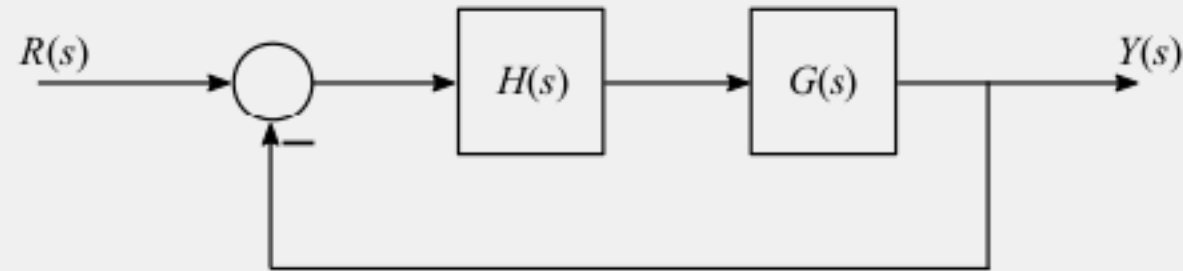


Figure 2

# Analysis and Simulation of Closed Loop Systems Based on $G(s)H(s)$



Open Loop Transfer Function

Load Default Values

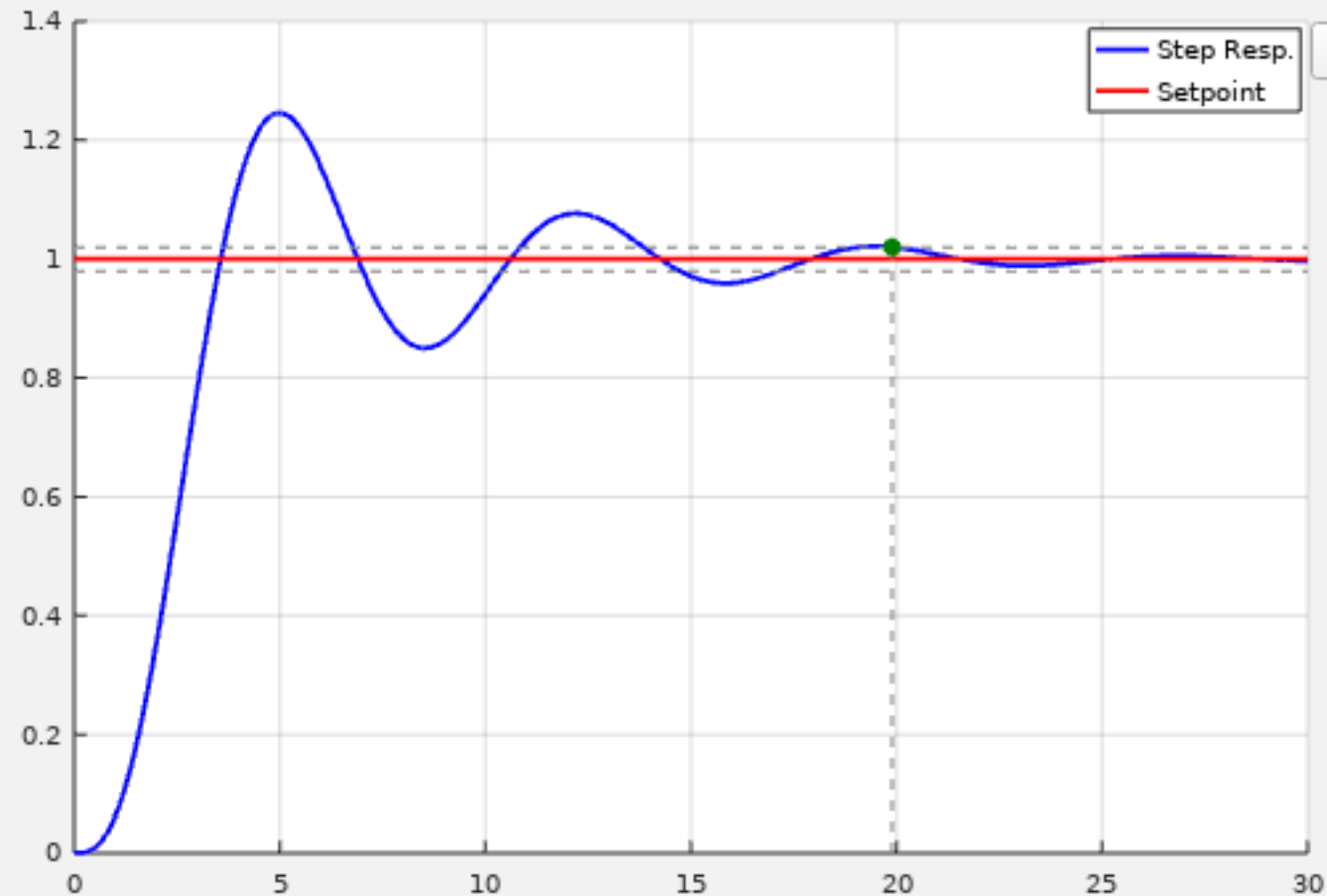
$$G(s)H(s)/K = \frac{0.4}{1*s^3 + 1*s^2 + 1*s^1 + 0}$$

$bm*s^m + \dots + b1*s^1 + b0$

$an*s^n + \dots + a1*s^1 + a0$

Variable Gain,  $K = 1.25$ 

## Step Response of the Feedback System



## Additional Information

System: Asympt. Stable

 $y(\infty) = 1$ Settling Time. = 19.89  
(Approximate) $[K^*] = 0.5$  $[K^*u] = 1$  $\omega_{-180} = 1$ 

GM = 2

 $\omega_{gc} = 0.5652$ 

PM = 50.2904

About  $G(s)H(s)$ 

Zeros-Poles Map

About Closed Loop

Zeros-Poles Map

Analysis

Root Locus

Bode

Nyquist

Simulation

Step Response

Impulse Response

Simulation Parameters

SP Step Amplitude =

1

Simulation Time =

30

Help

Save

Close