ji} x_i \leq -b_j$
3. $\sum_{1 \leq i \leq n} A_{ji} x_i = b_j$
 - $\sum_{1 \leq i \leq n} A_{ji} x_i \leq b_j$
 - $\sum_{1 \leq i \leq n} A_{ji} x_i \geq b_j$
4. If x_i has no lower bound, replace x_i with $x_i - x'_i$

6.9 Schreier-Sims Algorithm

```

namespace schreier {
int n;
vector<vector<vector<int>>> bkts, binv;
vector<vector<int>> lk;

```

```

vector<int> operator*(const vector<int> &a, const vector<int> &
    b) {
    vector<int> res(a.size());
    for (int i = 0; i < (int)a.size(); ++i) res[i] = b[a[i]];
    return res;
}
vector<int> inv(const vector<int> &a) {
    vector<int> res(a.size());
    for (int i = 0; i < (int)a.size(); ++i) res[a[i]] = i;
    return res;
}
int filter(const vector<int> &g, bool add = true) {
    n = (int)bks.size();
    vector<int> p = g;
    for (int i = 0; i < n; ++i) {
        assert(p[i] >= 0 && p[i] < (int)lk[i].size());
        int res = lk[i][p[i]];
        if (res == -1) {
            if (add) {
                bks[i].push_back(p);
                binv[i].push_back(inv(p));
                lk[i][p[i]] = (int)bks[i].size() - 1;
            }
            return i;
        }
        p = p * binv[i][res];
    }
    return -1;
}
bool inside(const vector<int> &g) { return filter(g, false) ==
    -1; }
void solve(const vector<vector<int>> &gen, int _n) {
    n = _n;
    bks.clear(), bks.resize(n);
    binv.clear(), binv.resize(n);
    lk.clear(), lk.resize(n);
    vector<int> iden(n);
    iota(iden.begin(), iden.end(), 0);
    for (int i = 0; i < n; ++i) {
        lk[i].resize(n, -1);
        bks[i].push_back(iden);
        binv[i].push_back(iden);
        lk[i][i] = 0;
    }
    for (int i = 0; i < (int)gen.size(); ++i) filter(gen[i]);
    queue<pair<pair<int, int>, pair<int, int>>> upd;
    for (int i = 0; i < n; ++i) {
        for (int j = i; j < n; ++j) {
            for (int k = 0; k < (int)bks[i].size(); ++k) {
                for (int l = 0; l < (int)bks[j].size(); ++l)
                    upd.emplace(make_pair(i, k), make_pair(j, l));
            }
        }
    }
    while (!upd.empty()) {
        auto a = upd.front().first;
        auto b = upd.front().second;
        upd.pop();
        int res = filter(bks[a.first][a.second] * bks[b.first][b.
            second]);
        if (res == -1) continue;
        pair<int, int> pr = make_pair(res, (int)bks[res].size() -
            1);
        for (int i = 0; i < n; ++i) {
            for (int j = 0; j < (int)bks[i].size(); ++j) {
                if (i <= res) upd.emplace(make_pair(i, j), pr);
                if (res <= i) upd.emplace(pr, make_pair(i, j));
            }
        }
    }
}
long long size() {
    long long res = 1;
    for (int i = 0; i < n; ++i) res = res * bks[i].size();
    return res;
}
}

```

6.10 Berlekamp-Massey Algorithm

```

template <int P>
vector<int> BerlekampMassey(vector<int> x) {
    vector<int> cur, ls;
    int lf = 0, ld = 0;
    for (int i = 0; i < (int)x.size(); ++i) {

```

```

        int t = 0;
        for (int j = 0; j < (int)cur.size(); ++j)
            (t += 1LL * cur[j] * x[i - j - 1] % P) %= P;
        if (t == x[i]) continue;
        if (cur.empty()) {
            cur.resize(i + 1);
            lf = i, ld = (t + P - x[i]) % P;
            continue;
        }
        int k = 1LL * fpow(ld, P - 2, P) * (t + P - x[i]) % P;
        vector<int> c(i - lf - 1);
        c.push_back(k);
        for (int j = 0; j < (int)ls.size(); ++j)
            c.push_back(1LL * k * (P - ls[j]) % P);
        if (c.size() < cur.size()) c.resize(cur.size());
        for (int j = 0; j < (int)cur.size(); ++j)
            c[j] = (c[j] + cur[j]) % P;
        if (i - lf + (int)ls.size() >= (int)cur.size()) {
            ls = cur, lf = i;
            ld = (t + P - x[i]) % P;
        }
        cur = c;
    }
    return cur;
}

```

6.11 Miller Rabin

```

// n < 4759123141   chk = [2, 7, 61]
// n < 1122004669633   chk = [2, 13, 23, 1662803]
// n < 2^64         chk = [2, 325, 9375, 28178, 450775, 9780504,
//                        1795265022]
//
vector<long long> chk = { 2, 325, 9375, 28178, 450775, 9780504,
    1795265022 };

bool check(long long a, long long u, long long n, int t) {
    a = fpow(a, u, n);
    if (a == 0) return true;
    if (a == 1 || a == n - 1) return true;
    for (int i = 0; i < t; ++i) {
        a = fmul(a, a, n);
        if (a == 1) return false;
        if (a == n - 1) return true;
    }
    return false;
}

bool is_prime(long long n) {
    if (n < 2) return false;
    if (n % 2 == 0) return n == 2;
    long long u = n - 1; int t = 0;
    for (; !(u & 1); u >>= 1, ++t);
    for (long long i : chk) {
        if (!check(i, u, n, t)) return false;
    }
    return true;
}

```

6.12 Pollard's Rho

```

map<long long, int> cnt;

long long f(long long x, long long n, int p) { return (fmul(x,
    x, n) + p) % n; }
void pollard_rho(long long n) {
    if (n == 1) return;
    if (prime(n)) return ++cnt[n], void();
    if (n % 2 == 0) return pollard_rho(n / 2), ++cnt[2], void();
    long long x = 2, y = 2, d = 1, p = 1;
    while (true) {
        if (d != n && d != 1) {
            pollard_rho(n / d);
            pollard_rho(d);
            return;
        }
        if (d == n) ++p;
        x = f(x, n, p); y = f(f(y, n, p), n, p);
        d = __gcd(abs(x - y), n);
    }
}

```


6.13 Meissel–Lehmer Algorithm

```
int prc[maxn];
long long phic[msz][nsz];

void sieve() {
    bitset<maxn> v;
    pr.push_back(0);
    for (int i = 2; i < maxn; ++i) {
        if (!v[i]) pr.push_back(i);
        for (int j = 1; i * pr[j] < maxn; ++j) {
            v[i * pr[j]] = true;
            if (i % pr[j] == 0) break;
        }
    }
    for (int i = 1; i < pr.size(); ++i) prc[pr[i]] = 1;
    for (int i = 1; i < maxn; ++i) prc[i] += prc[i - 1];
}

long long p2(long long, long long);
long long phi(long long m, long long n) {
    if (m < msz && n < nsz && phic[m][n] != -1) return phic[m][n];
    if (n == 0) return m;
    if (pr[n] >= m) return 1;
    long long ret = phi(m, n - 1) - phi(m / pr[n], n - 1);
    if (m < msz && n < nsz) phic[m][n] = ret;
    return ret;
}

long long pi(long long m) {
    if (m < maxn) return prc[m];
    long long n = pi(cbrt(m));
    return phi(m, n) + n - 1 - p2(m, n);
}

long long p2(long long m, long long n) {
    long long ret = 0;
    long long lim = sqrt(m);
    for (int i = n + 1; pr[i] <= lim; ++i) ret += pi(m / pr[i]) -
        pi(pr[i]) + 1;
    return ret;
}
```

6.14 Discrete Logarithm

```
// to solve discrete x for x^a = b (mod p) with p is prime
// let c = primitive root of p
// find k such that c^k = b (mod p) by bsgs
// solve fa = k (mod p - 1) by euclidean algorithm
// x = c^f
int bsgs(int a, int b, int p) {
    // return L such that a^L = b (mod p)
    if (p == 1) {
        if (!b) return a != 1;
        return -1;
    }
    if (b == 1) {
        if (a) return 0;
        return -1;
    }
    if (a % p == 0) {
        if (!b) return 1;
        return -1;
    }
    int num = 0, d = 1;
    while (true) {
        int r = __gcd(a, p);
        if (r == 1) break;
        if (b % r) return -1;
        ++num;
        b /= r, p /= r;
        d = (1ll * d * a / r) % p;
    }
    for (int i = 0, now = 1; i < num; ++i, now = 1ll * now * a % p) {
        if (now == b) return i;
    }
    int m = ceil(sqrt(p)), base = 1;
    map<int, int> mp;
    for (int i = 0; i < m; ++i) {
        if (mp.find(base) == mp.end()) mp[base] = i;
        else mp[base] = min(mp[base], i);
        base = 1ll * base * a % p;
    }
    for (int i = 0; i < m; ++i) {
        // can be modified to fpow if p is prime
```

```
int r, x, y; tie(r, x, y) = extgcd(d, p);
x = (1ll * x * b % p + p) % p;
if (mp.find(x) != mp.end()) return i * m + mp[x] + num;
d = 1ll * d * base % p;
}
return -1;
}
```

