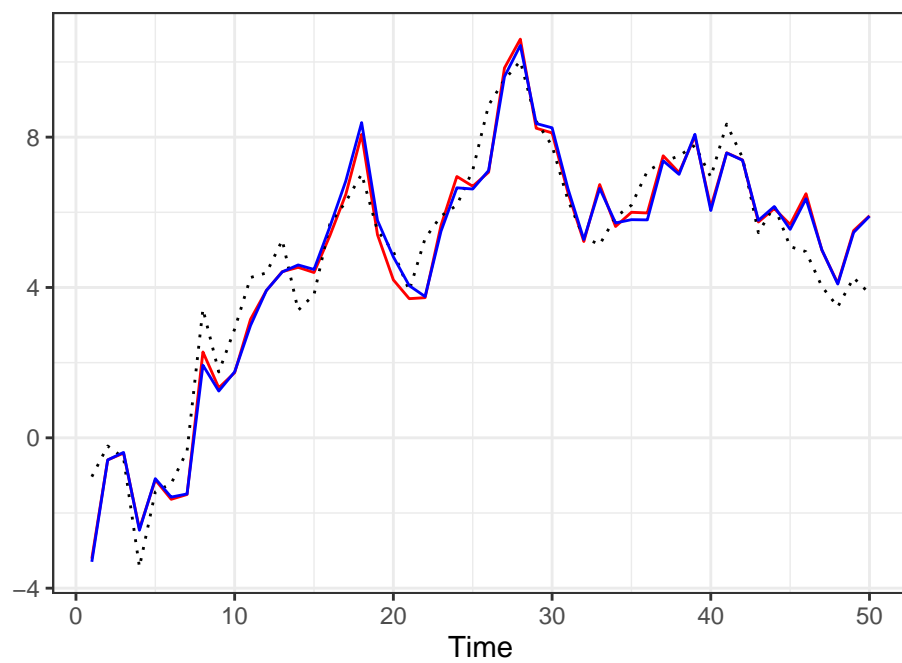


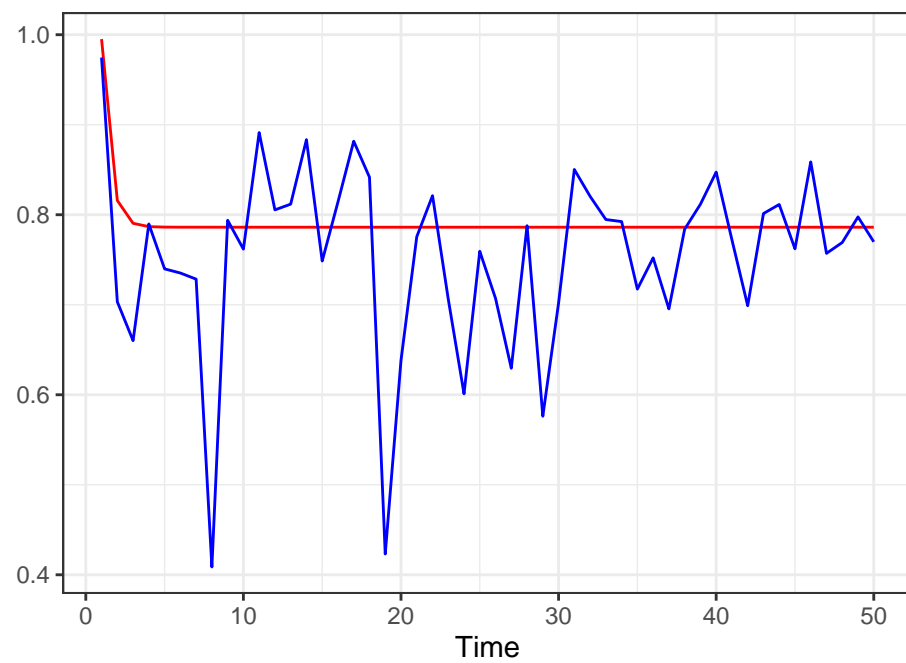
N=100

Filtered States

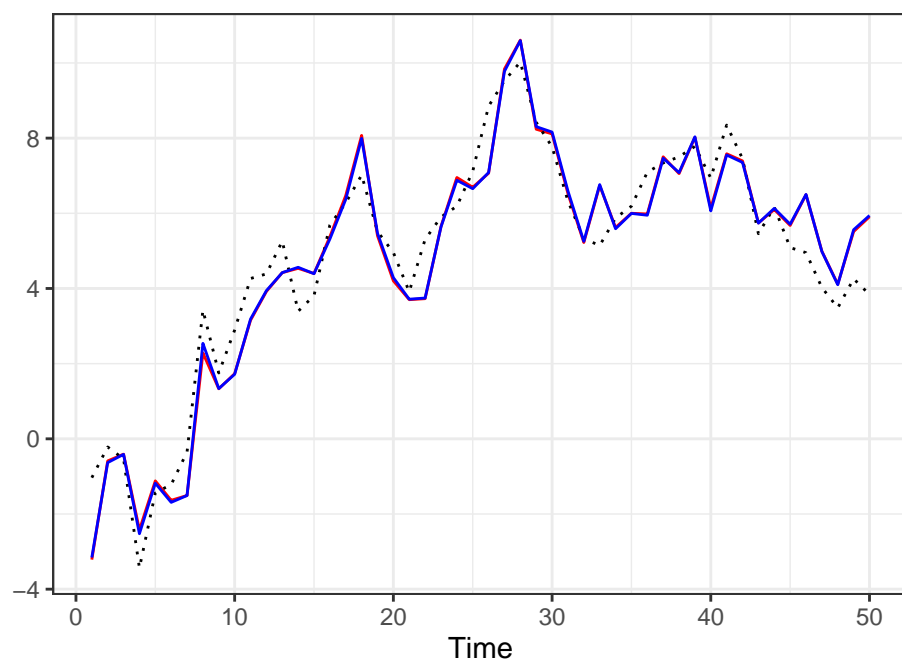


