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#### To cite this article:

Constantine Toregas, Ralph Swain, Charles ReVelle, Lawrence Bergman, (1971) The Location of Emergency Service Facilities. Operations Research 19(6):1363-1373. <a href="http://dx.doi.org/10.1287/opre.19.6.1363">http://dx.doi.org/10.1287/opre.19.6.1363</a>

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# THE LOCATION OF EMERGENCY SERVICE FACILITIES

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(Received October 7, 1970)

This paper views the location of emergency facilities as a set covering problem with equal costs in the objective. The sets are composed of the potential facility points within a specified time or distance of each demand point. One constraint is written for each demand point requiring 'cover,' and linear programming is applied to solve the covering problem, a singlecut constraint being added as necessary to resolve fractional solutions.

DETERMINING 'good' locations for facilities on a network has received a reasonable amount of attention in the last decade. Many of the approaches to this class of problems are indicated in Cabot et al., and Revelle et al., This paper is concerned with a facility-location problem with the special aspect that the maximum time or distance that separates a user from his closest service is a crucial parameter. As such, the problem is seen as most applicable to the location of emergency services such as fire stations, although one may equally well apply it to the location of ordinary services, such as schools, libraries, etc.

If an upper limit is placed on the response time or distance to any user node, consideration can be given to determining the minimum-cost spatial arrangement of service facilities that adequately serves the entire user region. If costs (determined in any manner desired) are identical for all possible facility locations, then an equivalent problem is to minimize the total number of service facilities required to meet the response time or distance standards for each of the users. The solution to this problem will indicate both the number and location of the facilities that provide the desired service.

The location of fire stations might be approached according to the struc-



ture just described. The limit on response time is imposed to ensure that no more than a specified time period will elapse before a response will occur to any fire. In applications, the definition of response time may not be unique. Clearly, its definition must be such that it indicates the spatial effects of distributing the emergency service; but, beyond this requirement, the definition of response time depends primarily upon the available data. Once a response time s is specified, then for each point of demand there must be a fire station located within s time units. (It is assumed here that each facility has response capability at all times.) The desired solution to this problem locates the minimum number of fire stations that satisfies the response-time requirement.

In order to achieve a more tractable problem structure, several abstractions are required. First, it will be assumed that the user demands can be represented as occurring at a finite set of points and that the potential locations for service facilities are also a finite set of points. Second, it is assumed that the minimum distance or minimum response time between any user-node/service-facility pair is known. Third, it will be assumed that the user-demand points and the possible facility-location points constitute the same set of points. As will be seen shortly, this final assumption is not essential in structuring the solution technique. It has been included here to bring the formulation in line with earlier work in the same area. Under these simplifications, the problem has now been reduced to a problem of 'covering' each of the user nodes with one of the facility nodes.

Hakimi<sup>[3,4]</sup> was the earliest to consider similar problems. A part of his first study<sup>[3]</sup> was directed toward the location of the center of a network, where the center of a network is the point of the network from which the distance to the furthest point is a minimum. Hakimi<sup>[4]</sup> later generalized the concept of a center, and, using Boolean functions, he sought the minimum number of centers (chosen from a discrete set) that covered all demand points within a specified maximum distance. The resulting method requires an enumeration of all feasible solutions, and, as problem size grows, the effort of determining the minimum number of facilities can be expected to grow rapidly. The technique given in the following section avoids enumeration, so that the growth in problem size has a less significant effect upon computational requirements.

#### PROBLEM FORMULATION AND SOLUTION

RECALLING THE assumptions that all user points may also be emergency-facility locations and that the minimum time or distance between any pair of user nodes is known, the problem will now be structured as an integer programming problem.

