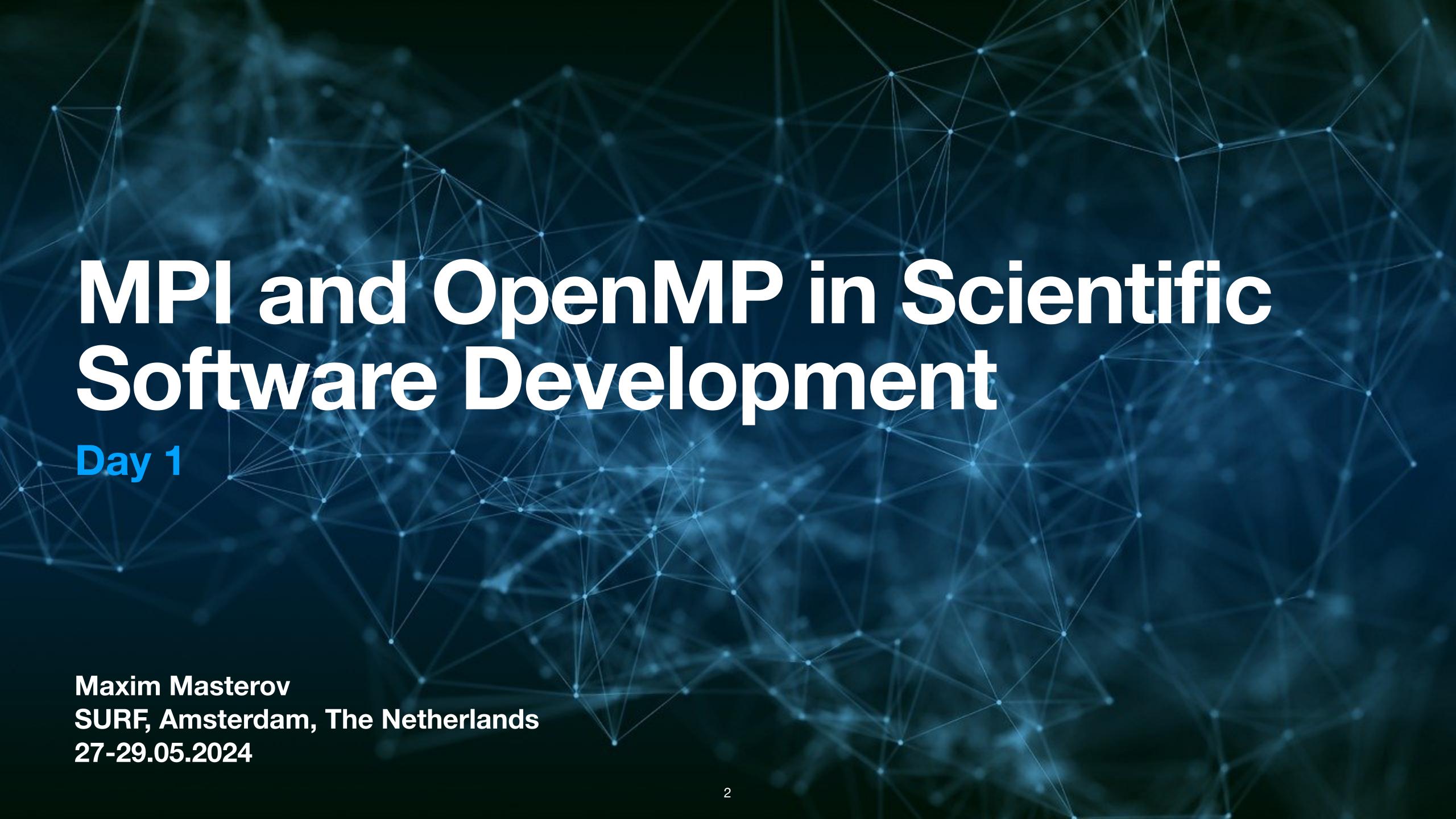
We start @9:05



Contents

Overview

Day 1

- @16:00 Dr. Matthias Möller (TU Delft)
- MPI (recap)
- Connecting to Snellius supercomputer
- Jacobi solver
- Performance analysis & debugging tools
- Hands-on

Day 2

- @12:00 Dr. Nicola
 Spallanzani (MaX CoE)
- MPI communications
- Domain decomposition
- MPI topologies
- Hands-on

Day 3

- @12:00 Dr. Remco Havenith (RUG)
- MPI IO
- Advanced OpenMP
- Hybrid programming
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Disclaimer

Just a disclaimer

- This is **not the 2nd part** of the course for the "beginners".
- The whole course is about **hands-on experience**. Please, pay attention, you will write a lot of code.
- All codes are written in C++. However, it's sufficient to know C to do assignments.
- If you are only familiar with FORTRAN, please, check out some cheat sheets on the Internet.
- All materials will be available after the course under MIT license. You can use them or distribute, just keep the references:)
- This is the **3rd time** this course is been **offered**. We might have missed something, made typos etc. Your feedback is most appreciated.

Message Passing Interface



2023 - MPI 4.1











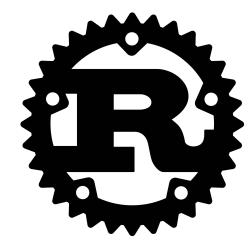












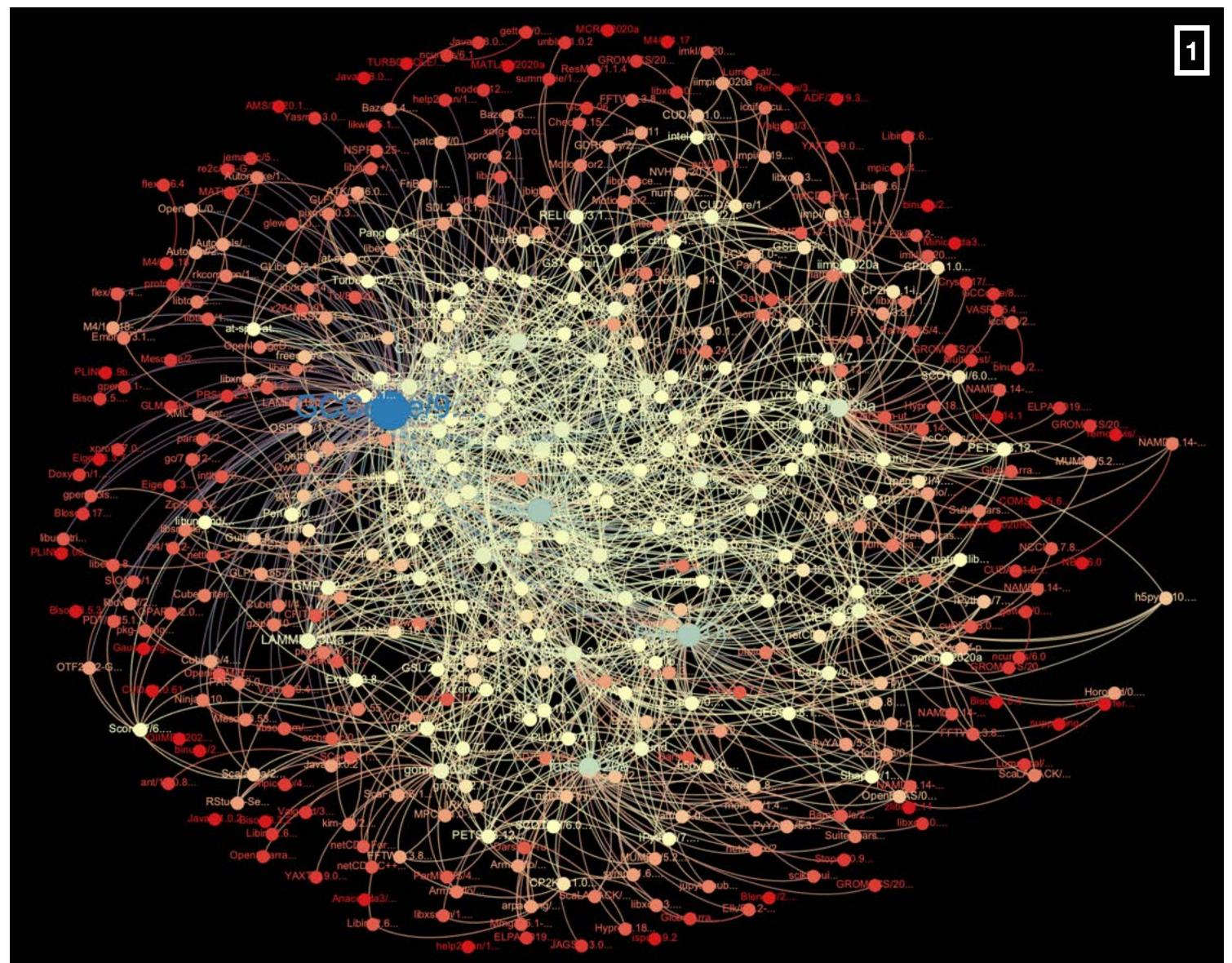
2012 - MPI 3.0

Microsoft

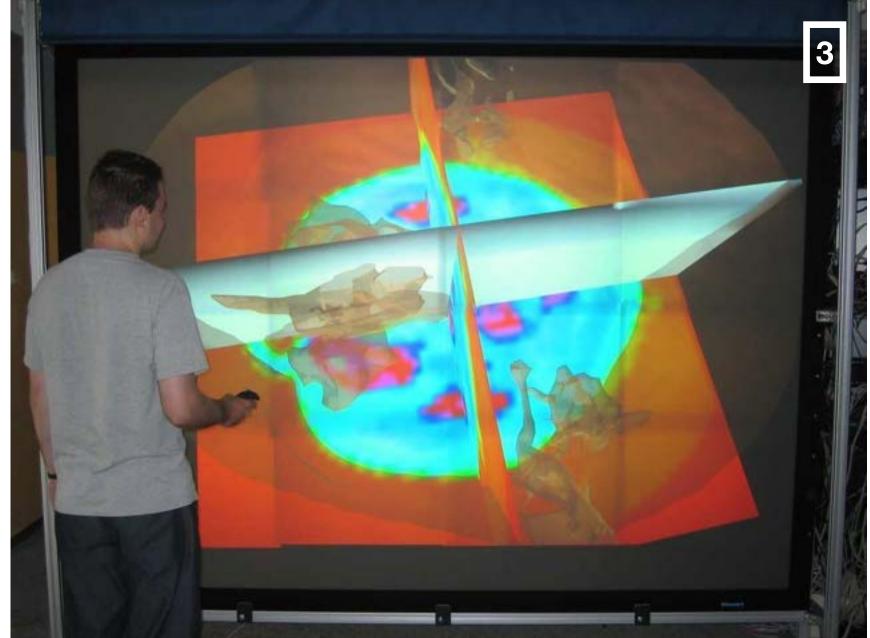


1994 - MPI 1.0

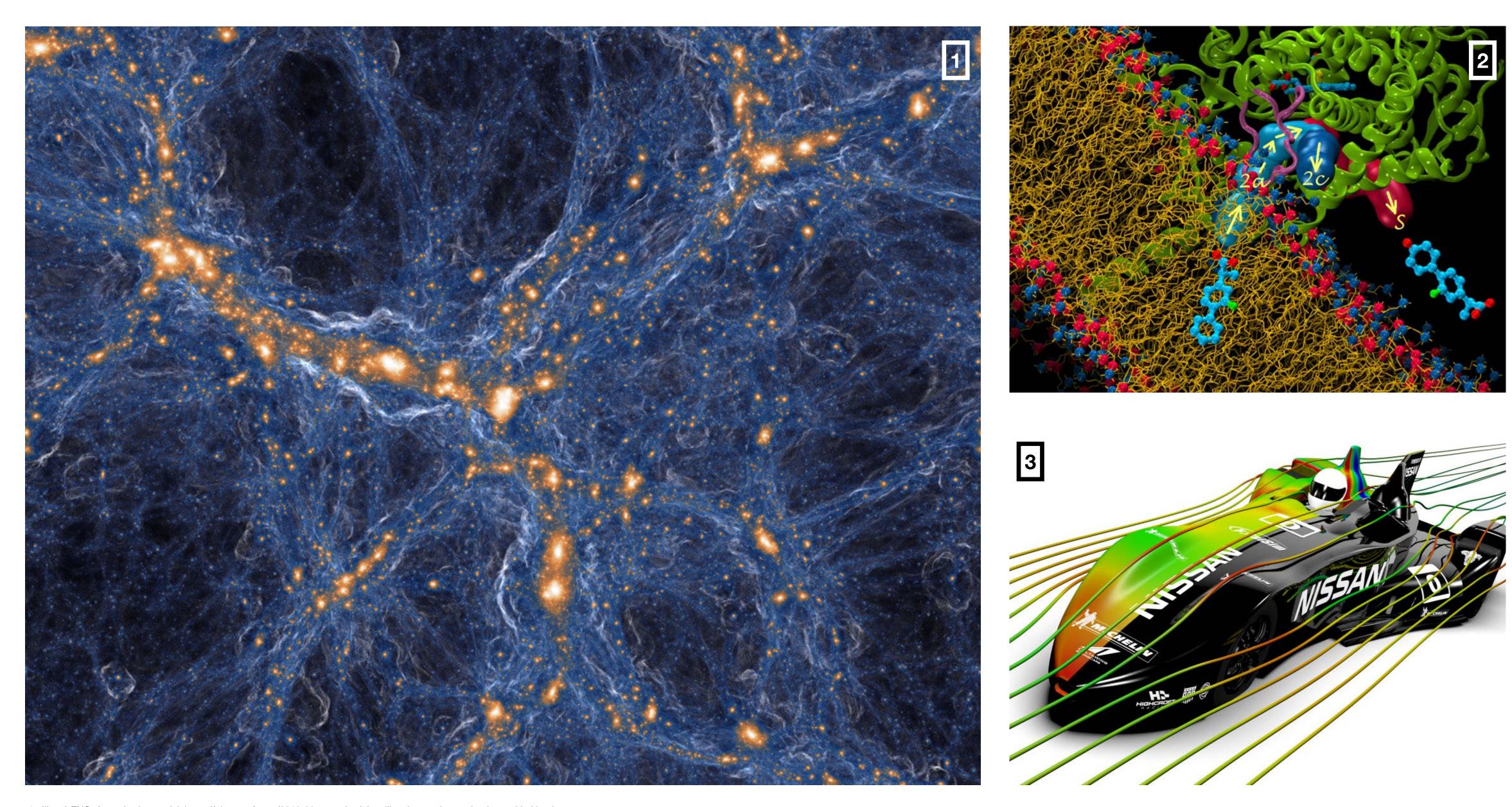
1991 - First discussion



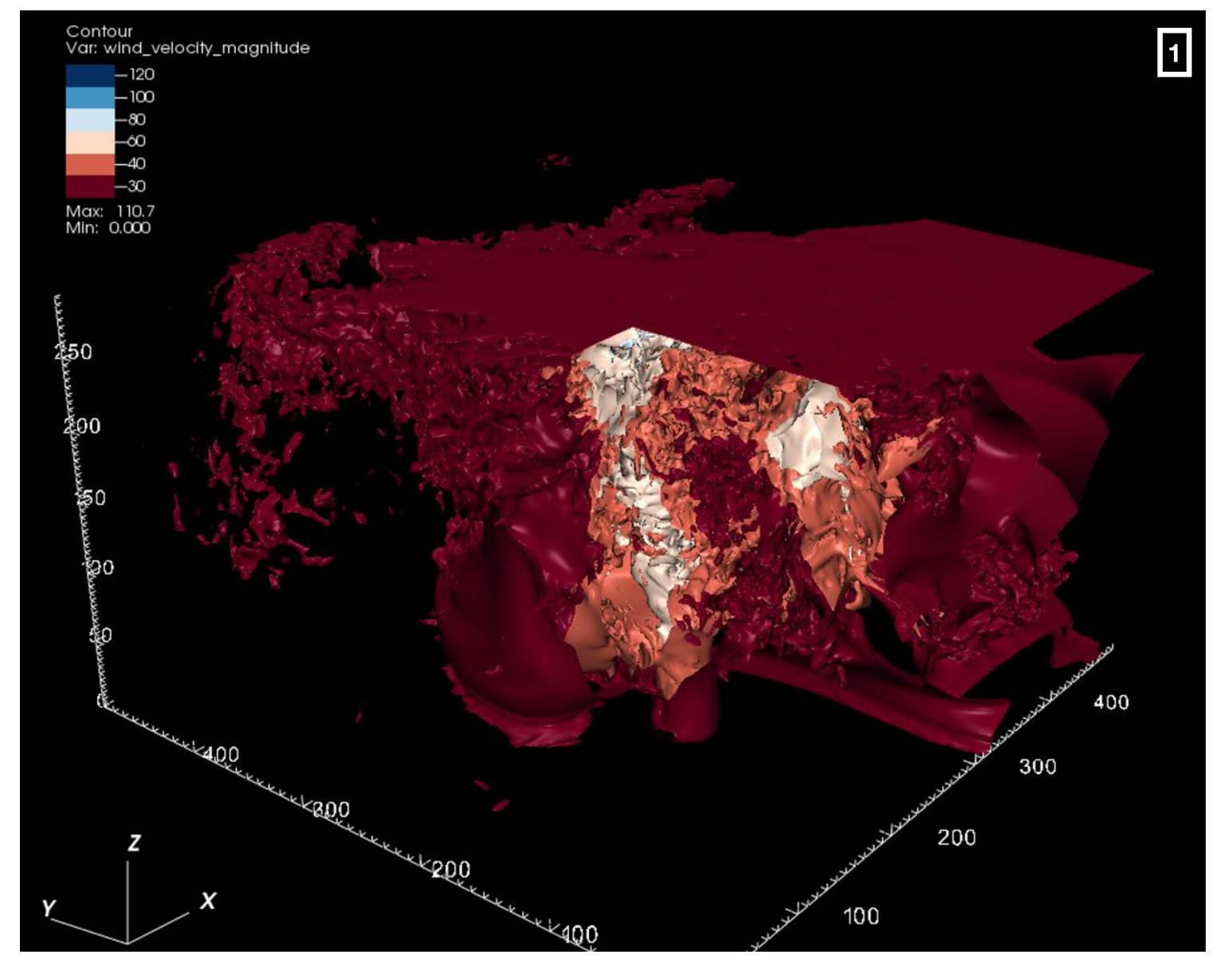


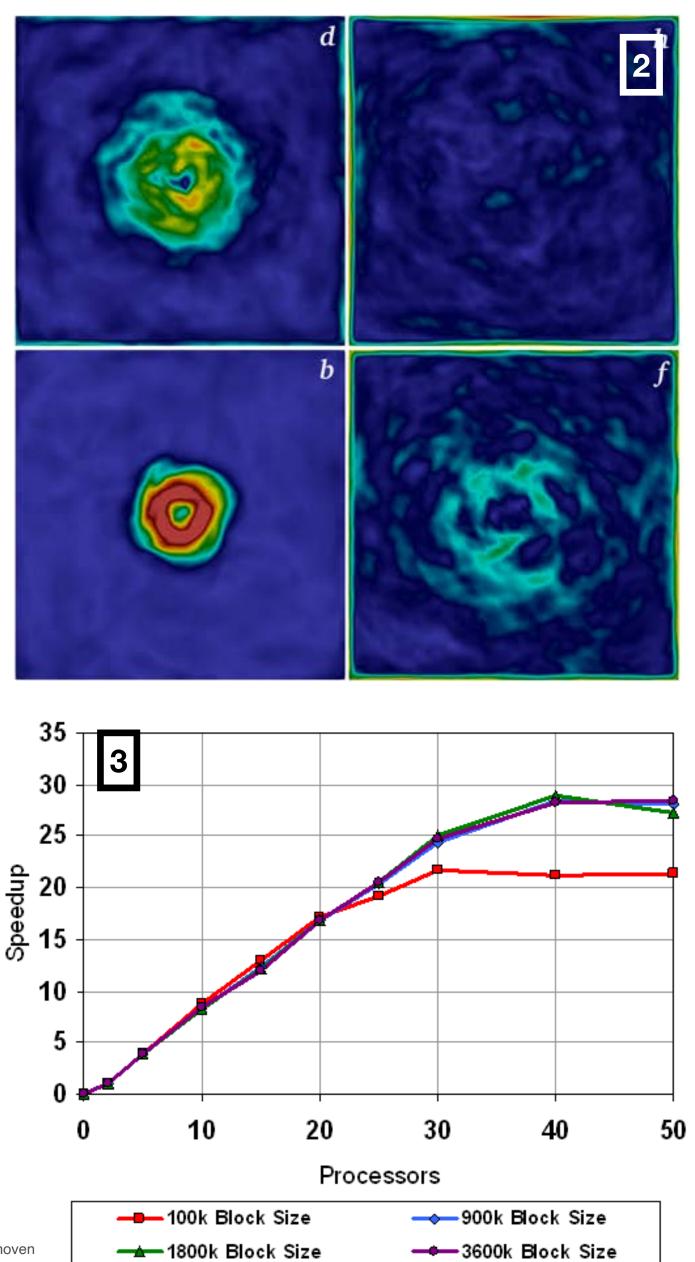


- Graph of modules installed on Cartesius. Visualised with Gephi.
 An example of a mobile game. Doolan, Daniel & Tabirca, Sabin. (2007). Bluetooth Gaming with the Mobile Message Passing Interface (MMPI).
 FlowVR. Visualisation software. Jérémie Allard, Bruno Raffin (2005), A Shader-Based Parallel Rendering Framework, IEEE Visualization 2005 conference proceedings



- IllustrisTNG. Astrophysics model. https://phys.org/news/2018-02-astrophysicists-illustristng-advanced-universe-kind.html
 VMD. Visualisation software. (2011) *PLoS Computational Biology* Issue Image I Vol. 7(8) August 2011. PLoS Comput Biol 7(8)
 TotalSim. CFD software. https://www.totalsimulation.co.uk/digital-race-car/





- Vislt. Visualisation software. https://www.technologynetworks.com/informatics/articles/visit-application-speeds-visualization-workloads-empowering-global-research-305352
 FoxBerry. Multiphase CFD software. Visualized with ParaView. Masterov, M. V. (2019). Towards industrial-scale bubble columns: the development and application of the high performance computing framework. Technische Universiteit Eindhoven MPIBZIP2. Parallel compressing library. http://compression.ca/mpibzip2/ 10

Alternatives







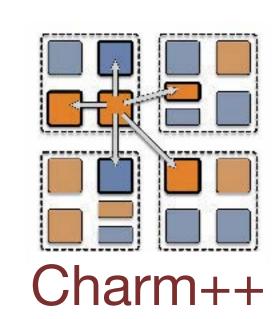
- The goal:
 - Raise the level of abstraction
 - Create domain-specific framework
- Issues, compared to MPI+X:
 - Less known
 - Less mature
- Look at PAW-ATM: https://sourceryinstitute.github.io/PAW/















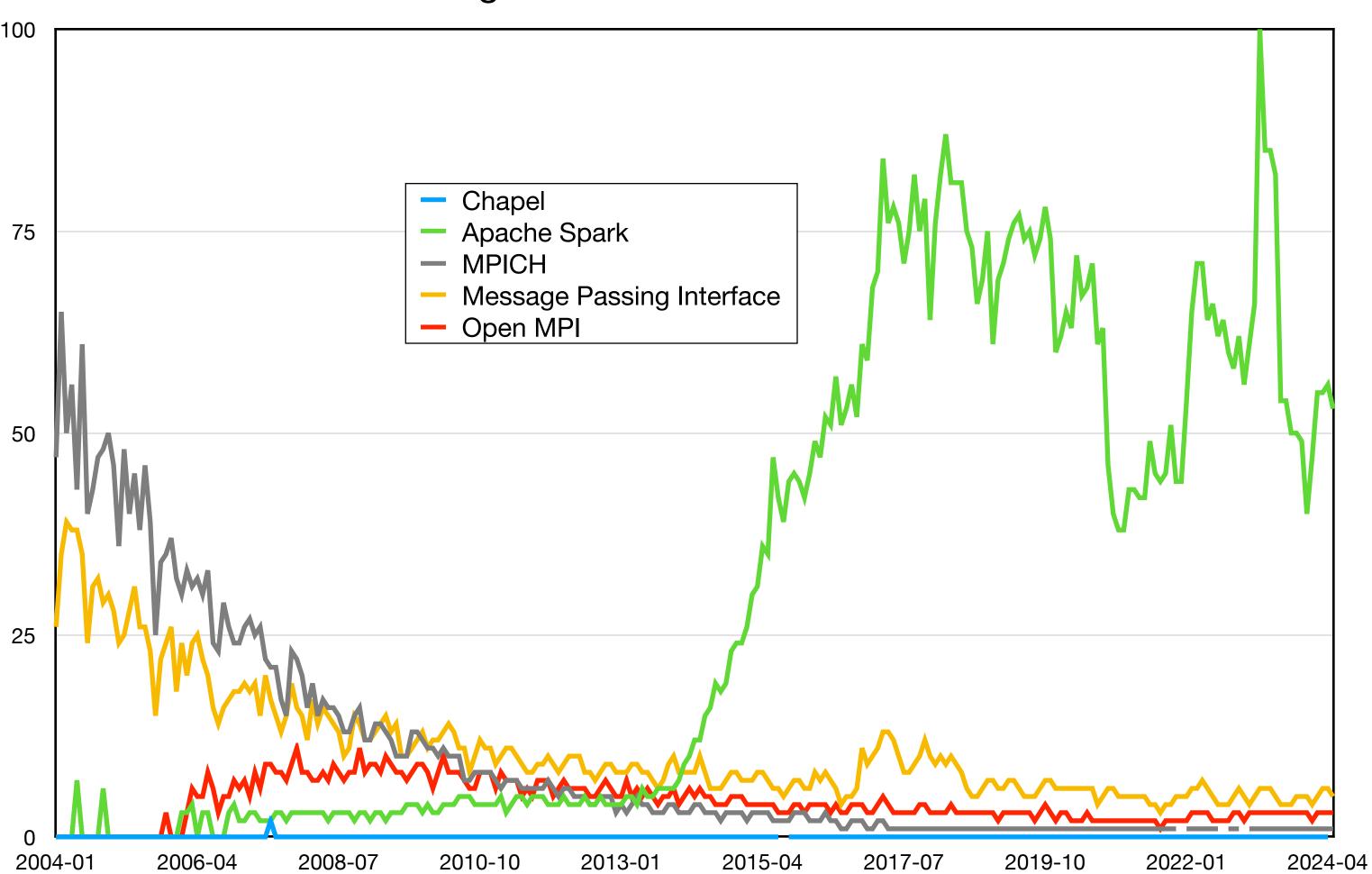
Alternatives







Google search. Interest over time!



