

# MIDDLE EAST TECHNICAL UNIVERSITY

## ELECTRICAL & ELECTRONICS ENGINEERING

## 

Emre Deniz Şenel - 2167237

18.05.2020

### Contents

1	Part A - Pre Design Stage	2
	1.1 Q1	2
	1.2 Q2	2
	1.3 Q3	4
2 Part B: Sinusoidal PWM		
	2.1 Q1	4
	2.2 Q2	4
	2.3 Q3	4
	2.4 Q4	4
3	Part C - Space Vector PWM	4
	3.1 Q1	4
	3.2 Q2	5
	3.3 Q3	5
	$3.4  \Omega 4$	5

#### 1 Part A - Pre Design Stage

#### 1.1 Q1

In this part, we are asked to calculate the rated torque of the motor.

$$T_{rated} = \frac{P_{nominal}}{\omega_{nominal}} = \frac{400kW}{50\pi} = 2546 Nm \tag{1}$$

#### 1.2 Q2

In this part, we are going to calculate the rated frequency of the machine, and depending on the maximum frequency, we will choose a switching frequency.

$$f_{m,max} = \frac{2250}{60} = 37.5Hz,\tag{2}$$

$$f_{max} = f_{m,max}pp = 75Hz \tag{3}$$

As we increase the switching frequency, the losses will increase. So, we need to choose an adequate switching frequency. Also, to eliminate the lower harmonics we are going to choose a large switching frequency.

We choose the switching frequency as

$$f_s = 3000 \tag{4}$$

1.3	$Q_3$	<b>3</b>		
2	Par	rt B: Sinusoidal PWM		
2.1	Q1	<del>-</del>		
2.2	$Q_2$	2		
2.3	$Q_3$	<b>3</b>		
2.4	m 2.4  Q4			
3 Part C - Space Vector PWM				
3.1	Q1			
		tn.png		

Figure 1: Ideal torque vs speed

- 3.2 Q2
- 3.3 Q3
- 3.4 Q4