# Eduardo **Alvarado**

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# Education

#### Ph.D. in Virtual Avatars and Human Motion

Palaiseau, France

ÉCOLE POLYTECHNIQUE, LIX

Oct. 2020 - Oct. 2023

- Topic: Efficient Models for Human Locomotion and Interaction in Natural Environments.
- Supervisors: Prof. Damien Rohmer and Prof. Marie-Paule Cani.
- Funding: European Union's Horizon 2020 Research Programme. Marie Skłodowska-Curie Grant Agreement n. 860768 (CLIPE project).

#### M.Sc. in Embedded Systems and AI

Freiburg, Germany

ALBERT-LUDWIGS-UNIVERSITÄT FREIBURG

Apr. 2017 - Nov. 2019

- · Framework: Robotics, Computer Vision, Machine Learning, Deep Learning and Reinforcement Learning.
- Thesis: Deep Multimodal Learning for Autonomous Driving.
- Supervisors: Prof. Joschka Bödecker and Prof. Abhinav Valada.

#### **B.Sc.** in Electronics and Automation Engineering

Madrid, Spain

UNIVERSIDAD CARLOS III - POZNAN UNIVERSITY OF TECHNOLOGY (ERASMUS)

Sep. 2010 - Sep. 2014

- Framework: Digital/Analog Electronics, CS, Robotics and Control Engineering.
- Thesis: Development of a localization-based AR framework in C++ for smart glasses.
- Supervisors: Prof. Angel Garcia Crespo.

# Academic & Industry Experience

#### **Postdoctoral Researcher - Virtual Avatars and Human Motion**

Saarbrücken, Germany

MAX PLANCK INSTITUTE FOR INFORMATICS

Jan. 2024 - Currently

- Research on plausible human avatars and locomotion models using data-driven and physics-based approaches.
- Supervisors: Prof. Christian Theobalt and Dr. Marc Habermann.

Ph.D. Intern Bordeaux, France

UBISOFT LA FORGE Mar. 2023 - Jun. 2023

• Topic: Development of authoring tools for the production stages of crowd/character animation.

#### **Research Scientist - AI for Material Rendering**

Stuttgart, Germany

Jun. 2020 - Sep. 2020

• Research on AI (Image Processing, GANs) for 3D Materials Synthesis (SVBRDFs) with focus on the game- and film-industry.

#### M.Sc. Thesis - Deep Multimodal Learning for Autonomous Driving

Renningen, Germany

ROBERT BOSCH GMBH

May 2019 - Nov. 2019

• Topic: Sensor-fusion algorithms (Radar, RGB) for Autonomous Driving.

#### **Research Assistant - Autonomous Intelligent Systems**

Freiburg, Germany

ALBERT-LUDWIGS-UNIVERSITÄT FREIBURG

Sep. 2017 - Feb. 2019

• TurtleBot3 Waffle HW/SW setup for teleoperation, SLAM and indoor mapping.

### Languages\_

Spanish Native **English** Fluent German Fluent **French** Intermediate

#### Skills

**Programming** Python, C#, C++, MT<sub>E</sub>X Game/3D Unity, Unreal Engine, Blender Robotics ROS, Gazebo

> **AI** PyTorch, Tensorflow Windows, Linux **SW-Dev** CMake, Visual Studio, PyCharm, Git

> > EDUARDO ALVARADO · CURRICULUM VITAE

# Academic Activities

#### **Teaching Assistant for INF633 - Advanced 3D Graphics**

Palaiseau, France

ÉCOLE POLYTECHNIQUE

Oct. 2020 - Oct. 2023

• Topic: Ecosystems Authoring, Procedural Animations, Al for Behavior Planning.

OCTOBER 27, 2025

Research Visitor

Nicosia, Cyprus

CYENS CENTRE OF EXCELLENCE

Jul. 2021 - Oct. 2021

Topic: Character Animation with focus on Motion Capture and Motion Matching. Supervisor: Prof. Yiorgos Chrysanthou.

Research Visitor Barcelona, Spain

Universitat Politècnica de Catalunya

Sep. 2022 - Dec. 2022

• Topic: Crowds Authoring in Natural Environments. Supervisor: Prof. Nuria Pelechano.

