

Convex Functions cont'

Lecture 3 for 18660/18460: Optimization

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Admin Stuff

- HW 1 will be released and due **Feb 5**
- Quiz for Lecture 3 out, due Jan 22 before lecture

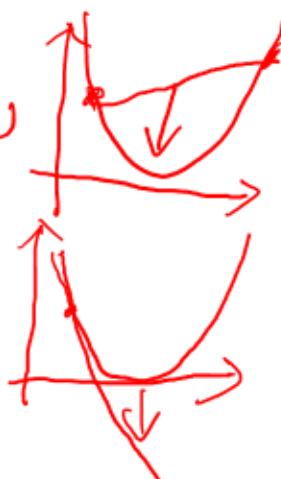
Recall

Typical functions and their convexity

- Affine $f(x) = a^T x + b$
- Quadratic $f(x) = x^T A x$ where A is symmetric & positive semi-definite
- Simple univariate functions e^x , x^α over $(0, +\infty)$ ($\alpha \leq 0, \alpha \geq 1$)
- $\log x$ over $(0, +\infty)$

Ways to check convexity

- Definition $\forall x, y, \forall t \in [0, 1] \quad f(tx + (1-t)y) \leq tf(x) + (1-t)f(y)$
- First order and second order condition $\begin{cases} \forall x, y, f(y) \geq f(x) + \nabla f(x)^T (y-x) \\ \forall x, \nabla^2 f(x) \succeq 0, 1-d case: f''(x) \geq 0 \end{cases}$



Recall: Norm Functions

Recall: ℓ_p norms for a vector $x \in \mathbb{R}^n$ is defined by

$$\|x\|_p = \left(\sum_{i=1}^n |x_i|^p \right)^{1/p} \quad \text{for } p \geq 1$$

Special cases:

$$\|x\|_2 = \sqrt{\sum_{i=1}^n |x_i|^2}$$

$$\|x\|_1 = \sum_{i=1}^n |x_i|$$

$$\|x\|_\infty = \max_{i=1,\dots,n} |x_i|$$

Properties: Any norm $\|x\|$ satisfies

- For $a \in \mathbb{R}$, $\|ax\| = |a|\|x\|$
- $\|x\| = 0$ if and only if $x = 0$
- Triangle inequality: $\|x + y\| \leq \|x\| + \|y\|$

Recall: Norm Functions

Lemma. All norm functions are convex!

Proof: use triangle inequality

$$\begin{aligned} \|\underbrace{tx + (1-t)y}\| &\leq \|tx\| + \|(1-t)y\| \\ &= \underbrace{t \cdot \|x\| + (1-t) \cdot \|y\|} \end{aligned}$$

Quiz Results

$$\det(\lambda I - A)$$

$$|A - \lambda I|$$

Select all functions that are convex.

100 % (A) $f(x) = e^x + 1$ over domain \mathbb{R}

12 % (B) $f(x_1, x_2) = x_1 x_2$ over domain \mathbb{R}^2

88 % (C) $f(x) = x \log x + (1 - x) \log(1 - x)$ over domain $(0, 1)$

84 % (D) $f(x_1, x_2) = x_1^2 + x_2^2 + x_1 x_2$ over domain \mathbb{R}^2

$$(B) \nabla^2 f(x_1, x_2) = \begin{bmatrix} \frac{\partial^2 f}{\partial x_1^2} & \frac{\partial^2 f}{\partial x_1 \partial x_2} \\ \frac{\partial^2 f}{\partial x_1 \partial x_2} & \frac{\partial^2 f}{\partial x_2^2} \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$$

$$\det(\lambda I - \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}) = \det \begin{vmatrix} \lambda - 0 & -1 \\ -1 & \lambda - 0 \end{vmatrix} = \lambda^2 - 1 = 0$$

$\Rightarrow \begin{cases} \lambda=1 \\ \lambda=-1 \end{cases} \Leftarrow \text{means } \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \text{ NOT PSD.}$

$$(C) f(x) = \underline{x \log x} + \underline{(1-x) \log(1-x)}$$

$$\begin{aligned} f'(x) &= \underline{(x)' \cdot \log x} + \underline{x \cdot (\log x)' } \\ &\quad + \underline{(1-x)' \log(1-x)} \\ &\quad + \underline{(1-x)(\log(1-x))'} \\ &= \underline{\log x} + x \cdot \frac{1}{x} + (-1) \cdot \log(1-x) \\ &\quad + (1-x) \cdot \frac{1}{1-x} \cdot (-1) \end{aligned}$$

$$\begin{aligned} &= \log x + 1 - \log(1-x) - 1 \\ &= \underline{\log x} - \log(1-x) \end{aligned}$$

