Analysis and Simulation of Closed Loop Systems

Plant

$R(s)$ → $G_t(s)$ → ⊖ → $E(s)$ → $C(s)$ → $Y_r(s)$ → $G_v(s)$ → $U(s)$ → $G_p(s)$ → $Y(s)$

$L(s)$ → $G_l(s)$

$Y_m(s)$ ← $G_m(s)$ ← $N(s)$

Load Data

Reload Default Values

Analysis Tools

Simulation Parameters

Additional Information

Simulate

Clear SImulation Window

System:	
y(inf) =	
Settling Time. = (Approximate)	
[K*] =	
[K*u] =	
ω_{-180} =	
GM =	
ω_{gc} =	
PM (grad.) =	

Help   Save   Close