

Tropical Forest Carbon Accounting through Deep Learning-Based Species Mapping And Tree Crown Delineation

*An Independent Research Project in Partial Fulfilment of the
Requirements for the Degree MSc Environmental Data Science and
Machine Learning*

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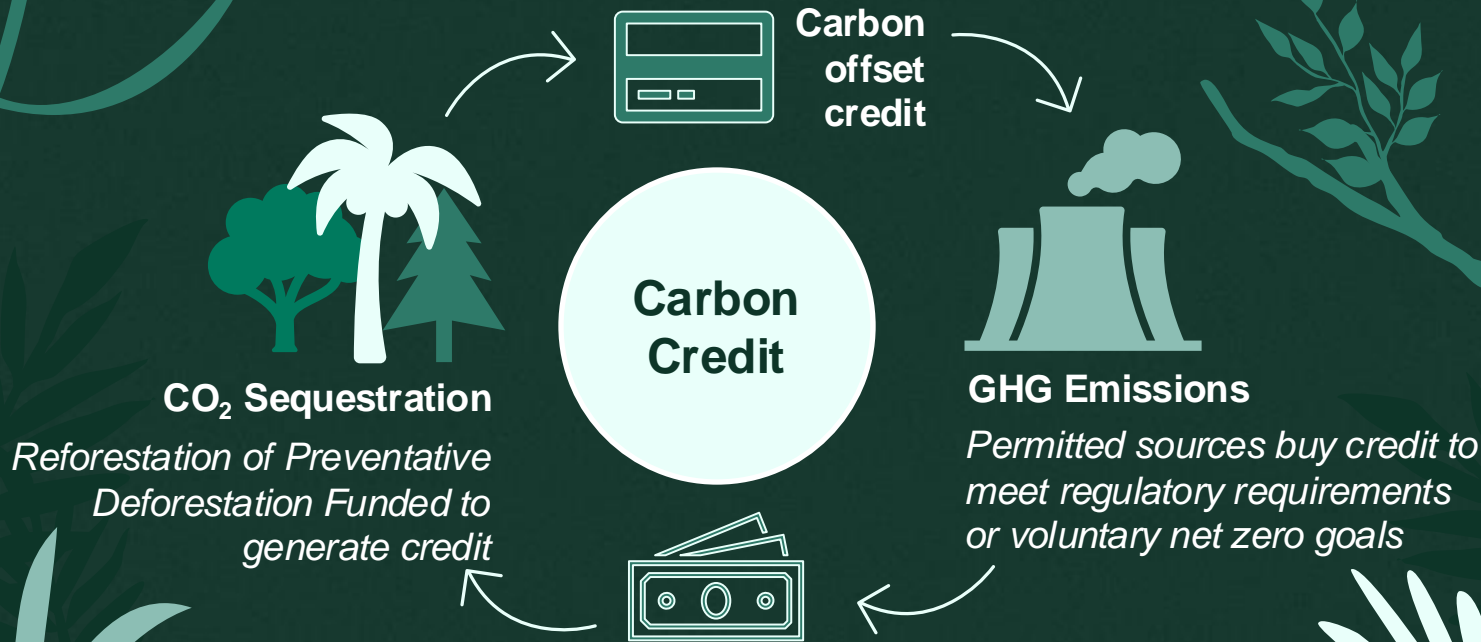
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01

Background



**Visualization inspired by similar chart
from Blue Sky Analytics*



Fast Facts About the Voluntary Carbon Market



70%




Amount of global, vegetation-based carbon storage attributed to forests

4.7 million ha

Forest land was lost per year; equating over the studied 10-year-period to approximately the whole of Kenya

\$410 million

The cost of inaccurate carbon accounting of forests in California alone



Study Area and Groundtruth

Used the ReforestTree Database provided by Reiersen et al. for the purpose of developing Machine Learning solutions to the problem of carbon accounting:

- Six agroforestry carbon offsetting sites in the central coastal region of Ecuador
- Each site approximately 0.5 ha
- Dry tropical forest type
- Mavic 2 Pro drone with a resolution of 2cm per pixel
- Hand-gathered groundtruth measurements in Diameter at Breast Height (DBH), Aboveground Biomass (AGB), species type, and more

<i>Species Name</i>	Total ITCs	Percent ITCs
<i>Cacao</i>	2021	43.54%
<i>Musacea</i>	1504	32.41%
<i>Guaba</i>	597	12.87%
<i>Other</i>	428	9.22%
<i>Mango</i>	89%	1.92%

A stylized illustration of a forest scene in shades of teal and dark green. It features a large tree on the right, hanging vines on the left, and various foliage and plants at the bottom.

