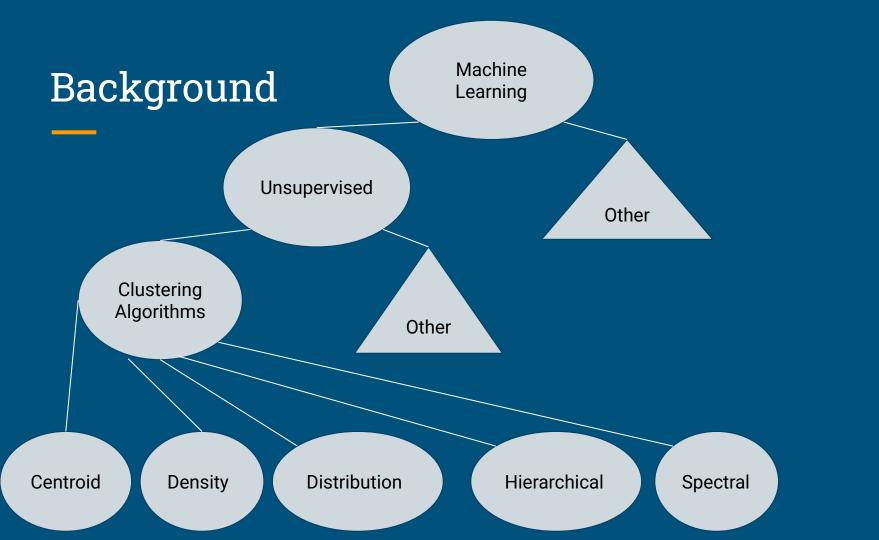
# DBSCAN Theory and Applications Introduction

Eduardo Lopez



# K-Means(Centroid Based)

- K-means
  - Dev: 1950s 1960s by a group of researchers
  - Purpose: clustering data with K number
  - of clusters
  - Required parameter: n\_clusters=#

#### **Definitions:**

- Centroid: the mean/center of the distributed cluster
  - On each iteration, the centroid is assigned to minimize the variance/distribution of each cluster
- Distance Metric:
  - Function the calculates the distance between two points (e.g Squared Euclidean Distance, Manhattan, etc.)

- 1. Initialize cluster centroids  $\mu_1, \mu_2, \dots, \mu_k \in \mathbb{R}^n$  randomly.
- 2. Repeat until convergence: {

For every i, set

$$c^{(i)} := \arg \min_{j} ||x^{(i)} - \mu_{j}||^{2}.$$

For each j, set

$$\mu_j := \frac{\sum_{i=1}^{m} 1\{c^{(i)} = j\}x^{(i)}}{\sum_{i=1}^{m} 1\{c^{(i)} = j\}}.$$

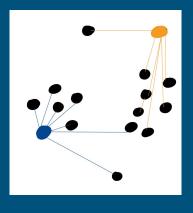
}



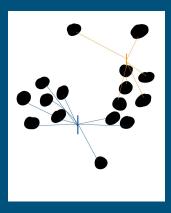


$$d(x_i, x_{i'}) = \sum_{j=1}^{p} (x_{ij} - x_{i'j})^2 = ||x_i - x_{i'}||^2$$

# Simulation(k=2)

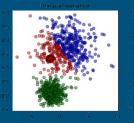








## Drawbacks!!







- The number of clusters have to be set by the user
  - o Dataset may have hundreds, thousands of clusters, many features!!
- Doesn't perform well with complex clusters/noisy data

# Solution??



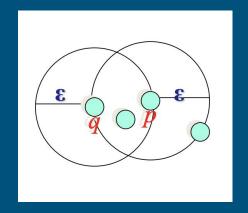
# (Density Based) Spatial Clustering with App. Noise

- DBSCAN:
  - Dev: 1996 by a group of researchers
  - Purpose: clustering data by discovery
  - Required parameters: eps=#, min\_samples=#

#### Definitions:

- Core point: a point that meets the following criteria
  - Given eps, it has at least min\_samples of neighbors in its neighbor(within radius of eps)
- Border point:
  - Has fewer than min\_samples but is in the neighborhood of another core point
- Noise point:
  - Is neither a core point nor a border point

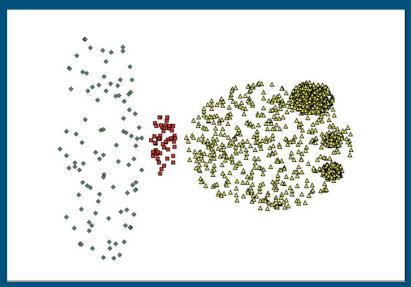
min\_samples=3



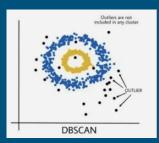
# Simulation(min\_samples=3)