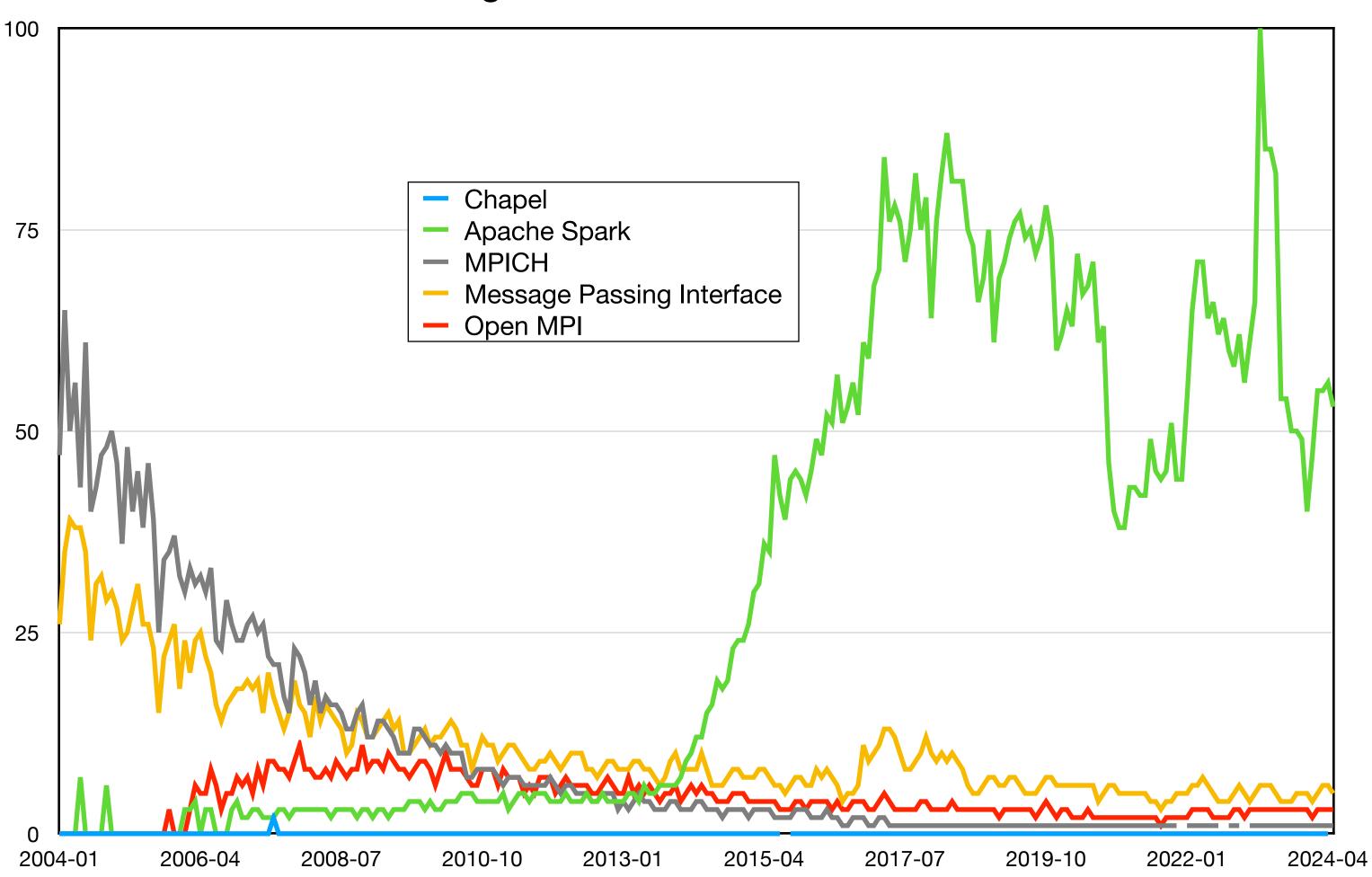
Alternatives

- New hardware —> new software requirements —> new standards
- MPI remains the #1 standard for scientific applications, but there are some competitors

Example, 1D diffusion²

Implementation	LoC
MPI+Python	65
Spark+Python	34
Chapel	26

Google search. Interest over time!



https://trends.google.com/trends/explore?cat=5&date=all&q=%2Fm%2F0gnckq,%2Fm%2F0ndhxqz,%2Fm%2F03z8q2,%2Fm%2F01gb80,%2Fm%2F07yb2g
 https://www.dursi.ca/post/hpc-is-dying-and-mpi-is-killing-it.html#mpi

Alternatives

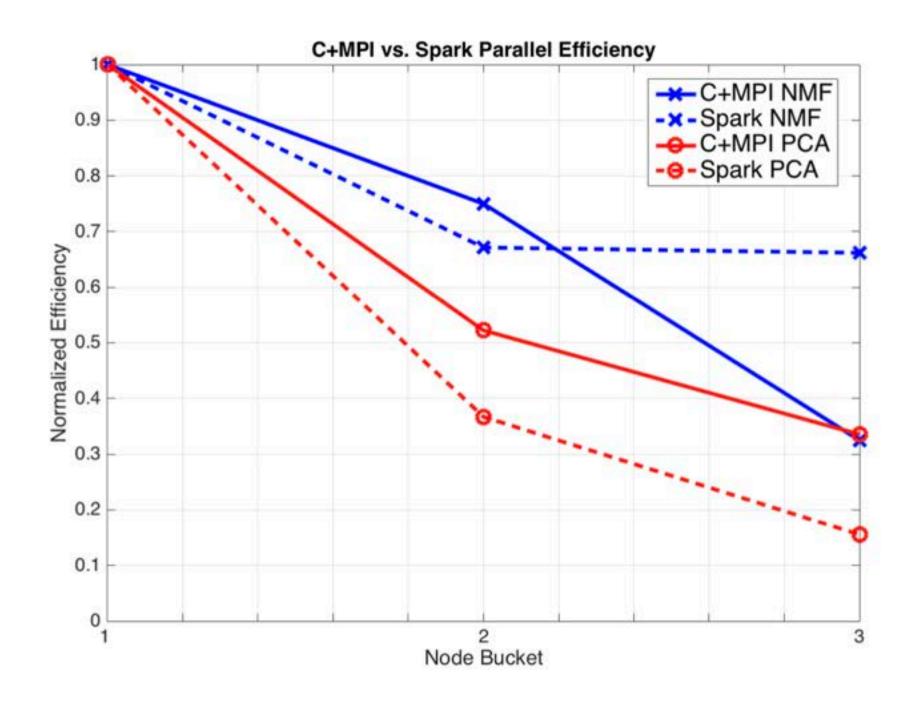


Figure 4: Comparison of parallel efficiency for C+MPI and Spark. The x-axis label "Node Bucket" refers to the node counts. For NMF these are 50, 100, and 300 nodes (left to right) and 100, 300, and 500 nodes for PCA. For both algorithms, efficiency is measured relatively to the performance at the smallest node count.

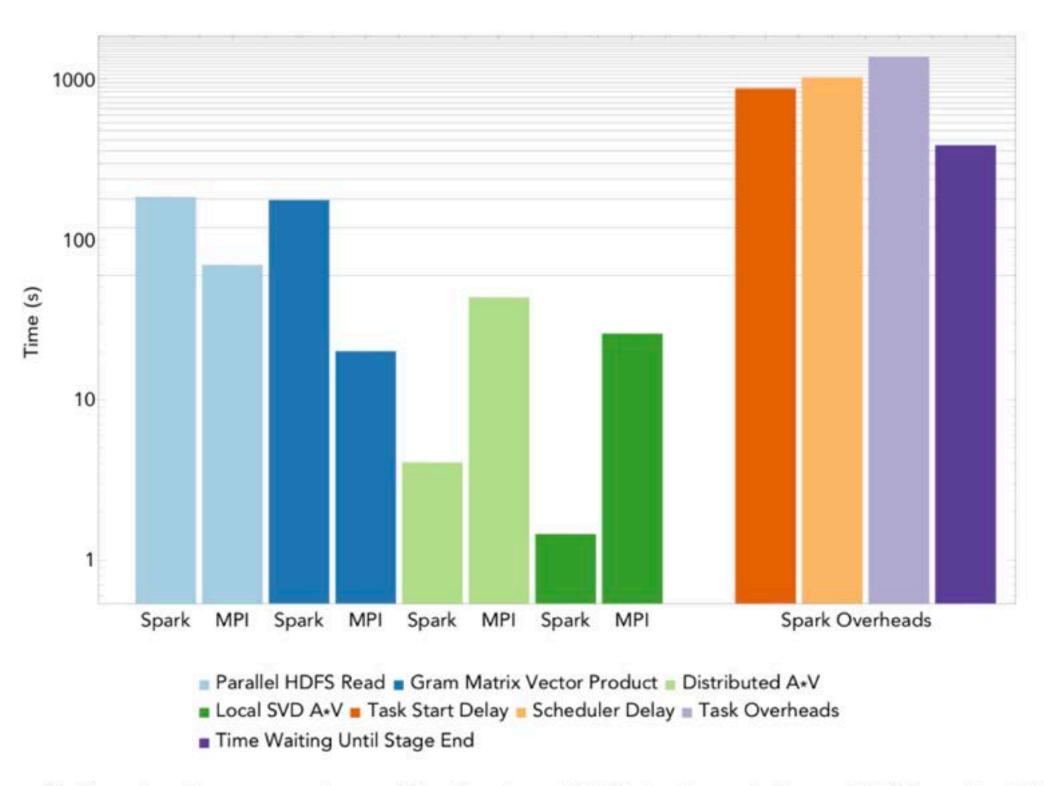
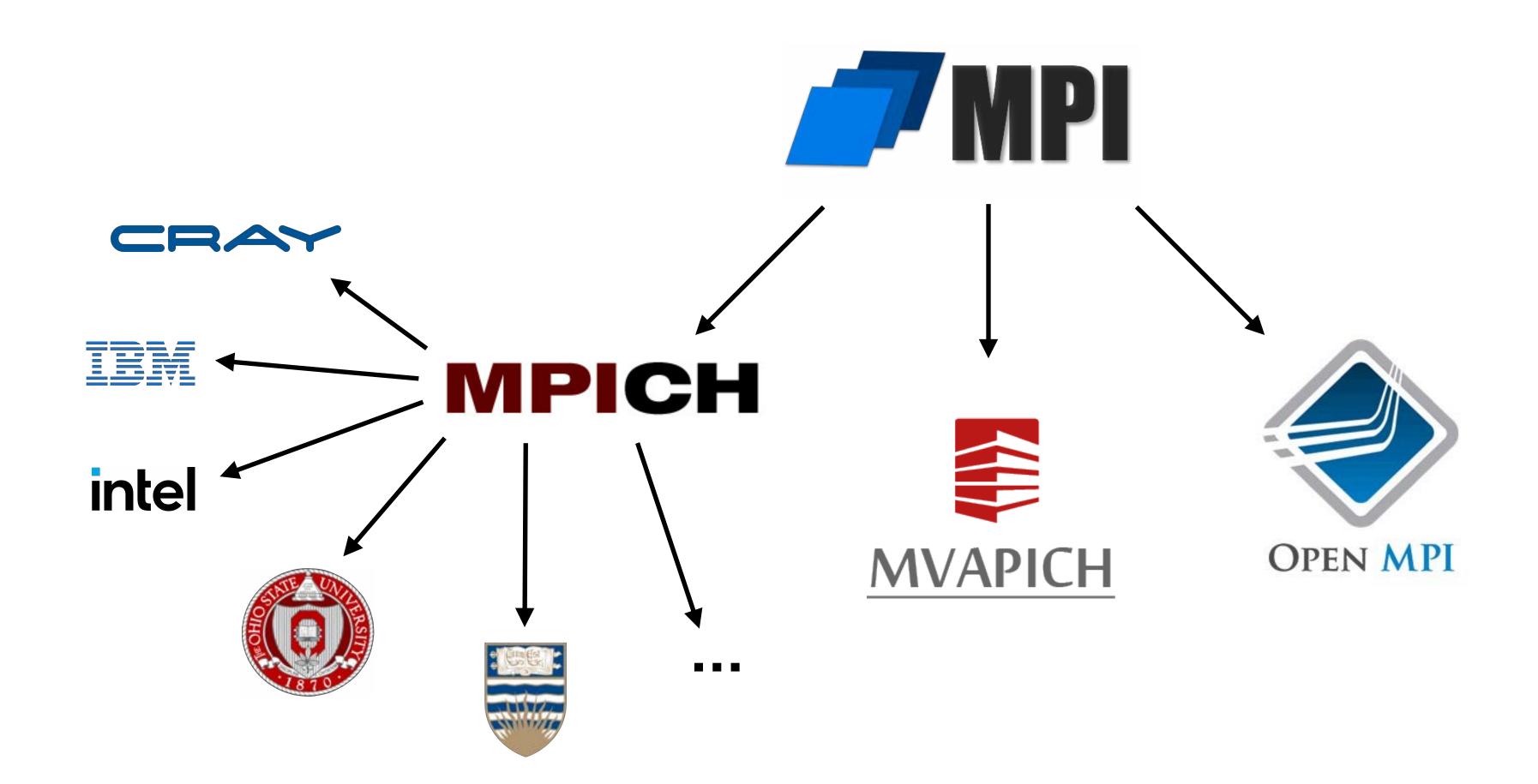


Figure 6: Running time comparison of the Spark and MPI implementations of PCA on the 16TB Atmosphere matrix. Each bin depicts the sum, over all stage, of the time spent in that bin by the average task within a stage.

^{1.} A. Gittens et al., "Matrix factorizations at scale: A comparison of scientific data analytics in spark and C+MPI using three case studies," 2016 IEEE International Conference on Big Data (Big Data), 2016, pp. 204-213

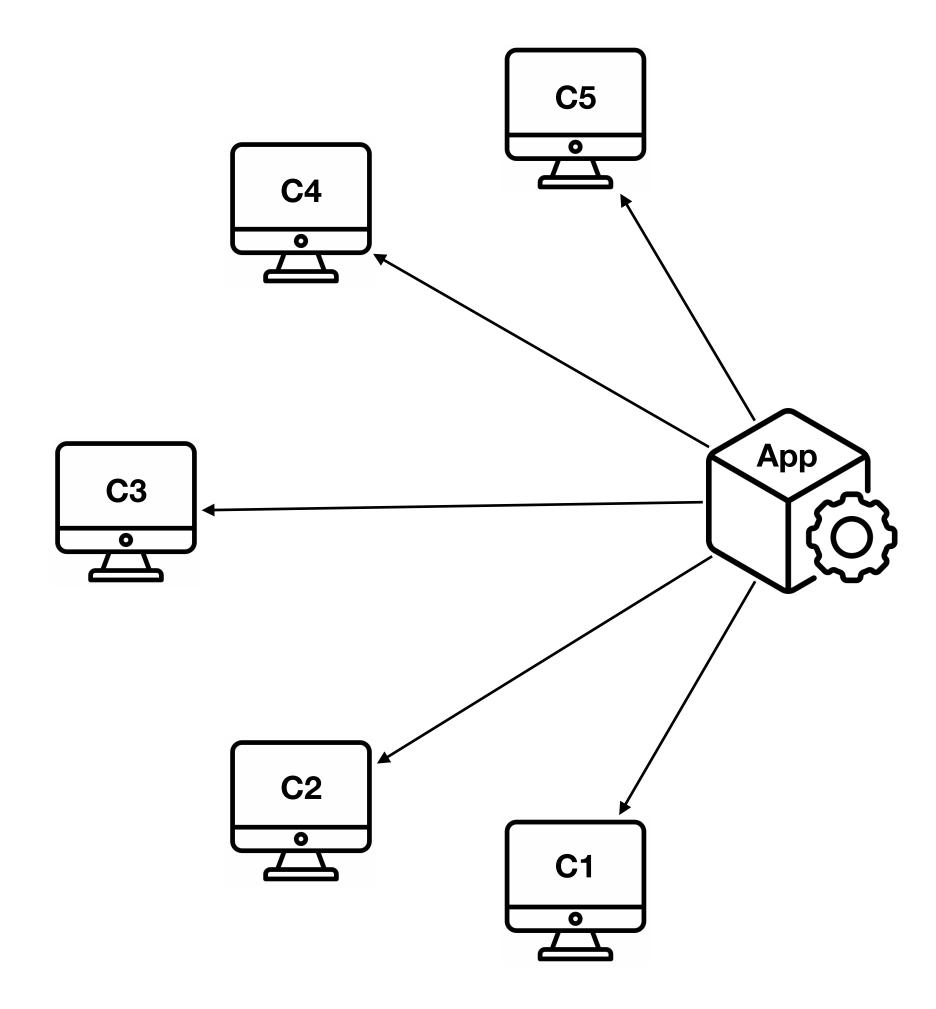
MP

Versions



Idea

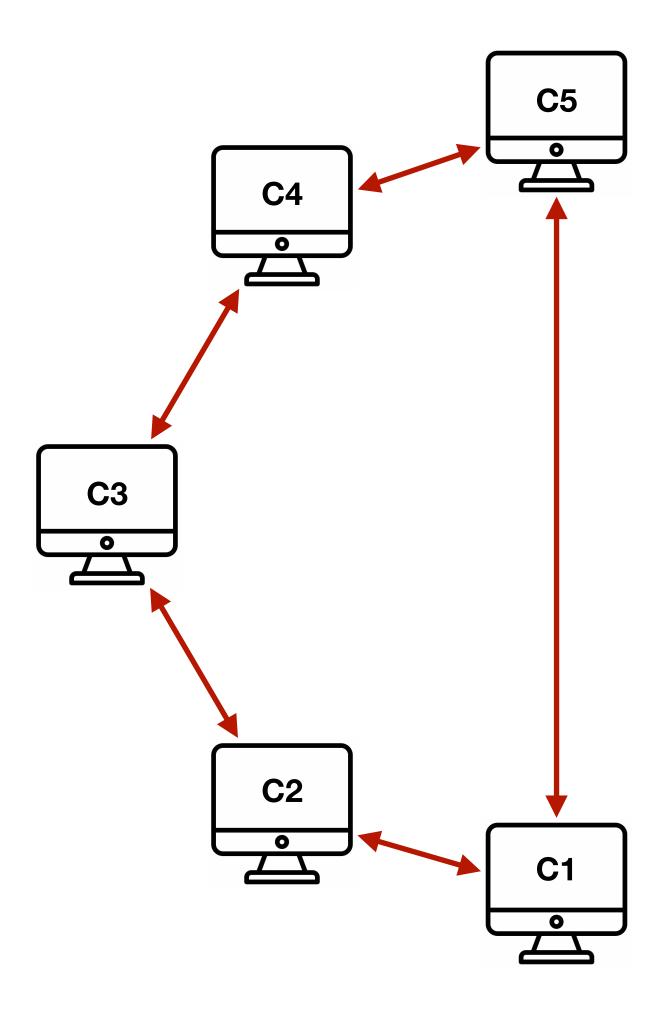
Distribution of the workload across multiple processes



https://www.flaticon.com/free-icon/computer 2344269
 https://www.flaticon.com/free-icon/3d-modeling 4229105

Idea

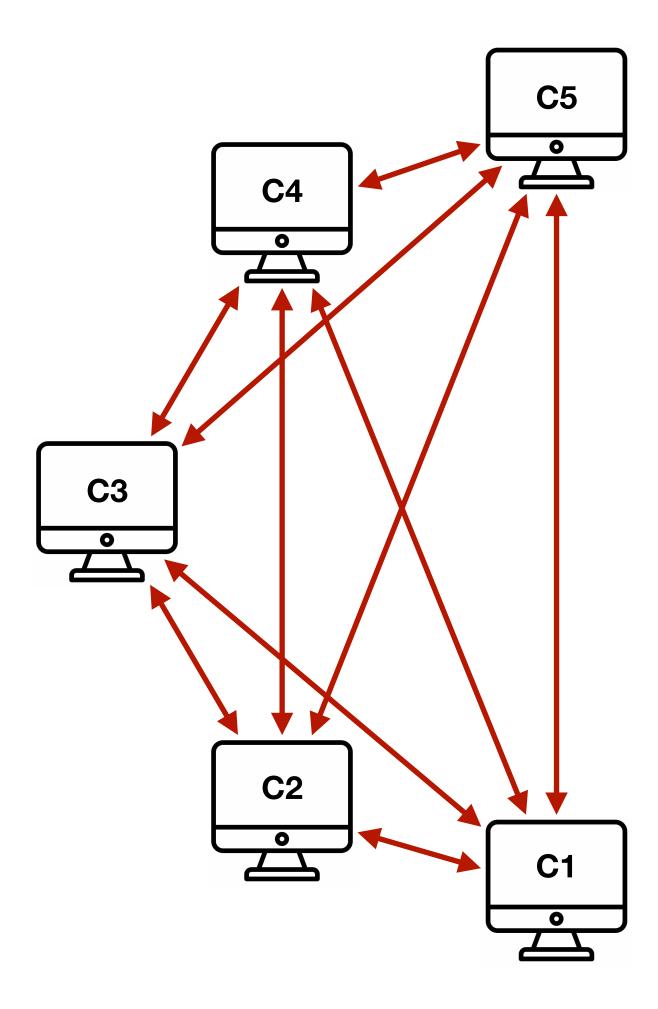
- Distribution of the workload across multiple processes
- Main influence from:
 - the network



17

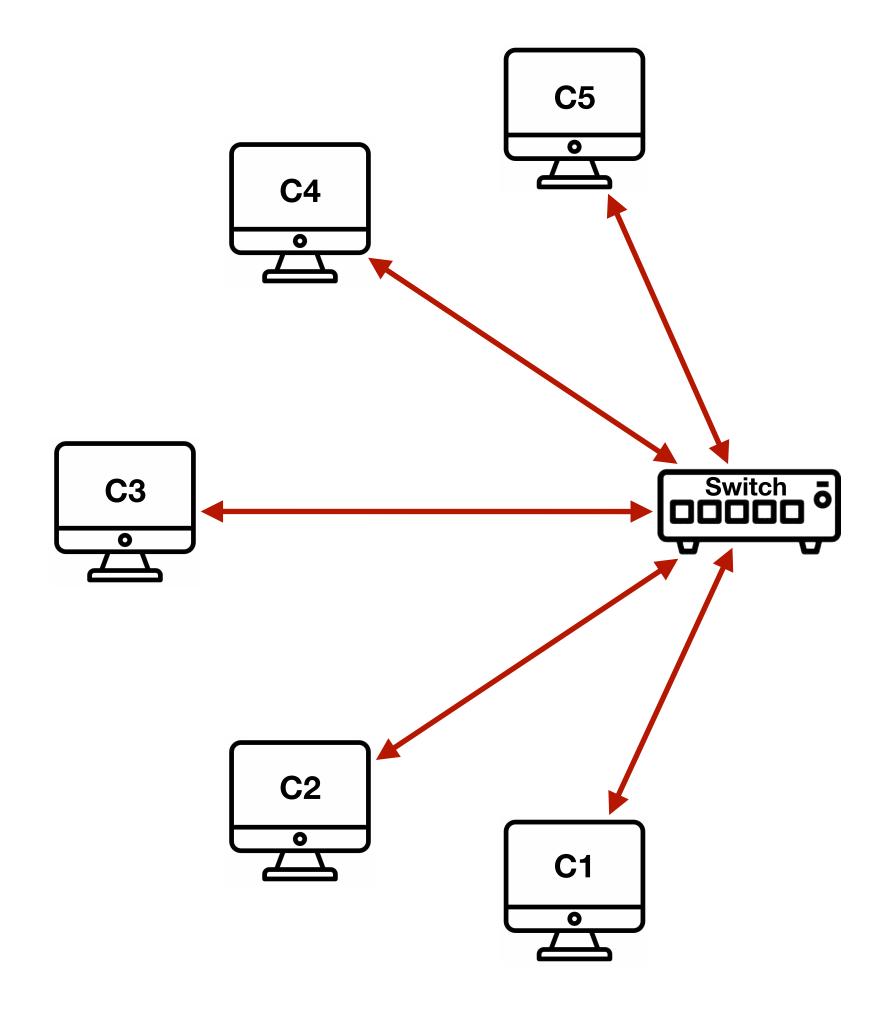
Idea

- Distribution of the workload across multiple processes
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Idea

