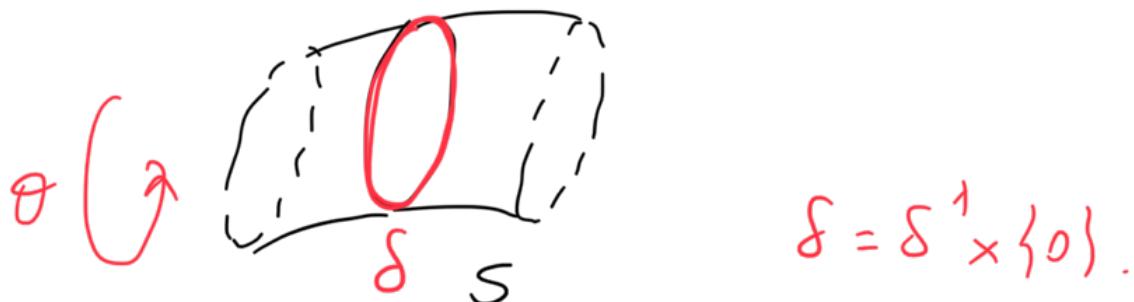


Otros ejemplos:

③

$$S = S^1 \times (-1, 1) . \quad \text{cilindro.}$$



Calcular $H_{DR}^1(S)$

Consideramos

$$U = (S^1 \setminus N) \times (-1, 1) \approx \mathbb{R}^2$$

$$V = (S^1 \setminus S_{\text{sur}}) \times (-1, 1) \approx \mathbb{R}^2$$

Notar

$U \cap V$ no es conexa!

$U \cap V$ Tiene dos componentes conexas:

$$U \cap V = (S^1 \setminus N \cup S) \times (-1, 1).$$

$$\gamma_1 \cup \gamma_2$$



$$\bar{\gamma}_1 \cup \bar{\gamma}_2 \text{ (proj. a } S^1\text{).}$$

Afirmación: $L^1 \hookrightarrow \Phi_{\gamma, D}$

$\text{DR}^{\wedge \wedge} \rightarrow \text{IR}$ isomorfismo.

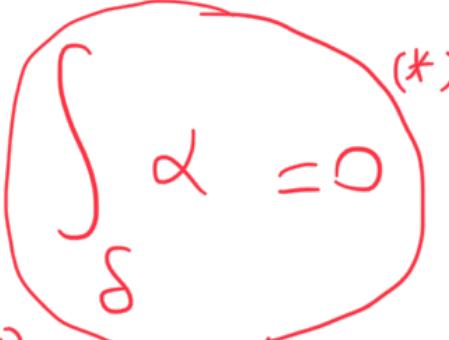
$$\alpha \mapsto \int_{\gamma} \alpha$$

✓ sobrey: $\alpha = d\theta$

• inyectiva:

sea α cerrada. ($d\alpha = 0$)

$$y \quad \forall(\alpha) = 0 \Rightarrow \alpha = 0.$$

 (*)

$\int_{\gamma} \alpha = 0 \Rightarrow \alpha = 0$

? α exacta.

Si (*) se cumple
se puede construir $f \in \mathcal{C}^{\infty}(S)$ tq.

$$df = \alpha ?$$

Como en el caso de $S = \underline{S^2}$,

$$\cdot d|_U = df_u \quad f_u: U \rightarrow \mathbb{R}$$

$$\cdot d|_V = df_v \quad f_v: V \rightarrow \mathbb{R}.$$

$f_u - f_v$ definida en $U \cap V = Y_1 \cup Y_2$

=====

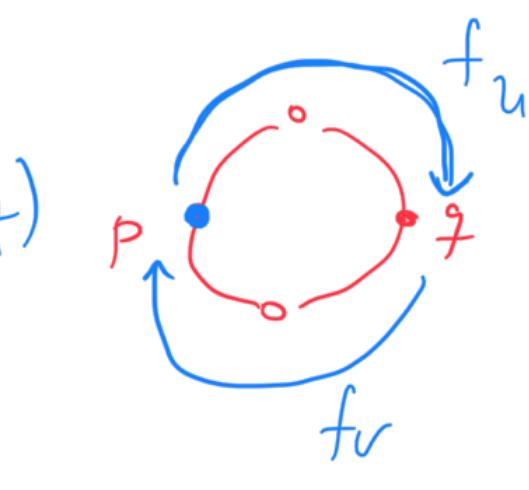
(dos comp.
conexas)

