STM32 course

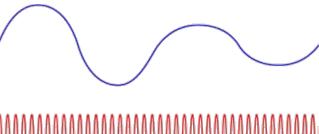
Timers as output

Outline

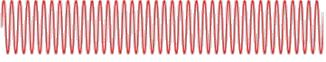
- Introduction to what is modulation
- What is PWM (briefly)
- Timer schematic diagram overview
- Time Base Unit and Output Compare Unit register sets
- PWM Zoo
- Advanced features

Analog modulation

Modulating Wave



Carrier Wave



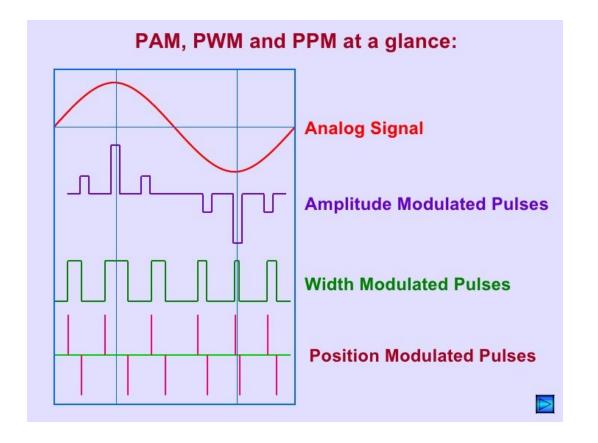
Amplitude Modulation



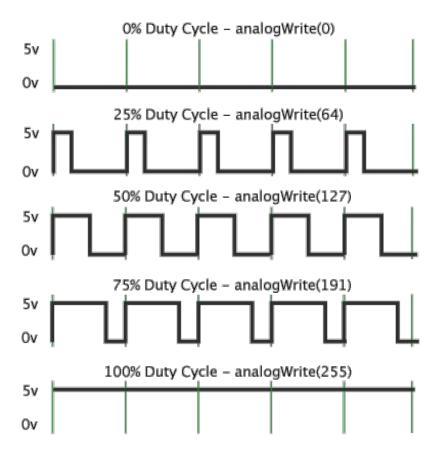
Frequency Modulation



Digital modulation



PWM

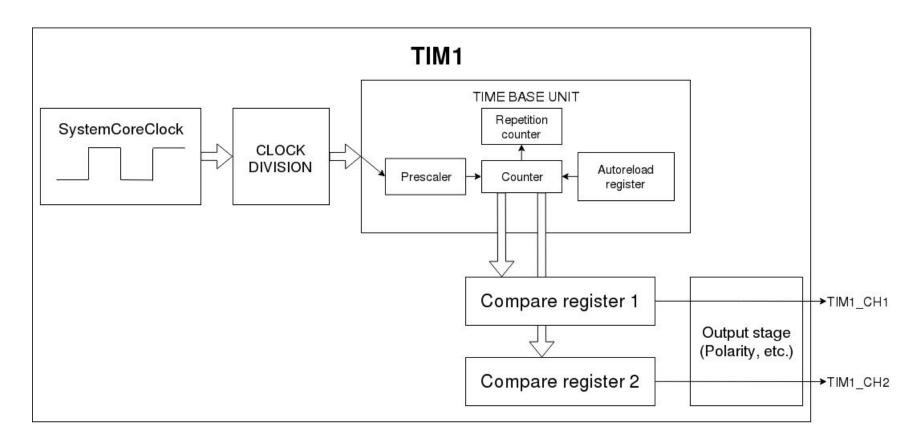


PWM parameters

- Frequency Time Base Unit
- Duty cycle Output Compare Unit
- Accuracy Time Base Unit

Each timer has one TBU and several OCUs - channels.

