

2D and 3D Transformations

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Topics

- Motivation
- 2D Transformations
- 3D Transformations
- Transformations in Three.js
- The Scene Graph

MOTIVATION

CG Main Tasks

■ Modeling

- ❑ Construct individual **models** / objects
- ❑ Assemble them into a 2D or 3D **scene**

■ Animation

- ❑ Static vs. dynamic scenes
- ❑ Movement and / or deformation

■ Rendering

- ❑ Generate final images
- ❑ Where is the viewer / camera ?
- ❑ How is he / she looking at the scene?

Modeling vs Rendering

■ Modeling

- ❑ Create models
- ❑ Apply materials to models
- ❑ Place models around scene
- ❑ Place lights in the scene
- ❑ Place the camera

[YouTube Demo](#)

■ Rendering

- ❑ Take picture with the camera

[van Dam]

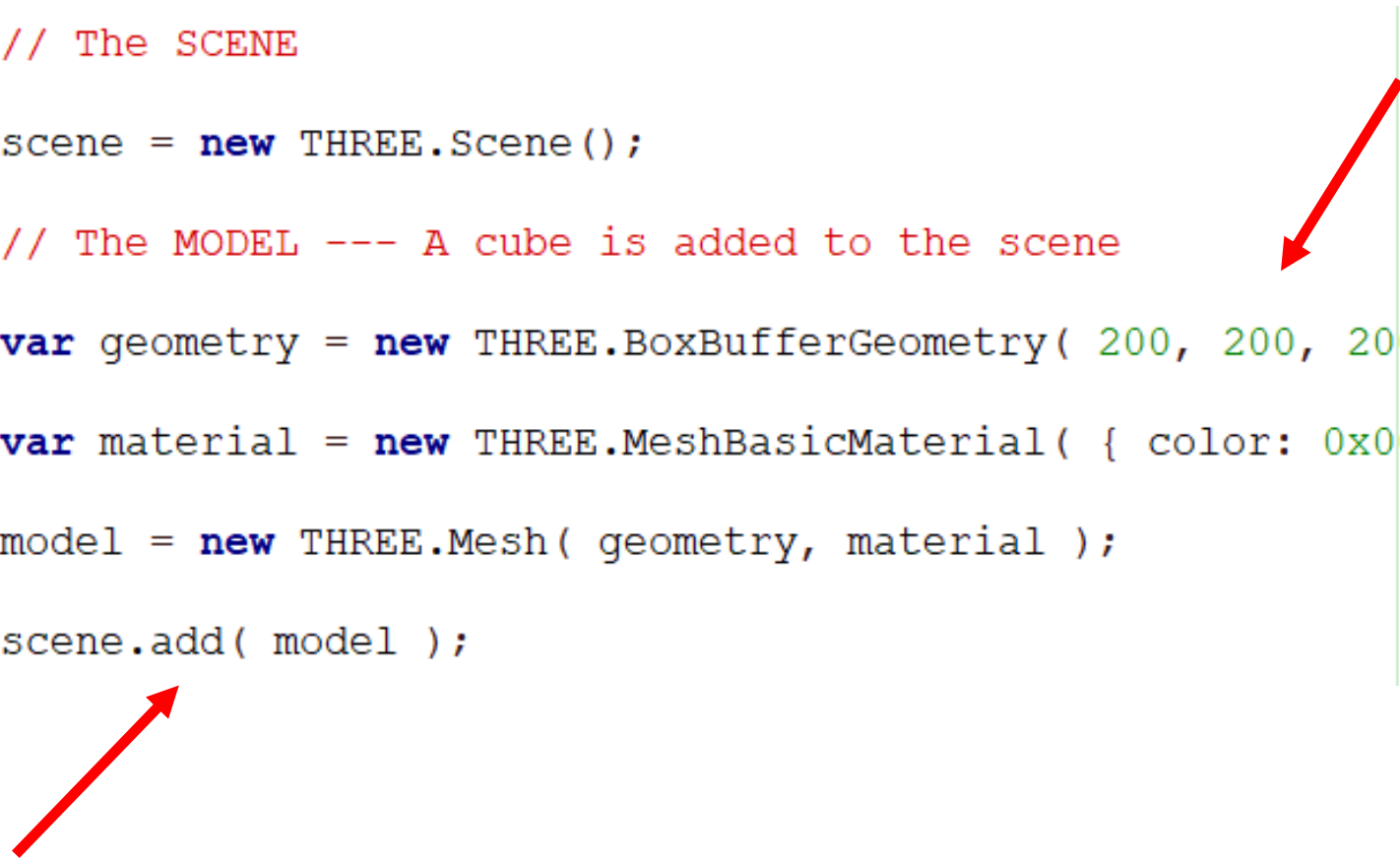
Three.js – A scene with a cube

```
// The SCENE

scene = new THREE.Scene();

// The MODEL --- A cube is added to the scene

var geometry = new THREE.BoxBufferGeometry( 200, 200, 200 );
var material = new THREE.MeshBasicMaterial( { color: 0x00ff00 } );
model = new THREE.Mesh( geometry, material );
scene.add( model );
```




Three.js – The camera

```
// The CAMERA

// --- Where the viewer is and how he is looking at the scene

camera = new THREE.PerspectiveCamera( 70,
                                     window.innerWidth / window.innerHeight, 1, 1000 );

camera.position.z = 400;
```



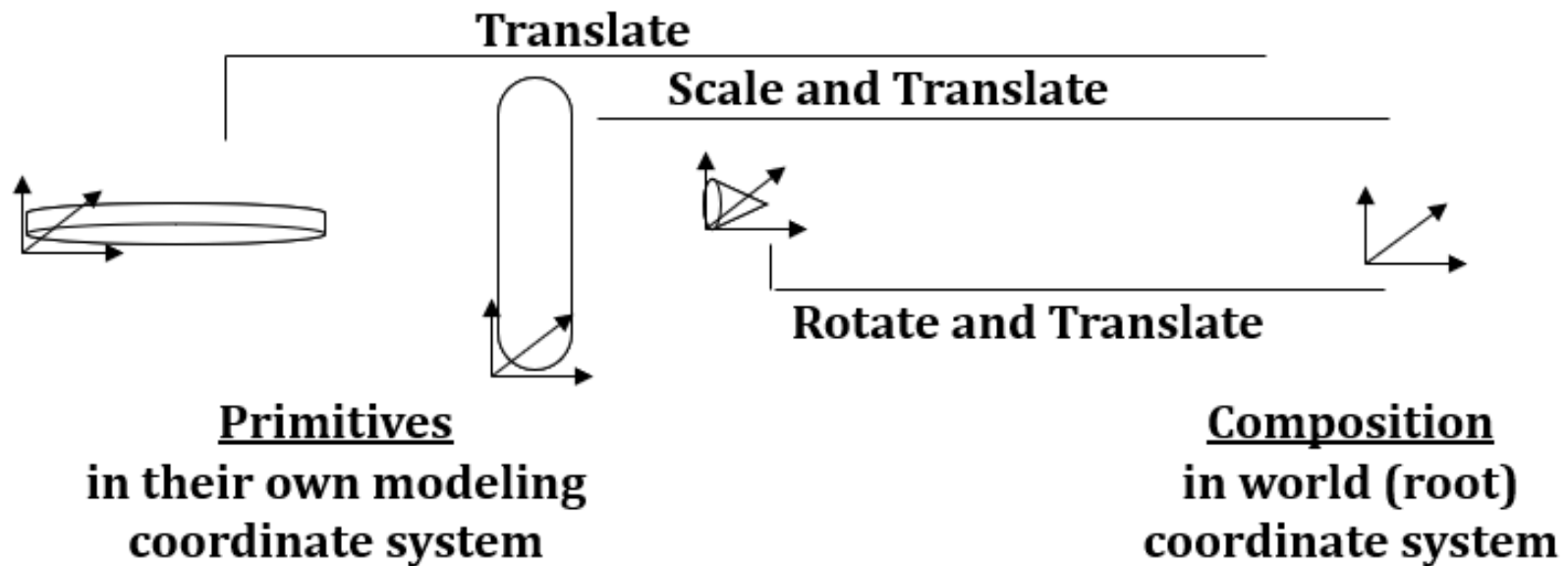
Three.js – Animation

```
function animate() {  
    requestAnimationFrame( animate );  
    model.rotation.x += 0.005;  
    model.rotation.y += 0.01;  
    renderer.render( scene, camera );  
}
```



