GABots Reference Manual 0.99

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CONTENTS 1

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•	.,			_		١,	7

1	GABots Namespace Index	1
2	GABots Compound Index	1
3	GABots Namespace Documentation	2
4	GABots Class Documentation	2

1 GABots Namespace Index

1.1 GABots Namespace List

Here is a list of all documented namespaces with brief descriptions:

BotRotation (Rotation enumerated type The namespace was needed to resolve some naming conflicts)

2 GABots Compound Index

2.1 GABots Compound List

Here are the classes, structs, unions and interfaces with brief descriptions:

Arena (A graphical representation of the arena This class does not currently store locations of the bots, that task must be	
looked after by the data classes)	2
Ball (Ball class)	4
Bot (Bot class)	6
BotView (This is not the actual "playing field" widget. It is simply the main widget that will own all the others)	10
Coordinate (Coordinate object)	13
floatbot (Use for sorting bots in order of fitness)	14
GABot (GA Bot (p. 6) data object)	14

ball positions and then using each bot's ruleset to determine its moves)	18
GARule (Main class for the rules in our Genetic Algorithm)	20
MainWindow (Main widget for the GABots app)	23
Random (Some useful functions for generating random numbers)	27
SimpleGA (Main class for Simple Genetic Algorithm used in the program)	28
Team (Team class: defines a "team" or population of Bots pre- sumably there are two of these at a time, unless we decide to play more than two teams at once)	29
TeamData (Read and Write team xml files)	32
TeamParser (Main class for parsing team XML data files, Derived from QXmlDefaultHandler from QT Library)	32

3 GABots Namespace Documentation

3.1 BotRotation Namespace Reference

Rotation enumerated type The namespace was needed to resolve some naming conflicts.

Enumerations

• enum Rotation { Left, None, Right }

 $Enumeric\ type\ for\ bot\ rotations.$

3.1.1 Detailed Description

Rotation enumerated type The namespace was needed to resolve some naming conflicts.

4 GABots Class Documentation

4.1 Arena Class Reference

A graphical representation of the arena This class does not currently store locations of the bots, that task must be looked after by the data classes.

#include <arena.h>

Public Methods

- Arena (QWidget *parent=0, const char *name=0)

 Constructor.
- ~Arena ()

 Destructor.
- void **putBotA** (int X, int Y, int R)

 Places a team A pixmap at (X, Y), with Rotation R.
- void **putBotB** (int X, int Y, int R)

 Places a team B pixmap at (X,Y), with Rotation R.
- void **putBall** (int X, int Y)

 Places the ball at (X, Y).
- void clear At (int X, int Y)

 Clears a grid square with UL Corner (X,y).
- void **clear All** (void)

 Clears the entire arena.

Protected Methods

• void **paintEvent** (QPaintEvent *)

QT Repaint event.

Protected Attributes

• QPixmap * BotImageA

Pixmap image for Team (p. 29) A.

• QPixmap * **BotImageB**

Pixmap image for Team (p. 29) B.

4.1.1 Detailed Description

A graphical representation of the arena This class does not currently store locations of the bots, that task must be looked after by the data classes.

Definition at line 11 of file arena.h.

The documentation for this class was generated from the following files:

- arena.h
- arena.cpp

4.2 Ball Class Reference

Ball class.

#include <ball.h>

Signals

• void ballMove (Coordinate, Coordinate)

indicate ball movement.

Public Methods

- Ball (QObject *parent=0, const char *name=0)
 - Constructor.
- ~Ball ()

Destructor.

• unsigned int **speed** ()

return speed.

• unsigned int **speed** (unsigned int)

return / set speed.

• Coordinate position ()

 $return\ position.$

• Coordinate position (Coordinate)

return / set speed.

• Direction direction ()

return direction.

• Direction direction (Direction)

return / set direction.

• unsigned int team ()

return which team has the ball.

• unsigned int team (unsigned int)

return / set which team has the ball.

• unsigned int **player** ()

return which player has the ball.

• unsigned int **player** (unsigned int)

return / set which player has the ball.

• unsigned int ticksUntilNextMove ()

return Ticks.

• unsigned int ticksUntilNextMove (unsigned int)

return / set Ticks.

• void moveBall (unsigned int, unsigned int)

move the ball.

• void reset (Coordinate)

reset position of the ball.

Private Attributes

• unsigned int Speed

whatever maximum speed is (10?) - this = how many ticks between moves if θ , then not moving.

• Coordinate Pos

(x,y) position on board.

• Direction **Dir**

direction of movement.

• unsigned int **Team**

most recent team to have ball (0, 1 or 2).

• unsigned int Player

most recent player on team to have ball.

• unsigned int TicksUntilNextMove

 $wait\ states.$

4.2.1 Detailed Description

Ball class.

Definition at line 9 of file ball.h.

The documentation for this class was generated from the following files:

- ball.h
- ball.cpp

4.3 Bot Class Reference

Bot class.

#include <bot.h>

Signals

• void botMove (Coordinate, Coordinate)

Indicate the bot has moved.

• void botDirection (Coordinate, Direction)

Indicate the bot has changed direction.

Public Methods

- **Bot** (QObject *parent=0, const char *name=0) Constructor.
- **Bot** (QObject *parent, unsigned int mass) Constructor.
- $\bullet \ \sim \! \mathbf{Bot} \ ()$

Destructor.

 \bullet unsigned int ${\bf mass}$ ()

 $Return\ Mass.$

- unsigned int **mass** (unsigned int) Set Mass.
- Coordinate position ()

Return Position.

• Coordinate position (Coordinate)

 $Set\ Position.$

• Direction direction ()

Return Direction.

• Direction direction (Direction)

Set Direction.

