

1 Vectors in \mathbb{R}^n

Recall

Vectors in $\mathbb{R}^n = \left\{ \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} \mid x_i \in \mathbb{R} \right\}$

We can also work with $\mathbb{C}^n = \left\{ \begin{bmatrix} z_1 \\ \vdots \\ z_n \end{bmatrix} \mid z_i \in \mathbb{C} \right\}$

1.5 Dot Product

Definition

Let $\vec{u} = \begin{bmatrix} u_1 \\ u_2 \\ \vdots \\ u_n \end{bmatrix}$ and $\vec{v} = \begin{bmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{bmatrix}$ be vectors in \mathbb{R}^n . We define their **dot product** by

$$\vec{u} \cdot \vec{v} = u_1 v_1 + u_2 v_2 + \cdots + u_n v_n$$

Theorem 1.1: Property 1.5.3

1. $\vec{u}, \vec{v}, \vec{w} \in \mathbb{R}^n$
2. $\vec{u} \cdot \vec{v} = \vec{v} \cdot \vec{u}$
3. $(\vec{u} + \vec{v}) \cdot \vec{w} = \vec{u} \cdot \vec{w} + \vec{v} \cdot \vec{w}$
4. $(\vec{u} \cdot \vec{v}) \cdot \vec{w} = \vec{v} \cdot (\vec{u} \cdot \vec{w})$
5. $\vec{v} \cdot \vec{v} \geq 0$

Geometry in \mathbb{R}^2

Definition

The **length** of the vector $\vec{v} \in \mathbb{R}^n$ is $\|\vec{v}\| = \sqrt{\vec{v} \cdot \vec{v}}$

Aside: In \mathbb{R}^1 :

$$\|\vec{v}\| = \|[v_1]\| = \sqrt{v_1^2} = |v|$$

Theorem 1.2: Properties of Length

1. $\|\vec{0}\| = 0$
2. $\|c \cdot \vec{v}\| = |c| \cdot \|\vec{v}\|$
3. $\|\vec{v} + \vec{u}\| \neq \|\vec{v}\| + \|\vec{u}\|$
4. $\|\vec{v} + \vec{u}\| \leq \|\vec{v}\| + \|\vec{u}\|$

Importance of dot product: It gives angles between vectors in \mathbb{R}^2 !

Definition

$\vec{v} \in \mathbb{R}^n$ is a **unit vector** if $\|\vec{v}\| = 1$

Definition

When $\vec{v} \in \mathbb{R}^n$ is a non-zero vector, we can produce a unit vector

$$\hat{v} = \frac{\vec{v}}{\|\vec{v}\|}$$

in the direction of \vec{v} by scaling \vec{v} . This process is called normalization.

Definition

Let \vec{v} and \vec{u} be non-zero vectors in \mathbb{R}^n . The angle θ , in radians ($0 \leq \theta < \pi$), between \vec{u} and \vec{v} is such that

$$\vec{v} \cdot \vec{u} = \|\vec{u}\| \cdot \|\vec{v}\| \cos \theta, \text{ that is } \theta = \arccos\left(\frac{\vec{u} \cdot \vec{v}}{\|\vec{v}\| \cdot \|\vec{u}\|}\right)$$

Example

Problem: Given 2 vectors, $\begin{bmatrix} 0 \\ 1 \end{bmatrix}$ and $\begin{bmatrix} 1 \\ 0 \end{bmatrix}$ find θ .

Solution:

$$\begin{aligned}\cos \theta &= \frac{\begin{bmatrix} 0 \\ 1 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 0 \end{bmatrix}}{\left\| \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right\| \cdot \left\| \begin{bmatrix} 1 \\ 0 \end{bmatrix} \right\|} \\ &= \frac{0}{1} = 0 \\ \theta &= \frac{\pi}{2}\end{aligned}$$

Definition

Let $\vec{u}, \vec{v} \in \mathbb{R}^n$. We say \vec{u} and \vec{v} are perpendicular (or orthogonal) if $\vec{u} \cdot \vec{v} = 0$

Example

Problem: Find a non-zero vector in \mathbb{R}^2 that is orthogonal to $\begin{bmatrix} 1 \\ 2 \end{bmatrix}$

Solution: $\begin{bmatrix} 2 \\ -1 \end{bmatrix}, \begin{bmatrix} -2 \\ 1 \end{bmatrix}, \begin{bmatrix} 6 \\ -3 \end{bmatrix}$

Example

Problem: Find a non-zero vector perpendicular to $\begin{bmatrix} a \\ b \end{bmatrix}$

Solution:

$$\begin{aligned}&\begin{bmatrix} -b \\ a \end{bmatrix} \cdot \begin{bmatrix} a \\ b \end{bmatrix} \\ &= -ba + ab \\ &= 0\end{aligned}$$

Therefore, $\begin{bmatrix} -b \\ a \end{bmatrix}$ is a solution.