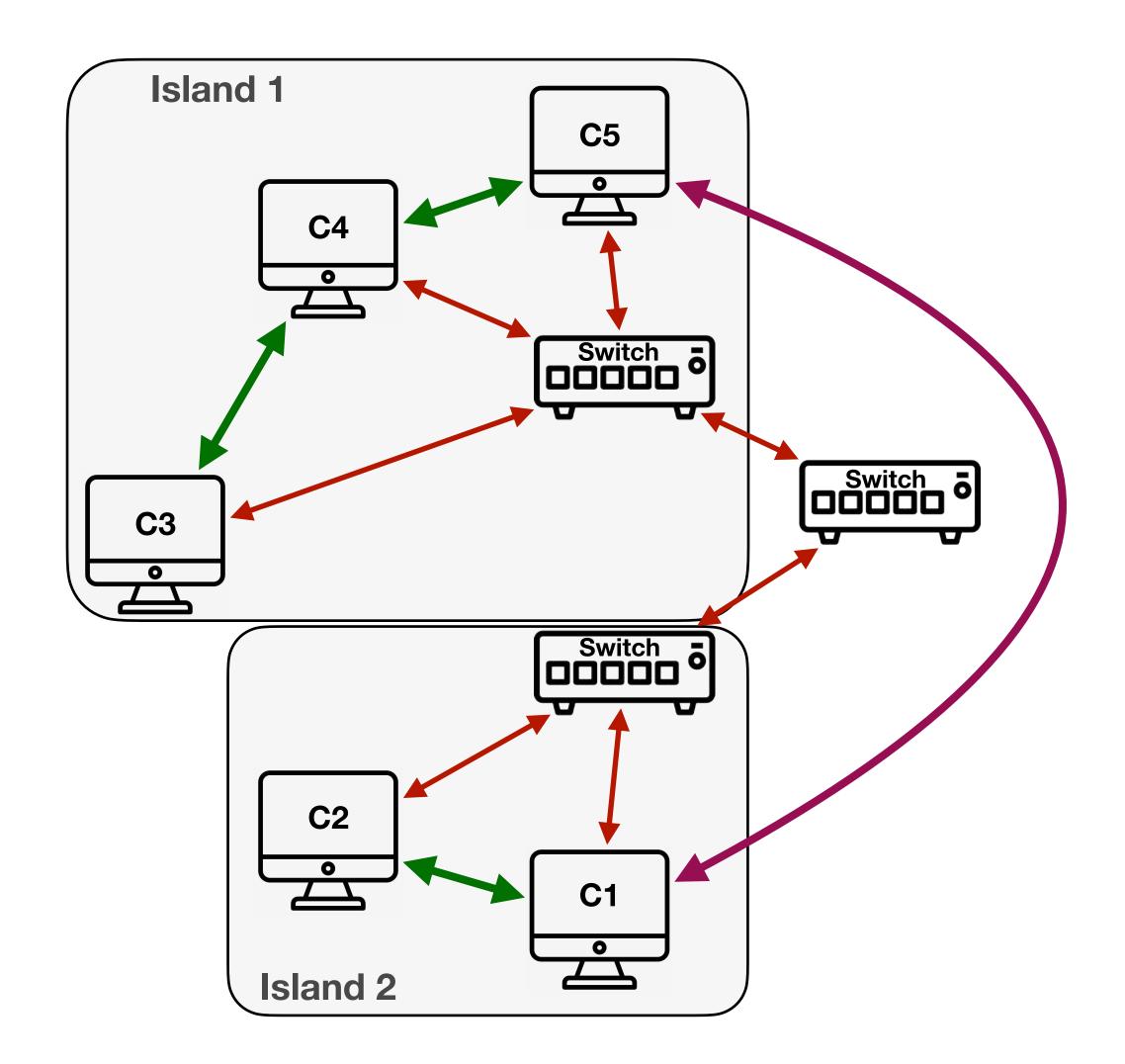
- Distribution of the workload across multiple processes
- Main influence from:
 - the network



Idea

- Distribution of the workload across multiple processes
- Main influence from:
 - the network
 - the communication frequency
 - the message size
 - the file system

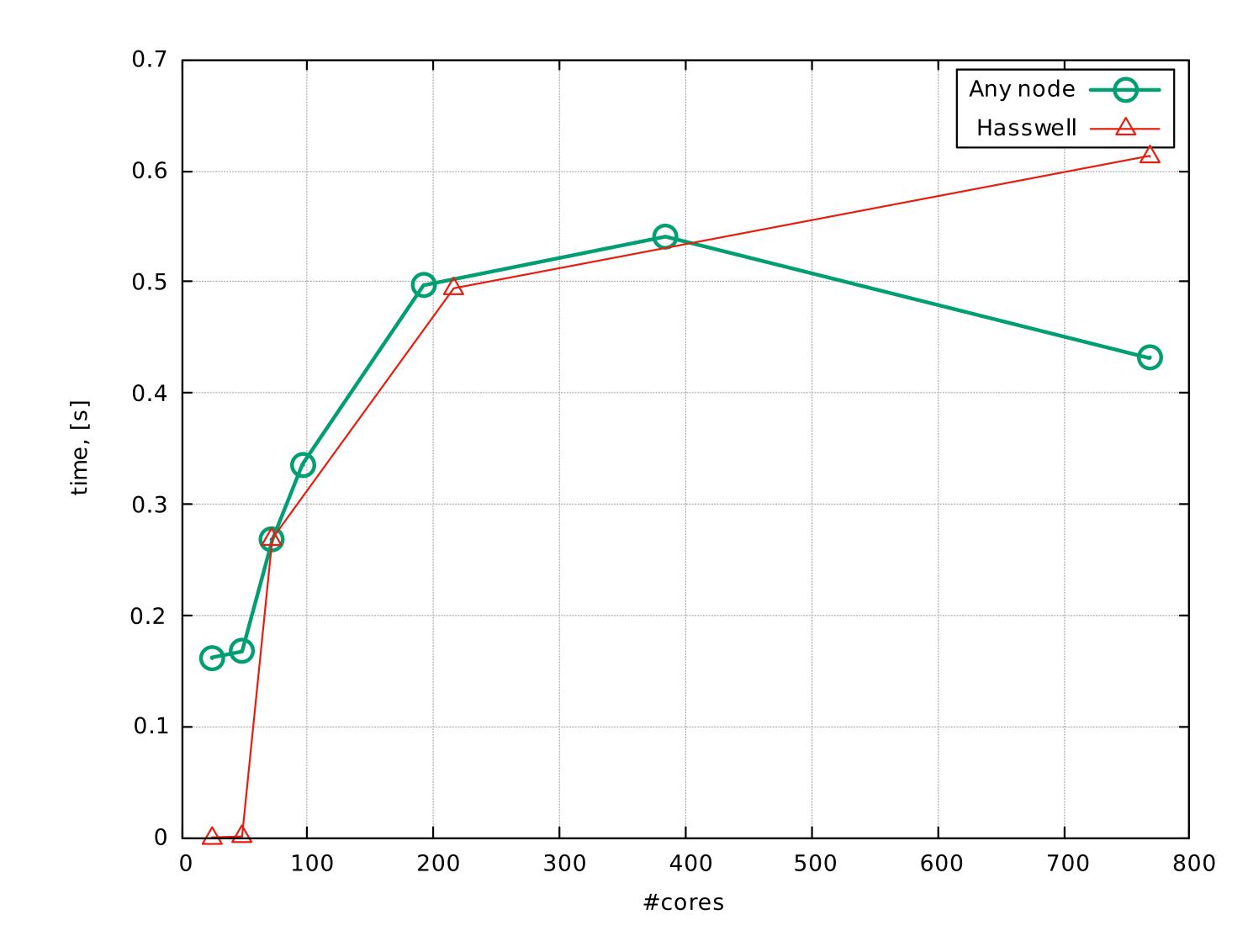
 Will come back to it later

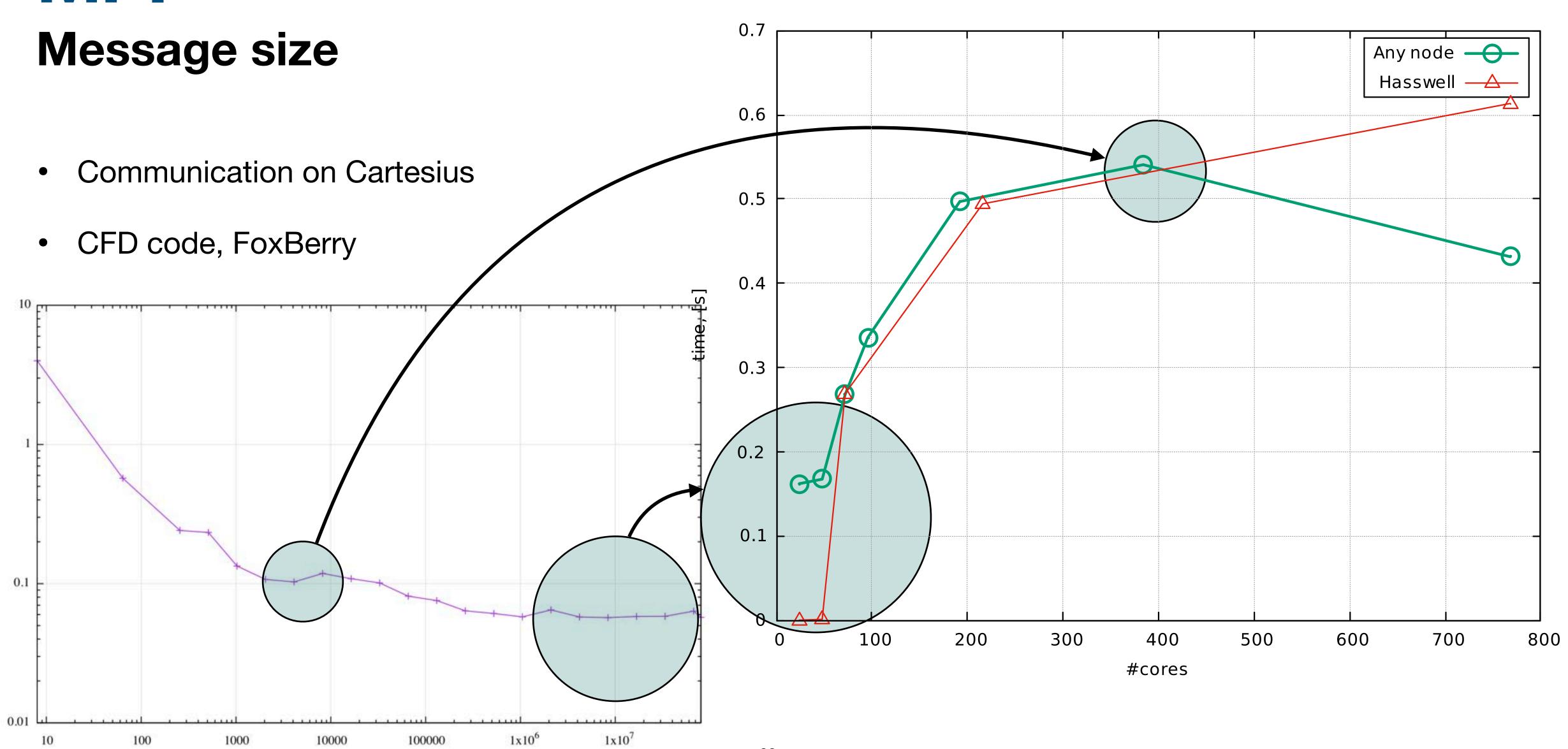


^{1.} https://www.flaticon.com/free-icon/computer 2344269

Message size

- Communication time (Cartesius)
- CFD code, FoxBerry
- Structured grid with 27M DoFs
- Double precision FP
- Non-blocking communication
- Buffered messaged
- The message size at 700 cores is ~3KB



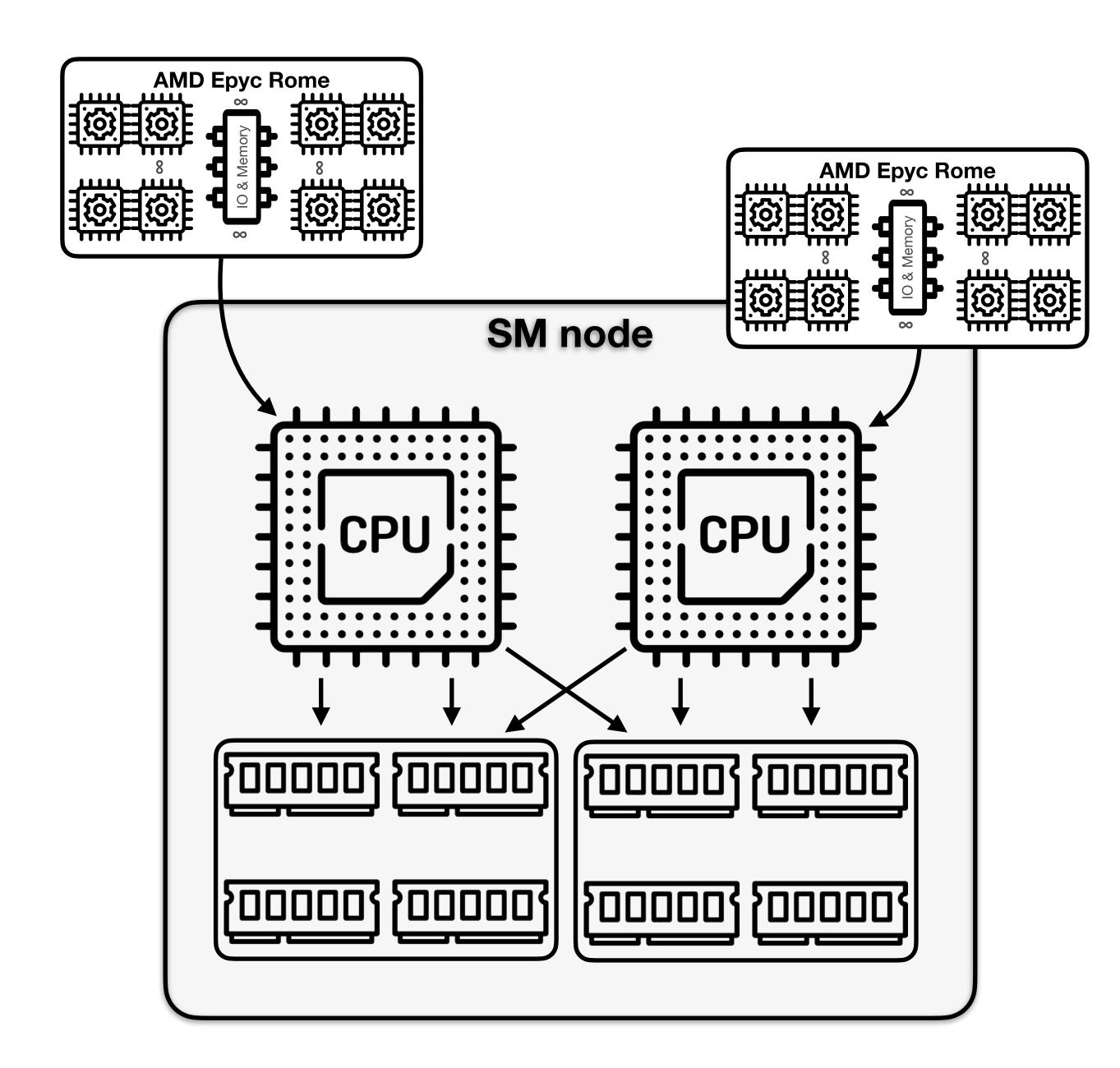


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Message size, [B]

Shared Memory Nodes

- Behaviour on SM nodes is implementationspecific and is not described by the standard
- Some MPI libraries avoid "standard" communications on SM nodes thus, improving the performance (see BTL in OpenMPI)
- Some implementations provide run-time tuning parameters for SM execution
- There is no such problem as memory affinity (as with threads)



^{1. &}lt;a href="https://www.flaticon.com/free-icon/ram_900330">https://www.flaticon.com/free-icon/ram_900330

^{2.} https://www.flaticon.com/free-icon/cpu 689379

^{3.} https://www.flaticon.com/free-icon/cpu 4272570

^{4.} https://www.flaticon.com/free-icon/ram 3076285

Rules of thumb

- Follow the KISS principle keep it simple stupid
- Make it maintainable
- Make it efficient
- Unless it is completely necessary:
 - Avoid complex data structures
 - Avoid complex logic
- Always do refactoring

Typical MPI example

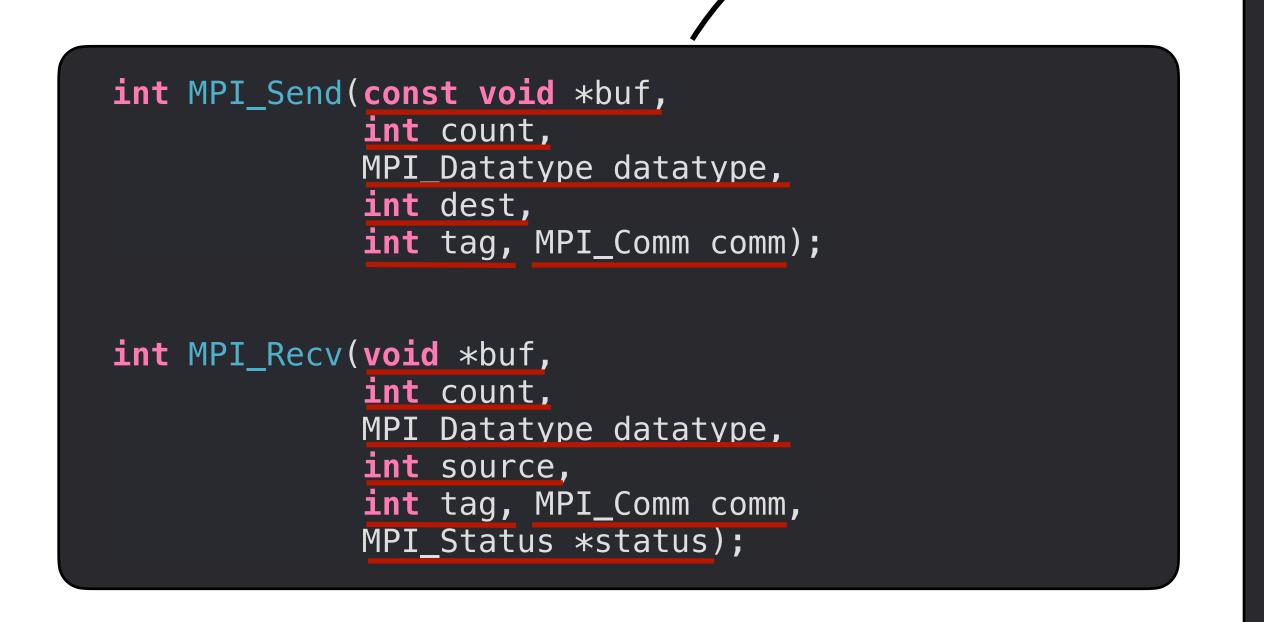
```
#include <cmath>
#include <mpi.h>
#include <stdio.h>
int main(int argc, char** argv) {
    // Initialize the MPI environment
   MPI_Init(&argc, &argv);
    // Get the number of processes
    int world_size;
    MPI_Comm_size(MPI_COMM_WORLD, &world_size);
    // Get the rank of the process
    int world_rank;
   MPI_Comm_rank(MPI_COMM_WORLD, &world_rank);
    // Get the name of the processor
    char processor_name[MPI_MAX_PROCESSOR_NAME];
    int name_len;
   MPI_Get_processor_name(processor_name, &name_len);
    // Print out a hello world message
    printf("Hello world from processor %s, "
           "rank %d out of %d processors\n",
           processor_name, world_rank, world_size);
    // Finalize the MPI environment.
   MPI_Finalize();
```

Rules of thumb

- Follow the KISS principle keep it simple stupid
- Make it maintainable
- Make it efficient
- Unless it is completely necessary:
 - Avoid complex data structures
 - Avoid complex logic
- Always do refactoring

```
Example of a
if(greater1 && lesser1)
                                                                 real code
    nozzle_1_send_to_root_proc = true;
    for(size_t i = 0; i < (size_t)(max_graph_neighbours); ++i)</pre>
        ++comm_look_up_table(my_rank, source[i]);
       MPI_Isend(&nozzle_1_send_to_root_proc,
                 MPI_CXX_B00L,
                  source[i],
                  nozzle1_tag1,
                  _grid->GetLocMPIComm(),
                  &nozzle1_snd_rqst[i]);
MPI_Bcast(comm_look_up_table.data(),
          comm_look_up_table.size(),
         MPI_INT,
          rank_with_nozzle1_center,
          internal_MPI_Comm);
MPI_Waitall(max_graph_neighbours, nozzle1_snd_rqst, nozzle1_status);
MPI_Request rqst;
int count_to_root_proc = 0;
if(comm_look_up_table(rank_with_nozzle1_center, my_rank))
    int dummy = 0, weighted = 0;
    MPI_Recv(&nozzle_1_send_to_root_proc,
            MPI CXX BOOL,
             rank_with_nozzle1_center,
             nozzle1_tag1,
             _grid->GetLocMPIComm(),
             &nozzle1_status_point1);
    MPI_Dist_graph_neighbors_count(_grid->GetLocMPIComm(),
                                   &max_graph_neighbours, &dummy, &weighted);
    source.resize(max_graph_neighbours);
    source_weights.resize(max_graph_neighbours);
    dest.resize(max_graph_neighbours);
    dest_weights.resize(max_graph_neighbours);
    MPI_Dist_graph_neighbors(_grid->GetLocMPIComm(),
                             max_graph_neighbours,
                            source.data(),
                            source_weights.data(),
                            max_graph_neighbours,
                             dest.data(),
                             dest_weights.data());
```

MPI MPI code



```
class MPIManager{
public:
    inline int send(const int* buff, int size, int pid,
int tag)
        MPI_Send(
                 &buff,
                 size,
                 MPI_INT,
                 pid,
                 tag,
                 mpi_comm);
        // handle errors
    inline int recv(int* buff, int size, int pid, int
tag)
        MPI_Status status;
        MPI_Recv(
                 &buff,
                 size,
                 MPI_INT,
                 pid,
                 tag,
                 mpi_comm,
                 &status);
        // handle errors
private:
   MPI_Comm mpi_comm;
};
```

MPI code

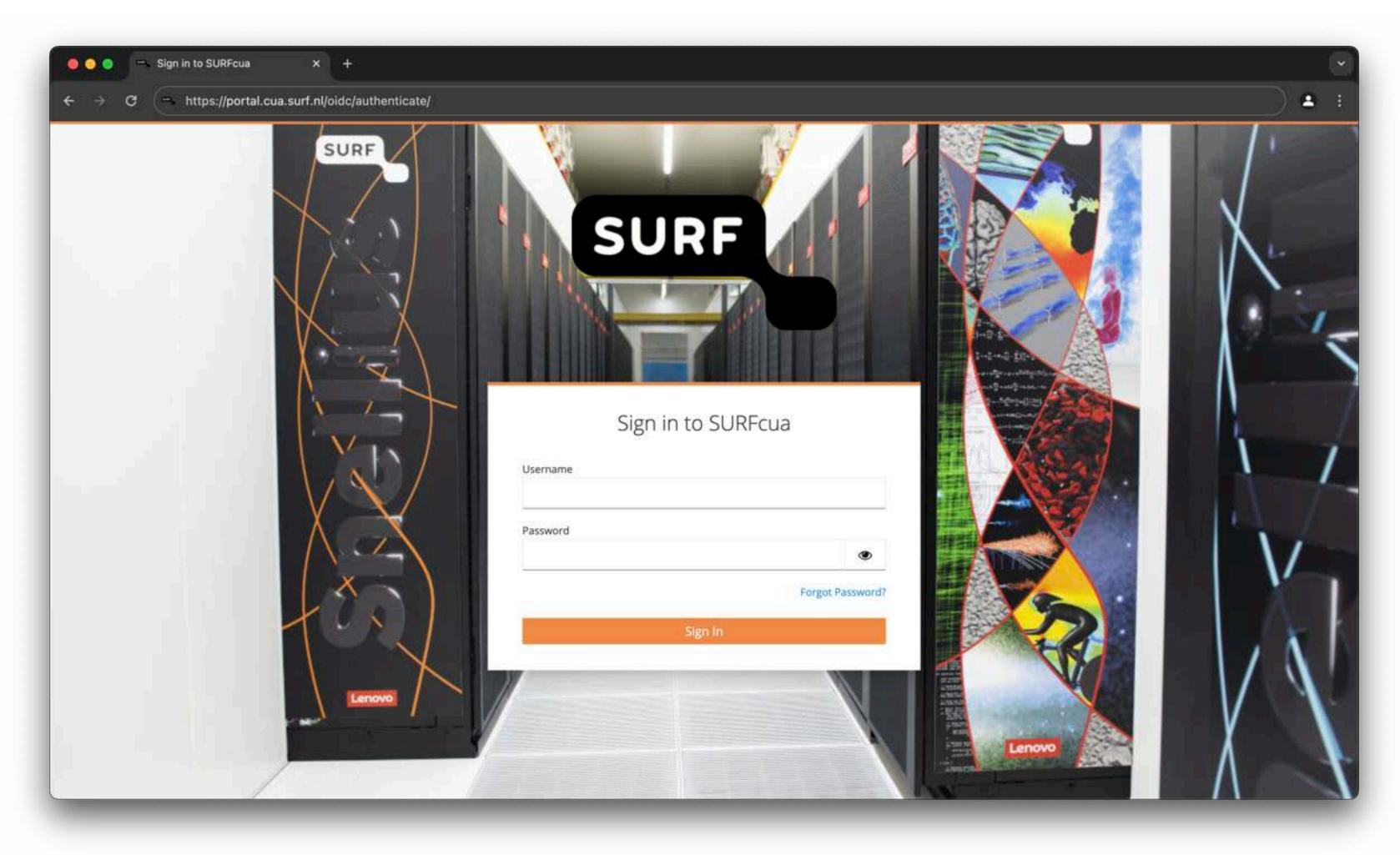
```
int main(int argc, char** argv) {
    // Initialize the MPI environment
   MPI_Init(&argc, &argv);
    // Get the number of processes
    int world_size;
    MPI_Comm_size(MPI_COMM_WORLD, &world_size);
    // Get the rank of the process
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    // Get the name of the processor
    char processor_name[MPI_MAX_PROCESSOR_NAME];
    int name_len;
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    printf("Hello world from processor %s, "
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   MPI_Finalize();
```