• unsigned int ruleSetSize ()

 $Return\ Rule Set Size.$

 \bullet unsigned int ticksUntilNextMove ()

Return Ticks.

• unsigned int ticksUntilNextMove (unsigned int)

Set Ticks.

• void execRule (GARule *, Ball *, unsigned int, unsigned int)

Execute Rule.

• bool myBall ()

 $Return\ myBall.$

• bool myBall (bool)

 $Set\ myBall.$

• QList< GARule > rules ()

Get all Rules.

• QList< GARule > rules (QList< GARule >)

Get / Set all Rules.

• GARule * rule (unsigned int)

Get Rule with specific number.

• GARule * removeRule (unsigned int)

Remove specific Rule.

• GARule * removeRule (GARule *)

Remove the given Rule.

• GARule * insertRule (GARule *, unsigned int)

Add the given Rule in position number.

• GARule * insertRule (GARule *)

Add the given Rule at the end of the list.

• GARule * bestRule (GARule *)

Return the best rule given a rule of conditions.

• void randomBot (unsigned int, unsigned int)

Generate a random Bot with a given number of rules and mass.

• void mutateBot ()

Mutate a rule chosen at random.

• int goals ()

Get number of goals scored by this bot.

• int goals (int)

Get / Set goals.

• unsigned int interceptions ()

Get number of interceptions by this bot.

• unsigned int interceptions (unsigned int)

Get / Set interceptions.

• unsigned int timeWithBall ()

Get time with ball.

• unsigned int timeWithBall (unsigned int)

Get / Set time with ball.

• float **fitnessFunction** ()

Compute this bot's fitness based upon stats.

Static Public Methods

• float goalsWeight ()

Get Weight to give goals.

• float goalsWeight (float)

Get / Set weight to give goals.

• float interceptionsWeight ()

Get Weight to give interceptions.

• float interceptionsWeight (float)

Get / Set weight to give interceptions.

• float timeWithBallWeight ()

Get Weight to time with ball.

• float timeWithBallWeight (float)

Get / Set Weight to time with Ball (p. 4).

Private Attributes

 \bullet unsigned int **Mass**

Mass of the bot.

• Coordinate Pos

Position of the bot.

• Direction **Dir**

Direction facing of the bot.

• QList < GARule > Rules

List of Rules.

• unsigned int Goals

Goasl scored by this bot.

• unsigned int Interceptions

Interceptions made by this bot.

\bullet unsigned int TimeWithBall

Number of moves this bot carried the ball.

• unsigned int TicksUntilNextMove

Wait states.

• bool MyBall

True if this bot has the ball.

• int BotID

An identifying integer.

Static Private Attributes

• float GoalsWeight = 1.0

Weight to give goals in fitness function.

• float InterceptionsWeight = 0.5

Weight to give interceptions.

• float TimeWithBallWeight = 0.2

Weight to give moves.

4.3.1 Detailed Description

Bot class.

Definition at line 21 of file bot.h.

The documentation for this class was generated from the following files:

- bot.h
- bot.cpp

4.4 BotView Class Reference

This is not the actual "playing field" widget. It is simply the main widget that will own all the others.

#include <botview.h>

Public Slots

• void slotScoreA (void)

Increases Team (p. 29) A's score by one.

• void **slotScoreB** (void)

Increases Team (p. 29) B's score by one.

• void slotClearScores (void)

Resets the LCD scores.

• void slotClearField (void)

Resets the Field.

• void slotMoveTeamA (Coordinate, Coordinate)

Moves a bot.

• void slotMoveTeamB (Coordinate, Coordinate)

 $Moves\ a\ bot.$

• void slotTurnTeamA (Coordinate, Direction)

Turns a bot.

• void slotTurnTeamB (Coordinate, Direction)

Turns a bot.

• void slotMoveBall (Coordinate, Coordinate)

Moves the ball, spawns a ball if needed.

Signals

• void valueChanged (int)

Relay signal for changing game speed.

Public Methods

- **BotView** (QWidget *parent, const char *name=0, int w=800, int h=400) Constructor.
- ~BotView ()

Destructor.

• int **fieldWidth** (void)

Return the playing field's width.

• int fieldHeight (void)

 $Return\ the\ playing\ field\ 's\ width.$

• int fieldWidth (int)

Set the arena Width, return true on success.

• int **fieldHeight** (int)

Set the arena Height, return true on success.

Protected Slots

• void slotValueChanged (int)

Relay slot for changing game speed.

Protected Attributes

• Arena * Field

Pointer to the widget that is the "playing field".

- QLCDNumber * LCDScoreA

 LCD widget for Team (p. 29) A's score.
- QLCDNumber * LCDScoreB

 LCD widget for Team (p. 29) B's score.
- int **FieldWidth**Width of field.
- int **FieldHeight**Height of field.
- int **ScoreA Team** (p. 29) A's score.
- int ScoreB

 Team (p. 29) B's score.

4.4.1 Detailed Description

This is not the actual "playing field" widget. It is simply the main widget that will own all the others.

Definition at line 14 of file botview.h.

The documentation for this class was generated from the following files:

- botview.h
- botview.cpp

4.5 Coordinate Class Reference

Coordinate object.

#include <coordinate.h>

Public Methods

- Coordinate ()

 default constructor.
- Coordinate (int x1, int y1) constructor.

Public Attributes

- int \mathbf{x} direction in x.
- int \mathbf{y} direction in y.

4.5.1 Detailed Description

Coordinate object.

Definition at line 12 of file coordinate.h.

The documentation for this class was generated from the following file:

• coordinate.h

4.6 floatbot Struct Reference

Use for sorting bots in order of fitness.

#include <simplega.h>

Public Attributes

• float fit

Value of fitness.