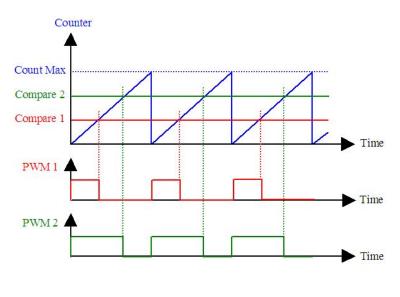
Timer schematic diagram



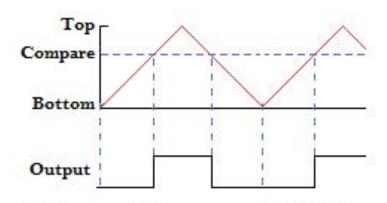
Time Base Unit registers

- Counter register
- Counter mode register (UP/DOWN/CENTER)
- Autoreload register
- Clock division register
- Prescaler register
- Repetition counter

Counter Mode



UP or DOWN



Phase Correct PWM

CENTER_UP, CENTER_DOWN or CENTER_UP_DOWN

Output Compare Unit registers

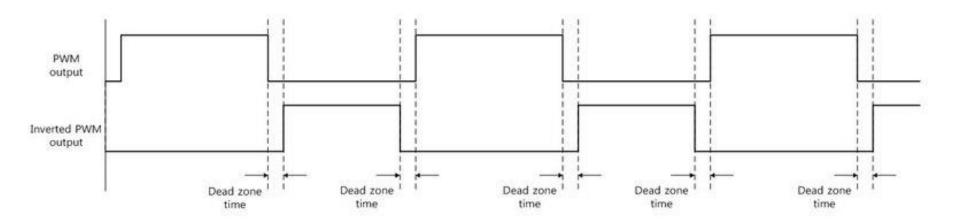
- Compare value register. Example for 25% duty cycle:
 CompareValue = (Autoreload_Value / 4).
- OC Mode register (PWM1/PWM2)
- OCPolarity, OCNPolarity
- OC State register (ENABLE/DISABLE) enables pin
- OCN State register (ENABLE/DISABLE) enables complementary pin

OC Mode; OC(N) Polarity

Mode	Counter < CCR	Counter ≥ CCR
PWM mode I (Low True)	Active	Inactive
PWM mode 2 (High True)	Inactive	Active

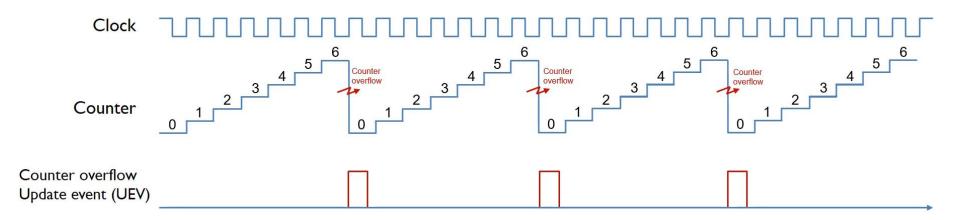
Polarity	Active	Inactive
Active High	High Voltage	Low Voltage
Active Low	Low Voltage	High Voltage

OC(N) State



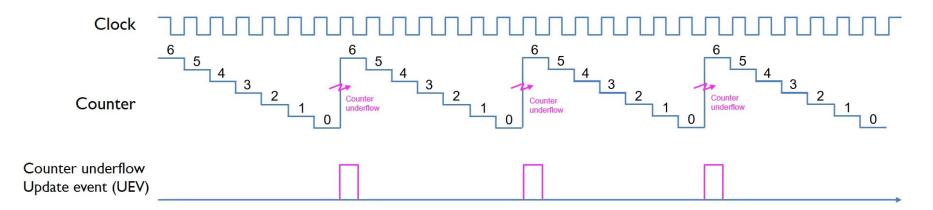
UEV MODES

Up-counting mode(UEV)



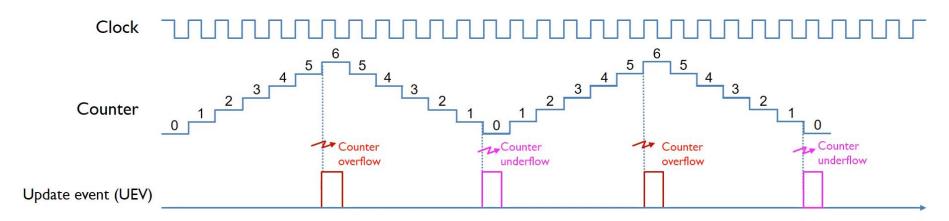
Autoreload register = 6 Repetition counter = 0

Down-counting mode(UEV)