Reviewer / Committee Worldwide

SIGGRAPH, SIGGRAPH ASIA, IEEE VR, TVCG, EUROGRAPHICS (PC), CEIG (PC), CASA (PC)

Oct. 2020 - Currently

# **Publications**

PEER-REVIEWED JOURNAL AND CONFERENCE ARTICLES

FRAME: Floor-aligned Representation for Avatar Motion from Egocentric Video (🖓 🛢 🔼)

Andrea Boscolo Camiletto, Jian Wang, <u>Eduardo Alvarado</u>, Rishabh Dabral, Thabo Beeler, Marc Habermann, Christian Theobalt Computer Vision and Pattern Recognition (CVPR), 2025

BimArt: A Unified Approach for the Synthesis of 3D Bimanual Interaction with Articulated Objects (🗘 🖺 🔼)

Wanyue Zhang, Rishabh Dabral, Vladislav Golyanik, Vasileios Choutas, **Eduardo Alvarado**, Thabo Beeler, Marc Habermann, Christian Theobalt Computer Vision and Pattern Recognition (CVPR), 2025

TRAIL: Simulating the Impact of Human Locomotion on Natural Landscapes ( 🗘 🖺 🗖 )

EDUARDO ALVARADO, OSCAR ARGUDO, DAMIEN ROHMER, MARIE-PAULE CANI, NURIA PELECHANO

Computer Graphics International (CGI), 2024

How Much Do We Pay Attention? A Comparative Study of User Gaze and Synthetic Vision during Navigation (**b**)

Julia Melgare, Guido Mainardi, **Eduardo Alvarado**, Damien Rohmer, Marie-Paule Cani, Soraia Musse

Poster, Motion, Interactions and Games (MIG), 2023

Generating Upper-Body Motion for Real-Time Characters Making their Way through Dynamic Environments (🗘 🖺 🕒)

EDUARDO ALVARADO, DAMIEN ROHMER, MARIE-PAULE CANI

Proceedings of the ACM SIGGRAPH/Eurographics Symposium on Computer Animation (SCA), 2022 - Best Paper Honorable Mention Award

Real-Time Locomotion on Soft Grounds With Dynamic Footprints (🖓 🖺 🔼)

EDUARDO ALVARADO, CHLOÉ PALIARD, DAMIEN ROHMER, MARIE-PAULE CANI

Frontiers in Virtual Reality, Frontiers, 2022, 3, (10.3389/frvir.2022.801856)

A Survey on Reinforcement Learning Methods in Character Animation (

Ariel Kwiatkowski, <u>Eduardo Alvarado</u>, Vicky Kalogeiton, Karen C. Liu, Julien Pettré, Michiel van de Panne, Marie-Paule Cani Eurographics 2022, Computer Graphics Forum, Wiley, 2022, pp.1-27. (10.1111/cgf.14504)

Soft Walks: Real-Time, Two-Ways Interaction between a Character and Loose Grounds ( 🗘 🖹 🔼 )

CHLOÉ PALIARD, **EDUARDO ALVARADO**, DAMIEN ROHMER, MARIE-PAULE CANI

Eurographics 2021 (short), May 2021, Vienna, Austria.

# **Dissemination Activities**

PhD Research. "Present and Future of Character Animation"

Saarbrücken, Germany

Max Planck Institute for Informatics

Oct. 2022

Summer School Youth Program. "Can AI be Creative? Using AI for Animation"

Palaiseau, France

HEC Business School

Jul. 2022 Online

Workshop on Virtual Humans and Crowds in Immersive Environments (VHCIE)

Mar. 2022

PhD Research in Motion Matching and Motion Capture

Nicosia, Cyprus

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Sep. 2021

**Doctoral Consortium** 

Online

EUROGRAPHICS 2021

May 2021

## Interests

I'm passionate about skiing and make it a point to explore a new destination each year with friends and family. I stay actively engaged with the latest developments in robotics and AI, often sharing that curiosity with my nieces to spark their interest. In my spare time, I work on my photography portfolio and contribute to my personal blog focused on game dev where I hope to one day launch my own startup. I also enjoy hands-on DIY projects and diving into unfamiliar fields through reading and exploration.