02

*SEDD and Deep
Forest Models*

SEDD Model – A Combined Encoder and Two Decoders

Shared Encoder

- ResNet18 (He et al., 2015) with 7x7 convolutions, max pooling, and 3x3 convolutional layers for feature extraction.
- Pre-trained on ImageNet, fully connected layers were removed, deeper layers fine-tuned.

Semantic Decoder

- DeepLabv3 decoder (Chen et al., 2018) using Atrous Spatial Pyramid Pooling (ASPP).
- 3x3 and 1x1 convolutions, batch normalization, and softmax activation to produce probability map.
- Loss calculated using **Partial Weighted Categorical Focal Loss**.

Distance Decoder

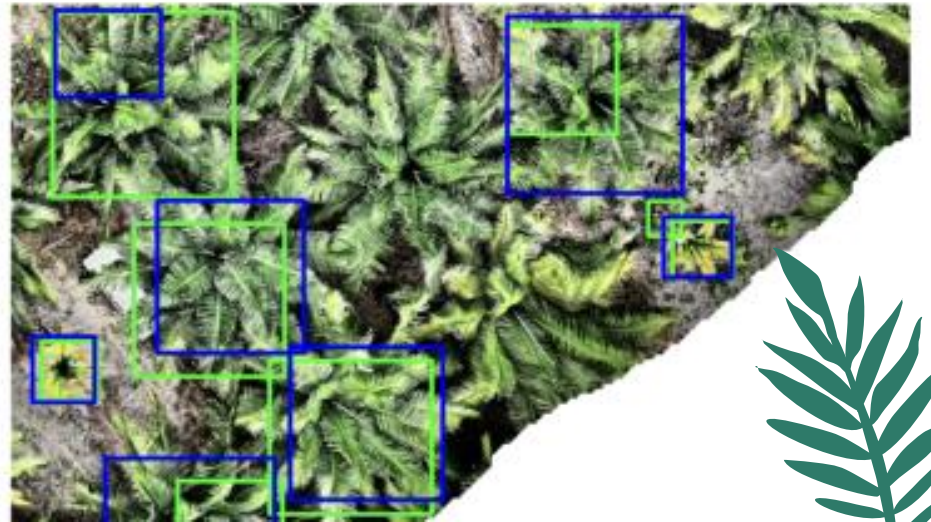
- 3x3 convolution, ReLU activation, and dropout (rate 0.65) to reduce overfitting.
- A 1x1 convolution refines the feature map, followed by a sigmoid activation to output normalized pixel distances (0-1).
- Loss calculated as MSE.

Final Loss

Combination of Semantic and Distance loss; either 1:1 or 2:1 favoring Semantic (termed S-SEDD model) ; S-SEDD model uses masking in semantic segmentation and DS-SEDD model does not.