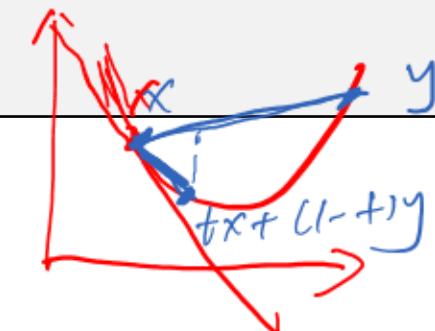
$$\begin{aligned} f''(x) &= \frac{1}{x} + \frac{1}{1-x} > 0 \\ &> 0 &> 0 \end{aligned}$$

Tool 1: First Order Condition for Convexity

$$\lim_{t \rightarrow 0} \frac{f(x + t(y-x)) - f(x)}{t(y-x)} = f'(x)(y-x)$$

Lemma. A differentiable function $f(x)$ is convex if and only if for any x, y ,

$$f(y) \geq f(x) + \nabla f(x)^T(y - x). \quad (*)$$



How to prove this lemma? \Rightarrow , Assume f convex. prove $(*)$

By Def. of convex: $\forall x, y, t \in [0, 1]$

$$f((1-t)x + ty) \leq (1-t)f(x) + tf(y)$$

"Directional Gradient"

$$\frac{f(x + t(y-x)) - f(x)}{t} \leq f(y) - f(x)$$

Let $t \rightarrow 0$

$$\nabla f(x)^T(y-x) \leq f(y) - f(x)$$

$$\Rightarrow f(y) \geq f(x) + \nabla f(x)^T(y-x)$$

Def. of grad
 $\lim_{\Delta x \rightarrow 0} \frac{f(x + \Delta x) - f(x)}{\Delta x} = f'(x)$

Tool 1: First Order Condition for Convexity

Lemma. A differentiable function $f(x)$ is convex if and only if for any x, y ,

$$f(y) \geq f(x) + \nabla f(x)^T(y - x). \quad (*)$$

How to prove this lemma? \Leftarrow Assume $(*)$. prove convexity
in other words, want to prove, $\forall x, y, t$

$$\underline{f((1-t)x + ty)} \leq (1-t)f(x) + t f(y)$$

$$\underline{z = (1-t)x + ty}$$

Apply $(*)$ to (x, z)

$$f(x) \geq f(z) + \nabla f(z)^T(\underline{x - z}) \quad \textcircled{1}$$

Apply $(*)$ to (y, z)

$$f(y) \geq f(z) + \nabla f(z)^T(\underline{y - z}) \quad \textcircled{2}$$

observation

$$\begin{aligned} & \frac{(1-t)(x-z) + t(y-z)}{(1-t)x + ty - z} \\ &= 0 \end{aligned}$$

$$\begin{aligned} & \frac{\textcircled{1}x(1-t) + \textcircled{2}x + (1-t)f(x) + t f(y)}{(1-t)x + ty} \\ & \geq \frac{(1-t)f(z) + \underline{(1-t)\nabla f(z)^T(x-z)}}{\underline{+ t f(z) + t \nabla f(z)^T(y-z)}} \\ &= f(z) + 0 \end{aligned}$$

