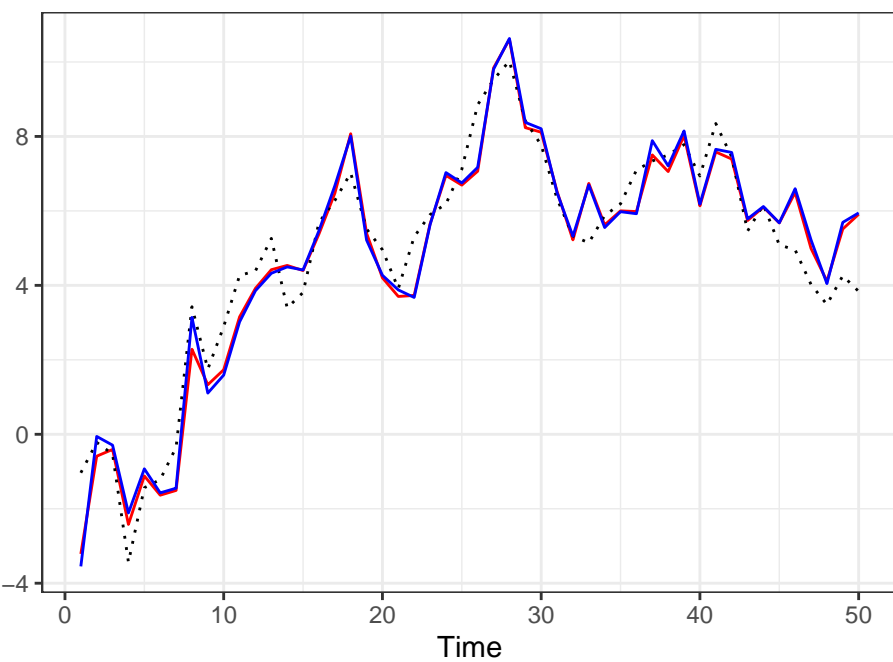
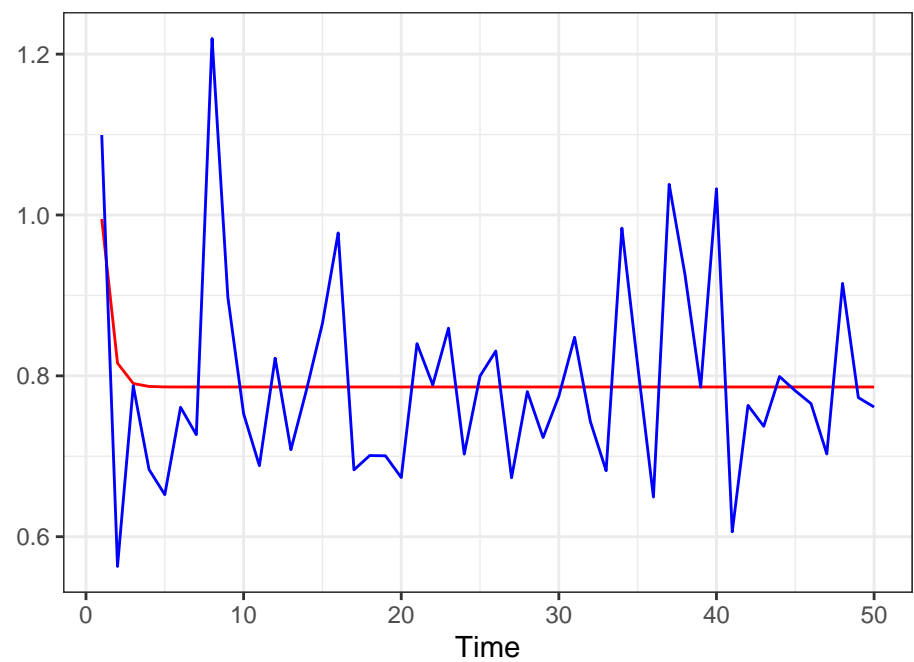
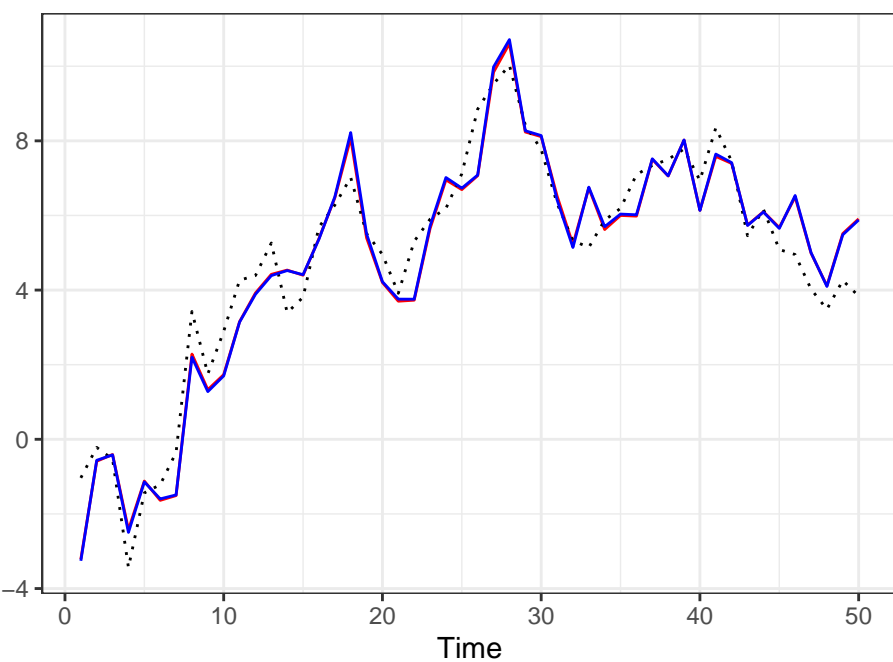