Composition of a geometric model

- **Assemble primitives** to create final object
 - Apply **affine transformations**



[van Dam]

2D and 3D Transformations

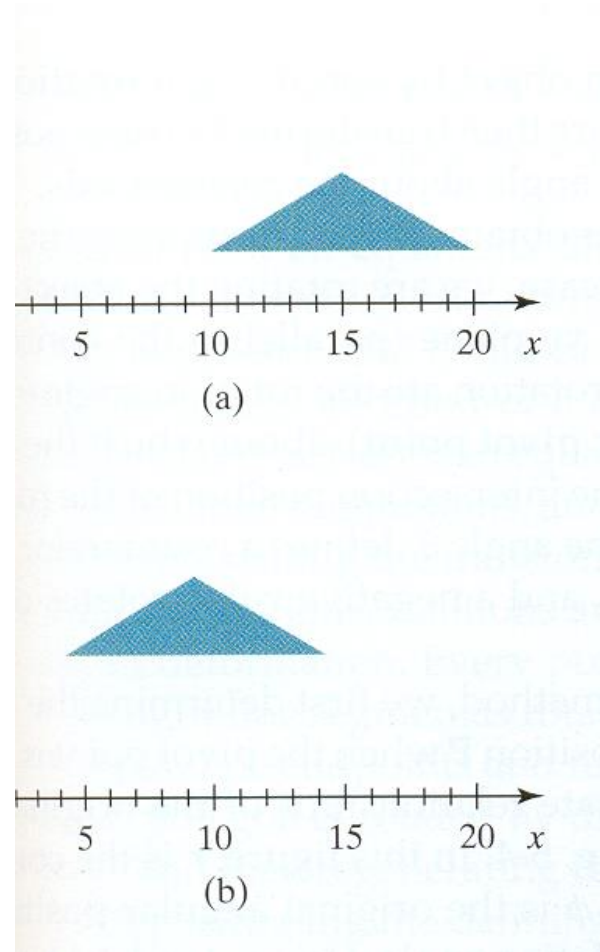
- **Position**, **rotate** and **scale** objects on the **2D** plane or in **3D** space
- Basic transformations
 - Translation
 - Rotation
 - Scaling
- Matricial representation
 - **Homogeneous coordinates !!**
 - Concatenation = **Matrix products**
- Complex transformations ?
 - **Decompose** into a sequence of basic transformations

2D TRANSFORMATIONS

2D Translation

$$\begin{bmatrix} x' \\ y' \\ 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & t_x \\ 0 & 1 & t_y \\ 0 & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} x \\ y \\ 1 \end{bmatrix}$$

$$\mathbf{P}' = \mathbf{T}(t_x, t_y) \cdot \mathbf{P}$$



2D Scaling

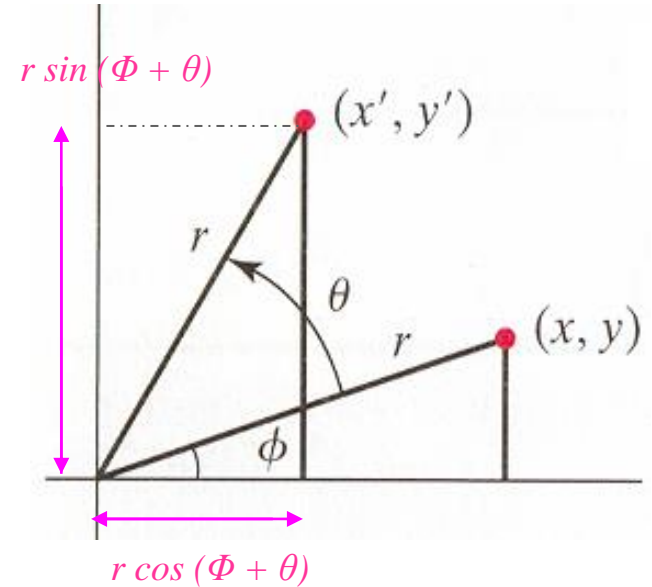
$$\begin{bmatrix} x' \\ y' \\ 1 \end{bmatrix} = \begin{bmatrix} s_x & 0 & 0 \\ 0 & s_y & 0 \\ 0 & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} x \\ y \\ 1 \end{bmatrix}$$

$$\mathbf{P}' = \mathbf{S}(s_x, s_y) \cdot \mathbf{P}$$



2D Rotation

$$\begin{aligned}x' &= r \cos(\phi + \theta) = r \cos \phi \cos \theta - r \sin \phi \sin \theta \\y' &= r \sin(\phi + \theta) = r \cos \phi \sin \theta + r \sin \phi \cos \theta\end{aligned}$$



$$\begin{bmatrix} x' \\ y' \\ 1 \end{bmatrix} = \begin{bmatrix} \cos \theta & -\sin \theta & 0 \\ \sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} x \\ y \\ 1 \end{bmatrix}$$

$$\mathbf{P}' = \mathbf{R}(\theta) \cdot \mathbf{P}$$

Concatenation

$$\begin{aligned}\mathbf{P}' &= \mathbf{T}(t_{2x}, t_{2y}) \cdot \{\mathbf{T}(t_{1x}, t_{1y}) \cdot \mathbf{P}\} \\ &= \{\mathbf{T}(t_{2x}, t_{2y}) \cdot \mathbf{T}(t_{1x}, t_{1y})\} \cdot \mathbf{P}\end{aligned}$$

$$\begin{bmatrix} 1 & 0 & t_{2x} \\ 0 & 1 & t_{2y} \\ 0 & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} 1 & 0 & t_{1x} \\ 0 & 1 & t_{1y} \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & t_{1x} + t_{2x} \\ 0 & 1 & t_{1y} + t_{2y} \\ 0 & 0 & 1 \end{bmatrix}$$

