

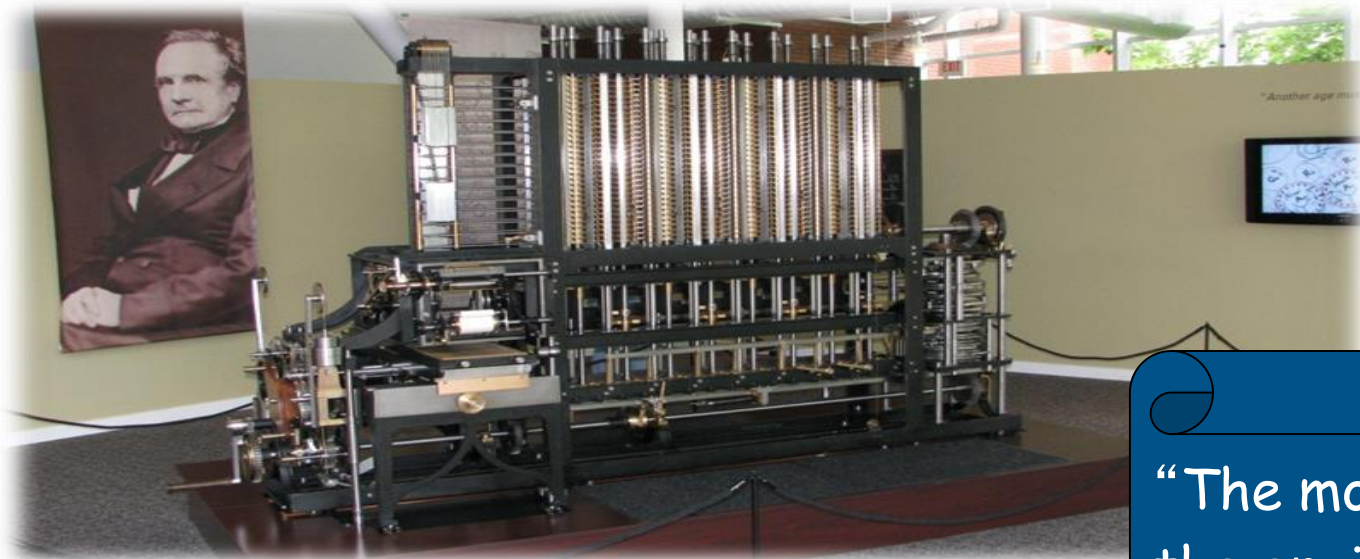
# Introduction to Parallel Performance Engineering

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(with content used with permission from tutorials  
by Bill Williams/TU Dresden,  
Bernd Mohr/JSC and Luiz DeRose/Oracle)