If the maximum response time s has been decided upon, then, for any



node i, only the set of nodes within s of i can provide acceptable emergency service to i; this set will be denoted as  $N_i$ . If  $d_{ji}$  is the response time or distance from any node j to node i, the set  $N_i$  can be defined as  $N_i = \{j | d_{ii}\}$  $\leq s$ . (One may equally well define the set  $N_i$  as the nodes within  $s_i$  of node i, where s<sub>i</sub> may be different for each node i. Problems with this feature have been examined and do not appear to add any difficulties to the solution process.) If there are n user nodes, there will be n sets  $N_i$ , and each set will have at least one member, if  $d_{ii}$  is taken to be zero. It is important to notice that the definition of  $N_i$  does not depend on the nature of the points j that may be used to provide emergency service to i. fore, the potential facility locations may be both user and other locations. The theoretical requirement is that  $d_{ji}$  be known and that the number of potential facility locations be finite; if this number is too enormous, then, of course, the proposed solution method will not be practicable. choice of which points should be taken as potential facility locations is up to the analyst.

To structure the mathematical program, the following decision variables are now defined:

$$x_{j} = \begin{cases} 0, & \text{if no facility is established at point } j, \\ 1, & \text{if a facility is established at point } j. \end{cases}$$
  $(j=1, 2, \dots, n)$ 

Thus,  $x_j$  is a zero-one integer variable. Values of  $x_j$  other than zero or one will not be acceptable in a solution.

As discussed in the first section, any user node i must have at least one facility within s. Recalling that the set of potential facility locations within s of i is  $N_i$  and using the decision variables, we can write the service requirement for user node i as

$$\sum_{j \in \mathcal{N}_i} x_j \ge 1. \tag{1}$$

The objective z that is to be minimized is the total number of facilities used:

$$z = \sum_{j=1}^{j=n} x_j. \tag{2}$$

Even if the  $x_i$ 's are only restricted to be nonnegative, none of them will be greater than one in an optimal solution to (1) and (2). If any one  $x_i$  were not, it could be reduced in value without violating a constraint. This reduction would cause a corresponding reduction in the objective function, indicating that the optimum was not at hand. The entire program can be written:

(I) subject to: 
$$\sum_{j \in N_i} x_j \ge 1, \qquad (i=1, 2, \dots, n) \quad (1)$$

$$x_j = (0, 1).$$
  $(j = 1, 2, \dots, n)$  (3)



The structure is that of the set-covering problem with inequality constraints; the set-covering problem has received extensive treatment in the literature, both as a problem in its own right and as a special class of the integer programming problem. A recent review of many of the approaches to the problem is found in Garfinkle. [2]

Three approaches to this problem seem most favored; these are linear-programming and cutting-plane techniques, reduction techniques, and implicit enumeration. Some investigators combine these approaches. The technique utilized here is linear programming supplemented by the addition of a single cut constraint. The technique has not yet failed to yield all zero-one variables.

The simplicity of this program is particularly important. It should be observed that only one constraint is written for each of the user points to be served, and it should also be noted that only one variable is associated with each of the potential facility locations. These two items, coupled with the capacity of the current mathematical programming systems, should permit the solution of problems with several hundred or more user points and potential locations. A second important feature of the model is the ease with which a facility location can be forced in or out of the solution by specifying its  $x_i$  to be either one or zero. This feature may be important in situations where a facility already exists or where the possibility of prohibiting a facility at a given location is to be examined.

The actual implementation of (I) requires two steps. The first is determination of the sets  $N, (i=1, 2, \dots, n)$  for a given value of s and a given matrix of shortest distances D. The second step is solution of (I) using the sets established in step one.

We formed the sets using a Fortran program, and they were recorded on disk storage in a form acceptable for use by MPS/360 (the mathematical programming code available on IBM S/360 Equipment). The solution then was obtained using the linear programming algorithm of MPS/360 for the sets produced by the Fortran program. This coupling of procedures saves the tedious operation of forming and punching the sets. It should be noted that s is not explicitly contained in (I). Consequently, it is not possible to obtain a set of solutions parameterized on s using only the mathematical programming code. Both the set determination and mathematical programming procedures must be used for this operation. The potential inefficiency of this circumstance is reasonably surmounted by generating several different-data sets corresponding to a sequence of values of s, and then solving each of the associated mathematical programming problems.



