

Graph Neural Networks: The Convolutional Layer

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A Comprehensive Survey on Graph Neural Networks

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Machine Learning on Networks?

Network Embedding

- Represent nodes as low dimensional vector;
- Preserve network topology structure as well as node content information;
- Use off-the-shelf ML algorithms.

GNN

- Develop ad hoc algorithm to address graph-related tasks.
- RecGNN, **ConvGNN**, GAE, GGAN, ...

Convolutional Neural Networks

2	4	9	1	4
2	1	4	4	6
1	1	2	9	2
7	3	5	1	3
2	3	4	8	5

Image

X

1	2	3
-4	7	4
2	-5	1

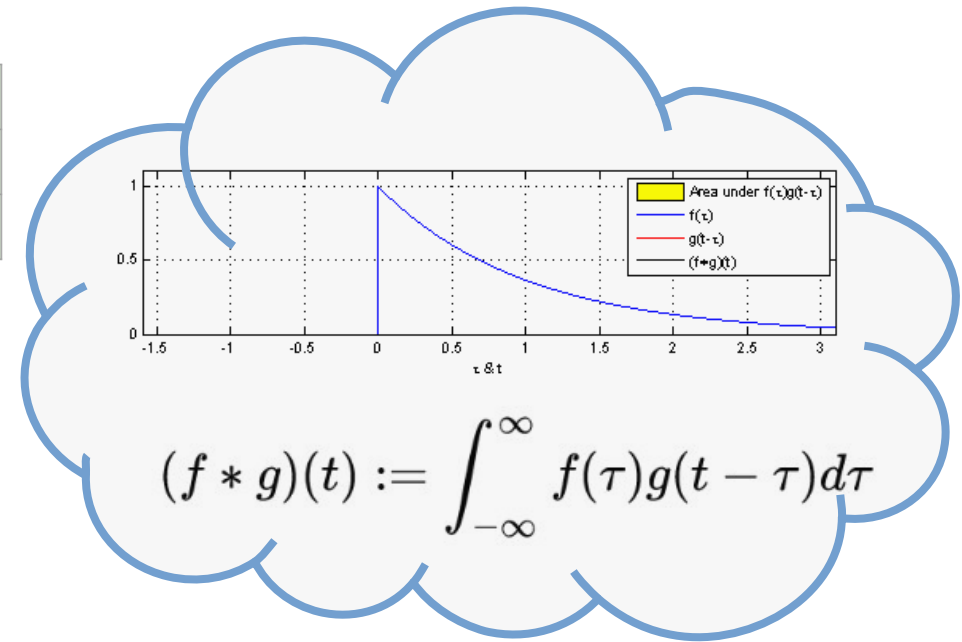
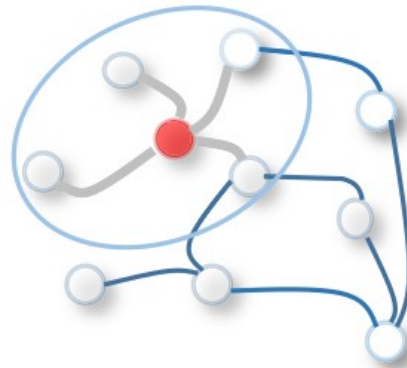
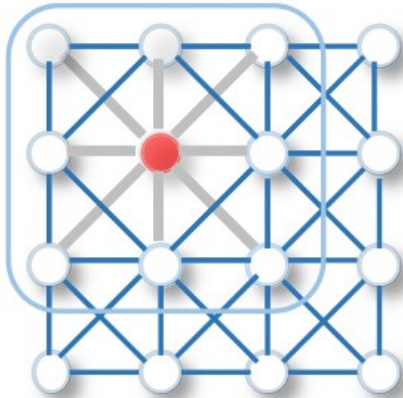
Filter /
Kernel

=

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Feature

Problem:



$$(f * g)(t) := \int_{-\infty}^{\infty} f(\tau)g(t - \tau)d\tau$$

What about non-euclidean spaces?

- *Spectral-based ConvGNN* ←
- *Spatial-based ConvGNN*

FCNN: Fourier Convolutional Neural Networks

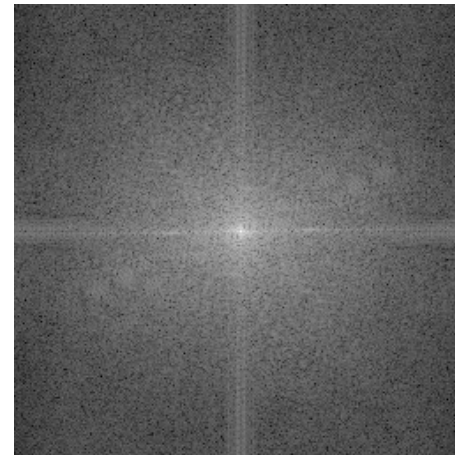
Harry Pratt, Bryan Williams, Frans Coenen, and Yalin Zheng

Convolution Theorem:

$$\mathcal{F}(\kappa * u) = \mathcal{F}(\kappa) \odot \mathcal{F}(u)$$



$$F(k, l) = \sum_{i=0}^{N-1} \sum_{j=0}^{N-1} f(i, j) e^{-i2\pi(\frac{ki}{N} + \frac{lj}{N})}$$



- Shift filter and multiply image by filter $\sim N^2$ times.