 $\bullet \ \, {\rm unsigned \ int} \ \, {\bf bot}$

Bot (p.6) number.

4.6.1 Detailed Description

Use for sorting bots in order of fitness.

Definition at line 37 of file simplega.h.

The documentation for this struct was generated from the following file:

• simplega.h

4.7 GABot Class Reference

GA Bot (p. 6) data object. #include <gabot.h>

Public Slots

- void **slotTickInterval** (int)

 Change the tickInterval.
- void **slotStartTimer** (void)

 Activate the timer (Go!).
- void **slotStopTimer** (void)

 Stop the timer (Pause).
- void **slotGameOver** (void)

 End the game.

Signals

- void **teamAScores** (void)

 Signal that **Team** (p. 29) A has Scored.
- void **teamBScores** (void)

 Signal that **Team** (p. 29) B has Scored.
- void clearScores (void)

 Signal that the scores should be cleared.
- void **putBall** (**Coordinate**)

 Signal that ball should be spawned at Coord.
- void moveBall (Coordinate, Coordinate)

 Signal that ball has moved.
- void moveTeamA (Coordinate, Coordinate)

 Signal that a team A bot has moved.

• void moveTeamB (Coordinate, Coordinate)

- Signal that a team B bot has moved.

• void turnTeamA (Coordinate, Direction)

Signal that a team A bot has turned Direction.

• void turnTeamB (Coordinate, Direction)

Signal that a team B bot has turned Direction.

• void clearField (void)

Signal that the field should be cleared.

• void **gameReady** (bool)

Signal that it is safe to start a game.

• void gameOver (void)

Signal that the current game is over.

Public Methods

• **GABot** (QObject *parent=0, const char *name=0) Constructor.

• \sim GABot ()

Destructor.

• int loadTeamFromFile (QString Filename, int TeamNumber)

Load a rule set from Filename into TeamNumber.

• int saveTeamToFile (QString Filename, int TeamNumber)

Save a team to file.

• void randomTeam (int TeamNumber)

Generate Random (p. 27) team.

Protected Slots

• void **slotTurn** (void)

Executed every tick interval, if Timer isActive().

• void slotBallMoved (Coordinate, Coordinate)

Game (p. 18) class has indicated the ball has moved.

• void slotBotMoveA (Coordinate, Coordinate)

• void slotBotMoveB (Coordinate, Coordinate)

Team (p.29) class has indicated a Bot (p.6) from Team (p.29) B has moved.

• void slotBotDirectionA (Coordinate, Direction)

Team (p. 29) class has indicated a **Bot** (p. 6) from **Team** (p. 29) A has changed Direction.

• void slotBotDirectionB (Coordinate, Direction)

Team (p.29) class has indicated a **Bot** (p.6) from **Team** (p.29) B has changed Direction.

• void **slotTeamAScores** (void)

Execute when Team (p. 29) A scores.

• void **slotTeamBScores** (void)

Execute when Team (p. 29) B scores.

• void **slotClearField** (void)

Clear the field in the Arena (p. 2).

Protected Methods

• void **prepareGame** (void)

Prepares the game object.

Protected Attributes

 \bullet Team * TeamA

Pointer to Team (p. 29) A object.

• Team * TeamB

Pointer to Team (p. 29) B object.

• QTimer * Tick

 $Timer\ for\ interval\ between\ moves.$

• int TickInterval

Tick interval in milliseconds.

• Game * GAGame

Game (p. 18) instance.

• SimpleGA GenAlg

 $Genetic\ Algorithm\ instance.$

4.7.1 Detailed Description

GA Bot (p. 6) data object.

Definition at line 18 of file gabot.h.

The documentation for this class was generated from the following files:

- gabot.h
- gabot.cpp

4.8 Game Class Reference

Game class: perform game playing by assigning bot and ball positions and then using each bot's ruleset to determine its moves.

```
#include <game.h>
```

Signals

• void ballMoved (Coordinate, Coordinate)

emitted when the ball changes locations.

• void teamAScores (void)

emitted when team A scores.

• void teamBScores (void)

emitted when team B scores.

• void **clearField** (void)

emitted when the field should be cleared.

• void gameOver (void)

emitted at the end of a game.

Public Methods

• Game (QObject *parent, Team *, Team *, unsigned int, unsigned int, unsigned int)

two teams, game length, and board size (width, height).

• ~Game ()

destruct 1-1-A-2-B.

• void turn ()

perform one turn.

• bool over ()

true if this game is over.

• void reset ()

reset ball and bots to start positions (at start, after goal).

Protected Slots

• void slotBallMoved (Coordinate, Coordinate)

Activated by the ball emitting a location signal.

Private Methods

• GARule * botState (Bot *, unsigned int teamnum)

determine a Bot (p. 6)'s state; also need its team.

• void **botCollision** (**Bot** *, unsigned int teamnum)

determine and resolve bots colliding with things.

• unsigned int posIndex (Coordinate, Coordinate)

determine an index into a sensor array given two coordinates.

• unsigned int ballInNet ()

determine if the ball is in the net and allocate goals to the proper team and player.

• bool tradeBall (Bot *, Bot *, unsigned int, unsigned int) when bots collide, choose which one keeps the ball.

Private Attributes

• Team * T1

Pointer to first team.

• Team * T2

Pointer to second team.

• unsigned int GameLength

Length of game in turns.

 \bullet unsigned int **Turns**

Number of turns so far.

• unsigned int Width

Board width.

• unsigned int **Height**

Board height.

• unsigned int NetStart

Start of net location (calculated from height).

ullet unsigned int \mathbf{NetEnd}

End of net location (calculated from height).

• Ball * B

Pointer to the ball.

4.8.1 Detailed Description

Game class: perform game playing by assigning bot and ball positions and then using each bot's ruleset to determine its moves.