Summary so far

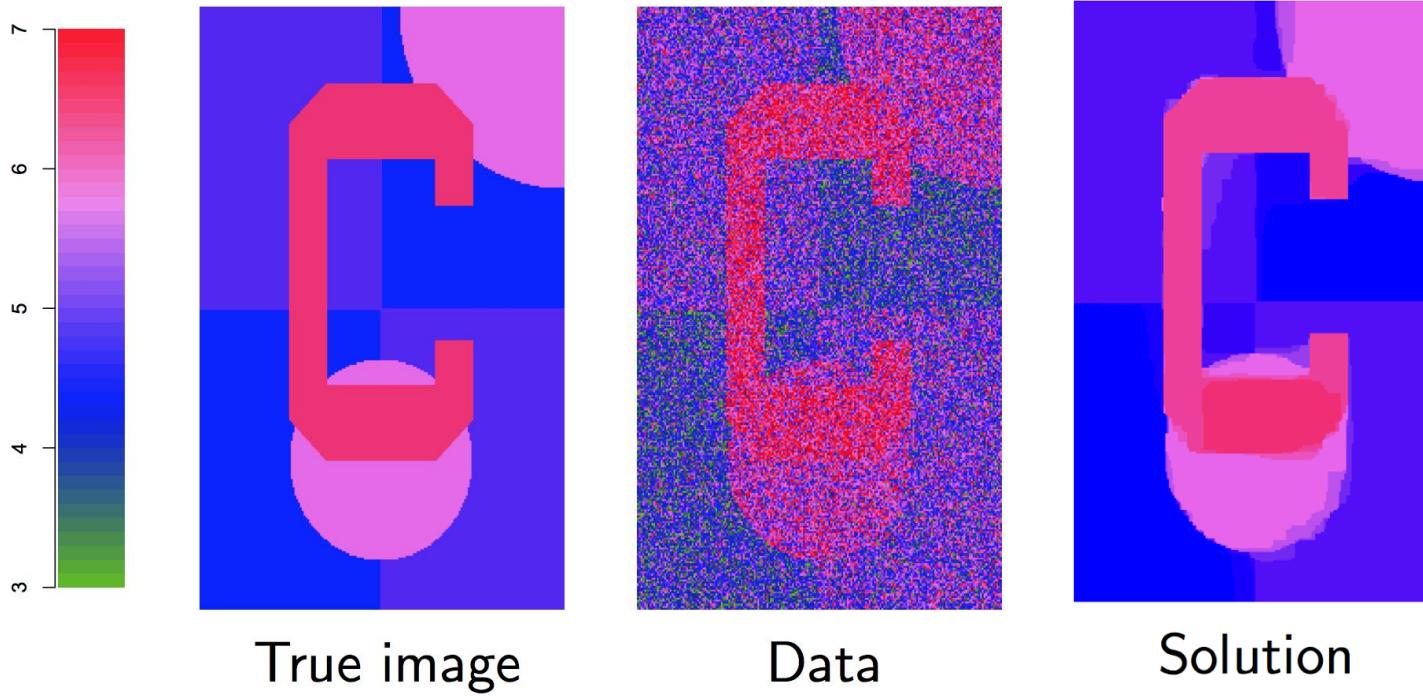
We have studied the convexity of

- Linear/affine functions
- Quadratic functions
- Simple univariate functions
- Norm functions

What about more sophisticated functions?

- e.g. $f(x) = \underline{x^2} + \underline{e^x}$?
- e.g. $f(x) = \frac{1}{2} \underline{x^\top A x} + \underline{b^\top x} + c$?
- e.g. the denoising example last lecture

Revisit: Denoising



$$\min_{\theta_1, \dots, \theta_n} \frac{1}{2} \sum_{i=1}^n (y_i - \theta_i)^2 + \lambda \sum_{(i,j) \text{ adjacent}} |\theta_i - \theta_j|$$

θ_i stays close to y_i penalize changes in adjacent pixels

Revisit: Denoising

Is this function convex?

$$\min_{\theta_1, \dots, \theta_n} \frac{1}{2} \sum_{i=1}^n (y_i - \theta_i)^2 + \lambda \sum_{(i,j) \text{ adjacent}} |\theta_i - \theta_j|$$

Summary so far

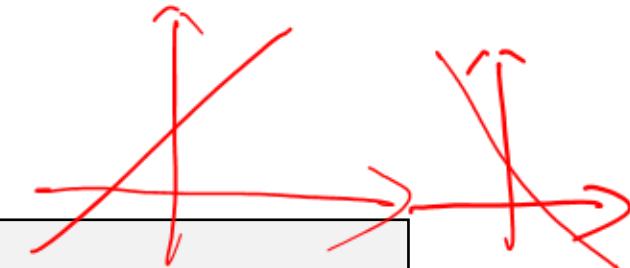
We have studied the convexity of

- Linear/affine functions
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What about more sophisticated functions?

- e.g. $f(x) = x^2 + e^x$?
- e.g. $f(x) = \frac{1}{2}x^T Ax + b^T x + c$
- e.g. the denoising example last lecture
- Next: operations that preserve convexity!

Operations Preserving Convexity



Nonnegative linear combination

f_1, \dots, f_m convex implies $a_1 f_1 + \dots + a_m f_m$ convex for any $a_1, \dots, a_m \geq 0$.

Proof: Checking Hessian

f

$$\nabla^2 f = a_1 \underbrace{\nabla^2 f_1}_{\text{Psd}} + a_2 \underbrace{\nabla^2 f_2}_{\text{Psd}} + \dots + a_m \underbrace{\nabla^2 f_m}_{\text{Psd}}$$

is Psd.

Consequence: $f(x) = x^2 + e^x$ is convex!

$f(x) = \frac{1}{2} x^T A x + b^T x + c$ is convex if A positive semi-definite!

Psd

Operations Preserving Convexity

If M is psd

Then $A^T M A$ is still psd

Affine composition:

Suppose $h: \mathbb{R}^m \rightarrow \mathbb{R}$ is convex, then $f(x) = h(Ax + b)$ is convex where $A \in \mathbb{R}^{m \times n}, b \in \mathbb{R}^m$.

$$\begin{array}{ccccc} & mxn & & m \times 1 & \\ x & \xrightarrow{n-d} & Ax+b & \xrightarrow{m-d} & h \\ & & & & \xrightarrow{1-d} \\ & & & & f(x) = h(Ax+b) \end{array}$$

Proof $m = n = 1$ $A \in a$
 $b \in b$

$$f(x) = h(ax+b)$$

$$f'(x) = \underline{h'(ax+b) \cdot a}$$

$$f''(x) = \underbrace{h''(ax+b) \cdot a \cdot a}_{\geq 0} \geq 0$$

Because h convex

$$f(x) = h(Ax+b)$$

$$\nabla f(x) = A^T \nabla h(Ax+b)$$

$$\nabla^2 f(x) = A^T \nabla^2 h(Ax+b) \cdot A$$

psd
psd.

