(i) a) Using Q-learning
$$Q_{t+1}(n_t, a_t) = Q_t(n_t, a_t) + \alpha \left[ c_t + \sum_{a' \in A} \min_{a' \in A} Q_t(n_{t+1}, a') - Q_t(n_t, a_t) \right]$$

$$Q_{t+1}((E_{t}, a_{t}, a_{t}), R) = 2.0 + 0.1 \left[ 0.2 + 0.9 \times 2.0 - 2.0 \right] = 2.0$$

$$Q_{t+1}((E_{t}, a_{t}, a_{t}), R) = \left[ 2.8 + 2.8 + 2.8 + 2.8 + 2.0 \right]$$

b) 
$$U_{iimg}$$
  $SARSA$ 

$$Q_{t+1}(n_t, a_t) = Q_t(n_t, a_t) + x \left[ e_t + y Q_t(n_{t+1}, a_{t+1}) - Q_t(n_t, a_t) \right]$$

$$Q_{t+1}((E,1,0,1),R) = 2.0 + 0.1 \left[ 0.2 + 0.9 \times 2.8 - 2.0 \right] = 2.072$$

$$Q_{(E,1,0,1)} = \left[ 2.8 + 2.8 + 2.8 + 2.8 + 2.54 + 2.072 \right]$$

e) G-leasuring updates its values using the optimal policy (min Q<sub>1</sub>(n<sub>1</sub>, a')). Since Q-learning descrit use the sense policy as the one used to select actions, we can say that is aff-policy.

SARSA updates its values using the policy used to select actions, so its on-policy.

As we can see, using Q-learning the chosen action is DOWN and using SARSA the chosen action is RIGHT as chosen by the used policy.