

INDUSTRIAL ROBOT ARM

Idris Group ; Idris Yahya & Ahmad Sami & Ibrahim Saber

THE TEAM





Project Plan

The way we work will be collective, The team will work together in all tasks and in parallel to conserve time, exchange experiences and skills, and preserve time.

• Our industrial robot arm is to help laboratories, and factories to increase production by carrying materials and small products.

Poduction Line

Cutting tool ,3D print and CNC 01



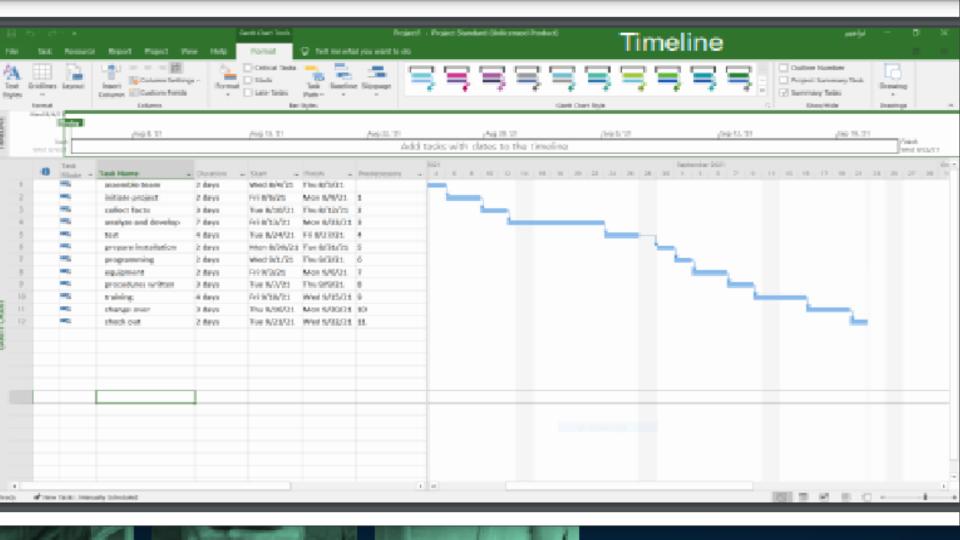
PACKEGS Box

02

ASSEMBLY Mechanical

03 @

PROGRAM App and Web



Introduction



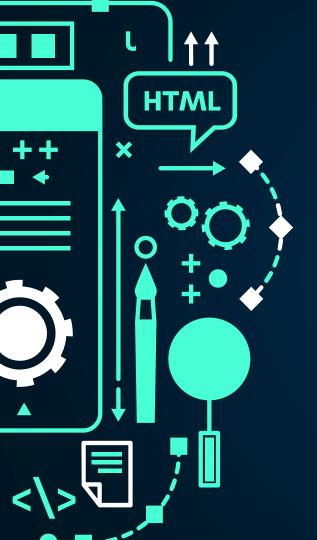
Robotic arms are generally made to simulate a human arm. This is achieved by giving it 7 various segments each part giving it a larger degree of motion.



Robot arms will often have: The above stated 7 various segments bound together with 6 joints



Programmable which gives the user a choice to rotate each motor at various times



THANKS!