Non-Stationary Time Series

EC 421, Set 9

Edward Rubin Winter 2022

Prologue

Schedule

Last Time

Autocorrelation

Today

Brief introduction to nonstationarity

Upcoming

New assignment available.

Intro

Let's go back to our assumption of weak dependence/persistence

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We'll define this good behavior as **stationarity**.

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3. The **covariance** between x_t and x_{t-k} depends only on k—not on t, i.e.,

$$\mathrm{Cov}(x_t,\,x_{t-k})=\mathrm{Cov}(x_s,\,x_{s-k})$$
 for all t and s

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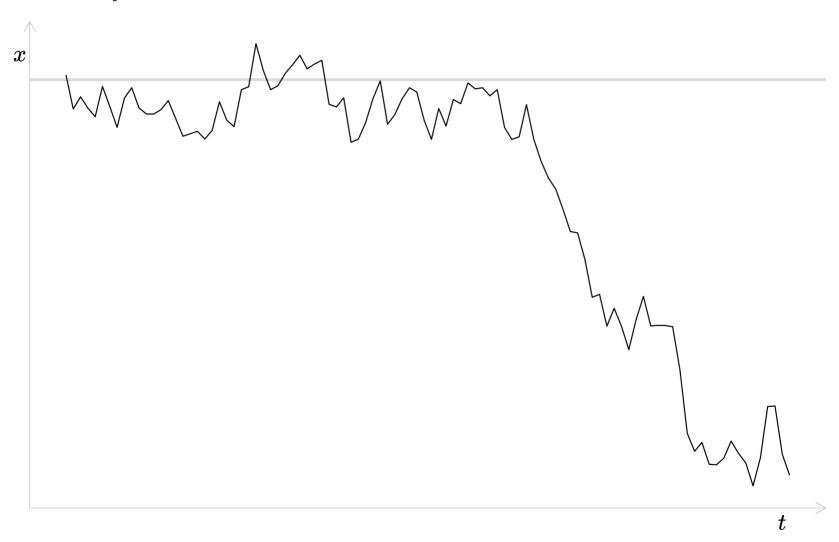
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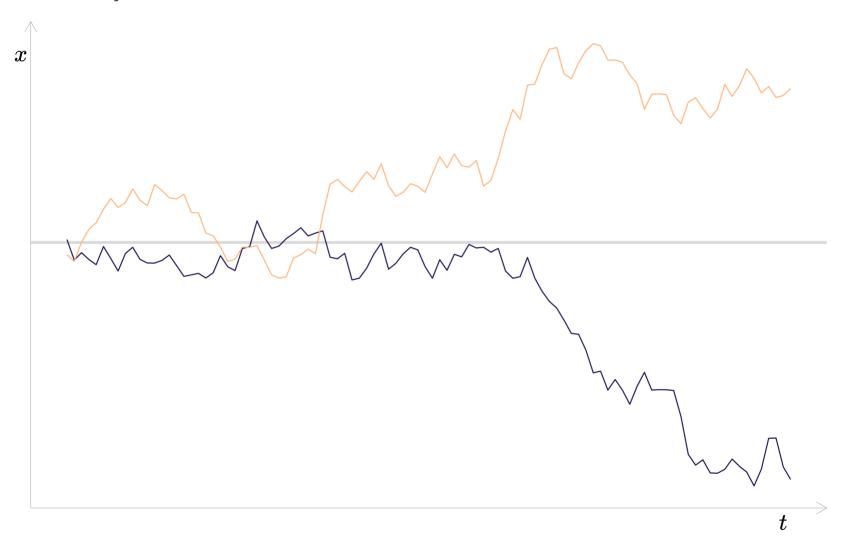
$$egin{aligned} \operatorname{Var}(x_t) &= \operatorname{Var}(x_{t-1} + arepsilon_t) \ &= \operatorname{Var}(x_{t-2} + arepsilon_{t-1} + arepsilon_t) \ &= \operatorname{Var}(x_{t-3} + arepsilon_{t-2} + arepsilon_{t-1} + arepsilon_t) \ &\cdots \ &= \operatorname{Var}(x_0 + arepsilon_1 + \cdots + arepsilon_{t_2} + arepsilon_{t-1} + arepsilon_t) \ &= \sigma_arepsilon^2 + \cdots + \sigma_arepsilon^2 + \sigma_arepsilon^2 + \sigma_arepsilon^2 \ &= t\sigma_arepsilon^2 \end{aligned}$$

Q: What's the big deal with this violation?