N=100**Filtered States**

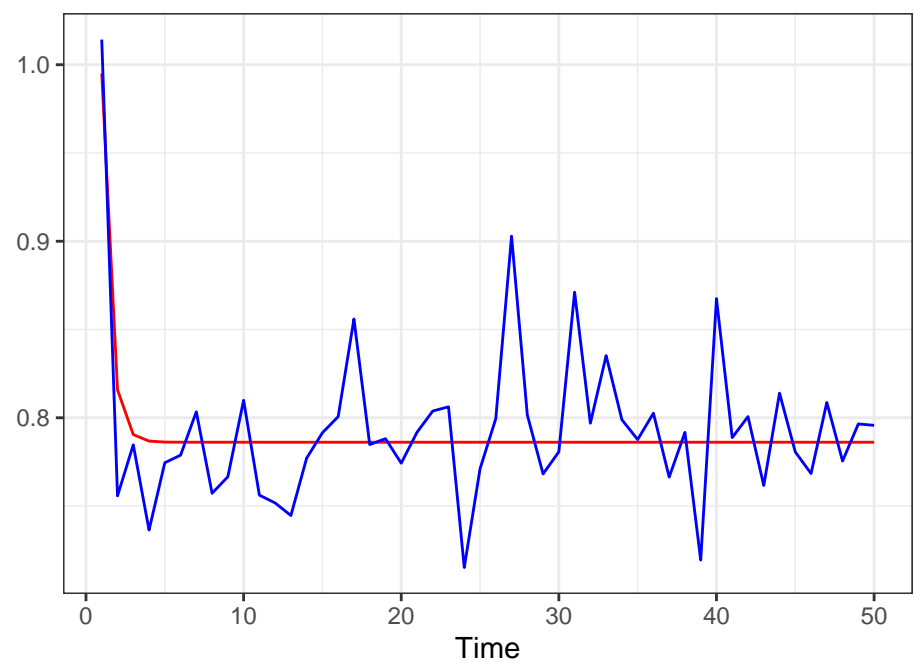
— KF ··· True States — BPF

Standard Deviation

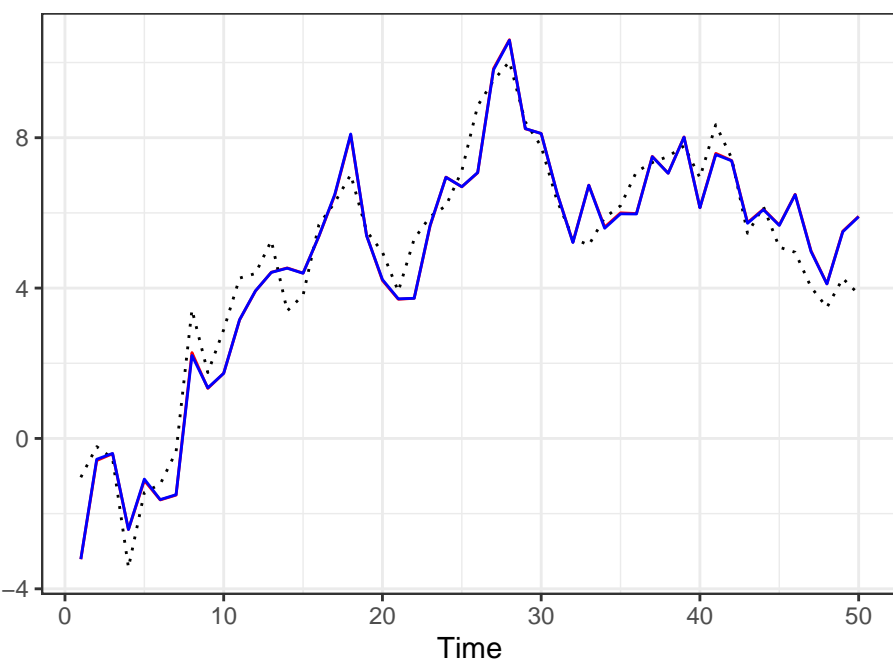
