

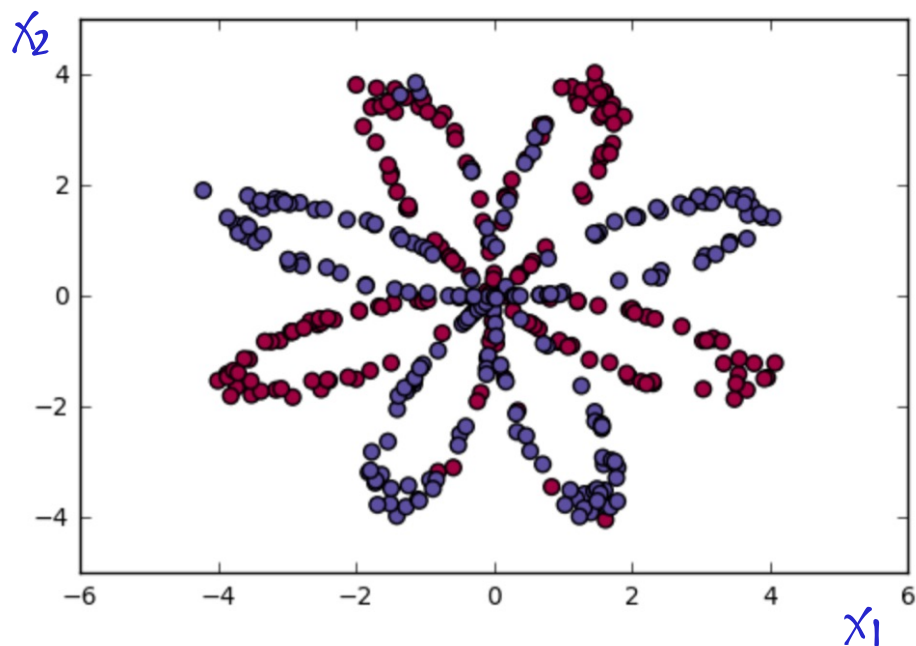
§ planar data classification with a hidden layer

1. Dataset

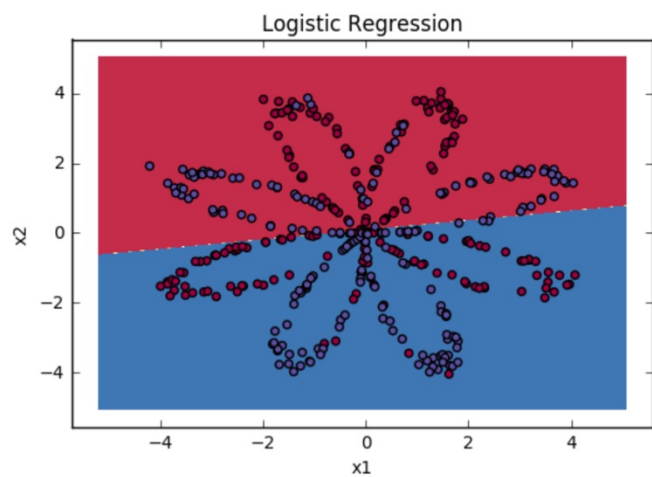
$X, Y = \text{load_planar_dataset}()$

X - a numpy-array contains your features (x_1, x_2)
 2×4000

Y - a numpy-array contains your labels (red: 0, blue: 1)
 1×4000



2. Logistic Regression (Sample)

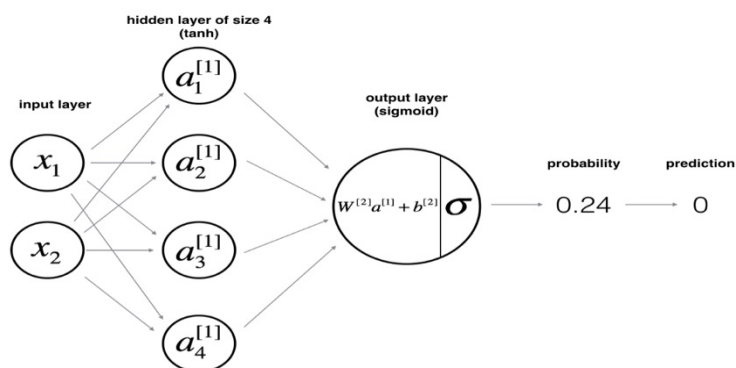


Expected Output:

Accuracy	47%
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The logistic regression doesn't perform well since the dataset is not linearly separable.