## Performance: an old problem



Difference Engine

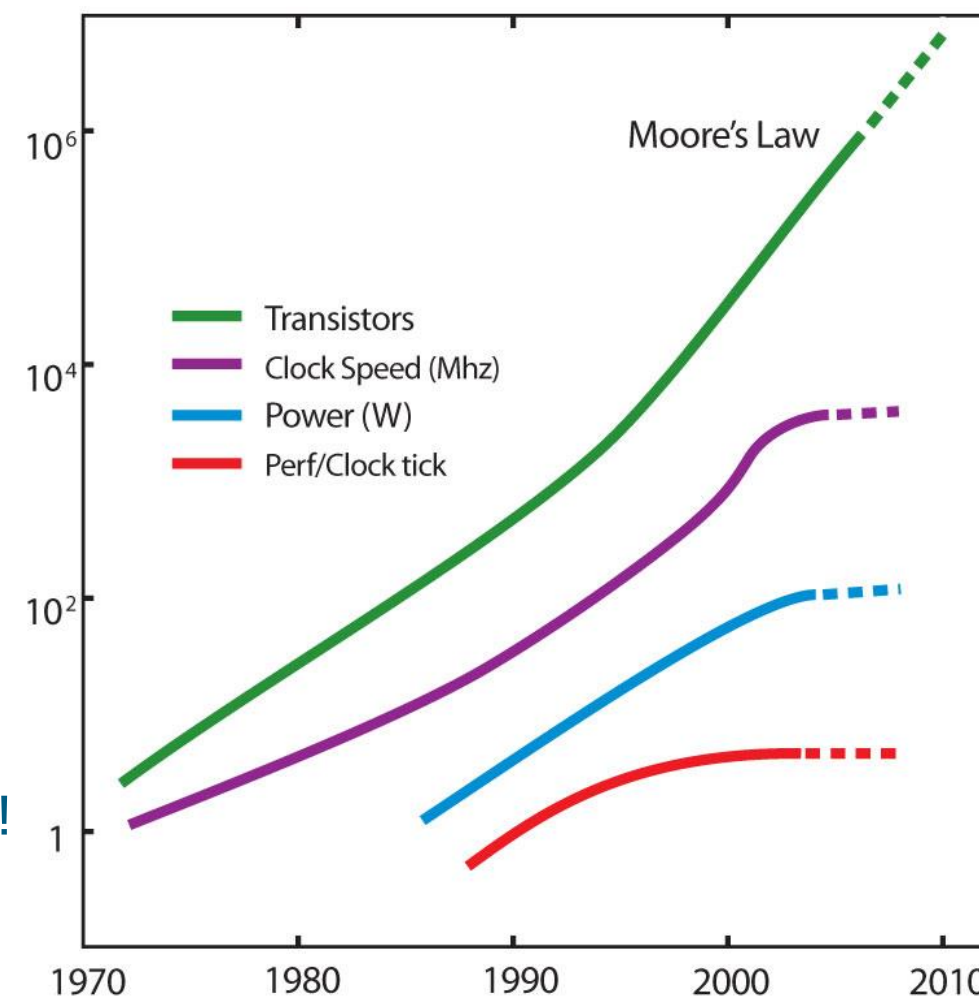
“The most constant difficulty in contriving the engine has arisen from the desire to reduce the time in which the calculations were executed to the shortest which is possible.”

Charles Babbage  
1791 – 1871

# Today: the “free lunch” is over

- Moore's law is still in charge, but
  - Clock rates no longer increase
  - Performance gains only through increased parallelism
- Optimizations of applications more difficult
  - Increasing application complexity
    - Multi-physics
    - Multi-scale
  - Increasing machine complexity
    - Hierarchical networks / memory
    - More CPUs / multi-core

👉 Every doubling of scale reveals a new bottleneck!



