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ABSTRACT

In this thesis we'll see how digital twins can be used and applied in a range of scenarios, we'll introduce the language 'SMOL', created specifically for this purpose, and talk about the work of me and my colleagues

INTRODUCTION TO DIGITAL TWINS

NASA's definition of digital twin

"An integrated multiphysics, multiscale, probabilistic simulation of a vehicle or system that uses the best available physical models, sensor updates, fleet history, etc., to mirror the life of its flying twin. It is ultra-realistic, and may consider one or more important and interdependent vehicle systems"

A digital twin is a live replica of a Physical System and is connected to it in real time, application. Digital Twins are meant to understand and control assets in nature, industry or society at large, they are meant to adapt as the underlying assets evolve with time. [1]

Applications. Digital Twins are already extensively used in a wide range of fields, ranging from power generation equipment - like large engines, power generation turbines - to establish timeframes for regularly scheduled maintenance, to the health industry where they can be used profile patients and help tracking a variety of health indicators. [2]

SMOL

SMOL (Semantic Micro Object Language) is an imperative, object-oriented language with integrated semantic state access. It can be used served as a framework for creating digital twins. The interpreter can be used to examine the state of the system with SPARQL, SHACL and OWL queries.

Co-Simulation. SMOL uses *Functional Mock-Up Objects* (FMOs) as a programming layer to encapsulate simulators compliant with the FMI standard into object oriented structures [1]

The project is in its early stages of development, during our internship one of our objectives was to demonstrate the capabilities of the language and help with its development by being the first users.

THE PROJECT

The project was realized in collaboration with the University of Oslo and the Sirius Research Center. The project consists in the creation of a greenhouse and program the corresponding digital twin of it. The greenhouse consists in a series of shelves with plants, each plant in its own pot, we then control the environmental conditions such as temperature, humidity, moisture and light level with a series of sensors connected to a fleet of Raspberry Pi 4. The only actuator present in the project is a water pump but it could be expanded to include more actuators such as a heater or a fan.

The Goal. The creation of a digital twin of the greenhouse and the optimization of the environmental conditions for maximum growth. Using SMOL we can predict when to water the plants and how much water to use.

THE GREENHOUSE

The specific greenhouse we're working on has the following characteristics:

- It is divided in two shelves
- Each shelf is composed by two groups of plants
- Each group of plants is watered by a single water pump
- Each group of plants is composed by two plants
- Each plant is associated with a pot

Assets - Sensors. The following sensors are used to monitor the environmental conditions of the greenhouse and the plants:

Greenhouse

- 1 webcam used to measure the light level, can be replaced with a light sensor that would also provide an accurate lux measurement

Shelves

- 1 DHT22 sensor used to measure the temperature and humidity

Pots

- 1 capacitive soil moisture sensor used to measure the moisture of the soil

Plants

- 1 Raspberry Pi Camera Module v2 NoIR used to take pictures of the plants and measure their growth by calculating the NDVI

THE ROLE OF EACH RASPBERRY PI

There are in total 5 Raspberry Pi 4 used in this project. The division in roles and the usage of the same hardware makes it very scalable and easy to replicate. As follows:

- 1 Raspberry Pi 4 is used as a server, it hosts the digital twin and the FMI simulators, the server is also used to host the database in which all the data is stored and accessed.
- 3 Raspberry Pi 4 are used as clients, they are connected to the sensors and the actuators and are responsible for sending the data to the server.
- 1 Raspberry Pi 4 is used as a router and serves to connect clients and server wirelessly.

The Server The host runs an InfluxDB instance that holds the data retrieved from the clients (*data collectors*) and a Java program that periodically runs the SMOL Twinning program which is responsible for creating the digital twin and running the FMI simulators.

The Clients We also refer to them as *data collectors*

The Router The Raspberry was configured with `hostapd` and `dnsmasq` to act as a router and provide a wireless network for the clients to connect to. The local network is used to access the client via SSH and to send data to the server via HTTP requests.

TOOLS AND TECHNOLOGIES

InfluxDB. InfluxDB is a time-series database that is used to store the data collected by the *data collectors*.

It's organized in *buckets* that are used to store the *measurements*. Each *measurement* is composed of:

- *measurement name*

- *tag set*
 - Used as keys to index the data
- *field set*
 - Used to store the actual data
- *timestamp*

Developing a library to interface with the sensors.

When working with the Raspberry Pi 4 the obvious choice for a programming language is Python, it is the most widely used language for the Raspberry Pi and it has a lot of support and libraries available.

The goal was to make it extremely modular to be able to add new sensors and actuators with ease.

OWL. OWL is a knowledge representation language that is used to describe the **asset model** of the greenhouse. It is used to create a formal description of the greenhouse's physical structure and the relationships between the different components.

SMOL Language. As introduced in Section II, SMOL is an OO programming language in its early development stages, it allows us to:

- Interact with the InfluxDB and read data from the database, directly without the need of a third party libraries
- Read and query the knowledge graph, mapping the data to objects in the heap
- Map the program state to a knowledge graph by means of semantic lifting, the program state can be then queried to extract information about the state of the system
- Represent and run simulation and interact with `modelica`, refer to Section II.A

THE DIGITAL TWIN

GREENHOUSE ASSET MODEL

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SMOL TWINNING PROGRAM

The SMOL program is run periodically by the server and is responsible for creating the digital twin and

running the FMI simulators. It achieves this in the following steps:

1. It reads the `asset model` from the `OWL` file
2. It generates `SMOL` objects from the asset model individuals
3. For each asset object it retrieves the sensor data associated with that specific asset from the database
4. After retrieving the data it performs the semantic lifting of the program state, creating a knowledge graph that represents the state of the assets in the greenhouse

SEMANTIC LIFTING

REFERENCES

- [1] Eduard Kamburjan, and Rudolf Schlatte, “The SMOL language.” <https://smolang.org/>
- [2] IBM, “What is a digital twin?.” <https://www.ibm.com/topics/what-is-a-digital-twin>