6.15 Quadratic Residue

```
int Jacobi(int a, int m) {
    int s = 1;
    for (; m > 1; ) {
        a %= m;
        if (a == 0) return 0;
        const int r = __builtin_ctz(a);
        if ((r & 1) && ((m + 2) & 4)) s = -s;
        a >>= r;
        if (a & m & 2) s = -s;
        swap(a, m);
    }
    return s;
}

int QuadraticResidue(int a, int p) {
    if (p == 2) return a & 1;
    const int jc = Jacobi(a, p);
    if (jc == 0) return 0;
    if (jc == -1) return -1;
    int b, d;
    for (; ) {
        b = rand() % p;
        d = (1LL * b * b + p - a) % p;
        if (Jacobi(d, p) == -1) break;
    }
    int f0 = b, f1 = 1, g0 = 1, g1 = 0, tmp;
    for (int e = (p + 1) >> 1; e; e >>= 1) {
        if (e & 1) {
            tmp = (1LL * g0 * f0 + 1LL * d * (1LL * g1 * f1 % p)) % p;
            g1 = (1LL * g0 * f1 + 1LL * g1 * f0) % p;
            g0 = tmp;
        }
        tmp = (1LL * f0 * f0 + 1LL * d * (1LL * f1 * f1 % p)) % p;
        f1 = (2LL * f0 * f1) % p;
        f0 = tmp;
    }
    return g0;
}
```

6.16 Gaussian Elimination

```
double gauss(vector<vector<double>> &d) {
    int n = d.size(), m = d[0].size();
    double det = 1;
    for (int i = 0; i < m; ++i) {
        int p = -1;
        for (int j = i; j < n; ++j) {
            if (fabs(d[j][i]) < eps) continue;
            if (p == -1 || fabs(d[j][i]) > fabs(d[p][i])) p = j;
        }
        if (p == -1) continue;
        if (p != i) det *= -1;
        for (int j = 0; j < m; ++j) swap(d[p][j], d[i][j]);
        for (int j = 0; j < n; ++j) {
            if (i == j) continue;
            double z = d[j][i] / d[i][i];
            for (int k = 0; k < m; ++k) d[j][k] -= z * d[i][k];
        }
    }
    for (int i = 0; i < n; ++i) det *= d[i][i];
    return det;
}
```

6.17 μ function

```
int mu[maxn], pi[maxn];
vector<int> prime;

void sieve() {
    mu[1] = pi[1] = 1;
```

```

for (int i = 2; i < maxn; ++i) {
    if (!pi[i]) {
        pi[i] = i;
        prime.push_back(i);
        mu[i] = -1;
    }
    for (int j = 0; i * prime[j] < maxn; ++j) {
        pi[i * prime[j]] = prime[j];
        mu[i * prime[j]] = -mu[i];
        if (i % prime[j] == 0) {
            mu[i * prime[j]] = 0;
            break;
        }
    }
}
}
}

```

6.18 Partition Function

```

void Build(int n) {
    // P[i] = the number of ways of representing i as the sum of
    // a non-decreasing sequence.
    vector<pair<int, int>> g = {{0, 0}};
    for (int i = 1; g.back().second <= n; ++i) {
        g.emplace_back(i % 2 ? 1 : kMod - 1, i * (3 * i - 1) / 2);
        g.emplace_back(i % 2 ? 1 : kMod - 1, i * (3 * i + 1) / 2);
    }
    P[0] = P[1] = 1;
    for (int i = 2; i <= n; ++i) {
        for (auto it : g) {
            if (i < it.second) continue;
            P[i] += 1LL * P[i - it.second] * it.first % kMod;
            P[i] %= kMod;
        }
    }
}

```

6.19 $\lfloor \frac{n}{i} \rfloor$ Enumeration

$$T_0 = 1, T_i = \lfloor \frac{n}{\lfloor \frac{n}{T_{i-1}+1} \rfloor} \rfloor$$

6.20 De Bruijn Sequence

```

int res[maxn], aux[maxn], a[maxn], sz;
void db(int t, int p, int n, int k) {
    if (t > n) {
        if (n % p == 0) {
            for (int i = 1; i <= p; ++i) res[sz++] = aux[i];
        }
    } else {
        aux[t] = aux[t - p];
        db(t + 1, p, n, k);
        for (int i = aux[t - p] + 1; i < k; ++i) {
            aux[t] = i;
            db(t + 1, t, n, k);
        }
    }
}
int de_bruijn(int k, int n) {
    // return cyclic string of length k^n such that every string
    // of length n using k character appears as a substring.
    if (k == 1) {
        res[0] = 0;
        return 1;
    }
    for (int i = 0; i < k * n; i++) aux[i] = 0;
    sz = 0;
    db(1, 1, n, k);
    return sz;
}

```

6.21 Extended GCD

```

template <typename T> tuple<T, T, T> extgcd(T a, T b) {
    if (!b) return make_tuple(a, 1, 0);
    T d, x, y;

```

```

    tie(d, x, y) = extgcd(b, a % b);
    return make_tuple(d, y, x - (a / b) * y);
}

```

6.22 Euclidean Algorithms

- $m = \lfloor \frac{a+b}{c} \rfloor$
- Time complexity: $O(\log n)$

$$f(a, b, c, n) = \sum_{i=0}^n \lfloor \frac{ai+b}{c} \rfloor$$

$$= \begin{cases} \lfloor \frac{a}{c} \rfloor \cdot \frac{n(n+1)}{2} + \lfloor \frac{b}{c} \rfloor \cdot (n+1) \\ + f(a \bmod c, b \bmod c, c, n), & a \geq c \vee b \geq c \\ 0, & n < 0 \vee a = 0 \\ nm - f(c, c - b - 1, a, m - 1), & \text{otherwise} \end{cases}$$

$$g(a, b, c, n) = \sum_{i=0}^n i \lfloor \frac{ai+b}{c} \rfloor$$

$$= \begin{cases} \lfloor \frac{a}{c} \rfloor \cdot \frac{n(n+1)(2n+1)}{6} + \lfloor \frac{b}{c} \rfloor \cdot \frac{n(n+1)}{2} \\ + g(a \bmod c, b \bmod c, c, n), & a \geq c \vee b \geq c \\ 0, & n < 0 \vee a = 0 \\ \frac{1}{2} \cdot (n(n+1)m - f(c, c - b - 1, a, m - 1)) \\ - h(c, c - b - 1, a, m - 1), & \text{otherwise} \end{cases}$$

$$h(a, b, c, n) = \sum_{i=0}^n \lfloor \frac{ai+b}{c} \rfloor^2$$

$$= \begin{cases} \lfloor \frac{a}{c} \rfloor^2 \cdot \frac{n(n+1)(2n+1)}{6} + \lfloor \frac{b}{c} \rfloor^2 \cdot (n+1) \\ + \lfloor \frac{a}{c} \rfloor \cdot \lfloor \frac{b}{c} \rfloor \cdot n(n+1) \\ + h(a \bmod c, b \bmod c, c, n) \\ + 2 \lfloor \frac{a}{c} \rfloor \cdot g(a \bmod c, b \bmod c, c, n) \\ + 2 \lfloor \frac{b}{c} \rfloor \cdot f(a \bmod c, b \bmod c, c, n), & a \geq c \vee b \geq c \\ 0, & n < 0 \vee a = 0 \\ nm(m+1) - 2g(c, c - b - 1, a, m - 1) \\ - 2f(c, c - b - 1, a, m - 1) - f(a, b, c, n), & \text{otherwise} \end{cases}$$

6.23 Chinese Remainder Theorem

```

long long crt(vector<int> mod, vector<int> a) {
    long long mult = mod[0];
    int n = (int)mod.size();
    long long res = a[0];
    for (int i = 1; i < n; ++i) {
        long long d, x, y;
        tie(d, x, y) = extgcd(mult, mod[i] * 1ll);
        if ((a[i] - res) % d) return -1;
        long long new_mult = mult / __gcd(mult, 1ll * mod[i]) * mod[i];
        res += x * ((a[i] - res) / d) % new_mult * mult % new_mult;
        mult = new_mult;
        ((res %= mult) += mult) %= mult;
    }
    return res;
}

```

6.24 Theorem

6.24.1 Kirchhoff's Theorem

Denote L be a $n \times n$ matrix as the Laplacian matrix of graph G , where $L_{ii} = d(i)$, $L_{ij} = -c$ where c is the number of edge (i, j) in G .