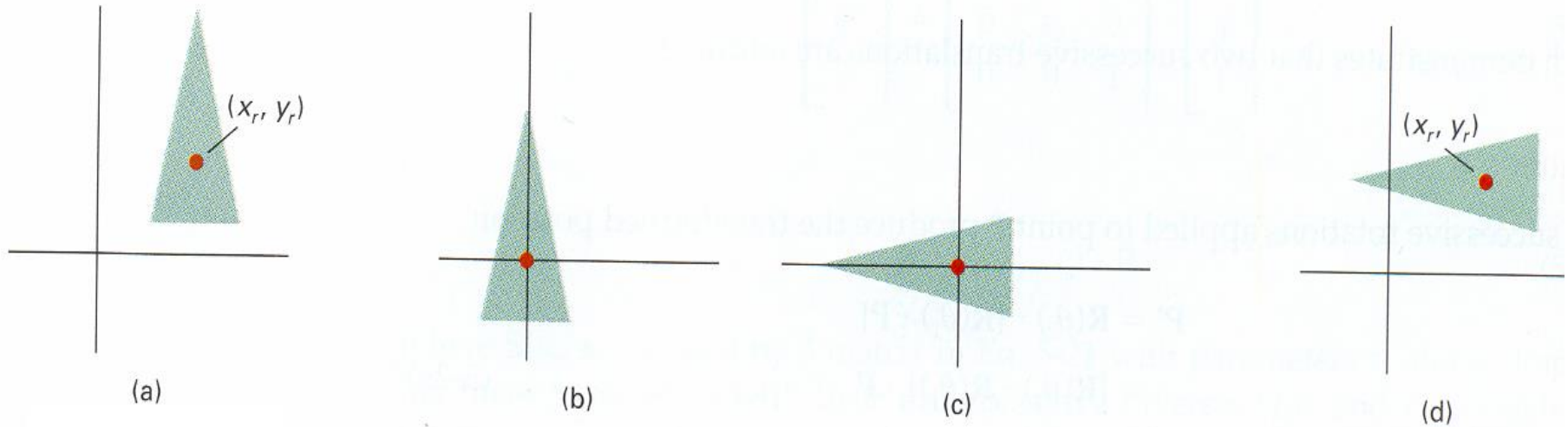
$$\mathbf{T}(t_{2x}, t_{2y}) \cdot \mathbf{T}(t_{1x}, t_{1y}) = \mathbf{T}(t_{1x} + t_{2x}, t_{1y} + t_{2y})$$

Concatenation

$$\begin{bmatrix} s_{2x} & 0 & 0 \\ 0 & s_{2y} & 0 \\ 0 & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} s_{1x} & 0 & 0 \\ 0 & s_{1y} & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} s_{1x} \cdot s_{2x} & 0 & 0 \\ 0 & s_{1y} \cdot s_{2y} & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

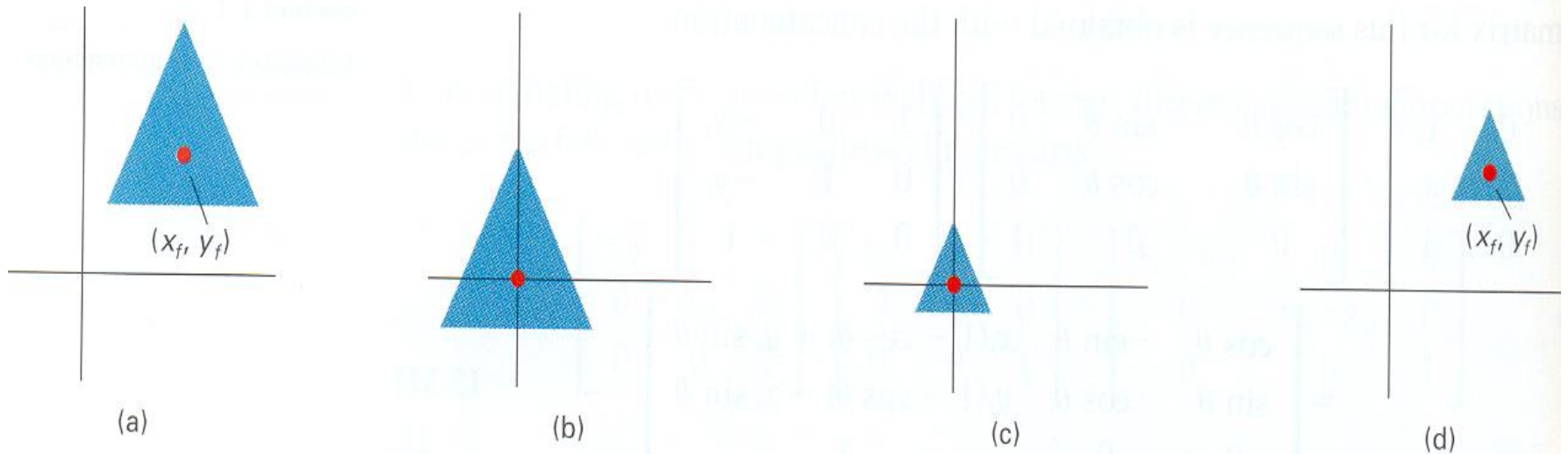
$$\mathbf{S}(s_{2x}, s_{2y}) \cdot \mathbf{S}(s_{1x}, s_{1y}) = \mathbf{S}(s_{1x} \cdot s_{2x}, s_{1y} \cdot s_{2y})$$

Arbitrary Rotation



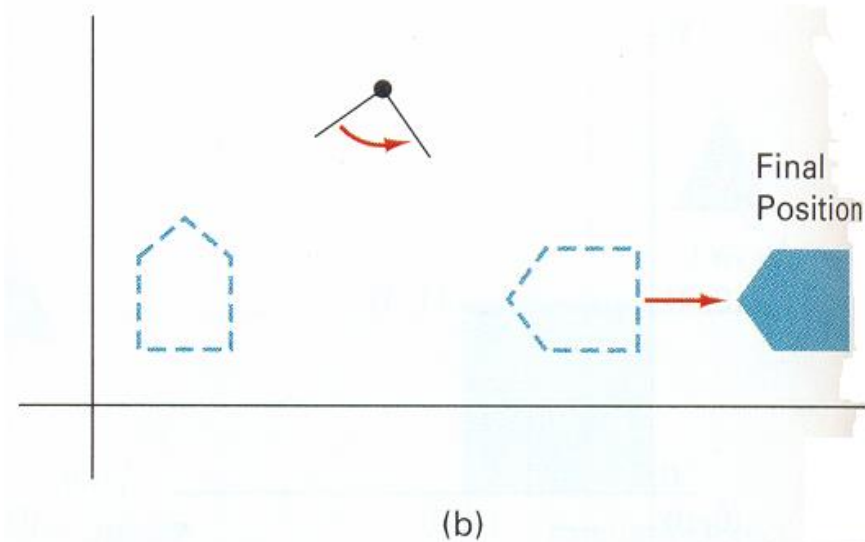
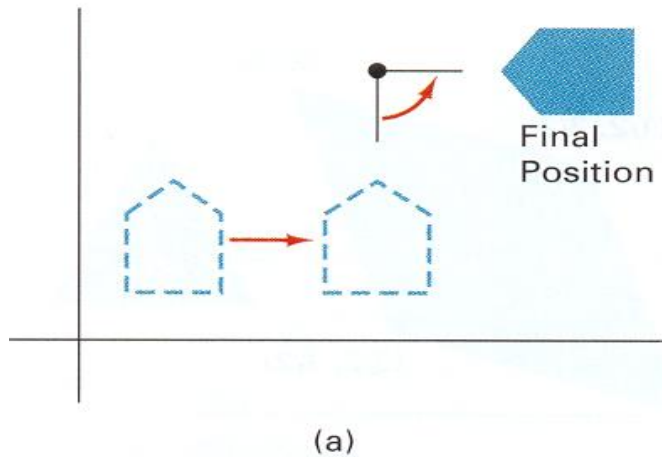
Translation + Rotation + Inverse Translation

Arbitrary Scaling



Translation + Scaling + Inverse Translation

Order is important !