Autoreload register = 6 Repetition counter = 0

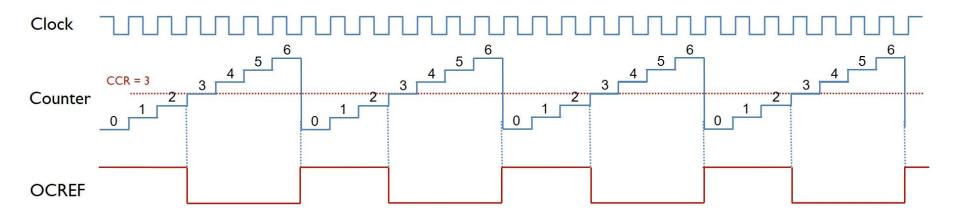
Center-aligned mode(UEV)



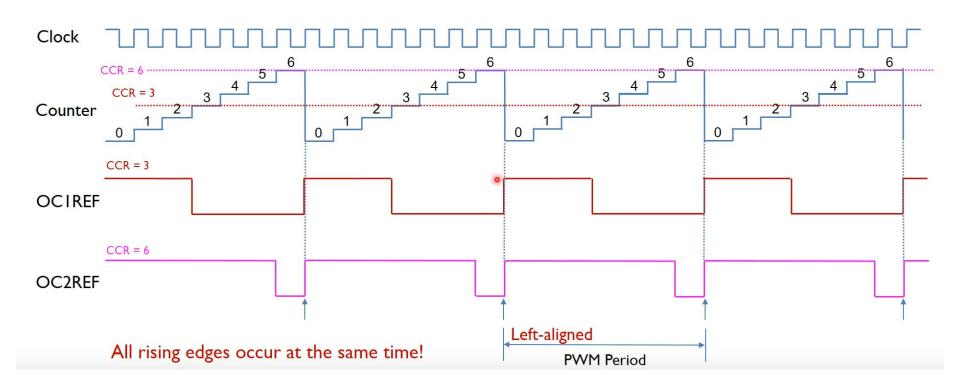
Autoreload register = 6 Repetition counter = 0

PWM MODES

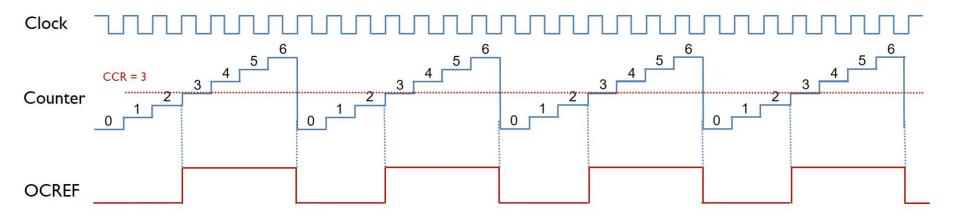
Upcounting low-true mode(PWM1)



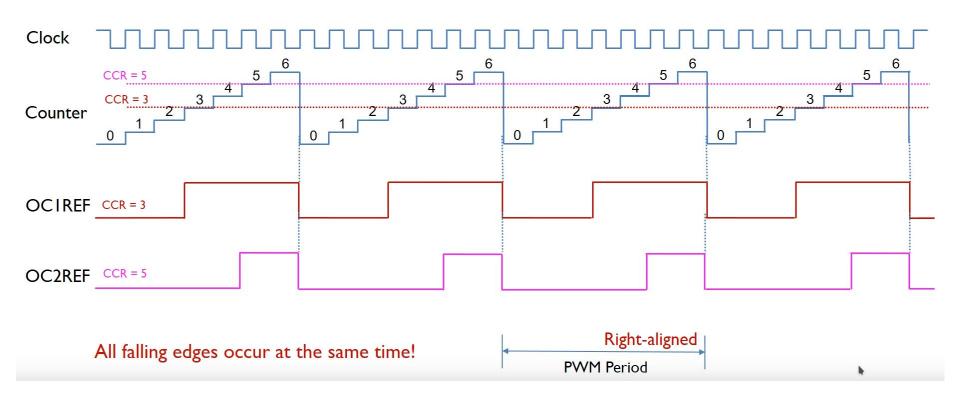
PWM1 mode(edge aligned)



