Basic Linear Algebra Refresher

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Vector

Dot product is the sum of the product of two vectors' pairwise components:

$$\boldsymbol{x} \cdot \boldsymbol{y} = \sum_{i=1}^{n} x_i y_i$$

Angle between two vectors

$$\cos \theta = \frac{oldsymbol{x} \cdot oldsymbol{y}}{||oldsymbol{x}||||oldsymbol{y}||}$$

Length of a vector: $||x|| = \sqrt{xx}$

Orthogonal vectors if their dot product is zero.

i.e. the angle $\theta = 90^{\circ} \Leftrightarrow \cos \theta = 0$.

Projection of vector x onto vector y results the vector

$$(oldsymbol{x} \cdot oldsymbol{y}) rac{oldsymbol{y}}{||oldsymbol{y}||}$$

Linear Transformations

Scalar and vectors

$$T(k_1v_1 + k_2v_2 + ... + k_rv_r) = k_1T(v_1) + k_2T(v_2) + ... + k_rT(v_r)$$

Matrix t
multiplication $\boldsymbol{A} = \boldsymbol{B}\boldsymbol{C}$

$$a_{ij} = \sum_{k=1}^{N} b_{ik} c_{kj}$$

Matrix

Transpose

- $\bullet \ \boldsymbol{A}_{i,j}^T = \boldsymbol{A}_{j,i}$
- $(A^T)^{-1} = (A^{-1})^T$
- $\bullet \ (\boldsymbol{A} + \boldsymbol{B})^T = \boldsymbol{A}^T + \boldsymbol{B}^T$
- $\bullet \ (\boldsymbol{A}\boldsymbol{B})^T = \boldsymbol{B}^T \boldsymbol{A}^T$
- If A has only real entries, $A^T A$ is positive semi-definite.

Symmetric: $A^T = A$ Orthogonal: $A^T = A^{-1}$

Square Matrix Properties

Determinant

$$\begin{aligned} \boldsymbol{A} &= \begin{bmatrix} a & b \\ c & d \end{bmatrix} \Rightarrow det(\boldsymbol{A}) = ad - bc \\ & \boldsymbol{A} &= \begin{bmatrix} a & b & c \\ d & e & f \\ g & h & i \end{bmatrix} \\ det(\boldsymbol{A}) &= a \times det \begin{bmatrix} e & f \\ h & i \end{bmatrix} - b \times det \begin{bmatrix} d & f \\ g & i \end{bmatrix} + c \times det \begin{bmatrix} d & e \\ g & h \end{bmatrix} \end{aligned}$$

Properties

- (1) If B is obtained by multiplying any row or column in A by a scalar λ , $det(B) = \lambda det(A)$
- (2) If B is obtained by interchanging two rows or columns in A, det(B) = det(A)
- (3) $det(\mathbf{A}^T) = det(\mathbf{A})$
- (4) $B_{n\times n}$ and $A_{n\times n} \Rightarrow det(AB) = det(A)det(B)$

Inverse

$$m{A} = egin{bmatrix} a & b \ c & d \end{bmatrix} \Rightarrow m{A}^{-1} = egin{bmatrix} d & -b \ -c & a \end{bmatrix} \ m{A}m{A}^{-1} = m{A}^{-1}m{A} = m{I}$$

If $A_{(m \times n)}$ and $B_{(m \times n)}$ are both invertible:

$$(AB)^{-1} = B^{-1}A^{-1}$$

If \boldsymbol{A} is invertible:

- $\bullet \ \mathbf{A}^{-1} = \frac{adj(\mathbf{A})}{det(\mathbf{A})}$
- $det(\mathbf{A}^{-1}) = \frac{1}{det(\mathbf{A})}$

Invertability

$$det(\mathbf{A}) = \begin{cases} 0, & \text{singular} \Rightarrow \text{not invertible} \\ \text{else}, & \text{nonsingular} \Rightarrow \text{invertible} \end{cases}$$

Quadratic Forms and Positive Definitive Matrix

Quadratic Form of real, symmetric matrix $A_{n \times n}$: $x^T A x$

Quadratic form $\boldsymbol{x}^T \boldsymbol{A} \boldsymbol{x}$	Matrix
>0 for all $x \neq 0$	positive definite
≥ 0	positive semi-definite
<0	negative definite
$\neq 0$	negative semi-definite
>0 for some x and <0 for others	indefinite matrix

Necessary and sufficient conditions for A to be positive definite

- All eigenvalues of **A** are positive, or
- determinant of every principal submatrix is positive.

References

- [1] https://www.cs.utexas.edu/~dana/MLClass/
- [2] https://www.cs.utexas.edu/~dana/MLClass/MT2013.pdf
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- $[4] \ \mathtt{https://www.cs.utexas.edu/~dana/MLClass/practice-midterm-1.pdf}$
- [5] https://www.cs.utexas.edu/~dana/MLClass/practice-midterm-2.pdf