3D TRANSFORMATIONS

3D Transformations

■ Translation

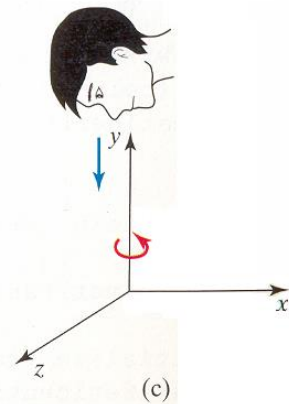
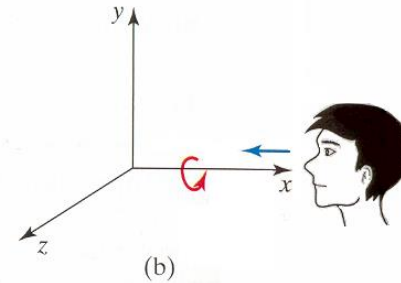
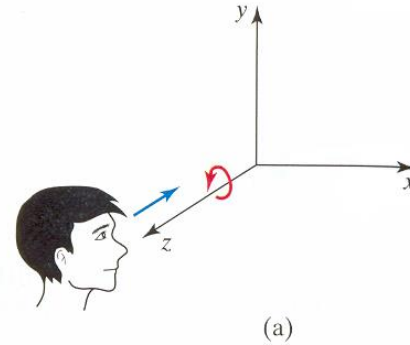
$$\begin{bmatrix} x' \\ y' \\ z' \\ 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & t_x \\ 0 & 1 & 0 & t_y \\ 0 & 0 & 1 & t_z \\ 0 & 0 & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} x \\ y \\ z \\ 1 \end{bmatrix}$$

■ Scaling

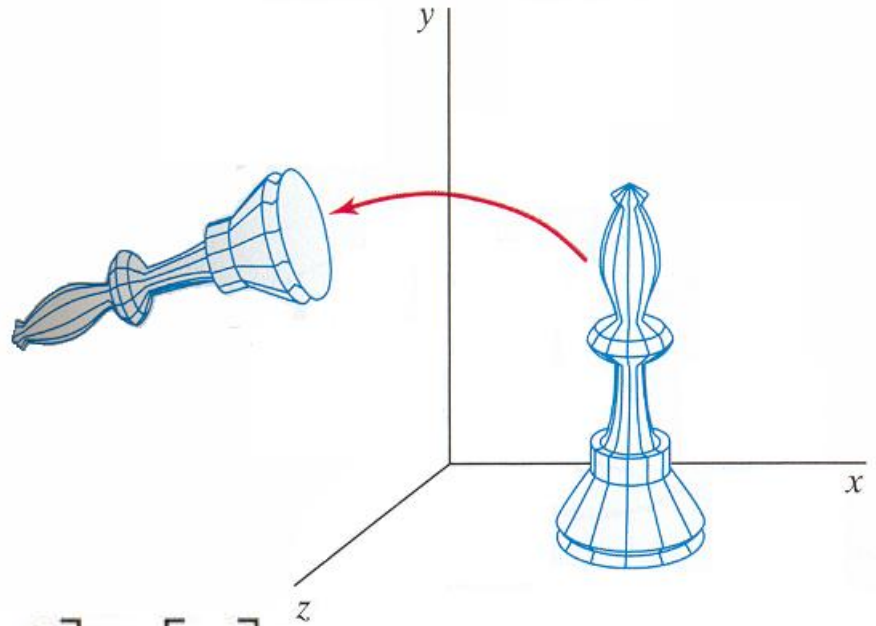
$$\mathbf{S} = \begin{bmatrix} s_x & 0 & 0 & 0 \\ 0 & s_y & 0 & 0 \\ 0 & 0 & s_z & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

3D Rotation

- **Rotation** around each one of the **coordinate axis**
- Positive rotations are **CCW !!**



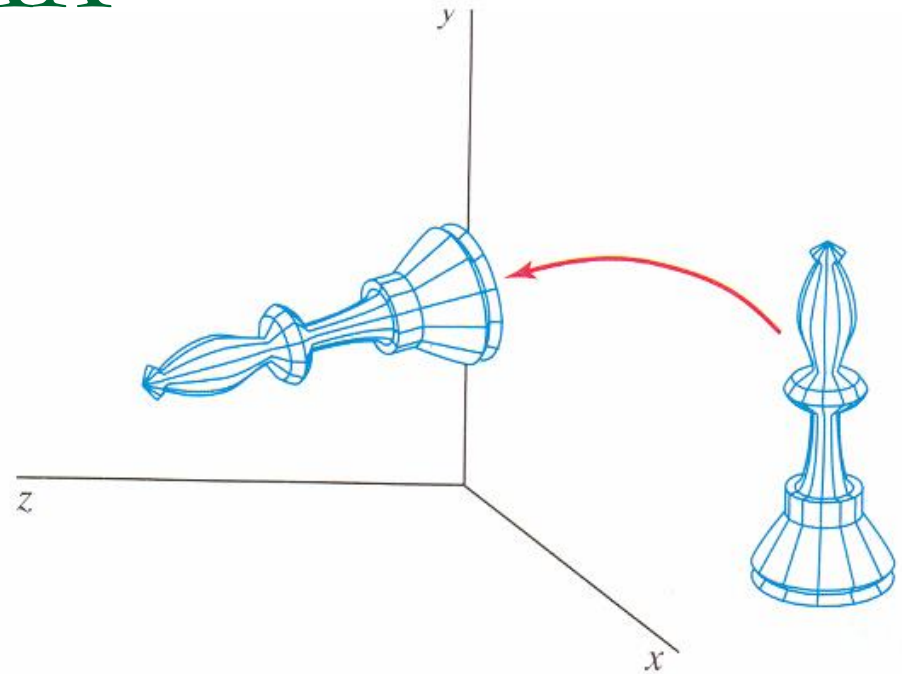
Rotation around ZZ'



$$\begin{bmatrix} x' \\ y' \\ z' \\ 1 \end{bmatrix} = \begin{bmatrix} \cos \theta & -\sin \theta & 0 & 0 \\ \sin \theta & \cos \theta & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} x \\ y \\ z \\ 1 \end{bmatrix}$$