- The number of undirected spanning in G is $|\det(\tilde{L}_{11})|$.
- The number of directed spanning tree rooted at r in G is $|\det(\tilde{L}_{rr})|$.

6.24.2 Tutte's Matrix

Let D be a $n \times n$ matrix, where $d_{ij} = x_{ij}$ (x_{ij} is chosen uniform randomly) if $i < j$ and $(i, j) \in E$, otherwise $d_{ij} = -d_{ji}$. $\frac{\text{rank}(D)}{2}$ is the maximum matching on G .

6.24.3 Cayley's Formula

- Given a degree sequence d_1, d_2, \dots, d_n for each labeled vertices, there're $\frac{(n-2)!}{(d_1-1)!(d_2-1)!\dots(d_n-1)!}$ spanning trees.
- Let $T_{n,k}$ be the number of labeled forests on n vertices with k components, such that vertex $1, 2, \dots, k$ belong to different components. Then $T_{n,k} = kn^{n-k-1}$.

6.24.4 Erdős–Gallai Theorem

A sequence of non-negative integers $d_1 \geq d_2 \geq \dots \geq d_n$ can be represented as the degree sequence of a finite simple graph on n vertices if and only if $d_1 + d_2 + \dots + d_n$ is even and

$$\sum_{i=1}^k d_i \leq k(k-1) + \sum_{i=k+1}^n \min(d_i, k)$$

holds for all $1 \leq k \leq n$.

6.25 Primes

97, 101, 131, 487, 593, 877, 1087, 1187, 1487, 1787, 3187, 12721, 13331, 14341, 75577, 123457, 222557, 556679, 999983, 1097774749, 1076767633, 100102021, 999997771, 1001010013, 1000512343, 987654361, 999991231, 999888733, 98789101, 987777733, 999991921, 1000000007, 1000000087, 1000000123, 1010101333, 1010102101, 1000000000039, 1000000000000037, 2305843009213693951, 4611686018427387847, 9223372036854775783, 18446744073709551557

7 Dynamic Programming

7.1 Dynamic Convex Hull

```
struct Line {
    mutable int64_t a, b, p;
    bool operator<(const Line &rhs) const { return a < rhs.a; }
    bool operator<(int64_t x) const { return p < x; }
};

struct DynamicHull : multiset<Line, less<>> {
    static const int64_t kInf = 1e18;
    int64_t Div(int64_t a, int64_t b) { return a / b - ((a ^ b) < 0 && a % b); }
    bool Isect(iterator x, iterator y) {
        if (y == end()) { x->p = kInf; return false; }
        if (x->a == y->a) x->p = x->b > y->b ? kInf : -kInf;
        else x->p = Div(y->b - x->b, x->a - y->a);
        return x->p >= y->p;
    }
    void Insert(int64_t a, int64_t b) {
        auto z = insert({a, b, 0}); y = z++; x = y;
        while (Isect(y, z)) z = erase(z);
        if (x != begin() && Isect(--x, y)) Isect(x, y = erase(y));
        while ((y = x) != begin() && (--x)->p >= y->p) Isect(x, erase(y));
    }
    int64_t Query(int64_t x) {
        auto l = *lower_bound(x);
        return l.a * x + l.b;
    }
};
```

7.2 1D/1D Convex Optimization

```
struct segment {
    int i, l, r;
    segment() {}
    segment(int a, int b, int c): i(a), l(b), r(c) {}
};

inline long long f(int l, int r) {
    return dp[l] + w(l + 1, r);
}

void solve() {
    dp[0] = 0ll;
    deque<segment> deq; deq.push_back(segment(0, 1, n));
    for (int i = 1; i <= n; ++i) {
        dp[i] = f(deq.front().i, i);
```

```
while (deq.size() && deq.front().r < i + 1) deq.pop_front();
deq.front().l = i + 1;
segment seg = segment(i, i + 1, n);
while (deq.size() && f(i, deq.back().l) < f(deq.back().i, deq.back().l)) deq.pop_back();
if (deq.size()) {
    int d = 1048576, c = deq.back().l;
    while (d >= 1) if (c + d <= deq.back().r) {
        if (f(i, c + d) > f(deq.back().i, c + d)) c += d;
    }
    deq.back().r = c; seg.l = c + 1;
}
if (seg.l <= n) deq.push_back(seg);
}
```

7.3 Conditon

7.3.1 Totally Monotone (Concave/Convex)

$$\forall i < i', j < j', B[i][j] \leq B[i'][j] \implies B[i][j'] \leq B[i'][j']$$

$$\forall i < i', j < j', B[i][j] \geq B[i'][j] \implies B[i][j'] \geq B[i'][j']$$

7.3.2 Monge Condition (Concave/Convex)

$$\forall i < i', j < j', B[i][j] + B[i'][j'] \geq B[i][j'] + B[i'][j]$$

$$\forall i < i', j < j', B[i][j] + B[i'][j'] \leq B[i][j'] + B[i'][j]$$

7.3.3 Optimal Split Point

If

$$B[i][j] + B[i+1][j+1] \geq B[i][j+1] + B[i+1][j]$$

then

$$H_{i,j-1} \leq H_{i,j} \leq H_{i+1,j}$$

8 Geometry

8.1 Basic

```
bool same(double a, double b) { return abs(a - b) < eps; }
```

```
struct P {
    double x, y;
    P() : x(0), y(0) {}
    P(double x, double y) : x(x), y(y) {}
    P operator + (P b) { return P(x + b.x, y + b.y); }
    P operator - (P b) { return P(x - b.x, y - b.y); }
    P operator * (double b) { return P(x * b, y * b); }
    P operator / (double b) { return P(x / b, y / b); }
    double operator * (P b) { return x * b.x + y * b.y; }
    double operator ^ (P b) { return x * b.y - y * b.x; }
    double abs() { return hypot(x, y); }
    P unit() { return *this / abs(); }
    P spin(double o) {
        double c = cos(o), s = sin(o);
        return P(c * x - s * y, s * x + c * y);
    }
    double angle() { return atan2(y, x); }
};
```

```
struct L {
    // ax + by + c = 0
    double a, b, c, o;
    P pa, pb;
    L() : a(0), b(0), c(0), o(0), pa(), pb() {}
    L(P pa, P pb) : a(pa.y - pb.y), b(pb.x - pa.x), c(pa ^ pb), o(atan2(-a, b)), pa(pa), pb(pb) {}
    P project(P p) { return pa + (pb - pa).unit() * ((pb - pa) * (p - pa) / (pb - pa).abs()); }
    P reflect(P p) { return p + (project(p) - p) * 2; }
    double get_ratio(P p) { return (p - pa) * (pb - pa) / ((pb - pa).abs() * (pb - pa).abs()); }
};
```

```
bool SegmentIntersect(P p1, P p2, P p3, P p4) {
    if (max(p1.x, p2.x) < min(p3.x, p4.x) || max(p3.x, p4.x) < min(p1.x, p2.x)) return false;
    if (max(p1.y, p2.y) < min(p3.y, p4.y) || max(p3.y, p4.y) < min(p1.y, p2.y)) return false;
```

```

return sign((p3 - p1) ^ (p4 - p1)) * sign((p3 - p2) ^ (p4 - p2)) <= 0 &&
    sign((p1 - p3) ^ (p2 - p3)) * sign((p1 - p4) ^ (p2 - p4)) <= 0;
}

bool parallel(L x, L y) { return same(x.a * y.b, x.b * y.a); }

P Intersect(L x, L y) { return P(-x.b * y.c + x.c * y.b, x.a * y.c - x.c * y.a) / (-x.a * y.b + x.b * y.a); }

