

# Emotion Recognition

Edoardo De Matteis

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# 1 Task and motivations

Facial emotion recognition [2] is the process of analyzing someone’s human state from facial expressions, the human brain does it automatically but developing software able to recognize human emotions is a growing topic in research, the technology is constantly improving and some people are confident machines will be able to read emotions as our brains do . Emotion AI has a wide range of use cases from scanning for signs of terrorism [12] to emotion judgement for commercial purposes as *Disney* did, or at least wanted to do, for the release of *Toy Story 5* [7].

But all that glitters is not gold and these technologies could be a threat to freedom and equality [3], in China *Hanwang Technology* deployed a system that tracks students’ behaviour during lessons and analyzes their actions to infer if they’re keeping attention or not [5]. This software seems to be unefficient and based on pseudoscientific assumptions, however these allegations didn’t stop *Amazon*, *Microsoft* and *Google* from offering emotion recognition to their customers. Even though the first two companies claim that their product can’t determine a person’s internal emotional state from only facial expressions [9].

Other than the ethical dilemma that arises from these technologies is important to note how these are not real emotion recognition systems. In the same way this project will not recognize real emotions but rather expressions, to be precise it aims to differentiate positive expressions from negative ones. With this abuse of terminology let’s proceed describing the strategy adopted against that task.

# 2 Strategy

To recognizing a facial expression first a face is needed, in the online demo facial detection is achieved through Haar cascade classifiers while in offline developing it has been done automatically by *Dlib*’s landmark detection. To extract features at first I considered using LBP histograms but since I was interested only in facial expressions it seemed reasonable to use landmark points. The key idea is that similar expressions have a similar position on different faces, then through an SVM classifier it could be possible to predict someone’s ”emotion”<sup>1</sup>. In figure 2.1 is displayed how landmark points are disposed in the pretrained model [6], for our purposes we’re not considering all points but only ones defining the eyes and the mouth (i.e. points from 37 to 68); it is possible for the user to define an arbitrary list of points and the algorithm will locate them. I’m aware that this approach is not the state of the art and that to get good results is recommended to use neural networks [1], anyway I was interested in using SVM classifiers and seeing how they would perform.

The adopted dataset is the *First Affect-in-the-Wild* (affwild) [8], it consists of 298 videos of which 252 for training and 46 for testing. I ignored videos in the train set since there are no responses associated, such responses are defined

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<sup>1</sup>As said earlier someone’s emotions are more deep than just their facial expression.

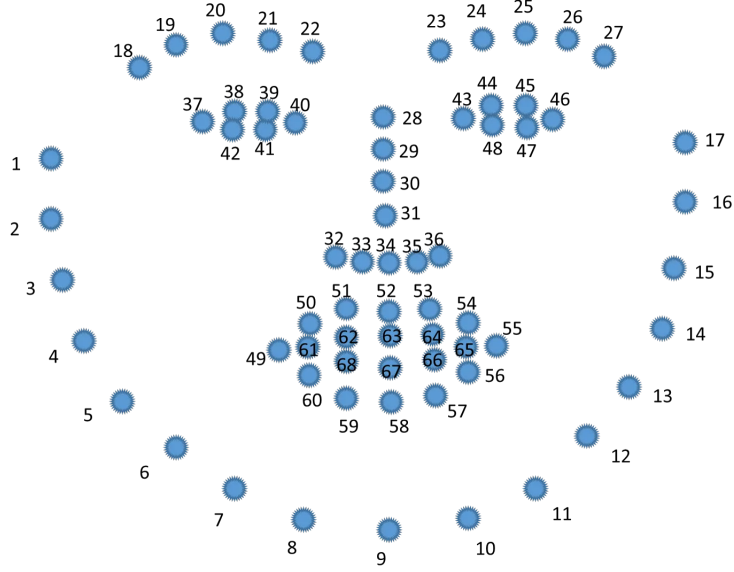


Figure 2.1: Face landmark points from [11].

for each frame in which a face is identified. In the dataset are stored bounding boxes too but since I was interested in landmark points, and the detection is done by *Dlib* I just discarded them.