- Multiply image by filter one time;
- Calculate DFT for $N \times N$ image Cooley-Tukey $\rightarrow N \cdot \log(N)$;
- Very efficient pooling.

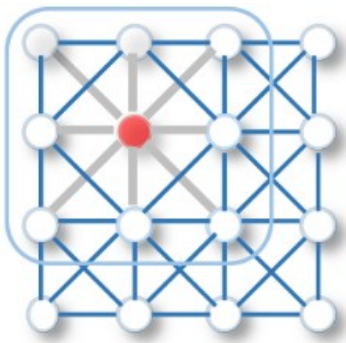
Same thing applied on Graphs

For a graph with n vertices:

$$\mathbf{L} = \mathbf{I}_n - \mathbf{D}^{-(1/2)} \mathbf{A} \mathbf{D}^{-(1/2)} \quad \text{Symmetrically normalized laplacian}$$

$$\mathbf{L} = \mathbf{U} \mathbf{\Lambda} \mathbf{U}^T \quad \mathbf{U} = [\mathbf{u}_0, \mathbf{u}_1, \dots, \mathbf{u}_{n-1}] \in \mathbf{R}^{n \times n} \quad \text{Spectral decomposition}$$

Let $\mathbf{x} \in \mathbf{R}^n$ be a graph signal, each entry x_i is the value of the signal for the i -th node.

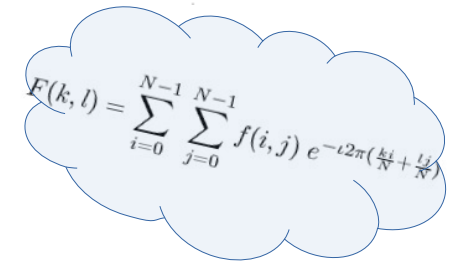


Using an analogy, this can be viewed as the greyscale value of the pixel in a matrix-like graph.

Same thing applied on Graphs

The graph Fourier Transform of a signal is defined as: $\mathcal{F}(\mathbf{x}) = \mathbf{U}^T \mathbf{x}$

And the inverse Fourier Transform: $\mathcal{F}^{-1}(\hat{\mathbf{x}}) = \mathbf{U} \hat{\mathbf{x}}$


$$F(k, l) = \sum_{i=0}^{N-1} \sum_{j=0}^{N-1} f(i, j) e^{-i2\pi(\frac{ki}{N} + \frac{lj}{N})}$$



The graph convolution of the input signal \mathbf{x} with a filter $\mathbf{g} \in \mathbf{R}^n$ is:

$$\begin{aligned} \mathbf{x} *_G \mathbf{g} &= \mathcal{F}^{-1}(\mathcal{F}(\mathbf{x}) \odot \mathcal{F}(\mathbf{g})) \\ &= \mathbf{U}(\mathbf{U}^T \mathbf{x} \odot \mathbf{U}^T \mathbf{g}) \end{aligned}$$

$$\left\{ \mathbf{x}_1 \odot \mathbf{x}_2 = \text{diag}(\mathbf{x}_2) \mathbf{x}_1 \right\}$$

Let $\mathbf{g}_\theta = \text{diag}(\mathbf{U}^T \mathbf{g})$  $\mathbf{U}(\mathbf{U}^T \mathbf{x} \odot \mathbf{U}^T \mathbf{g}) = \mathbf{U} \mathbf{g}_\theta \mathbf{U}^T \mathbf{x}$

SEMI-SUPERVISED CLASSIFICATION WITH GRAPH CONVOLUTIONAL NETWORKS

Thomas N. Kipf

Max Welling

$$g_{\theta} \star x = U g_{\theta} U^{\top} x$$

Where $g_{\theta} = \text{diag}(\theta)$ is a filter parametrized by $\theta \in \mathbb{R}^N$ in the **Fourier domain**.
 g_{θ} is a function of the eigenvalues of the laplacian: $g_{\theta}(\Lambda)$.

PROBLEM

- Multiplication with the eigenvector matrix U is $O(N^2)$;
- Computing the eigendecomposition of L might be prohibitively expensive for large graphs.

