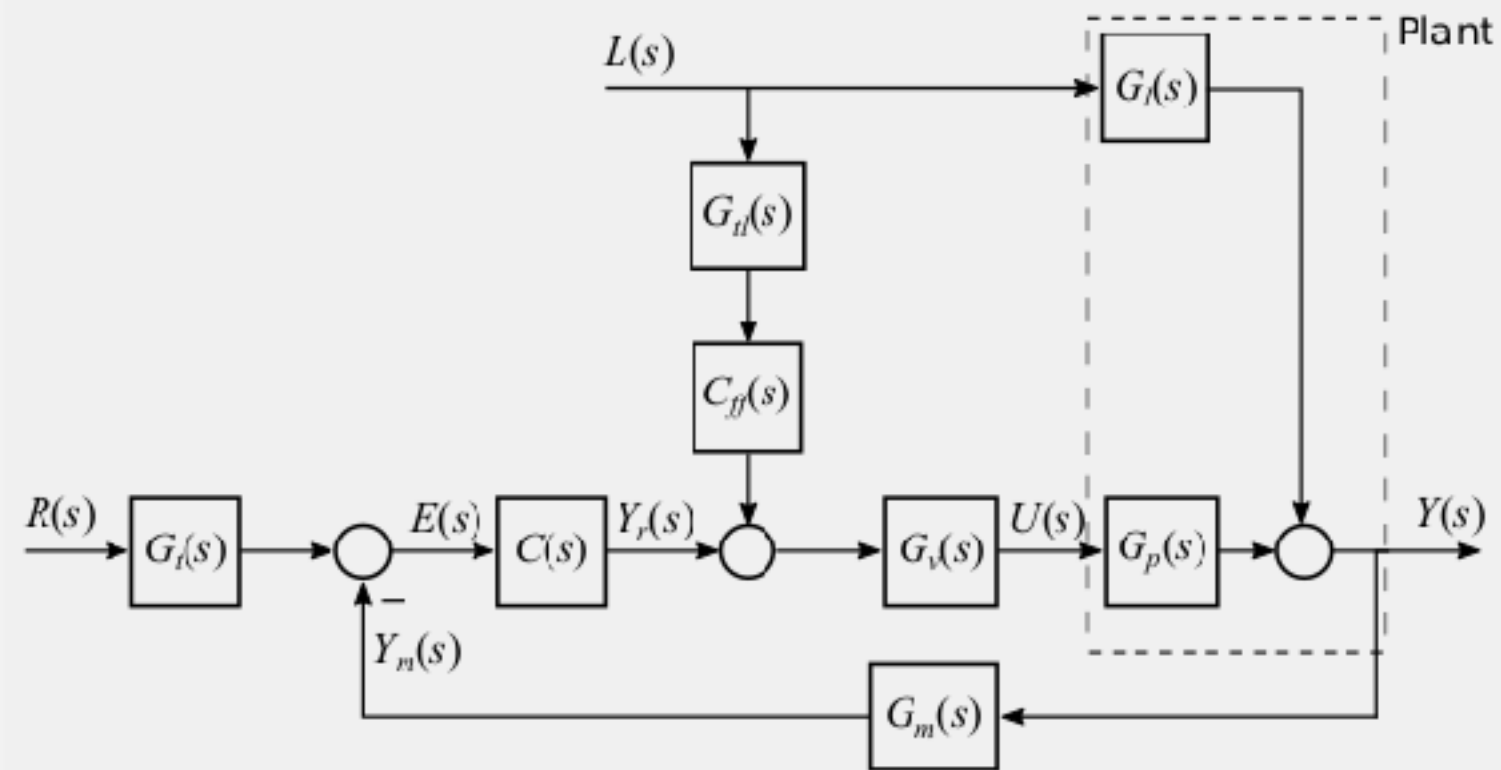


Figure 3



Analysis and Simulation of Feedforward-Feedback Control Systems

Load Data

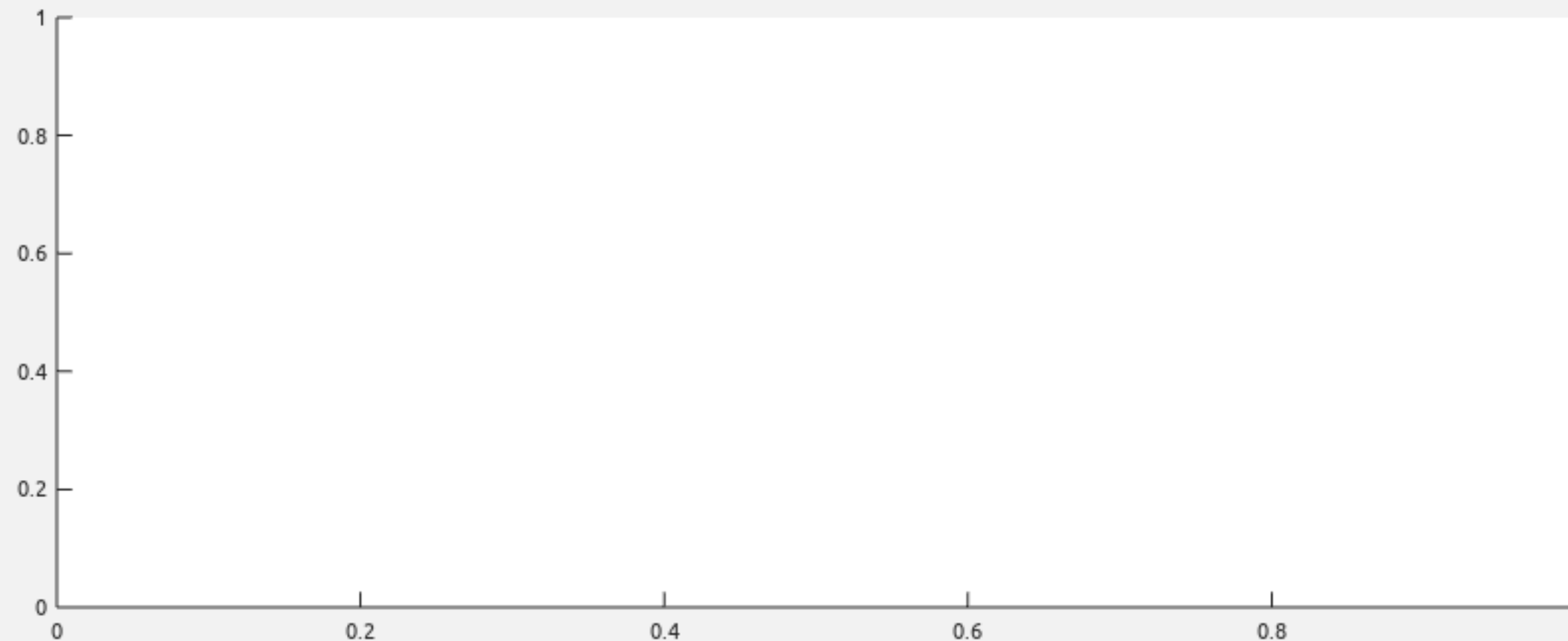
Reload Default Values

Analysis Tools

Simulation Parameters

Additional Information

Simulate



Clear Simulation Window

Help

Save

Close

System:

+

$y(\infty) =$

Settling Time. =
(Approximate)

$[K^*] =$

$[K^*u] =$

$\omega_{-180} =$

GM =

$\omega_{gc} =$

PM =