

Clase 8: Preparación para el Examen 1

(Con respuestas)

1. (Allen B. Downey, *The Little Book of Semaphores*, Second Edition, Version 2.2.1, 2016) From Chapter 3 Basic synchronization patterns. 3.6 Barrier:

El código del patrón de la barrera, en su primera versión de la página 25, se puede modelar con el programa lbs_3.6.2a.pml:

```
$ cat -n lbs_3.6.2a.pml
 1 /* The Little Book of Semaphores (2.2.1)
 2    by A. Downey
 3
 4    Chapter 3. Basic synchronization patterns
 5
 6    3.6 Barrier
 7    3.6.2 Barrier non-solution
 8 */
 9
10 #define N 3
11
12 #define wait(sem)  atomic { sem > 0; sem-- }
13 #define signal(sem) sem++
14
15 byte count=0, mutex=1, barrier=0
16
17 proctype P() {
18     do
19         :: wait(mutex)
20             count++
21             signal(mutex)
22             if
23                 :: count == N ->
24                     signal(barrier)
25                 :: else
26                     fi
27             wait(barrier)
28     od
29 }
30
31 init {
32     byte i
33
34     atomic {
35         for (i: 1 .. N) {
36             run P()
37         }
38     }
39 }
```

```
$ spin lbs_3.6.2a.pml | expand
timeout
#processes: 4
count = 4
mutex = 1
barrier = 0
41:  proc 3 (P:1) lbs_3.6.2a.pml:27 (state 13)
41:  proc 2 (P:1) lbs_3.6.2a.pml:27 (state 13)
41:  proc 1 (P:1) lbs_3.6.2a.pml:27 (state 13)
41:  proc 0 (:init::1) lbs_3.6.2a.pml:39 (state 11) <valid end state>
4 processes created
```

1a) ¿Por qué es valor final de la variable count es 4 si esta variable se incrementa solamente por 3 procesos?

Respuesta: Porque mientras los 2 procesos no completan su primera iteración, un proceso lo logra e incrementa la variable count por 2da vez.

1b) ¿Qué significa y por qué sucede timeout?

Respuesta: timeout significa que en ningún proceso activo no hay sentencias ejecutables. Aquí sucede porque los 3 procesos activos P están en la línea 27 de wait(barrier) lo que es por definición barrier > 0; ... - la condición que es falsa y por eso no ejecutable mientras la variable barrier tiene el valor 0.

2. El código anterior **no siempre** produce *deadlock*. Modifique el código anterior obteniendo el programa lbs_3.6.3a.pml y encuentre el escenario sin *deadlock* más corto posible.

Nota: El escenario buscado significa que los 3 procesos **diferentes** pasan la barrera y no que un proceso la pasa 2 veces. Para esto podría ser necesaria una identificación de cada proceso.

Respuesta: Identificaremos cada proceso con su parámetro y obtendremos el siguiente código:

```
$ cat -n lbs_3.6.3a.pml
1 /* The Little Book of Semaphores (2.2.1)
2    by A. Downey
3
4    Chapter 3. Basic synchronization patterns
5
6    3.6 Barrier
7    3.6.3 Barrier non-solution (sin deadlock)
8 */
9
10 #define N 3
11
12 #define wait(sem)  atomic { sem > 0; sem-- }
13 #define signal(sem) sem++
14
15 byte count=0, mutex=1, barrier=0
16 byte passed=0
17
18 proctype P(int i) {
19     do
20         :: wait(mutex)
21             count++
22             signal(mutex)
23             if
24                 :: count == N ->
25                     signal(barrier)
26                 :: else
27                     fi
28             wait(barrier)
29             passed=passed*10 + i
30             assert(passed!=123 && passed!=213 && passed!=231
31                 && passed!=312 && passed!=321)
32     od
33 }
34
35 init {
36     byte i
37
38     atomic {
39         for (i: 1 .. N) {
40             run P(i)
```

```

41     }
42   }
43 }

```

```

$ spin -run lbs_3.6.3a.pml | expand
pan:1: invalid end state (at depth 32)
pan: wrote lbs_3.6.3a.pml.trail

```

Ignoremos los estados finales inválidos con la opción -E del pan:

```

$ spin -run -E lbs_3.6.3a.pml | expand
pan:1: assertion violated (((((passed!=123)&&(passed!=213))&&(passed!=231))&&(passed!=312))&&(passed!=321)) (at depth 44)
pan: wrote lbs_3.6.3a.pml.trail
...
Full statespace search for:
    never claim          - (none specified)
    assertion violations +
    cycle checks        - (disabled by -DSAFETY)
    invalid end states  - (disabled by -E flag)

```

```

State-vector 48 byte, depth reached 49, errors: 1
...

