

# Two-country DSGE model for Scotland and the rest of the UK

Closely follows Galí (2015) and Gali and Monacelli (2005)

1. Home country: Scotland (notation -  $X$ )
2. Foreign country: rUK (notation -  $X^*$ )
3. Notation for UK-wide variables -  $X^{UK}$
4. Scotland and rUK are SOEs
  - (a) They trade, take world output, inflation, and consumption as given and cannot influence it
5. Calvo staggered prices, no capital/investment
6. Scotland and RUK are assumed to be symmetrical in market structure and preferences
7. Monetary Union: There is a population-weighted UK-wide interest rate in place, and all four nations within the UK purchase government-issued bonds at this rate
  - (a) We also consider counterfactual scenarios, i.e. where both Holyrood and Westminster can issue bonds at country-specific interest rate
8. The government spending can be financed via a lump-sum tax, a labour (income) tax, and borrowing.
9. We consider 4 scenarios:
  - (a) Two governments funded by lump-sum tax, two of which can issue bonds
  - (b) Two governments funded by lump-sum tax, one of which can issue bonds
  - (c) Two governments funded by an income tax, two of which can issue bonds
  - (d) Two governments funded by an income tax, one of which can issue bonds

Scenario 1 (G: 2, $\tau : 0$ )	S HBC:	$P_t C_t + \mathbb{E}_t[R_{t+1}^{-1} B_{t+1}] = B_t + W_t N_t + T_t$
	rUK HBC:	$P_t^* C_t^* + \mathbb{E}_t[R_{t+1}^{*-1} B_{t+1}^*] = B_t^* + W_t^* N_t^* + T_t^*$
	S GBC:	$\mathbb{E}_t[R_{t+1}^{-1} B_{t+1}] + T_t = P_t G_t + B_t$
	rUK GBC:	$\mathbb{E}_t[R_{t+1}^{*-1} B_{t+1}^*] + T_t^* = P_t^* G_t^* + B_t^*$
	S TR:	$T_t = P_t G_t$
	rUK TR:	$T_t^* = P_t^* G_t^*$
	S Debt s.:	$T_t/P_t = \phi_g^* G_Y g_t + \phi_b^*(B_t/P_t); \quad G_Y = 0$
	rUK Debt s.:	$T_t^*/P_t^* = \phi_g^* G_Y^* g_t^* + \phi_b^*(B_t^*/P_t^*); \quad G_Y = 0$
	S Bonds:	$(B_{t+1}/P_t)/R_{t+1} = (1 - \phi_g) G_Y g_t + (1 - \phi_b)(B_t/P_t); \quad G_Y = 0$
	rUK Bonds:	$(B_{t+1}^*/P_t^*)/R_{t+1}^* = (1 - \phi_g^*) G_Y^* g_t^* + (1 - \phi_b^*)(B_t^*/P_t^*); \quad G_Y^* = 0$
Scenario 2 (G: 1, $\tau : 0$ )	S RC:	$Y_t = C_t + G_t + X_t$
	rUK RC:	$Y_t^* = C_t^* + G_t^* + X_t^*$
	S HBC:	$P_t C_t + \mathbb{E}_t[R_{t+1}^{UK-1} B_{t+1}^{UK}] = B_t^{UK} + W_t N_t + \varpi T_t^{UK}$
	rUK HBC:	$P_t^* C_t^* + \mathbb{E}_t[R_{t+1}^{UK*-1} B_{t+1}^{UK*}] = B_t^{UK} + W_t^* N_t^* + (1 - \varpi) T_t^{UK}$
	S GBC:	N/A
	rUK GBC:	$\mathbb{E}_t[R_{t+1}^{UK-1} B_{t+1}^{UK}] + T_t^{UK} = P_t^{UK} G_t^{UK} + B_t^{UK}$
	S TR:	N/A
	rUK TR:	$T_t^{UK} = P_t^{UK} G_t^{UK}$
	S Debt s.:	N/A
	rUK Debt s.:	$T_t^{UK}/P_t^{UK} = \phi_g^{UK} G_Y^{UK} g_t^{UK} + \phi_b^{UK}(B_{t+1}^{UK}/P_t^{UK}); \quad G_Y^{UK} = 0$
Scenario 3 (G: 2, $\tau : 1$ )	S Bonds:	N/A
	rUK Bonds:	$(B_t^{UK}/P_t^{UK})/R_{t+1}^{UK} = (1 - \phi_g^{UK}) G_Y^{UK} g_t^{UK} + (1 - \phi_b^{UK})(B_t^{UK}/P_t^{UK}); \quad G_Y^{UK} = 0$
	S RC:	$Y_t = C_t + \varpi G_t^{UK} + X_t$
	rUK RC:	$Y_t^* = C_t^* + (1 - \varpi) G_t^{UK} + X_t^*$
	S HBC:	$P_t C_t + \mathbb{E}_t[R_{t+1}^{-1} B_{t+1}] = B_t + (1 - \tau_t) W_t N_t + T_t$
	rUK HBC:	$P_t^* C_t^* + \mathbb{E}_t[R_{t+1}^{*-1} B_{t+1}^*] = B_t^* + (1 - \tau_t^*) W_t^* N_t^* + T_t^*$
	S GBC:	$\mathbb{E}_t[R_{t+1}^{-1} B_{t+1}] + T_t = P_t G_t + B_t$
	rUK GBC:	$\mathbb{E}_t[R_{t+1}^{*-1} B_{t+1}^*] + T_t^* = P_t^* G_t^* + B_t^*$
	S TR:	$T_t = \tau_t W_t N_t$
	rUK TR:	$T_t^* = \tau_t^* W_t^* N_t^*$
Scenario 4 (G: 1, $\tau : 1$ )	S Debt s.:	$T_t/P_t = \phi_g^* G_Y g_t + \phi_b^*(B_t/P_t); \quad G_Y = \tau$
	rUK Debt s.:	$T_t^*/P_t^* = \phi_g^* G_Y^* g_t^* + \phi_b^*(B_t^*/P_t^*); \quad G_Y = \tau^*$
	S Bonds:	$(B_{t+1}/P_t)/R_{t+1} = (1 - \phi_g) G_Y g_t + (1 - \phi_b)(B_t/P_t); \quad G_Y = \tau$
	rUK Bonds:	$(B_{t+1}^*/P_t^*)/R_{t+1}^* = (1 - \phi_g^*) G_Y^* g_t^* + (1 - \phi_b^*)(B_t^*/P_t^*); \quad G_Y^* = \tau^*$
	S RC:	$Y_t = C_t + G_t + X_t$
	rUK RC:	$Y_t^* = C_t^* + G_t^* + X_t^*$
	S HBC:	$P_t C_t + \mathbb{E}_t[R_{t+1}^{UK-1} B_{t+1}^{UK}] = B_t^{UK} + (1 - \tau_t^{UK}) W_t N_t + \varpi T_t^{UK}$
	rUK HBC:	$P_t^* C_t^* + \mathbb{E}_t[R_{t+1}^{UK*-1} B_{t+1}^{UK*}] = B_t^{UK} + (1 - \tau_t^{UK}) W_t^* N_t^* + (1 - \varpi) T_t^{UK}$
	S GBC:	N/A
	rUK GBC:	$\mathbb{E}_t[R_{t+1}^{UK-1} B_{t+1}^{UK}] + T_t^{UK} = P_t^{UK} G_t^{UK} + B_t^{UK}$
Scenario 4 (G: 1, $\tau : 1$ )	S TR:	N/A
	rUK TR:	$T_t^{UK} = \varpi \tau_t^{UK} W_t N_t + (1 - \varpi) \tau_t^{UK} W_t^* N_t^*$
	S Debt s.:	N/A
	rUK Debt s.:	$T_t^{UK}/P_t^{UK} = \phi_g^{UK} G_Y^{UK} g_t^{UK} + \phi_b^{UK}(B_t^{UK}/P_t^{UK}); \quad G_Y^{UK} = \tau^{UK}$
	S Bonds:	N/A
	rUK Bonds:	$(B_{t+1}^{UK}/P_t^{UK})/R_{t+1}^{UK} = (1 - \phi_g^{UK}) G_Y^{UK} g_t^{UK} + (1 - \phi_b^{UK})(B_t^{UK}/P_t^{UK}); \quad G_Y^{UK} = \tau^{UK}$
	S RC:	$Y_t = C_t + \varpi G_t^{UK}$
	rUK RC:	$Y_t^* = C_t^* + (1 - \varpi) G_t^{UK}$