Definition at line 15 of file game.h.

The documentation for this class was generated from the following files:

- game.h
- game.cpp

4.9 GARule Class Reference

Main class for the rules in our Genetic Algorithm.

#include <garule.h>

Public Methods

- **GARule** (QObject *parent=0, const char *name=0) Constructor.
- \sim GARule ()

Destructor.

• GARule (const GARule &)

Copy Constructor.

• GARule & operator= (const GARule &)

Copy Assignment.

• int teamBall ()

 $Member\ function\ to\ return\ team Ball.$

• bool myBall ()

Member function to return myBall.

• Thing * sensors ()

Member function to return the pointer of the sensor array.

• bool fire ()

Member function to return fire.

• bool move ()

Member function to return move.

• Rotation turn ()

Member function to return turn.

• int teamBall (int)

Member function to set teamBall.

• bool myBall (bool)

 $Member\ function\ to\ set\ myBall.$

• Thing * sensors (Thing[])

 $Member\ function\ to\ set\ the\ sensors.$

• bool fire (bool)

Member function to set fire.

• bool **move** (bool)

Member function to set move.

• Rotation turn (Rotation)

Member function to set rotation.

• void randomRule ()

Generate a random rule.

• void mutateRule ()

Mutate the rule.

• unsigned int difference (GARule *)

Find the difference between the conditions in this rule and the ones in the given rule.

Private Attributes

• int TeamBall

Ball (p. 4) is ours (+ve), theirs (-ve), or nither (0).

• bool MyBall

Ball (p. 4) is in this bot's posessioin.

• Thing Sensors [8]

Sensor states.

• bool Fire

Fire the ball (shoot or pass, same thing).

• bool Move

Move in directions being faced.

• Rotation Turn

Angle to turn by (Left, Right, None).

4.9.1 Detailed Description

Main class for the rules in our Genetic Algorithm.

Definition at line 20 of file garule.h.

The documentation for this class was generated from the following files:

- garule.h
- garule.cpp

4.10 MainWindow Class Reference

Main widget for the GABots app.

#include <mainwindow.h>

Public Methods

• MainWindow ()

Constructor.

• ~MainWindow ()

Destructor.

Protected Slots

• void **slotFileClose** ()

This should be changed.

• void **slotFileQuit** ()

Runs on quiting the application.

• void slotViewToolBar (bool toggle)

Toggles the Toolbar.

 $\bullet \ \operatorname{void} \ \mathbf{slotViewStatusBar} \ (\operatorname{bool} \ \operatorname{toggle})$

Toggles the Statusbar.

• void slotViewGame (bool toggle)

Toggles the Game (p. 18) Display.

• void **slotHelpAbout** ()

Launches the About box.

ullet void ${f loading}$ (QString)

Runs on loading a file.

• void slotLoadTeamA ()

Load a file for team A.

• void slotLoadTeamB ()

Load a file for team B.

• void slotSaveTeamA ()

Save a file for team A.

• void **slotSaveTeamB** ()

Save a file for team B.

• void slotGenerateTeamA ()

Generate a new team for team A.

• void slotGenerateTeamB ()

Generate a new team for team B.

• void **slotGoGame** (void)

Start QTimer, begin a game.

• void **slotStopGame** (void)

Stops an active game.

• void slotGameReady (bool)

Toggles game ready status.

• void slotTickInterval (int)

Changed the game speed.

• void slotGameOver (void)

Handle game over.

Protected Methods

• void initActions ()

Create the QT Actions.

• void initMenuBar ()

Create the menu bar.

• void initToolBar ()

Create the tool bar.

• void initStatusBar ()

Create the status bar.

• void initGABotDoc ()

Create the GA Bot (p. 6) object.

• void initView ()

Create the GA Bot (p.6) view object.

• bool queryExit ()

Query the user if they wish to quit without saving.

• void teamFileOpen (int)

Open a team ruleset file.

• void teamFileSave (int)

Save a team ruleset to file.

• void teamGenerateRandom (int)

 $Generate\ new\ team\ randomly.$

Private Attributes

• BotView * View

Pointer to the View.

• GABot * GABotDoc

Pointer to the GABot (p. 14) document.

\bullet QPopupMenu * **FileMenu**

Pointer to the file menu pop up.

• QPopupMenu * **ViewMenu**

Pointer to the view menu pop up.

• QPopupMenu * **HelpMenu**

Pointer to the help menu pop up.

• QToolBar * Toolbar

Pointer to the tool bar pop up.

• QAction * TeamAFileOpen

Action for opening team A file.

• QAction * TeamBFileOpen

Action for opening team B file.

• QAction * TeamAFileSave

Action for saving team A file.

• QAction * TeamBFileSave

Action for saving team B file.

• QAction * FileQuit

Action for quitting the application.

• QAction * ViewToolBar

Action for toggling the toolbar.

• QAction * ViewStatusBar

Action for toggoling the status bar.

• QAction * ViewGame

Action for toggling the view game.

• QAction * **HelpAbout**

Action for launching the About box.

 \bullet QAction * **GoGame**

Action for starting a game.

• QAction * StopGame

 $Action\ for\ stopping\ a\ game.$

• QAction * TeamAGenerate

Action for generate a random team A.

• QAction * TeamBGenerate

Action for generate a random team B.

• QAction * ResetScreen

Action for reset display.

4.10.1 Detailed Description

Main widget for the GABots app.

Definition at line 18 of file mainwindow.h.

The documentation for this class was generated from the following files:

- mainwindow.h
- mainwindow.cpp

4.11 Random Class Reference

some useful functions for generating random numbers.

#include <random.h>

Static Public Methods

• void initseed ()

initialize the seed with the time.