3. Neural Network model



For one example $x^{(i)}$:

$$\begin{aligned} z^{[1](i)} &= W^{[1]}x^{(i)} + b^{[1](i)} \\ a^{[1](i)} &= \tanh(z^{[1](i)}) \\ z^{[2](i)} &= W^{[2]}a^{[1](i)} + b^{[2](i)} \\ y^{(i)} &= a^{[2](i)} = \sigma(z^{[2](i)}) \\ y_{\text{prediction}}^{(i)} &= \begin{cases} 1 & \text{if } a^{[2](i)} > 0.5 \\ 0 & \text{otherwise} \end{cases} \end{aligned}$$

Given the predictions on all the examples, you can also compute the cost J as follows:

$$J = -\frac{1}{m} \sum_{i=0}^m \left(y^{(i)} \log(a^{[2](i)}) + (1 - y^{(i)}) \log(1 - a^{[2](i)}) \right)$$

Reminder: The general methodology to build a Neural Network is to:

1. Define the neural network structure (# of input units, # of hidden units, etc).
2. Initialize the model's parameters
3. Loop:
 - Implement forward propagation
 - Compute loss
 - Implement backward propagation to get the gradients
 - Update parameters (gradient descent)

(1) define the neural network structure

n_x : the size of the input layer
 n_h : the size of the hidden layer
 n_y : the size of the output layer

(2) initialize the model's parameters

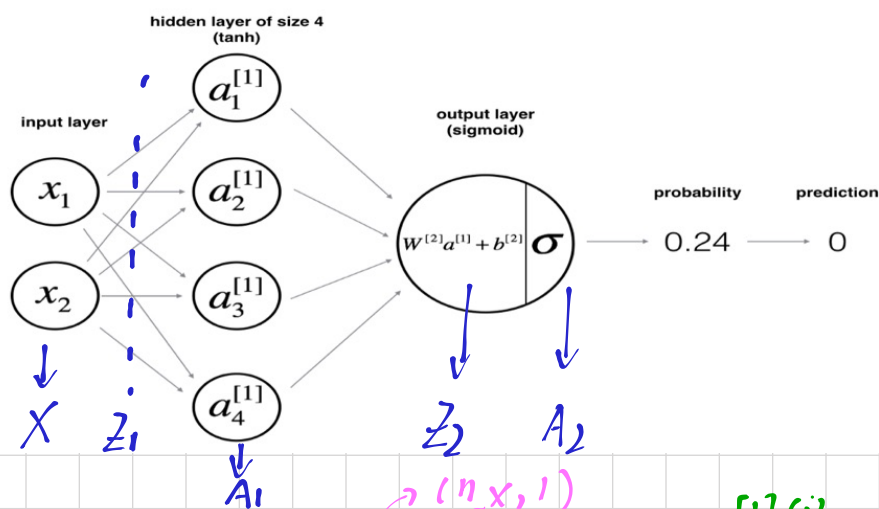
$W1 = \text{np.random.randn}(n_h, n_x) * 0.01 \rightarrow \text{weight matrix}$