Operations Preserving Convexity

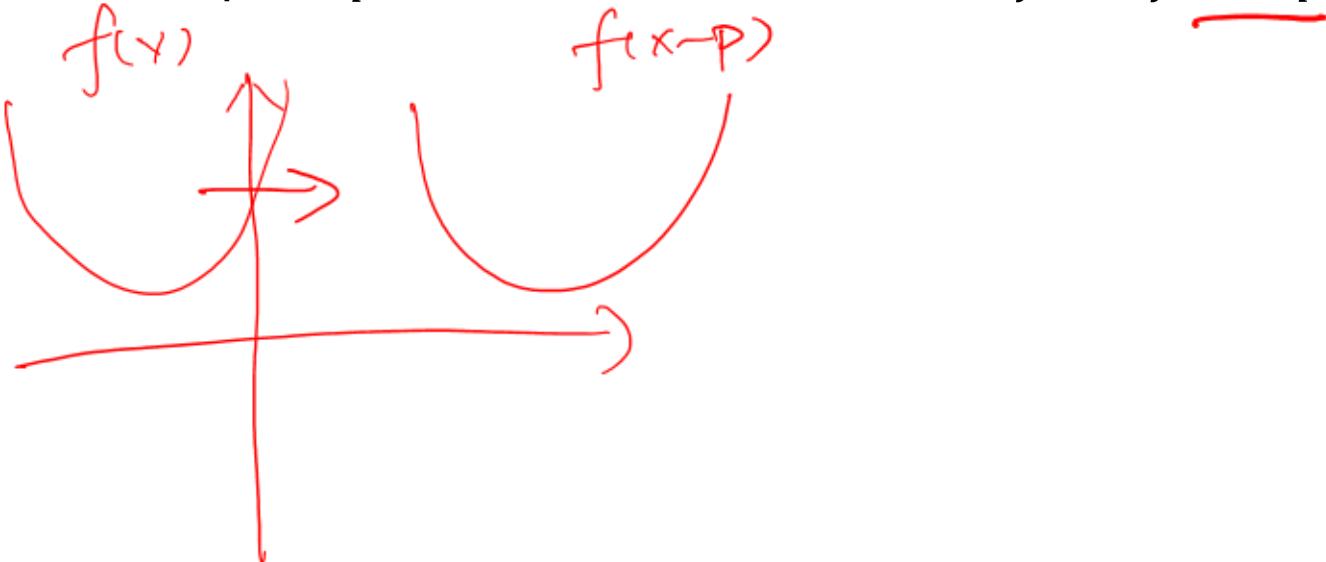
Affine composition:

Suppose $h: \mathbb{R}^m \rightarrow \mathbb{R}$ is convex, then $f(x) = h(Ax + b)$ is convex where $A \in \mathbb{R}^{n \times m}, b \in \mathbb{R}^n$.