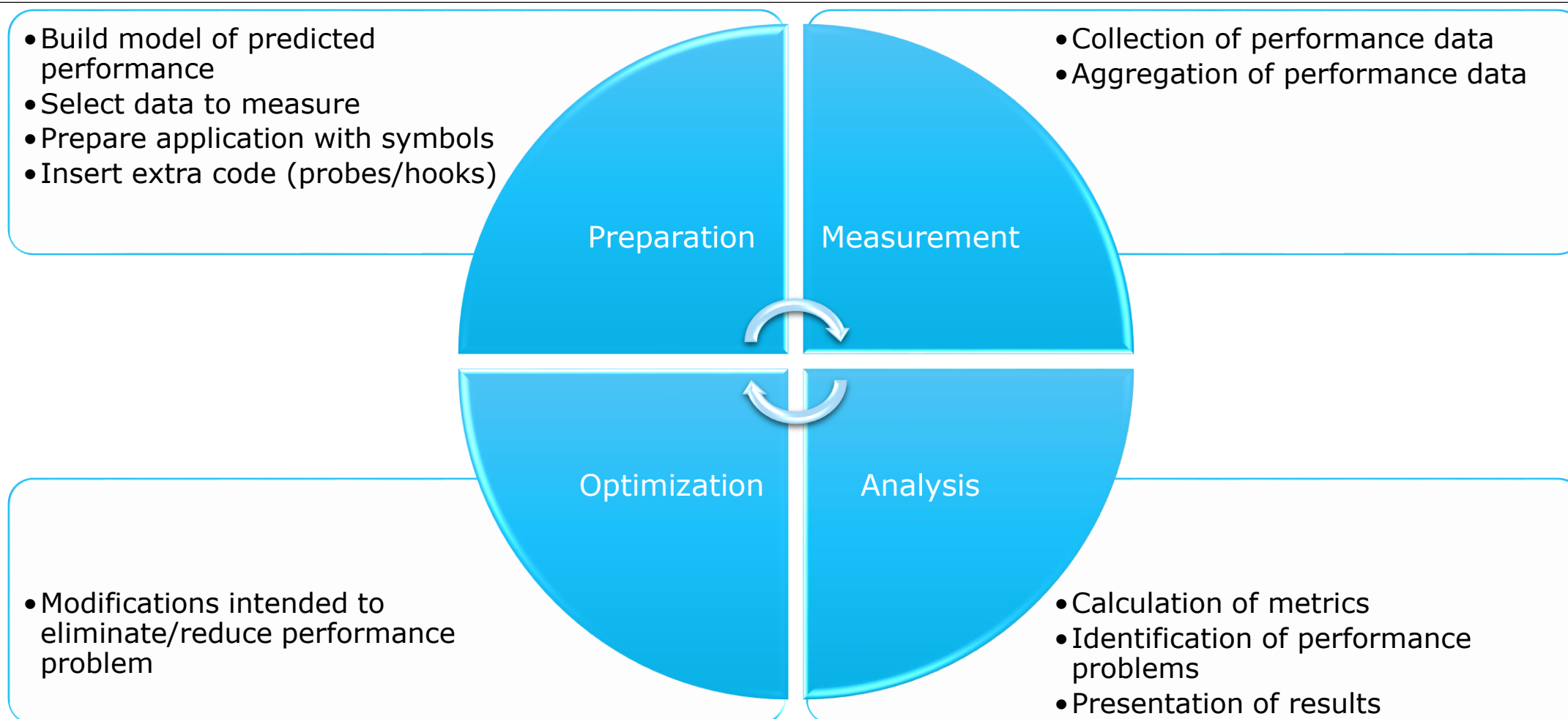
# Performance factors of parallel applications

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- “Sequential” performance factors
  - Computation
  - Cache and memory
  - Input / output
- “Parallel” performance factors
  - Partitioning / decomposition
  - Communication (i.e., message passing)
  - Multithreading
  - Synchronization / locking



# Performance engineering workflow



# Parallel Performance Engineering in Practice

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- Starting point: well-understood, well-optimized code at scale N
- Goal: scale to  $M \gg N$
- Predict behavior: what is the current bottleneck, what performance should we see?
- Measure possible bottlenecks
  - Idle resources
  - Changes in profile
- Minimize perturbation
  - May require multiple measurements!

# Performance Modeling: Predicting Behavior

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- Simplest models: scaling properties
  - What parts of the code are serial and parallel?
  - How much time is spent in each?
  - How efficient are they currently?
- More complex concepts
  - Roofline model (comparing throughput to theoretical maxima)
  - Load balancing: what code is responsible for idle resources?
  - Critical path analysis (e.g. Scalasca)