```

Pero la traza corresponde al escenario cuando pasaron 3 procesos pero el contador ya está con 5 procesos, entonces el escenario obtenido no es el más corto:

```

$ spin -t -p -g lbs_3.6.3a.pml | expand
...
44:   proc  1 (P:1) lbs_3.6.3a.pml:29 (state 14)      [passed = ((passed*10)+i)]
      passed = 231
spin: lbs_3.6.3a.pml:30, Error: assertion violated
spin: text of failed assertion: assert((((passed!=123)&&(passed!=213))&&(passed!=231))&&(passed!=312))&&(passed!=321))
45:   proc  1 (P:1) lbs_3.6.3a.pml:31 (state 15)      [assert((((passed!=123)&&(passed!=213))&&(passed!=231))&&(passed!=312))&&(passed!=321)))]
spin: trail ends after 45 steps
#processes: 4
      count = 5
      mutex = 1
      barrier = 0
      passed = 231
45:   proc  3 (P:1) lbs_3.6.3a.pml:28 (state 13)
45:   proc  2 (P:1) lbs_3.6.3a.pml:28 (state 13)
45:   proc  1 (P:1) lbs_3.6.3a.pml:19 (state 16)
45:   proc  0 (:init::1) lbs_3.6.3a.pml:43 (state 11) <valid end state>
4 processes created

```

Usaremos Breadth-First Search:

```

$ spin -run -E -DBFS lbs_3.6.3a.pml | expand
Depth=    10 States=    11 Transitions=    11 Memory=   128.195
Depth=    20 States=    62 Transitions=    83 Memory=   128.195
Depth=    30 States=   502 Transitions=  1e+03 Memory=   128.195
pan:1: assertion violated (((((passed!=123)&&(passed!=213))&&(passed!=231))&&(passed!=312))&&(passed!=321)) (at depth 34)
pan: wrote lbs_3.6.3a.pml.trail
...
Warning: Search not completed
      + Breadth-First Search
      + Partial Order Reduction

```

Full statespace search for:

never claim - (none specified)
 assertion violations +
 cycle checks - (disabled by -DSAFETY)
 invalid end states - (disabled by -E flag)

State-vector 48 byte, depth reached 34, errors: 1

...

\$ spin -t -p -g lbs_3.6.3a.pml | expand

...

```

14:  proc 3 (P:1) lbs_3.6.3a.pml:20 (state 1)      [((mutex>0))]
14:  proc 3 (P:1) lbs_3.6.3a.pml:20 (state 2)      [mutex = (mutex-1)]
      mutex = 0
15:  proc 3 (P:1) lbs_3.6.3a.pml:21 (state 4)      [count = (count+1)]
      count = 1
16:  proc 3 (P:1) lbs_3.6.3a.pml:22 (state 5)      [mutex = (mutex+1)]
      mutex = 1
17:  proc 2 (P:1) lbs_3.6.3a.pml:20 (state 1)      [((mutex>0))]
17:  proc 2 (P:1) lbs_3.6.3a.pml:20 (state 2)      [mutex = (mutex-1)]
      mutex = 0
18:  proc 2 (P:1) lbs_3.6.3a.pml:21 (state 4)      [count = (count+1)]
      count = 2
19:  proc 2 (P:1) lbs_3.6.3a.pml:22 (state 5)      [mutex = (mutex+1)]
      mutex = 1
20:  proc 1 (P:1) lbs_3.6.3a.pml:20 (state 1)      [((mutex>0))]
20:  proc 1 (P:1) lbs_3.6.3a.pml:20 (state 2)      [mutex = (mutex-1)]
      mutex = 0
21:  proc 1 (P:1) lbs_3.6.3a.pml:21 (state 4)      [count = (count+1)]
      count = 3
22:  proc 3 (P:1) lbs_3.6.3a.pml:24 (state 6)      [((count==3))]
23:  proc 3 (P:1) lbs_3.6.3a.pml:25 (state 7)      [barrier = (barrier+1)]
      barrier = 1
24:  proc 3 (P:1) lbs_3.6.3a.pml:28 (state 11)     [((barrier>0))]
24:  proc 3 (P:1) lbs_3.6.3a.pml:28 (state 12)     [barrier = (barrier-1)]
      barrier = 0
25:  proc 2 (P:1) lbs_3.6.3a.pml:24 (state 6)      [((count==3))]
26:  proc 2 (P:1) lbs_3.6.3a.pml:25 (state 7)      [barrier = (barrier+1)]
      barrier = 1
27:  proc 2 (P:1) lbs_3.6.3a.pml:28 (state 11)     [((barrier>0))]
27:  proc 2 (P:1) lbs_3.6.3a.pml:28 (state 12)     [barrier = (barrier-1)]
      barrier = 0
28:  proc 2 (P:1) lbs_3.6.3a.pml:29 (state 14)     [passed = ((passed*10)+i)]
      passed = 2
29:  proc 3 (P:1) lbs_3.6.3a.pml:29 (state 14)     [passed = ((passed*10)+i)]
      passed = 23
30:  proc 1 (P:1) lbs_3.6.3a.pml:22 (state 5)      [mutex = (mutex+1)]
      mutex = 1
31:  proc 1 (P:1) lbs_3.6.3a.pml:24 (state 6)      [((count==3))]
32:  proc 1 (P:1) lbs_3.6.3a.pml:25 (state 7)      [barrier = (barrier+1)]
      barrier = 1
33:  proc 1 (P:1) lbs_3.6.3a.pml:28 (state 11)     [((barrier>0))]
33:  proc 1 (P:1) lbs_3.6.3a.pml:28 (state 12)     [barrier = (barrier-1)]
      barrier = 0
34:  proc 1 (P:1) lbs_3.6.3a.pml:29 (state 14)     [passed = ((passed*10)+i)]
      passed = 231