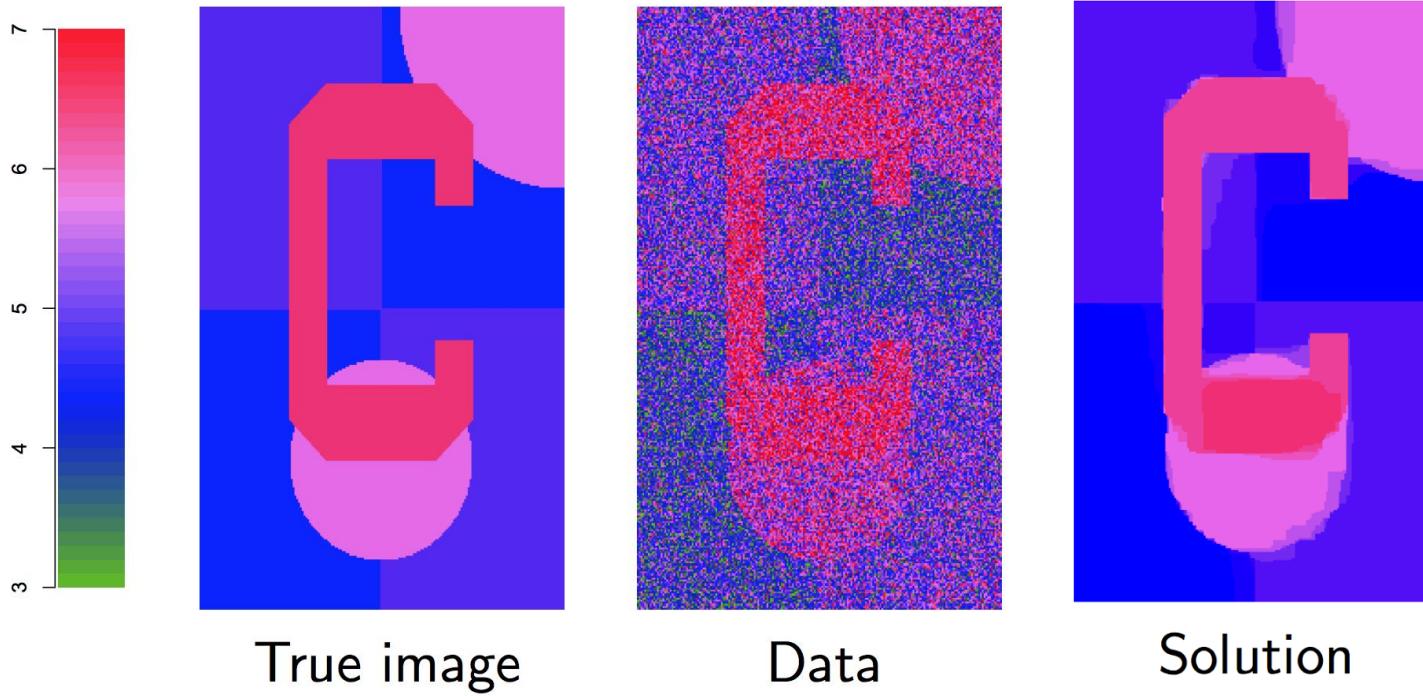
Consequence

$$A=I \quad b=-P$$

- Given point $p \in \mathbb{R}^n$ and convex function $f(x)$, $f(x - p)$ is convex.



Revisit: Denoising



$$\min_{\theta_1, \dots, \theta_n} \frac{1}{2} \sum_{i=1}^n (y_i - \theta_i)^2 + \lambda \sum_{(i,j) \text{ adjacent}} |\theta_i - \theta_j|$$

θ_i stays close to y_i penalize changes in adjacent pixels

Revisit: Denoising

$$[\nabla^2 g(\theta)]_{l,k} \stackrel{?}{=} 0 \text{ if } l,k=i$$

$$\min_{\theta_1, \dots, \theta_n} \frac{1}{2} \sum_{i=1}^n (y_i - \theta_i)^2 + \lambda \sum_{(i,j) \text{ adjacent}} |\theta_i - \theta_j|$$

Show that this is a convex function:

$$g(\theta) = (y_i - \theta_i)^2 = \underbrace{\theta_i^2}_{\text{Convex}} - 2y_i \theta_i + y_i^2$$

affine in θ_i convex

$$\rightarrow |\theta_i - \theta_j| = \left\| \begin{bmatrix} 1 & -1 \end{bmatrix} \begin{bmatrix} \theta_i \\ \theta_j \end{bmatrix} \right\|_1 = \underbrace{\left\| \begin{bmatrix} 1 & -1 \end{bmatrix} \begin{bmatrix} \theta_i \\ \theta_j \end{bmatrix} \right\|_1}_{\theta_i - \theta_j} = \underbrace{\sum_j h(|\theta_i - \theta_j|)}_{\text{convex}} \Rightarrow \text{convex}$$

$h(x) = |x|$ affine transformation

Operations Preserving Convexity

General composition:

Suppose $f(x) = h(g(x))$, where $\underline{g : \mathbb{R}^n \rightarrow \mathbb{R}}$, $\underline{h : \mathbb{R} \rightarrow \mathbb{R}}$, $\underline{f : \mathbb{R}^n \rightarrow \mathbb{R}}$. Then when

- $\underline{g \text{ is convex}}$
- $\underline{h \text{ is nondecreasing and convex}}$

$$h' \geq 0$$

Then $f(x) = h(g(x))$ is convex.

Example: why the “nondecreasing” condition is necessary

$$g(x) = x^2 \text{ convex}$$

$$h(y) = -y \text{ convex decreasing}$$

$$h(g(x)) = -x^2 \text{ NOT convex}$$

Operations Preserving Convexity

General composition:

Suppose $f(x) = h(g(x))$, where $g : \mathbb{R}^n \rightarrow \mathbb{R}$, $h : \mathbb{R} \rightarrow \mathbb{R}$, $f : \mathbb{R}^n \rightarrow \mathbb{R}$. Then when

- g is convex
- h is nondecreasing and convex

Then $f(x) = h(g(x))$ is convex.

Example: logistic regression $f(x) = -\log \frac{1}{1+e^{a^\top x}}$

Operations Preserving Convexity

General composition:

Suppose $f(x) = h(g(x))$, where $g : \mathbb{R}^n \rightarrow \mathbb{R}$, $h : \mathbb{R} \rightarrow \mathbb{R}$, $f : \mathbb{R}^n \rightarrow \mathbb{R}$. Then when

- g is convex
- h is nondecreasing and convex

Then $f(x) = h(g(x))$ is convex.