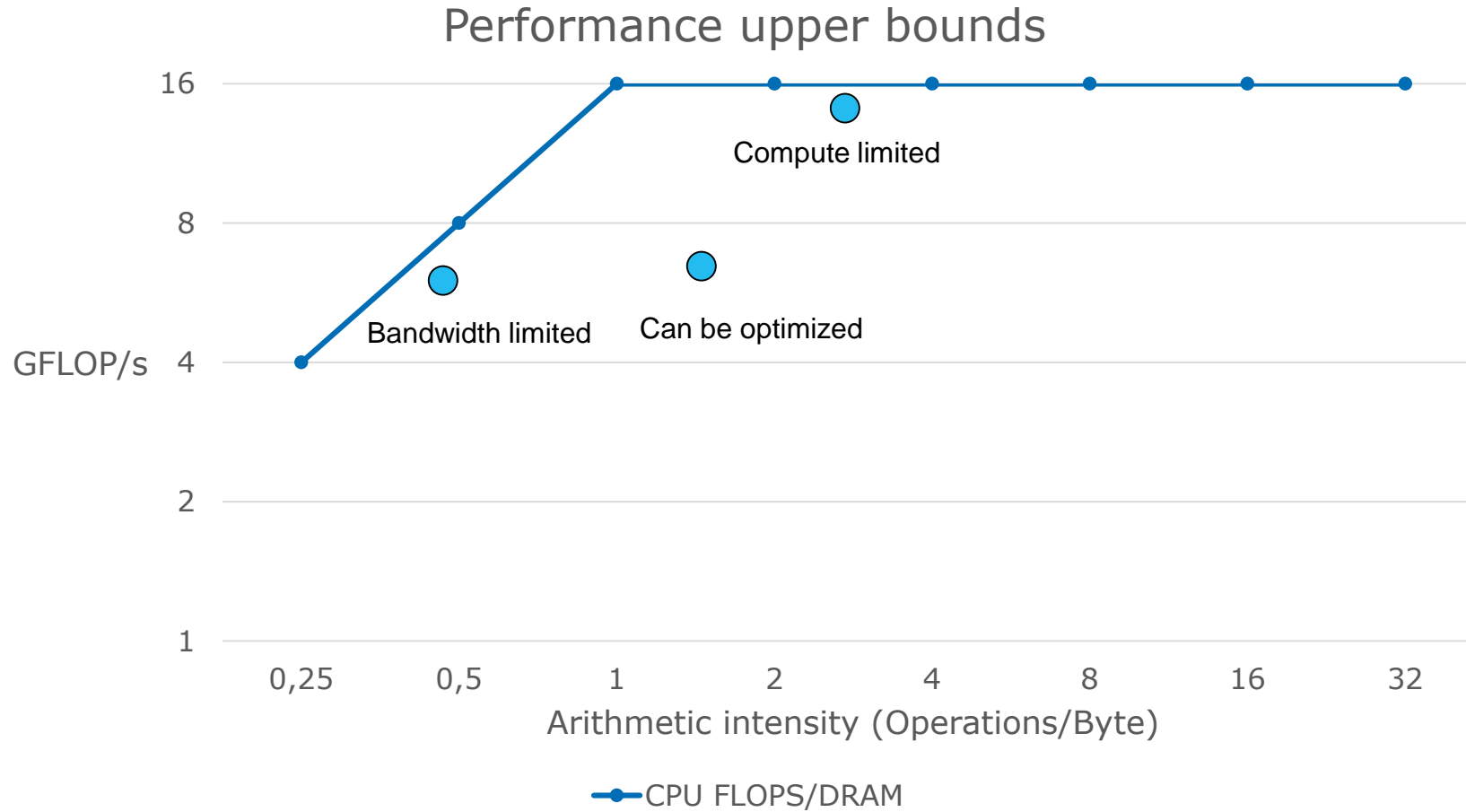
## Strong and weak scaling

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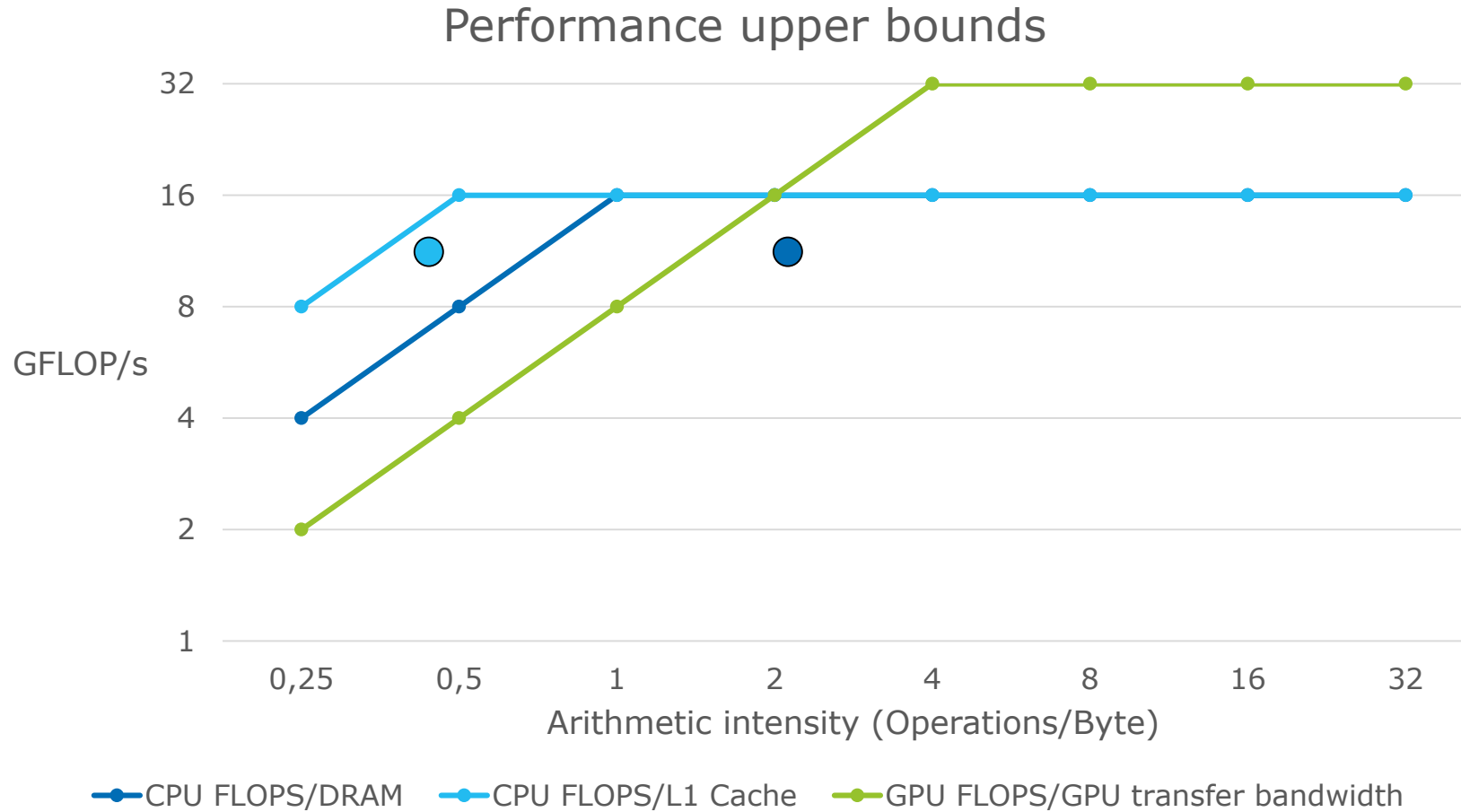
- Strong scaling: increasing compute power yields faster solutions on the same problem
  - Amdahl's law:  $\text{Speedup} = (\text{serial} + \text{parallel}) / (\text{serial} + \text{parallel} / N) = 1 / (\text{serial} + \text{parallel} / N)$
- Weak scaling: increasing compute power yields larger problems solved in the same time
  - Gustafson's law: convert Amdahl's law to measure scaled speedup (as a factor of problem size)