Pare probar que $f_u - f_v \sim \text{cte.}$
 Sean $p, q \in \cup Y$ $p \in Y_1, q \in Y_2$

$$(f_u - f_v)(p) - (f_u - f_v)(q)$$

$$= \pm \int_S \alpha$$

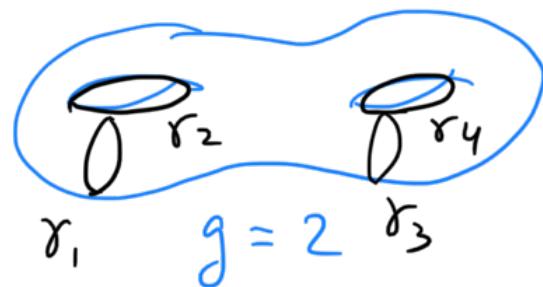
$$\downarrow \\ 0.$$



$$\left\{ \begin{array}{l} f_u(f_q) - f_u(p) \\ + f_v(p) - f_v(q) \end{array} \right.$$

$$\textcircled{4} \quad S = \text{bitono}$$

$$= S_g, g=2$$



$$= T_1 \# T_2$$

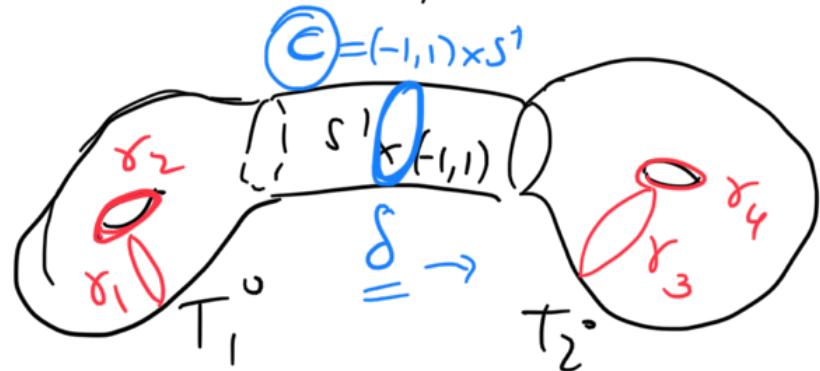


removemos los discos



usamos $S^1 \times (-1, 1)$

para "pegarlos"



$$S_2 = T_1 \# T_2$$

Afirmación:

$$H_{DR}^1(S_2) = \mathbb{R}^4$$

(en general

$$H_{DR}^1(S_g) = \mathbb{R}^{2g})$$

✓ a través del isomorfismo

$$\rho: H_{DR}^1(S_2) \longrightarrow \mathbb{R}^4$$

$$\alpha \longmapsto \left(\int_{\gamma_1} \alpha, \int_{\gamma_2} \alpha, \int_{\gamma_3} \alpha, \int_{\gamma_4} \alpha \right)$$

ρ inyectiva:

supongamos $\alpha \in H_{DR}^1(S_2)$ tal que
 $\rho(\alpha) = 0 \rightarrow (\alpha = 0)$

$$\rho(\alpha) = 0 .$$

Así

$$\int_{\gamma_i} \alpha = 0 \quad \forall i=1,\dots,4. \quad (**)$$

Debemos mostrar $\alpha = 0$ (α exacta).

Notar:

$$\int_S \alpha = ?$$



Por Stokes:

$$\left(\int_S \alpha \right) = \int_{S'} d\alpha = 0$$

Luego: por el ejm. anterior, existe

$g \in C^\infty(C)$ tal que

$$\alpha = dg \text{ en } C.$$

① Sea P función suave en S con soporte en $C = (-1, 1) \times S^1 \subseteq S$

$$\text{tal que } P|_S = 1$$

- Consideramos



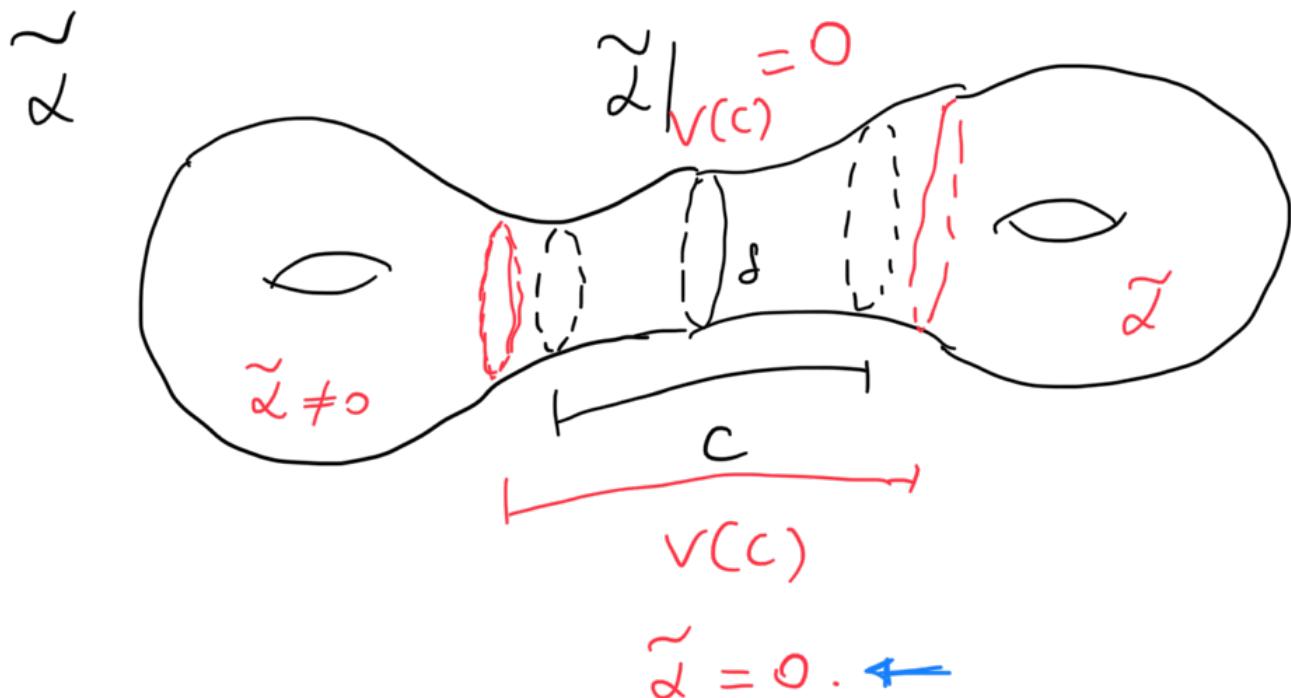
$$1/P_n$$

$$\tilde{\alpha} = \alpha - \alpha' \gamma'$$

Notar $\tilde{\alpha} = \alpha$ en $H_{DR}^1(S)$

Además

$\tilde{\alpha}$ se anula en una vecindad de C .



$\tilde{\alpha}$ genera dos formas en T_1 y T_2



$\tilde{\alpha} = 0.$ ←

$\tilde{\alpha}$ genera dos formas en T_1 y T_2

También

$$\int_{\gamma_1} \beta = \int_{\gamma_2} \beta = 0$$

$$\int_{\gamma_3} \beta' = \int_{\gamma_4} \beta' = 0$$

β es 1-forma exacta
en T_1
(ejm. anterio)

$$\beta = df$$

$$f \in C^\infty(T_1)$$

β' es 1-forma
exacta
en T_2
(ejm. anterior)

$$\beta' = df'$$

$$f' \in C^\infty(T_2)$$

$$d(f - f') = 0$$

$f - f'$ def.
en $V(C)$

$$f = f' \text{ en } V(C) \approx \tilde{T}_1 \cap \tilde{T}_2$$

↑
recindido
de
 T_1 ↑
recindido
de T_2



$\Rightarrow f$ y f' se pueden pegar y obteneremos

$$\text{así } \exists \tilde{f} = \begin{cases} f & \text{en } \tilde{T}_1 \\ f' & \text{en } \tilde{T}_2 \end{cases}$$

de modo que \tilde{f} es 1-forma

$$\alpha = df.$$

$$\Rightarrow \alpha = 0 \text{ en } H^1(S_2).$$

Obs:

En general

$$H_{DR}^1(S_g) \simeq \mathbb{R}^{2g} \simeq \mathbb{R}^g \oplus \mathbb{R}^g \\ H^{1,0} \quad H^{0,1}$$

Sea X una superficie de Riemann.

