Problema 1: 28/08

With the same assumptions as in Problem 6.10 discuss the conservation of angular momentum. Show that the differential and integral forms of the conservation law are

$$\frac{\partial}{\partial t}(\mathcal{L}_{mech} + \mathcal{L}_{held}) + \nabla \cdot \overset{\leftrightarrow}{\mathbf{M}} = 0$$

and

$$\frac{d}{dt} \int_{V} d^{3}x \quad (\mathcal{L}_{mech} + \mathcal{L}_{held}) + \int_{S} da \quad \hat{\mathbf{n}} \cdot \overrightarrow{\mathbf{M}} = 0$$

where the field angular-momentum density is

$$\mathcal{L}_{field} = \mathbf{x} \times \mathbf{g} = \frac{\mu \epsilon}{4\pi c} \mathbf{x} \times (\mathbf{E} \times \mathbf{H})$$

and the flux of angular momentum is described by the tensor

$$\stackrel{\leftrightarrow}{\mathbf{M}} = \stackrel{\leftrightarrow}{\mathbf{T}} \times x$$

Note: Here we have used the diadic notation for \mathbf{M}_{ij} and \mathbf{T}_{ij} . The double-headed arrow conveys a fairly obvious meaning. For example, $\hat{n} \cdot M$ is a vector whose jth component is $\Sigma_i n_i M_{ij}$. The second-rank M can be written as a third-rank tensor $M_{ij} = T_{ij}x_k - T_{ik}x_j$. But the indices j and k is antisymmetric and so has only three independent elements. Including the index i, $M_i j$ therefore has nine components and can be written as a pseudo tensor of a second rank, as above.

Vamos assumir a conservação de momento linear deduzida em classe e também na lista de exercícios 3:

$$\frac{d}{dt}\left(\mathbf{P}_m + \mathbf{P}_c\right)_k = \sum_{m=1}^3 \oint_{S(V)} T_{km} n_m \tag{1.1}$$

Uma vez que temos o momento angular definido como o produto vetorial da posição com o momento das massas carregadas definido como

$$\mathbf{L} = \mathbf{r} \times \mathbf{P}_m \tag{1.2}$$

Assim como no caso do momento linear queremos analisar suas características de conservação. Para ser conservada temos então que visualizar sua variação no tempo dada por

$$\frac{d}{dt}\mathbf{L} = \frac{d}{dt}(\mathbf{r} \times \mathbf{P}_m)$$

$$= \frac{d}{dt}\mathbf{r} \times \mathbf{P}_m + \mathbf{r} \times \frac{d}{dt}\mathbf{P}_m$$

$$= \mathbf{r} \times \frac{d}{dt}\mathbf{P}_m$$
(1.3)

Podemos substituir 1.1 em 1.3 para trabalharmos explicitamente

$$\frac{d}{dt}\mathbf{L} = \mathbf{r} \times \frac{d}{dt}\mathbf{P}_{m}$$

$$= \mathbf{r} \times \left[\oint_{S(V)} T_{km} n_{m} - \frac{d}{dt} \int_{V} d^{3}r' \frac{1}{4\pi c} \mathbf{E} \times \mathbf{B} \right]$$
(1.4)

uma vez que

$$\frac{d}{dt}\mathbf{P}_c = \frac{d}{dt} \int_{V_{\infty}} d^3r' \frac{1}{4\pi c} \mathbf{E} \times \mathbf{B}$$
 (1.5)

Aplicando o teorema de Gauss na integral de linha em 1.4 considerando as propriedades vetoriais apontadas no enunciado do problema chegamos em

$$\frac{d}{dt}\mathbf{L} = \mathbf{r} \times \left[\int_{V_{\infty}} d^{3}r' \nabla \cdot \overrightarrow{\mathbf{T}} - \frac{d}{dt} \int_{V} d^{3}r' \frac{1}{4\pi c} \mathbf{E} \times \mathbf{B} \right]
= \int_{V_{\infty}} d^{3}r' \quad \mathbf{r} \times \left[\nabla \cdot \overrightarrow{\mathbf{T}} - \frac{d}{dt} \frac{1}{4\pi c} \mathbf{E} \times \mathbf{B} \right]
= \int_{V_{\infty}} d^{3}r' \quad \left[-\nabla \cdot \left(\mathbf{r} \times \overrightarrow{\mathbf{T}} \right) - \frac{d}{dt} \left(\mathbf{r} \times \mathbf{g} \right) \right]
= \int_{V_{\infty}} d^{3}r' \quad \left[-\nabla \cdot \overrightarrow{\mathbf{M}} - \frac{d}{dt} \left(\mathbf{r} \times \mathbf{g} \right) \right]
= \int_{V_{\infty}} d^{3}r' \quad \left[-\nabla \cdot \overrightarrow{\mathbf{M}} - \frac{d}{dt} \mathcal{L}_{field} \right]$$
(1.6)

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$$\stackrel{\leftrightarrow}{\mathbf{M}} = \stackrel{\leftrightarrow}{\mathbf{T}} \times \mathbf{r}$$
 e $\mathbf{g} \equiv \frac{1}{4\pi c} \mathbf{E} \times \mathbf{B}$.

Finalmente, podemos demonstrar as equações enunciadas anteriormente. Para isso, vamos propor uma densidade de momento angular no espaço \mathcal{L}_{mech} .

$$\mathbf{L} = \int_{V} d^{3}r' \mathcal{L}_{mech} \implies \frac{d}{dt} \mathbf{L} = \frac{d}{dt} \int_{V} d^{3}r' \mathcal{L}_{mech}$$
 (1.7)

logo,

$$\frac{d}{dt} \int_{V} d^{3}r' \mathcal{L}_{mech} = \int_{V_{\infty}} d^{3}r' \left[-\nabla \cdot \overset{\leftrightarrow}{\mathbf{M}} - \frac{d}{dt} \mathcal{L}_{field} \right]
\frac{d}{dt} \int_{V} d^{3}r' \left(\mathcal{L}_{mech} + \mathcal{L}_{field} \right) = -\int_{V_{\infty}} d^{3}r' \nabla \cdot \overset{\leftrightarrow}{\mathbf{M}}$$
(1.8)

assim,

$$\frac{d}{dt} \oint_{V} d^{3}r' \left(\mathcal{L}_{mech} + \mathcal{L}_{field} \right) + \int_{S(V)} da \quad \hat{\mathbf{n}} \cdot \dot{\mathbf{M}} = 0$$
 (1.9)

$$\frac{\partial}{\partial t} \left(\mathcal{L}_{mech} + \mathcal{L}_{field} \right) + \nabla \cdot \overset{\leftrightarrow}{\mathbf{M}} = 0 \tag{1.10}$$