Proof: $x \text{ l-d}$:

$$f'(x) = h'(g(x)) \cdot g'(x)$$

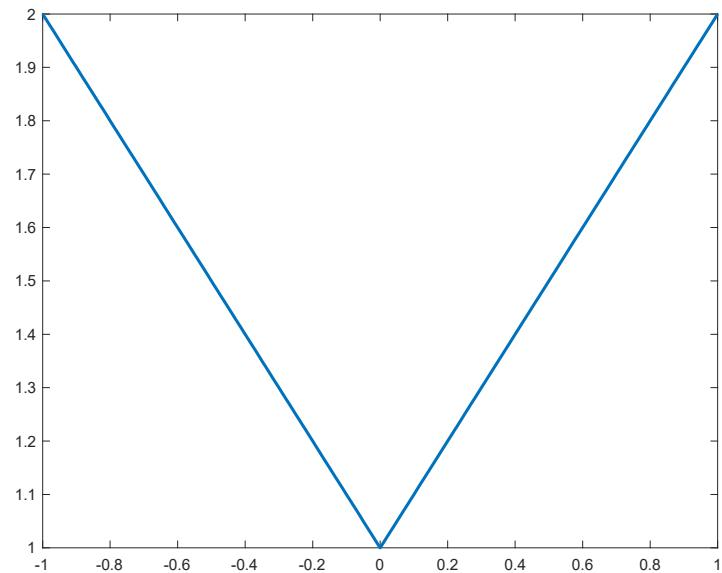
$$\begin{aligned} f''(x) &= [h(g(x))]' g'(x) + h'(g(x)) [g'(x)]' \\ &= \underbrace{h''(g(x))}_{\geq 0} \underbrace{g'(x) \cdot g'(x)}_{\geq 0} + \underbrace{h'(g(x)) \underbrace{g''(x)}_{\geq 0}}_{\geq 0} \geq 0 \end{aligned} \quad \begin{matrix} \text{non-decreasing} \\ \text{of } h \end{matrix}$$

Operations Preserving Convexity

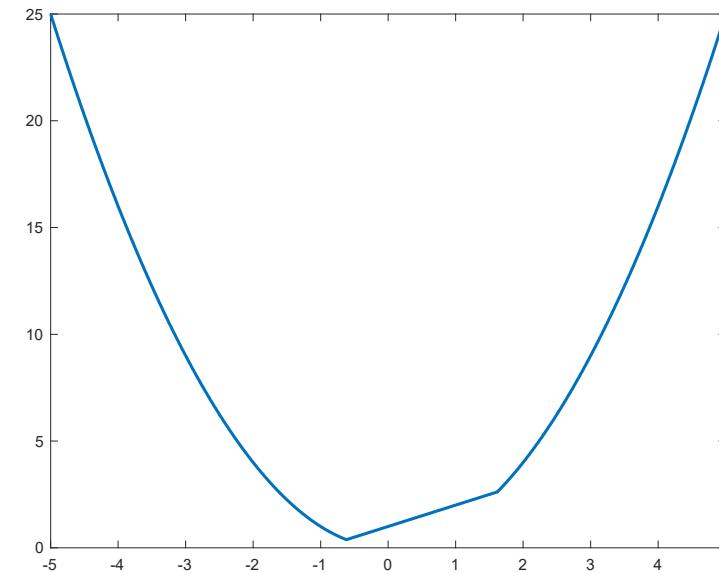
Pointwise maximization:

If f_1, f_2, \dots, f_m is convex, then $f(x) = \max(f_1(x), \dots, f_m(x))$ is convex.

$$f(x) = \max(x + 1, -x + 1)$$



$$f(x) = \max(x + 1, x^2)$$



Operations Preserving Convexity

Pointwise maximization:

If f_1, f_2, \dots, f_m is convex, then $f(x) = \max(f_1(x), \dots, f_m(x))$ is convex.

Proof: we use definition. Given $t \in [0,1]$ and x, y ,

Operations Preserving Convexity

Pointwise maximization:

If f_i is convex for all $i \in I$ where I may be an infinite set, then

$$f(x) = \max_{i \in I} f_i(x)$$

is convex.