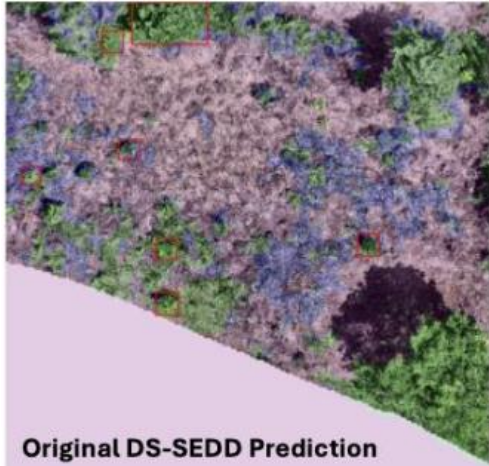
DeepForest Model



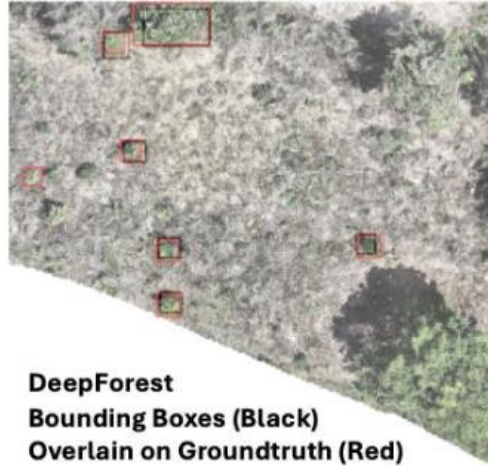
The background is a dark teal color with stylized illustrations of a jungle. On the right side, there is a large tree with a thick trunk and several branches with small, pointed leaves. On the left side, there are large, curved vines hanging down. At the bottom, there are various plants, including a spiky-leafed plant on the left and a palm-like plant on the right.

03

*Post-Processing &
Results*

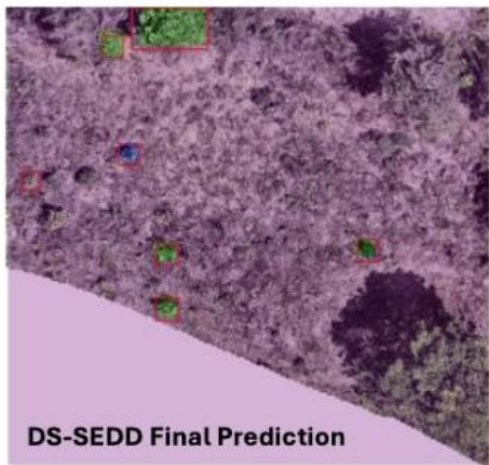


Original DS-SEDD Prediction

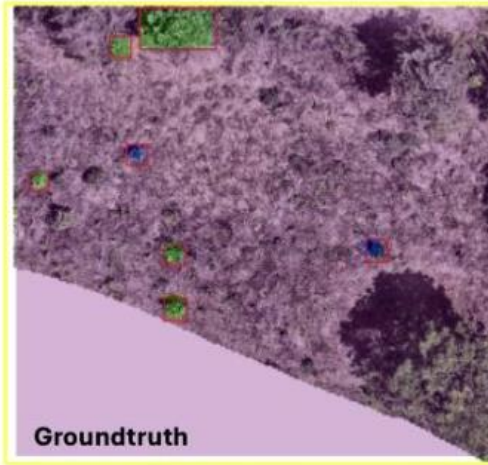


DeepForest
Bounding Boxes (Black)
Overlain on Groundtruth (Red)