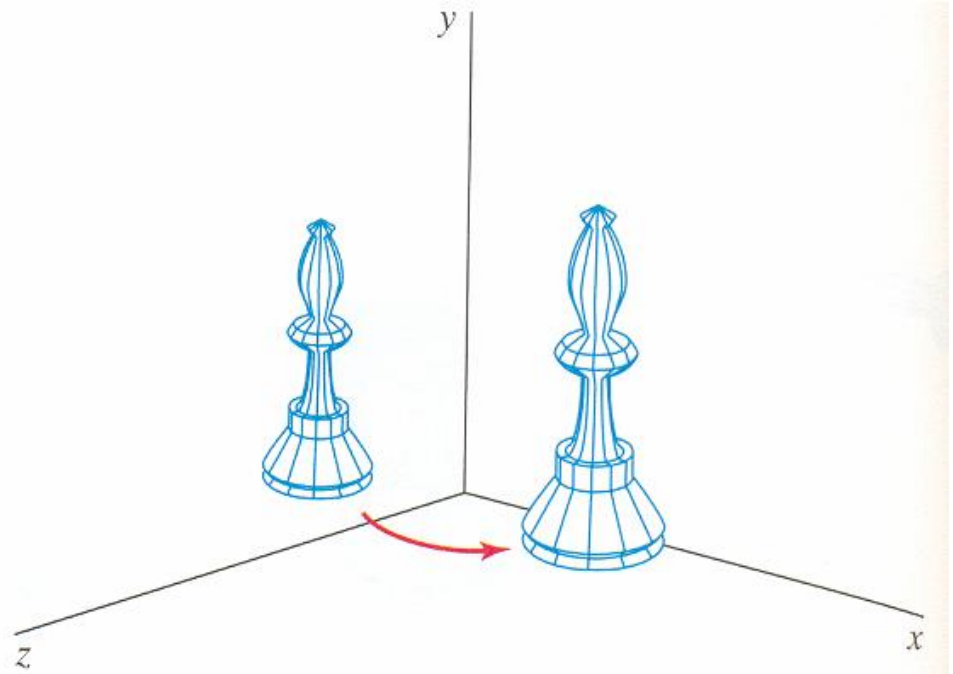


Rotation around XX'



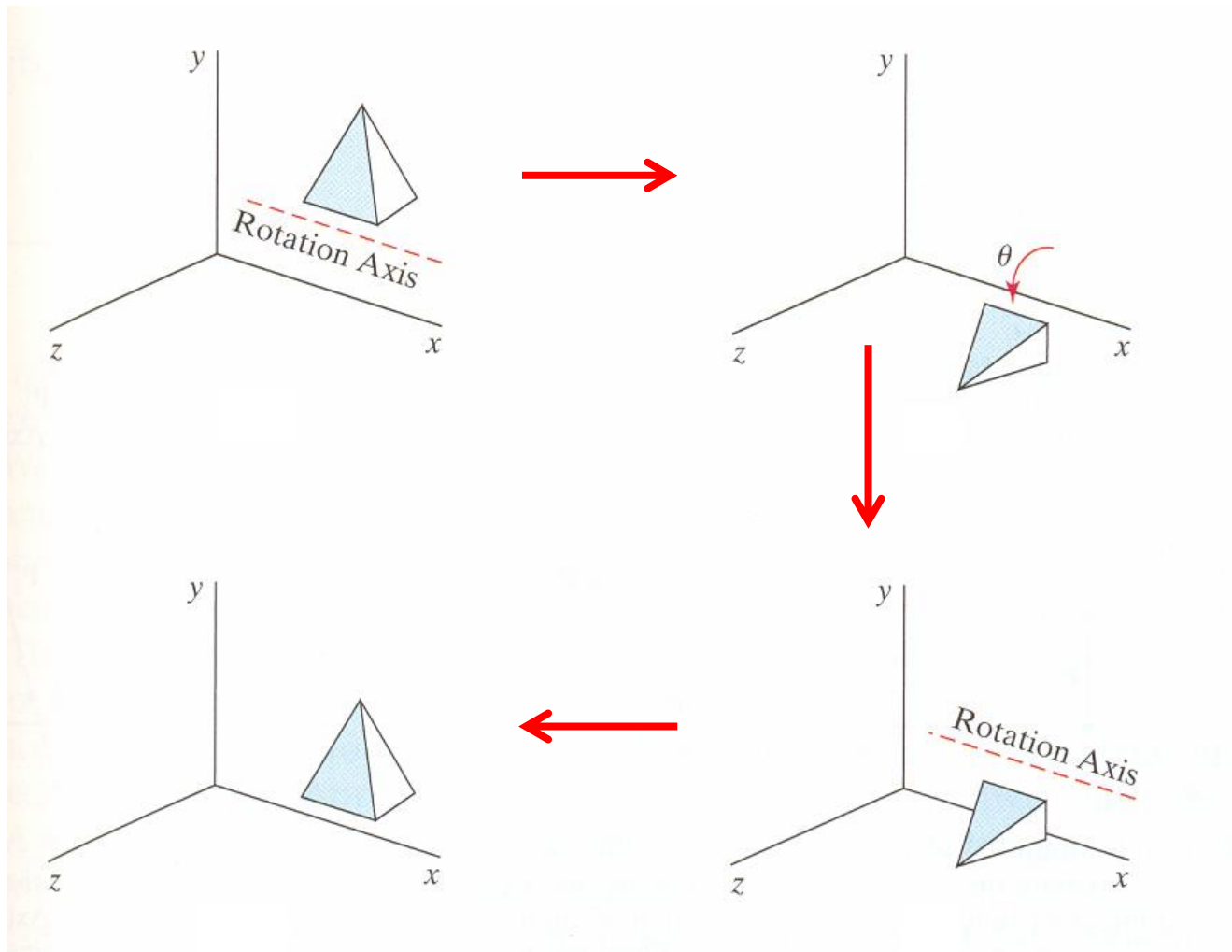
$$\begin{bmatrix} x' \\ y' \\ z' \\ 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & \cos \theta & -\sin \theta & 0 \\ 0 & \sin \theta & \cos \theta & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} x \\ y \\ z \\ 1 \end{bmatrix}$$

Rotation around YY'



$$\begin{bmatrix} x' \\ y' \\ z' \\ 1 \end{bmatrix} = \begin{bmatrix} \cos \theta & 0 & \sin \theta & 0 \\ 0 & 1 & 0 & 0 \\ -\sin \theta & 0 & \cos \theta & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} x \\ y \\ z \\ 1 \end{bmatrix}$$

Example – Decomposition



Task – Application Problems

- Solve the **first application problems !!**
- See if you have any **questions / difficulties**

Possible References

- 2D and 3D transformations are presented in any Computer Graphics book
- E. Angel and D. Shreiner. Interactive Computer Graphics, 7th Ed., Addison-Wesley, 2015
- J M Pereira, et al. Introdução à Computação Gráfica. FCA, 2018

TRANSFORMATIONS IN THREE.JS

Three.js – position

- **Position** of a model/object **relative to** the position of its **parent** in the scene graph
 - Default: (0,0,0)
- The parent is usually a **THREE.Scene** object or a **THREE.Object3D** object

```
cube.position.x=10;
```

```
cube.position.y=3;
```

```
cube.position.z=1;
```

```
cube.position.set(10,3,1);
```

```
cube.postion=new THREE.Vector3(10,3,1)
```

Three.js – scale

- **Scale factors** of a model/object relative to its **XX, YY or ZZ axis**
 - Default: (1,1,1)

Three.js – rotation

- **Rotation angle(s)** for a model/object around any one of its **XX, YY** or **ZZ axis**
 - In **radians !!**
- And the **order** in which the rotations are carried out
 - Optional argument **!!**
- Default: (0,0,0,'XYZ')

```
cube.rotation.x = 0.5*Math.PI;  
cube.rotation.set(0.5*Math.PI, 0, 0);  
cube.rotation = new THREE.Vector3(0.5*Math.PI, 0, 0);
```


Three.js – 4×4 Matrix Class

Matrix4

A class representing a 4x4 [matrix](#).