Proof: identical

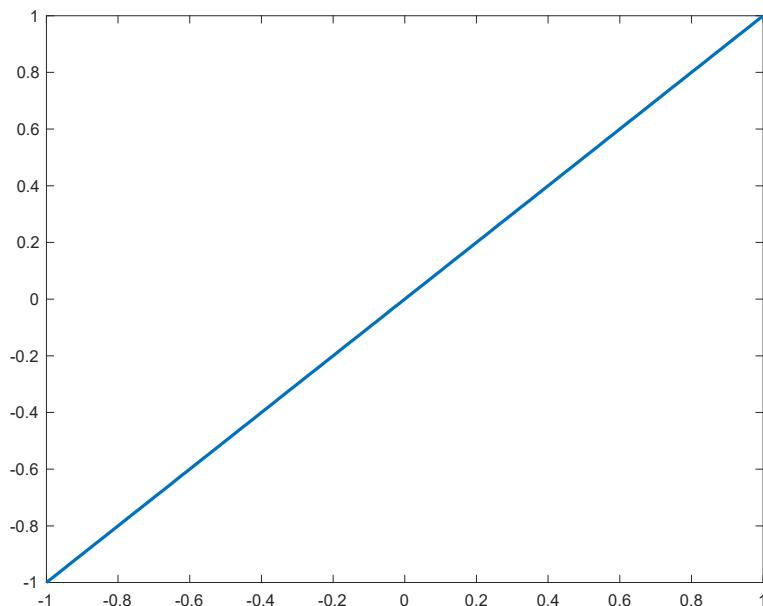
Summary: Operations Preserving Convexity

- Nonnegative linear combination
- Compositions
- Pointwise maximization

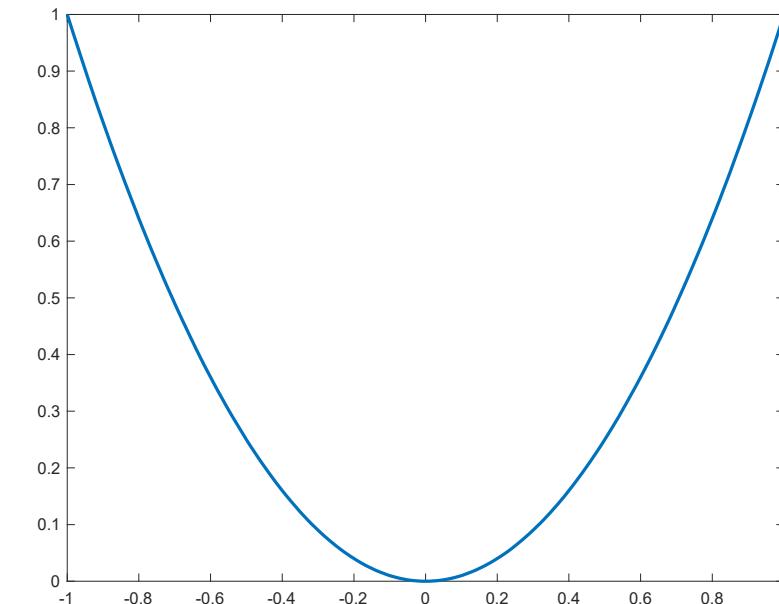
Next: strict convexity, strong convexity, smoothness

Strict Convexity and Strong Convexity

Both these functions are convex, but they look different



An affine function



A quadratic function

Strict Convexity

Definition. A function $f(x)$ is strictly convex if for any $x \neq y$, $t \in (0,1)$

$$f(tx + (1 - t)y) < tf(x) + (1 - t)f(y).$$

Equivalent definition using first order condition:

$$f(y) > f(x) + \nabla f(x)^\top (y - x).$$

Equivalent definition using second order condition:

$$\nabla^2 f(y) > 0.$$

Strong Convexity

Definition. For $\mu > 0$, a function $f(x)$ is μ -strongly convex if $f(x) - \frac{\mu}{2} \|x\|^2$ is convex

Equivalent definition using first order condition: for any x, y

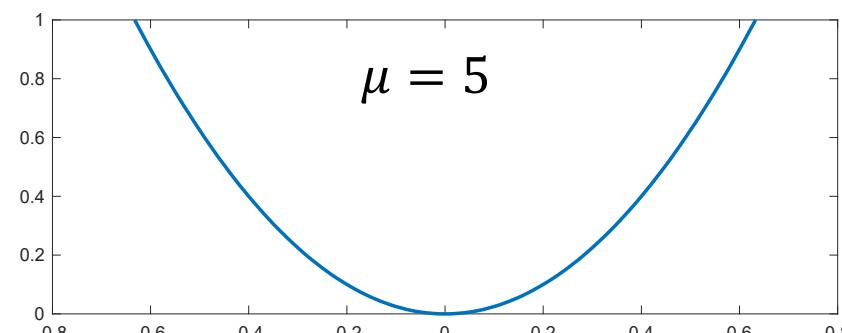
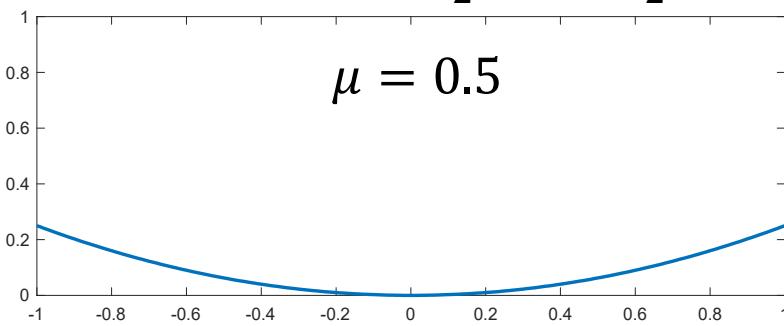
$$f(y) \geq f(x) + \nabla f(x)^T(y - x) + \frac{\mu}{2} \|y - x\|^2.$$

Equivalent definition using second order condition: for any x

$$\nabla^2 f(x) \succcurlyeq \mu I$$

How to understand strong convexity?