$$p \in X$$

$$T^*X_p = \text{Hom}_{\mathbb{R}}(TX, \mathbb{R})$$

Complexificamos:

$$T^*X_p^{\mathbb{C}} = \text{Hom}_{\mathbb{R}}(TX, \mathbb{C})$$

$$\simeq T^*X_p \otimes_{\mathbb{R}} \mathbb{C}.$$

Notar:

$$T^*X \simeq \mathbb{C}^n$$

$$| \quad X_p \simeq \mathbb{K} \{ dx, dy \}.$$

$$T^*X_p \otimes \mathbb{C} \simeq \mathbb{C} \{ dx, dy \}.$$

$$\simeq \mathbb{C} \{ dz, d\bar{z} \}$$

Donde $\begin{cases} dz = dx + i dy \\ d\bar{z} = dx - i dy \end{cases}$

Así:

- $T^*X_p \otimes \mathbb{C} = \underbrace{T^*X_p'}_{\text{parte holomorfa}} \oplus \underbrace{T^*X_p''}_{\text{parte antiholomorfa}}$

$$\mathbb{C} \{ dz \} \oplus \mathbb{C} \{ d\bar{z} \}$$

De ese modo $f: X \rightarrow \mathbb{C}$ función

holomorfa, entonces

$$df \in T^*X_p'$$

$$d\bar{f} \in T^*X_p''.$$

Asimismo

...*

fibres
 cotang.
 $\downarrow \pi$
 X

$\int s$: 1-formas dif. son
 secciones globales del
 fibrado cotangente.

$$\Omega^1_{X, \mathbb{C}} = \Gamma(X, T^* X_p \otimes \mathbb{C})$$

secciones globales

$$= \underbrace{\Omega^{1,0}_X}_{\text{rango en } T^* X_p^1} \oplus \underbrace{\Omega^{0,1}_X}_{\text{rango en } T^* X_p^{11}}$$

Recordar:

$$0 \rightarrow \Omega^0(X) \xrightarrow{d} \Omega^1(X) \xrightarrow{d} \Omega^2(X) \rightarrow 0$$

similarmente, se tiene

$$0 \rightarrow \Omega^0_{\mathbb{C}}(X) \xrightarrow{d} \underbrace{\Omega^1_{\mathbb{C}}(X)}_{\Omega^{1,0} \oplus \Omega^{0,1}} \xrightarrow{d} \Omega^2_{\mathbb{C}}(X) \rightarrow 0$$

¿cómo se descompone d en este contexto?

Obj: descomponer d usando la descomp.
 de $\Omega^k_{\mathbb{C}}(X)$. ($d = \partial + \bar{\partial}$)

$$\mathbb{R}^{0,1} \xrightarrow{\partial} \mathbb{R}^2$$

$$\bar{z} \uparrow \quad \quad \quad \uparrow \bar{\partial}$$

$$\mathbb{R}^0 \xrightarrow{\partial} \mathbb{R}^{(1,0)}$$

En coordenadas locales

$$z = x + iy.$$

$$dz = dx + i dy \text{ base de } T^* X_p'$$

$$d\bar{z} = dx - i dy \longrightarrow T^* X_p''$$

Escribir

$$\cdot dx = \frac{1}{2} (dz + d\bar{z})$$

$$\cdot dy = \frac{1}{2i} (dz - d\bar{z}) \quad \text{←}$$

Así:

$$\underline{df} = \frac{\partial f}{\partial x} dx + \frac{\partial f}{\partial y} dy.$$

$$1 (\partial f : \partial f), \quad \checkmark, [f_1, \dots]$$

$$= -\frac{1}{2} \left(\overline{\frac{\partial f}{\partial x}} - i \overline{\frac{\partial f}{\partial y}} \right) dz + \frac{1}{2} \left(\frac{\partial \bar{f}}{\partial x} + i \frac{\partial \bar{f}}{\partial y} \right) d\bar{z}$$

$\underbrace{\frac{\partial f}{\partial z}}$
 \oplus
 $\underbrace{\frac{\partial \bar{f}}{\partial \bar{z}}}$

Definiens: $\frac{\partial f}{\partial z} = \frac{1}{2} \left(\frac{\partial f}{\partial x} - i \frac{\partial f}{\partial y} \right) dz$

. $\frac{\partial \bar{f}}{\partial \bar{z}} = \frac{1}{2} \left(\frac{\partial \bar{f}}{\partial x} + i \frac{\partial \bar{f}}{\partial y} \right) d\bar{z}$

Ademais

$$\frac{\partial f}{\partial z} = \frac{1}{2} \left(\frac{\partial f}{\partial x} - i \frac{\partial f}{\partial y} \right) \checkmark$$

$$\frac{\partial \bar{f}}{\partial \bar{z}} = \frac{1}{2} \left(\frac{\partial \bar{f}}{\partial x} + i \frac{\partial \bar{f}}{\partial y} \right) \checkmark$$

