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predictable process

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A predictable process is a real-valued stochastic process whose values are known, in a sense, just in advance of time. Predictable processes are also called *previsible*.

1 predictable processes in discrete time

Suppose we have a [filtration](http://planetmath.org/FiltrationOfSigmaAlgebras) $(\mathcal{F}_n)_{n \in \mathbb{Z}_+}$ on a measurable space (Ω, \mathcal{F}) . Then a stochastic process X_n is predictable if X_n is \mathcal{F}_{n-1} -[measurable](http://planetmath.org/MeasurableFunctions) for every $n \geq 1$ and X_0 is \mathcal{F}_0 -measurable. So, the value of X_n is known at the previous time step. Compare with the definition of adapted processes for which X_n is \mathcal{F}_n -measurable.

2 predictable processes in continuous time

In continuous time, the definition of predictable processes is a little more subtle. Given a filtration (\mathcal{F}_t) with time index t ranging over the non-negative real numbers, the class of predictable processes forms the smallest set of real valued stochastic processes containing all left-continuous \mathcal{F}_t -adapted processes and which is closed under taking limits of a sequence of processes.

Equivalently, a real-valued stochastic process

$$\begin{aligned} X: \mathbb{R}_+ \times \Omega &\rightarrow \mathbb{R} \\ (t, \omega) &\mapsto X_t(\omega) \end{aligned}$$

is predictable if it is measurable with respect to the predictable sigma algebra \mathcal{P} . This is defined as the smallest σ -algebra on $\mathbb{R}_+ \times \Omega$ making all left-continuous and adapted processes measurable.

Alternatively, \mathcal{P} is generated by either of the following collections of subsets of $\mathbb{R}_+ \times \Omega$

$$\begin{aligned} \mathcal{P} &= \sigma(\{(t, \infty) \times A : t \geq 0, A \in \mathcal{F}_t\} \cup \{\{0\} \times A : A \in \mathcal{F}_0\}) \\ &= \sigma(\{(T, \infty) : T \text{ is a stopping time}\} \cup \{\{0\} \times A : A \in \mathcal{F}_0\}) \\ &= \sigma(\{[T, \infty) : T \text{ is a predictable stopping time}\}) \end{aligned}$$

Note that in these definitions, the sets (T, ∞) and $[T, \infty)$ are stochastic intervals, and subsets of $\mathbb{R}_+ \times \Omega$.

3 general predictable processes

The definition of predictable process given above can be extended to a filtration (\mathcal{F}_t) with time index t lying in an arbitrary subset \mathbb{T} of the extended real numbers. In this case, the predictable sets form a σ -algebra on $\mathbb{T} \times \Omega$. If \mathbb{T} has a minimum element t_0 then let S be the collection of sets of the form $\{t_0\} \times A$ for $A \in \mathcal{F}_{t_0}$, otherwise let S be the empty set. Then, the predictable σ -algebra is defined by

$$\begin{aligned}\wp &= \sigma(\{(t, \infty] \times A : t \in \mathbb{T}, A \in \mathcal{F}_t\} \cup S) \\ &= \sigma(\{(T, \infty] : T : \Omega \rightarrow \mathbb{T} \text{ is a stopping time}\} \cup S).\end{aligned}$$

Here, $(t, \infty]$ and $(T, \infty]$ are understood to be intervals containing only times in the index set \mathbb{T} . If \mathbb{T} is an interval of the real numbers then \wp can be equivalently defined as the σ -algebra generated by the class of left-continuous and adapted processes with time index ranging over \mathbb{T} .

A stochastic process $X : \mathbb{T} \times \Omega \rightarrow \mathbb{R}$ is predictable if it is \wp -measurable. It can be verified that in the cases where $\mathbb{T} = \mathbb{Z}_+$ or $\mathbb{T} = \mathbb{R}_+$ then this definition agrees with the ones given above.