• int randint (int start, int end)

random integer from start to end.

• double randd (double start, double end)

random double from start to end.

• bool randbool ()

random boolean value.

4.11.1 Detailed Description

some useful functions for generating random numbers.

Definition at line 6 of file random.h.

The documentation for this class was generated from the following files:

- random.h
- random.cpp

4.12 SimpleGA Class Reference

Main class for Simple Genetic Algorithm used in the program.

#include <simplega.h>

Public Methods

• SimpleGA ()

Constructor.

• SimpleGA (double)

Constructor.

• ~SimpleGA ()

Destructor.

• double mutationRate ()

Member function for returning mutation rate.

• double mutationRate (double rate)

 $Member\ function\ for\ setting\ mutation\ rate.$

• void crossover (Bot *, Bot *, Bot *, Bot *)

Crossover two bots and produce two new bots.

• void evolve (Team *)

Evolve a team.

Private Attributes

• double MutationRate

Mutation Rate.

4.12.1 Detailed Description

Main class for Simple Genetic Algorithm used in the program.

Definition at line 14 of file simplega.h.

The documentation for this class was generated from the following files:

- simplega.h
- simplega.cpp

4.13 Team Class Reference

Team class: defines a "team" or population of Bots presumably there are two of these at a time, unless we decide to play more than two teams at once.

```
#include <team.h>
```

Signals

• void botMove (Coordinate, Coordinate)

emitted when a bot has moved.

• void botDirection (Coordinate, Direction)

emitted when a bot has changed direction.

Public Methods

- Team (QObject *parent=0, const char *name=0)
 - Constructor.
- ~Team ()

Destructor.

• unsigned int size ()

return size of team.

- QList< **Bot** > **bots** ()

 return a list of bots.
- QList< Bot > bots (QList< Bot >) set the list of bots.
- Bot * removeBot (unsigned int X) send bot X back to the minors.
- unsigned int insertBot (Bot *)

 pull a bot up from the minors.
- unsigned int **insertBot** (**Bot** *, unsigned int)

 pull a bot up from the minors, with number.
- Bot * bot (unsigned int)

 returns a particular bot, by number.
- void randomTeam (unsigned int X)
 generate a random team of size X.
- int goals ()

 return number of team goals.
- int goals (int)

 set number of team goals.
- unsigned int wins ()

 return number of wins.
- unsigned int wins (unsigned int)

 set number of wins.
- unsigned int **losses** () return number of losses.
- unsigned int **losses** (unsigned int) set number of losses.
- unsigned int ties ()

 return number of ties.

- unsigned int **ties** (unsigned int) set number of ties.
- unsigned int **generations** () return number of generations.
- unsigned int **generations** (unsigned int) set number of generations.
- QString name ()
 return team name.
- QString **name** (QString) set team name.

Protected Slots

- void slotBotMove (Coordinate, Coordinate)

 Handle Bot (p. 6) movements.
- void **slotBotDirection** (**Coordinate**, Direction)

 Handle **Bot** (p. 6) direction changes.

Private Attributes

- int **TeamBall**ball is ours (+ve), theirs (-ve), or neither (0).
- int Goals

 goals scored by this team in its current game.
- unsigned int **Wins**number of wins by this team.
- unsigned int **Losses**number of losses by this team.
- unsigned int **Ties**number of ties by this team.

• unsigned int **Generations**number of generations.

• QString Name

Team name.

• QList < Bot > Bots

 $List\ of\ bots.$

4.13.1 Detailed Description

Team class: defines a "team" or population of Bots presumably there are two of these at a time, unless we decide to play more than two teams at once.

Definition at line 14 of file team.h.

The documentation for this class was generated from the following files:

- team.h
- team.cpp

4.14 TeamData Class Reference

Read and Write team xml files.

#include <teamdata.h>

Public Methods

• Team * readTeamData (QString filename)
read team data from xml file.

write team data into xml file.

4.14.1 Detailed Description

Read and Write team xml files.

Definition at line 19 of file teamdata.h.

The documentation for this class was generated from the following files:

- teamdata.h
- teamdata.cpp

4.15 TeamParser Class Reference

Main class for parsing team XML data files, Derived from QXmlDefaultHandler from QT Library.

#include <teamparser.h>

Public Methods

• TeamParser ()

Constructor.

• bool startDocument ()

Member function for the start of document.

• bool **startElement** (const QString &, const QString &, const QString &, const QXmlAttributes &)

Member function for the start of a XML element (tag).

- bool **endElement** (const QString &, const QString &, const QString &)

 Member function for the end of a XML element (tag).
- Team * teamData ()

Member function for return the parsed data.

Private Attributes

• Team * team

Pointer to the team data.

• **Bot** * **bot**

Pointer to the bot data.

• GARule * rule

Pointer to the rule data.

• Thing * sens

Poniter to the sensor array.

• int botcount

Internal counter for bots.

\bullet int rulecount

Internal counter for rules.

4.15.1 Detailed Description

Main class for parsing team XML data files, Derived from QXmlDefaultHandler from QT Library.

Definition at line 23 of file teamparser.h.