```

spin: lbs_3.6.3a.pml:30, Error: assertion violated

spin: text of failed assertion: assert((((passed!=123)&&(passed!=213))&&(passed!=231))&&(passed!=312))&&(passed!=321)))

```

35:  proc 3 (P:1) lbs_3.6.3a.pml:31 (state 15)      [assert((((passed!=123)&&(passed!=213))&&(passed!=231))&&(passed!=312))&&(passed!=321)))]

```

spin: trail ends after 35 steps

#processes: 4

```

      count = 3
      mutex = 1
      barrier = 0
      passed = 231

```

```

35:    proc  3 (P:1) lbs_3.6.3a.pml:19 (state 16)
35:    proc  2 (P:1) lbs_3.6.3a.pml:31 (state 15)
35:    proc  1 (P:1) lbs_3.6.3a.pml:31 (state 15)
35:    proc  0 (:init::1) lbs_3.6.3a.pml:43 (state 11) <valid end state>
4 processes created

```

Este escenario es casi de intercalación perfecta y es el más corto.

3. (*Bridge Crossing Problem*) El problema de cruce de puente para 3 personas se puede modelar y resolver con el código presentado en el programa `bridge3.pml`.

```

$ spin -run -e bridge3.pml | expand
pan:1: assertion violated (t==7) (at depth 3)
pan: wrote bridge3.pml1.trail
pan: wrote bridge3.pml2.trail
pan: wrote bridge3.pml3.trail

...
Full statespace search for:
    never claim           - (none specified)
    assertion violations  +
    cycle checks         - (disabled by -DSAFETY)
    invalid end states   +

State-vector 16 byte, depth reached 5, errors: 3
...

```

Los tiempos de las soluciones posibles son: 8, 9 y 15 minutos para 3 ($2n-3$) viajes:

```

$ spin -t1 bridge3.pml | expand
(a,b)-->, t = 2
<--a, t = 3
(a,c)-->, t = 8
tiempo total = 8
...

$ spin -t2 bridge3.pml | expand
(a,b)-->, t = 2
<--b, t = 4
(b,c)-->, t = 9
tiempo total = 9
...

$ spin -t3 bridge3.pml | expand
(a,c)-->, t = 5
<--c, t = 10
(b,c)-->, t = 15
tiempo total = 15
...

```

Para 4 personas el código se presenta en el programa `bridge4.pml`.

```

$ spin -run -e bridge4.pml | expand
pan:1: assertion violated (t==7) (at depth 5)
pan: wrote bridge4.pml1.trail
pan: wrote bridge4.pml2.trail
pan: wrote bridge4.pml3.trail
pan: wrote bridge4.pml4.trail
pan: wrote bridge4.pml5.trail
pan: wrote bridge4.pml6.trail
pan: wrote bridge4.pml7.trail

```

```

pan: wrote bridge4.pml8.trail
pan: wrote bridge4.pml9.trail
pan: wrote bridge4.pml10.trail
pan: wrote bridge4.pml11.trail
pan: wrote bridge4.pml12.trail
pan: wrote bridge4.pml13.trail
pan: wrote bridge4.pml14.trail
pan: wrote bridge4.pml15.trail

```

```

...
Full statespace search for:
    never claim          - (none specified)
    assertion violations +
    cycle checks        - (disabled by -DSAFETY)
    invalid end states  +

```

State-vector 16 byte, depth reached 7, errors: **15**

...

