

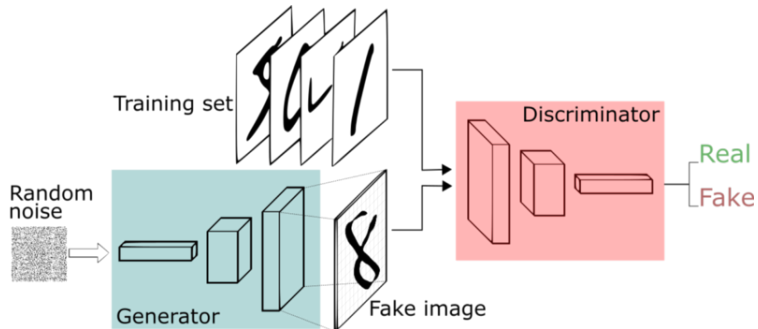
cDCGAN

conditional Deep Convolutional Generative Adversarial
Networks

Edoardo De Matteis

Generative adversarial networks

The idea behind generative models is to learn a distribution from training data and generate new samples from it. GANs do it setting up a zero-sum game between a **discriminator** and a **generator**.



DCGAN

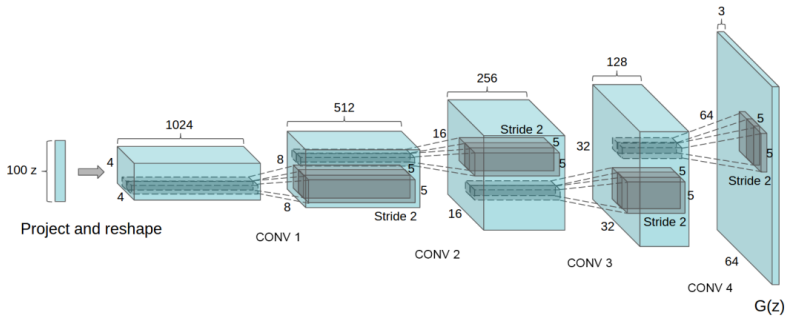
GANs were first introduced based only on FC layers, it came natural to extend them with convolutions when dealing with images.

To make them more stable to train we can constraint their architectural topology.

Architectural guidelines

- *All-convolutional net* i.e. replace deterministic spatial pooling with strided convolutions, allowing the network to learn its own spatial downsampling/upsampling.
- Eliminate fully connected layers on top of CNNs in favor of deeper architectures.

- Use of batch normalization in both the generator and discriminator, yet the first could be made unstable.
- Use ReLU activation in generator for all layers except for the output, which uses Tanh, and use LeakyReLU activation in the discriminator for all layers.



Results

It is hard in general to train GANs, after a few epochs with a small learning rate the generator learns well general features, yet it still far from realism.

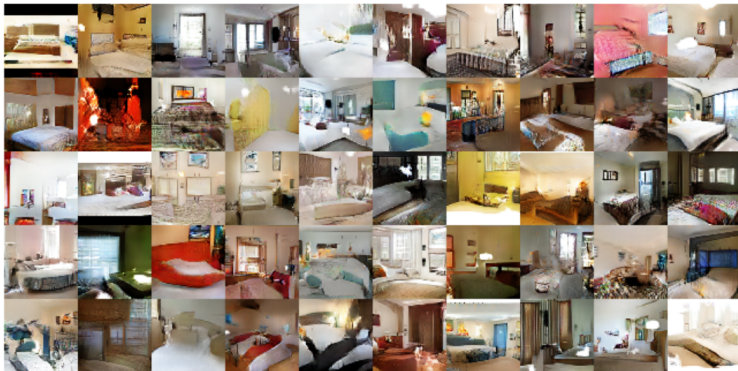
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LSUN