— KF — BPF

N=1000

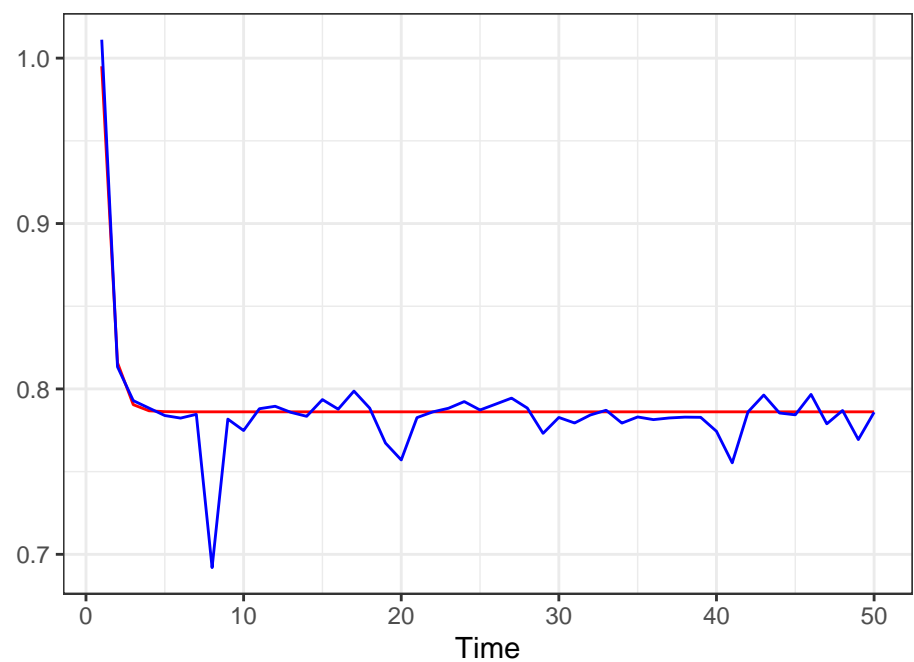
— KF ··· True States — BPF



— KF — BPF

N=10000

— KF ··· True States — BPF



— KF — BPF