Son 15 soluciones para 5 ($2n-3$) viajes con los tiempos: 17, 19, 20, 21, 23, 24, 26, 27, 30, 33, 34, 36, 37, 40, 50:

```

$ spin -t1 bridge4.pml | expand

```

```

(a,b)-->, t = 2
<--a, t = 3
(a,c)-->, t = 8
<--a, t = 9
(a,d)-->, t = 19
tiempo total = 19

```

...

```

$ spin -t2 bridge4.pml | expand

```

```

(a,b)-->, t = 2
<--a, t = 3
(a,c)-->, t = 8
<--b, t = 10
(b,d)-->, t = 20
tiempo total = 20

```

...

```

$ spin -t15 bridge4.pml | expand

```

```

(a,d)-->, t = 10
<--d, t = 20
(b,d)-->, t = 30
<--d, t = 40
(c,d)-->, t = 50
tiempo total = 50

```

...

La solución con el mejor tiempo es la siguiente:

```

$ spin -t5 bridge4.pml | expand

```

```

(a,b)-->, t = 2
<--a, t = 3
(c,d)-->, t = 13
<--b, t = 15
(a,b)-->, t = 17
tiempo total = 17

```

...

En esta solución los 2 más rápidos son los quien devuelven la linterna a la orilla izquierda.

Buscaremos la solución para n personas usando las siguientes consideraciones:

- Entrada: un *array* *a* que contiene los tiempos de *n* personas numeradas 0, 1, ..., *n*-1.
- Salida: el tiempo total del cruce.
- Estrategia: usar las personas 0 y 1 como *shuttles* con linterna y enviar los otros en parejas:

```

for i ← 2 to n/2 do
  t ← a[1]           // 0 & 1 cruzan
  t ← t + a[0]       // 0 regresa
  t ← t + a[2i-1]    // 2i-1 & 2i-2 cruzan
  t ← t + a[1]       // 1 regresa
t ← t + a[1]         // 0 & 1 cruzan
return t

```

3a) Prepare el modelo correspondiente a esta propuesta en el archivo `bridgeNa.pml` para resolver el problema para 4 personas visto anteriormente obteniendo el mejor tiempo de 17 minutos.

Respuesta:

```

$ cat -n bridgeNa.pml | expand
 1  #define N 4
 2
 3  byte a[N]=0, t=0
 4
 5  proctype Bridge() {
 6      byte i
 7
 8      for (i: 2 .. N/2) {
 9          t=a[1]
10          printf("(0,1) -->      , t = %d\n", t)
11          t=t+a[0]
12          printf("      <-- (0), t = %d\n", t)
13          t=t+a[2*i-1]
14          printf("(%d,%d) -->      , t = %d\n", a[2*i-2],a[2*i-1],t)
15          t=t+a[1]
16          printf("      <-- (1), t = %d\n", t)
17      }
18      t=t+a[1]
19      printf("(0,1) -->      , t = %d\n", t)
20  }
21
22  init {
23      a[0]=1; a[1]=2; a[2]=5; a[3]=10
24      run Bridge()
25  }

```

```

$ spin bridgeNa.pml
  (0,1) -->      , t = 2
    <-- (0), t = 3
  (5,10) -->      , t = 13
    <-- (1), t = 15
  (0,1) -->      , t = 17
2 processes created

```

3b) ¿Cuáles son las precondiciones? Incorpóralas en el código obteniendo la versión del modelo en el archivo `bridgeNb.pml`. Verifique que su modelo procesa todas las precondiciones.

Respuesta: El arreglo *a* debe estar ordenado, *n* debe ser par y mayor que 3.

```

$ cat -n bridgeNb.pml | expand
 1  #define N 4
 2
 3  byte a[N]=0, t=0

```

```

4 bool sorted=true
5
6 proctype Bridge() {
7     byte i
8
9     for (i: 2 .. N/2) {
10         t=a[1]
11         printf("(0,1) -->    , t = %d\n", t)
12         t=t+a[0]
13         printf("        <-- (0), t = %d\n", t)
14         t=t+a[2*i-1]
15         printf("(d,d) -->    , t = %d\n", a[2*i-2],a[2*i-1],t)
16         t=t+a[1]
17         printf("        <-- (1), t = %d\n", t)
18     }
19     t=t+a[1]
20     printf("(0,1) -->    , t = %d\n", t)
21 }
22
23 init {
24     byte i
25
26     a[0]=1; a[1]=2; a[2]=5; a[3]=10
27     for (i: 0 .. N-2) {
28         sorted=sorted && (a[i]<=a[i+1])
29     }
30     assert(sorted)
31     assert(N%2==0 && N>3)
32     run Bridge()
33 }

```

3c) ¿Siempre se obtiene la respuesta óptima? ¿Por ejemplo, para el caso de 1, 20, 21, 22? Prepare este caso en el código `bridgeNc.pml` para obtener el tiempo. ¿Pero cuál es el mejor tiempo?

