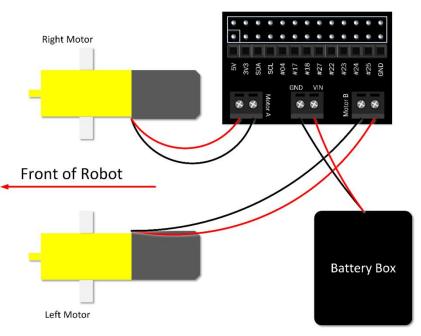




Circuit:



All that is needed for this worksheet is your robot. Although you can still keep the circuit from the last sheet.

Steps:

1. Open up a terminal window and type in:

sudo nano 7-keycontrol.py

2. Then in that window type:

```
from edupy import *
key_control()
```

3. Save the file by doing. CTRL+X and y then ENTER.

4. Now type in this to run it:

sudo python3 7-keycontrol.py

Now your can use your arrow keys to control your robot!