- Background
- Musacea
- Guaba
- Cacao
- Mango
- Otra Variedad

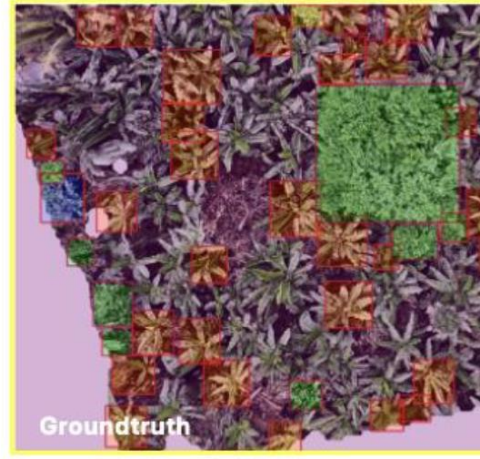
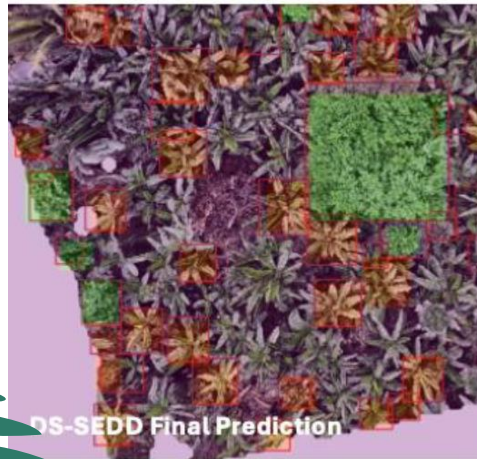
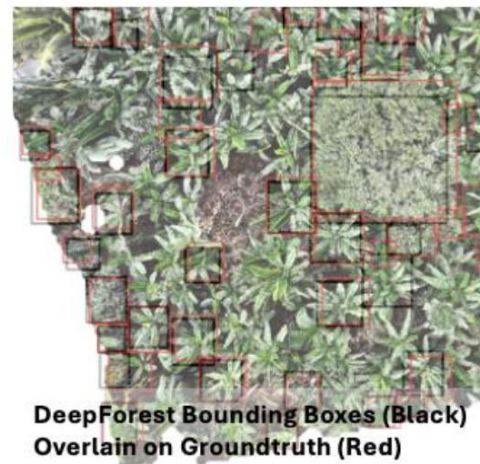
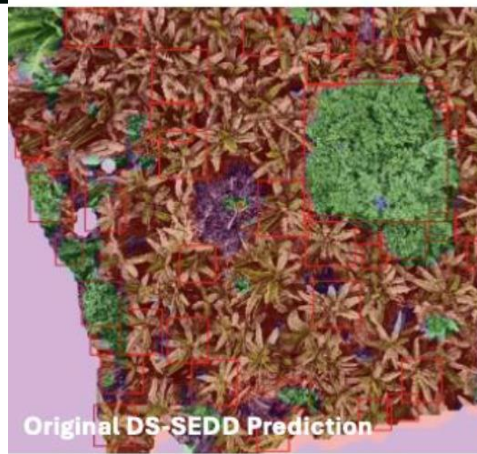