Respuesta: El algoritmo propuesto proporciona 83 minutos, mientras que el modelo del código `bridge4.pml` proporciona 65 minutos como el mejor tiempo de 65, 83, 84, 85, 86, 87, 88, 103, 104, 105, 106, 107, 108, 110 minutos.

4. (PCDP2E by M. Ben-Ari, Exercise 5 (Apt and Olderog)) Assume that for the function f , there is some integer value i for which $f(i) = 0$. This concurrent algorithm searches for i . The algorithm is correct if for all scenarios, **both** processes terminate after one of them has found the zero. Show that this algorithm is correct or find a scenario that is a counterexample.

Algorithm 2.11: Zero A	
boolean found	
p	q
integer $i \leftarrow 0$	integer $j \leftarrow 1$
p1: found \leftarrow false	q1: found \leftarrow false
p2: while not found	q2: while not found
p3: $i \leftarrow i + 1$	q3: $j \leftarrow j - 1$
p4: found $\leftarrow f(i) = 0$	q4: found $\leftarrow f(j) = 0$

Se propone el código presentado en el programa zeroA.pml:

```
$ cat -n zeroA.pml | expand
 1 #define MAX 100
 2 #define HALF MAX/2
 3
 4 #define f(x) (44 - x)
 5
 6 bool found
 7
 8 active proctype P() {
 9     byte i=HALF
10
11     found=false
12     do
13     :: found ->
14         break
15     :: else ->
16         i++
17         if
18         :: i==MAX+1 ->
19             i=HALF+1
20         :: else
21             fi
22         found = (f(i) == 0)
23     od
24 }
25
26 active proctype Q() {
27     byte j = HALF+1
28
29     found = false
30     do
31     :: found ->
32         break
33     :: else ->
34         j--
35         if
36         :: j==0 ->
37             j=HALF
38         :: else
39             fi
40         found = (f(j) == 0)
41     od
42 }
```

A veces la ejecución de este programa termina, a veces no, y hay que cortar su ejecución con Ctrl-C:

```
$ spin zeroA.pml
2 processes created
$ spin zeroA.pml
2 processes created
$ spin zeroA.pml
2 processes created
$ spin zeroA.pml
2 processes created
$ spin zeroA.pml
2 processes created
$ spin zeroA.pml
^C
$
```

¿Cómo se puede verificar el modelo? ¿Cómo se puede encontrar el escenario cuando el proceso P encuentra el valor buscado pero, en seguida, el proceso Q pone la variable found en false en la línea 29 (sin saber previamente que este escenario existe).

Respuesta:

Simplificamos el modelo para $N = 4$ e introducimos las variables ficticias para indicar la terminación de cada proceso con la fórmula de LTL correspondiente (zeroA_1.pml):

```
$ cat -n zeroA_1.pml | expand
 1 #define MAX 4 /* 1..2, 3..4 */
 2 #define HALF MAX/2
 3
 4 #define f(x) (3 - x) /* P will find it */
 5
 6 #define ok (Pexited && Qexited) /* both are terminated */
 7
 8 ltl { <>ok }
 9
10 bool found
11 bool Pexited=false, Qexited=false /* ghost variables */
12
13 active proctype P() {
14     byte i=HALF
15
16     found=false
17     do
18     :: found ->
19         break
20     :: else ->
21         i++
22         if
23             :: i==MAX+1 ->
24                 i=HALF+1
25             :: else
26                 fi
27             found = (f(i) == 0)
28         od
29     Pexited=true
30 }
31
32 active proctype Q() {
33     byte j = HALF+1
34
35     found = false
36     do
37     :: found ->
38         break
39     :: else ->
40         j--
41         if
42             :: j==0 ->
43                 j=HALF
44             :: else
45                 fi
46             found = (f(j) == 0)
47         od
48     Qexited=true
49 }

$ spin -run -a -f zeroA_1.pml | expand
pan:1: acceptance cycle (at depth 66)
pan: wrote zeroA_1.pml.trail
...
Full statespace search for:
    never claim          + (ltl_0)
    assertion violations + (if within scope of claim)
    acceptance cycles   + (fairness enabled)
```

invalid end states - (disabled by never claim)

State-vector 36 byte, depth reached 156, errors: 1

...