TABLE I

THE MINIMUM-DISTANCE MATRIX FOR LOCATIONS IN NEW YORK STATE (The distances are in miles)

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# COMPUTATIONAL EXPERIENCE AND THE ELIMINATION OF FRACTIONAL RESULTS

THE SOLUTION of (I) requires zero-one variables, but the use of a linear-programming code admits the possibility that fractional solutions may be produced.

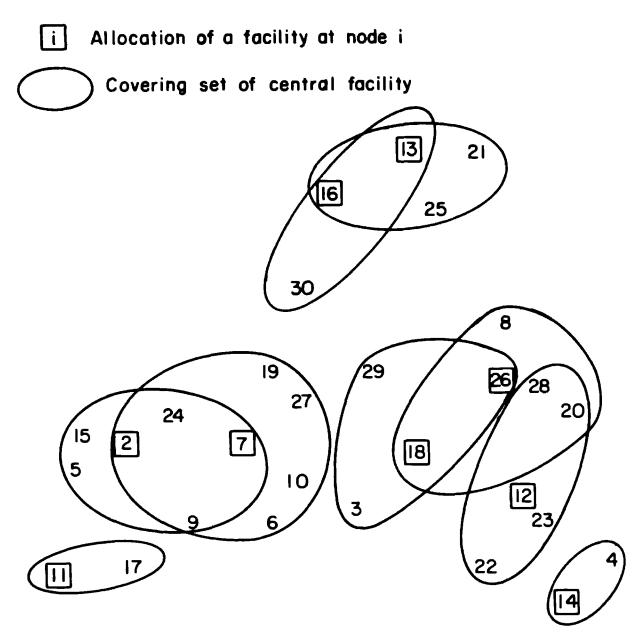


Fig. 1. Allocation of service facilities in an example problem.

To examine the properties of solutions generated by such a code, a 30-node problem was examined for many values of s, ranging from the minimum distance between nodes, 7, to the maximum distance between any two nodes, 275. These nodes represent major areas in New York State and the distance matrix between them is shown in Table I.

An example solution, obtained with s = 68, is shown in Fig. 1. For a number of



the user nodes, two service facilities are within s. This feature may be desirable in many applications.

Figure 2 indicates the number of service facilities required as a function of the maximum response distance. Notice that, for s = 69, the number of centers used is noninteger, with a value of  $8\frac{1}{2}$ . The corresponding solution is shown in Fig. 3. Although each user node is covered by at least one service facility, many of the facilities are at level  $\frac{1}{2}$ , which is invalid according to the definition of  $x_j$ . To

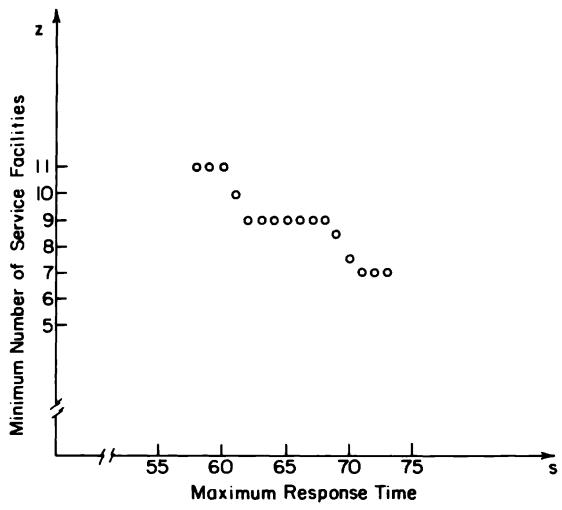


Fig. 2. Minimum number of service facilities as a function of maximum response time s.

achieve a solution with all  $x_j$  either zero or one, the facility-sharing patterns must be broken up.