DS-SEDD Final Prediction



Groundtruth

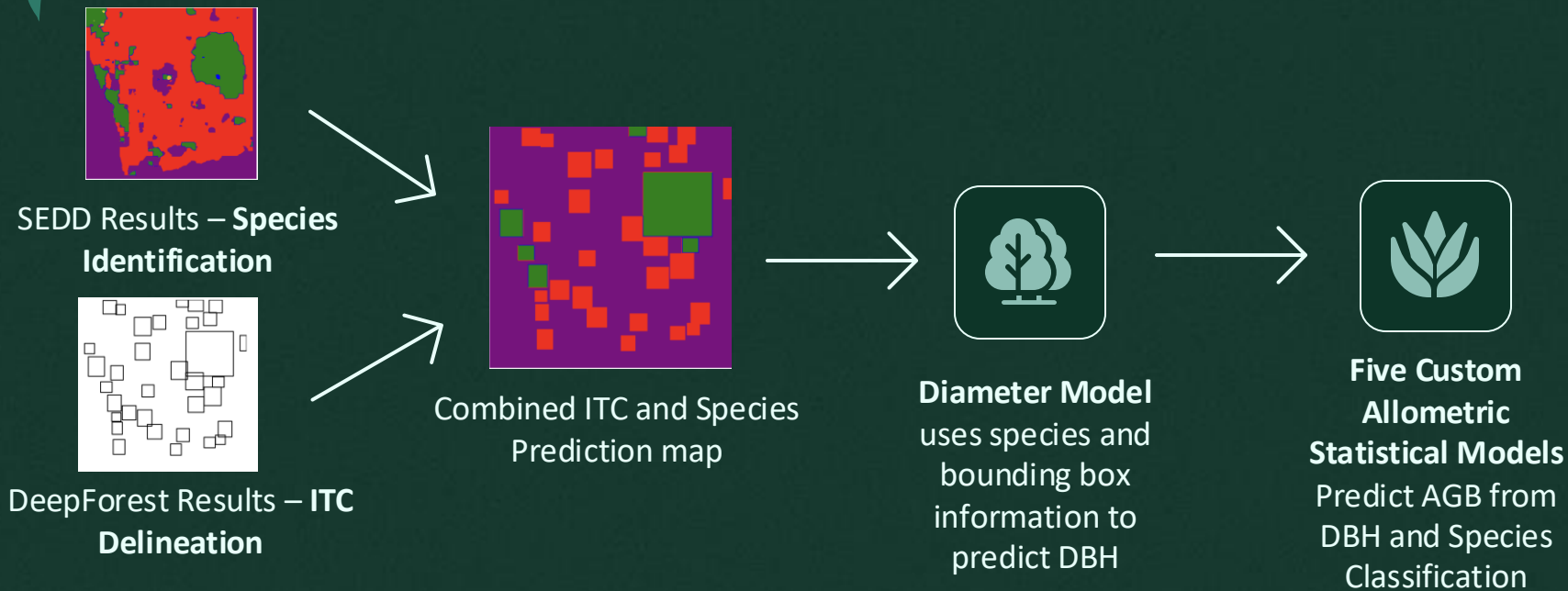




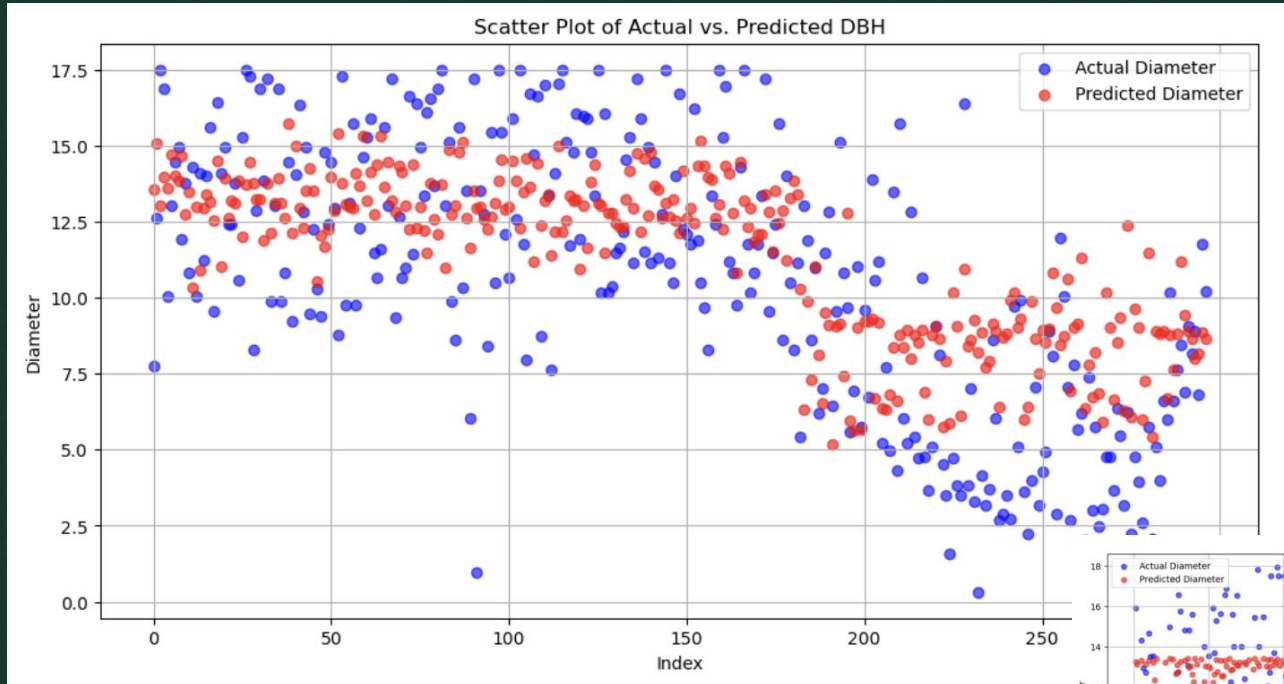
- Background
- Musacea
- Guaba
- Cacao
- Mango
- Otra Variedad