```

8.2 KD Tree

```

namespace kdt {
int root, lc[maxn], rc[maxn], xl[maxn], xr[maxn], yl[maxn], yr[maxn];
point p[maxn];
int build(int l, int r, int dep = 0) {
    if (l == r) return -1;
    function<bool(const point &, const point &)> f = [dep](const point &a, const point &b) {
        if (dep & 1) return a.x < b.x;
        else return a.y < b.y;
    };
    int m = (l + r) >> 1;
    nth_element(p + l, p + m, p + r, f);
    xl[m] = xr[m] = p[m].x;
    yl[m] = yr[m] = p[m].y;
    lc[m] = build(l, m, dep + 1);
    if (~lc[m]) {
        xl[m] = min(xl[m], xl[lc[m]]);
        xr[m] = max(xr[m], xr[lc[m]]);
        yl[m] = min(yl[m], yl[lc[m]]);
        yr[m] = max(yr[m], yr[lc[m]]);
    }
    rc[m] = build(m + 1, r, dep + 1);
    if (~rc[m]) {
        xl[m] = min(xl[m], xl[rc[m]]);
        xr[m] = max(xr[m], xr[rc[m]]);
        yl[m] = min(yl[m], yl[rc[m]]);
        yr[m] = max(yr[m], yr[rc[m]]);
    }
    return m;
}

bool bound(const point &q, int o, long long d) {
    double ds = sqrt(d + 1.0);
    if (q.x < xl[o] - ds || q.x > xr[o] + ds ||
        q.y < yl[o] - ds || q.y > yr[o] + ds) return false;
    return true;
}

long long dist(const point &a, const point &b) {
    return (a.x - b.x) * 1ll * (a.x - b.x) +
        (a.y - b.y) * 1ll * (a.y - b.y);
}

void dfs(const point &q, long long &d, int o, int dep = 0) {
    if (!bound(q, o, d)) return;
    long long cd = dist(p[o], q);
    if (cd != 0) d = min(d, cd);
    if ((dep & 1) && q.x < p[o].x || !(dep & 1) && q.y < p[o].y) {
        if (~lc[o]) dfs(q, d, lc[o], dep + 1);
        if (~rc[o]) dfs(q, d, rc[o], dep + 1);
    } else {
        if (~rc[o]) dfs(q, d, rc[o], dep + 1);
        if (~lc[o]) dfs(q, d, lc[o], dep + 1);
    }
}

void init(const vector<point> &v) {
    for (int i = 0; i < v.size(); ++i) p[i] = v[i];
    root = build(0, v.size());
}

long long nearest(const point &q) {
    long long res = 1e18;
    dfs(q, res, root);
    return res;
}
}

```

8.3 Delaunay Triangulation

```

/* Delaunay Triangulation:
Given a sets of points on 2D plane, find a
triangulation such that no points will strictly

```

```

inside circumcircle of any triangle.
find : return a triangle contain given point
add_point : add a point into triangulation
A Triangle is in triangulation iff. its has_chd is 0.
Region of triangle u: iterate each u.edge[i].tri,
each points are u.p[(i+1)%3], u.p[(i+2)%3]
calculation involves O(IVI^6) */
const double inf = 1e9;
double eps = 1e-6; // 0 when integer
// return p4 is in circumcircle of tri(p1,p2,p3)
bool in_cc(P &p1, P &p2, P &p3, P &p4) {
    double u11 = p1.x - p4.x, u12 = p1.y - p4.y;
    double u21 = p2.x - p4.x, u22 = p2.y - p4.y;
    double u31 = p3.x - p4.x, u32 = p3.y - p4.y;
    double u13 = sq(p1.x) - sq(p4.x) + sq(p1.y) - sq(p4.y);
    double u23 = sq(p2.x) - sq(p4.x) + sq(p2.y) - sq(p4.y);
    double u33 = sq(p3.x) - sq(p4.x) + sq(p3.y) - sq(p4.y);
    double det = -u13 * u22 * u31 + u12 * u23 * u31 + u13 * u21 *
        u32 - u11 * u23 * u32 - u12 * u21 * u33 + u11 * u22 * u33;
    return det > eps;
}

double side(P &a, P &b, P &p) { return (b - a) ^ (p - a); }
struct Tri;
struct Edge {
    Tri *tri;
    int side;
    Edge() : tri(0), side(0) {}
    Edge(Tri *_tri, int _side) : tri(_tri), side(_side) {}
};
struct Tri {
    P p[3];
    Edge edge[3];
    Tri *chd[3];
    Tri() {}
    Tri(P p0, P p1, P p2) {
        p[0] = p0;
        p[1] = p1;
        p[2] = p2;
        chd[0] = chd[1] = chd[2] = 0;
    }
    bool has_chd() { return chd[0] != 0; }
    int num_chd() {
        return chd[0] == 0 ? 0 : chd[1] == 0 ? 1 : chd[2] == 0 ? 2 : 3;
    }
    bool contains(P &q) {
        for (int i = 0; i < 3; ++i)
            if (side(p[i], p[(i + 1) % 3], q) < -eps) return false;
        return true;
    }
} pool[maxn * 10], *tris;
void edge(Edge a, Edge b) {
    if (a.tri) a.tri->edge[a.side] = b;
    if (b.tri) b.tri->edge[b.side] = a;
}
struct Trig { // Triangulation
    Trig() {
        the_root =
            new (tris++) Tri(P(-inf, -inf), P(inf * 2, -inf), P(-inf,
                inf * 2));
    } // all p should in
    Tri *find(P p) { return find(the_root, p); }
    void add_point(P &p) { add_point(find(the_root, p), p); }
    Tri *the_root;
    static Tri *find(Tri *root, P &p) {
        while (true) {
            if (!root->has_chd()) return root;
            for (int i = 0; i < 3 && root->chd[i]; ++i)
                if (root->chd[i]->contains(p)) {
                    root = root->chd[i];
                    break;
                }
        }
        assert(false); // "point not found"
    }
    void add_point(Tri *root, P &p) {
        Tri *tab, *tbc, *tca;
        /* split it into three triangles */
        tab = new (tris++) Tri(root->p[0], root->p[1], p);
        tbc = new (tris++) Tri(root->p[1], root->p[2], p);
        tca = new (tris++) Tri(root->p[2], root->p[0], p);
        edge(Edge(tab, 0), Edge(tbc, 1));
        edge(Edge(tbc, 0), Edge(tca, 1));
        edge(Edge(tca, 0), Edge(tab, 1));
        edge(Edge(tab, 2), root->edge[2]);
        edge(Edge(tbc, 2), root->edge[0]);
    }
}

```

```

    edge(Edge(tca, 2), root->edge[1]);
    root->chd[0] = tab;
    root->chd[1] = tbc;
    root->chd[2] = tca;
    flip(tab, 2);
    flip(tbc, 2);
    flip(tca, 2);
}
void flip(Tri *tri, int pi) {
    Tri *trj = tri->edge[pi].tri;
    int pj = tri->edge[pi].side;
    if (!trj) return;
    if (!in_cc(tri->p[0], tri->p[1], tri->p[2], trj->p[pj]))
        return;
    /* flip edge between tri, trj */
    Tri *trk = new (tris++) Tri(tri->p[(pi + 1) % 3], trj->p[pj],
    tri->p[pi]);
    Tri *trl = new (tris++) Tri(trj->p[(pj + 1) % 3], tri->p[pi],
    trj->p[pj]);
    edge(Edge(trk, 0), Edge(trl, 0));
    edge(Edge(trk, 1), tri->edge[(pi + 2) % 3]);
    edge(Edge(trk, 2), trj->edge[(pj + 1) % 3]);
    edge(Edge(trl, 1), trj->edge[(pj + 2) % 3]);
    edge(Edge(trl, 2), tri->edge[(pi + 1) % 3]);
    tri->chd[0] = trk;
    tri->chd[1] = trl;
    tri->chd[2] = 0;
    trj->chd[0] = trk;
    trj->chd[1] = trl;
    trj->chd[2] = 0;
    flip(trk, 1);
    flip(trk, 2);
    flip(trl, 1);
    flip(trl, 2);
}
};
vector<Tri *> triang;
set<Tri *> vst;
void go(Tri *now) {
    if (vst.find(now) != vst.end()) return;
    vst.insert(now);
    if (!now->has_chd()) {
        triang.push_back(now);
        return;
    }
    for (int i = 0; i < now->num_chd(); ++i) go(now->chd[i]);
}
void build(int n, P *ps) { // shuffle before call
    tris = pool;
    random_shuffle(ps, ps + n);
    Trig tri;
    for (int i = 0; i < n; ++i) tri.add_point(ps[i]);
    go(tri.the_root);
}
}

```

8.4 Sector Area

```

// calc area of sector which include a, b
double SectorArea(P a, P b, double r) {
    double o = atan2(a.y, a.x) - atan2(b.y, b.x);
    while (o <= 0) o += 2 * pi;
    while (o >= 2 * pi) o -= 2 * pi;
    o = min(o, 2 * pi - o);
    return r * r * o / 2;
}

```

8.5 Half Plane Intersection

```

bool jizz(L l1, L l2, L l3) {
    P p = Intersect(l2, l3);
    return ((l1.pb - l1.pa) ^ (p - l1.pa)) < -eps;
}

bool cmp(const L &a, const L &b) {
    return same(a.o, b.o) ? ((b.pb - b.pa) ^ (a.pb - b.pa)) > eps : a.o < b.o;
}

// availble area for L l is (l.pb - l.pa) ^ (p - l.pa) > 0
vector<P> HPI(vector<L> &ls) {
    sort(ls.begin(), ls.end(), cmp);
    vector<L> pls(1, ls[0]);
}