where:

S HBC	Household (Scotland) budget constraint
rUK HBC	Household (rUK) budget constraint
S GBC	Government (Holyrood) budget constraint
rUK GBC	Government (Westminister) budget constraint
S TR	Government (Holyrood) tax revenue
rUK TR	Government (Westminister) tax revenue
S RC	Resource (Scotland) constraint
rUK RC	Resource (rUK) constraint

# Tax Revenue

$$T_t^* = \varpi \tau_t W_t N_t + (1 - \varpi) \tau_t W_t^* N_t^*$$

$$T^* = \varpi \tau W N + (1 - \varpi) \tau W^* N^* \quad (\text{Steady state})$$

Using Uhlig's (1999) method,  $X_t Y_t \approx X Y e^{\tilde{X}_t + \tilde{Y}_t}$ :

$$T e^{\tilde{T}_t^*} = \varpi \tau W N e^{\tilde{\tau}_t + \tilde{W}_t + \tilde{N}_t} + (1 - \varpi) \tau W^* N^* e^{\tilde{\tau}_t + \tilde{W}_t^* + \tilde{N}_t^*}$$

Using  $e^{\tilde{X}_t} \approx 1 + \tilde{X}_t$ :

$$T^*(1 + \tilde{T}_t^*) = \varpi \tau W N (1 + \tilde{\tau}_t + \tilde{W}_t + \tilde{N}_t) + (1 - \varpi) \tau W^* N^* (1 + \tilde{\tau}_t + \tilde{W}_t^* + \tilde{N}_t^*)$$