All noninteger solutions observed in execution of the covering problem have been resolved with the addition of a single cut constraint, which is a direct result of the integer requirements. Suppose that  $m^0$  is the optimal objective value obtained from a fractional linear programming solution to (I). If  $m^0$  is noninteger, then, in any integer solution, the minimum number of servers must be at least as great as the least integer greater than  $m^0$ . Therefore, one adds the cut



$$\sum_{j=1}^{j=n} x_j \ge [m^0] + 1, \tag{4}$$

where  $[m^0]$  is the integer part of  $m^0$ . Although it is possible to have a fractional solution where  $m^0$  is integer, no such condition has yet occurred. Should such a case occur, it appears that (4) may still be useful.

The use of (4) can be illustrated by referring to the noninteger solution already discussed. In that example,  $m^0$  had the value  $8^{1}$ <sub>2</sub>. The application of (4) indi-

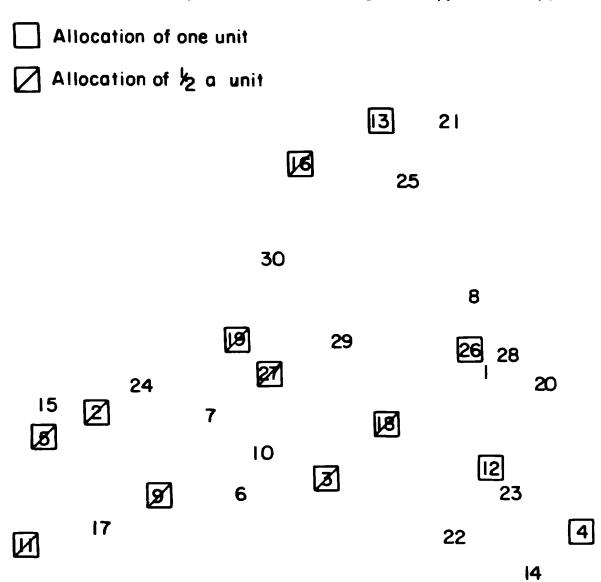


Fig. 3. Noninteger solution of the example problem for the value of s=69.

cates that any integer solution must have at least 9 facilities. The constraint  $\sum_{j=1}^{j=30} x_j \ge 9$  was added to (I), and the problem was solved again. The resulting solution, shown in Fig. 4, is integer, as were all solutions in which (4) was included to eliminate noninteger results.

Several observations about the properties of solutions to this problem can be made.

First, if the minimum number of servers is  $m^*$  for two different values of s,  $s_1$ , and  $s_2$ , then the minimum number of servers is  $m^*$  for any s in  $[s_1, s_2]$ .



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Second, for any s greater than the maximum distance entry in the distance matrix, only one server is required.

Third, for any s less than the minimum distance  $d_{ij}(i \neq j)$ , all nodes must have a service facility.

We have solved this problem at sizes up to 50 nodes over 150 times with a standard linear programming code. In the few cases of fractional results,



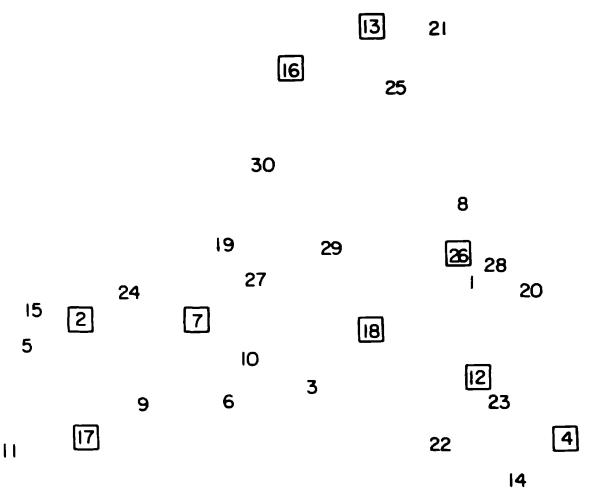


Fig. 4. Integer solution of the example problem for the value of s = 69.

the addition of the cut (4) to the linear program always resulted in an all zero-one solution.