cGAN

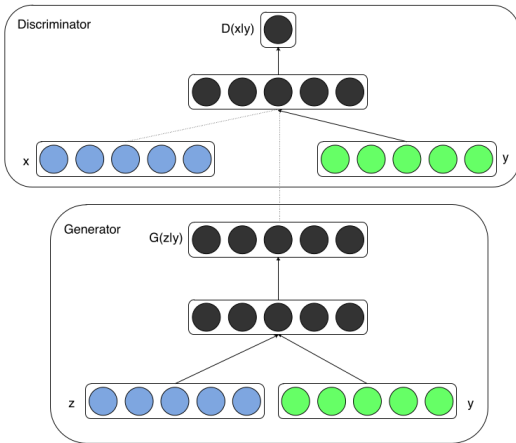
One issue with GANs is that we cannot choose which output we get, however by conditioning the model on additional information is possible to direct data generation.

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cDCGAN

Combine the strengths of three models:

- *GAN*: Great generative model.
- *DCGAN*: Strong priors on images.
- *cGAN*: Conditional model.

Motivations

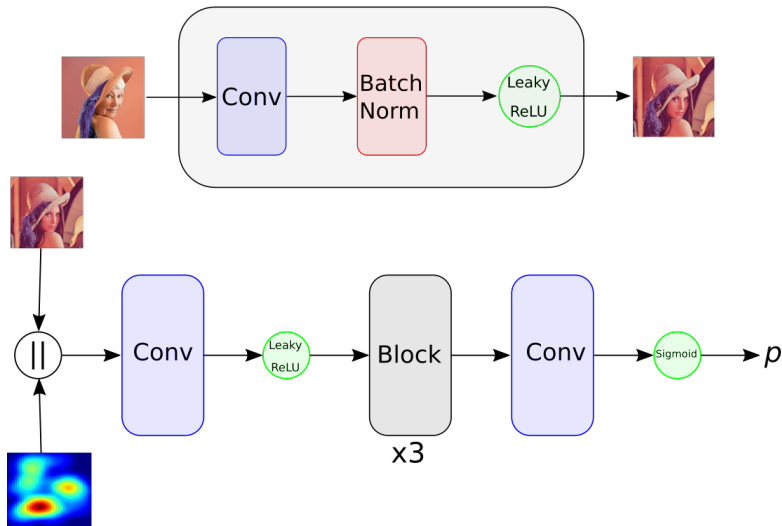
- Adding conditional data can have a regularizing effect.
- Specialized data enrichment.
- Entertainment e.g. *FaceApp*.
- Integration with other branches e.g. text to image.
- ...

Dataset

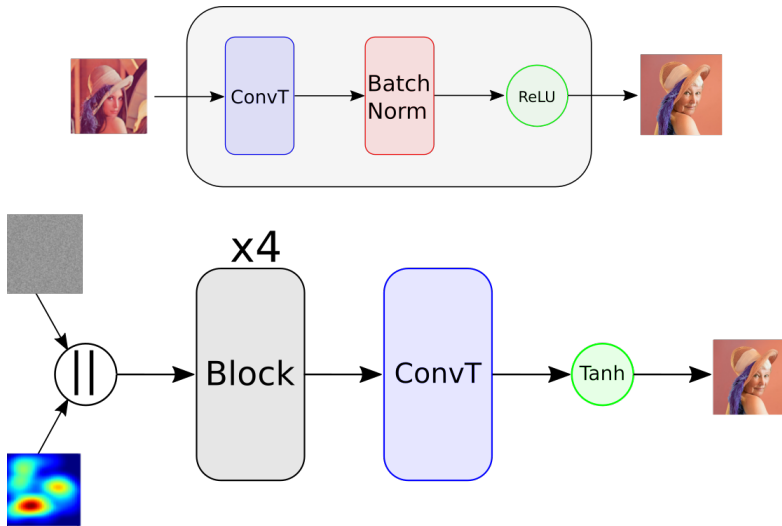
- MNIST.
- FashionMNIST.
- CIFAR10.