Subtract (??):

$$T^*(1 + \tilde{T}_t^*) - T^* = \varpi \tau W N (1 + \tilde{\tau}_t + \tilde{W}_t + \tilde{N}_t) - \varpi \tau W N + (1 - \varpi) \tau W^* N^* (1 + \tilde{\tau}_t + \tilde{W}_t^* + \tilde{N}_t^*) - (1 - \varpi) \tau W^* N^*$$

$$T^* [(1 + \tilde{T}_t^*) - 1] = \varpi \tau W N [(1 + \tilde{\tau}_t + \tilde{W}_t + \tilde{N}_t) - 1] + (1 - \varpi) \tau W^* N^* [(1 + \tilde{\tau}_t + \tilde{W}_t^* + \tilde{N}_t^*) - 1]$$

$$T^* \tilde{T}_t^* = \varpi \tau W N (\tilde{\tau}_t + \tilde{W}_t + \tilde{N}_t) + (1 - \varpi) \tau W^* N^* (\tilde{\tau}_t + \tilde{W}_t^* + \tilde{N}_t^*)$$

Divide by  $T^*$  :

$$\boxed{\tilde{T}_t^* = \tau \frac{W N}{T^*} \times \varpi (\tilde{\tau}_t + \tilde{W}_t + \tilde{N}_t) + \tau \frac{W^* N^*}{T^*} \times (1 - \varpi) (\tilde{\tau}_t + \tilde{W}_t^* + \tilde{N}_t^*)} \quad (1)$$

$$C_t^\sigma N_t^\varphi = \frac{W_t}{P_t} (1 - \tau_t) \quad (2)$$

$$C_t^\sigma N_t^\varphi = \frac{W_t}{P_t} - \frac{W_t}{P_t} \tau_t \quad (3)$$

$$C^\sigma N^\varphi = \frac{W}{P} - \frac{W}{P} \tau \quad (\text{Steady state}) \quad (4)$$

Using Uhlig's (1999) method,  $X_t Y_t \approx X Y e^{\tilde{X}_t + \tilde{Y}_t}$ , (5)

...and since  $\tau_t$  is tax rate (percentage), we do not need to take logs of it: (6)

$$C^\sigma N^\varphi e^{\sigma c_t + \varphi n_t} = \frac{W}{P} e^{w_t - p_t} - \frac{W}{P} \tau e^{w_t - p_t} - \tilde{\tau}_t \quad (7)$$

Using  $e^{\tilde{X}_t} \approx 1 + \tilde{X}_t$ : (8)

$$C^\sigma N^\varphi (1 + \sigma c_t + \varphi n_t) = \frac{W}{P} (1 + w_t - p_t) - \frac{W}{P} \tau (1 + w_t - p_t) - \tilde{\tau}_t \quad (9)$$

Subtract (4): (10)

$$C^\sigma N^\varphi (\sigma c_t + \varphi n_t) = \frac{W}{P} (w_t - p_t) - \frac{W}{P} \tau (w_t - p_t) - \tilde{\tau}_t \quad (11)$$

$$C^\sigma N^\varphi (\sigma c_t + \varphi n_t) = \frac{W}{P} [(w_t - p_t) - \tau (w_t - p_t) - \tilde{\tau}_t] \quad (12)$$

$$C^\sigma N^\varphi (\sigma c_t + \varphi n_t) = \frac{W}{P} [(1 - \tau)(w_t - p_t) - \tilde{\tau}_t] \quad (13)$$

$$C^\sigma N^\varphi \frac{P}{W} (\sigma c_t + \varphi n_t) = [(1 - \tau)(w_t - p_t) - \tilde{\tau}_t] \quad (14)$$

$$(1 - \tau)(\sigma c_t + \varphi n_t) = [(1 - \tau)(w_t - p_t) - \tilde{\tau}_t] \quad (15)$$

$$\sigma c_t + \varphi n_t = w_t - p_t - \frac{1}{1 - \tau} \tilde{\tau}_t \quad (16)$$

(17)

$$y_t = a_t + (1 - \alpha)n_t \quad (18)$$

$$n_t = \frac{1}{1 - \alpha}(y_t - a_t) \quad (19)$$

$$\varpi = \sigma\eta + (1 - v)(\sigma\eta - 1) \quad (20)$$

$$\sigma c_t + \varphi n_t = w_t - p_t - \frac{1}{1 - \tau}\tau_t \quad (21)$$

$$y_t = (1 - v)c_t + v_t(2 - v)\eta s_t + v y_t^* \quad (22)$$

$$c_t = y_t^* + \frac{1}{\sigma}z_t + \frac{1 - v}{\sigma}s_t \quad (23)$$

$$\implies c_t = y_t - v s_t \left( (2 - v)\eta + \frac{1 - v}{\sigma} \right) + \frac{v}{\sigma}z_t \quad (24)$$

$$\mu_t = -(\sigma c_t + \varphi n_t + \frac{1}{1 - \tau}\tau_t) - v s_t + a_t - \alpha n_t \quad (25)$$

$$= -\sigma c_t - \varphi n_t - \frac{1}{1 - \tau}\tau_t - v s_t + a_t - \alpha n_t \quad (26)$$

$$= -\sigma c_t - \frac{1}{1 - \tau}\tau_t - v s_t + a_t - n_t(\varphi + \alpha) \quad (27)$$

$$(28)$$

$$-n_t(\varphi + \alpha) = -\frac{1}{1 - \alpha}(y_t - a_t)(\varphi + \alpha) \quad (29)$$

$$-n_t(\varphi + \alpha) = -\frac{\varphi + \alpha}{1 - \alpha}(y_t - a_t) \quad (30)$$

$$-n_t(\varphi + \alpha) = -\frac{\varphi + \alpha}{1 - \alpha}y_t + \frac{\varphi + \alpha}{1 - \alpha}a_t \quad (31)$$

