

Bayesian Functional Mixed Model using Non-Linear Representations (Bayes-FMM-NL)

Edward Gunning, Giles Hooker and Jeffrey Morris

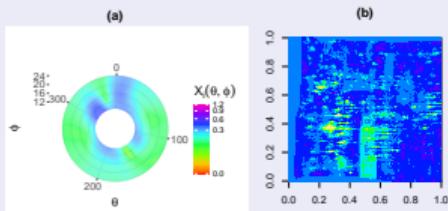
WIT meeting

September 2025

Functional Mixed Models (FMMs)

Functional Data

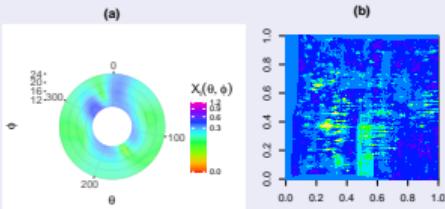
Figures/gait-data-plot.pdf



Functional Mixed Models (FMMs)

Functional Data

Figures/gait-data-plo



Regression Outcomes

Regress the objects on scalar (or functional) covariates.

$$\begin{array}{c} \overbrace{y(t)} \\ \vdots \\ \overbrace{\text{---}} \\ \overbrace{\text{---}} \end{array} = \begin{array}{c} \overbrace{X} \\ \vdots \\ \overbrace{\text{---}} \\ \overbrace{\text{---}} \end{array} \begin{array}{c} \overbrace{\beta(t)} \\ \vdots \\ \overbrace{\text{---}} \\ \overbrace{\text{---}} \end{array} + \begin{array}{c} \overbrace{\varepsilon(t)} \\ \vdots \\ \overbrace{\text{---}} \\ \overbrace{\text{---}} \end{array}$$

$x_{11}=t$ $x_{1N}=\theta$

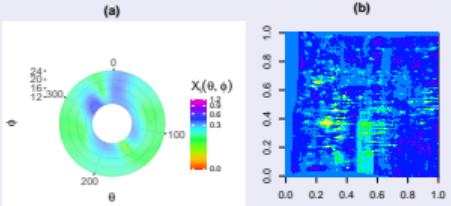
$\beta_0(t)$ $\beta_1(t)$

→ inference, prediction
(and data generation!).

Functional Mixed Models (FMMs)

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Figures/gait-data-plo



Regression Outcomes

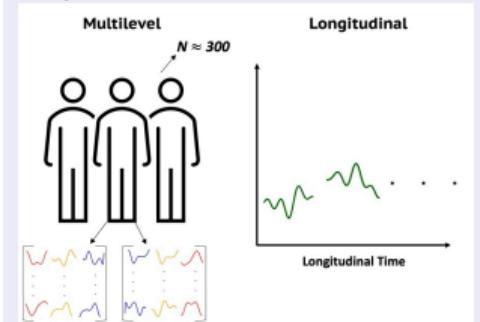
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Dependence Structures

Account for multilevel, longitudinal, spatial, etc. dependence.



Functional Mixed Model

Functional Mixed Model:

$$\mathbf{Y}(t) = \mathbf{XB}(t) + \mathbf{ZU}(t) + \mathbf{E}(t)$$

often measured on grid $\mathbf{t} = (0 = t_1, t_2, \dots, t_D = T)$.

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$$\mathbf{Y}_{\cdot, t_j} = \mathbf{X}\mathbf{B}_{\cdot, t_j} + \mathbf{Z}\mathbf{U}_{\cdot, t_j} + \mathbf{E}_{\cdot, t_j}, \quad j = 1, \dots, D,$$

and post-smooth the pointwise estimates to construct smooth $\widehat{\mathbf{B}}(t)$.

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- Scheipl, Staicu, and Greven (2015) and Guo (2002): Basis approximations $\beta_a(t) \approx \sum_k \beta_{ak}^* \phi_k^B(t)$ and $\mathbf{u}_i(t) \approx \sum_k u_{ik}^* \phi_k^U(t)$, so that:

$$\text{vec}(\mathbf{Y}(\mathbf{t})) = \boldsymbol{\Phi}^X \boldsymbol{\beta}^* + \boldsymbol{\Phi}^U \mathbf{u}^* + \boldsymbol{\varepsilon},$$

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- Morris and Carroll (2006): Near-lossless basis representation for the $\mathbf{Y}(t) \approx \mathbf{Y}^* \boldsymbol{\Phi}(t)$ and all other terms, then model the basis coefficients \mathbf{Y}^* using a multivariate Bayesian mixed model.