The documentation for this class was generated from the following files:

- \bullet teamparser.h
- teamparser.cpp

\mathbf{Index}

	,
~Arena	player, 5
Arena, 3	Pos, 5
~Ball	position, 4
Ball, 4	reset, 5
~Bot	Speed, 5
Bot, 6	speed , 4
~BotView	Team, 5
BotView, 11	team, 4, 5
\sim GABot	TicksUntilNextMove, 5
GABot, 16	ticksUntilNextMove, 5
~GARule	ballInNet
GARule, 20	Game, 19
~Game	$\operatorname{ballMove}$
Game, 18	Ball, 4
~MainWindow	$\operatorname{ballMoved}$
MainWindow, 23	Game, 18
\sim SimpleGA	$\mathrm{bestRule}$
$\operatorname{SimpleGA},\ 28$	$\mathrm{Bot},8$
∼Team	$\mathrm{Bot}, 6$
Team, 29	\sim Bot, 6
	bestRule, 8
Arena, 2	$\mathrm{Bot}, 6$
\sim Arena, 3	botDirection, 6
${ m Arena,\ 2}$	BotID, 10
BotImageA, 3	botMove, 6
${ m BotImageB},3$	Dir, 9
$\operatorname{clearAll}, 3$	direction, 7
$\operatorname{clearAt}, 3$	execRule, 7
$\operatorname{paintEvent},3$	fitnessFunction, 8
putBall, 3	Goals, 9
$\operatorname{putBotA},3$	goals, 8
putBotB, 3	GoalsWeight, 10
	m goals Weight, 9
В	insertRule, 8
$\mathrm{Game},20$	Interceptions, 9
Ball, 4	interceptions, 8
\sim Ball, 4	Interceptions Weight, 10
Ball, 4	interceptions Weight, 9
ballMove, 4	Mass, 9
Dir, 5	mass, 6, 7
direction, 4	mutateBot, 8
moveBall, 5	MyBall, 10
Player, 5	myBall, 7
	v ,

D 0	C LHI : L. 10
Pos, 9	fieldHeight, 12
position, 7	FieldWidth, 12
randomBot, 8	fieldWidth, 12
removeRule, 8	$\operatorname{LCDScoreA},12$
rule, 7	LCDScoreB, 12
Rules, 9	ScoreA, 12
rules, 7	ScoreB, 12
rule Set Size, 7	slotClearField, 11
TicksUntilNextMove, 10	slotClearScores, 11
ticksUntilNextMove, 7	slotMoveBall, 11
TimeWithBall, 9	slotMoveTeamA, 11
timeWithBall, 8	slotMoveTeamB, 11
TimeWithBallWeight, 10	$\operatorname{slotScoreA}, 11$
timeWithBallWeight, 9	slotScoreB, 11
bot	slotTurnTeamA, 11
float bot, 14	slotTurnTeamB, 11
Team, 30	slot ValueChanged, 12
TeamParser, 33	valueChanged, 11
botCollision	BotView, 10
Game, 19	Dot view, 10
botcount	clearAll
	Arena, 3
TeamParser, 33	clearAt
botDirection	Arena, 3
Bot, 6	clearField
Team, 29	GABot, 15
BotID	
Bot, 10	Game, 18
$\operatorname{BotImageA}$	clearScores
Arena, 3	GABot, 15
$\operatorname{BotImageB}$	Coordinate, 13
Arena, 3	Coordinate, 13
botMove	x, 13
Bot, 6	y, 13
Team, 29	crossover
BotRotation, 2	${ m Simple GA,\ 28}$
Bots	1.00
Team, 31	difference
bots	GARule, 22
Team, 29	Dir
botState	Ball, 5
Game, 19	$\mathrm{Bot},9$
BotView	$\operatorname{direction}$
~BotView, 11	Ball, 4
Bot View, 11	Bot, 7
Field, 12	
FieldHeight, 12	${ m endElement}$
1 101011018110, 12	

Toom Dangen 22	put Dall 15
TeamParser, 33 evolve	putBall, 15
	randomTeam, 16
SimpleGA, 28	saveTeamToFile, 16
execRule	slotBallMoved, 16
Bot, 7	slotBotDirectionA, 16
Field	slotBotDirectionB, 16
	slotBotMoveA, 16
Bot View, 12	slotBotMoveB, 16
FieldHeight	slotClearField, 17
Bot View, 12	slotGameOver, 14
fieldHeight	slotStartTimer, 14
Bot View, 12	slotStopTimer, 14
FieldWidth	$\operatorname{slotTeamAScores}$, 16
BotView, 12	slotTeamBScores, 17
fieldWidth	slotTickInterval, 14
BotView, 12	$\operatorname{slot} \operatorname{Turn}, 16$
FileMenu	TeamA, 17
MainWindow, 25	teamAScores, 15
FileQuit	TeamB, 17
MainWindow, 26	teamBScores, 15
Fire	$\mathrm{Tick},17$
${ m GARule,\ 22}$	${ m Tick Interval},17$
fire	${ m turnTeamA,15}$
GARule, 21	${ m turnTeamB},15$
fit	$\operatorname{GABotDoc}$
floatbot, 14	MainWindow, 25
fitnessFunction	GAGame
Bot, 8	GABot, 17
float bot, 14	Game, 18
bot, 14	\sim Game, 18
$\mathrm{fit},14$	B, 20
	ballInNet, 19
GABot, 14	ballMoved, 18
\sim GABot, 16	botCollision, 19
m clear Field, 15	botState, 19
${ m clear Scores},15$	clearField, 18
GABot, 16	Game, 18
GAGame, 17	GameLength, 19
gameOver, 15	gameOver, 18
gameReady, 15	Height, 20
GenAlg, 17	NetEnd, 20
loadTeamFromFile, 16	NetStart, 20
moveBall, 15	over, 18
moveTeamA, 15	posIndex, 19
moveTeamB, 15	reset, 19
prepareGame, 17	slotBallMoved, 19
- -	siocDanivioved, 19