$$(32)$$

$$\mu_t = -\sigma c_t - \frac{1}{1 - \tau}\tau_t - v s_t + a_t - \frac{\varphi + \alpha}{1 - \alpha}y_t + \frac{\varphi + \alpha}{1 - \alpha}a_t \quad (33)$$

$$\mu_t = -\sigma c_t - \frac{1}{1 - \tau}\tau_t - v s_t + \left(1 + \frac{\varphi + \alpha}{1 - \alpha}\right)a_t - \frac{\varphi + \alpha}{1 - \alpha}y_t \quad (34)$$

$$\mu_t = -\sigma \left( y_t - v s_t \left( (2 - v)\eta + \frac{1 - v}{\sigma} \right) + \frac{v}{\sigma}z_t \right) - \frac{1}{1 - \tau}\tau_t - v s_t + \left(1 + \frac{\varphi + \alpha}{1 - \alpha}\right)a_t - \frac{\varphi + \alpha}{1 - \alpha}y_t \quad (35)$$

$$\mu_t = -\left( \sigma + \frac{\varphi + \alpha}{1 - \alpha} \right) y_t + \sigma v s_t \left( (2 - v)\eta + \frac{1 - v}{\sigma} \right) - v z_t - \frac{1}{1 - \tau}\tau_t - v s_t + \left(1 + \frac{\varphi + \alpha}{1 - \alpha}\right)a_t \quad (36)$$

$$\mu_t = -\left( \sigma + \frac{\varphi + \alpha}{1 - \alpha} \right) y_t + v s_t \left( \sigma \left( (2 - v)\eta + \frac{1 - v}{\sigma} \right) - 1 \right) - \frac{1}{1 - \tau}\tau_t + \left(1 + \frac{\varphi + \alpha}{1 - \alpha}\right)a_t - v z_t \quad (37)$$

$$\mu_t = -\left( \sigma + \frac{\varphi + \alpha}{1 - \alpha} \right) y_t + v s_t ((2 - v)\sigma\eta + 1 - v) - 1 - \frac{1}{1 - \tau}\tau_t + \left(1 + \frac{\varphi + \alpha}{1 - \alpha}\right)a_t - v z_t \quad (38)$$

$$\mu_t = -\left( \sigma + \frac{\varphi + \alpha}{1 - \alpha} \right) y_t + v s_t ((2 - v)\sigma\eta - v) - \frac{1}{1 - \tau}\tau_t + \left(1 + \frac{\varphi + \alpha}{1 - \alpha}\right)a_t - v z_t \quad (39)$$

$$\mu_t = -\left( \sigma + \frac{\varphi + \alpha}{1 - \alpha} \right) y_t + v s_t (2\sigma\eta - v\sigma\eta - v) - \frac{1}{1 - \tau}\tau_t + \left(1 + \frac{\varphi + \alpha}{1 - \alpha}\right)a_t - v z_t \quad (40)$$

$$\mu_t = -\left( \sigma + \frac{\varphi + \alpha}{1 - \alpha} \right) y_t + v(\varpi - 1)s_t - \frac{1}{1 - \tau}\tau_t + \left(1 + \frac{\varphi + \alpha}{1 - \alpha}\right)a_t - v z_t \quad (41)$$

$$\pi_{H,t} = \beta \mathbb{E}\{\pi_{H,t+1}\} + \lambda \hat{\mu}_t \implies \pi_{H,t} = \beta \mathbb{E}\{\pi_{H,t+1}\} - \lambda \mu_t \quad (42)$$

$$\pi_{H,t} = \beta \mathbb{E}\{\pi_{H,t+1}\} + \lambda \left( \left( \sigma + \frac{\varphi + \alpha}{1 - \alpha} \right) y_t - v(\varpi - 1)s_t + \frac{1}{1 - \tau}\tau_t - \left(1 + \frac{\varphi + \alpha}{1 - \alpha}\right)a_t + v z_t \right) \quad (43)$$

$$\pi_{H,t} = \beta \mathbb{E}\{\pi_{H,t+1}\} + \kappa y_t + \lambda \left( -v(\varpi - 1)s_t + \frac{1}{1 - \tau}\tau_t - \left(1 + \frac{\varphi + \alpha}{1 - \alpha}\right)a_t + v z_t \right) \quad (44)$$

$$\pi_{H,t} = \beta \mathbb{E}\{\pi_{H,t+1}\} + \kappa y_t - \lambda v(\varpi - 1)s_t + \lambda \frac{1}{1 - \tau}\tau_t - \lambda \left(1 + \frac{\varphi + \alpha}{1 - \alpha}\right)a_t + \lambda v z_t \quad (45)$$

$$(46)$$



$$c_t = \mathbb{E}\{c_{t+1}\} - \frac{1}{\sigma}(i_t - \mathbb{E}\{\pi_{t+1}\} - \rho) + \frac{1}{\sigma}(1 - \rho_z)z_t \quad (53)$$

$$\pi_t = \pi_{H,t} + v\Delta s_t \quad (54)$$

$$\implies c_t = \mathbb{E}\{c_{t+1}\} - \frac{1}{\sigma}(i_t - \mathbb{E}\{\pi_{H,t+1}\} - \rho) + \frac{v}{\sigma}\mathbb{E}\{\Delta s_{t+1}\} + \frac{1}{\sigma}(1 - \rho_z)z_t \quad (55)$$

$$c_t = y_t^* + \frac{1}{\sigma}z_t + \left(\frac{1-v}{\sigma}\right)s_t \quad (56)$$

$$Y_t(i) = C(i)_t + X(i)_t + G(i)_t \quad (57)$$

$$= \left(\frac{P_{H,t}(i)}{P_{H,t}}\right)^{-\epsilon} \left[(1-v) \left(\frac{P_{H,t}}{P_t}\right)^{-\eta} C_t + vS_t^\eta Y_t^* + G_t\right] \quad (58)$$