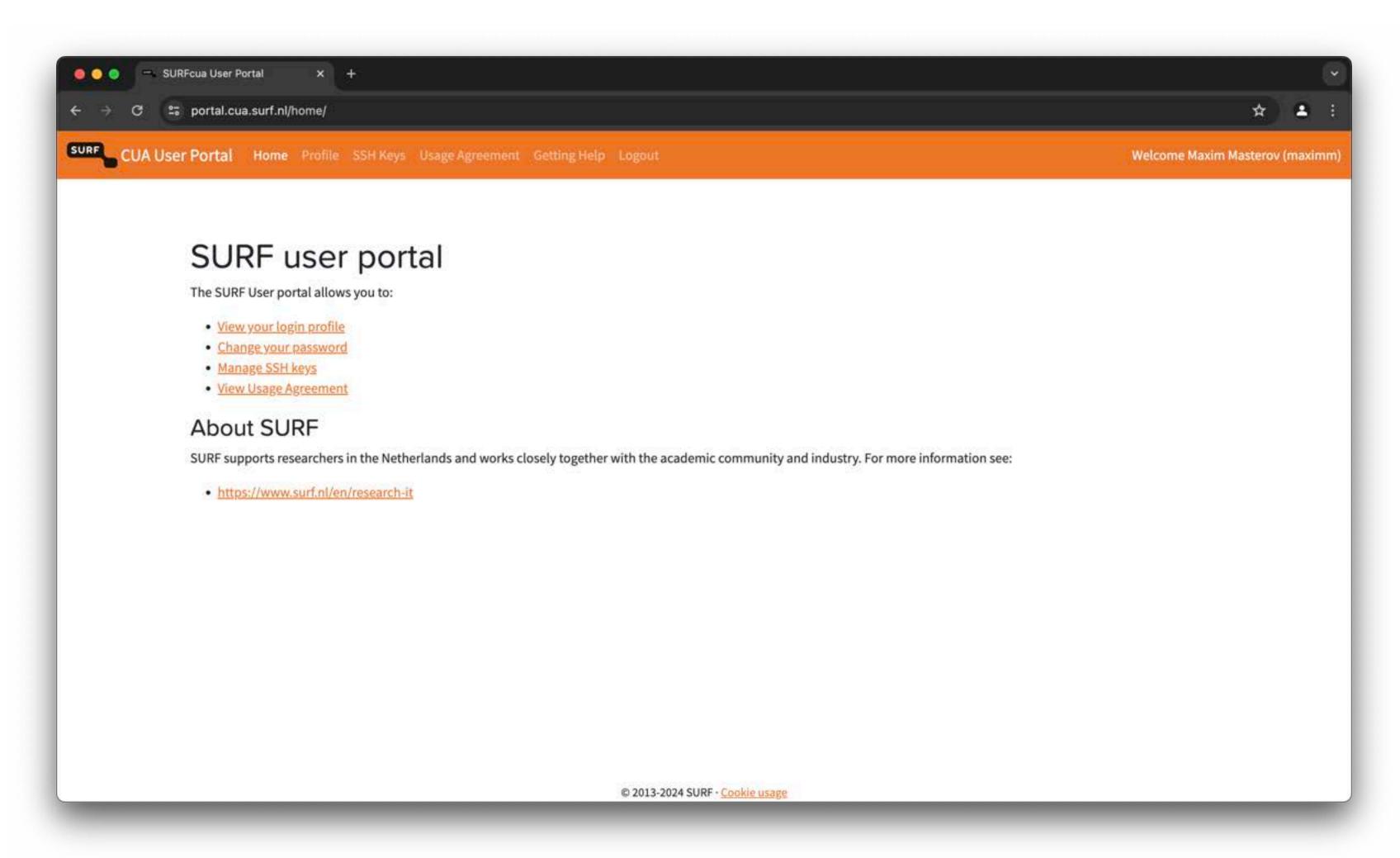
```
#include <cmath>
#include <mpi.h>
#include <stdio.h>
class MPIManager {
    MPI_Comm comm;
public:
    MPIManager1() : comm(MPI_COMM_WORLD) { }
    void initialize(int argc, char** argv) { ... }
    void finalize() { ... }
    char *getProcName() { ... }
    int getMyRank() { ... }
    int getNumProcs() { ... }
};
int main(int argc, char** argv) {
    MPIManager mpi_manager;
    // Initialize the MPI environment
    mpi_manager.initialize(argc, argv);
    // Print off a hello world message
    printf("Hello world from processor %s, "
           "rank %d out of %d processes\n",
           mpi_manager.getProcName(),
           mpi_manager.getMyRank(),
           mpi_manager.getNumProcs());
    // Finalize the MPI environment.
    mpi_manager.finalize();
```

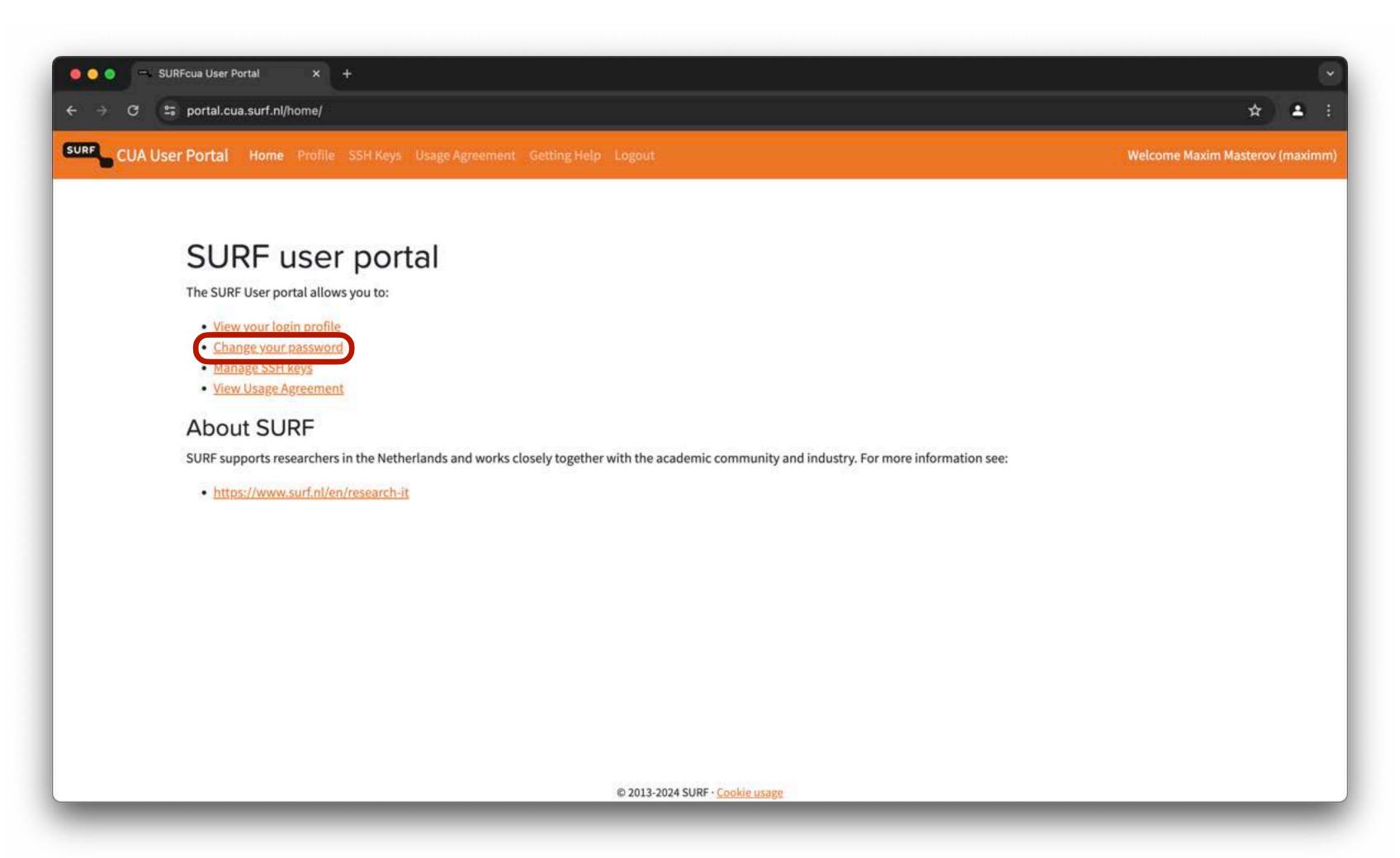
Connecting to Snellius

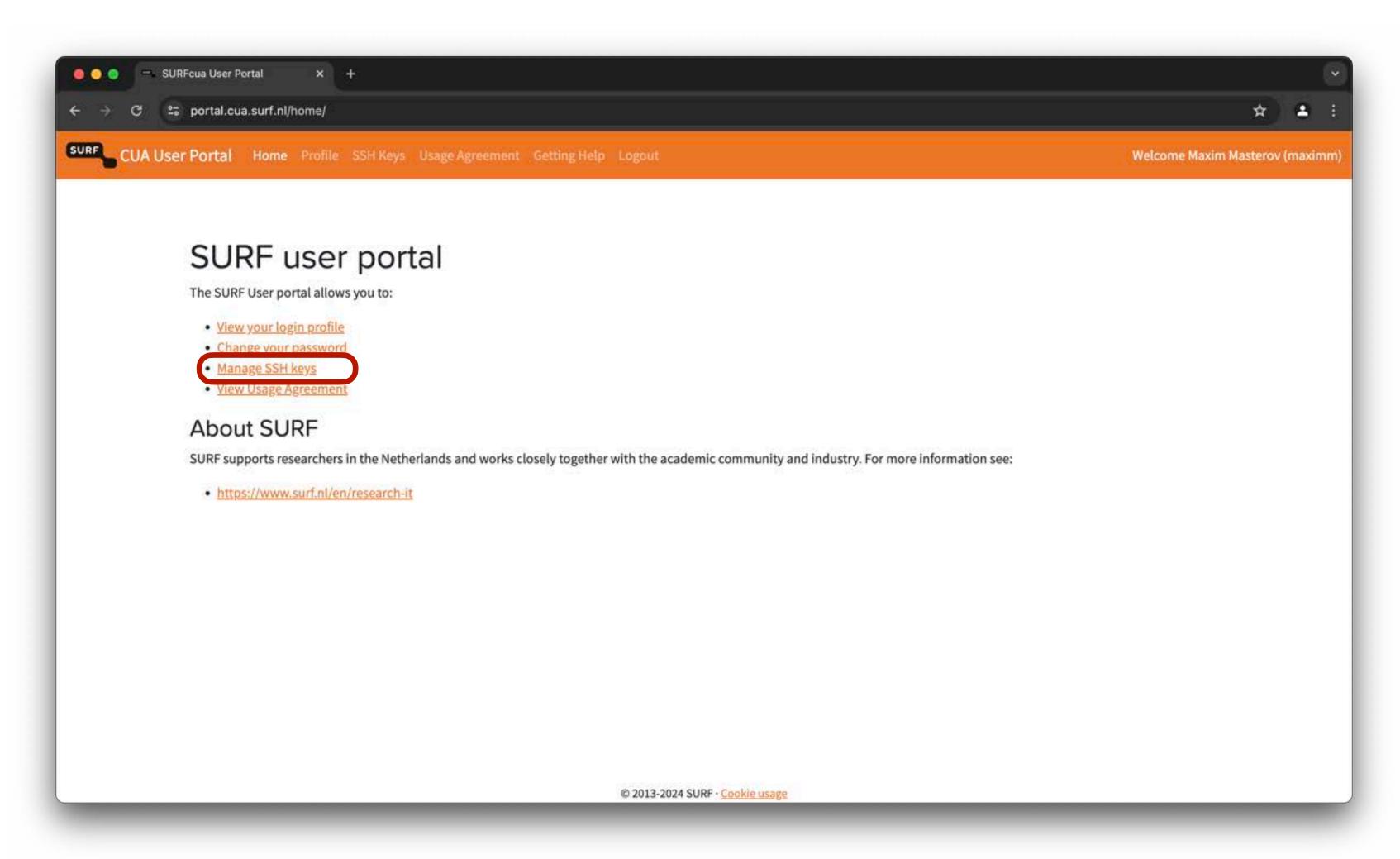
Snellius Connecting to

- Windows OS:
 - MobaXterm: https://mobaxterm.mobatek.net/
 (download potable edition)
 - Putty
- macOS and Linux OS:
 - You are already well equipped
- Domain name: snellius.surf.nl
- Use -X or -Y flag in the ssh command to allow X11 forwarding (for visualisation)
 - macOS users should install XQuartz: (https://www.xquartz.org/)



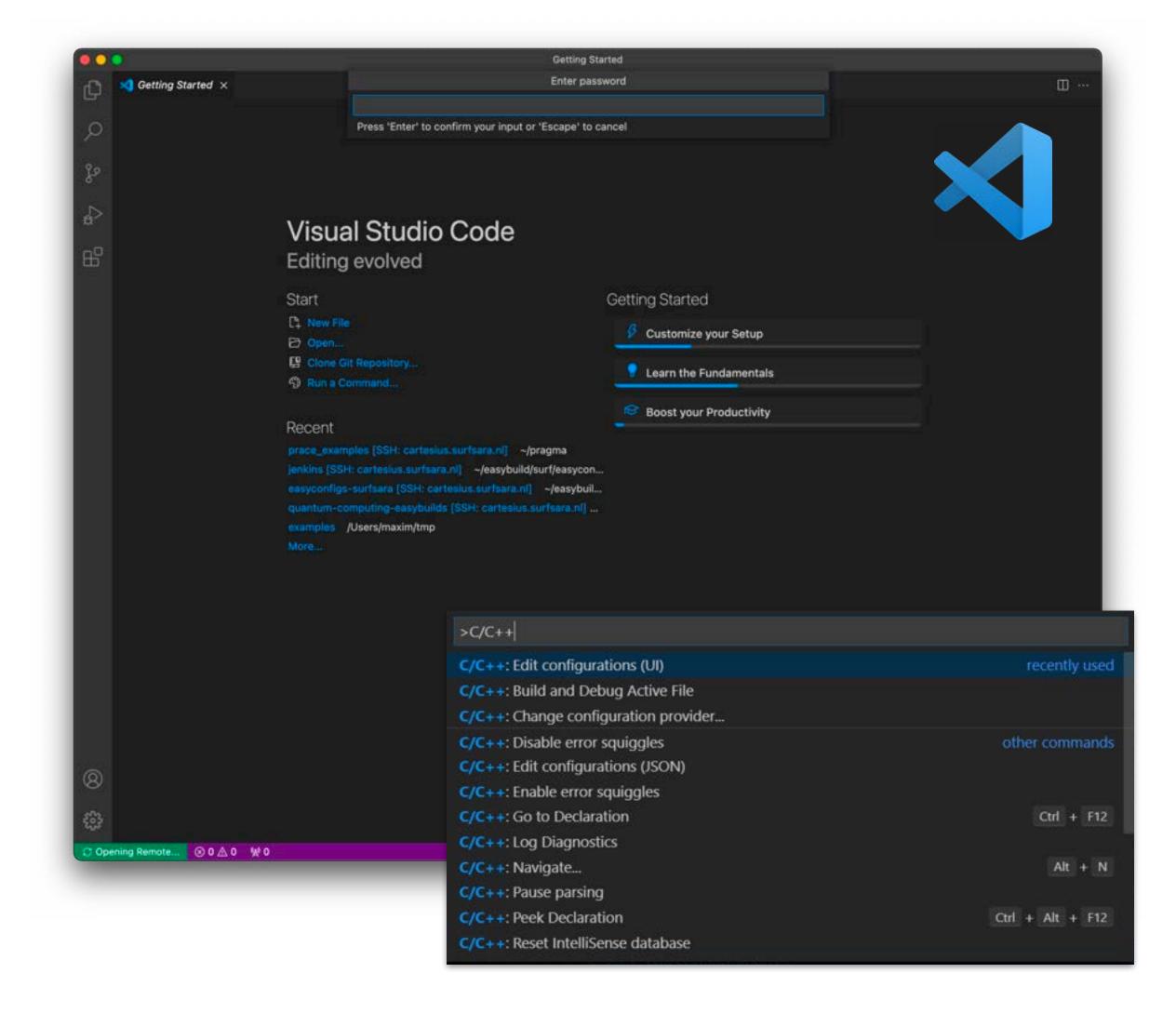






Snellius VS Code (recommendation)

- Download VS Code from
 - https://code.visualstudio.com
- Install plugins
 - Locally: Remote SSH
 - Remotely: C/C++ Extension Pack
- Press F1 and run the Remote-SSH: Open SSH Host...
 command
- Or use any other IDE (or text editor) with support for the remote development (CLion, Eclipse, Atom, ...)
- Some help: https://servicedesk.surf.nl/wiki/display/WIKI/
 Visual+Studio+Code+for+remote+development



Jacobi Solver

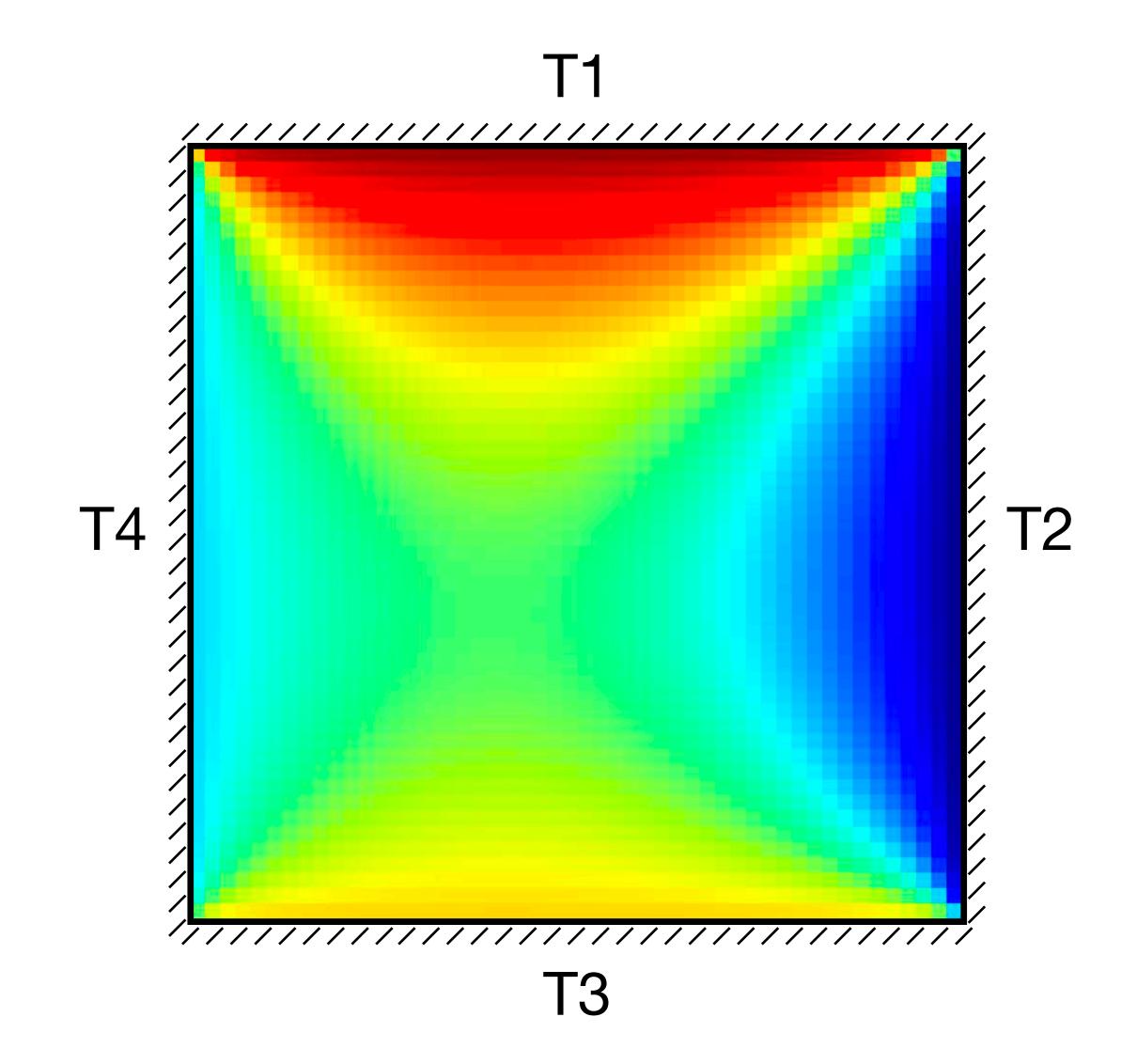
Heat transfer

The problem

- Consider a basic steady state conduction in a closed box
- No sources are present
- All walls have constant temperature

The governing equation:

$$\Delta T = 0 \qquad \frac{\partial^2 T}{\partial x^2} + \frac{\partial^2 T}{\partial y^2} = 0$$



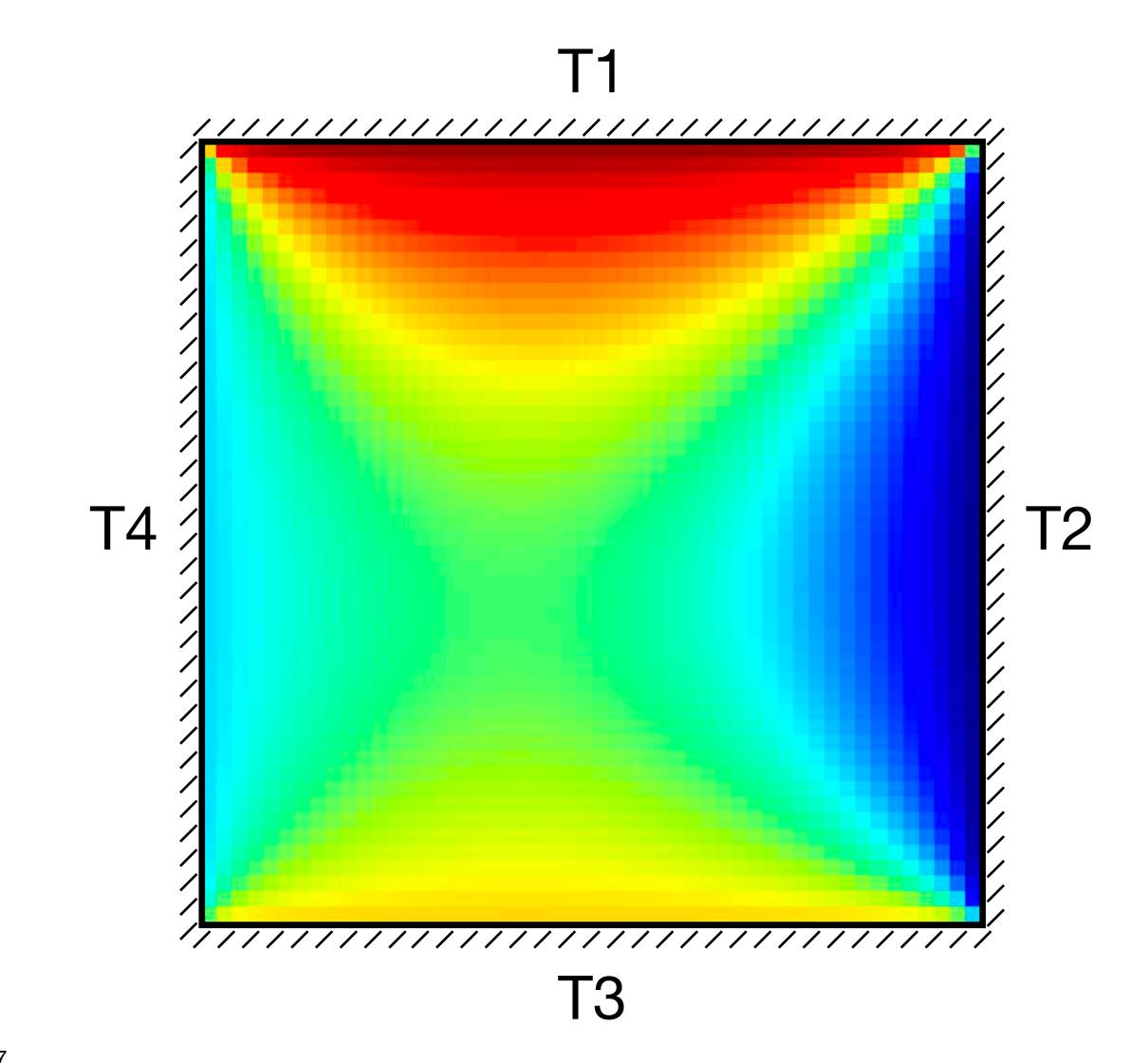
The problem

• The governing equation:

$$\Delta T = 0 \qquad \frac{\partial^2 T}{\partial x^2} + \frac{\partial^2 T}{\partial y^2} = 0$$

 All derivatives are approximated with the 2ndorder central difference scheme:

$$\frac{\partial^2 T}{\partial x^2} \approx \frac{T_{i+1,j} - 2T_{i,j} + T_{i-1,j}}{\delta x^2}$$

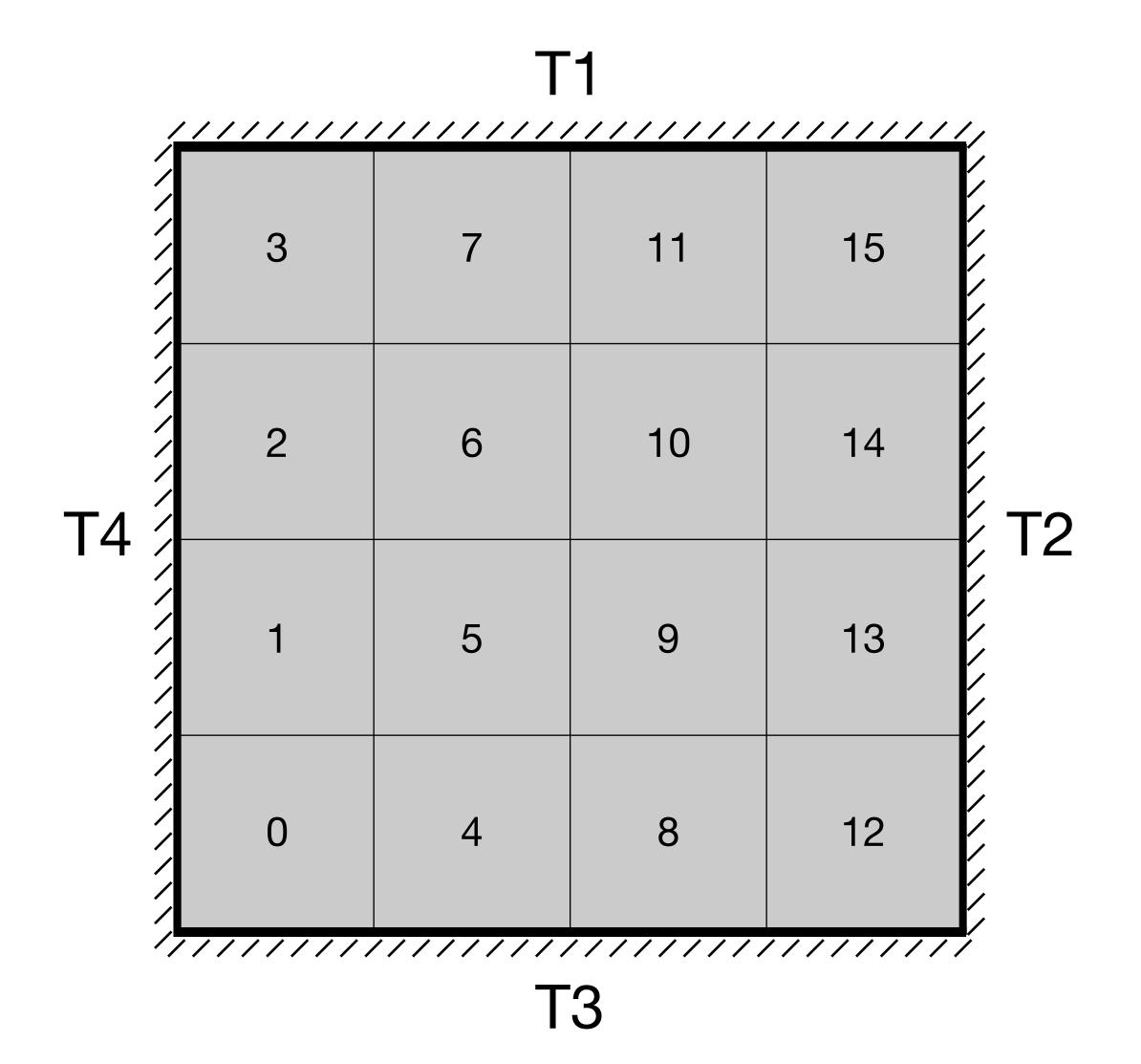


The problem

 All derivatives are approximated with the 2ndorder central difference scheme:

$$\frac{\partial^2 T}{\partial x^2} \approx \frac{T_{i+1,j} - 2T_{i,j} + T_{i-1,j}}{\delta x^2}$$

$$\frac{\partial^2 T}{\partial y^2} \approx \frac{T_{i,j+1} - 2T_{i,j} + T_{i,j-1}}{\delta y^2}$$