$b1 = \text{np.zeros}(n_h, 1) \rightarrow \text{bias vector}$

$W2 = \text{np.random.randn}(n_y, n_h) * 0.01 \rightarrow \text{weight matrix}$

$b2 = \text{np.zeros}(n_y, 1) \rightarrow \text{bias vector}$

(3) loop



$$Z1 = \text{np.dot}(W1, X) + b1 \rightarrow Z^{[1](i)} = W^{[1]} X^{(i)} + b^{[1](i)}$$

$$A1 = \text{np.tanh}(Z1) \rightarrow a^{[1](i)} = \tanh(Z^{[1](i)})$$

$$Z2 = \text{np.dot}(W2, A1) + b2 \rightarrow Z^{[2](i)} = W^{[2]} a^{[1](i)} + b^{[2](i)}$$

$$A2 = \text{sigmoid}(Z2) \rightarrow a^{[2](i)} = \sigma(Z^{[2](i)})$$

$$J = -\frac{1}{m} \sum_{i=0}^m (y^{(i)} \log(a^{[2](i)}) + (1 - y^{(i)}) \log(1 - a^{[2](i)}))$$

$\log \text{probs} = \text{np.multiply}(\text{np.log}(A2), Y) + \text{np.multiply}(\text{np.log}(1 - A2), (1 - Y))$
 $\text{cost} = -1/m * \text{np.sum}(\log \text{probs})$

P.S. Broadcasting

When operating on two arrays, Numpy compares their shapes element-wise.

Two dimensions are compatible when:

① they are equal, or

② one of them is 1

others → Value Error

g. ① A: 8x1x6x1
 B: 7x1x5
 result: 8x7x6x1

② A: 15x3x5
 B: 15x1x5
 result: 15x3x5

③ A: 8x4x3
 B: 2x1
 result: Error

Backward propagation

Summary of gradient descent

$$dz^{[2]} = a^{[2]} - y$$

$$dW^{[2]} = dz^{[2]} a^{[1]T}$$

$$db^{[2]} = dz^{[2]}$$

$$dz^{[1]} = W^{[2]T} dz^{[2]} * g^{[1]'}(z^{[1]})$$

$$dW^{[1]} = dz^{[1]} x^T$$

$$db^{[1]} = dz^{[1]}$$

$$dZ^{[2]} = A^{[2]} - Y$$

$$dW^{[2]} = \frac{1}{m} dZ^{[2]} A^{[1]T}$$

$$db^{[2]} = \frac{1}{m} \text{np.sum}(dZ^{[2]}, \text{axis} = 1, \text{keepdims} = \text{True})$$

$$dZ^{[1]} = W^{[2]T} dZ^{[2]} * g^{[1]'}(Z^{[1]})$$

$$dW^{[1]} = \frac{1}{m} dZ^{[1]} X^T$$

$$db^{[1]} = \frac{1}{m} \text{np.sum}(dZ^{[1]}, \text{axis} = 1, \text{keepdims} = \text{True})$$

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$$dZ2 = A2 - Y$$

$$dW2 = (1/m) * \text{np.dot}(dZ2, A1.T)$$

$$db2 = (1/m) * \text{np.sum}(dZ2, \text{axis} = 1, \text{keepdims} = \text{True})$$

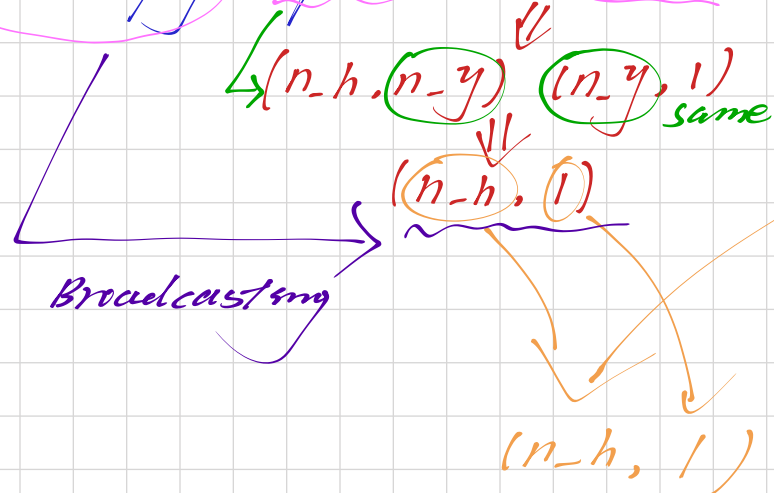
$$dZ1 = \text{np.multiply}(\text{np.dot}(W2.T, dZ2), (1 - \text{np.power}(A1, 2)))$$