Emotions are defined as points on a two dimensional cartesian plane where the abscissa is the *valence*, it expresses if an emotion is positive or negative, and the ordinate is the *arousal*, it discriminates animated emotions from languid ones. An example of this plane can be seen in figure 2.2, in which 4 different emotions are defined but is possible to have more. To avoid possible performance reduction due to discrimination between too many classes, and considering also that SVMs in their purest form are binary classifiers, it came natural to me to just consider only one response. I chose valence since it may be more interesting to distinguish between positive and negative expressions rather than exciting or not ones.

### 3 Design

I decided to code in *Python* with the external library *OpenCV* for simplicity. Since I do not use the bounding boxes in the affwild dataset, the first thing I need to get is a correspondence between landmark points and the valence for each frame of each video, the execution took almost 21 hours so I made possible to save the results as text files.

Each valence ranges from -1 to 1 and values ranging between  $-0.5$  and  $0.5$  were discarded, it has been done to reduce noise and rule out uncertain

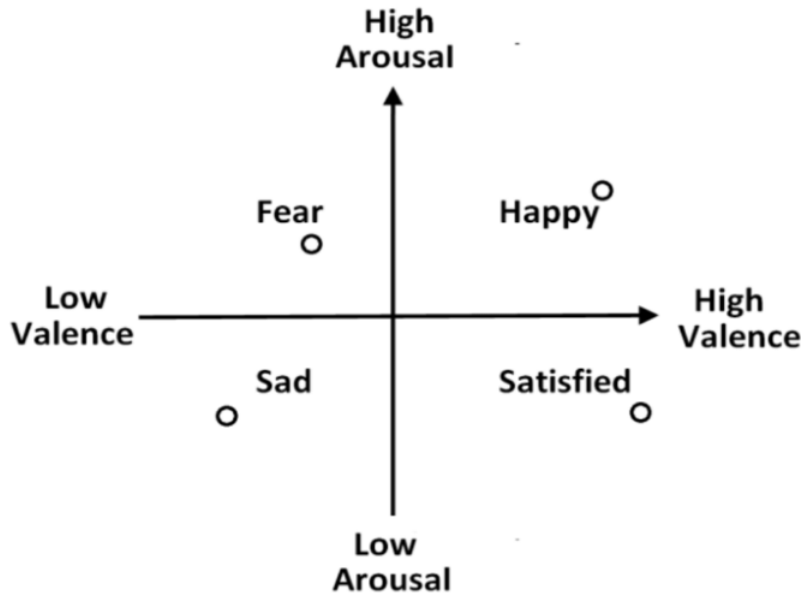


Figure 2.2: Emotion classification model from [13].

valences; in the end were extracted 136909 landmark-valence tuples. Is possible for a single frame to contain more than one face as seen in figure 3.1<sup>2</sup>. Since the affwild dataset collects videos with foreground faces is reasonable to assume that the face we're interested in is the widest one, hence I pick the landmark feature with the largest euclidean distance between the first and last point (respectively the lateral commissure of the viewer's left eye and the lower lip).

Valences are saved and read as an array of floats while landmarks are a two dimensional array. For each face dlib stores landmark points as an array of  $[x, y]$  coordinates, to make things more readable (and possibly to make the code faster in corner cases due to caching) I decided to flatten it as a one dimensional vector. This different encoding should not change SVM's predictions.

Regarding SVM classification I first used both the OpenCV implementation and the *scikit-learn* one, the latter is way better than the first and for this reason the demo uses the scikit-learn SVM. During tests the dataset has been splitted as 80-20 percent for train and test respectively, it comes without saying that demo's SVM classifier is trained over the whole dataset.

As said before in the demo instead of directly detecting landmark points I first detected bboxes. This may be odd but I noticed how given an arbitrary frame there is more probability to detect a face with dlib's landmarks than with OpenCV's haar cascade, detecting less landmarks makes the demo less precise but also makes the video smoother for a presentation. Were used pretrained

<sup>2</sup>I find bounding boxes less invasive, in this case landmark detects two faces as well.