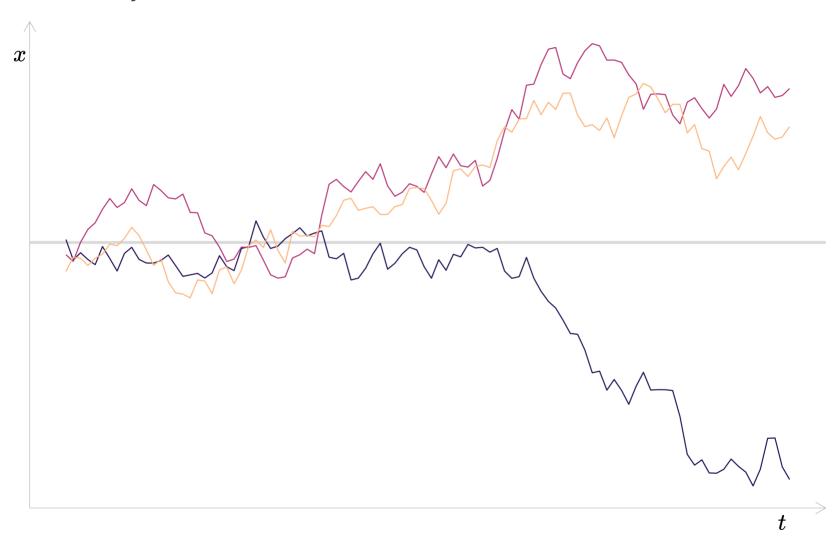
One 100-period random walk



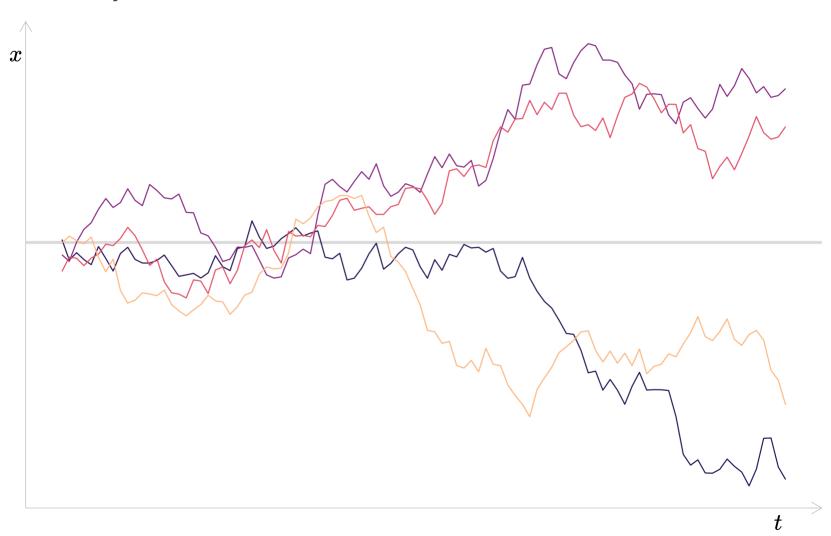
Two 100-period random walks



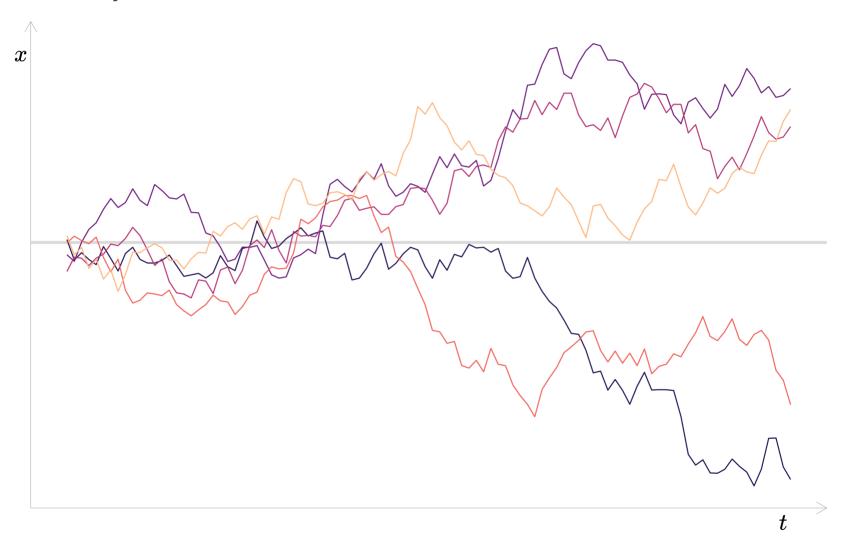
Three 100-period random walks



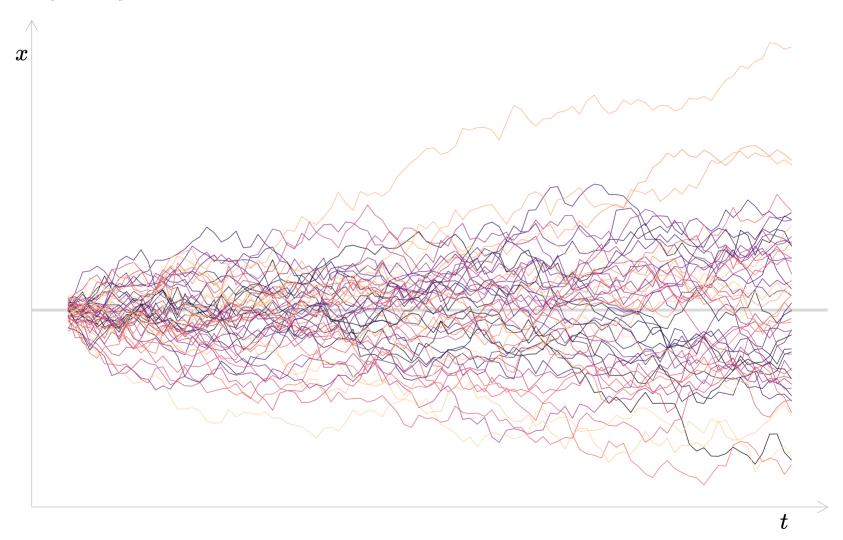
Four 100-period random walks