Given that

$$Y_t = \left(\int_0^1 (Y_t(i))^{\frac{\epsilon-1}{\epsilon}}\right)^{\frac{\epsilon}{\epsilon-1}} \quad (59)$$

$$Y_t = (1-v) \left(\frac{P_{H,t}}{P_t}\right)^{-\eta} C_t + vS_t^\eta Y_t^* + G_t \quad (60)$$

$$Y\mathbf{e}^{y_t} = (1-v) \left(\frac{P}{P_H}\right)^\eta C\mathbf{e}^{-\eta p_{H,t} + \eta p_t + c_t} + vS^\eta Y^* \mathbf{e}^{\eta s_t + y_t^*} + G\mathbf{e}^{g_t} \quad (61)$$

$$Y(1+y_t) = (1-v) \left(\frac{P}{P_H}\right)^\eta C(1-\eta p_{H,t} + \eta p_t + c_t) + vS^\eta Y^*(1+\eta s_t + y_t^*) + G(1+g_t) \quad (62)$$

$$Yy_t = (1-v) \left(\frac{P}{P_H}\right)^\eta C(-\eta p_{H,t} + \eta p_t + c_t) + vS^\eta Y^*(\eta s_t + y_t^*) + Gg_t \quad (63)$$

$$\text{Using } P/P_H = vS, S = 1, \text{ and } C = Y^* : \quad (64)$$

$$y_t = (1-v)(-\eta p_{H,t} + \eta p_t + c_t) + v(\eta s_t + y_t^*) + G_Y g_t \quad (65)$$

$$\text{Using } p_t - p_{H,t} = vs_t : \quad (66)$$

$$y_t = (1-v)(\eta vs_t + c_t) + v(\eta s_t + y_t^*) + G_Y g_t \quad (67)$$

$$y_t = (1-v)c_t + (1-v)\eta vs_t + v\eta s_t + vy_t^* + G_Y g_t \quad (68)$$

$$y_t = (1-v)c_t + v(2-v)\eta s_t + vy_t^* + G_Y g_t \quad (69)$$

$$(70)$$

$$c_t = y_t^* + \frac{1}{\sigma} z_t + \frac{1-v}{\sigma} s_t \quad (71)$$

$$y_t = (1-v)c_t + v(2-v)\eta s_t + v y_t^* + G_Y g_t \quad (72)$$

$$\implies y_t = (1-v) \left( y_t^* + \frac{1}{\sigma} z_t + \frac{1-v}{\sigma} s_t \right) + v(2-v)\eta s_t + v y_t^* + G_Y g_t \quad (73)$$

$$y_t = (1-v)y_t^* + \frac{1-v}{\sigma} z_t + (1-v)\frac{1-v}{\sigma} s_t + v(2-v)\eta s_t + v y_t^* + G_Y g_t \quad (74)$$

$$y_t = y_t^* + \frac{1-v}{\sigma} z_t + (1-v)\frac{1-v}{\sigma} s_t + v(2-v)\eta s_t + G_Y g_t \quad (75)$$

$$y_t = y_t^* + \frac{1-v}{\sigma} z_t + \left( (1-v)\frac{1-v}{\sigma} + v(2-v)\eta \right) s_t + G_Y g_t \quad (76)$$

$$\left( (1-v)\frac{1-v}{\sigma} + v(2-v)\eta \right) s_t = y_t - y_t^* - \frac{1-v}{\sigma} z_t - G_Y g_t \quad (77)$$

$$\left( \frac{(1-v)(1-v) + \sigma v(2-v)\eta}{\sigma} \right) s_t = y_t - y_t^* - \frac{1-v}{\sigma} z_t - G_Y g_t \quad (78)$$

$$\left( \frac{1-2v+v^2+\sigma v(2-v)\eta}{\sigma} \right) s_t = y_t - y_t^* - \frac{1-v}{\sigma} z_t - G_Y g_t \quad (79)$$

$$\left( \frac{1-v(2-v) + \sigma v(2-v)\eta}{\sigma} \right) s_t = y_t - y_t^* - \frac{1-v}{\sigma} z_t - G_Y g_t \quad (80)$$

$$\left( \frac{1-v(2-v)(1-\sigma\eta)}{\sigma} \right) s_t = y_t - y_t^* - \frac{1-v}{\sigma} z_t - G_Y g_t \quad (81)$$

$$\left( \frac{1+v(2-v)(\sigma\eta-1)}{\sigma} \right) s_t = y_t - y_t^* - \frac{1-v}{\sigma} z_t - G_Y g_t \quad (82)$$