Bayesian Functional Mixed Model

BayesFMM modeling framework (Morris and Carroll, 2006; Morris, Baladandayuthapani, et al., 2011; Morris, 2017):

$\mathbf{Y}(\mathbf{t})$

	$Y(t_1)$	$Y(t_2)$...	$Y(t_T)$
	-4.33	-5.26	...	-4.11

	-3.95	-5.96	...	-2.12

N

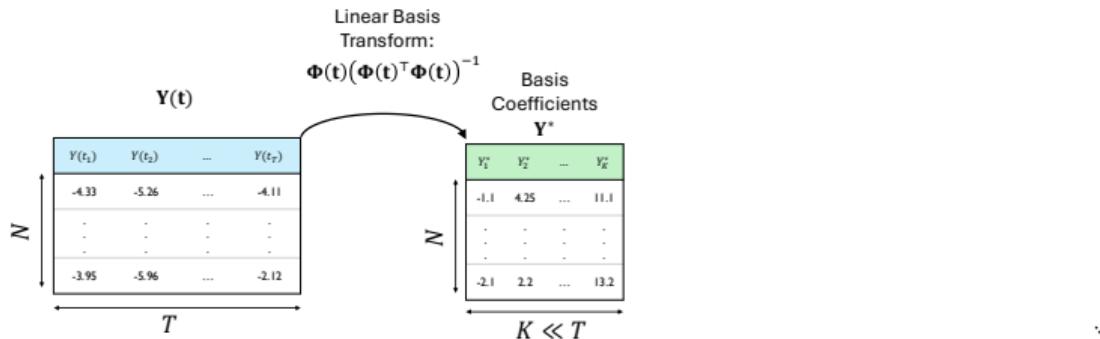
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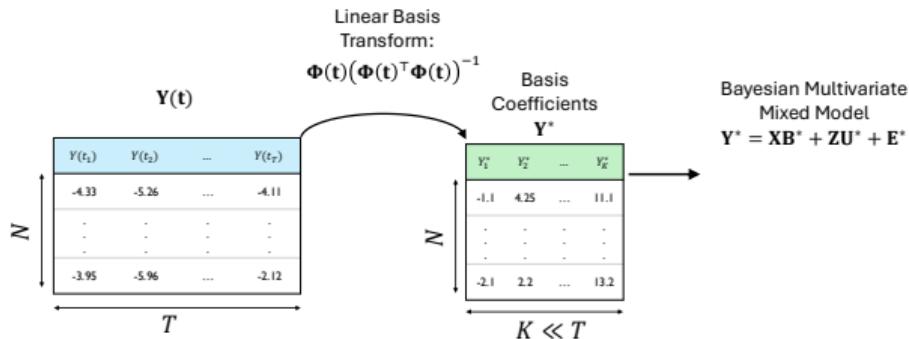