$$dW1 = (1/m) * \text{np.dot}(dZ1, X.T)$$

$$db1 = (1/m) * \text{np.sum}(dZ1, \text{axis} = 1, \text{keepdims} = \text{True})$$

$$dz^{[1]} = W^{[2]T} dz^{[2]} * g^{[1]'}(z^{[1]})$$

$$dz1 = np.multiply(np.dot(W2.T, dz2), ci-mp.power(A1,2))$$



⚠ attention the difference between $np.dot()$ and $np.multiply$

Gradient rule

$$\theta = \theta - \alpha \frac{\partial J}{\partial \theta}$$

(4) Integrate parts in nn_model

① Initialize parameters

parameters = initialize_parameters(n_x, n_h, n_y)

② Loop

for i in range(0, num_iterations):

i. Forward propagation

A2.cache = forward_propagation(X, parameters)

ii. Cost function

cost = compute_cost(A2, Y, parameters)

iii. Backpropagation

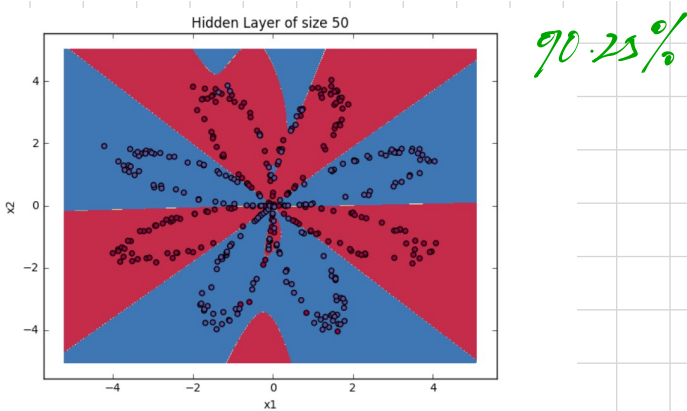
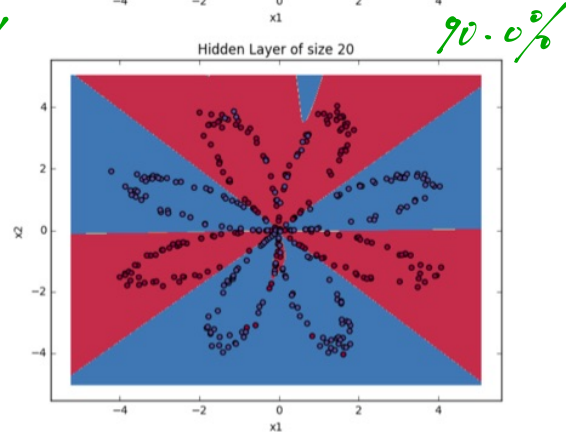
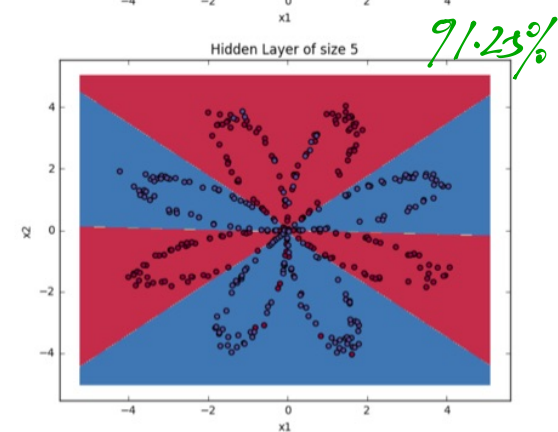