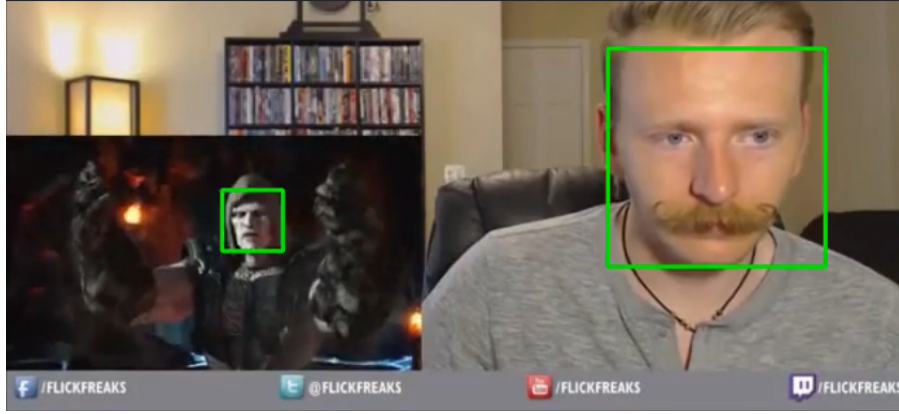


Figure 3.1: Two faces detected in the video 309.

models both for bounding boxes [10] and landmark points [6].

The structure of classes and packages can be seen in the diagram in figure 3.2, it is all original code except the function `src.test.Test.plot_roc` used to plot ROC curves. It has been taken from [4] as commented in the source code.

Other code that is not original are clearly external functions, see table 1

Table 1: Imported libraries

<b>os</b>	To explore the filesystem.
<b>re</b>	For regular expressions.
<b>fire</b>	To implement command line arguments.
<b>numpy</b>	Arrays are essential thanks to the faster C implementation.
<b>cv2</b>	OpenCV, used for detection with Haar features and SVM.
<b>dlib</b>	In Python OpenCV landmark detection is not implemented.
<b>sklearn</b>	Scikit-learn implements a more efficient SVM classifier.
<b>joblib</b>	Used to save scikit-learn's SVM model.

## 4 Performance evaluation

The SVM classifier implemented in the scikit-learn library uses a RBF kernel (equation 1), on the other hand in OpenCV is possible to choose which kernel to use and eventually the degree of the model.

$$K(x, x') = \exp\left(\frac{\|x - x'\|^2}{2\sigma^2}\right) \quad (1)$$

Comparing these two classifiers with the same kernel the scikit-learn's one offers better performances, in figure 4.1 are displayed the confusion matrices for

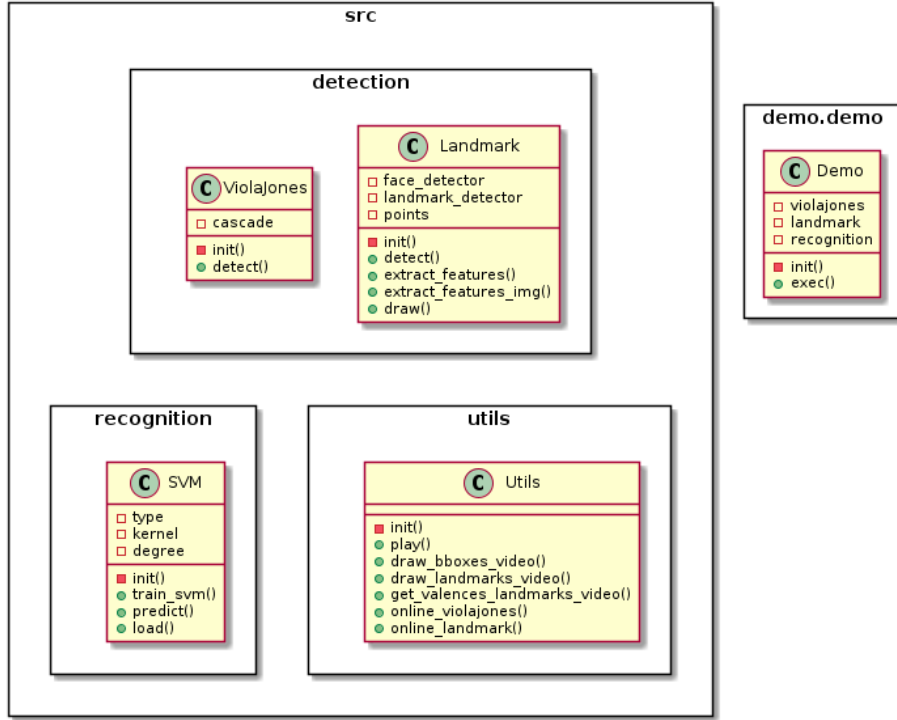


Figure 3.2: Diagram of the packages.

both of them and in table 2 relative scores.