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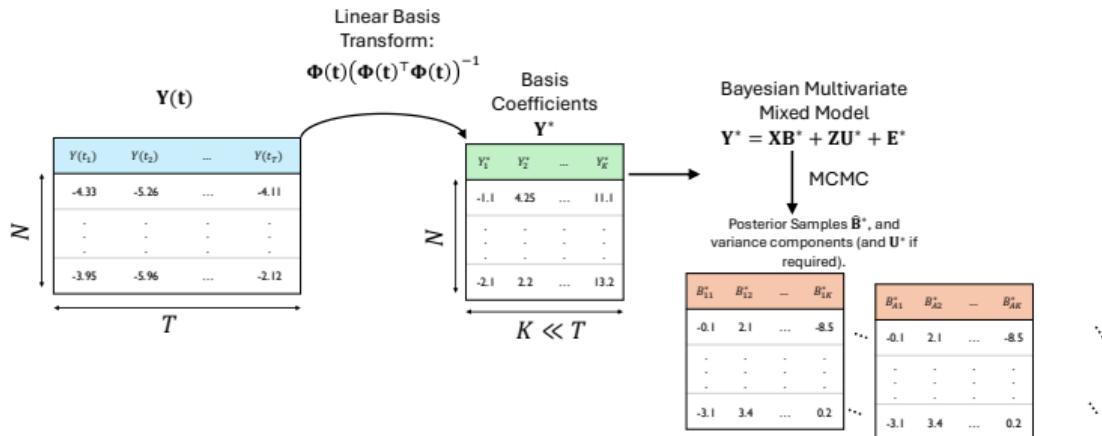
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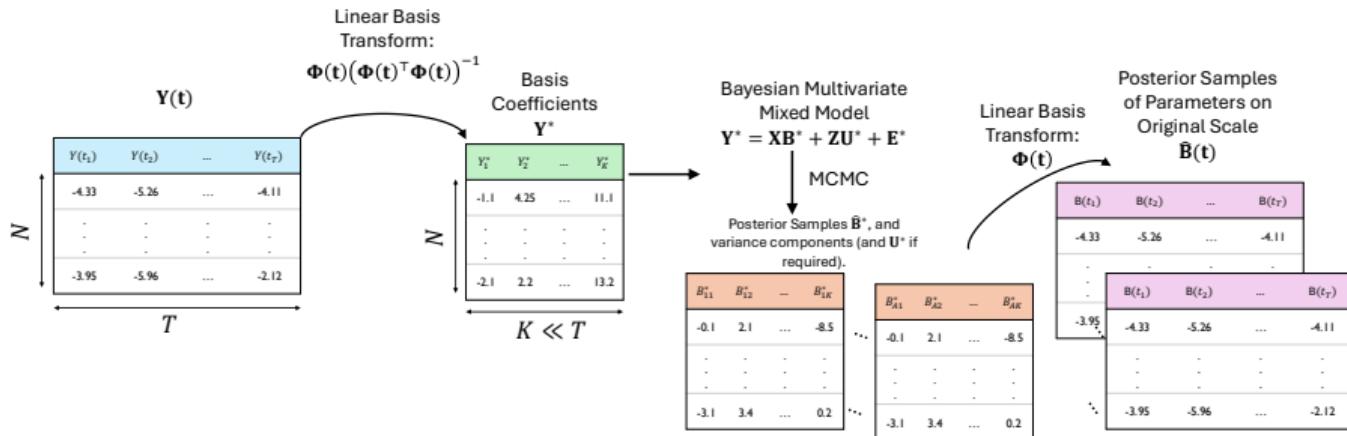
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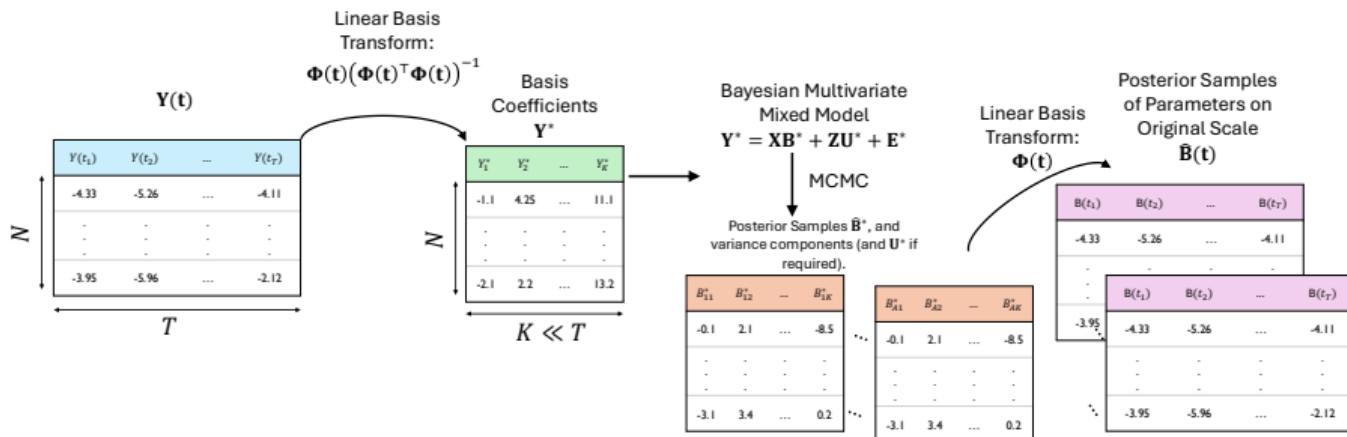
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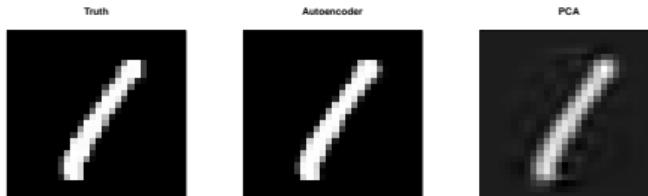
with different bases $\{\phi_k(t)\}_{k=1}^K$ for different data types. E.g., wavelets, FPCs.