- Use quadratic function $\frac{\mu}{2} \|x\|^2 = \frac{\mu}{2} x^T x$ as a reference to tell how “curved” functions are



Strong Convexity

Definition. For $\mu > 0$, a function $f(x)$ is μ -strongly convex if $f(x) - \frac{\mu}{2} \|x\|^2$ is convex

Equivalent definition using first order condition: for any x, y

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Equivalent definition using second order condition: for any x

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How to understand strong convexity?

- Use quadratic function $\frac{\mu}{2} \|x\|^2 = \frac{\mu}{2} x^T x$ as a reference to tell how “curved” functions are
- Why choosing $\frac{\mu}{2} \|x\|^2$ as the reference? - its Hessian is μI , a simple matrix

More on Strong Convexity

Definition. For $\mu > 0$, a function $f(x)$ is μ -strongly convex if $f(x) - \frac{\mu}{2} \|x\|^2$ is convex

Equivalent definition using first order condition: for any x, y

$$f(y) \geq f(x) + \nabla f(x)^\top (y - x) + \frac{\mu}{2} \|y - x\|^2.$$

Equivalent definition using second order condition: for any x

$$\nabla^2 f(x) \succcurlyeq \mu I$$

Strong convexity of general quadratic functions $f(x) = \frac{1}{2} x^\top A x$

$$\nabla^2 f(x) = A \succcurlyeq \sigma_{min}(A) I$$

When A is positive definite (i.e. $\sigma_{min}(A) > 0$), $f(x) = \frac{1}{2} x^\top A x$ is $\sigma_{min}(A)$ -strongly convex

Comparison btw Strict/Strong convexity

strict convexity

$$\nabla^2 f(x) > 0, \forall x \in \text{dom}(f)$$

Example: $f(x) = \frac{1}{x}$ over $(0, +\infty)$

μ -strong convexity

$$\nabla^2 f(x) \geq \mu I, \forall x \in \text{dom}(f)$$

Example: $f(x) = \frac{1}{2}ax^2$ over \mathbb{R} , $a > 0$

Concavity

A function f is concave if $-f$ is convex

A function f is strictly concave if $-f$ is strictly convex

A function f is μ -strongly concave if $-f$ is μ -strongly convex

	Definition	First-order condition	Second-order condition
concave	$f(tx + (1 - t)y) \geq tf(x) + (1 - t)f(y), \forall x, y, \forall t \in [0,1]$	$f(y) \leq f(x) + \nabla f(x)^\top (y - x), \forall x, y$	$\nabla^2 f(x) \leq 0, \forall x$
convex	$f(tx + (1 - t)y) \leq tf(x) + (1 - t)f(y), \forall x, y, \forall t \in [0,1]$	$f(y) \geq f(x) + \nabla f(x)^\top (y - x), \forall x, y$	$\nabla^2 f(x) \geq 0, \forall x$
strictly concave	$f(tx + (1 - t)y) > tf(x) + (1 - t)f(y), \forall x \neq y, \forall t \in (0,1)$	$f(y) < f(x) + \nabla f(x)^\top (y - x), \forall x \neq y$	$\nabla^2 f(x) < 0, \forall x$
strictly convex	$f(tx + (1 - t)y) < tf(x) + (1 - t)f(y), \forall x \neq y, \forall t \in (0,1)$	$f(y) > f(x) + \nabla f(x)^\top (y - x), \forall x \neq y$	$\nabla^2 f(x) > 0, \forall x$
μ -strongly concave	$f(x) + \frac{\mu}{2} \ x\ ^2$ is concave	$f(y) \leq f(x) + \nabla f(x)^\top (y - x) - \frac{\mu}{2} \ y - x\ ^2, \forall x, y$	$\nabla^2 f(x) \leq -\mu I, \forall x$
μ -strongly convex	$f(x) - \frac{\mu}{2} \ x\ ^2$ is convex	$f(y) \geq f(x) + \nabla f(x)^\top (y - x) + \frac{\mu}{2} \ y - x\ ^2, \forall x, y$	$\nabla^2 f(x) \geq \mu I, \forall x$

Summary for Convex Functions

Typical functions and their convexity

- Affine, quadratic
- Simple univariate functions
- Norm functions

Ways to check convexity

- Definition
- First order and second order condition
- Operations that preserve convexity

Strict and strong convexity

Next: smoothness, convex constraint sets