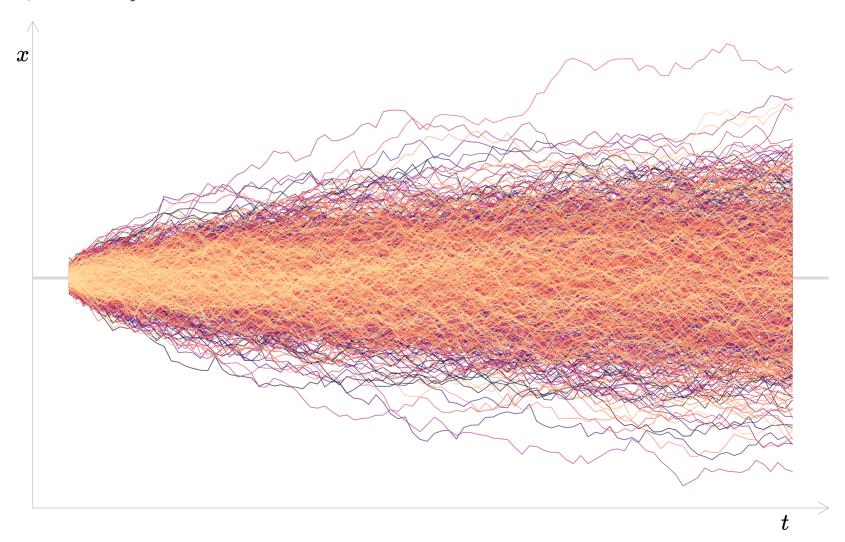
Five 100-period random walks



Fifty 100-period random walks



1,000 100-period random walks



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Defintion: Spurious

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- apparently but not actually valid