Flora Pluas RGB_9

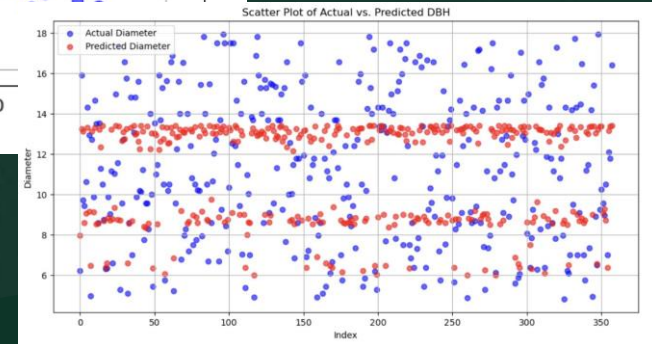
Post-Processing Pipeline



Diameter Model - XGBoost



SVM Regression





Custom Allometric Models R^2 Values

	Log Log	Linear	Exponential	Logarithmic	Polynomial	GAM
<i>Musacea</i>	1.0	0.99	0.99	0.97	1.0	1.0
<i>Cacao</i>	1.0	0.99	0.98	0.95	1.0	1.0
<i>Guaba</i>	1.0	0.97	0.98	0.93	1.0	1.0
<i>Mango</i>	1.0	1.0	1.0	0.99	1.0	1.0
<i>Other</i>	0.87	0.86	0.92	0.71	0.93	0.98

Species Matching Results (DS-SEDD Model)

	Actual Carbon	Predicted Carbon	Absolute Difference	Relative Difference
<i>Test Tile 1</i>	46.16	36.73	9.43	0.2
<i>Test Tile 2</i>	16.6	15.84	0.77	0.05
<i>Test Tile 3</i>	6.64	6.74	0.09	0.01
<i>Test Tile 4</i>	104.34	94.44	9.91	0.09
<i>Test Tile 5</i>	88.1	68.13	19.97	0.23
<i>Test Tile 6</i>	157.86	131.07	26.79	0.17
<i>Test Tile 7</i>	93.55	71.39	22.16	0.24
<i>Test Tile 8</i>	16.69	20.84	4.16	0.25
<i>Test Tile 9</i>	87.63	113.82	26.19	0.3
<i>Test Tile 10</i>	134.21	147.01	12.8	0.1
<i>Test Tile 11</i>	168.7	171.92	3.23	0.02
<i>Test Tile 12</i>	17.85	18.28	0.42	0.02
<i>Test Tile 13</i>	16.29	24.13	7.84	0.48
<i>Test Tile 14</i>	0.53	2.95	2.42	4.6
<i>Test Tile 15</i>	106.47	99.9	6.57	0.06
<i>Test Tile 16</i>	160.42	166.26	5.84	0.04
Total	1222.04	1189.45	32.59	0.02

The background is a dark teal color with stylized illustrations of a jungle. On the right side, there is a large tree with a thick trunk and several branches with small, pointed leaves. On the left side, there are hanging vines and some leafy plants at the bottom. The overall style is minimalist and modern.

03

Discussion

Discussion & Comparison of Results

- Challenge comparing to non-ITC research.
 - Relative error comparisons used to avoid data leakage.
- 2% relative error across test set; outperforms or matches previous methods, including those requiring more data (e.g., manually collected DBH and species metrics).
- The approach is lightweight, relying only on RGB imagery, showing that deep learning and statistical models can accurately estimate individual tree-level carbon sequestration from aerial images.

Site Number	GFW 2019	Spawn 2020	Santoro 2021	Reierson 2022
1	10.3	9.5	0.75	0.13
2	5.6	5.8	0.2	0.46
3	1.5	2.3	0.9	0.5
4	0.8	15.4	1.4	0.27
5	4.2	4.1	0.0	0.27
6	1.5	1.91	0.33	0.25
Total	4.0	5.25	0.34	0.02

Limitations & Future Work

Data Accessibility

RGB aerial data was chosen for its availability in lower-income areas, though using multispectral or LiDAR data could improve DBH approximation.

Scalability Challenge


High-performance computing (HPC) requirements for model evaluation limit scalability; future work may focus on a more efficient model for less powerful infrastructure.

Sparse and Unbalanced Data

Future Efforts could explore more techniques to remedy this.



Resources

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Thanks!

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