# THE RELATION OF THE PROBLEM TO THE MODIFIED p-MEDIAN PROBLEM

The solutions provided from (I) can be used to provide valuable information for a modified form of the p-median problem.<sup>[6]</sup>



In the original version of the p-median problem, there is no restriction on the distance that a user group might be required to travel to the closest open facility. A limit on the maximum distance any user group may travel can be imposed in the same manner as it is imposed in (I). The same definition of  $N_i$  as given previously is used in this modified version of the p-median problem.

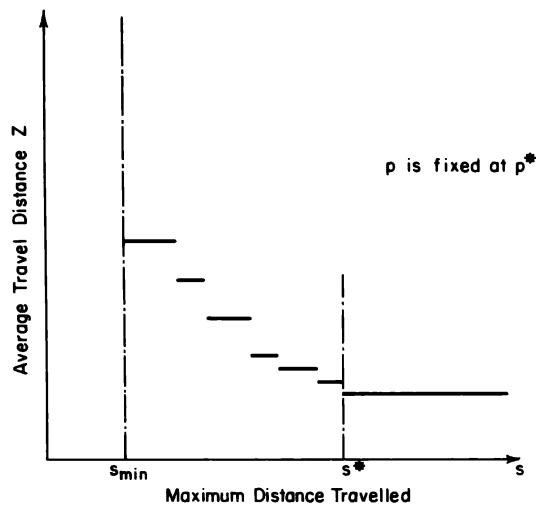


Fig. 5. Average travel distance as a function of the maximal distance travelled.

To structure the problem, the following additional definitions are provided:

 $x_{ij}$  = the fraction of population of node i that receives service at node j;

 $d_{ij}$  = the distance from node i to node j;

 $a_i$  = the user population at node i;

p = the number of facilities to be established.

Model I utilized distances  $d_{ji}$  and considered (at least implicitly) movement from facility to user (e.g., fire engines). Here, the orientation of this model is shifted, reflecting movement from user to facility (e.g., schools),



hence the use of  $d_{ij}$  rather than  $d_{ji}$ . The subscript reversal is irrelevant for the mathematics.

The problem is then written:

$$\sum_{i=1}^{i=n} \sum_{j \in N_i} a_i d_{ij} x_{ij}, \qquad (5)$$

subject to 
$$\sum_{j \in N_i} x_{ij} = 1,$$
  $(i = 1, 2, \dots, n)$  (6)

(II) 
$$x_{ij} \ge x_{ij}, \qquad (i=1,2,\cdots,n; j \in N_i; i \ne j)$$
 (7)

$$\sum_{j=1}^{j=n} x_{jj} = p, \tag{8}$$

 $x_{ij} \ge 0$  for all i, j, and  $x_{jj} = (0, 1)$  for all j.

In this formulation,  $x_{jj}=1$  is taken to indicate that a facility is established at node j. The objective, as expressed in (5), is to minimize the total user distance travelled by users to their closest open facilities. The constraints represented by (6) ensure that the user population of each node is assigned to a service facility. Constraints (7) require that users are assigned only to open facilities, and (8) requires that exactly p facilities be established.

It is important to note that for some (s, p) combinations, no feasible solution to (II) may exist. In addition, given a particular value of p, there is a maximum value of s beyond which the solution of (II) will not differ from the solution without distance constraints. Figure 5 indicates the effect that s has upon the solution of (II) for a particular value of p.

The solutions obtained from the formulation (I) provide the value of  $s_{\min}$ , the lowest feasible limit on maximum distance, for a particular value of p. For a particular value of p, say  $p^*$ ,  $s_{\min}$  is the least value of s for which problem (I) has an objective value of  $p^*$ . No indication of either  $s^*$ , or the values of s in  $[s_{\min}, s^*]$  at which the objective of (II) changes, is provided by the solutions to (I).

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