— BPF — KF ··· True States

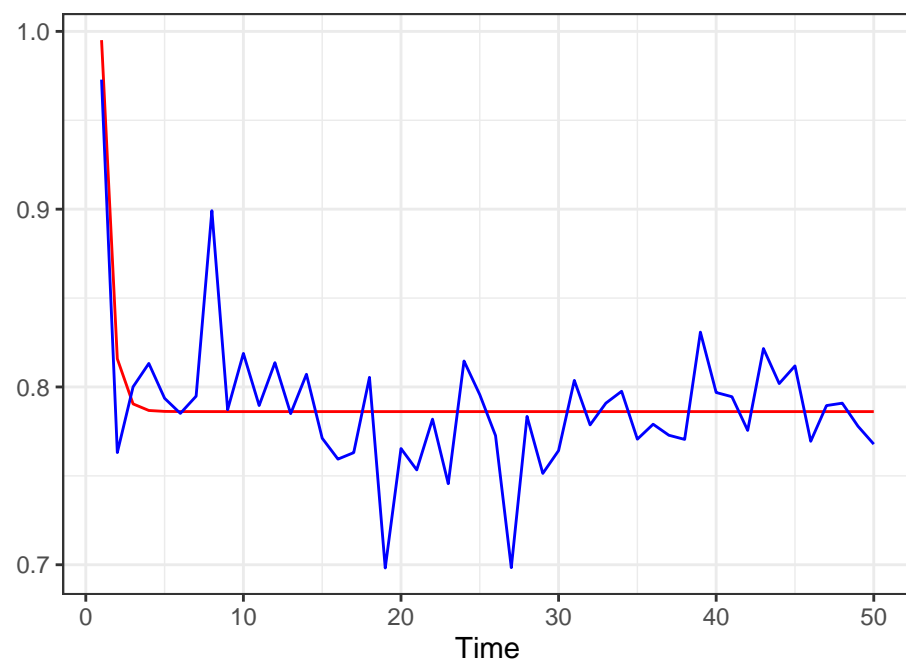
Standard Deviation



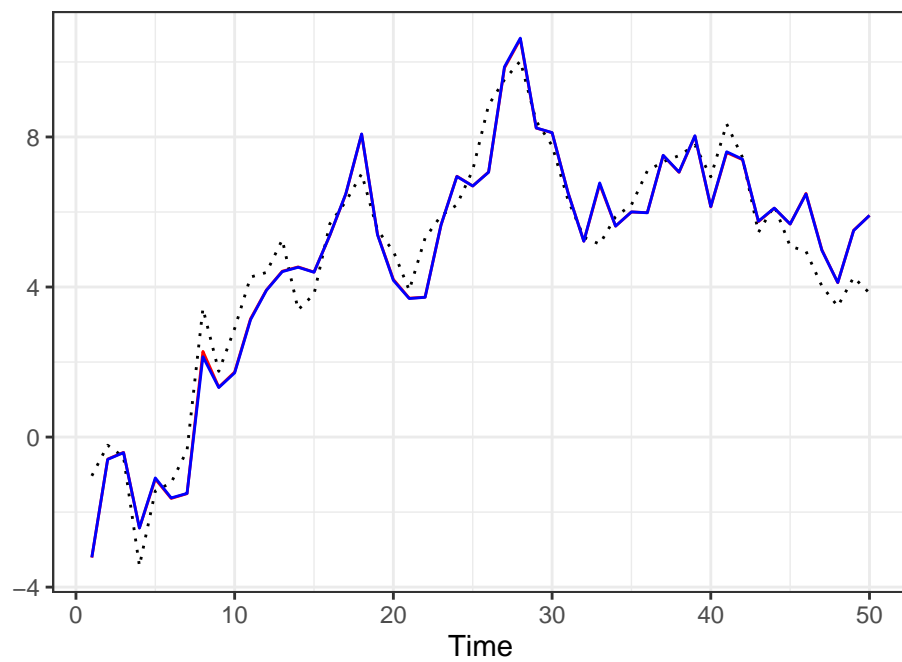
— BPF — KF