```

```

for (int i = 0; i < (int) ls.size(); ++i) if (!same(ls[i].o, pls.back().o)) pls.push_back(ls[i]);
deque<int> dq; dq.push_back(0); dq.push_back(1);
#define meow(a, b, c) while (dq.size() > 1u && jizz(pls[a], pls[b], pls[c]))
for (int i = 2; i < (int) pls.size(); ++i) {
    meow(i, dq.back(), dq[dq.size() - 2]); dq.pop_back();
    meow(i, dq[0], dq[1]); dq.pop_front();
    dq.push_back(i);
}
meow(dq.front(), dq.back(), dq[dq.size() - 2]); dq.pop_back();
meow(dq.back(), dq[0], dq[1]); dq.pop_front();
if (dq.size() < 3u) return vector<P>(); // no solution or
solution is not a convex
vector<P> rt;
for (int i = 0; i < (int) dq.size(); ++i) rt.push_back(Intersect(pls[dq[i]], pls[dq[(i + 1) % dq.size()]]));
return rt;
}

```

8.6 Rotating Sweep Line

```

void rotatingSweepLine(vector<pair<int, int>> &ps) {
    int n = (int) ps.size();
    vector<int> id(n), pos(n);
    vector<pair<int, int>> line(n * (n - 1) / 2);
    int m = -1;
    for (int i = 0; i < n; ++i) for (int j = i + 1; j < n; ++j) line[++m] = make_pair(i, j);
    sort(line.begin(), line.end(), [&](const pair<int, int> &a, const pair<int, int> &b) -> bool {
        if (ps[a.first].first == ps[a.second].first) return 0;
        if (ps[b.first].first == ps[b.second].first) return 1;
        return (double)(ps[a.first].second - ps[a.second].second) / (ps[a.first].first - ps[a.second].first) < (double)(ps[b.first].second - ps[b.second].second) / (ps[b.first].first - ps[b.second].first);
    });
    for (int i = 0; i < n; ++i) id[i] = i;
    sort(id.begin(), id.end(), [&](const int &a, const int &b) {
        return ps[a] < ps[b]; });
    for (int i = 0; i < n; ++i) pos[id[i]] = i;

    for (int i = 0; i < m; ++i) {
        auto l = line[i];
        // meow
        tie(pos[l.first], pos[l.second], id[pos[l.first]], id[pos[l.second]]) = make_tuple(pos[l.second], pos[l.first], l.second, l.first);
    }
}

```

8.7 Triangle Center

```

Point TriangleCircumCenter(Point a, Point b, Point c) {
    Point res;
    double a1 = atan2(b.y - a.y, b.x - a.x) + pi / 2;
    double a2 = atan2(c.y - b.y, c.x - b.x) + pi / 2;
    double ax = (a.x + b.x) / 2;
    double ay = (a.y + b.y) / 2;
    double bx = (c.x + b.x) / 2;
    double by = (c.y + b.y) / 2;
    double r1 = (sin(a2) * (ax - bx) + cos(a2) * (by - ay)) / (sin(a1) * cos(a2) - sin(a2) * cos(a1));
    return Point(ax + r1 * cos(a1), ay + r1 * sin(a1));
}

Point TriangleMassCenter(Point a, Point b, Point c) {
    return (a + b + c) / 3.0;
}

Point TriangleOrthoCenter(Point a, Point b, Point c) {
    return TriangleMassCenter(a, b, c) * 3.0 - TriangleCircumCenter(a, b, c) * 2.0;
}

Point TriangleInnerCenter(Point a, Point b, Point c) {
    Point res;
    double la = len(b - c);
    double lb = len(a - c);
    double lc = len(a - b);
}

```

```

    res.x = (la * a.x + lb * b.x + lc * c.x) / (la + lb + lc);
    res.y = (la * a.y + lb * b.y + lc * c.y) / (la + lb + lc);
    return res;
}

```

8.8 Polygon Center

```

Point BaryCenter(vector<Point> &p, int n) {
    Point res(0, 0);
    double s = 0.0, t;
    for (int i = 1; i < p.size(); i++) {
        t = Cross(p[i] - p[0], p[i + 1] - p[0]) / 2;
        s += t;
        res.x += (p[0].x + p[i].x + p[i + 1].x) * t;
        res.y += (p[0].y + p[i].y + p[i + 1].y) * t;
    }
    res.x /= (3 * s);
    res.y /= (3 * s);
    return res;
}

```

8.9 Maximum Triangle

```

double ConvexHullMaxTriangleArea(Point p[], int res[], int
    chnum) {
    double area = 0, tmp;
    res[chnum] = res[0];
    for (int i = 0, j = 1, k = 2; i < chnum; i++) {
        while (fabs(Cross(p[res[j]] - p[res[i]], p[res[(k + 1) %
            chnum]] - p[res[i]])) > fabs(Cross(p[res[j]] - p[res[i]],
            p[res[k]] - p[res[i]]))) k = (k + 1) % chnum;
        tmp = fabs(Cross(p[res[j]] - p[res[i]], p[res[k]] - p[res[i]
            ])));
        if (tmp > area) area = tmp;
        while (fabs(Cross(p[res[(j + 1) % chnum]] - p[res[i]], p[
            res[k]] - p[res[i]])) > fabs(Cross(p[res[j]] - p[res[i]],
            p[res[k]] - p[res[i]]))) j = (j + 1) % chnum;
        tmp = fabs(Cross(p[res[j]] - p[res[i]], p[res[k]] - p[res[i]
            ])));
        if (tmp > area) area = tmp;
    }
    return area / 2;
}

```

8.10 Point in Polygon

```

int pip(vector<P> ps, P p) {
    int c = 0;
    for (int i = 0; i < ps.size(); ++i) {
        int a = i, b = (i + 1) % ps.size();
        L l(ps[a], ps[b]);
        P q = l.project(p);
        if ((p - q).abs() < eps && l.inside(q)) return 1;
        if (same(ps[a].y, ps[b].y) && same(ps[a].y, p.y)) continue;
        if (ps[a].y > ps[b].y) swap(a, b);
        if (ps[a].y <= p.y && p.y < ps[b].y && p.x <= ps[a].x + (ps
            [b].x - ps[a].x) / (ps[b].y - ps[a].y) * (p.y - ps[a].y))
            ++c;
    }
    return (c & 1) * 2;
}

```

8.11 Circle

```

struct C {
    P c;
    double r;
    C(P c = P(0, 0), double r = 0) : c(c), r(r) {}
};

vector<P> Intersect(C a, C b) {
    if (a.r > b.r) swap(a, b);
    double d = (a.c - b.c).abs();
    vector<P> p;
    if (same(a.r + b.r, d)) p.push_back(a.c + (b.c - a.c).unit()
        * a.r);
    else if (a.r + b.r > d && d + a.r >= b.r) {

```

```

        double o = acos((sq(a.r) + sq(d) - sq(b.r)) / (2 * a.r * d)
            );
        P i = (b.c - a.c).unit();
        p.push_back(a.c + i.spin(o) * a.r);
        p.push_back(a.c + i.spin(-o) * a.r);
    }
    return p;
}

double IntersectArea(C a, C b) {
    if (a.r > b.r) swap(a, b);
    double d = (a.c - b.c).abs();
    if (d >= a.r + b.r - eps) return 0;
    if (d + a.r <= b.r + eps) return sq(a.r) * acos(-1);
    double p = acos((sq(a.r) + sq(d) - sq(b.r)) / (2 * a.r * d));
    double q = acos((sq(b.r) + sq(d) - sq(a.r)) / (2 * b.r * d));
    return p * sq(a.r) + q * sq(b.r) - a.r * d * sin(p);
}

// remove second level if to get points for line (default:
// segment)
vector<P> CircleCrossLine(P a, P b, P o, double r) {
    double x = b.x - a.x, y = b.y - a.y, A = sq(x) + sq(y), B = 2
        * x * (a.x - o.x) + 2 * y * (a.y - o.y);
    double C = sq(a.x - o.x) + sq(a.y - o.y) - sq(r), d = B * B -
        4 * A * C;
    vector<P> t;
    if (d >= -eps) {
        d = max(0., d);
        double i = (-B - sqrt(d)) / (2 * A);
        double j = (-B + sqrt(d)) / (2 * A);
        if (i - 1.0 <= eps && i >= -eps) t.emplace_back(a.x + i * x
            , a.y + i * y);
        if (j - 1.0 <= eps && j >= -eps) t.emplace_back(a.x + j * x
            , a.y + j * y);
    }
    return t;
}

// calc area intersect by circle with radius r and triangle OAB
double AreaOfCircleTriangle(P a, P b, double r) {
    bool ina = a.abs() < r, inb = b.abs() < r;
    auto p = CircleCrossLine(a, b, P(0, 0), r);
    if (ina) {
        if (inb) return abs(a ^ b) / 2;
        return SectorArea(b, p[0], r) + abs(a ^ p[0]) / 2;
    }
    if (inb) return SectorArea(p[0], a, r) + abs(p[0] ^ b) / 2;
    if (p.size() == 2u) return SectorArea(a, p[0], r) +
        SectorArea(p[1], b, r) + abs(p[0] ^ p[1]) / 2;
    else return SectorArea(a, b, r);
}

// for any triangle
double AreaOfCircleTriangle(vector<P> ps, double r) {
    double ans = 0;
    for (int i = 0; i < 3; ++i) {
        int j = (i + 1) % 3;
        double o = atan2(ps[i].y, ps[i].x) - atan2(ps[j].y, ps[j].x
            );
        if (o >= pi) o = o - 2 * pi;
        if (o <= -pi) o = o + 2 * pi;
        ans += AreaOfCircleTriangle(ps[i], ps[j], r) * (o >= 0 ? 1
            : -1);
    }
    return abs(ans);
}