Table 2: Scores for the classifiers.

	scikit-learn	OpenCV
Accuracy	0.805	0.491
Precision	0.814	0.421
Recall	0.639	0.860
F1	0.358	0.283

They're not particularly good, except maybe accuracy and precision, but is clear how scikit-learn's classifier is more balanced. Even in recall, where OpenCV performs better, the difference is less significant with respect to cases in which scikit-learn is better.

In image 4.2 the ROC curves for the scikit-learn SVM classifier and OpenCV ones are plotted. For OpenCV were considered three different classifiers: a linear one, a polynomial one with degree 3 and, for comparison, an RBF one.

The polynomial one has terrible performances, is like throwing chances <sup>3</sup>,

<sup>3</sup>With an AUC of 0.5

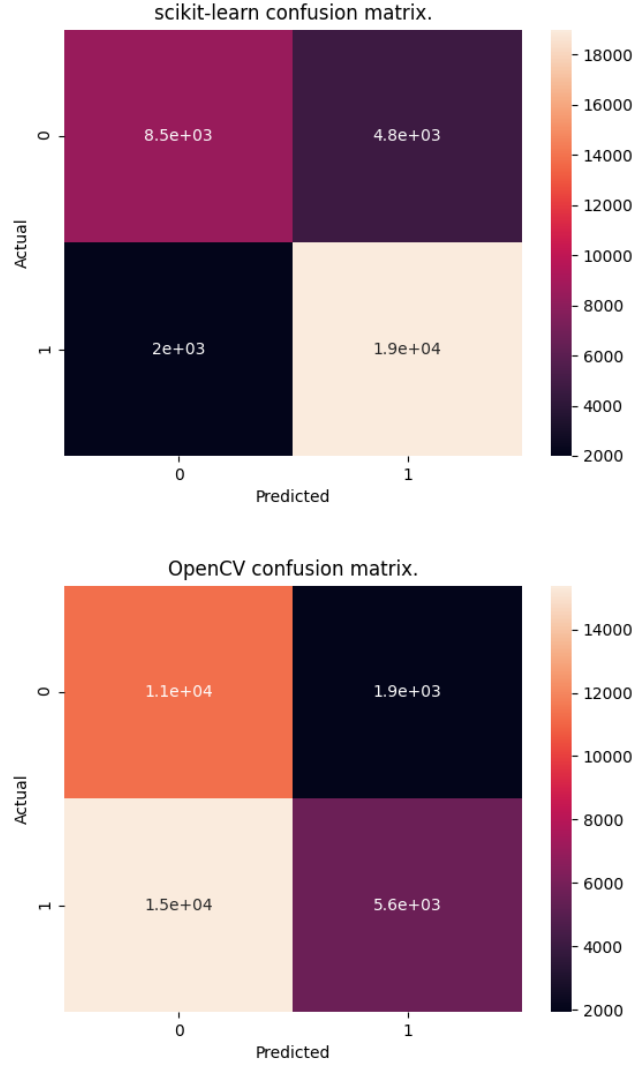


Figure 4.1: Confusion matrices.

while the linear and RBF ones overlap each other with quite better performances. Again the best performing classifier is the scikit-learn with a RBF kernel, the AUCs are displayed in table 3.

Also the DET curves for the scikit-learn and OpenCV, both with the RBF kernel, were plot in figure 4.3 and again the scikit-learn model is better than the OpenCV one.

On figure 4.4 are plotted the false positive and the false negative error rates,

Table 3: Scores for the classifiers.

	scikit	OpenCV
AUC	0.774	0.560

the intersection point is the equal error rate (EER) and the ideal threshold seems to be 1.25. Keep in mind that these two error rates are plotted against only three thresholds so this value does not necessarily match the best threshold. The EET is identified only for the scikit-learn SVM since it is the best model so far.