Ass:

$$df = \underbrace{\frac{\partial f}{\partial z} \cdot dz}_{\equiv} + \underbrace{\frac{\partial \bar{f}}{\partial \bar{z}} \cdot d\bar{z}}_{\equiv}$$

Obs:

$\underbrace{\circledast}_{\equiv} \quad \frac{\partial \bar{f}}{\partial \bar{z}} = 0 \iff f \text{ holomorfa.}$

(cc. Cauchy Riemann) $\underbrace{\star}_{\equiv}$

$$f = u + i v$$

$$\begin{pmatrix} \frac{\partial u}{\partial x} & \frac{\partial u}{\partial v} \\ \frac{\partial v}{\partial x} & \frac{\partial v}{\partial y} \end{pmatrix} = \begin{pmatrix} a & b \\ b & a \end{pmatrix}$$

$$\left\{ \begin{array}{l} \frac{\partial u}{\partial x} = \frac{\partial v}{\partial y} \\ \frac{\partial u}{\partial v} = -\frac{\partial v}{\partial x} \end{array} \right\} (*)$$

Ast si f es holomorfa

$$df = \partial f = \underbrace{f'(z)}_{\text{d}z}.$$

Obs:

$$d^2 = 0 \Rightarrow \partial \bar{\partial} = 0 \quad /$$

$$(\partial + \bar{\partial})^2 = 0 \qquad \bar{\partial} \bar{\partial} = 0 \quad /$$

$$\partial \bar{\partial} = - \bar{\partial} \partial .$$

Ahora consideremos $\partial, \bar{\partial}$ en $\underline{\mathbb{R}}^{0,1}, \underline{\mathbb{R}}^{1,0}$

$$0 \partial(A d \bar{z}) = \frac{\partial A}{\partial z} d\underline{z} d\bar{z} = 2i \frac{\partial A}{\partial z} \underbrace{dx dy}_{\text{d}x \text{d}y}.$$

$$\Theta \bar{\partial} (B dz) = \frac{\partial B}{\partial \bar{z}} d\bar{z} dz = -2i \frac{\partial B}{\partial \bar{z}} dx dy.$$

Def:

una $(1,0)$ -forma B es una

1-forma holomorfa si

$$\bar{\partial} B = 0.$$

(i.e. en cord. locales "1-forma holo.

se puede escribir como $\underline{\underline{B}} dz$ con
B holomorfa).

$$S \subseteq X$$

Sea S una superficie compacta

con frontera, $S \subseteq X$.

Sea α 1-forma holomorfa en una vecindad de S .

$$\Rightarrow \alpha \text{ es cerrada. } (d\alpha = 0) \quad (\bar{\partial}\alpha = 0)$$

$$(\partial + \bar{\partial})\alpha = \alpha^{\text{holo}}$$

(*)

$$\partial \alpha = \frac{\partial f}{\partial z} dz \wedge dz$$

Por Stokes

$$\Rightarrow \boxed{\int_{\partial S} \alpha = 0} \quad \checkmark$$

(versión del T. de Cauchy para sup. de Riemann).

X sup. de Riemann.

$$\Omega_{\mathbb{C}}^*(x)$$

• $\Omega_{\mathbb{C}}^2(x) \leftarrow$ gen. por $\underline{dz d\bar{z}}$. ($\cong \Omega^1(x)$)

$$• \Omega_{\mathbb{C}}^1(x) = \Omega^{1,0}(x) \oplus \Omega^{0,1}(x)$$

$$• \Omega^0(x)$$

X var. compleja

$$• \Omega_x^{p,q} = \Gamma \left(X, \Lambda^p T_x^* X^1 \wedge \Lambda^q T_x^* X^2 \right)$$

$w \in$

$$w = \sum_{I,J} f_{IJ} dz_I \wedge d\bar{z}_J$$

$$|I| = p$$

... -

$$|J| = \frac{1}{2}.$$

• fijamos \mathcal{P} :

$$\bar{\partial} : \Omega^{p,q}(X) \xrightarrow{\bar{\partial}} \Omega^{p,q+1}(X) \xrightarrow{\bar{\partial}} \dots$$

Complejo de cedemas, con $\bar{\partial}$

"derivada exterior". ($\bar{\partial} \circ \bar{\partial} = 0$)