```

8.12 Tangent of Circles and Points to Circle

```

vector<L> tangent(C a, C b) {
#define Pij \
    P i = (b.c - a.c).unit() * a.r, j = P(i.y, -i.x);\
    z.emplace_back(a.c + i, a.c + j);
#define deo(I,J) \
    double d = (a.c - b.c).abs(), e = a.r I b.r, o = acos(e / d)
    ;\
    P i = (b.c - a.c).unit(), j = i.spin(o), k = i.spin(-o);\
    z.emplace_back(a.c + j * a.r, b.c J j * b.r);\
    z.emplace_back(a.c + k * a.r, b.c J k * b.r);
    if (a.r < b.r) swap(a, b);
    vector<L> z;
    if ((a.c - b.c).abs() + b.r < a.r) return z;
    else if (same((a.c - b.c).abs() + b.r, a.r)) { Pij; }
    else {
        deo(+,+);
        if (same(d, a.r + b.r)) { Pij; }
        else if (d > a.r + b.r) { deo(+,-); }
    }
}

```



```

    return z;
}

vector<L> tangent(C c, P p) {
    vector<L> z;
    double d = (p - c.c).abs();
    if (same(d, c.r)) {
        P i = (p - c.c).spin(pi / 2);
        z.emplace_back(p, p + i);
    } else if (d > c.r) {
        double o = acos(c.r / d);
        P i = (p - c.c).unit(), j = i.spin(o) * c.r, k = i.spin(-o) * c.r;
        z.emplace_back(c.c + j, p);
        z.emplace_back(c.c + k, p);
    }
    return z;
}

```

8.13 Area of Union of Circles

```

vector<pair<double, double>> CoverSegment(C &a, C &b) {
    double d = (a.c - b.c).abs();
    vector<pair<double, double>> res;
    if (same(a.r + b.r, d)) {
        else if (d <= abs(a.r - b.r) + eps) {
            if (a.r < b.r) res.emplace_back(0, 2 * pi);
        } else if (d < abs(a.r + b.r) - eps) {
            double o = acos((sq(a.r) + sq(d) - sq(b.r)) / (2 * a.r * d));
            z = (b.c - a.c).angle();
            if (z < 0) z += 2 * pi;
            double l = z - o, r = z + o;
            if (l < 0) l += 2 * pi;
            if (r > 2 * pi) r -= 2 * pi;
            if (l > r) res.emplace_back(l, 2 * pi), res.emplace_back(0, r);
            else res.emplace_back(l, r);
        }
    }
    return res;
}

double CircleUnionArea(vector<C> c) { // circle should be identical
    int n = c.size();
    double a = 0, w;
    for (int i = 0; w = 0, i < n; ++i) {
        vector<pair<double, double>> s = {{2 * pi, 9}}, z;
        for (int j = 0; j < n; ++j) if (i != j) {
            z = CoverSegment(c[i], c[j]);
            for (auto &e : z) s.push_back(e);
        }
        sort(s.begin(), s.end());
        auto F = [&](double t) { return c[i].r * (c[i].r * t + c[i].c.x * sin(t) - c[i].c.y * cos(t)); };
        for (auto &e : s) {
            if (e.first > w) a += F(e.first) - F(w);
            w = max(w, e.second);
        }
    }
    return a * 0.5;
}

```

8.14 Minimun Distance of 2 Polygons

```

// p, q is convex
double TwoConvexHullMinDist(Point P[], Point Q[], int n, int m)
{
    int YMinP = 0, YMaxQ = 0;
    double tmp, ans = 999999999;
    for (i = 0; i < n; ++i) if (P[i].y < P[YMinP].y) YMinP = i;
    for (i = 0; i < m; ++i) if (Q[i].y > Q[YMaxQ].y) YMaxQ = i;
    P[n] = P[0], Q[m] = Q[0];
    for (int i = 0; i < n; ++i) {
        while (tmp = Cross(Q[YMaxQ + 1] - P[YMinP + 1], P[YMinP] - P[YMinP + 1]) > Cross(Q[YMaxQ] - P[YMinP + 1], P[YMinP] - P[YMinP + 1])) YMaxQ = (YMaxQ + 1) % m;
        if (tmp < 0) ans = min(ans, PointToSegDist(P[YMinP], P[YMinP + 1], Q[YMaxQ]));
        else ans = min(ans, TwoSegMinDist(P[YMinP], P[YMinP + 1], Q[YMaxQ], Q[YMaxQ + 1]));
        YMinP = (YMinP + 1) % n;
    }
    return ans;
}

```

8.15 2D Convex Hull

```

bool operator < (const P &a, const P &b) { return same(a.x, b.x) ? a.y < b.y : a.x < b.x; }
bool operator > (const P &a, const P &b) { return same(a.x, b.x) ? a.y > b.y : a.x > b.x; }

#define crx(a, b, c) ((b - a) ^ (c - a))

vector<P> convex(vector<P> ps) {
    vector<P> p;
    sort(ps.begin(), ps.end(), [&](P a, P b) { return same(a.x, b.x) ? a.y < b.y : a.x < b.x; });
    for (int i = 0; i < ps.size(); ++i) {
        while (p.size() >= 2 && crx(p[p.size() - 2], ps[i], p[p.size() - 1]) >= 0) p.pop_back();
        p.push_back(ps[i]);
    }
    int t = p.size();
    for (int i = (int)p.size() - 2; i >= 0; --i) {
        while (p.size() > t && crx(p[p.size() - 2], ps[i], p[p.size() - 1]) >= 0) p.pop_back();
        p.push_back(ps[i]);
    }
    p.pop_back();
    return p;
}

int sgn(double x) { return same(x, 0) ? 0 : x > 0 ? 1 : -1; }

P isLL(P p1, P p2, P q1, P q2) {
    double a = crx(q1, q2, p1), b = -crx(q1, q2, p2);
    return (p1 * b + p2 * a) / (a + b);
}

struct CH {
    int n;
    vector<P> p, u, d;
    CH() {}
    CH(vector<P> ps) : p(ps) {
        n = ps.size();
        rotate(p.begin(), min_element(p.begin(), p.end()), p.end());
        ;
        auto t = max_element(p.begin(), p.end());
        d = vector<P>(p.begin(), next(t));
        u = vector<P>(t, p.end()); u.push_back(p[0]);
    }
    int find(vector<P> &v, P d) {
        int l = 0, r = v.size();
        while (l + 5 < r) {
            int L = (l * 2 + r) / 3, R = (l + r * 2) / 3;
            if (v[L] * d > v[R] * d) r = R;
            else l = L;
        }
        int x = l;
        for (int i = l + 1; i < r; ++i) if (v[i] * d > v[x] * d) x = i;
        return x;
    }
    int findForest(P v) {
        if (v.y > 0 || v.y == 0 && v.x > 0) return ((int)d.size() - 1 + find(u, v)) % p.size();
        return find(d, v);
    }
}

P get(int l, int r, P a, P b) {
    int s = sgn(crx(a, b, p[l % n]));
    while (l + 1 < r) {
        int m = (l + r) >> 1;
        if (sgn(crx(a, b, p[m % n])) == s) l = m;
        else r = m;
    }
    return isLL(a, b, p[l % n], p[(l + 1) % n]);
}

vector<P> getIS(P a, P b) {
    int X = findForest((b - a).spin(pi / 2));
    int Y = findForest((a - b).spin(pi / 2));
    if (X > Y) swap(X, Y);
    if (sgn(crx(a, b, p[X])) * sgn(crx(a, b, p[Y])) < 0) return {get(X, Y, a, b), get(Y, X + n, a, b)};
    return {};
}

void update_tangent(P q, int i, int &a, int &b) {
    if (sgn(crx(q, p[a], p[i])) > 0) a = i;
    if (sgn(crx(q, p[b], p[i])) < 0) b = i;
}

void bs(int l, int r, P q, int &a, int &b) {
    if (l == r) return;
}