T1, 19 T2, 19 teamAScores, 18 teamBScores, 18 tradeBall, 19 turn, 18 Turns, 19 Width, 20 GameLength	Goals Weight Bot, 10 goals Weight Bot, 9 GoGame Main Window, 26 Height Game, 20
Game, 19	HelpAbout
gameOver	MainWindow, 26
GABot, 15	HelpMenu
Game, 18	MainWindow, 25
gameReady	* * A *
GABot, 15	initActions
GARule, 20	MainWindow, 24
\sim GARule, 20	initGABotDoc
difference, 22	MainWindow, 25 initMenuBar
Fire, 22	MainWindow, 24
fire, 21	initseed
GARule, 20, 21	Random, 27
Move, 22	initStatusBar
move, 21	MainWindow, 24
mutateRule, 22	initToolBar
MyBall, 22	MainWindow, 24
myBall, 21	initView
operator = 21 $ random Rule, 22$	MainWindow, 25
Sensors, 22	insertBot
sensors, 21	Team, 29, 30
TeamBall, 22	insertRule
teamBall, 21	Bot, 8
Turn, 22	Interceptions
turn, 21	Bot, 9
GenAlg	interceptions
\widetilde{GABot} , 17	Bot, 8
Generations	InterceptionsWeight
Team, 31	Bot, 10
generations	interceptionsWeight
Team, 30	$\mathrm{Bot},9$
Goals	LCDScoreA
$\mathrm{Bot},9$	BotView, 12
Team, 31	LCDScoreB
goals	BotView, 12
Bot, 8	loading
Team, 30	J

MainWindow, 23	${\it TeamAGenerate}, 26$
loadTeamFromFile	TeamBFileOpen, 26
GABot, 16	TeamBFileSave, 26
Losses	TeamBGenerate, 26
Team, 31	teamFileOpen, 25
losses	teamFileSave, 25
Team, 30	teamGenerateRandom, 25
ream, 50	Toolbar, 25
MainWindow	View, 25
~MainWindow, 23	ViewGame, 26
FileMenu, 25	ViewGame, 20 ViewMenu, 25
FileQuit, 26	ViewStatusBar, 26
GABotDoc, 25	
GoGame, 26	ViewToolBar, 26
HelpAbout, 26	MainWindow, 23
HelpMenu, 25	Mass
initActions, 24	$\mathrm{Bot},9$
initGABotDoc, 25	mass
initMenuBar, 24	Bot, 6, 7
	Move
initStatusBar, 24	${ m GARule},22$
initToolBar, 24	move
init View, 25	GARule, 21
loading, 23	moveBall
MainWindow, 23	Ball, 5
queryExit, 25	$\mathrm{GABot},15$
ResetScreen, 26	${ m move Team A}$
slotFileClose, 23	$\mathrm{GABot},15$
slotFileQuit, 23	${ m move Team B}$
slotGameOver, 24	${ m GABot},15$
slotGameReady, 24	$\operatorname{mutateBot}$
slotGenerateTeamA, 24	$\mathrm{Bot},8$
slotGenerateTeamB, 24	$\mathrm{mutateRule}$
slotGoGame, 24	${ m GARule},22$
${ m slot}{ m HelpAbout},23$	$\operatorname{MutationRate}$
$\operatorname{slotLoadTeamA}, 23$	$\operatorname{SimpleGA}$, 28
slotLoadTeamB, 23	$\operatorname{mutationRate}$
slotSaveTeamA, 24	$\operatorname{SimpleGA}$, 28
slotSaveTeamB, 24	MyBall
slotStopGame, 24	Bot, 10
${ m slotTickInterval,\ 24}$	${ m GARule},22$
$\operatorname{slotViewGame},\ 23$	myBall
${ m slot View Status Bar},23$	Bot, 7
${ m slotViewToolBar,\ 23}$	GARule, 21
StopGame, 26	
TeamAFileOpen, 25	Name
TeamAFileSave, 26	Team, 31

name	initseed, 27
Team, 30, 31	randbool, 27
NetEnd	randd, 27
Game, 20	randint, 27
NetStart	randomBot
$\mathrm{Game},20$	$\mathrm{Bot},8$
	${ m randomRule}$
operator=	$\operatorname{GARule},22$
GARule, 21	$\operatorname{randomTeam}$
over	GABot, 16
Game, 18	Team, 30
,	${ m readTeamData}$
paint Event	
Arena, 3	TeamData, 32
	${ m removeBot}$
Player	Team, 29
Ball, 5	${ m removeRule}$
player	Bot, 8
Ball, 5	reset
Pos	Ball, 5
Ball, 5	Game, 19
Bot, 9	
posIndex	ResetScreen
Game, 19	MainWindow, 26
	rule
position	$\mathrm{Bot},\ 7$
Ball, 4	TeamParser, 33
Bot, 7	$\operatorname{rulecount}$
$\operatorname{prepareGame}$	TeamParser, 33
GABot, 17	Rules
putBall	
Arena, 3	$\mathrm{Bot}, 9$
GABot, 15	rules
putBotA	$\mathrm{Bot},\ 7$
	${\rm rule Set Size}$
Arena, 3	$\mathrm{Bot},7$
$\mathrm{putBotB}$	
Arena, 3	${f save Team To File}$
	GABot, 16
queryExit	\mathbf{ScoreA}
MainWindow, 25	BotView, 12
	ScoreB
randbool	
Random, 27	BotView, 12
randd	sens
Random, 27	${\it TeamParser,33}$
randint	${f Sensors}$
	${ m GARule,22}$
Random, 27	sensors
Random, 27	GARule, 21
	31110dio, 21