Data normalized by z-score and resized to 64×64 resolution.
Random samples have dimension 64 and conditioning is directly concatenated as a channel to input vectors.

Discriminator



Generator



Loss

$$\mathcal{L}_{GAN} = \min_{\gamma} \max_{\delta} \mathbb{E}_{x \sim p_d} \log D(x) + \mathbb{E}_{z \sim \mathcal{N}} \log(1 - D(G(z))) \quad (1)$$

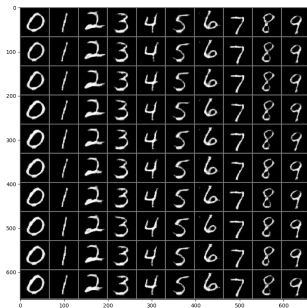
$$BCE = -\frac{1}{N} \sum_{i=1}^N y_i \log(f(x_i)) + (1 - y_i) \log(1 - f(x_i)) \quad (2)$$

We define the ground truth on real and fake data as a vector of ones and zeros respectively.

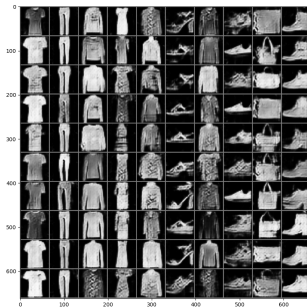
MNIST



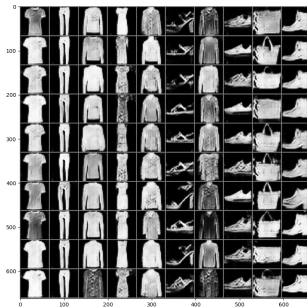
Weighting conditioning



FashionMNIST



Doing the same...



Multiclass conditioning

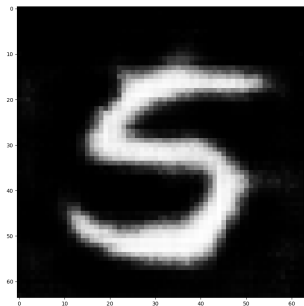


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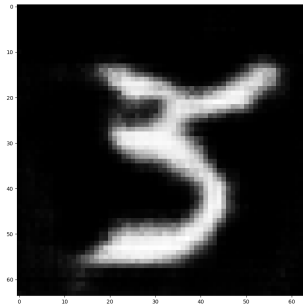


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With different weights

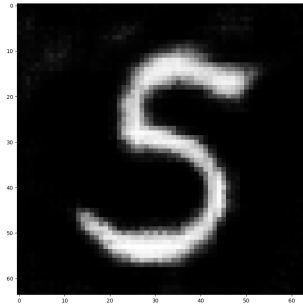


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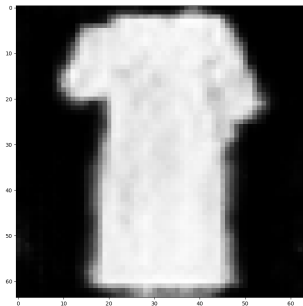
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The same on FashionMNIST

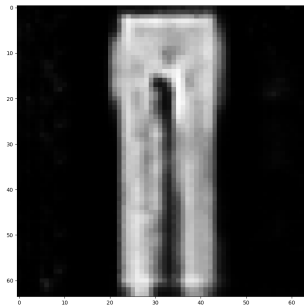


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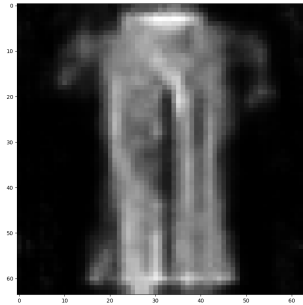


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Thank you

References



A. Radford, L. Metz, S. Chintala

Unsupervised representation learning with deep convolutional generative adversarial networks.



M. Mirza, S. Osindero

Conditional generative adversarial nets.