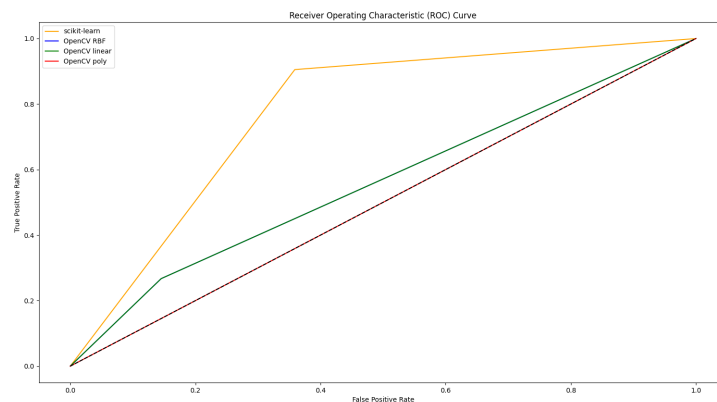


Figure 4.2: ROC.

## 5 Conclusions

Starting from the fact that I did not expect too high performances a 76% AUC is not too bad, unfortunately I did not find any notebook or any other software to compare mine with. I expected the polynomial kernel to be better than the linear one and I was surprised of how a degree of 3 makes the model overfit.

Last the online demo seems to work better under precise conditions: is recommended to make the face visible for face detection, glasses too can compromise the expression identification. Brightness is crucial, not only for the emotion recognition phase but, if the background features clutter, for the face detection too. After some experiments I noticed how the ideal distance is along 22 centimeters from the webcam, if the distance is shorter there can be false positive face detections and if it is shorter or higher then the emotion recognition tends to fail and stick to an emotion. Another interesting point is that three-quarter poses tend to be recognized as positive emotions even when they're not, this



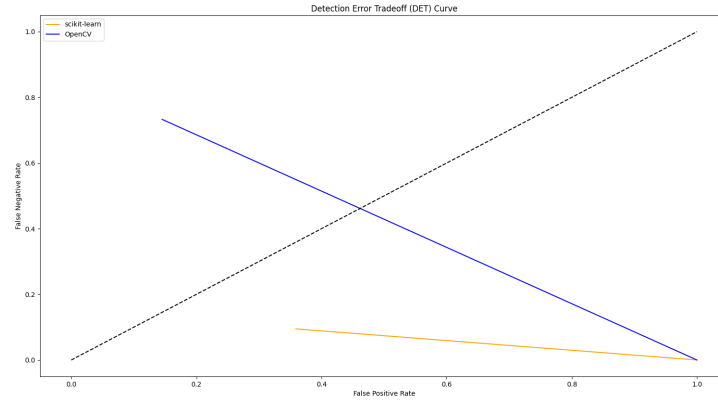


Figure 4.3: DET.

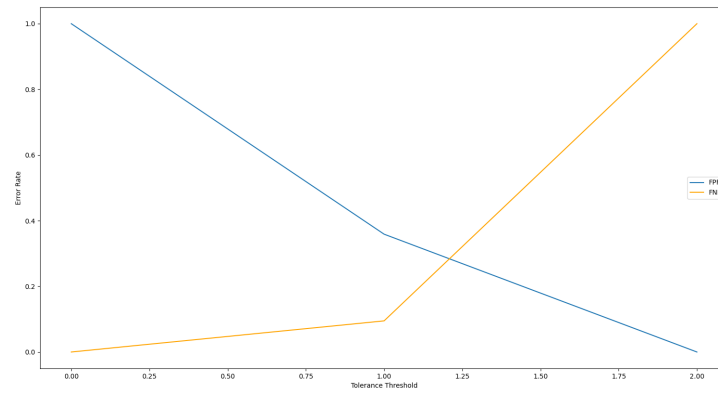


Figure 4.4: EET.

could be due to a selection bias in the dataset.

## 5.1 Future works

It could be possible to implement a classifier that predicts both valence and arousal, it could be done with a SVM multiclass classifier that uses softmax regression or with two binary SVMs. Another possible improvement could be implementing the emotion detection with a neural network and see how results compare.

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