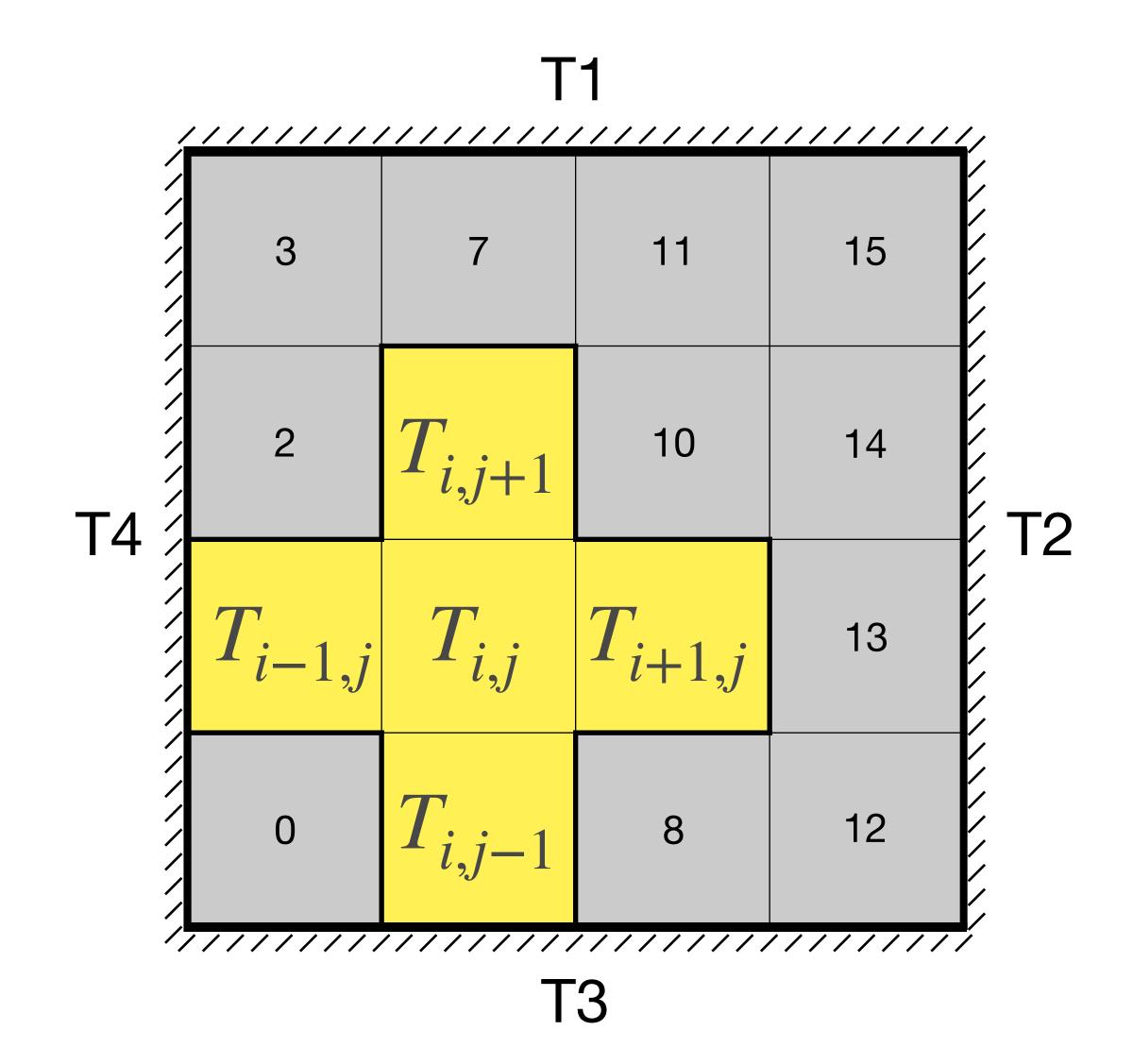


The problem

 All derivatives are approximated with the 2ndorder central difference scheme:

$$\frac{\partial^2 T}{\partial x^2} \approx \frac{T_{i+1,j} - 2T_{i,j} + T_{i-1,j}}{\delta x^2}$$

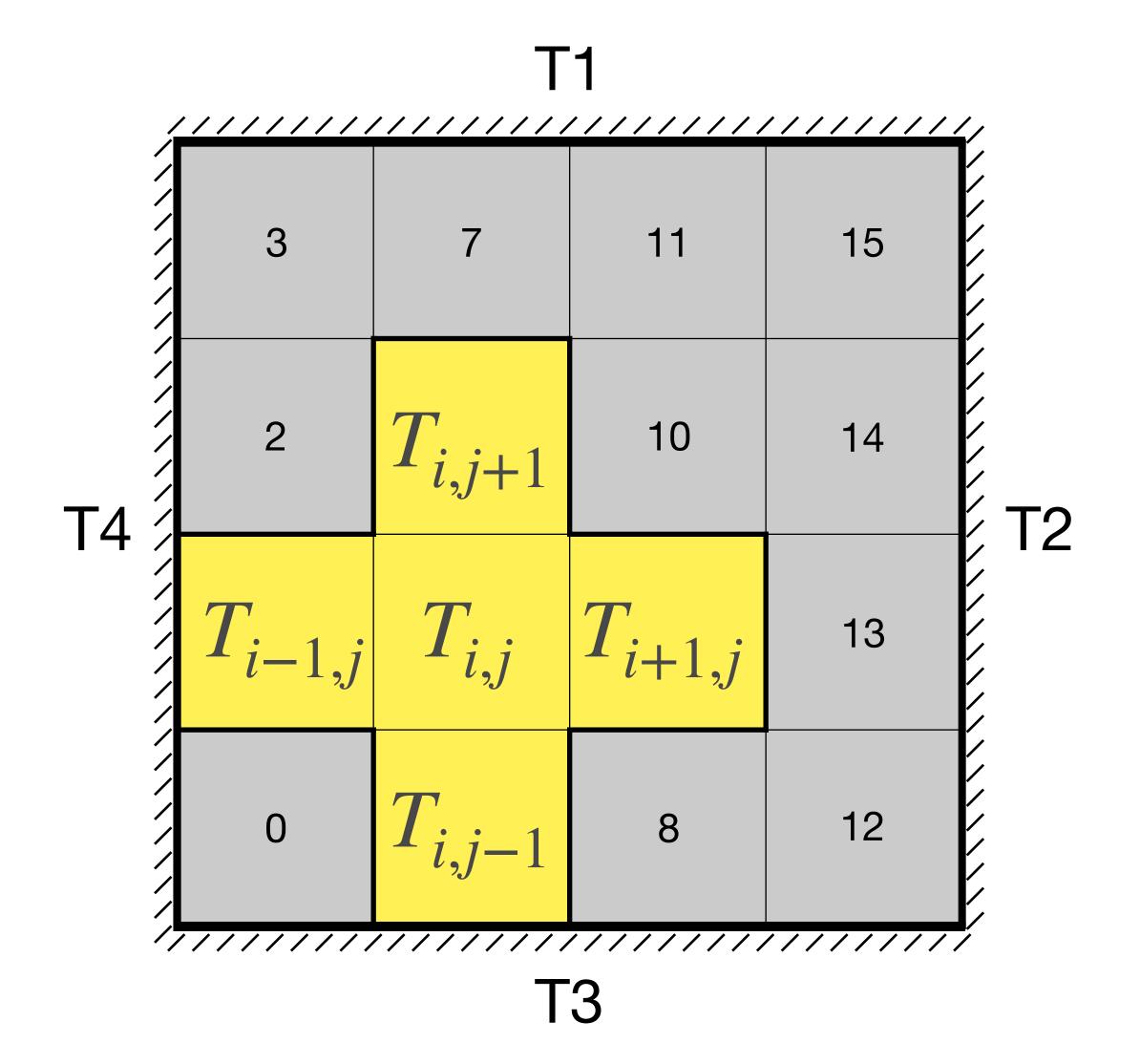
$$\frac{\partial^2 T}{\partial y^2} \approx \frac{T_{i,j+1} - 2T_{i,j} + T_{i,j-1}}{\delta y^2}$$



The problem

We need to solve the following system of linear equations:

$$\frac{T_{i+1,j} - 2T_{i,j} + T_{i-1,j}}{\delta x^2} + \frac{T_{i,j+1} - 2T_{i,j} + T_{i,j-1}}{\delta y^2} = 0$$



The problem

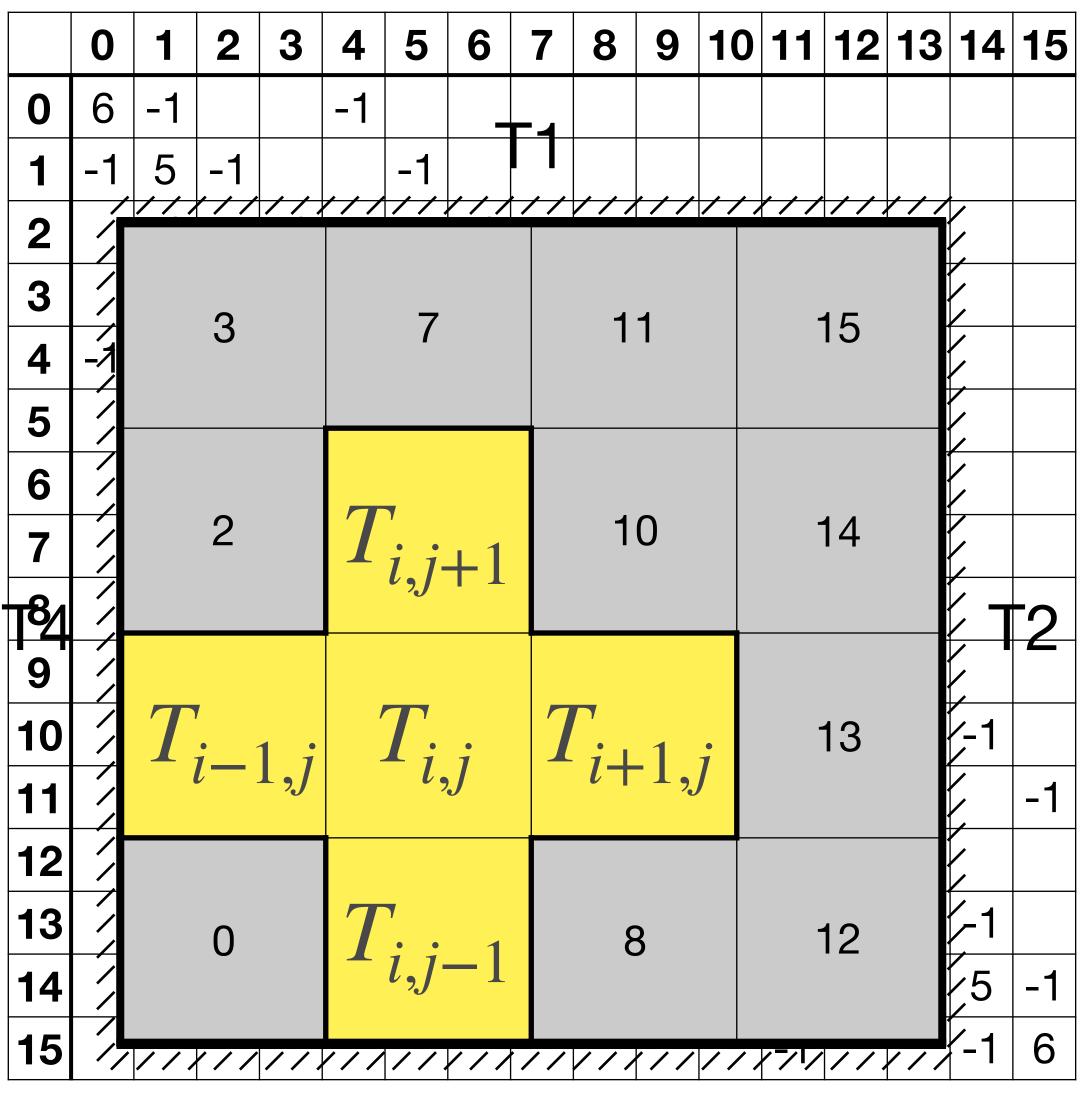
Assume unit grid cells:

$$4T_{i,j} - T_{i+1,j} - T_{i-1,j}$$
$$-T_{i,j+1} - T_{i,j-1} = 0$$

• Boundary conditions (linear interpolation):

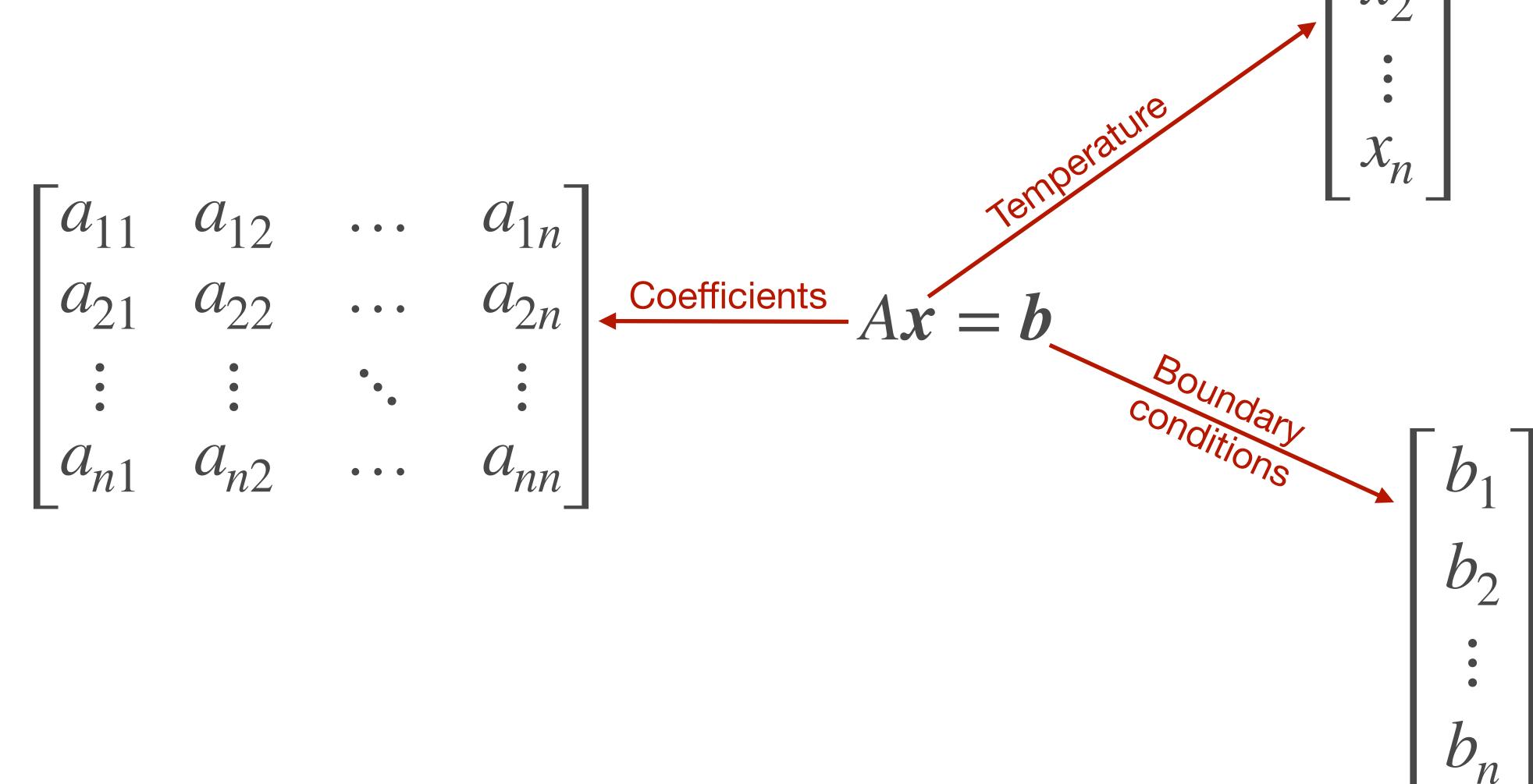
$$T_{i-1,j} = 2T_w - T_{i,j}$$

Matrix representation

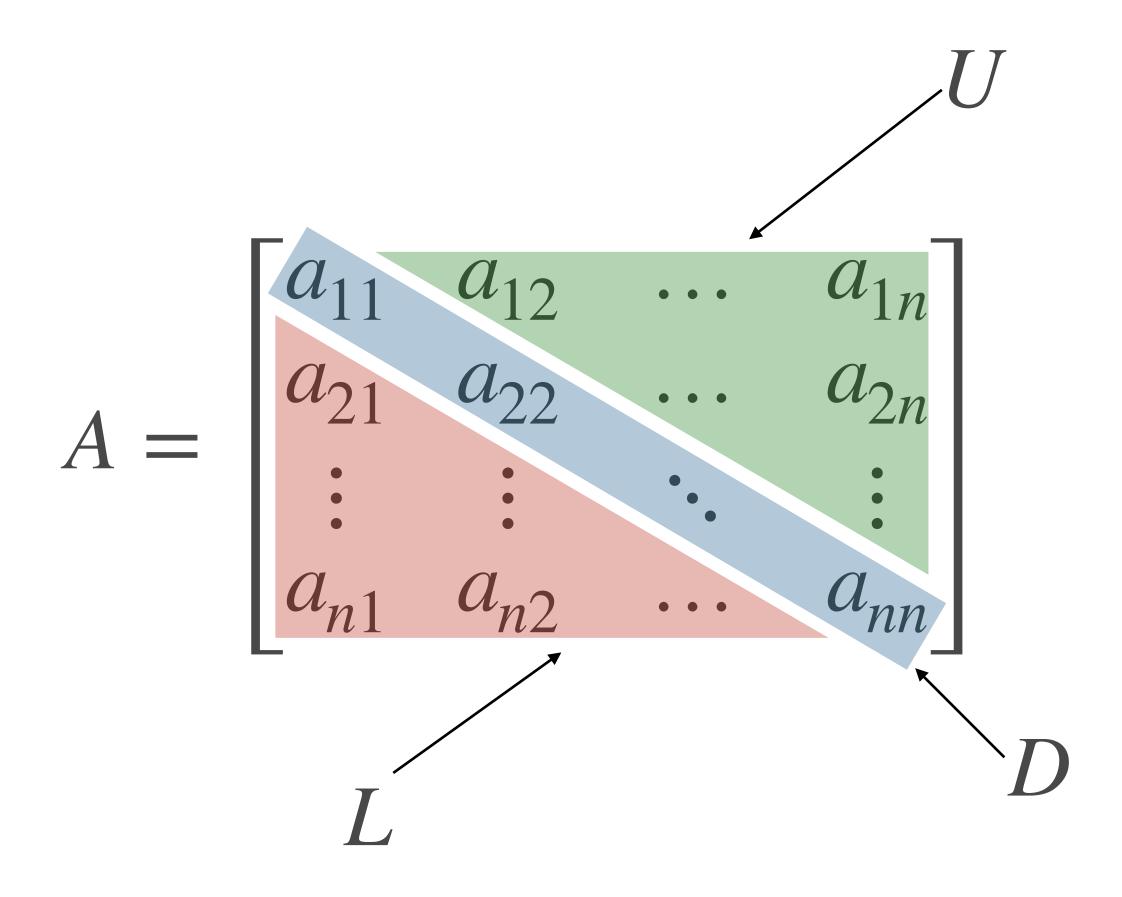


T3

Weighted Jacobi method



Weighted Jacobi method



$$A = D + L + U$$

$$x^{(k+1)} = \omega D^{-1}(b - (L + U)x^{(k)})$$

$$+ (1 - \omega)x^{(k)}$$

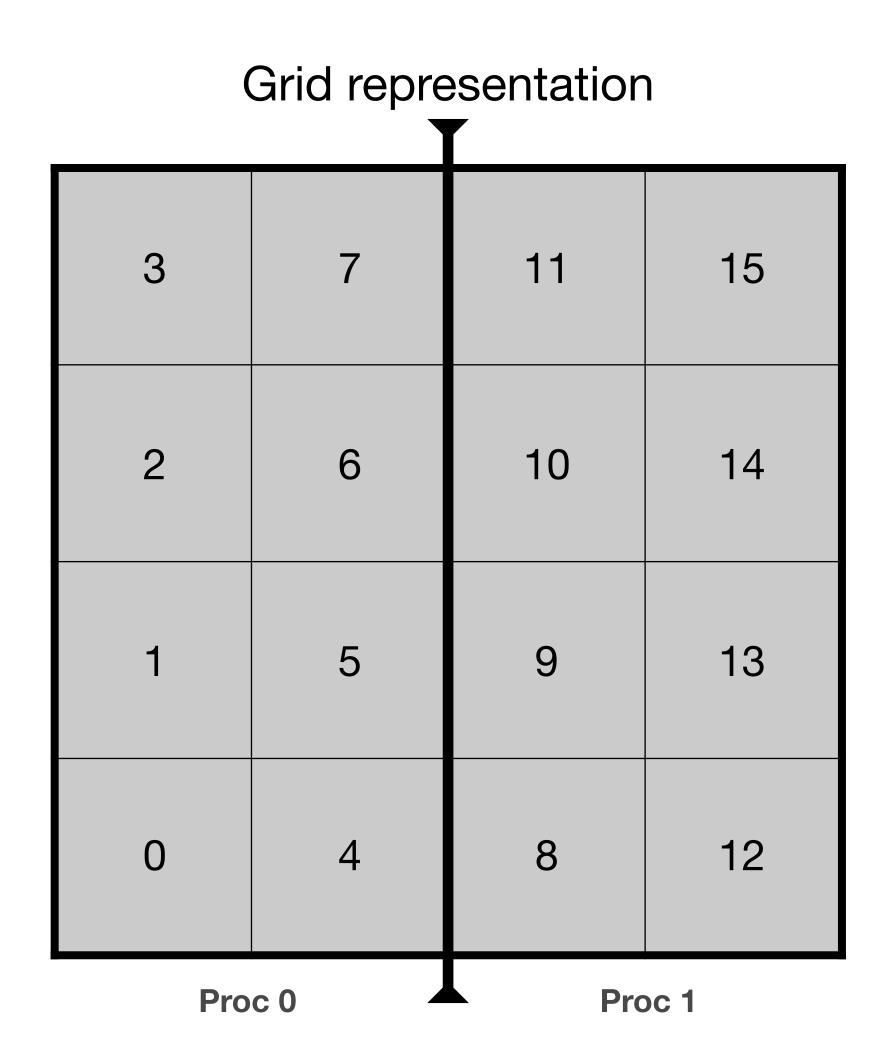
$$x_i^{(k+1)} = \omega \frac{1}{a_{ii}}(b_i - \sum_{j \neq i} a_{ij}x_j^{(k)})$$

$$+ (1 - \omega)x_i^{(k)}$$

Why weighted Jacobi method?