$$\left( \frac{1+v(2\sigma\eta-v\sigma\eta-2+v)}{\sigma} \right) s_t = y_t - y_t^* - \frac{1-v}{\sigma} z_t - G_Y g_t \quad (83)$$

$$\left( \frac{1+v(\varpi-1)}{\sigma} \right) s_t = y_t - y_t^* - \frac{1-v}{\sigma} z_t - G_Y g_t \quad (84)$$

$$\sigma^{-1}\Phi^{-1} s_t = y_t - y_t^* - \frac{1-v}{\sigma} z_t - G_Y g_t \quad (85)$$

$$s_t = \sigma\Phi(y_t - y_t^*) - (1-v)\Phi z_t - G_Y \sigma\Phi g_t \quad (86)$$

$$s_t = \sigma_v(y_t - y_t^*) - (1-v)\Phi z_t - G_Y \sigma_v g_t \quad (87)$$

$$(88)$$

$$\Phi = \frac{1}{1+v(\varpi-1)} \quad (89)$$

$$\varpi = \sigma\eta + (1-v)(\sigma\eta-1) = 2\sigma\eta - v\sigma\eta - 1 + v \quad (90)$$

$$\sigma_v = \sigma\Phi \quad (91)$$



$$y_t = (1-v)c_t + v(2-v)\eta s_t + v y_t^* + G_Y g_t \quad (92)$$

$$\implies c_t = (1-v)^{-1}(y_t - v(2-v)\eta s_t - v y_t^* - G_Y g_t) \quad (93)$$

$$c_t = \mathbb{E}\{c_{t+1}\} - \frac{1}{\sigma}(i_t - \mathbb{E}\{\pi_{t+1}\} - \rho) + \frac{v}{\sigma}\mathbb{E}\{\Delta s_{t+1}\} + \frac{1}{\sigma}(1-\rho_z)z_t \quad (94)$$

$$s_t = \sigma_v(y_t - y_t^*) - (1-v)\Phi z_t - G_Y \sigma_v g_t \quad (95)$$

$$(96)$$

$$0 = \mathbb{E}\{\Delta c_{t+1}\} - \frac{1}{\sigma}(i_t - \mathbb{E}\{\pi_{H,+1}\} - \rho) + \frac{v}{\sigma}\mathbb{E}\{\Delta s_{t+1}\} + \frac{1}{\sigma}(1-\rho_z)z_t$$

$$0 = \mathbb{E}\{\Delta y_{t+1}\} - v(2-v)\eta \mathbb{E}\{\Delta s_{t+1}\} - v \mathbb{E}\{\Delta y_{t+1}^*\} - G_Y \Delta g_{t+1} - \frac{1-v}{\sigma}(i_t - \mathbb{E}\{\pi_{H,+1}\} - \rho) + \frac{(1-v)v}{\sigma}\mathbb{E}\{\Delta s_{t+1}\} + \frac{1-v}{\sigma}(1-\rho_z)z_t$$

$$0 = \mathbb{E}\{\Delta y_{t+1}\} + \left(\frac{(1-v)v}{\sigma} - v(2-v)\eta\right)\mathbb{E}\{\Delta s_{t+1}\} - v \mathbb{E}\{\Delta y_{t+1}^*\} - G_Y \Delta g_{t+1} - \frac{1-v}{\sigma}(i_t - \mathbb{E}\{\pi_{H,+1}\} - \rho) + \frac{1-v}{\sigma}(1-\rho_z)z_t$$

$$0 = \mathbb{E}\{\Delta y_{t+1}\} - \left(\frac{v\varpi}{\sigma}\right)\mathbb{E}\{\Delta s_{t+1}\} - v \mathbb{E}\{\Delta y_{t+1}^*\} - G_Y \Delta g_{t+1} - \frac{1-v}{\sigma}(i_t - \mathbb{E}\{\pi_{H,+1}\} - \rho) + \frac{1-v}{\sigma}(1-\rho_z)z_t$$

$$0 = \mathbb{E}\{\Delta y_{t+1}\} - \left(\frac{v\varpi}{\sigma}\right)\mathbb{E}\left(\sigma_v(\Delta y_{t+1} - \Delta y_{t+1}^*) - (1-v)\Phi(\Delta z_{t+1}) - G_Y \sigma_v \Delta g_{t+1}\right) - v \mathbb{E}\{\Delta y_{t+1}^*\} - \frac{1-v}{\sigma}(i_t - \mathbb{E}\{\pi_{H,+1}\} - \rho) + \frac{1-v}{\sigma}(1-\rho_z)z_t$$

$$0 = \mathbb{E}\{\Delta y_{t+1}\} - v\varpi\Phi\Delta y_{t+1} + v\varpi\Phi\Delta y_{t+1}^* - v \mathbb{E}\{\Delta y_{t+1}^*\} + \frac{1-v}{\sigma}(1-\rho_z)z_t + v\varpi\Phi\frac{1-v}{\sigma}(\rho_z - 1)z_t + v\varpi\Phi G_Y \Delta g_{t+1} - G_Y \Delta g_{t+1} - \frac{1-v}{\sigma}(i_t - \mathbb{E}\{\pi_{H,+1}\} - \rho)$$

$$0 = \Phi^{-1}\mathbb{E}\{\Delta y_{t+1}\} - v\varpi\Delta y_{t+1} + v\varpi\Delta y_{t+1}^* - v\Phi^{-1}\mathbb{E}\{\Delta y_{t+1}^*\}$$