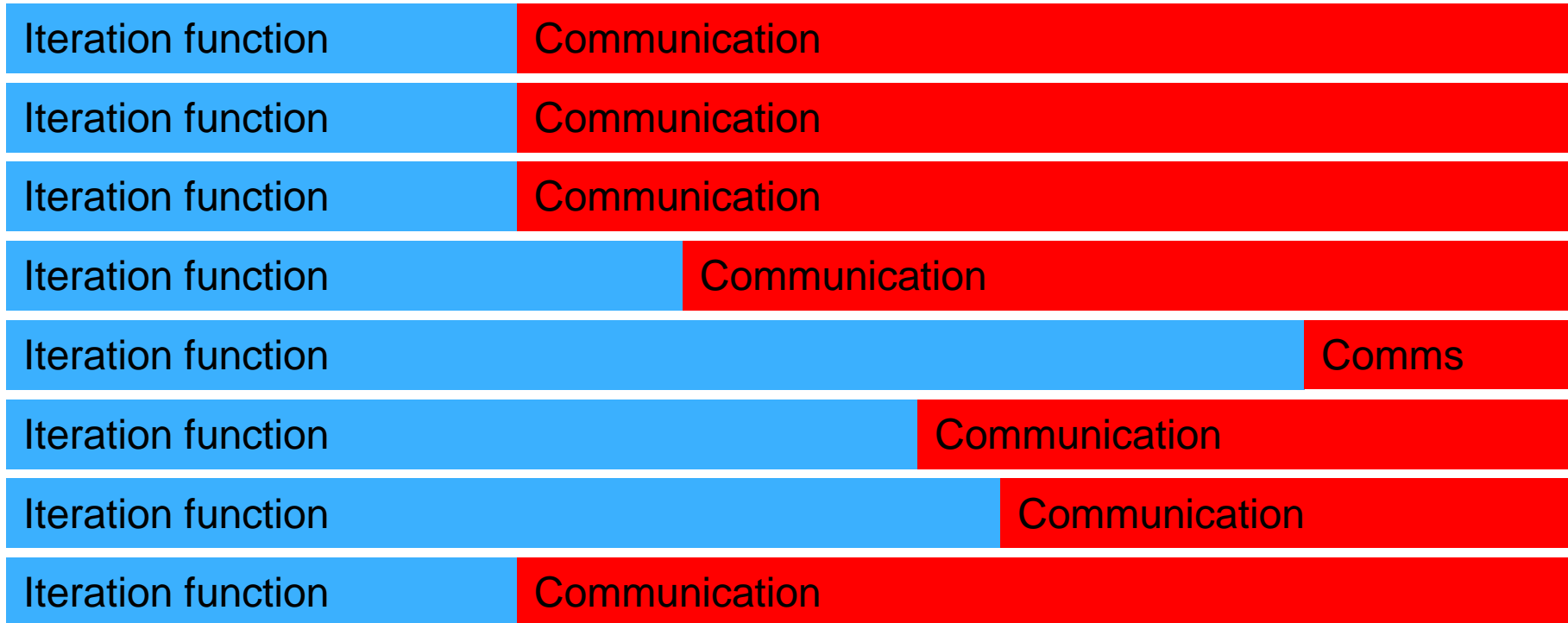
# Roofline Model



# Multiple Roofline Model



# Load balancing



Probably mostly idle!