The most common use of a 4x4 matrix in 3D computer graphics is as a [Transformation Matrix](#). For an introduction to transformation matrices as used in WebGL, check out [this tutorial](#).

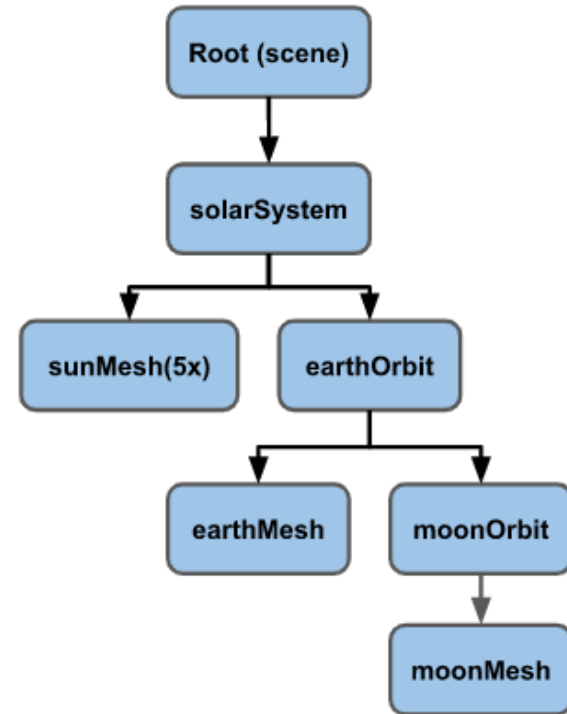
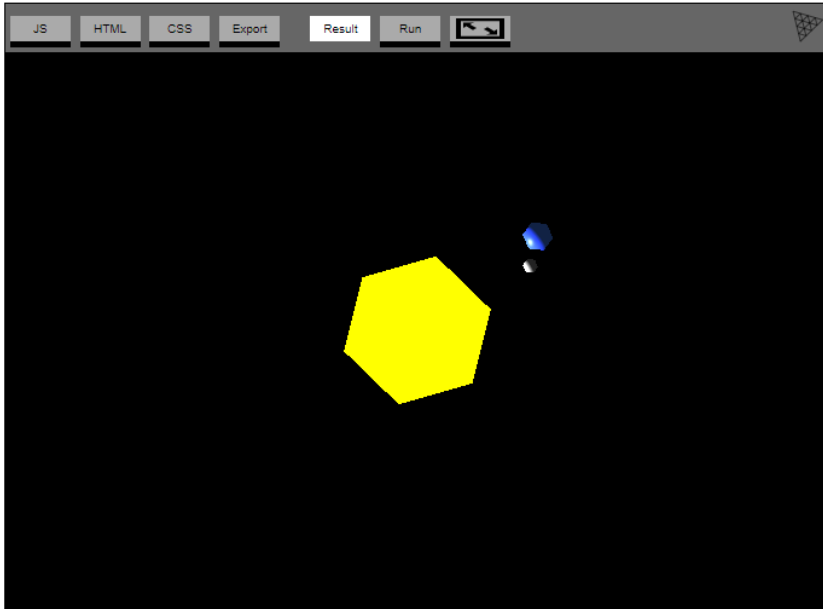
This allows a [Vector3](#) representing a point in 3D space to undergo transformations such as translation, rotation, shear, scale, reflection, orthogonal or perspective projection and so on, by being multiplied by the matrix. This is known as *applying* the matrix to the vector.

[\[https://threejs.org/docs/#api/en/math/Matrix4\]](https://threejs.org/docs/#api/en/math/Matrix4)

Local vs Global Transformations

- The **local transformation matrix** embodies the transformations defined on the **object own coordinate system**
 - **.matrix** attribute of a THREE.Object3D
- The **global transformation matrix** embodies **all transformations applied** to an object
 - **.matrixWorld** attribute of a THREE.Object3D
 - If the Object3D **has no parent**, it is identical to **.matrix**.

Local vs Global Transformations

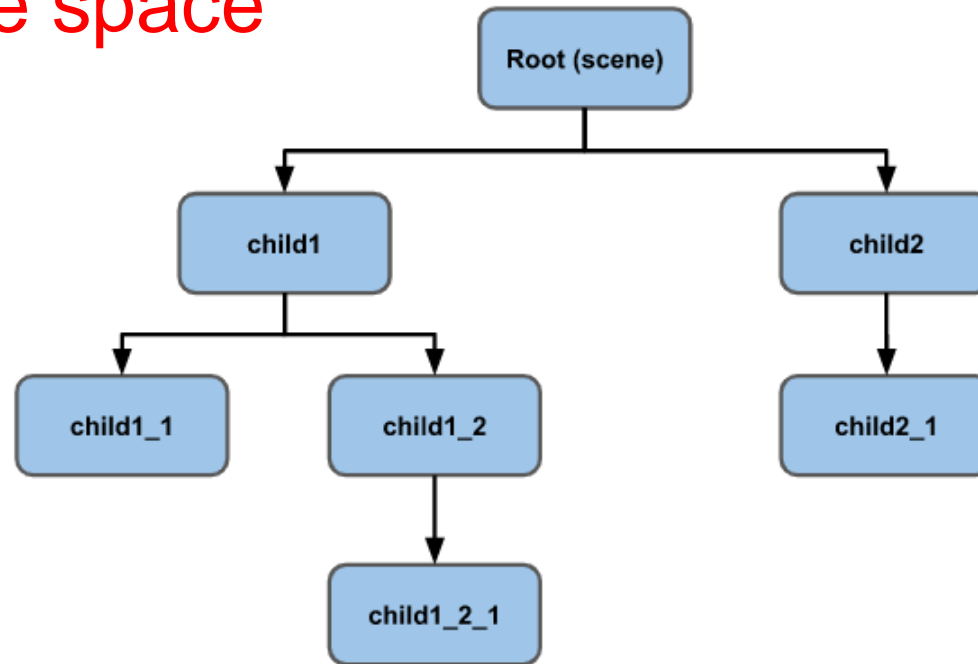


<https://threejs.org/manual/examples/scenegraph-sun-earth-moon.html>

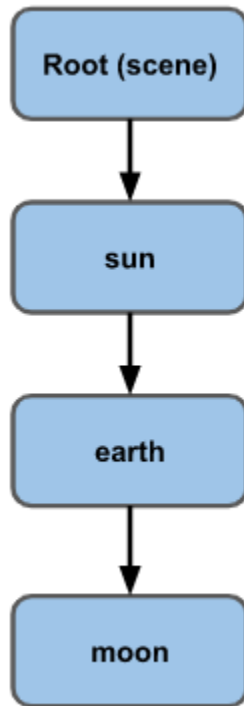
THE SCENE GRAPH

Scene Graph ?