$$+ \Phi^{-1}\frac{1-v}{\sigma}(1-\rho_z)z_t + v\varpi\frac{1-v}{\sigma}(\rho_z - 1)z_t + v\varpi G_Y \Delta g_{t+1} - G_Y \Delta g_{t+1}$$

$$- \frac{1-v}{\sigma_v}(i_t - \mathbb{E}\{\pi_{H,+1}\} - \rho)$$

$$0 = (\Phi^{-1} - v\varpi)\Delta y_{t+1} + v(\varpi - \Phi^{-1})\mathbb{E}\{\Delta y_{t+1}^*\}$$

$$- (\Phi^{-1} - v\varpi)\frac{1-v}{\sigma}(\rho_z - 1)z_t + (v\varpi - 1)G_Y \Delta g_{t+1}$$

$$- \frac{1-v}{\sigma_v}(i_t - \mathbb{E}\{\pi_{H,+1}\} - \rho)$$

$$0 = \Delta y_{t+1} + \frac{v(\varpi - \Phi^{-1})}{\Phi^{-1} - v\varpi}\mathbb{E}\{\Delta y_{t+1}^*\}$$

$$- \frac{1-v}{\sigma}(\rho_z - 1)z_t + \frac{(v\varpi - 1)}{\Phi^{-1} - v\varpi}G_Y \Delta g_{t+1}$$

$$- \frac{1-v}{\Phi^{-1} - v\varpi}\frac{1}{\sigma_v}(i_t - \mathbb{E}\{\pi_{H,+1}\} - \rho)$$

$$y_t = y_{t+1} - \frac{1-v}{\sigma}(\rho_z - 1)z_t$$

$$+ \frac{(v\varpi - 1)}{\Phi^{-1} - v\varpi}G_Y \Delta g_{t+1} + \frac{v(\varpi - \Phi^{-1})}{\Phi^{-1} - v\varpi}\mathbb{E}\{\Delta y_{t+1}^*\} - \frac{1-v}{\Phi^{-1} - v\varpi}\frac{1}{\sigma_v}(i_t - \mathbb{E}\{\pi_{H,+1}\} - \rho)$$

$$y_t = y_{t+1} - \frac{1-v}{\sigma}(\rho_z - 1)z_t - \frac{1-v}{1-v}\frac{1}{\sigma_v}(i_t - \mathbb{E}\{\pi_{H,+1}\} - \rho) + \frac{(1-v)(v\varpi - v)}{1-v}\mathbb{E}\{\Delta y_{t+1}^*\} + \frac{v\varpi - 1}{1-v}G_Y \Delta g_{t+1}$$

$$y_t = y_{t+1} - \frac{1}{\sigma_v}(i_t - \mathbb{E}\{\pi_{H,+1}\} - \rho) + v(\varpi - 1)\mathbb{E}\{\Delta y_{t+1}^*\} + \frac{1-v}{\sigma}(1-\rho_z)z_t + \frac{v\varpi - 1}{1-v}G_Y \Delta g_{t+1}$$

$$y_t^n = y_{t+1}^n - \frac{1}{\sigma_v}(r_t^n - \rho) + v(\varpi - 1)\mathbb{E}\{\Delta y_{t+1}^*\} + \frac{1-v}{\sigma}(1-\rho_z)z_t + \frac{v\varpi - 1}{1-v}G_Y \Delta g_{t+1} \quad (97)$$

$$0 = \Delta y_{t+1}^n - \frac{1}{\sigma_v}(r_t^n - \rho) + v(\varpi - 1)\mathbb{E}\{\Delta y_{t+1}^*\} + \frac{1-v}{\sigma}(1-\rho_z)z_t + \frac{v\varpi - 1}{1-v}G_Y \Delta g_{t+1} \quad (98)$$

$$0 = \sigma_v \Delta y_{t+1}^n - (r_t^n - \rho) + \sigma_v v(\varpi - 1)\mathbb{E}\{\Delta y_{t+1}^*\} + \Phi(1-v)(1-\rho_z)z_t + \sigma_v \frac{v\varpi - 1}{1-v}G_Y \Delta g_{t+1} \quad (99)$$

$$r_t^n = \sigma_v \Delta y_{t+1}^n + \rho + \sigma_v v(\varpi - 1)\mathbb{E}\{\Delta y_{t+1}^*\} + \Phi(1-v)(1-\rho_z)z_t + \sigma_v \frac{v\varpi - 1}{1-v}G_Y \Delta g_{t+1} \quad (100)$$

$$(101)$$

$$0 = \sigma_v \Delta y_{t+1} - (i_t - \mathbb{E}\{\pi_{H,+1}\}) + \rho + \sigma_v v(\varpi - 1)\mathbb{E}\{\Delta y_{t+1}^*\} + \Phi(1-v)(1-\rho_z)z_t + \sigma_v \frac{v\varpi - 1}{1-v}G_Y \Delta g_{t+1} \quad (102)$$

$$- (\sigma_v \Delta y_{t+1}^n - (r_t^n - \rho) + \sigma_v v(\varpi - 1)\mathbb{E}\{\Delta y_{t+1}^*\} + \Phi(1-v)(1-\rho_z)z_t + \sigma_v \frac{v\varpi - 1}{1-v}G_Y \Delta g_{t+1}) \quad (103)$$