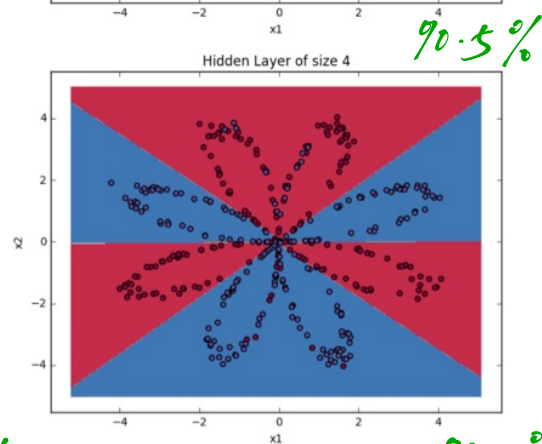
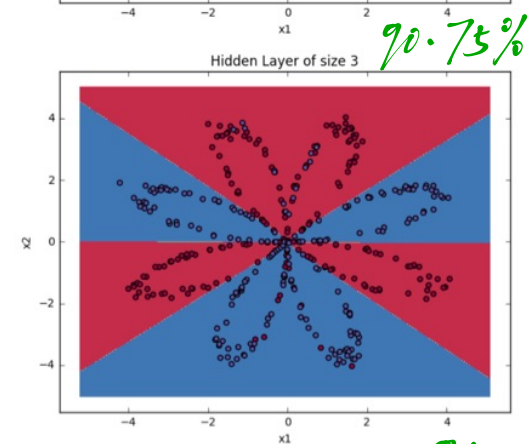
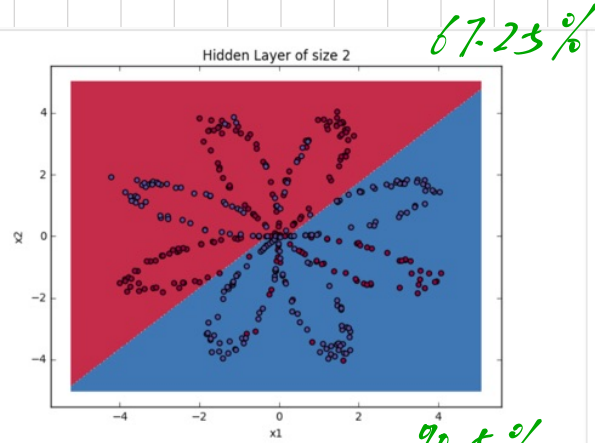
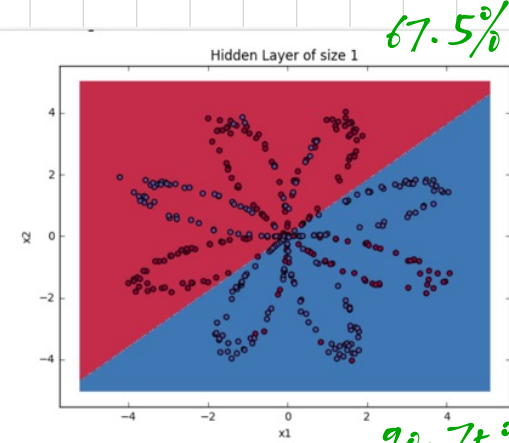
grads = backward_propagation(parameters, cache, X, Y)

iv. parameters update

parameters = update_parameters(parameters, grads)

(5) Turning hidden layer size

change the hidden layer size from 1 → 2 → 3 → 4 → 5 → 20 → 50



Interpretation:

The larger models (with more hidden units) are able to fit the training set better, until eventually the largest models overfit the data.

The best hidden layer size seems to be around $n_h = 5$. Indeed, a value around here seems to fit the data well without also incurring noticeable overfitting.

You will also learn later about regularization, which lets you use very large models (such as $n_h = 50$) without much overfitting.