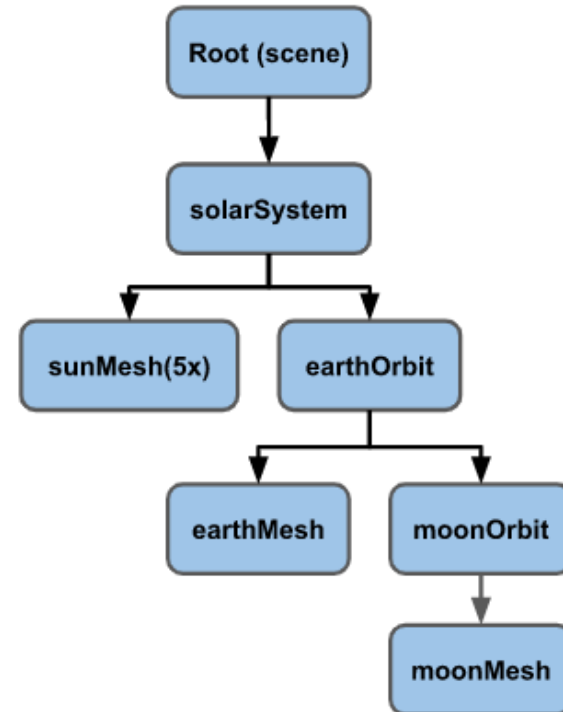
- A scene graph in a 3D engine is a **hierarchy of nodes**, where each node represents a **local coordinate space**



Simple solar system



?



The Sun

```
// an array of objects whose rotation to update
const objects = []; ←

// use just one sphere for everything
const radius = 1;
const widthSegments = 6;
const heightSegments = 6;
const sphereGeometry = new THREE.SphereGeometry(
    radius, widthSegments, heightSegments);

const sunMaterial = new THREE.MeshPhongMaterial({emissive: 0xFFFF00});
const sunMesh = new THREE.Mesh(sphereGeometry, sunMaterial);
sunMesh.scale.set(5, 5, 5); // make the sun large
scene.add(sunMesh);
objects.push(sunMesh); ←
```

The Earth

```
const earthMaterial = new THREE.MeshPhongMaterial({color: 0x2233FF, emissive: 0x112244});  
const earthMesh = new THREE.Mesh(sphereGeometry, earthMaterial);  
earthMesh.position.x = 10; ←  
scene.add(earthMesh); ←  
objects.push(earthMesh);
```

```
objects.forEach((obj) => {  
  obj.rotation.y = time;  
}); ←
```

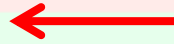
- Sun and Earth rotate around each own YY axis
 - How to improve ?

The Solar System – Objects ?

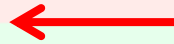
```
+ const solarSystem = new THREE.Object3D();  
+ scene.add(solarSystem);  
+ objects.push(solarSystem);
```



```
const sunMaterial = new THREE.MeshPhongMaterial({emissive: 0xFFFF00});  
const sunMesh = new THREE.Mesh(sphereGeometry, sunMaterial);  
sunMesh.scale.set(5, 5, 5);  
- scene.add(sunMesh);  
+ solarSystem.add(sunMesh);  
objects.push(sunMesh);
```



```
const earthMaterial = new THREE.MeshPhongMaterial({color: 0x2233FF, emissive: 0x112244});  
const earthMesh = new THREE.Mesh(sphereGeometry, earthMaterial);  
earthMesh.position.x = 10;  
- sunMesh.add(earthMesh);  
+ solarSystem.add(earthMesh);  
objects.push(earthMesh);
```



The Earth Orbit

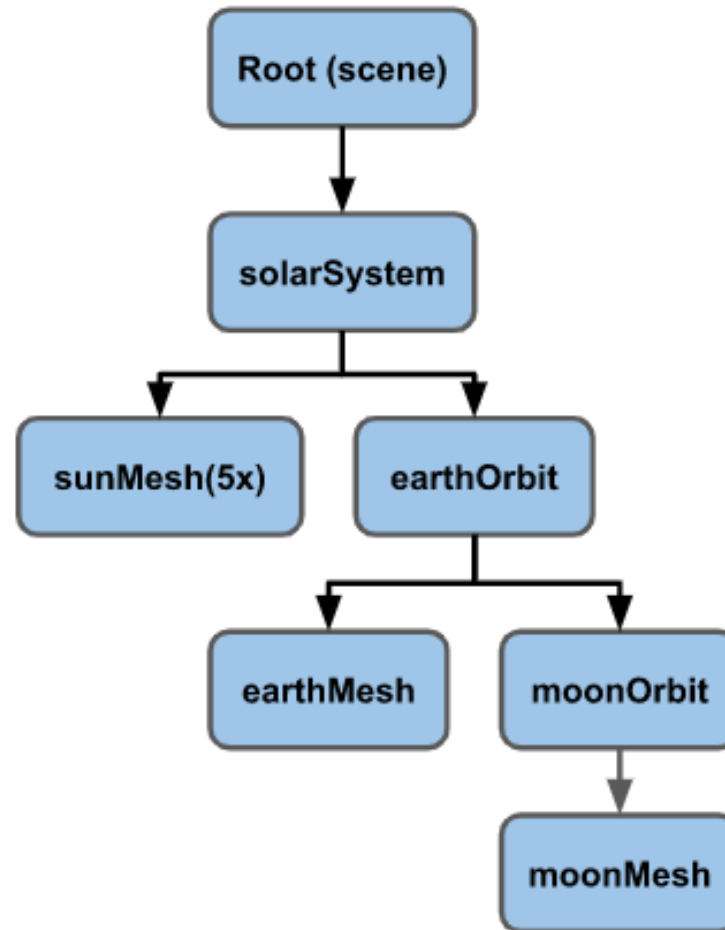
```
+ const earthOrbit = new THREE.Object3D(); ←
+ earthOrbit.position.x = 10; ←
+ solarSystem.add(earthOrbit);
+ objects.push(earthOrbit);

const earthMaterial = new THREE.MeshPhongMaterial({color: 0x2233FF, emissive: 0x112244});
const earthMesh = new THREE.Mesh(sphereGeometry, earthMaterial);
- earthMesh.position.x = 10; // note that this offset is already set in its parent's THREE
- solarSystem.add(earthMesh);
+ earthOrbit.add(earthMesh);
objects.push(earthMesh); ←
```

The Moon Orbit

```
+ const moonOrbit = new THREE.Object3D(); ←  
+ moonOrbit.position.x = 2; ←  
+ earthOrbit.add(moonOrbit);  
  
+ const moonMaterial = new THREE.MeshPhongMaterial({color: 0x888888, emissive: 0x222222});  
+ const moonMesh = new THREE.Mesh(sphereGeometry, moonMaterial);  
+ moonMesh.scale.set(.5, .5, .5); ←  
+ moonOrbit.add(moonMesh); ←  
+ objects.push(moonMesh);
```