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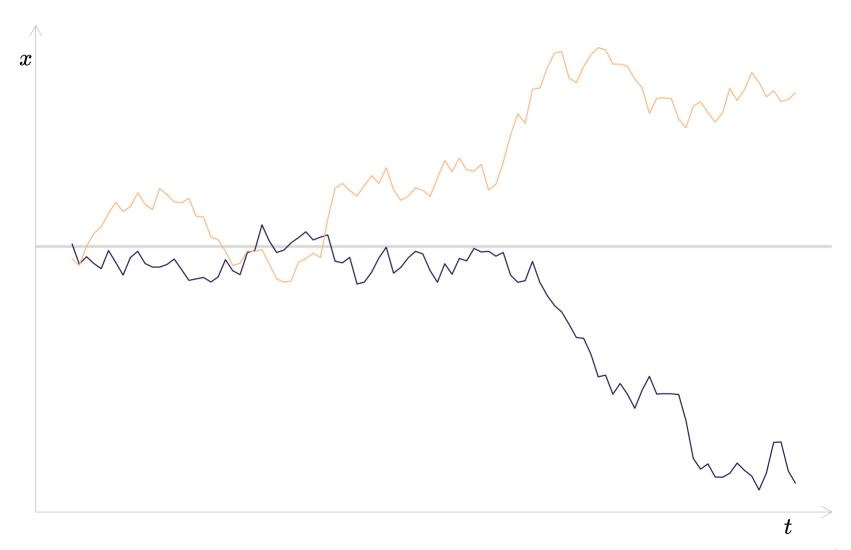
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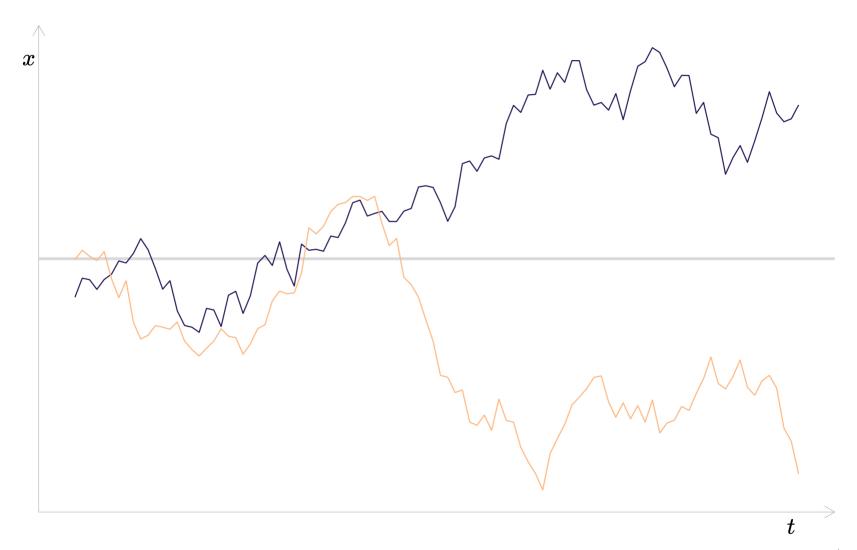
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Back in 1974, Granger and Newbold showed that when they **generated random walks** and **regressed the random walks on each other**, **77/100 regressions were statistically significant** at the 5% level (should have been approximately 5/100).

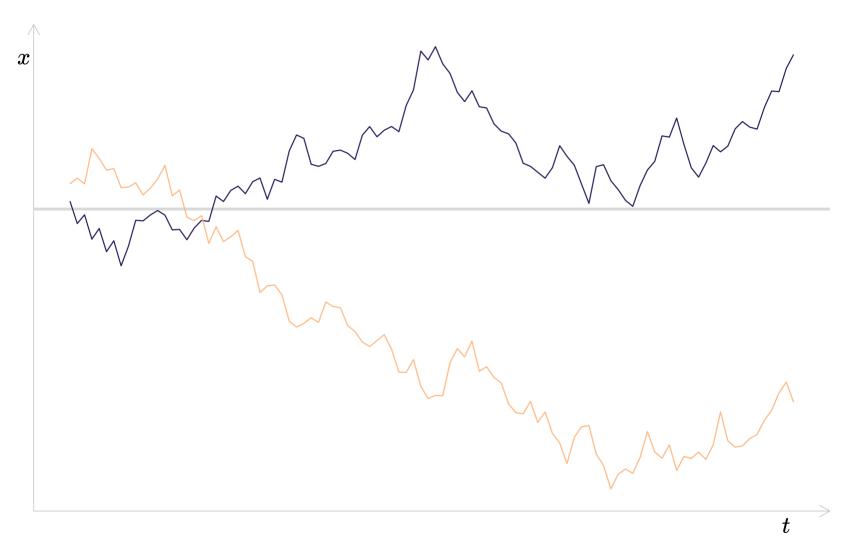
Granger and Newbold simulation example: t statistic \approx -10.58



Granger and Newbold simulation example: t statistic \approx -8.92



Granger and Newbold simulation example: t statistic \approx -7.23



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Deterministic trend: $u_t = lpha_0 + eta_1 t + arepsilon_t$

A potential solution

Some processes are **difference stationary**, which means we can get back to our stationarity (good behavior) requirement by taking the difference between u_t and u_{t-1} .

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$$egin{aligned} y_t &= eta_0 + eta_1 x_t + u_t \ y_{t-1} &= eta_0 + eta_1 x_{t-1} + u_{t-1} \ y_t - y_{t-1} &= eta_1 \left(x_t - x_{t-1}
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ight) \ \Delta y_t &= eta_1 \Delta x_t + \Delta u_t \end{aligned}$$

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using a t test that $|eta_1| < 1.^{\dagger}$

Table of contents

Admin

1. Schedule

Nonstationarity

- 1. Introduction
- 2. Random walks
- 3. The actual problem
- 4. A potential solution
- 5. Dickey-Fuller tests