# Drawbacks!

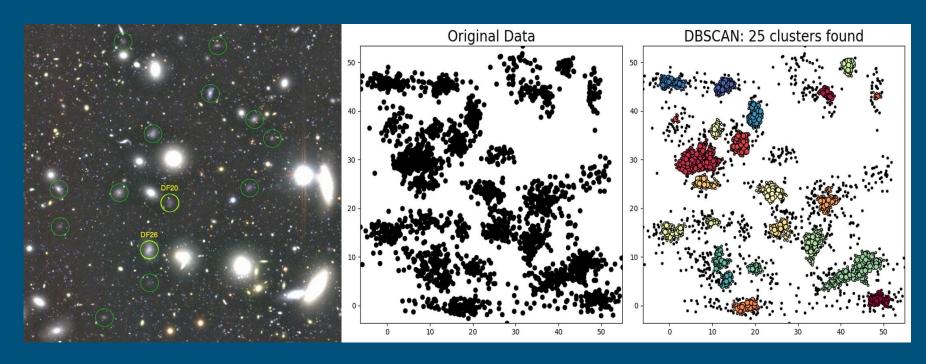
- Cannot handle varying densities within cluster
- Sensitive parameters may result in difficult training





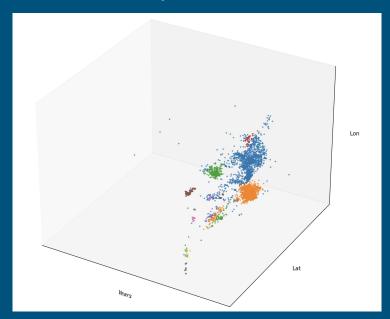


Great for discovering star clusters, galaxy groups, gamma-spectrum observations



# My Own Application

### Meteorite hotspots identification





- Discovering meteorite hotspot clusters on geographical data
- Membership testing can be done post training
- Using SVM soft scoring Kernel Density Estimator, membership testing is possible using cluster densities
- Gaussian RBF kernel is more simple!

$$k(x,y) = \exp\left(-\frac{\|x-y\|^2}{2\sigma^2}\right)$$

argmax[Pr(X is on cluster i) = density\_i \* weight\_i]

## Pseudocode

```
DBSCAN(D, eps, MinPts)
  C = 0
  for each unvisited point P in dataset D
     mark P as visited
      NeighborPts = regionQuery(P, eps)
      if sizeof(NeighborPts) < MinPts
        mark P as NOISE
      else
         C = next cluster
         expandCluster (P, NeighborPts, C, eps, MinPts)
expandCluster(P, NeighborPts, C, eps, MinPts)
   add P to cluster C
  for each point P' in NeighborPts
     if P' is not visited
         mark P' as visited
        NeighborPts' = regionQuery(P', eps)
         if sizeof(NeighborPts') >= MinPts
            NeighborPts = NeighborPts joined with NeighborPts'
      if P' is not yet member of any cluster
         add P' to cluster C
regionQuery(P, eps)
  return all points within P's eps-neighborhood (including P)
```

Time Complexity (Polynomial time problem):

Average Case:  $O(n \log n)$  Worst Case:  $O(n^2)$ 

Space Complexity: *O(n)* 

# Scikit-learn Implementation

```
# importing packages
import numpy as np
from sklearn import DBSCAN
from sklearn.preprocessing import StandardScaler
# preprocessing the dataset before implementation
dataset = np.array(dataset).astype(float)
# optional scaling depending on dataset to prevent bias
scaler = StandardScaler()
# scaling dataset
scaled_dataset = scaler.fit_transform(dataset)
# initializing DBSCAN algorithm and setting parameters
model = DBSCAN(eps=0.5, min_samples=5)
# training model to the dataset
output dataset = model.fit(scaled dataset)
# attributes (output after training)
labels = output data.labels
core points indices = output data.core sample indices
seen_features = output_data.n_features_in_
```





## Resources

Scikit-learn:

https://scikit-learn.org/stable/modules/generated/sklearn.cluster.DBSCAN.html

https://scikit-learn.org/stable/modules/generated/sklearn.cluster.KMeans.html

Textbook:

https://hastie.su.domains/ElemStatLearn/download.html

Papers:

https://file.biolab.si/papers/1996-DBSCAN-KDD.pdf