- Simple implementation
- Has simple but frequently used mathematical operations:
 - L2-norm
 - MVP
 - Vector update (copy)
- Simple parallelisation
- Straightforward hybrid parallelisation
- Often used as a supplement to more advanced linear solvers (e.g. as a smoother in AMG)

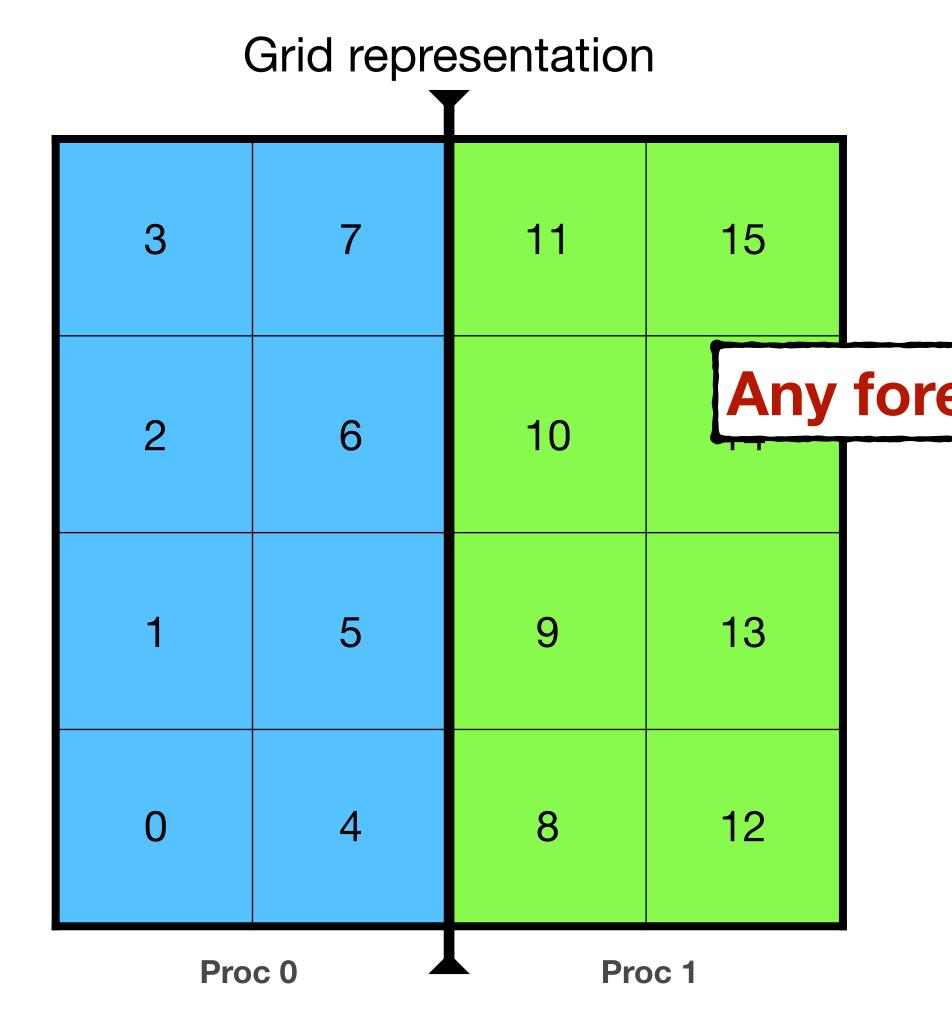
Data representation



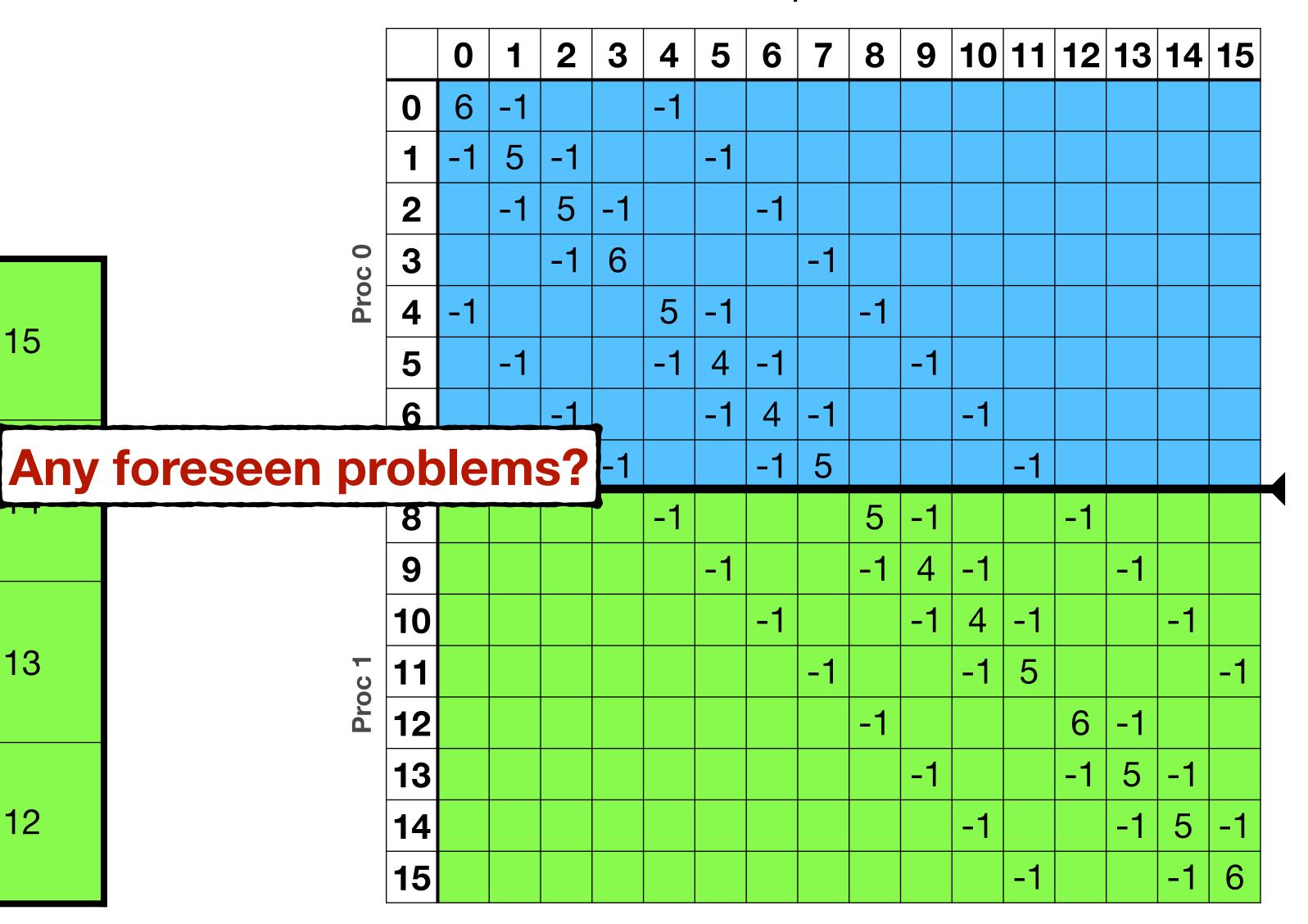
Matrix representation

		0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
			_					0			3	10	• •	12	10	17	10
	0	6	-1			-1											
	1	-1	5	-1			-1										
	2		-1	5	-1			-1									
Proc 0	3			-1	6				-1								
Pro	4	-1				5	-1			-1							
	5		-1			-1	4	-1			-1						
	6			-1			-1	4	-1			-1					
	7				-1			-1	5				-1				
	8					-1				5	-1			-1			
	9						-1			-1	4	-1			-1		
	10							-1			-1	4	-1			-1	
c 1	11								-1			-1	5				-1
Proc	12									-1				6	-1		
	13										-1			-1	5	-1	
	14											-1			-1	5	-1
	15												-1			-1	6

Data representation



Matrix representation



MVP

Data representation

		0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
	0	6	7			7											
	1	-1	5	-1			-1										
0	2		-1	5	-1			-1									
Proc	3			-1	6				-1								
△	4	-1				5	-1			-1							
	5		-1			-1	4	-1			-1						
	6			-1			-1	4	-1			-1					
	7				1			-1	5				-1				
	8					-1				5	-1			-1			
	9						-1			-1	4	-1			-1		
_	10							-1			-1	4	-1			-1	
Proc	11								-1			-1	5				-1
<u>.</u>	12									-1				6	-1		
	13										-1			-1	5	-1	
	14											-1			-1	5	-1
	15												-1			-1	6

x0		y0
x1		y1
x2		y2
хЗ		у3
x4		y4
x5		у5
х6		y6
x7		y7
x8	=	y8
x9		у9
x10		y10
x11		y11
x12		y12
x13		y13
x14		y14
x15		y15

$$y_i = \sum_{j=0}^{N} a_{ij} x_j$$

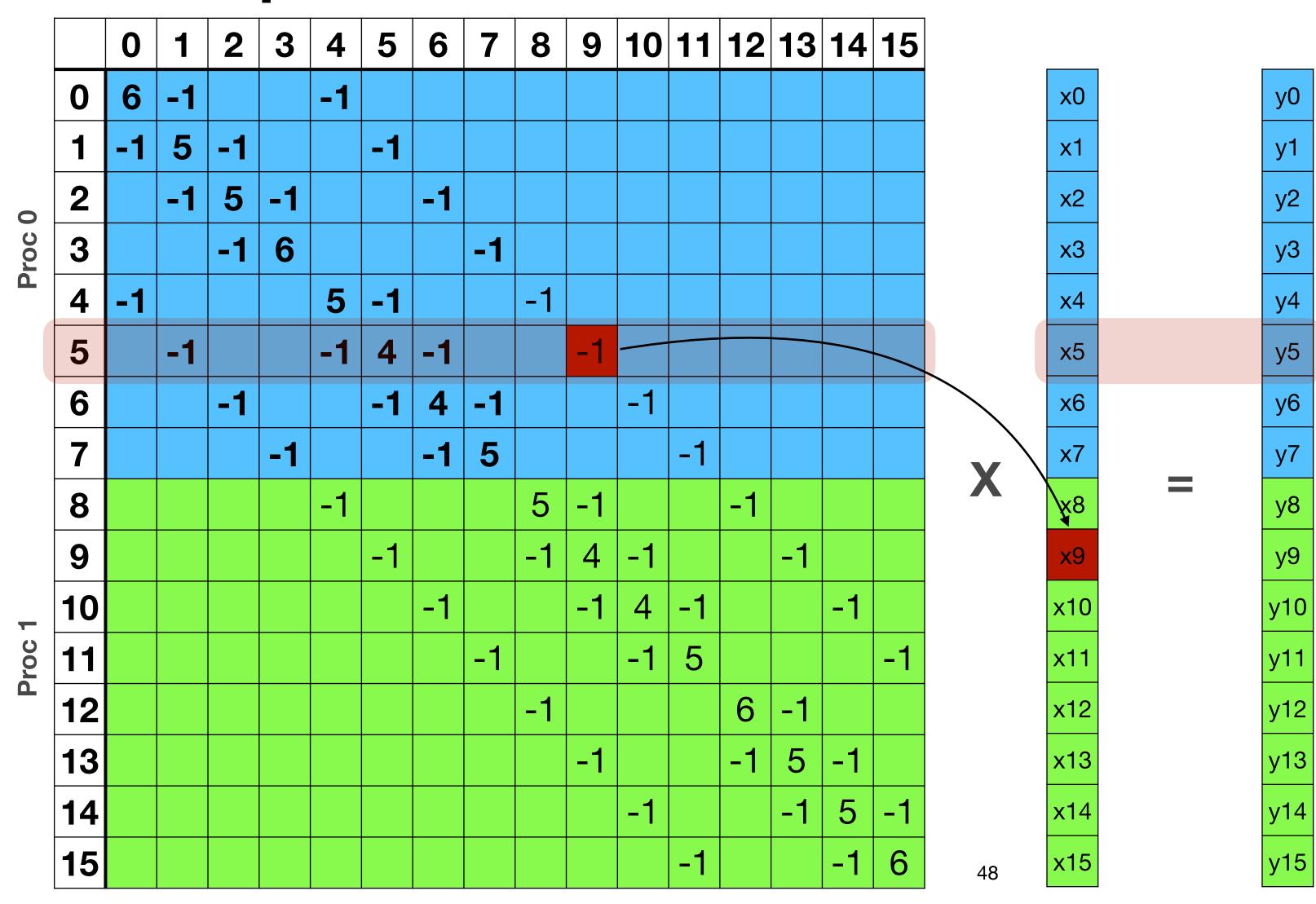
$$y_5 = a_{51}x_1 + a_{54}x_4$$

$$+a_{55}x_5 + a_{56}x_6$$

$$+a_{59}x_9$$

MVP

Data representation



We need access to the value from the neighbouring process!

$$y_i = \sum_{j=0}^{N} a_{ij} x_j$$

$$y_5 = a_{51}x_1 + a_{54}x_4$$

$$+a_{55}x_5 + a_{56}x_6$$

$$+a_{59}x_9$$

Data representation

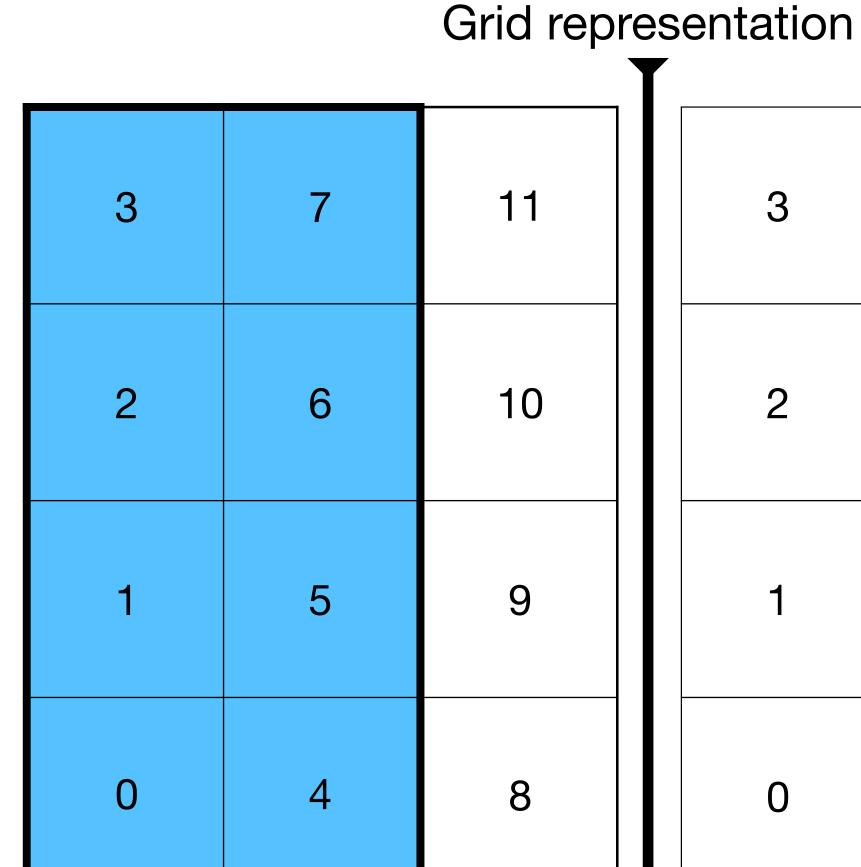
Grid representation

3	7	11	3	7	11
		1 1			
2	6	10	2	6	10
1	5	9	1	5	9
0	4	8	0	4	8
Pro	oc 0	H	lalo cells	Pro	c 1

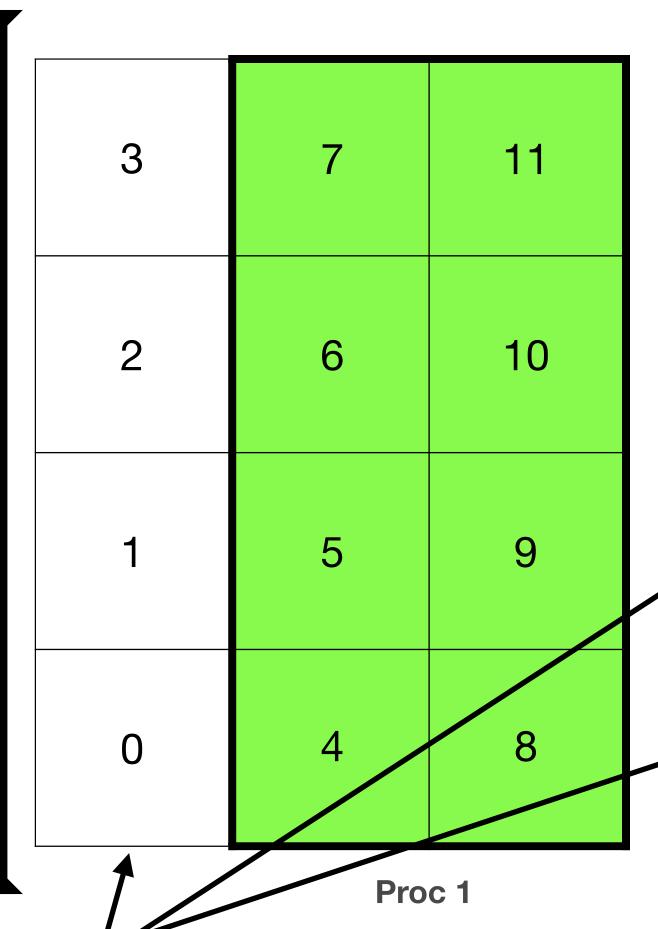
Matrix representation

		0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
	0	6	-1			-1											
	1	-1	5	-1			-1										
	2		-1	5	-1			-1									
000	3			-1	6				-1								
Proc	4	-1				5	-1			-1							
	5		-1			-1	4	-1			-1						
	6			-1			-1	4	-1			-1					
	7				-1			-1	5				-1				
	8					-1				5	-1			-1			
	9						-1			-1	4	-1			-1		
	10							-1			-1	4	-1			-1	
c 1	11								-1			-1	5				-1
Proc	12									-1				6	-1		
	13										-1			-1	5	-1	
	14											-1			-1	5	-1
	15												-1			-1	6

Data representation



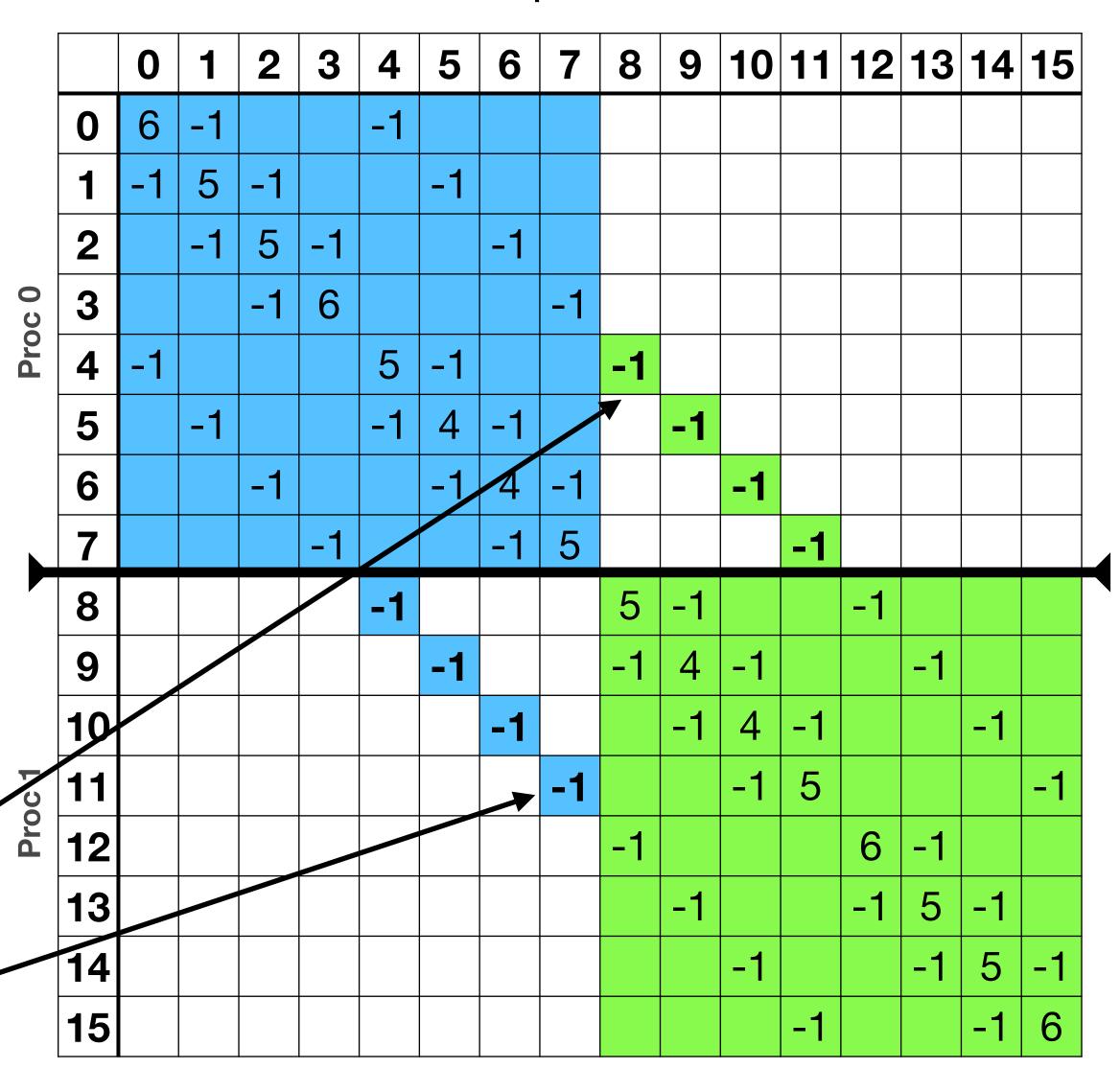
Proc 0



Halo cells

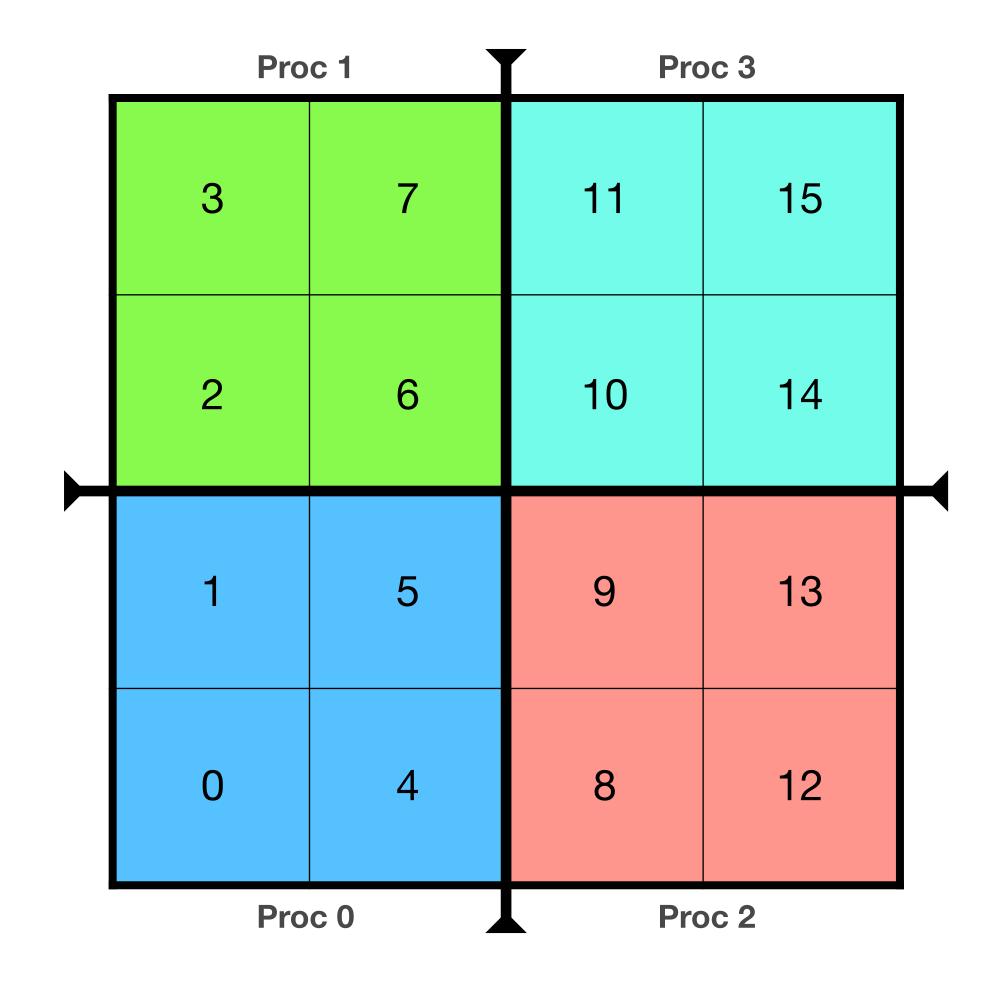
50

Matrix representation

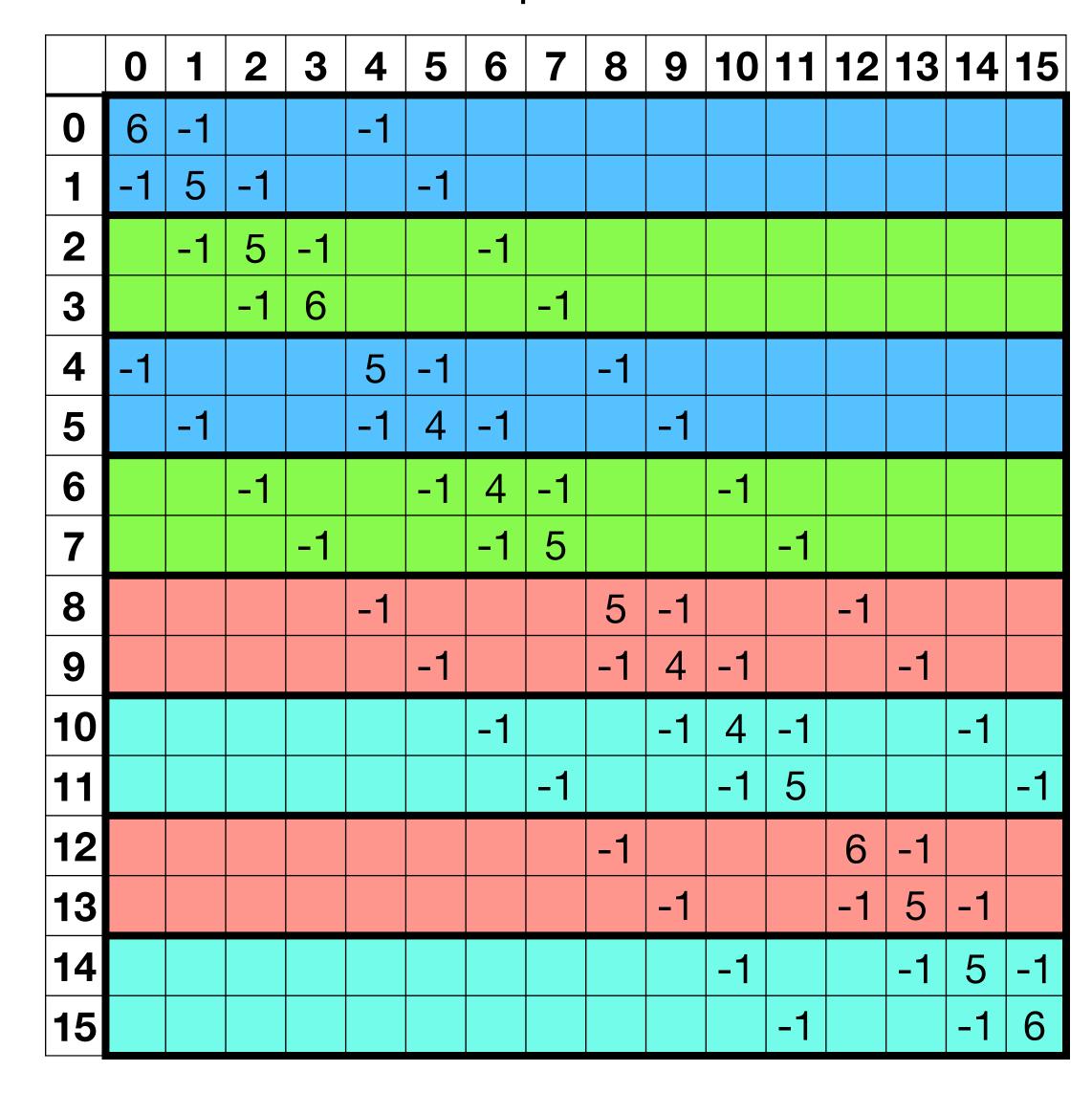


No problems so far!