SOLUTION

$g_{\theta}(\Lambda) \rightarrow$ Expansion in terms of the Chebychev polynomials, truncated to the first order. [Hammond et. al (2011)]

The Convolutional Layer

$$g_\theta \star x \approx \theta \underbrace{\left(I_N + D^{-\frac{1}{2}} A D^{-\frac{1}{2}} \right)}_{\text{Has eigenvalues } \leq 2 \rightarrow \text{Exploding Gradients}} x$$

Has eigenvalues $\leq 2 \rightarrow$ Exploding Gradients

Renormalization: $I_N + D^{-\frac{1}{2}} A D^{-\frac{1}{2}} \rightarrow \tilde{D}^{-\frac{1}{2}} \tilde{A} \tilde{D}^{-\frac{1}{2}}$

$$\tilde{A} = A + I_N \text{ and } \tilde{D}_{ii} = \sum_j \tilde{A}_{ij}$$

Generalize for signal $X \in \mathbb{R}^{N \times C}$: $Z = \tilde{D}^{-\frac{1}{2}} \tilde{A} \tilde{D}^{-\frac{1}{2}} X \Theta$

where $\Theta \in \mathbb{R}^{C \times F}$ is a matrix of filter parameters \rightarrow learnable weights
and $Z \in \mathbb{R}^{N \times F}$ is the convolved signal matrix.

Complexity: $\mathcal{O}(|\mathcal{E}|FC)$

The Convolutional Layer

FINAL STEP: Apply non-linearity

$$H^{(l+1)} = \sigma\left(\tilde{D}^{-\frac{1}{2}} \tilde{A} \tilde{D}^{-\frac{1}{2}} H^{(l)} W^{(l)}\right)$$

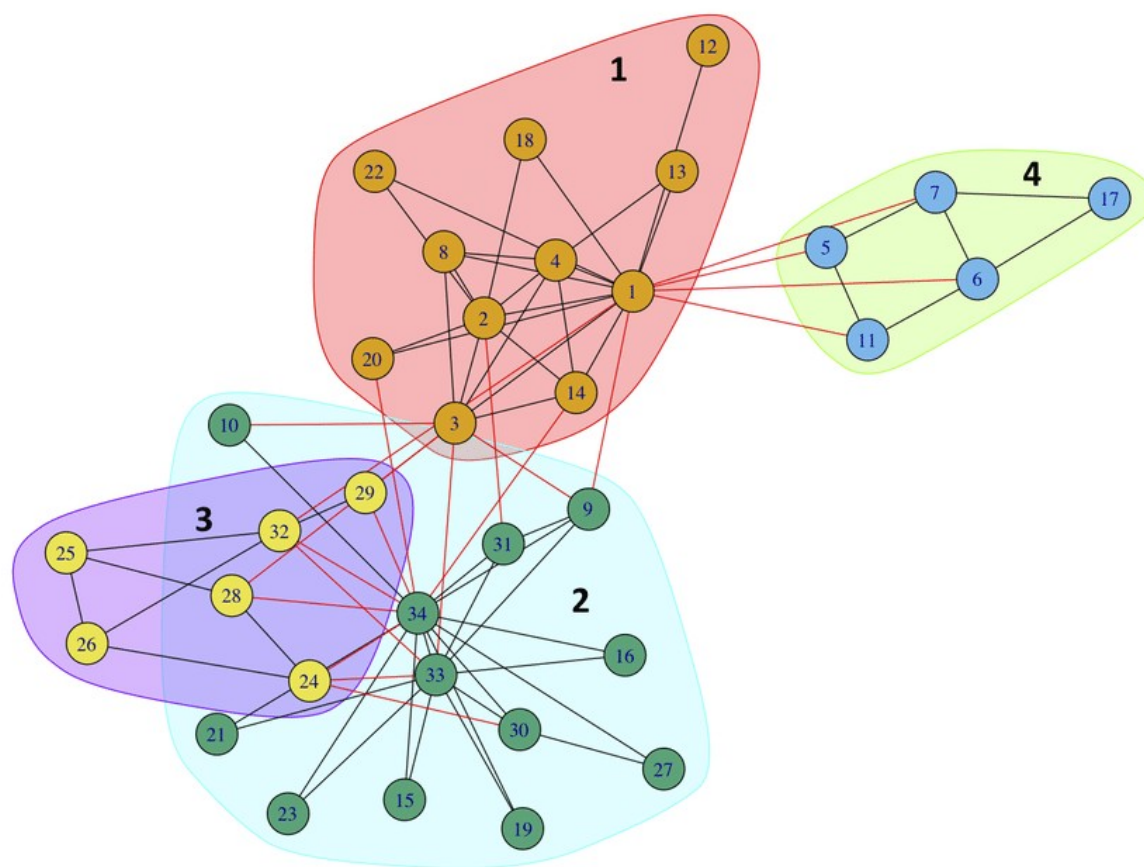
EXAMPLE: If we consider a two-layer GCN for semi-supervised node classification task we will have

$$Z = f(X, A) = \text{softmax}\left(\hat{A} \text{ReLU}\left(\hat{A} X W^{(0)}\right) W^{(1)}\right)$$

with $\hat{A} = \tilde{D}^{-\frac{1}{2}} \tilde{A} \tilde{D}^{-\frac{1}{2}}$.

Zachary's Karate Club?

$$Z = f(X, A) = \text{softmax}\left(\hat{A} \text{ReLU}\left(\hat{A}XW^{(0)}\right)W^{(1)}\right)$$



Questions?

Thanks for listening.