\$ spin -t -p -g -l zeroA_1.pml | expand

ltl ltl_0: <> ((Pexited) && (Qexited))

starting claim 2

using statement merging

Never claim moves to line 4 [(!((Pexited&&Qexited)))]

2: proc 1 (Q:1) zeroA_1.pml:35 (state 1) [found = 0]

4: proc 1 (Q:1) zeroA_1.pml:39 (state 4) [else]

6: proc 1 (Q:1) zeroA_1.pml:40 (state 5) [j = (j-1)]

Q(1):j = 2

8: proc 1 (Q:1) zeroA_1.pml:44 (state 8) [else]

10: proc 1 (Q:1) zeroA_1.pml:46 (state 11) [found = ((3-j)==0)]

12: proc 1 (Q:1) zeroA_1.pml:39 (state 4) [else]

14: proc 1 (Q:1) zeroA_1.pml:40 (state 5) [j = (j-1)]

Q(1):j = 1

16: proc 1 (Q:1) zeroA_1.pml:44 (state 8) [else]

18: proc 1 (Q:1) zeroA_1.pml:46 (state 11) [found = ((3-j)==0)]

20: proc 1 (Q:1) zeroA_1.pml:39 (state 4) [else]

22: proc 1 (Q:1) zeroA_1.pml:40 (state 5) [j = (j-1)]

Q(1):j = 0

24: proc 0 (P:1) zeroA_1.pml:16 (state 1) [found = 0]

26: proc 1 (Q:1) zeroA_1.pml:42 (state 6) [((j==0))]

26: proc 1 (Q:1) zeroA_1.pml:43 (state 7) [j = (4/2)]

Q(1):j = 2

28: proc 1 (Q:1) zeroA_1.pml:46 (state 11) [found = ((3-j)==0)]

30: proc 1 (Q:1) zeroA_1.pml:39 (state 4) [else]

32: proc 1 (Q:1) zeroA_1.pml:40 (state 5) [j = (j-1)]

Q(1):j = 1

34: proc 1 (Q:1) zeroA_1.pml:44 (state 8) [else]

36: proc 1 (Q:1) zeroA_1.pml:46 (state 11) [found = ((3-j)==0)]

38: proc 1 (Q:1) zeroA_1.pml:39 (state 4) [else]

40: proc 1 (Q:1) zeroA_1.pml:40 (state 5) [j = (j-1)]

Q(1):j = 0

42: proc 0 (P:1) zeroA_1.pml:20 (state 4) [else]

44: proc 1 (Q:1) zeroA_1.pml:42 (state 6) [((j==0))]

44: proc 1 (Q:1) zeroA_1.pml:43 (state 7) [j = (4/2)]

Q(1):j = 2

46: proc 0 (P:1) zeroA_1.pml:21 (state 5) [i = (i+1)]

P(0):i = 3

48: proc 0 (P:1) zeroA_1.pml:25 (state 8) [else]

50: proc 1 (Q:1) zeroA_1.pml:46 (state 11) [found = ((3-j)==0)]

52: proc 1 (Q:1) zeroA_1.pml:39 (state 4) [else]

54: proc 1 (Q:1) zeroA_1.pml:40 (state 5) [j = (j-1)]

Q(1):j = 1

56: proc 1 (Q:1) zeroA_1.pml:44 (state 8) [else]

58: proc 1 (Q:1) zeroA_1.pml:46 (state 11) [found = ((3-j)==0)]

60: proc 1 (Q:1) zeroA_1.pml:39 (state 4) [else]

62: proc 1 (Q:1) zeroA_1.pml:40 (state 5) [j = (j-1)]

Q(1):j = 0

64: proc 1 (Q:1) zeroA_1.pml:42 (state 6) [((j==0))]

64: proc 1 (Q:1) zeroA_1.pml:43 (state 7) [j = (4/2)]

Q(1):j = 2

66: proc 0 (P:1) zeroA_1.pml:27 (state 11) [found = ((3-i)==0)]

found = 1

<<<<<START OF CYCLE>>>>>

68: proc 1 (Q:1) zeroA_1.pml:46 (state 11) [found = ((3-j)==0)]

found = 0

70: proc 1 (Q:1) zeroA_1.pml:39 (state 4) [else]

72: proc 1 (Q:1) zeroA_1.pml:40 (state 5) [j = (j-1)]

Q(1):j = 1

74: proc 1 (Q:1) zeroA_1.pml:44 (state 8) [else]