Coh. de Dolbeault:

$$H^{p,q}(X) = \frac{\text{Ker } \bar{\partial}^{p,q}}{\text{Im } \bar{\partial}^{p,q-1}}$$

Para X sup. de Riemann:

$$\bullet H^2(X) \simeq H^{1,1}(X) \oplus H^{2,0}(X) \oplus H^{0,2}(X)$$

$$\bullet H^1(X) \simeq H^{1,0}(X) \oplus H^{0,1}(X)$$

$$\bullet H^0(X)$$

$$\dim X = n \quad (X \text{ var. cx})$$

$$H_{DR}^k(X, \mathbb{C}) = \bigoplus_{p+q=k} H^{p,q}(X)$$

$$q+p=k.$$

$$\overline{H^{p,q}(X)} = H^{q,p}(X).$$

X: sup. de Riemann)
Def: (1-forma meromorfa)

Decimos α 1-forma meromorfa en X

Si α holomorfa en $X \setminus D$, D subconjunto discreto de X, de modo que α se puede escribir localm. como

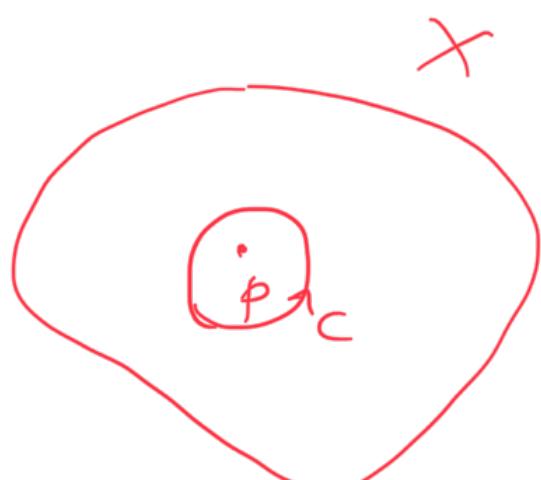
$$f(z)dz, f \text{ meromorfa}.$$

D: círculo de polos de f.

Sea p un polo de f.

Definimos:

$$\text{Res}_p(f) = \frac{1}{2\pi i} \int_C \alpha$$



↑ pequeño lazo alrededor de p.

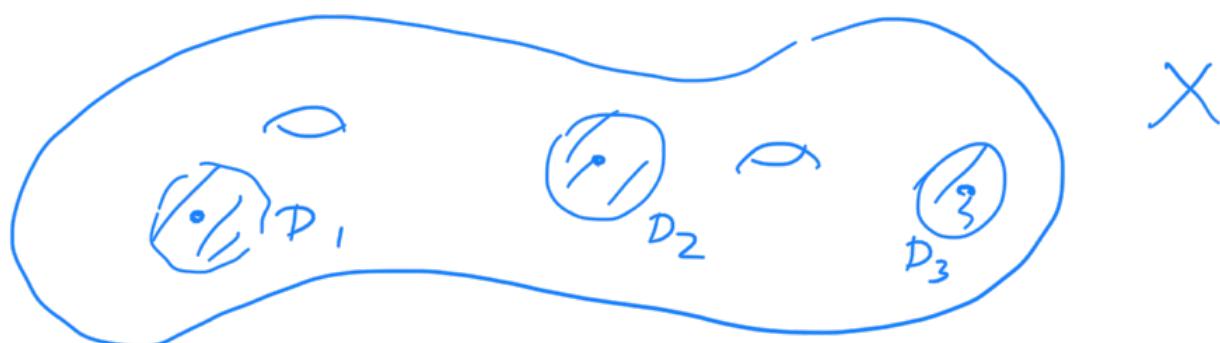
Prop: α 1-forma meromorfa. ✓

\rightarrow Residuos en X .

$$\sum_{P_i \in P} \text{Res}_{P_i}(f) = 0.$$

P polos de f

prueba:



D_i : discos alrededor de los polos.

$$S = \text{superficie con fronteras}$$
$$\bigcup_{i=1}^p \partial D_i \quad \partial D_j = C_j$$

Por Stokes

$$\int_{\partial S} \alpha = 0$$

$$\sum_j \int_{C_j} \alpha = 0$$

Próxima clase:

$$\Delta = 2i \frac{\partial}{\bar{\partial}} \varphi$$

Laplacians

ψ armónica s.t. $\Delta \psi = 0$.

ψ armónica $\Leftrightarrow \psi = \operatorname{Re}(f)$

f holomorfa.