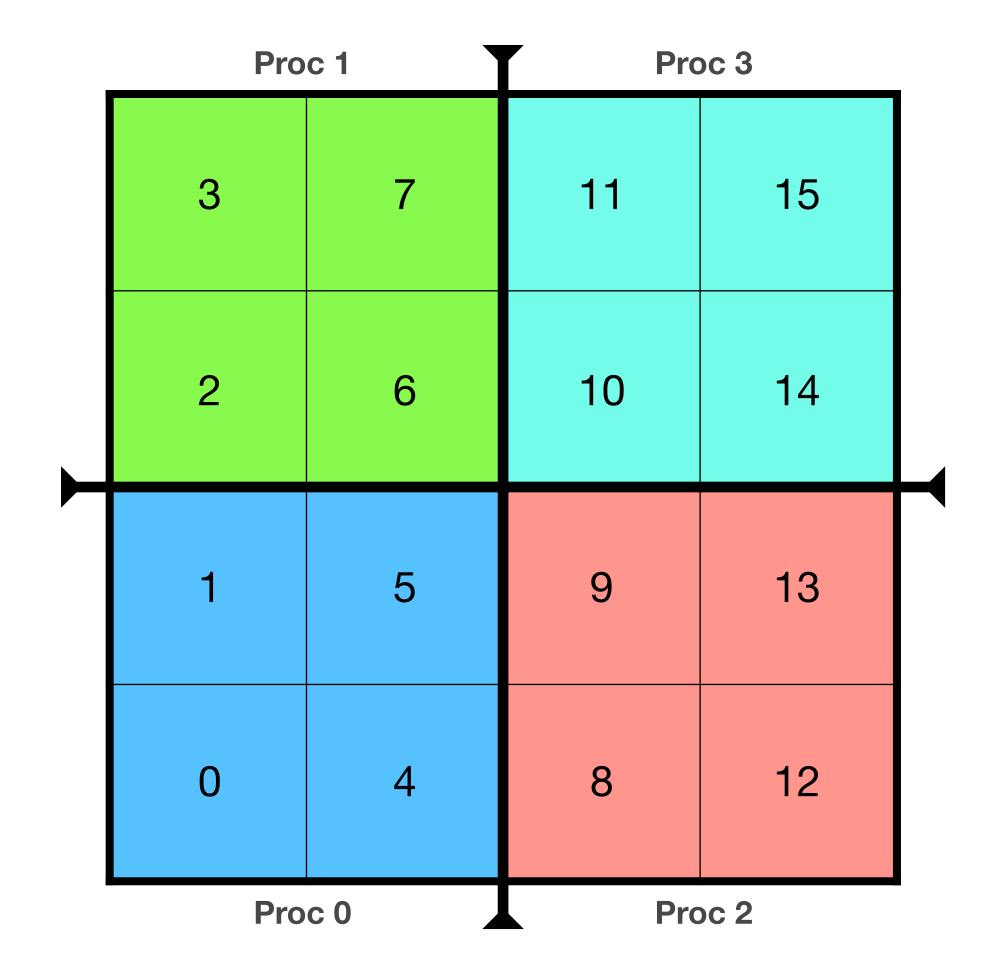
Data representation



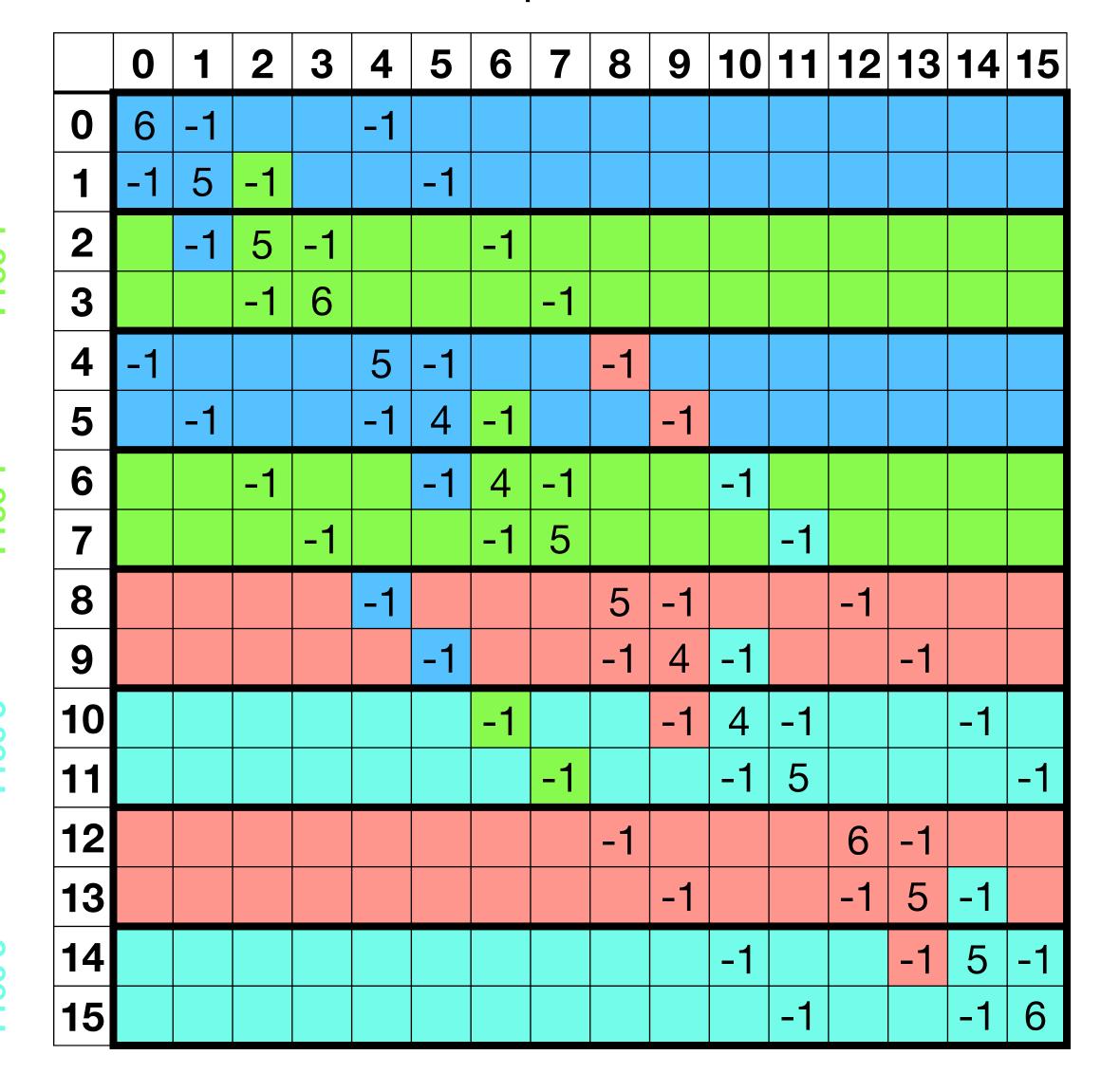
Matrix representation



Data representation



Matrix representation



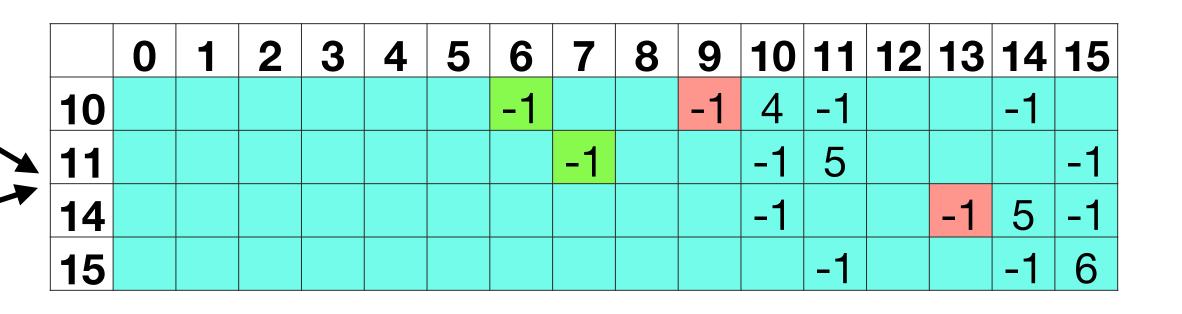
Data representation

0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	
6	-1			-1												
-1	5	-1			-1											
	-1	5	-1			-1										
		-1	6				-1									
-1				5	-1			-1								
	-1			-1	4	-1			-1							
		-1			-1	4	-1			-1						/
			-1			-1	5				1					
				-1				5	-1			-1				
					-1			۲-	4	-1			1			
						-1			-1	4	-1			-1		
							-1			-1	5				-1	
								-1				6	-1			
									-1			-1	5	1		
										-1			-1	5	-1	
											-1			-1	6	
	6 -1	6 -1 -1 5 -1 -1	6 -1 -1 -1 -1 -1 -1 -1 -1 -1	6 -1	6 -1 -1 -1 -1 -1 -1 -1 5 -1 -1 6 -1 -1 -1 -1 -1 -1 -1 -1 -1 -1 -1 -1 -1	6 -1 -1 -1 -1 -1 -1 -1 -1 -1 -1 -1 -1 -1	6 -1 -1 -1 -1 5 -1 -1 -1 5 -1 -1 -1 6 -1 -1 -1 -1 -1 4 -1 -1 -1 -1 -1 4 -1 -1 -1 -1 -1 -1 -1 -1 -1 -1	6 -1 -1 -1 -1 -1 5 -1 -1 -1 -1 5 -1 -1 -1 -1 6 -1 -1 -1 -1 -1 4 -1 -1 -1 -1 4 -1 -1 -1 -1 5 -1 -1 -1 5 -1 -1 -1 5 -1 -1 -1 5	6 -1	6 -1	6 -1	6 -1	6 -1	6 -1	6 -1	6 -1

	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
0	6	-1			-1											
1	-1	5	-1			-1										
4	-1				5	-1			-1							
5		-1			-1	4	-1			-1						

	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
2		-1	5	-1			-1									
3			-1	6				-1								
6			-1			-1	4	-1			-1					
7				-1			-1	5				-1				

	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
8					-1				5	-1			-1			
9						-1			-1	4	-1			-1		
12									-1				6	-1		
13										-1			-1	5	-1	



53

Data representation



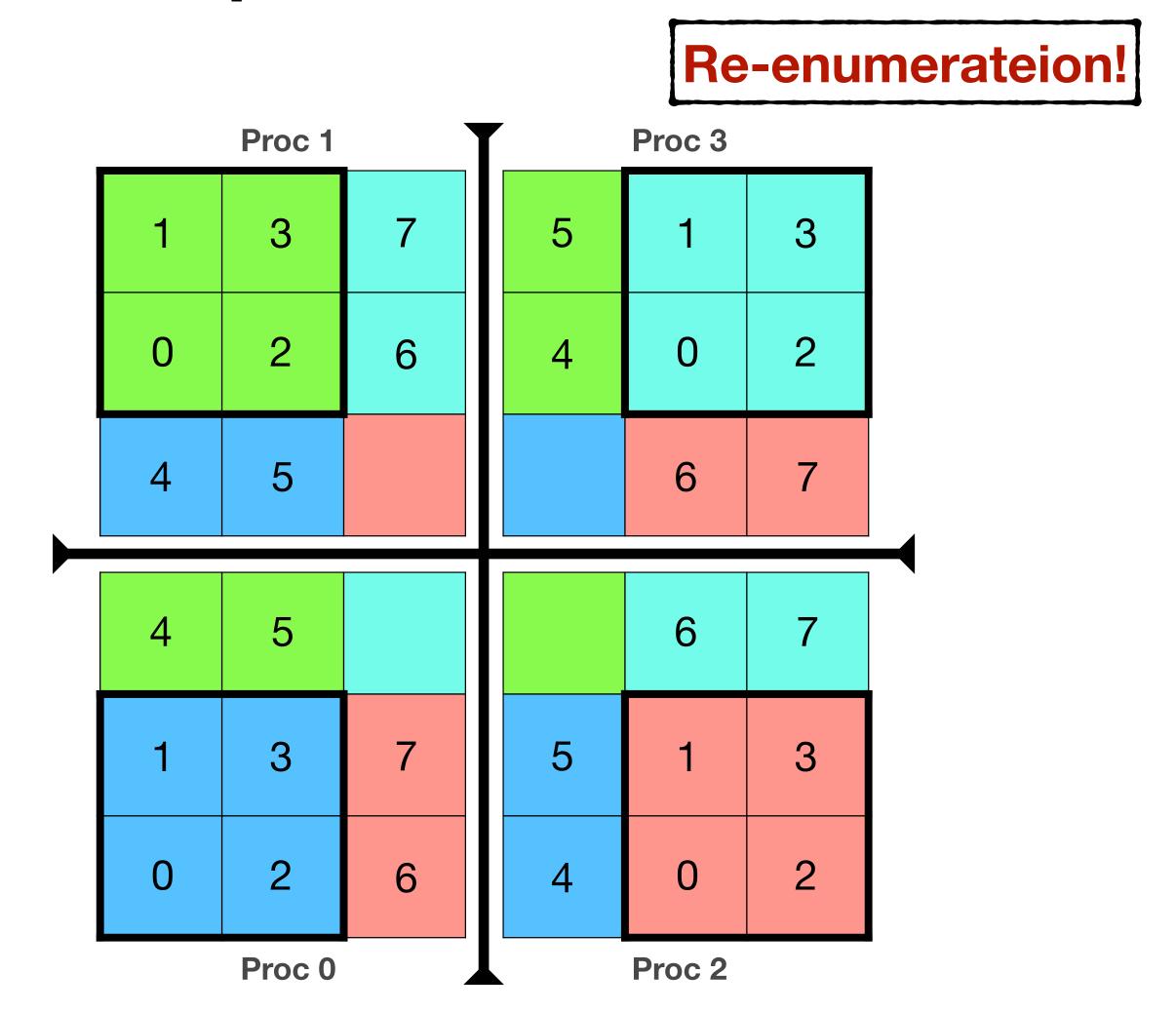
	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
0	6	-1		-1												
1	-1	5	-1		-1											
2	-1			5	-1		-1									
3		-1		-1	4	-1		-1								

	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
0	-1	5	-1		-1											
1		-1	6			1										
2		-1		-1	4	-1		-1								
3			-1		-1	5			-1							

	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
0	-1			5	-1		-1									
1		1		-1	4	۲-		-1								
2				-1			6	-1								
3					-1		-1	5	-1							

	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
0		-1		-1	4	1		-1								
1			-1		-1	5			-1							
2					-1		-1	5	1							
3						-1		-1	6							

Data representation



	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
0	6	-1	-1													
1	-1	5		1	1											
2	-1		5	1			-1									
3		-1	-1	4		-1		-1								

	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
0	5	-1	-1		-1											
1	-1	6		-1												
2	-1		4	-1		-1	-1									
3		-1	-1	5				-1								

	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
0	5	-1	-1		-1											
1	-1	4		-1		-1	-1									
2	-1		6	-1												
3		-1	-1	5				-1								

	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
0	4	-1	-1		-1		-1									
1	1	5		-1		-1										
2	٦		5	-1				1								
3		-1	-1	6												

Data representation

Optimised storage!

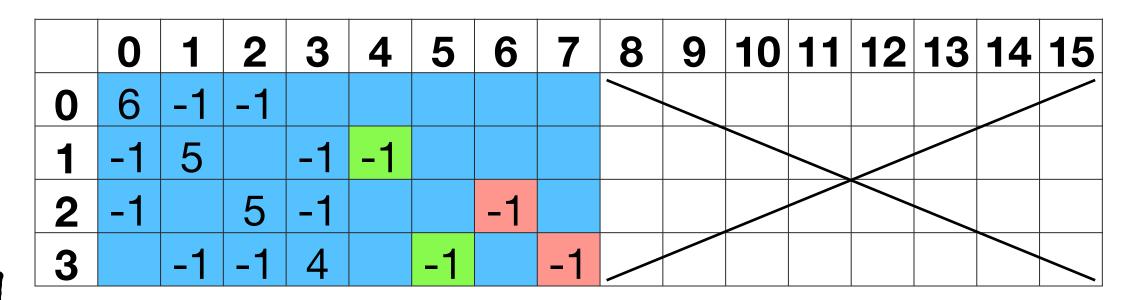
Memory reduction (~2x):

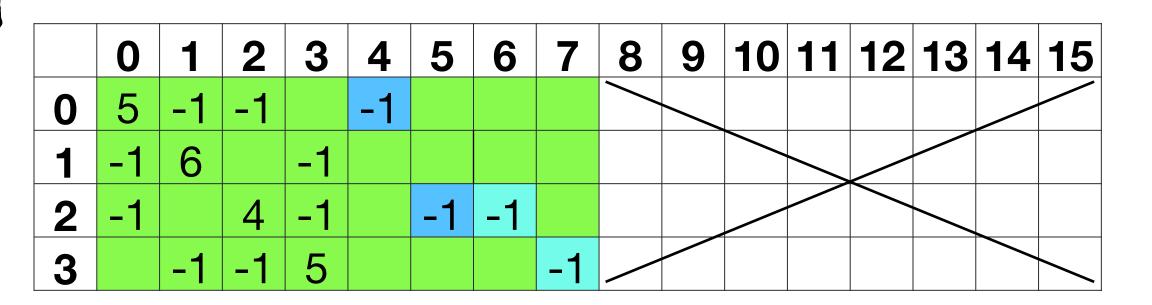
- Regular storage: $N_{loc} \times N_{glob}$
- Modified storage: $N_{loc} \times (N_{loc} + N_{halo})$

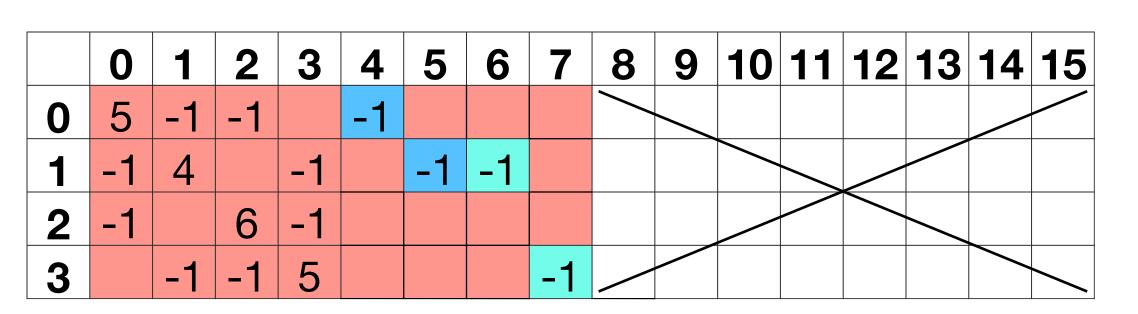
Easier access to halo values

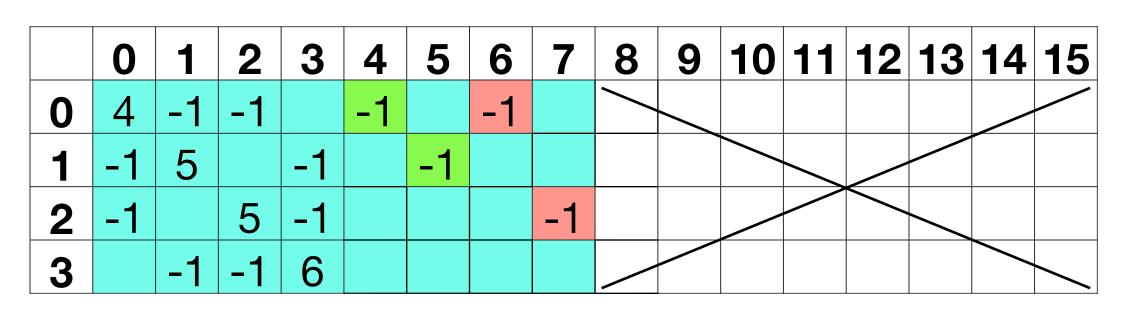
Compact storage of the "local" values

In many numerical codes the halo values are stored in a separate array







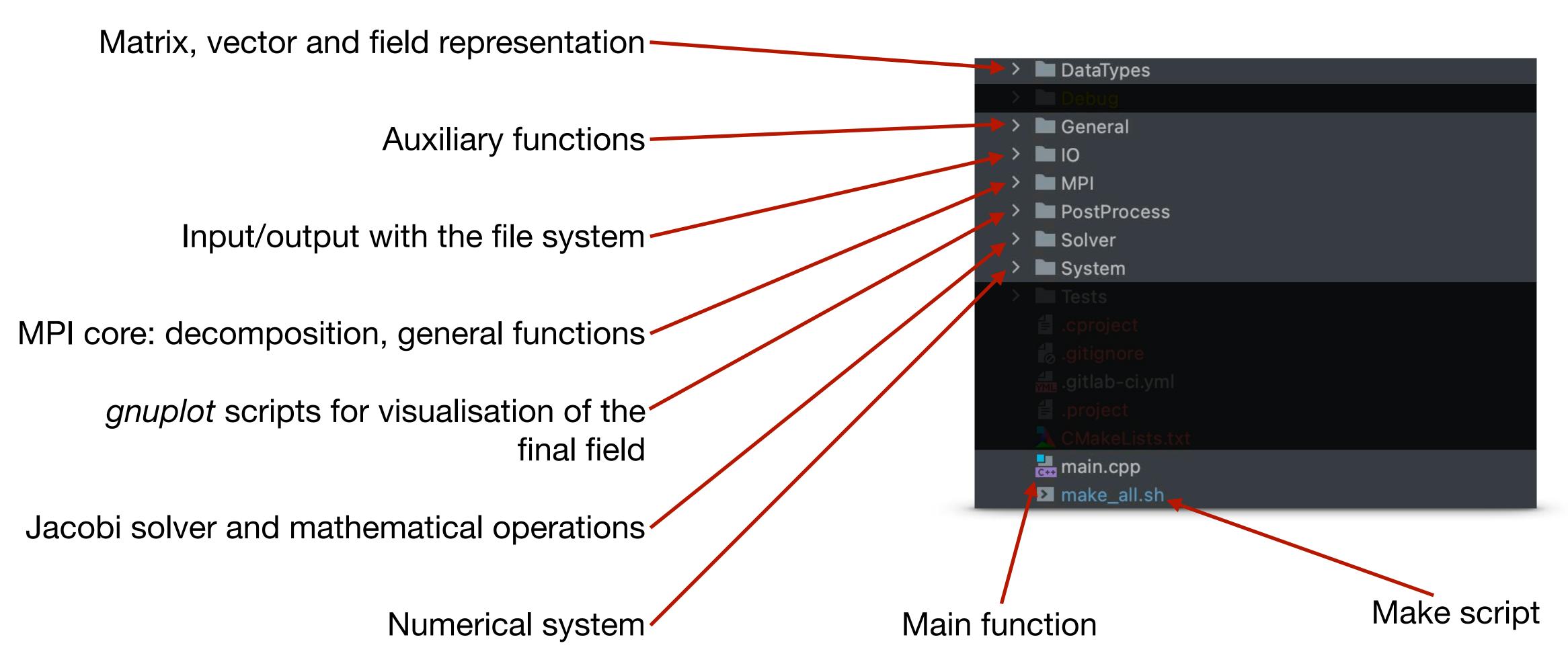


Repository

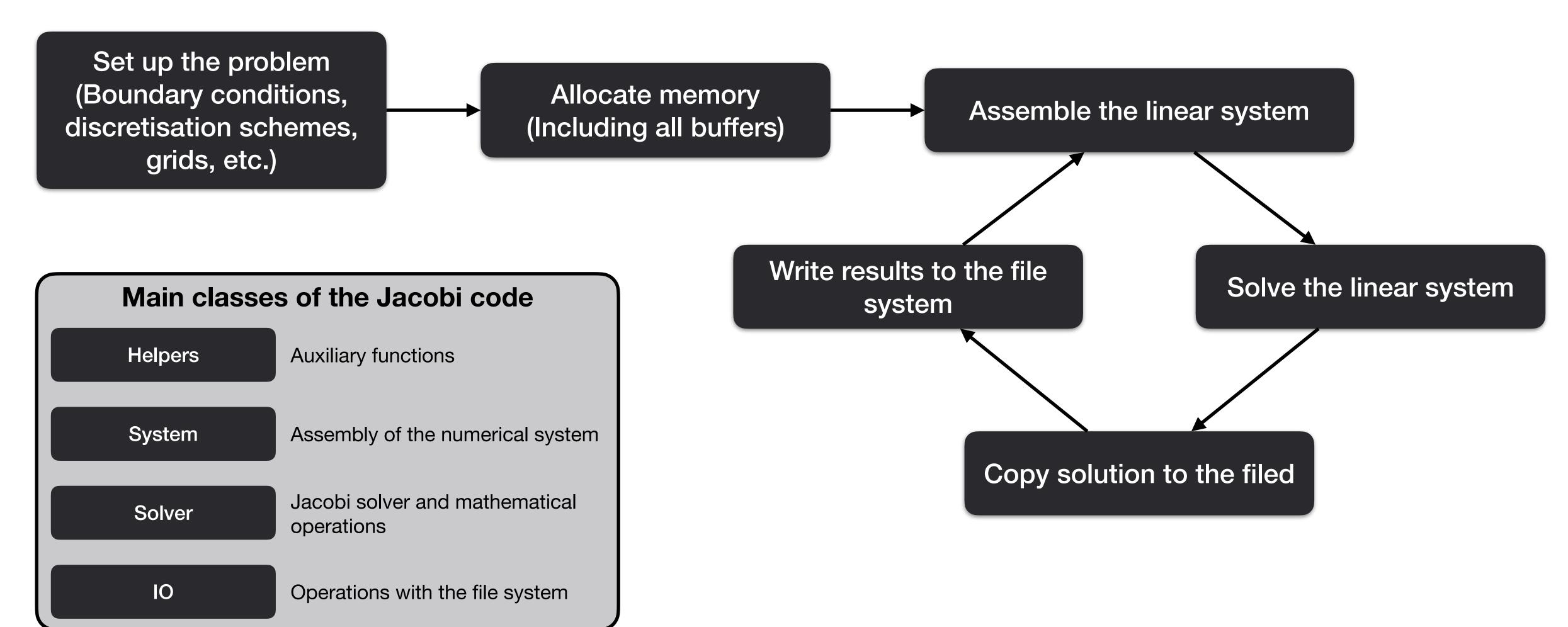
- SSH to Snellius
- Clone the repository from: https://github.com/sara-nl/prace_jacobi.git
- Compile with ./make_all.sh <type> (run ./make_all.sh to see all available types)

```
$ git clone https://github.com/sara-nl/prace_jacobi.git
$ cd prace_jacobi
$ ./make_all.sh mpi
```

