Computer Vision

Modelisation

Plan

Classification Results (CLS)



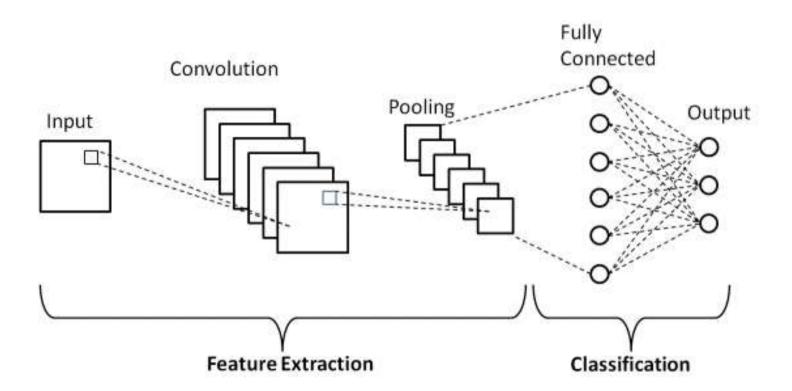
> CNN

- Convolution layer
- Pooling layer
- Fully-connected layer
- > Transfert learning
 - Purpose
 - Strategies
- > Performance evaluation
 - Hyperparameters
 - Fitting

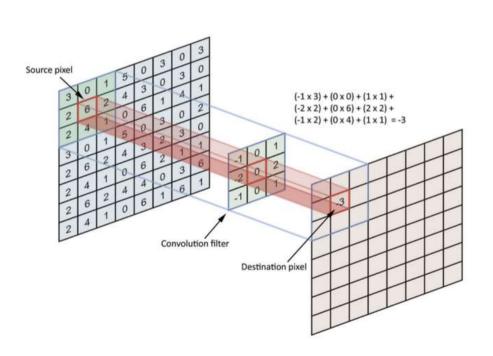
CNN

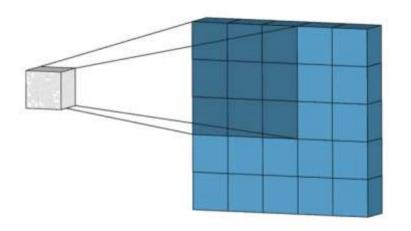
"Learn" the features

CNN



CNN: convolution layer





Activation function:

ightharpoonup ReLU: f(x) = Max(0, x)

CNN: convolution layer

Image (input):

➤ W: width (pixels)

➤ H: hight (pixels)

> D: number of channels

Hyperparameters:

> K: number of filters

 \rightarrow F: filter size in pixels (F x F x D)

➤ S: sliding step (pixels)

> P: 0 padding (pixels)

Feature maps (output):

➤ Wc: (W - F + 2P) / S + 1

 \rightarrow Hc: (H - F + 2P) / S + 1

> Dc: K

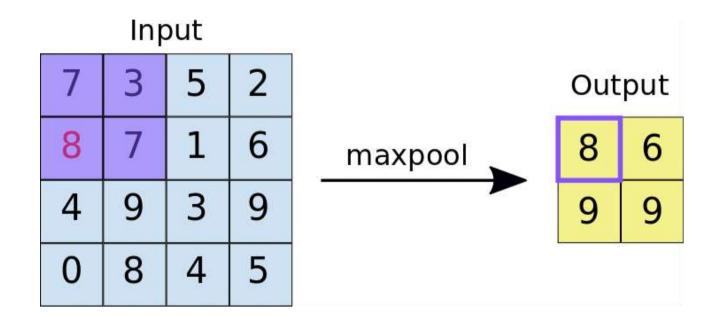
Common choice:

 \rightarrow F = 3 or 5

> S = 1 or 2

P = 1

CNN: pooling layer



Advantages:

- > Dimension reduction
- Less sensitive to feature position

CNN: pooling layer

Feature maps (input):

➤ W: width (pixels)

➤ H: hight (pixels)

> D: previously used number of filters

Hyperparameters:

> F : cell size (F x F pixels)

> S: pixels between cells

Feature maps (output):

> Wp: (W - F) / S + 1

 \rightarrow Hp: (H - F) / S + 1

➤ Dp:D

Common choce:

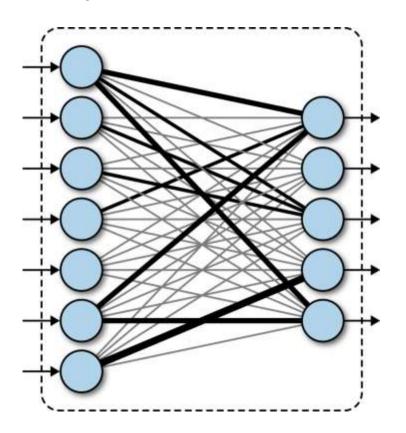
 \rightarrow F = 2 or 3

> S = 2

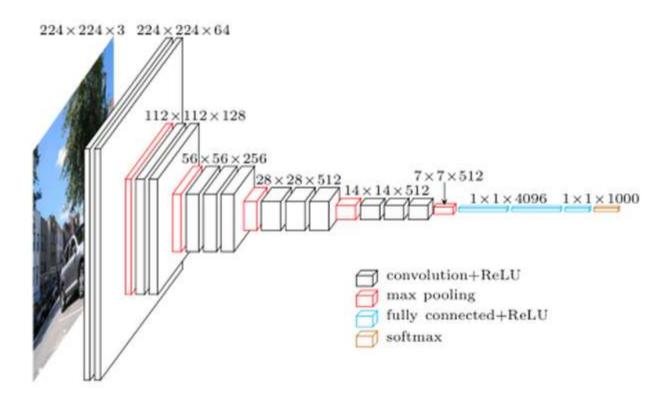
CNN: fully-connected layer

Options:

- > Flatten: convert output to 1D vector
- Number of neurons
- > Dropout: rate
- > Activation:
 - ReLU
 - Classifier 2N: logistic regression
 - Classifier xN: Softmax



CNN: VGG16



CNN: VGG16

```
from keras models import Sequential
from keras layers import Conv2D, MaxPooling2D, Flatten, Dense
# Empty NN
my VGG16 = Sequential()
****************
### Convolution block ###
******************
# Add the first CMN layer with relu activation
my V6G16_audi(Conv2D(64, (3, 3), input_shape=(224, 224, 3), padding='same', activation='relu'))
# Add the second CNN layer with relu activation
my VGG16.mdd(Curv20(64, (3, 3), padding='same', activation='relu'))
# Add the first pooling layer
my VGG16.mdd(MaxPooling2O(pool size=(2.2), strides=(2.21))
# Repeat the previous steps as often as needed...
***********************
### Fully-connected block ###
*********************
# Convert 3D matrix to 10 vector
my VGG16.add(Flatten())
# Add first fully-connected layer with reis activation
my V6616.add(Dense(4096, activation='relu'))
# Add second fully-connected layer with relu activation
my VGG16.mdd(Dense(4096, activation='relu'))
# Add last fully connected layer which is the classifier
my VGG16.add(Dense(1880, activation='softmax'))
```

Transfer learning

Time to be lazy and... smart!:)

Transfer learning: purpose

Weights:

- Convolution layer:
 - o F: filter size
 - K: number of filters
 - \circ weights = F x F x K + K
- Fully-connected:
 - W: width of input
 - H: height of input
 - K: number of filters
 - N: number of neurons
 - \circ Weights = W x H x K x N + N

VGG16 = 138 357 544 weights !!!

Transfer learning: strategies

The idea:

- Keep the architecture
- Replace the classifier

Strategies:

- Fine-tuning total:
 - Train all weights
 - Large dataset
- > Feature extraction:
 - o Fix all weights
 - Beside the ones of the classifier
 - Small / similar dataset
- > Fine-tuning partial:
 - Fix some of the weights
 - Most likely in the first layers
 - Small / different dataset

Transfer learning: exemple

```
### Pre-trained exemple ###
from keras.applications.vgg16 import VGG16
# Get VGG16 available in keras
model = VGG16()
from keras preprocessing image import load img, img to array
from keras.applications.vgg16 import preprocess input
# Load image and reshape image to match VGG16 dimensions expectation
img = load img('cat.jpg', target size=(224, 224))
# Convert to numpy array because keras processes images as such
img = img to array(img)
# A CNN expects (in general) a collection of images.
# Reshape the array to add the number of images
img = img.reshape((1, img.shape[0], img.shape[1], img.shape[2]))
# Preprocess images the same way the images used to train VGG16 were preprocessed.
ima = preprocess input(ima)
# Predict the class (or label) of this image
y = model.predict(img)
```

Transfer learning: exemple

```
****************
 ### Transfer learning ###
 *****************
 from keras import Model
 ≠ Load the VGGIS trained on imagenet images without the fully-connected layer
 model = VGG16(veights='imagenet', include top=False, input shape=(224, 224, 3))
 # Get the output of VGG16
 x = model output
 # Add your new classifier
 predictions - Dense(10, activation- softmax')(x)
 # Design your new model
 new model - Model (imputs model input, outputs predictions)
 # Strat nº1:
 for layer in new model layers:
    layer trainable = True
 # Strat nº2:
 for layer in new model layers:
    layer trainable = False
 # Strat n'3: let's not train the first 5 layers (the largests)
for layer in new model.layers[:5]:
   layer trainable - False
 # Compile the new model
new model.compile(loss="categorical crossentropy", optimizer-optimizers.500(lr=0.0001, momentum=0.9), metrics=["accuracy"])
 # Train it
 model info = new model. (ii(X train, y train, epochs=epochs, batch size=batch size, verbuse=2)
```

Performance evaluation

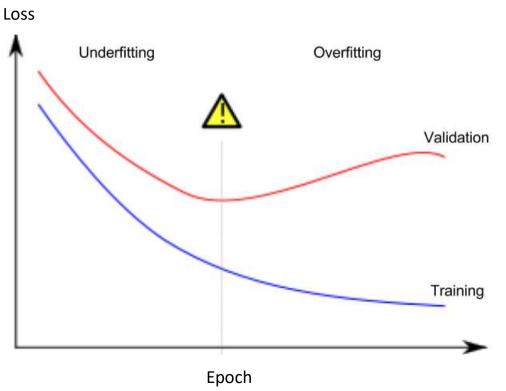
The suspense is intense!

Hyperparameters

- Loss function
- > Optimizer:
 - Learning rate
 - Momentum
- Metrics

```
****************
awa Transfer learning awa
*****************
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for layer in new model layers[:5]:
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# Compile the new model
new model compile(loss="categorical crossentropy", optimizer=optimizers.5GD(lr=8.0801, momentum=0.9), metrics=["accuracy"])
model info = new model. (it(X train, y train, epochs=epochs, batch size=batch size, verbose=2)
```

Underfitting vs. Overfitting



Practice

You know the drill

Ai design: dataset / concept

- Select a dataset or an app idea
- Create your team !
- > Define your strategy
- Prototype and test



Committee of the last of the l