76: proc 1 (Q:1) zeroA_1.pml:46 (state 11) [found = ((3-j)==0)]

```

78:    proc 1 (Q:1) zeroA_1.pml:39 (state 4) [else]
80:    proc 1 (Q:1) zeroA_1.pml:40 (state 5) [j = (j-1)]
      Q(1):j = 0
82:    proc 1 (Q:1) zeroA_1.pml:42 (state 6) [((j==0))]
82:    proc 1 (Q:1) zeroA_1.pml:43 (state 7) [j = (4/2)]
      Q(1):j = 2
84:    proc 0 (P:1) zeroA_1.pml:20 (state 4) [else]
86:    proc 0 (P:1) zeroA_1.pml:21 (state 5) [i = (i+1)]
      P(0):i = 4
88:    proc 0 (P:1) zeroA_1.pml:25 (state 8) [else]
90:    proc 1 (Q:1) zeroA_1.pml:46 (state 11) [found = ((3-j)==0)]
92:    proc 1 (Q:1) zeroA_1.pml:39 (state 4) [else]
94:    proc 1 (Q:1) zeroA_1.pml:40 (state 5) [j = (j-1)]
      Q(1):j = 1
96:    proc 1 (Q:1) zeroA_1.pml:44 (state 8) [else]
98:    proc 1 (Q:1) zeroA_1.pml:46 (state 11) [found = ((3-j)==0)]
100:   proc 1 (Q:1) zeroA_1.pml:39 (state 4) [else]
102:   proc 1 (Q:1) zeroA_1.pml:40 (state 5) [j = (j-1)]
      Q(1):j = 0
104:   proc 1 (Q:1) zeroA_1.pml:42 (state 6) [((j==0))]
104:   proc 1 (Q:1) zeroA_1.pml:43 (state 7) [j = (4/2)]
      Q(1):j = 2
106:   proc 0 (P:1) zeroA_1.pml:27 (state 11) [found = ((3-i)==0)]
108:   proc 1 (Q:1) zeroA_1.pml:46 (state 11) [found = ((3-j)==0)]
110:   proc 1 (Q:1) zeroA_1.pml:39 (state 4) [else]
112:   proc 1 (Q:1) zeroA_1.pml:40 (state 5) [j = (j-1)]
      Q(1):j = 1
114:   proc 1 (Q:1) zeroA_1.pml:44 (state 8) [else]
116:   proc 1 (Q:1) zeroA_1.pml:46 (state 11) [found = ((3-j)==0)]
118:   proc 1 (Q:1) zeroA_1.pml:39 (state 4) [else]
120:   proc 1 (Q:1) zeroA_1.pml:40 (state 5) [j = (j-1)]
      Q(1):j = 0
122:   proc 1 (Q:1) zeroA_1.pml:42 (state 6) [((j==0))]
122:   proc 1 (Q:1) zeroA_1.pml:43 (state 7) [j = (4/2)]
      Q(1):j = 2
124:   proc 0 (P:1) zeroA_1.pml:20 (state 4) [else]
126:   proc 0 (P:1) zeroA_1.pml:21 (state 5) [i = (i+1)]
      P(0):i = 5
128:   proc 1 (Q:1) zeroA_1.pml:46 (state 11) [found = ((3-j)==0)]
130:   proc 0 (P:1) zeroA_1.pml:23 (state 6) [((i==(4+1)))]
130:   proc 0 (P:1) zeroA_1.pml:24 (state 7) [i = ((4/2)+1)]
      P(0):i = 3
132:   proc 1 (Q:1) zeroA_1.pml:39 (state 4) [else]
134:   proc 1 (Q:1) zeroA_1.pml:40 (state 5) [j = (j-1)]
      Q(1):j = 1
136:   proc 1 (Q:1) zeroA_1.pml:44 (state 8) [else]
138:   proc 1 (Q:1) zeroA_1.pml:46 (state 11) [found = ((3-j)==0)]
140:   proc 1 (Q:1) zeroA_1.pml:39 (state 4) [else]
142:   proc 1 (Q:1) zeroA_1.pml:40 (state 5) [j = (j-1)]
      Q(1):j = 0
144:   proc 1 (Q:1) zeroA_1.pml:42 (state 6) [((j==0))]
144:   proc 1 (Q:1) zeroA_1.pml:43 (state 7) [j = (4/2)]
      Q(1):j = 2
146:   proc 0 (P:1) zeroA_1.pml:27 (state 11) [found = ((3-i)==0)]
      found = 1
spin: trail ends after 146 steps
#processes: 2
      found = 1
      Pexited = 0
      Qexited = 0
146:   proc 1 (Q:1) zeroA_1.pml:46 (state 11)
146:   proc 0 (P:1) zeroA_1.pml:17 (state 12)
146:   proc - (ltrl_0:1) _spin_nvr.tmp:3 (state 3)
2 processes created