$\operatorname{SimpleGA}$	MainWindow, 23
\sim SimpleGA, 28	$\operatorname{slotLoadTeamA}$
crossover, 28	MainWindow, 23
evolve, 28	${ m slot}{ m LoadTeamB}$
MutationRate, 28	MainWindow, 23
mutationRate, 28	${ m slot Move Ball}$
${ m SimpleGA,\ 28}$	BotView, 11
SimpleGA, 28	${ m slot}{ m MoveTeam}{ m A}$
size	BotView, 11
Team, 29	${\rm slotMoveTeamB}$
$\operatorname{slotBallMoved}$	BotView, 11
$\mathrm{GABot},16$	slotSaveTeamA
Game, 19	MainWindow, 24
${ m slot}{ m Bot}{ m Direction}$	${\bf slot Save Team B}$
Team, 31	MainWindow, 24
${f slot Bot Direction A}$	$\operatorname{slotScoreA}$
$\mathrm{GABot},16$	BotView, 11
${f slot Bot Direction B}$	${ m slot Score B}$
$\mathrm{GABot},16$	BotView, 11
${ m slot}{ m Bot}{ m Move}$	${ m slotStartTimer}$
Team, 31	GABot, 14
${ m slotBotMoveA}$	slotStopGame
GABot, 16	MainWindow, 24
${ m slotBotMoveB}$	slotStopTimer
GABot, 16	\overrightarrow{GABot} , 14
slotClearField	$\operatorname{slotTeamAScores}$
BotView, 11	GABot, 16
GABot, 17	$\operatorname{slotTeamBS}$ cores
slotClearScores	GABot, 17
BotView, 11	$\operatorname{slotTickInterval}$
slotFileClose	GABot, 14
MainWindow, 23	MainWindow, 24
$\operatorname{slotFileQuit}$	$\operatorname{slot}\operatorname{Turn}$
MainWindow, 23	GABot, 16
slotGameOver	$\operatorname{slot}\operatorname{Turn}\operatorname{Team}\operatorname{A}$
GABot, 14	BotView, 11
MainWindow, 24	$\operatorname{slot}\operatorname{Turn}\operatorname{Team}\operatorname{B}$
slotGameReady	BotView, 11
MainWindow, 24	$\operatorname{slotValueChanged}$
$\operatorname{slotGenerateTeamA}$	BotView, 12
MainWindow, 24	$\operatorname{slotViewGame}$
${ m slot}{ m Generate}{ m Team}{ m B}$	MainWindow, 23
MainWindow, 24	$\operatorname{slotViewStatusBar}$
slotGoGame	MainWindow, 23
MainWindow, 24	$\operatorname{slotViewToolBar}$
slotHelpAbout	MainWindow, 23
	1,16,111 1114 6 11 , 20

Speed		$\operatorname{Team} A$		
_	Ball, 5	GABot, 17		
speed		TeamAFileOpen		
	Ball, 4	MainWindow, 25		
_	Occument	TeamAFileSave		
	FeamParser, 33	MainWindow, 26		
	Element	TeamAGenerate		
	FeamParser, 33	MainWindow, 26		
StopG		teamAScores		
N.	IainWindow, 26	GABot, 15		
m 1		$\underline{Game, 18}$		
T1		TeamB		
	$\mathrm{Same},19$	GABot, 17		
T2		TeamBall		
	Same, 19	${ m GARule},22$		
Team,	. 29	Team, 31		
~	Team, 29	teamBall		
В	Ball, 5	GARule, 21		
b	ot, 30	TeamBFileOpen		
b	otDirection, 29	MainWindow, 26		
b	otMove, 29	TeamBFileSave		
	Sots, 31	MainWindow, 26		
	ots, 29	TeamBGenerate		
	Senerations, 31	MainWindow, 26		
	enerations, 30	teamBScores		
_	Soals, 31			
	oals, 30	GABot, 15		
		Game, 18		
	nsertBot, 29, 30	TeamData		
	osses, 31	readTeamData, 32		
	osses, 30	write Team Data, 32		
	Jame, 31	TeamData, 32		
	ame, 30, 31	${ m teamData}$		
	andomTeam, 30	TeamParser, 33		
	emoveBot, 29	${ m teamFileOpen}$		
	ze, 29	MainWindow, 25		
sl	totBotDirection, 31	teamFileSave		
sl	totBotMove, 31	MainWindow, 25		
${ m T}$	Feam, 29	${ m teamGenerateRandom}$		
${ m T}$	eamBall, 31	MainWindow, 25		
${ m T}$	lies, 31	TeamParser		
ti	6, 30	bot, 33		
	Vins, 31	botcount, 33		
	vins, 30	endElement, 33		
$_{ m team}$	•	rule, 33		
	Ball, 4, 5	rulecount, 33		
	FeamParser, 33	sens, 33		
_	<i>22.562</i> , 0.5	ъснь, ээ		

1 1D 1 22	77'
startDocument, 33	View
startElement, 33	MainWindow, 25
team, 33	ViewGame
teamData, 33	MainWindow, 26
TeamParser, 33	ViewMenu
TeamParser, 32	MainWindow, 25
Tick	ViewStatusBar
$\mathrm{GABot},17$	MainWindow, 26
TickInterval	ViewToolBar
GABot, 17	MainWindow, 26
TicksUntilNextMove	
Ball, 5	Width
Bot, 10	Game, 20
ticksUntilNextMove	Wins
Ball, 5	Team, 31
Bot, 7	wins
Ties	Team, 30
Team, 31	write Team Data
ties	TeamData, 32
Team, 30	
TimeWithBall	X
Bot, 9	Coordinate, 13
timeWithBall	
Bot, 8	у
TimeWithBallWeight	Coordinate, 13
Bot, 10	
timeWithBallWeight	
Bot, 9	
Toolbar	
MainWindow, 25	
tradeBall	
Game, 19	
Turn	
GARule, 22	
turn	
Game, 18	
GARule, 21	
Turns	
Game, 19	
turnTeamA	
GABot, 15	
turnTeamB	
${ m GABot},15$	
valueChanged	
<u> </u>	
BotView, 11	