N=1000

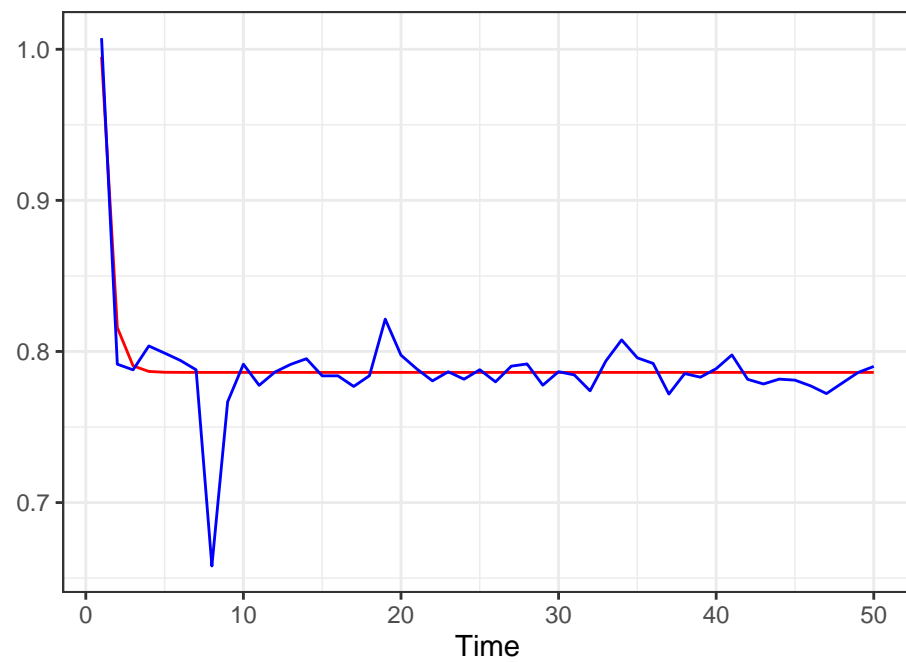
— BPF — KF ··· True States



— BPF — KF

N=10000

— BPF — KF ··· True States



— BPF — KF