```

```

    update_tangent(q, l % n, a, b);
    int s = sgn(crx(q, p[l % n], p[(l + 1) % n]));
    while (l + 1 < r) {
        int m = (l + r) >> 1;
        if (sgn(crx(q, p[m % n], p[(m + 1) % n])) == s) l = m;
        else r = m;
    }
    update_tangent(q, r % n, a, b);
}
bool contain(P p) {
    if (p.x < d[0].x || p.x > d.back().x) return 0;
    auto it = lower_bound(d.begin(), d.end(), P(p.x, -1e12));
    if (it->x == p.x) {
        if (it->y > p.y) return 0;
    } else if (crx(*prev(it), *it, p) < -eps) return 0;
    it = lower_bound(u.begin(), u.end(), P(p.x, 1e12), greater<
        P>());
    if (it->x == p.x) {
        if (it->y < p.y) return 0;
    } else if (crx(*prev(it), *it, p) < -eps) return 0;
    return 1;
}
bool get_tangent(P p, int &a, int &b) { // b -> a
    if (contain(p)) return 0;
    a = b = 0;
    int i = lower_bound(d.begin(), d.end(), p) - d.begin();
    bs(0, i, p, a, b);
    bs(i, d.size(), p, a, b);
    i = lower_bound(u.begin(), u.end(), p, greater<P>()) - u.
        begin();
    bs((int)d.size() - 1, (int)d.size() - 1 + i, p, a, b);
    bs((int)d.size() - 1 + i, (int)d.size() - 1 + u.size(), p,
        a, b);
    return 1;
}
};

```

```

    return 1;
}()return;
if([&]()->int{
    for(int i=3;i<n;++i)if(abs(((p[1]-p[0])^(p[2]-p[0]))*(p[i]-
        p[0]))>eps)return swap(p[3],p[i]),0;
    return 1;
}()return;
for(int i=0;i<4;++i){
    T t((i+1)%4,(i+2)%4,(i+3)%4,1);
    if(on(t,p[i]))swap(t.b,t.c);
    id[t.a][t.b]=id[t.b][t.c]=id[t.c][t.a]=m;
    f[m++]=t;
}
for(int i=4;i<n;++i)for(int j=0;j<m;++j)if(f[j].res && on(f[j]
    ],p[i])){
    dfs(i,j);
    break;
}
int mm=m; m=0;
for(int i=0;i<mm;++i)if(f[i].res)f[m++]=f[i];
}
bool same(int i,int j){
    return !absvol(p[f[i].a],p[f[i].b],p[f[i].c],p[f[j].a])>eps
        || absvol(p[f[i].a],p[f[i].b],p[f[i].c],p[f[j].b])>eps ||
        absvol(p[f[i].a],p[f[i].b],p[f[i].c],p[f[j].c])>eps;
}
int faces(){
    int r=0;
    for(int i=0;i<m;++i){
        int iden=1;
        for(int j=0;j<i;++j)if(same(i,j))iden=0;
        r+=iden;
    }
    return r;
}
}
} tb;

```

8.16 3D Convex Hull

```

double absvol(const P a,const P b,const P c,const P d){
    return abs(((b-a)^(c-a))*(d-a))/6;
}
struct convex3D{
    static const int maxn=1010;
    struct T{
        int a,b,c;
        bool res;
        T(){}
        T(int a,int b,int c,bool res=1):a(a),b(b),c(c),res(res){}
    };
    int n,m;
    P p[maxn];
    T f[maxn*8];
    int id[maxn][maxn];
    bool on(T &t,P &q){
        return ((p[t.c]-p[t.b])^(p[t.a]-p[t.b]))*(q-p[t.a])>eps;
    }
    void meow(int q,int a,int b){
        int f2=id[a][b];
        if(f[f2].res){
            if(on(f[f2],p[q]))dfs(q,f2);
        } else{
            id[q][b]=id[a][q]=id[b][a]=m;
            f[m++]=T(b,a,q,1);
        }
    }
}
void dfs(int p,int i){
    f[i].res=0;
    meow(p,f[i].b,f[now].a);
    meow(p,f[i].c,f[now].b);
    meow(p,f[i].a,f[now].c);
}
void operator()(){
    if(n<4)return;
    if([&]()->int{
        for(int i=1;i<n;++i)if(abs(p[0]-p[i])>eps)return swap(p[1],
            p[i]),0;
        return 1;
    }()return;
    if([&]()->int{
        for(int i=2;i<n;++i)if(abs((p[0]-p[i])^(p[1]-p[i]))>eps)
            return swap(p[2],p[i]),0;
    }
}

```

8.17 Minimum Enclosing Circle

```

pt center(const pt &a, const pt &b, const pt &c) {
    pt p0 = b - a, p1 = c - a;
    double c1 = norm2(p0) * 0.5, c2 = norm2(p1) * 0.5;
    double d = p0 ^ p1;
    double x = a.x + (c1 * p1.y - c2 * p0.y) / d;
    double y = a.y + (c2 * p0.x - c1 * p1.x) / d;
    return pt(x, y);
}
circle min_enclosing(vector<pt> &p) {
    random_shuffle(p.begin(), p.end());
    double r = 0.0;
    pt cent;
    for (int i = 0; i < p.size(); ++i) {
        if (norm2(cent - p[i]) <= r) continue;
        cent = p[i];
        r = 0.0;
        for (int j = 0; j < i; ++j) {
            if (norm2(cent - p[j]) <= r) continue;
            cent = (p[i] + p[j]) / 2;
            r = norm2(p[j] - cent);
            for (int k = 0; k < j; ++k) {
                if (norm2(cent - p[k]) <= r) continue;
                cent = center(p[i], p[j], p[k]);
                r = norm2(p[k] - cent);
            }
        }
    }
    return circle(cent, sqrt(r));
}

```

8.18 Closest Pair

```

double closest_pair(int l, int r) {
    // p should be sorted increasingly according to the x-
    // coordinates.
    if (l == r) return 1e9;
    if (r - l == 1) return dist(p[l], p[r]);
    int m = (l + r) >> 1;
    double d = min(closest_pair(l, m), closest_pair(m + 1, r));
    vector<int> vec;
    for (int i = m; i >= l && fabs(p[m].x - p[i].x) < d; --i) vec
        .push_back(i);
}

```

```

for (int i = m + 1; i <= r && fabs(p[m].x - p[i].x) < d; ++i)
    vec.push_back(i);
sort(vec.begin(), vec.end(), [&](int a, int b) { return p[a].
    y < p[b].y; });
for (int i = 0; i < vec.size(); ++i) {
    for (int j = i + 1; j < vec.size() && fabs(p[vec[j]].y - p[
        vec[i]].y) < d; ++j) {
        d = min(d, dist(p[vec[i]], p[vec[j]]));
    }
}
return d;
}
}

```

9 Miscellaneous

9.1 Bitwise Hack

```

long long next_perm(long long v) {
    long long t = v | (v - 1);
    return (t + 1) | (((~t & --t) - 1) >> (__builtin_ctz(v) + 1))
        ;
}
void subset(long long s) {
    long long sub = s;
    while (sub) sub = (sub - 1) & s;
}

```

9.2 Hilbert's Curve (faster Mo's algorithm)

```

long long hilbert(int n, int x, int y) {
    long long res = 0;
    for (int s = n / 2; s; s >>= 1) {
        int rx = (x & s) > 0;
        int ry = (y & s) > 0;
        res += s * 111 * s * ((3 * rx) ^ ry);
        if (ry == 0) {
            if (rx == 1) {
                x = s - 1 - x;
                y = s - 1 - y;
            }
            swap(x, y);
        }
    }
    return res;
}

```

9.3 Java

```

import java.io.*;
import java.util.*;
import java.lang.*;
import java.math.*;

public class filename{
    static Scanner in = new Scanner(System.in);
    public static void main(String[] args) throws Exception {
        Scanner fin = new Scanner(new File("infile"));
        PrintWriter fout = new PrintWriter("outfile", "UTF-8");
        fout.println(fin.nextLine());
        fout.close();
        while (in.hasNext()) {
            String str = in.nextLine(); // getline
            String stu = in.next(); // string
        }
        System.out.println("Case #" + t);
        System.out.printf("%d\n", 7122);
        int[][] d = {{7,1,2,2},{8,7}};
        int g = Integer.parseInt("-123");

        long f = (long)d[0][2];

        List<Integer> l = new ArrayList<>();
        Random rg = new Random();
        for (int i = 9; i >= 0; --i) {
            l.add(Integer.valueOf(rg.nextInt(100) + 1));
            l.add(Integer.valueOf((int)(Math.random() * 100) + 1));
        }
        Collections.sort(l, new Comparator<Integer>() {