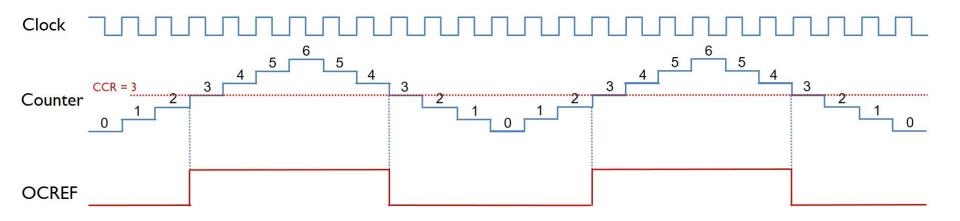
Upcounting high-true mode(PWM2)



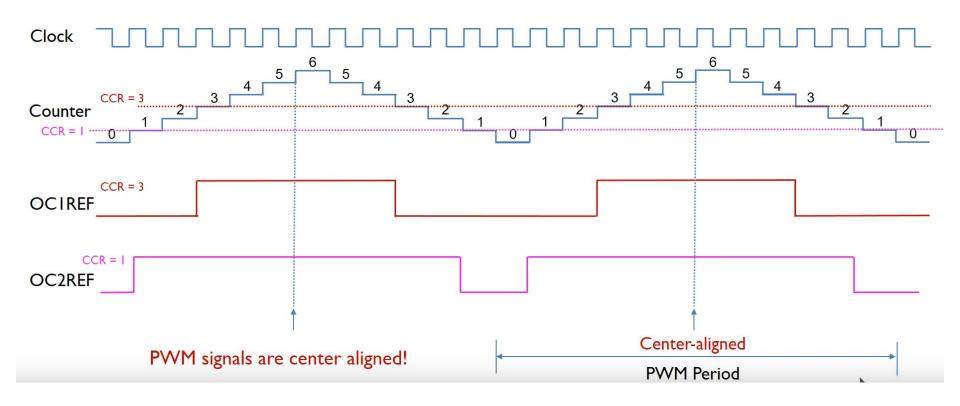
PWM2 mode(edge aligned)



PWM2 mode(center aligned, high-true)

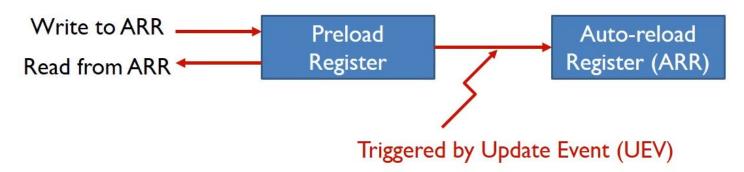


PWM2 mode(center aligned, high-true)



Preload register

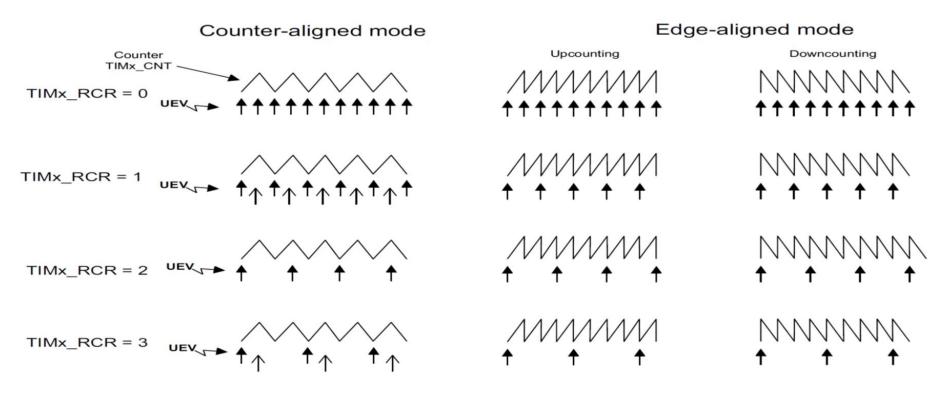
ARPE = 1 (Syn Update)



ARPE = 0 (Asyn Update)



Repetition counter register



Other features to google

- Break unit
- Master/slave controller unit

For usage tutorial see my article



vk.com/@drec_stm32-shim-glazami-praktika

Configuration sequence

- 1. Choose pin
- 2. Enable clock
- 3. Set pin for alternative function
- 4. Set up Time Base Unit
- 5. Set up Output Compare Unit
- 6. Enable Counter

QUESTIONS?