Code structure



Generic logic



Hands-on#1.1

Filling the empty space

- In Solver/solver.cpp implement the following (look for the NOT_IMPLEMENTED macro):
 - Vector copy: Solver::copyVector()
 - Residual calculation:
 Solver::calculateResidual()
 - L2-norm calculation: **Solver::calculateNorm()**
- Test your implementation by compiling with:
 - `./make_all.sh omp` (will result in a serial binary)
- Run the executable without any arguments
- Visualise results with gnuplot

```
void Solver::copyVector(Vector &vec_in, Vector &vec_out) {
    * for every n-th elements in `vec_in`
           assign element of vec_in(n) to vec_out(n)
   NOT_IMPLEMENTED
void Solver::calculateResidual(Matrix &A, Vector &x,
                               Vector &b, Vector &res) {
    /*
     * assign `b` to `res`
     * for vector `x` and matrix `A`, the residual `res`
     * is calculated as:
           res(i) = b(i) - sum(A(i, j) * x(j))
    NOT_IMPLEMENTED
double Solver::calculateNorm(Vector &vec) {
     * for vector `vec` with n elements
         L2-norm = sqrt(sum(vec(n) * vec(n))
                     local for every MPI process
                  one value for all MPI processes
    NOT IMPLEMENTED
   return 0.0;
```

Filling the empty space

- Class Vector is inherited from the Matrix class
- Most important methods:

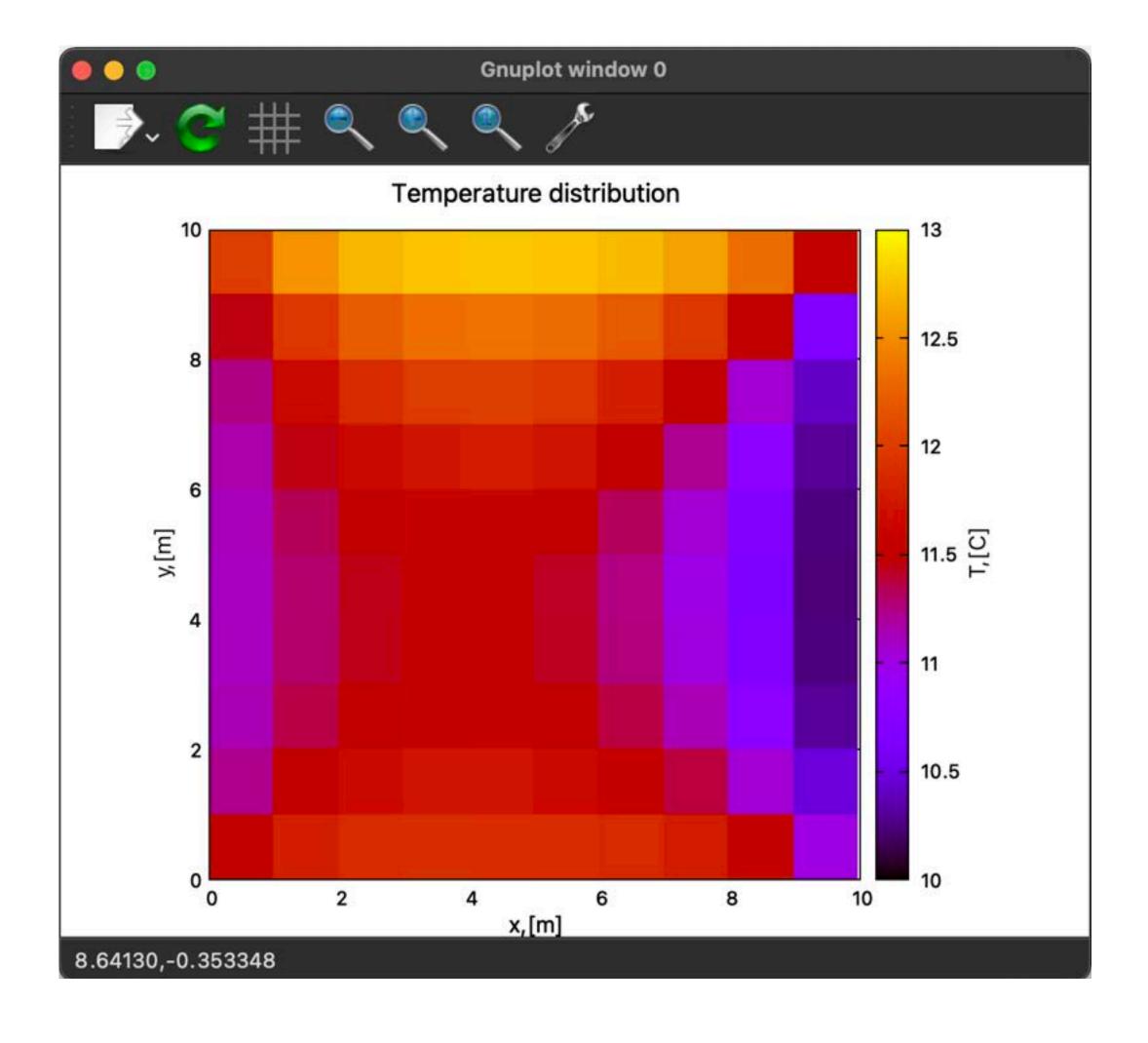
```
/*
  * Get number of local rows
  * (including halo cells)
  */
Matrix::numRows();

/*
  * Get number of local columns
  * (including halo cells)
  */
Matrix::numCols();

/*
  * Get number of local elements
  * (excluding halo cells)
  */
Matrix::getLocElts();
```

```
void Solver::copyVector(Vector &vec_in, Vector &vec_out) {
    * for every n-th elements in `vec_in`
          assign element of vec_in(n) to vec_out(n)
   NOT_IMPLEMENTED
void Solver::calculateResidual(Matrix &A, Vector &x,
                               Vector &b, Vector &res) {
    /*
    * assign `b` to `res`
    * for vector `x` and matrix `A`, the residual `res`
    * is calculated as:
          res(i) = b(i) - sum(A(i, j) * x(j))
   NOT_IMPLEMENTED
double Solver::calculateNorm(Vector &vec) {
    * for vector `vec` with n elements
        L2-norm = sqrt(sum(vec(n) * vec(n)))
                     local for every MPI process
                 one value for all MPI processes
   NOT_IMPLEMENTED
   return 0.0;
```

Building and execution



```
$ module load 2022 foss/2022a
$ ./make_all.sh omp
$
$ cat first_run.sh
#!/bin/bash
#SBATCH --reservation=mossd_cpu_course
#SBATCH -p rome
#SBATCH -n 1
#SBATCH --job-name=first_run
#SBATCH --output=first_run.out
#SBATCH --error=first_run.err
#SBATCH -time=0:05:00

module load 2022 foss/2022a
srun ./a.out
$
$ sbatch first_run.sh
```

```
$ cat first_run.out
                                            Output from
      0.588603
                                               the job
      0.392595
352
     1.02557e-06
     9.92268e-07
Writing results to file: output.dat
Elapsed time (Jacobi): 0.005982s.
Elapsed time (IO): 0.012528s.
$ # if used "ssh -X" or "ssh -Y"
$ module load gnuplot/5.4.4-GCCcore-11.3.0
$ cp PostProcess/plot_omp.plt .
$ gnuplot
gnuplot> load "plot_omp.plt"
```

Hands-on#1.2

Filling the empty space

- Add MPI communications:
 - In the iterative loop, the data must be exchanged between the real and the halo elements of the vector
 - Find the right implementation in DataTypes/vector.cpp
 - Insert the call for the function into the right place

```
while ( (iter < max_iter) && (residual_norm > tolerance) ) {
    for(int i = A.numRows() - 1; i >= 0; i--) {
        double diag = 1.;  // Diagonal element
        double sigma = 0.0;  // Just a temporary value
        x(i) = b(i);
        for(int j = 0; j < A.numCols(); ++j) {</pre>
            if (j != i)
                sigma = sigma + A(i, j) * x_old(j);
            else
                diag = A(i, j);
        x(i) = (x(i) - sigma) * omega / diag;
    for(int i = 0; i < x.numRows(); ++i) {</pre>
        x(i) += (1 - omega) * x_old(i);
       x_old(i) = x(i);
    calculateResidual(A, x, b, res);
    residual_norm = calculateNorm(res) / calculateNorm(b);
    if (my_rank == 0)
        cout << iter << '\t' << residual_norm << endl;</pre>
   ++iter;
```

Filling the empty space

- Note that the L2-norm calculation should actually fire up an MPI call
 - Which one?
 - Look at MPI/common.cpp to find the right function
- The MPI/common.cpp file has a lot of functions marked with NOT_IMPLEMENTED.
 Replace this macro with correct MPI calls, use MPI_COMM_WORLD as a communicator
- Compile the code with the `mpi` flag and execute it

```
$ module load 2022 foss/2022a
$ ./make_all.sh mpi
$ cat first_run.sh
#!/bin/bash
                                                Job script
#SBATCH --reservation=mossd_cpu_course
#SBATCH -p rome
#SBATCH -n 4
#SBATCH --job-name=first_run
#SBATCH --output=first_run.out
#SBATCH --error=first_run.err
#SBATCH -time=0:05:00
module load 2022 foss/2022a
srun ./a.out
$ sbatch first_run.sh
```

Tools

Tools

Overview: HPC tools

Tool name	Costs	Description
ARM DDT	Non-free	Full featured graphical, parallel debugger
HPCToolkit	Free	Integrated suite of tools for parallel program performance analysis
Intel One API	Free under certain conditions	Stack of different performance analysis and debuggingtools (MPI/OpenMP/SIMD)
Valgrind	Free	Memory errors debugging tool
TotalView	Non-free	Full featured graphical, parallel debugger
Vampir	Non-free	Full featured trace visualizer for parallel program OTF trace files
memP	Free	Lightweight memory profiling tool
mpiP	Free	Lightweight MPI profiling tool
MUST	Free	MPI runtime error detection tool
PAPI	Free	A standardized and portable API for accessing performance counter hardware
likwid	Free	A tool to measure hardware performance counters
TAU	Free	Full featured parallel program performance analyses toolkit
Extrae	Free	MPI/OpenMP profiler
Scalasca	Free	performance analysis tool for MPI+OpenMP
Darshan	Free	IO profiler
nvprof	Free	Thread profiler (inc. GPU) from NVIDIA
gdb	Free	Standard GNU debugger
ARM MAP	Non-free	performance analysis tool for MPI+OpenMP
uProf	Free	performance analysis tool for MPI+OpenMP
gprof	Free	Standard unix/linux profiling utility

Different support for:

- Hardware
- Parallelisation strategies
- Compilers
- Interface

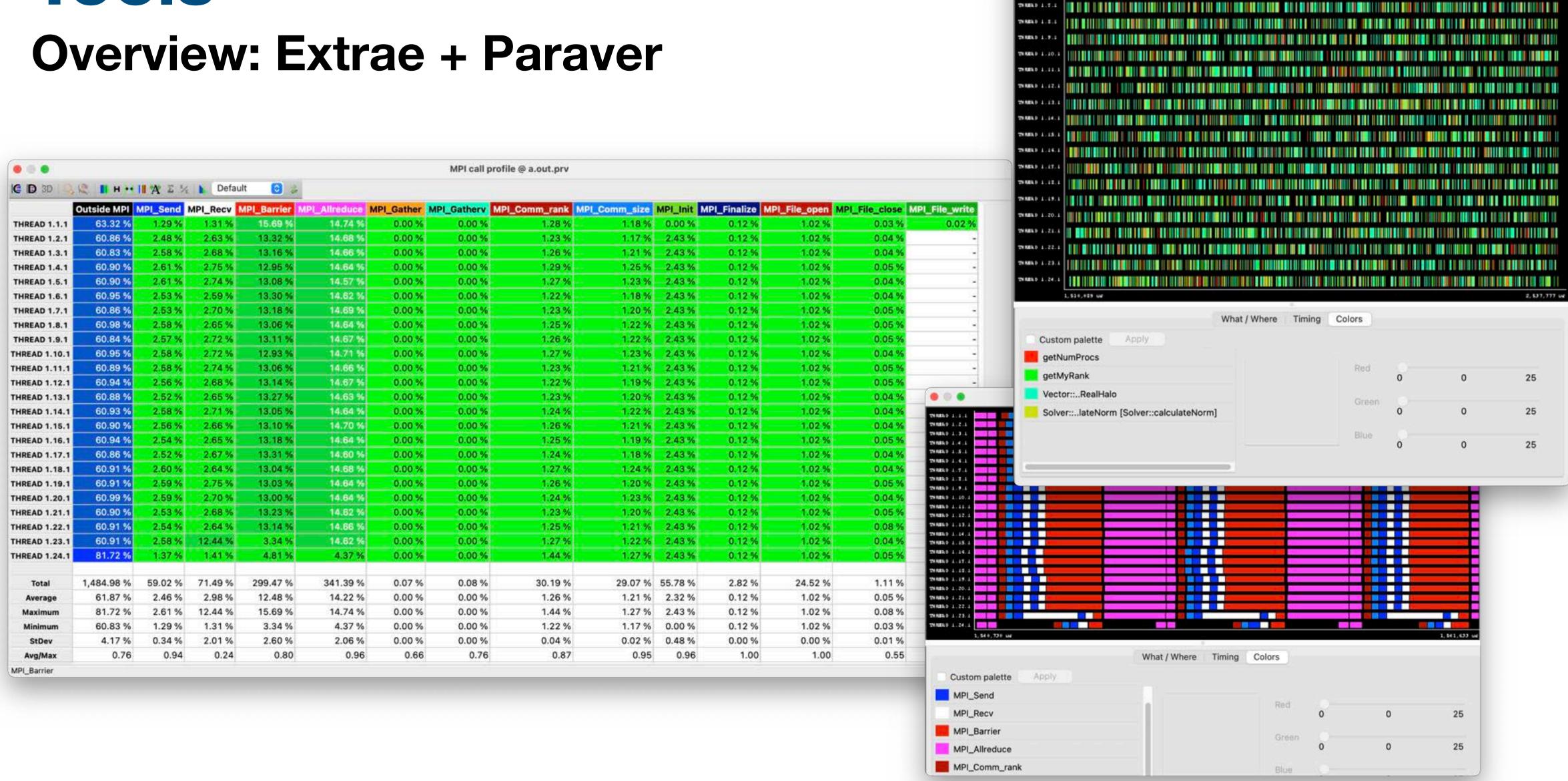
Other important aspects:

- Learning curve
- Completeness of the reports
- Costs and licenses
- Community support
- Documentation

Good overview:

https://hpc.llnl.gov/software/developmentenvironment-software

Tools

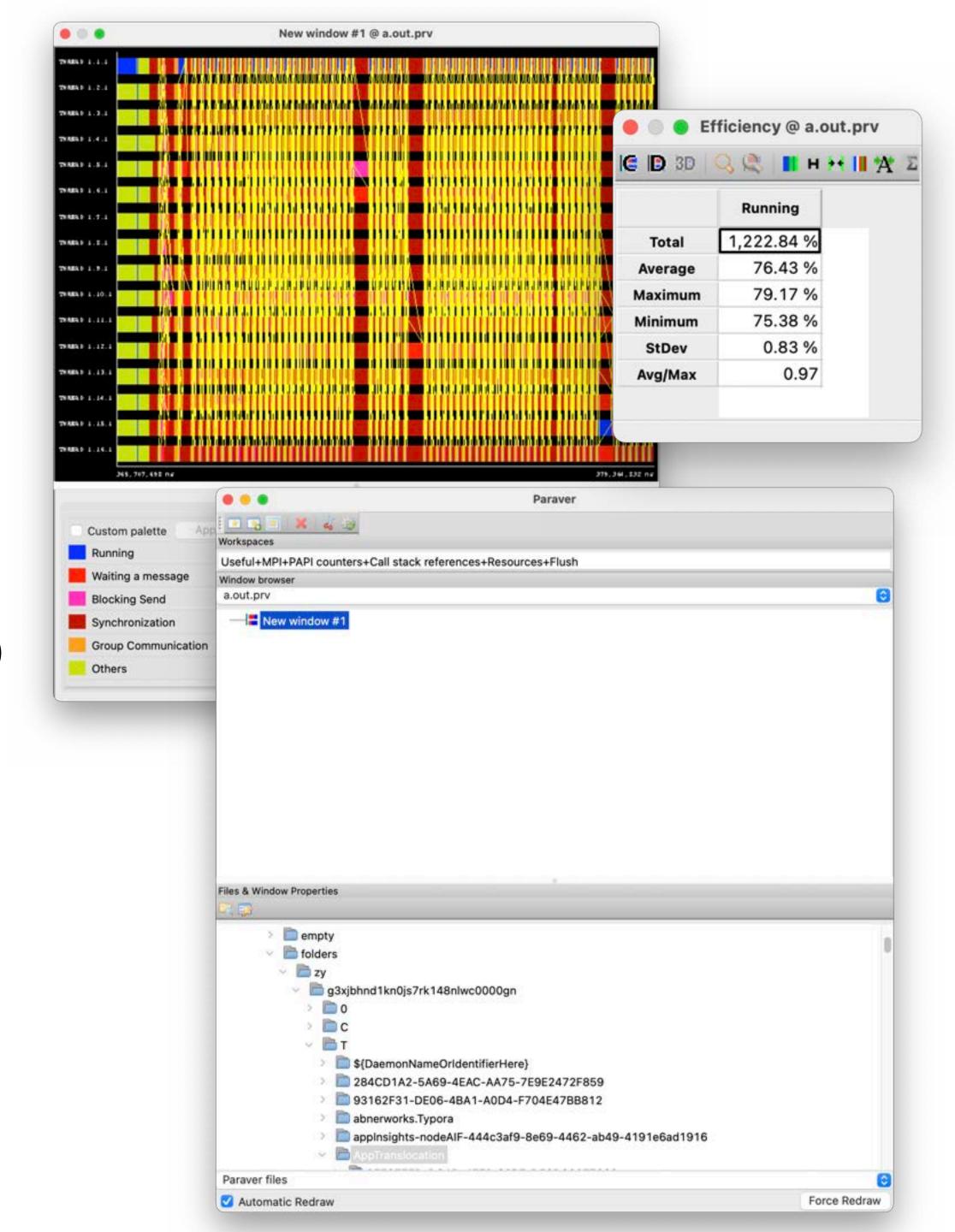


MPI caller @ a.out.prv

Hands-on#1.3

Profiling

- Profile the code with *Extrae* (use 32x32 grid)
- Download *Paraver* to your local machine: https://tools.bsc.es/downloads
- Find the bottlenecks using Paraver (see `Hints` menu)
 - Visualise the "MPI profile"
 - Visualise the "Profile caller line"
 - Visualise the "Caller function"



Profiling

- Comment out the io.WriteFile() call in main.cpp
- Copy configuration files to the project folder
- Modify the *trace.sh* script:
 - Replace "double dots" with a single "dot" in the EXTRAE_CONFIG_FILE environment variable
 - Comment out LD_PRELOAD for Fortran apps and uncomment it for C apps

```
$ module load 2022
$ module load Extrae/4.0.4-gompi-2022a
$
$ cd prace_jacobi
$
$ cp ${EBROOTEXTRAE}/share/example/MPI/ld-preload/trace.sh .
$ cp ${EBROOTEXTRAE}/share/example/MPI/extrae.xml .
```

trace.sh

```
#!/bin/bash
source /sw/arch/RHEL8/EB_production/2022/software/Extrae/
4.0.4-gompi-2022a/etc/extrae.sh

export EXTRAE_CONFIG_FILE=./extrae.xml
# For C apps
export LD_PRELOAD=${EXTRAE_HOME}/lib/libmpitrace.so
# For Fortran apps
#export LD_PRELOAD=${EXTRAE_HOME}/lib/libmpitracef.so

## Run the desired program
$*
```

Profiling

- Execute a test on 16 cores (Rome partition) with 10x10 grid and 4x4 decomposition
- Merge intermediate trace files into a single Paraver trace file at the end of the job script
- Visualise and analyse results
 - Copy the following files to your local machine: a.out.pcf, a.out.prv, a.out.row
 - Open a.out.prv using Paraver

```
Use the following keys:

-s - set number of the grid cells in each direction (i j)

-d - set decomposition for each direction (i j)

(doesn't affect the METIS decomposition, but should be set anyway!)
```

```
test_extrae.sh
#!/bin/bash
#SBATCH -reservation=mossd_cpu_course
#SBATCH -p rome
#SBATCH -n 16
#SBATCH --job-name=mpi_training
#SBATCH --output=out.p_np_16
#SBATCH --error=err.p_np_16
#SBATCH --time=0:05:00
module load 2022 foss/2022a Extrae/4.0.4-gompi-2022a
### Export trace sh and executable
export EXE="./a.out -s 10 10 -d
### Run the application
srun ./trace.sh $EXE
### Merge trace files
mpi2prv -f TRACE mpits
```

Hands-on#1.4

Simple profiling

- Measure the elapsed time of the Jacobi solver with the "foss/2022a" toolchain:
 - use 32x32 grid, 16 processes
 - see "Elapsed time (Jacobi):"
- Change the toolchain to "intel/2022a" (i.e. change OpenMPI to IMPI)
 - What happened to the elapsed time with IMPI?

```
$ cat simple_profiling.sh
#!/bin/bash
                                               Job script
#SBATCH --reservation=mossd_cpu_course
#SBATCH -p rome
#SBATCH -n 16
#SBATCH --job-name=simple_profiling
#SBATCH --output=simple_profiling.out
#SBATCH --error=simple_profiling.err
#SBATCH --time=0:05:00
echo "Open MPI"
module purge
module load 2022 foss/2022a
./make_all.sh mpi
srun ./a.out -s 32 32 -d 1 16
echo "Intel MPI"
module purge
module load 2022 intel/2022a
./make_all.sh mpi
srun ./a.out -s 32 32 -d 1 16
$ sbatch simple_profiling.sh
```

```
$ cat simple_profiling.out | grep "Elapsed time (Jacobi):"
Elapsed time (Jacobi): 0.153555s.
Elapsed time (Jacobi): 3.860522s. Results
```

Simple profiling

- MPI_Wtime() returns a floating-point number of seconds, representing elapsed wall-clock time since some moment in the past.
- MPI standard doesn't guarantee that clocks are synchronised!
- MPI_WTIME_IS_GLOBAL boolean variable that indicates whether clocks are synchronized. The value returned for MPI_WTIME_IS_GLOBAL is 1 if clocks at all processes in MPI_COMM_WORLD are synchronized, 0 otherwise.
- Check if clocks are synchronised.

Hands-on Simple profiling

OpenMPI

• The boolean variable MPI_WTIME_IS_GLOBAL, a predefined attribute key that indicates whether clocks are synchronized, does not have a valid value in Open MPI, as the clocks are not guaranteed to be synchronized.

Hands-on Simple profiling

Solution #1:

- Use other functions that do not rely on an arbitrary start moment in the past, e.g. "gettimeofday()" (expensive, limited precision)
- Solution #2:
 - report min, max and average elapsed times using MPI_Wtime() (fine resolution)

```
void reportElapsedTime(double start, double end,
                    const std::string &message)
    double elp time = end - start;
    double elp_time_min = elp_time;
    double elp_time_max = elp_time;
     findGlobalMin(elp_time_min);
     findGlobalMax(elp_time_max);
     findGlobalSum(elp_time);
     printByRoot("Elapsed time (" + message + "): ");
    printByRoot(" Min: "
           + std::to_string(elp_time_min) + "s.");
     printByRoot(" Max: "
          + std::to_string(elp_time_max) + "s.");
     printByRoot("
          + std::to_string(elp_time / getNumProcs()) +
          "s.");
```

Hands-on Simple profiling

- Solution #3:
 - Force custom synchronisation using MPI:
 - Sync all processes
 - Get time from one of the processes with MPI_Wtime()
 - Broadcast the measured time to all processes and calculate local offsets
 - Adjust subsequent timings using these offsets

```
double syncTime() {
   double local_time, base_time, offset;
   int my_rank = getMyRank();
   // Synchronize all processes
   MPI_Barrier(MPI_COMM_WORLD);
   // Get the local time
   local_time = MPI_Wtime();
   // Rank 0 gets the reference time
   if (my_rank == 0) base_time = local_time;
   // Broadcast the reference time to all processes
   MPI_Bcast(&base_time, 1, MPI_DOUBLE, 0, MPI_COMM_WORLD);
   // Calculate the offset for each process
   offset = base_time - local_time;
   return offset;
void runProblem(int argc, char** argv) {
    double offset = syncTime();
   elp_time[0] = helpers.tic() + offset;
    // Some work
   elp_time[1] = helpers.toc() + offset;
```