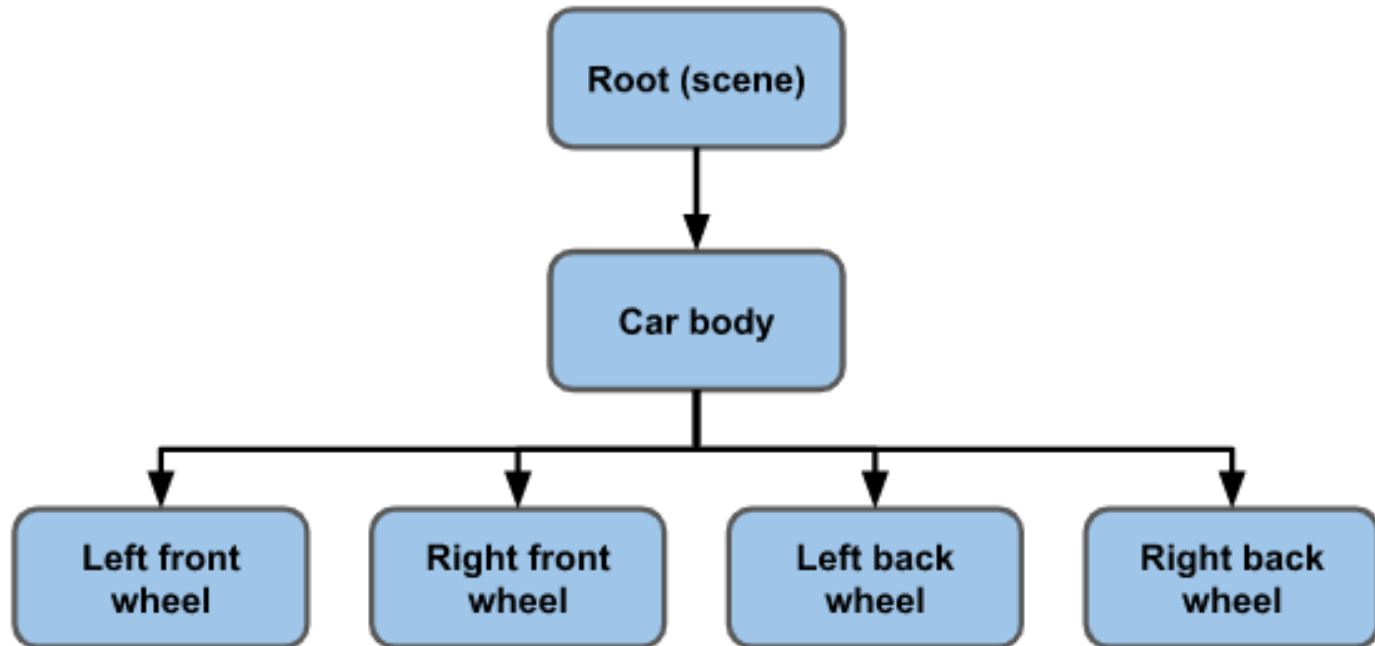
The Scene Graph



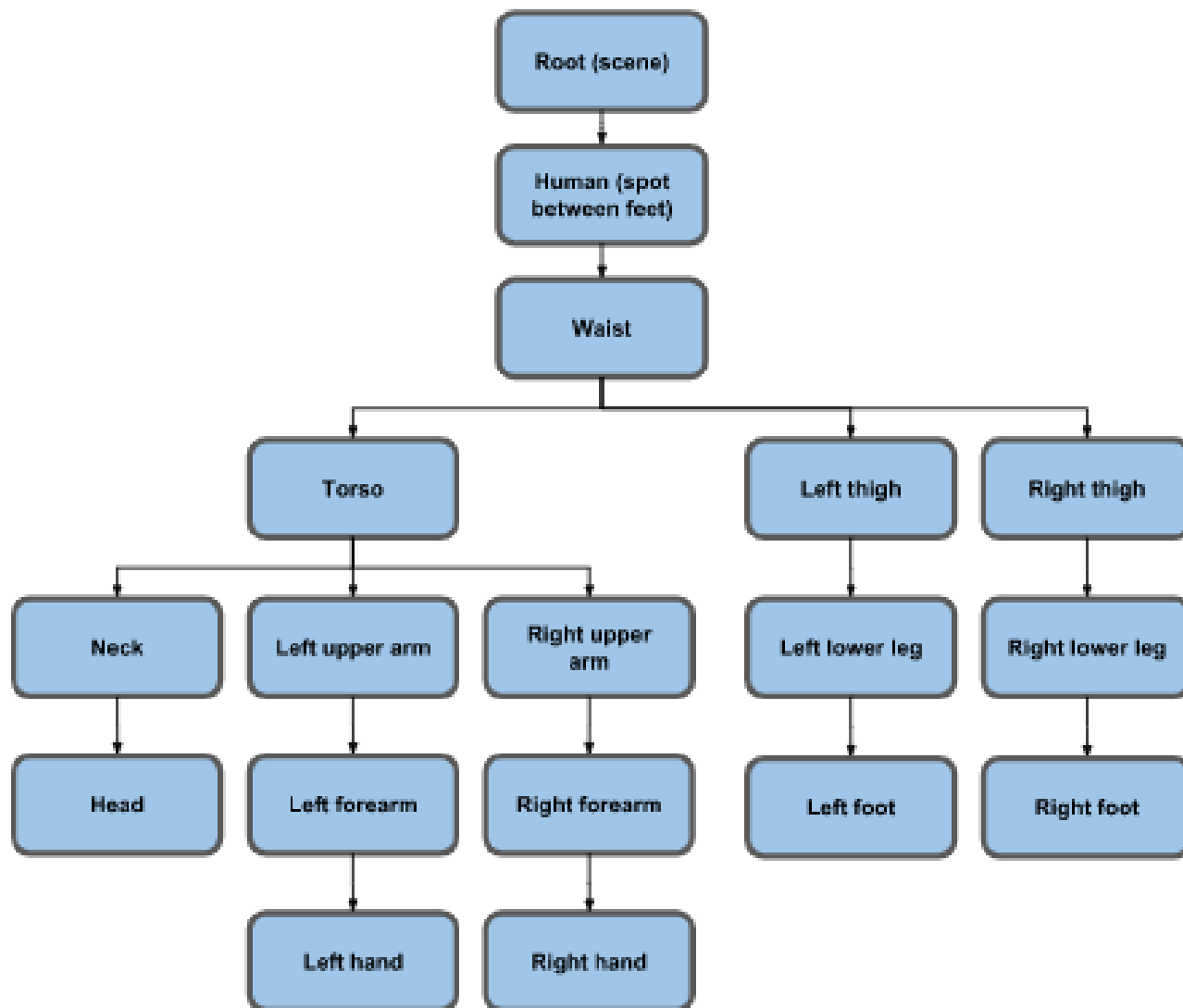
Task

- **Revise** the solar system example
<https://threejs.org/manual/#en/scenegraph>
- See if you have any **questions / difficulties !!**

Another example – A car



Example – A human in a game world



Acknowledgment

- Example code and figures taken from <https://threejs.org/manual/#en/scenegraph>