$$0 = \sigma_v \Delta \tilde{y}_{t+1} - (i_t - \mathbb{E}\{\pi_{H,+1}\} - r_t^n) \quad (104)$$

$$\tilde{y}_t = \tilde{y}_{t+1} - \frac{1}{\sigma_v}(i_t - \mathbb{E}\{\pi_{H,+1}\} - r_t^n) \quad \text{Dynamic IS Curve} \quad (105)$$

$$(106)$$

$$r_t^n = \sigma_v \Delta y_{t+1}^n + \rho + \sigma_v v(\varpi - 1) \mathbb{E}\{\Delta y_{t+1}^*\} + \Phi(1-v)(1-\rho_z)z_t + \sigma_v \frac{v\varpi - 1}{1-v} G_Y \Delta g_{t+1} \quad (107)$$

$$\sigma_v \Delta y_{t+1}^n = \sigma_v (\Gamma_* \Delta y_{t+1}^* + \Gamma_z \Delta z_{t+1} + \Gamma_a \Delta a_{t+1} + \Gamma_g \Delta g_{t+1} + \Gamma_\tau \Delta \tau_{t+1}) \quad (108)$$

$$y_t^* : \sigma_v \Gamma_* \Delta y_{t+1}^* + \sigma_v v(\varpi - 1) \Delta y_{t+1}^* = \sigma_v (\Gamma_* + v(\varpi - 1)) \Delta y_{t+1}^* = \Psi_* y_{t+1}^* \quad (109)$$

$$z_t : \sigma_v \Gamma_z \Delta z_{t+1} + \Phi(1-\rho_z)z_t = \sigma_v \Gamma_z (\rho_z - 1)z_t + \Phi(1-v)(1-\rho_z)z_t \quad (110)$$

$$= \sigma_v \Gamma_z (\rho_z - 1)z_t + \Phi(1-v)(1-\rho_z)z_t = (\Phi(1-v) - \sigma_v \Gamma_z)(1-\rho_z)z_t = \Psi_z (1-\rho_z)z_t \quad (111)$$

$$a_t : \sigma_v \Gamma_a \Delta a_{t+1} = \sigma_v \Gamma_a (\rho_a - 1)a_t = -\sigma_v \Gamma_a (1-\rho_a)a_t \quad (112)$$

$$g_t : \sigma_v \Gamma_g G_Y \Delta g_{t+1} + \sigma_v \frac{v\varpi - 1}{1-v} G_Y \Delta g_{t+1} = \left( \sigma_v \left( \Gamma_g + \frac{v\varpi - 1}{1-v} \right) \right) G_Y \Delta g_{t+1} = -\Psi_g G_Y (1-\rho_g)g_t \quad (113)$$

$$\tau_t : \sigma_v \Gamma_\tau \Delta \tau_{t+1} \quad (114)$$

$$r_t^n = \rho + \Psi_* y_{t+1}^* + \Psi_z (1-\rho_z)z_t - \sigma_v \Gamma_a (1-\rho_a)a_t - \Psi_g G_Y (1-\rho_g)g_t + \sigma_v \Gamma_\tau \Delta \tau_{t+1} \quad (115)$$

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# Structure. Max words: 10 000. Currently: 1691

1. Introduction: 1000 words
2. Literature Review 2000 words
  - (a) From RBC to NK DSGE: **1200 words**
  - (b) Why Scotland and the rest of the UK? (NIESR policy-related question): **800 words**
3. Theoretical DSGE model: 2000 words
  - (a) Households
  - (b) Firms
  - (c) Equilibrium
4. Application: 1500 words
  - (a) Data: **500 words**
  - (b) Estimation (MCMC): **1000 words**
5. Results: 2500 words
  - (a) Analysis of IRFs: **1000 words**
  - (b) Other insights (NIESR policy-related question): **1500 words**
6. Conclusion: 1000 words

Sum count: 1691  
 Words in text: 1518  
 Words in headers: 31  
 Words outside text (captions, etc.): 44  
 Number of headers: 13  
 Number of floats/tables/figures: 2  
 Number of math inlines: 42  
 Number of math displayed: 56  
 Files: 13  
 Subcounts:  
 text+headers+captions (#headers/#floats/#inlines/#displayed)  
 4+9+0 (7/0/0/0) File: main.tex  
 99+11+0 (1/0/0/0) Included file: ../model.tex  
 65+6+0 (1/0/0/0) Included file: ../structure.tex  
 591+2+0 (1/0/0/0) Included file: ../Introduction/literature\_review.tex  
 155+0+0 (0/0/3/0) Included file: ../Theoretical DSGE model/model.tex  
 557+1+33 (1/0/36/41) Included file: ../Theoretical DSGE model/households.tex  
 26+1+0 (1/0/3/5) Included file: ../Theoretical DSGE model/firms.tex  
 20+1+0 (1/0/0/10) Included file: ../Theoretical DSGE model/equilibrium.tex  
 1+0+0 (0/0/0/0) Included file: ../final\_wordcount.txt  
 0+0+11 (0/1/0/0) Included file: ../Graphs/timeline.tex  
 0+0+0 (0/1/0/0) Included file: ../Graphs/sigma\_varphi.tex