# Critical Path Analysis

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- Key concept: critical path is the sequence of tasks that govern execution time
  - At any given time, what is the job waiting for? May be computation or transfer or a combination!
- Optimizing tasks off the critical path can't speed up execution
- Example: load imbalance due to a rare case being 2x slower than the common case
  - The slow rare case may only be 1% of aggregated execution time, but responsible for 50% of wall time in iterations
  - Optimize the critical path = make the rare case closer to the speed of the common case

# What to Measure

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- So you have some hypothesis about how your code will behave
- This requires certain data
  - Simple scaling models: execution time, possibly subdivided between serial and parallel parts
  - Roofline model: operations/second and bytes/second corresponding to one or more rooflines
  - Load balancing: distribution of time spent in computation and communication
  - Critical path: detailed measurement of execution time across all nodes and threads
- Allows you to ignore certain other data
  - Example: load balancing
  - Detection typically based on communication wait states
  - Don't need to analyze computation details for that
- When possible, measure only what you need to test your hypothesis
  - All-in-one-run only when it's unavoidable



# Measurement Practices

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- Measurements on HPC systems are noisy
  - Shared resources: anything short of full-system DAT probably shares something (and maybe even then, if you use site-shared filesystems)
  - Nondeterminism: cache effects, which nodes were allocated, small race conditions
- Particularly relevant to wall time, but can affect other metrics
- As with all scientific measurements, repeat the experiment
  - Especially if the initial results look weird!

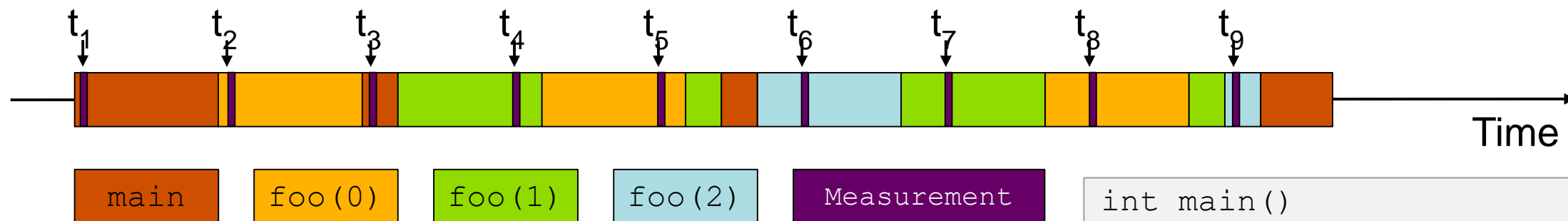
# Measurement issues

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- Accuracy
  - Intrusion overhead
    - Measurement itself needs time and thus lowers performance
  - Perturbation
    - Measurement alters program behaviour
    - E.g., memory access pattern
  - Accuracy of timers & counters
- Granularity
  - How many measurements?
  - How much information / processing during each measurement?

☞ *Tradeoff: Accuracy vs. Expressiveness of data*

# Sampling



- Running program is periodically interrupted to take measurement
  - Timer interrupt, OS signal, or HWC overflow
  - Service routine examines return-address stack
  - Addresses are mapped to routines using symbol table information
- Statistical inference of program behavior
  - Not very detailed information on highly volatile metrics
  - Requires long-running applications
- Works with unmodified executables

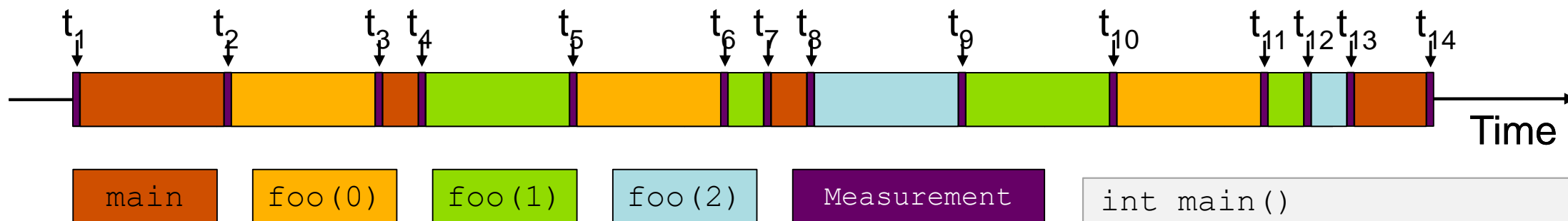
```
int main()
{
    int i;

    for (i=0; i < 3; i++)
        foo(i);

    return 0;
}

void foo(int i)
{
    if (i > 0)
        foo(i - 1);
}
```