```

O eliminando las variables ficticias (zeroA_2.pml):

```
$ cat -n zeroA_2.pml | expand
 1 #define MAX 4
 2 #define HALF MAX/2
 3
 4 #define f(x) (3 - x)
 5
 6 #define ok (P@Pexited && Q@Qexited)
 7
 8 ltl { <>ok }
 9
10 bool found
11
12 active proctype P() {
13     byte i=HALF
14
15     found=false
16     do
17         :: found ->
18             break
19         :: else ->
20             i++
21             if
22                 :: i==MAX+1 ->
23                     i=HALF+1
24                 :: else
25                     fi
26             found = (f(i) == 0)
27     od
28 Pexited:
29 }
30
31 active proctype Q() {
32     byte j = HALF+1
33
34     found = false
35     do
36         :: found ->
37             break
38         :: else ->
39             j--
40             if
41                 :: j==0 ->
42                     j=HALF
43                 :: else
44                     fi
45             found = (f(j) == 0)
46     od
47 Qexited:
48 }

$ spin -run -a -f zeroA_2.pml | expand
pan:1: acceptance cycle (at depth 144)
pan: wrote zeroA_2.pml.trail
...
Full statespace search for:
    never claim                + (ltl_0)
    assertion violations       + (if within scope of claim)
    acceptance cycles          + (fairness enabled)
    invalid end states         - (disabled by never claim)

State-vector 36 byte, depth reached 145, errors: 1
...
```

```

$ spin -t -p -g -l zeroA_2.pml | expand
ltl ltl_0: <> (((P@Pexited)) && ((Q@Qexited)))
...
66:   proc 0 (P:1) zeroA_2.pml:26 (state 11) [found = ((3-i)==0)]
      found = 1
68:   proc 1 (Q:1) zeroA_2.pml:45 (state 11) [found = ((3-j)==0)]
      found = 0
...

```

Para aislar el caso específico cuando el proceso P encuentra el valor colocando true en la variable found pero, en seguida, recién comienza ejecutarse el proceso Q inicializando con false la misma variable (zeroA_3.pml):

```

$ cat -n zeroA_3.pml | expand
1  #define MAX 4
2  #define HALF MAX/2
3
4  #define f(x) (3 - x)
5
6  ltl { !P@Pfound U Q@Qstart } /* Process P will not pass to Pfound UNTIL
7                                process Q reaches Qstart */
8
9  bool found
10
11  active proctype P() {
12    byte i=HALF
13
14    found=false
15    do
16      :: found ->
17        break
18      :: else ->
19        i++
20        if
21          :: i==MAX+1 ->
22            i=HALF+1
23          :: else
24            fi
25        found = (f(i) == 0)
26  Pfound:
27    od
28  }
29
30  active proctype Q() {
31    byte j = HALF+1
32
33    found = false
34  Qstart:
35    do
36      :: found ->
37        break
38      :: else ->
39        j--
40        if
41          :: j==0 ->
42            j=HALF
43          :: else
44            fi
45        found = (f(j) == 0)
46    od
47  }

```

```

$ spin -run -a -f zeroA_3.pml | expand
pan:1: assertion violated  !(( !( !(P._p==Pfound)))&& !((Q._p==Qstart)))) (at depth
10)
pan: wrote zeroA_3.pml.trail
...
Full statespace search for:
    never claim          + (ltl_0)
    assertion violations + (if within scope of claim)
    acceptance cycles   + (fairness enabled)
    invalid end states  - (disabled by never claim)

State-vector 36 byte, depth reached 16, errors: 1
...

$ spin -t -p -g -l zeroA_3.pml | expand
ltl ltl_0: (! ((P@Pfound))) U ((Q@Qstart))
starting claim 2
using statement merging
Never claim moves to line 4      [(!((Q._p==Qstart)))]
  2:   proc  0 (P:1) zeroA_3.pml:14 (state 1) [found = 0]
  4:   proc  0 (P:1) zeroA_3.pml:18 (state 4) [else]
  6:   proc  0 (P:1) zeroA_3.pml:19 (state 5) [i = (i+1)]
      P(0):i = 3
  8:   proc  0 (P:1) zeroA_3.pml:23 (state 8) [else]
 10:   proc  0 (P:1) zeroA_3.pml:25 (state 11) [found = ((3-i)==0)]
      found = 1
spin: _spin_nvr.tmp:5, Error: assertion violated
spin: text of failed assertion: assert(!(((P._p==Pfound)))&& !((Q._p==Qstart))))
Never claim moves to line 5      [assert(!(((P._p==Pfound)))&& !((Q._p==Qstart))))]
spin: trail ends after 11 steps
#processes: 2
      found = 1
      Pfound = 0
      Qstart = 0
 11:   proc  1 (Q:1) zeroA_3.pml:33 (state 1)
 11:   proc  0 (P:1) zeroA_3.pml:27 (state 12)
 11:   proc  - (ltl_0:1) _spin_nvr.tmp:3 (state 6)
2 processes created

```