

Università degli Studi di Torino

DIPARTIMENTO DI INFORMATICA

Corso di Laurea Triennale in Informatica



Anno Accademico 2022/2023

Eduard's Thesis :)

candidate

Eduard Antonovic Occhipinti

matricola: 947847

supervisor

Prof. Ferruccio Damiani

AKNOWLEDGEMENTS

Special thanks to prof. Einar Broch Jhonson, Rudolf TODO, Eduard TODO and my colleagues from UniTO, Gianluca Barmina and Marco Amato for TODO

DECLARATION OF ORIGINALITY:

"Dichiaro di essere responsabile del contenuto dell'elaborato che presento al fine del conseguimento del titolo, di non avere plagiato in tutto o in parte il lavoro prodotto da altri e di aver citato le fonti originali in modo congruente alle normative vigenti in materia di plagio e di diritto d'autore. Sono inoltre consapevole che nel caso la mia dichiarazione risultasse mendace, potrei incorrere nelle sanzioni previste dalla legge e la mia ammissione alla prova finale potrebbe essere negata."

CONTENTS

ABSTRACT	1
I. Introduction to Digital Twins	1
I.A. Applications	1
II. SMOL	1
II.A. Co-Simulation	1
III. The Project	1
III.A. The Goal	1
IV. The Greenhouse	1
V. The Role of each Raspberry Pi	2
V.A. The Server	2
V.B. The Clients	2
V.C. The Router	2
VI. Developing a library to interface with the sensors	2
VII. The Digital Twin	2
REFERENCES	3

ABSTRACT

In this thesis we'll see how digital twins can be used and applied in a range of scenarios, we'll introduce the language 'SMOL', created specifically for this purpose, and talk about the work of me and my colleagues

INTRODUCTION TO DIGITAL TWINS

NASA's definition of digital twin

"An integrated multiphysics, multiscale, probabilistic simulation of a vehicle or system that uses the best available physical models, sensor updates, fleet history, etc., to mirror the life of its flying twin. It is ultra-realistic, and may consider one or more important and interdependent vehicle systems"

A digital twin is a live replica of a Physical System and is connected to it in real time, application. Digital Twins are meant to understand and control assets in nature, industry or society at large, they are meant to adapt as the underlying assets evolve with time. [1]

Applications. Digital Twins are already extensively used in a wide range of fields, ranging from power generation equipment - like large engines, power generation turbines - to establish timeframes for regularly scheduled maintenance, to the health industry where they can be used profile patients and help tracking a variety of health indicators. [2]

SMOL

SMOL (Semantic Micro Object Language) is an imperative, object-oriented language with integrated semantic state access. It can be used served as a framework for creating digital twins. The interpreter can be used to examine the state of the system with SPARQL, SHACL and OWL queries.

Co-Simulation. SMOL uses *Functional Mock-Up Objects* (FMOs) as a programming layer to encapsulate simulators compliant with the FMI standard into object oriented structures [1]

The project is in its early stages of development, during our internship one of our objectives was to demonstrate the capabilities of the language and help with its development by being the first users.

THE PROJECT

The project was realized in collaboration with the University of Oslo and the Sirius Research Center. The project consists in the creation of a greenhouse and program the corresponding digital twin of it. The greenhouse consists in a series of shelves with plants, each plant in its own pot, we then control the environmental conditions such as temperature, humidity, moisture and light level with a series of sensors connected to a fleet of Raspberry Pi 4. The only actuator present in the project is a water pump but it could be expanded to include more actuators such as a heater or a fan.

The Goal. The creation of a digital twin of the greenhouse and the optimization of the environmental conditions for maximum growth. Using SMOL we can predict when to water the plants and how much water to use.

THE GREENHOUSE

Lorem ipsum dolor sit amet, consectetur adipiscing elit, sed do eiusmod tempor incididunt ut labore et dolore magnam aliquam quaerat voluptatem. Ut enim aequale doleamus animo, cum corpore dolemus, fieri tamen permagna accessio potest, si aliquod aeternum et infinitum impendere malum nobis opinemur. Quod idem licet transferre in voluptatem, ut postea variari voluptas distinguere possit, augeri amplificarique non possit. At etiam Athenis, ut e patre audiebam facete et urbane Stoicos irridente, statua est in quo a nobis philosophia defensa et collaudata est, cum id, quod maxime placeat, facere possimus, omnis voluptas assumenda est, omnis dolor repellendus. Temporibus autem quibusdam et aut officiis debitis aut rerum necessitatibus saepe eveniet, ut et voluptates repudiandae sint et molestiae non recusandae. Itaque earum rerum defuturum, quas natura non depravata desiderat. Et quem ad me accedis, saluto: 'chaere,' inquam, 'Tite!' lictores, turma omnis chorusque: 'chaere, Tite!' hinc hostis mi Albucius, hinc inimi-

cus. Sed iure Mucius. Ego autem mirari satis non queo unde hoc sit tam insolens domesticarum rerum fastidium. Non est omnino hic docendi locus; sed ita prorsus existimo, neque eum Torquatum, qui hoc primum cognomen invenerit, aut torquem illum hosti detraxisse, ut aliquam ex eo est consecutus? – Laudem et caritatem, quae sunt vitae.

THE ROLE OF EACH RASPBERRY PI

There are in total 5 Raspberry Pi 4 used in this project. The division in roles and the usage of the same hardware makes it very scalable and easy to replicate. As follows:

- 1 Raspberry Pi 4 is used as a server, it hosts the digital twin and the FMI simulators, the server is also used to host the database in which all the data is stored and accessed.
- 3 Raspberry Pi 4 are used as clients, they are connected to the sensors and the actuators and are responsible for sending the data to the server.
- 1 Raspberry Pi 4 is used as a router and serves to connect clients and server wirelessly.

The Server.

The Clients.

The Router. The Raspberry was configured with `hostapd` and `dnsmasq` to act as a router and provide a wireless network for the clients to connect to. The local network is used to access the client via `SSH` and to send data to the server via `HTTP` requests.

DEVELOPING A LIBRARY TO INTERFACE WITH THE SENSORS

When working with the Raspberry Pi 4 the obvious choice for a programming language is Python, it is the most widely used language for the Raspberry Pi and it has a lot of support and libraries available.

The goal was to make it extremely modular to be able to add new sensors and actuators with ease.

THE DIGITAL TWIN

REFERENCES

- [1] Eduard Kamburjan, and Rudolf Schlatte, “The SMOL language.” <https://smolang.org/>
- [2] IBM, “What is a digital twin?.” <https://www.ibm.com/topics/what-is-a-digital-twin>