```

```

        public int compare(Integer a, Integer b) { return a - b;
        }
    });
    for (int i = 0; i < l.size(); ++i)
        System.out.print(l.get(i));

    Set<String> s = new HashSet<String>(); // TreeSet
    s.add("jizz");
    System.out.println(s);
    System.out.println(s.contains("jizz"));

    Map<String, Integer> m = new HashMap<String, Integer>();
    m.put("lol", 7122);
    System.out.println(m);
    for (String key: m.keySet())
        System.out.println(key + " : " + m.get(key));
    System.out.println(m.containsKey("lol"));
    System.out.println(m.containsValue(7122));

    System.out.println(Math.PI);
    System.out.println(Math.acos(-1));

    BigInteger bi = in.nextBigInteger(), bj = new BigInteger("
        -7122"), bk = BigInteger.valueOf(17171);
    int sgn = bi.signum(); // sign(bi)
    bi = bi.subtract(BigInteger.ONE).multiply(bj).divide(bj).
        and(bj).gcd(bj).max(bj).pow(87);
    int meow = bi.compareTo(bj); // -1 0 1
    String stz = "f5abd69150";
    BigInteger b16 = new BigInteger(stz, 16);
    System.out.println(b16.toString(2));
}
}

```

9.4 Dancing Links

```

namespace dlx {
int lt[maxn], rg[maxn], up[maxn], dn[maxn], cl[maxn], rw[maxn],
    bt[maxn], s[maxn], head, sz, ans;
void init(int c) {
    for (int i = 0; i < c; ++i) {
        up[i] = dn[i] = bt[i] = i;
        lt[i] = i == 0 ? c : i - 1;
        rg[i] = i == c - 1 ? c : i + 1;
        s[i] = 0;
    }
    rg[c] = 0, lt[c] = c - 1;
    up[c] = dn[c] = -1;
    head = c, sz = c + 1;
}
void insert(int r, const vector<int> &col) {
    if (col.empty()) return;
    int f = sz;
    for (int i = 0; i < (int)col.size(); ++i) {
        int c = col[i], v = sz++;
        dn[bt[c]] = v;
        up[v] = bt[c], bt[c] = v;
        rg[v] = (i + 1 == (int)col.size() ? f : v + 1);
        rw[v] = r, cl[v] = c;
        ++s[c];
        if (i > 0) lt[v] = v - 1;
    }
    lt[f] = sz - 1;
}
void remove(int c) {
    lt[rg[c]] = lt[c], rg[lt[c]] = rg[c];
    for (int i = dn[c]; i != c; i = dn[i]) {
        for (int j = rg[i]; j != i; j = rg[j]) {
            up[dn[j]] = up[j], dn[up[j]] = dn[j];
            --s[cl[j]];
        }
    }
}
void restore(int c) {
    for (int i = up[c]; i != c; i = up[i]) {
        for (int j = lt[i]; j != i; j = lt[j]) {
            ++s[cl[j]];
            up[dn[j]] = j, dn[up[j]] = j;
        }
    }
    lt[rg[c]] = c, rg[lt[c]] = c;
}
// Call dlx::make after inserting all rows.
void make(int c) {

```

```

    for (int i = 0; i < c; ++i)
        dn[bt[i]] = i, up[i] = bt[i];
}
void dfs(int dep) {
    if (dep >= ans) return;
    if (rg[head] == head) return ans = dep, void();
    if (dn[rg[head]] == rg[head]) return;
    int c = rg[head];
    int w = c;
    for (int x = c; x != head; x = rg[x]) {
        if (s[x] < s[w]) w = x;
    }
    remove(w);
    for (int i = dn[w]; i != w; i = dn[i]) {
        for (int j = rg[i]; j != i; j = rg[j]) remove(cl[j]);
        dfs(dep + 1);
        for (int j = lt[i]; j != i; j = lt[j]) restore(cl[j]);
    }
    restore(w);
}
int solve() {
    ans = 1e9, dfs(0);
    return ans;
}
}

```

```

long long lc = c, rc = c;
djs.save();
for (int i = 0; i < (int)x.size(); ++i) {
    lc += cost[x[i]];
    djs.merge(st[x[i]], ed[x[i]]);
}
solve(l, m, y, lc);
djs.undo();
x.clear(), y.clear();
for (int i = m + 1; i <= r; ++i) cnt[qr[i].first]++;
for (int i = l; i <= m; ++i) {
    cnt[qr[i].first]--;
    if (cnt[qr[i].first] == 0) rv.push_back(qr[i].first);
}
contract(m + 1, r, rv, x, y);
djs.save();
for (int i = 0; i < (int)x.size(); ++i) {
    rc += cost[x[i]];
    djs.merge(st[x[i]], ed[x[i]]);
}
solve(m + 1, r, y, rc);
djs.undo();
for (int i = l; i <= m; ++i) cnt[qr[i].first]++;
}

```

9.5 Offline Dynamic MST

```

int cnt[maxn], cost[maxn], st[maxn], ed[maxn];
pair<int, int> qr[maxn];
// qr[i].first = id of edge to be changed, qr[i].second =
// weight after operation
// cnt[i] = number of operation on edge i
// call solve(0, q - 1, v, 0), where v contains edges i such
// that cnt[i] == 0
void contract(int l, int r, vector<int> v, vector<int> &x,
vector<int> &y) {
    sort(v.begin(), v.end(), [&](int i, int j) {
        if (cost[i] == cost[j]) return i < j;
        return cost[i] < cost[j];
    });
    djs.save();
    for (int i = l; i <= r; ++i) djs.merge(st[qr[i].first], ed[qr[i].first]);
    for (int i = 0; i < (int)v.size(); ++i) {
        if (djs.find(st[v[i]]) != djs.find(ed[v[i]])) {
            x.push_back(v[i]);
            djs.merge(st[v[i]], ed[v[i]]);
        }
    }
    djs.undo();
    djs.save();
    for (int i = 0; i < (int)x.size(); ++i) djs.merge(st[x[i]], ed[x[i]]);
    for (int i = 0; i < (int)v.size(); ++i) {
        if (djs.find(st[v[i]]) != djs.find(ed[v[i]])) {
            y.push_back(v[i]);
            djs.merge(st[v[i]], ed[v[i]]);
        }
    }
    djs.undo();
}
void solve(int l, int r, vector<int> v, long long c) {
    if (l == r) {
        cost[qr[l].first] = qr[l].second;
        if (st[qr[l].first] == ed[qr[l].first]) {
            printf("%lld\n", c);
            return;
        }
        int minv = qr[l].second;
        for (int i = 0; i < (int)v.size(); ++i) minv = min(minv, cost[v[i]]);
        printf("%lld\n", c + minv);
        return;
    }
    int m = (l + r) >> 1;
    vector<int> lv = v, rv = v;
    vector<int> x, y;
    for (int i = m + 1; i <= r; ++i) {
        cnt[qr[i].first]--;
        if (cnt[qr[i].first] == 0) lv.push_back(qr[i].first);
    }
    contract(l, m, lv, x, y);
}

```

9.6 Manhattan Distance MST

```

void solve(int n) {
    init();
    vector<int> v(n), ds;
    for (int i = 0; i < n; ++i) {
        v[i] = i;
        ds.push_back(x[i] - y[i]);
    }
    sort(ds.begin(), ds.end());
    ds.resize(unique(ds.begin(), ds.end()) - ds.begin());
    sort(v.begin(), v.end(), [&](int i, int j) { return x[i] == x[j] ? y[i] > y[j] : x[i] > x[j]; });
    int j = 0;
    for (int i = 0; i < n; ++i) {
        int p = lower_bound(ds.begin(), ds.end(), x[v[i]] - y[v[i]]) - ds.begin() + 1;
        pair<int, int> q = query(p);
        // query return prefix minimum
        if (~q.second) add_edge(v[i], q.second);
        add(p, make_pair(x[v[i]] + y[v[i]], v[i]));
    }
}
void make_graph() {
    solve(n);
    for (int i = 0; i < n; ++i) swap(x[i], y[i]);
    solve(n);
    for (int i = 0; i < n; ++i) x[i] = -x[i];
    solve(n);
    for (int i = 0; i < n; ++i) swap(x[i], y[i]);
    solve(n);
}

```

9.7 IOI 2016 Alien trick

```

long long Alien() {
    long long c = kInf;
    for (int d = 60; d >= 0; --d) {
        // cost can be negative as well, depending on the problem.
        if (c - (1LL << d) < 0) continue;
        long long ck = c - (1LL << d);
        pair<long long, int> r = check(ck);
        if (r.second == k) return r.first - ck * k;
        if (r.second < k) c = ck;
    }
    pair<long long, int> r = check(c);
    return r.first - c * k;
}

```