# Instrumentation



- Measurement code is inserted such that every event of interest is captured directly
  - Can be done in various ways
- Advantage:
  - Much more detailed information
- Disadvantage:
  - Processing of source-code / executable necessary
  - Large relative overheads for small functions

```
int main()
{
    int i;
    Enter("main");
    for (i=0; i < 3; i++)
        foo(i);
    Leave("main");
    return 0;
}

void foo(int i)
{
    Enter("foo");
    if (i > 0)
        foo(i - 1);
    Leave("foo");
}
```

# Profiling / Runtime summarization

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- Recording of aggregated information
  - Total, maximum, minimum, ...
- For measurements
  - Time
  - Counts
    - Function calls
    - Bytes transferred
    - Hardware counters
- Over program and system entities
  - Functions, call sites, basic blocks, loops, ...
  - Processes, threads

👉 *Profile = summarization of events over execution interval*



# Tracing

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- Recording detailed information about significant points (events) during execution of the program
  - Enter / leave of a region (function, loop, ...)
  - Send / receive a message, ...
- Save information in event record
  - Timestamp, location, event type
  - Plus event-specific information (e.g., communicator, sender / receiver, ...)
- Abstract execution model on level of defined events

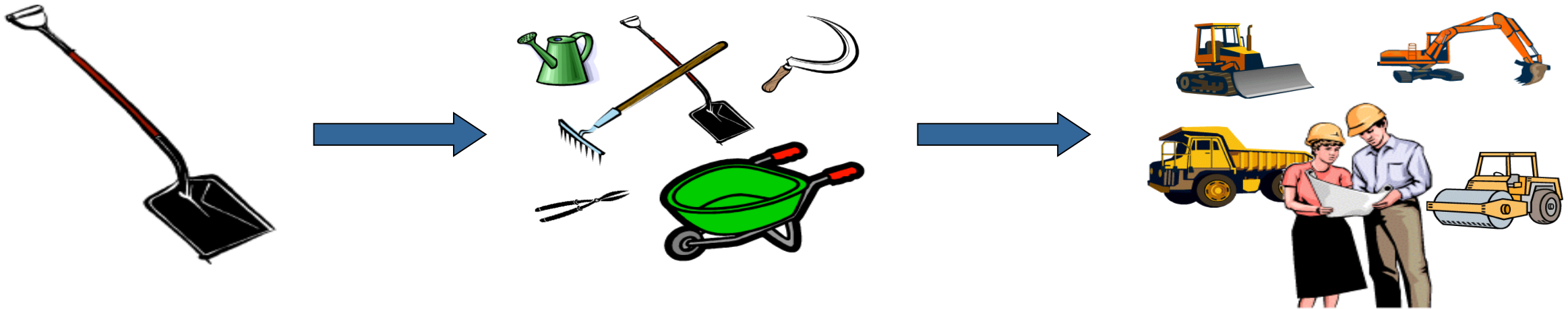
☞ *Event trace = Chronologically ordered sequence of event records*

# Tracing Pros & Cons

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- Tracing advantages
  - Event traces preserve the **temporal** and **spatial** relationships among individual events (👉 context)
  - Allows reconstruction of **dynamic** application behaviour on any required level of abstraction
  - Most general measurement technique
    - Profile data can be reconstructed from event traces
- Disadvantages
  - Traces can very quickly become extremely large
  - Writing events to file at runtime may causes perturbation

# No single solution is sufficient!



A combination of different methods, tools and techniques is typically needed!

- Analysis
  - Statistics, visualization, automatic analysis, data mining, ...
- Measurement
  - Sampling / instrumentation, profiling / tracing, ...
- Instrumentation
  - Source code / binary, manual / automatic, ...