Bayesian Functional Mixed Model

Linear basis representations may not provide the most compact or efficient representation (see, e.g., Zohner et al., 2025):

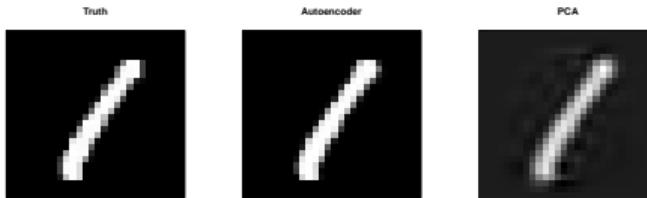
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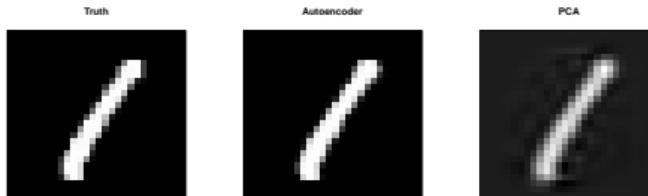
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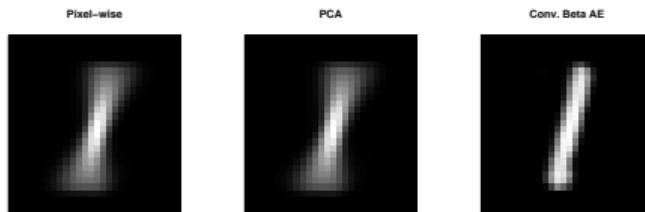
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Bayes-FMM-NL

Embed general, potentially **non-linear** encoding $f(\cdot)$ and decoding $g(\cdot)$ transformations into the BayesFMM framework:

$\mathbf{Y(t)}$

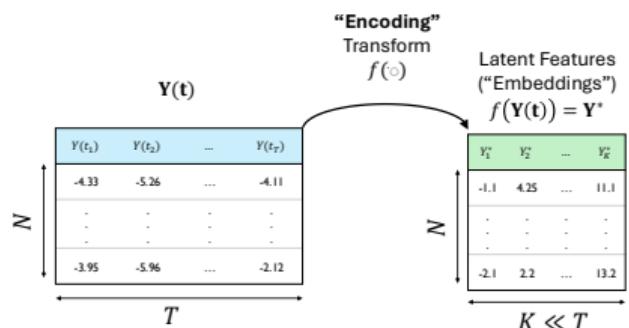
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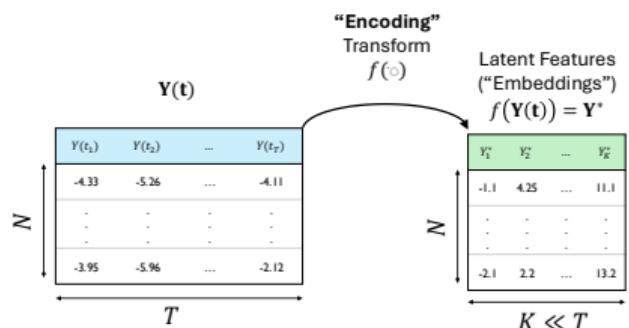
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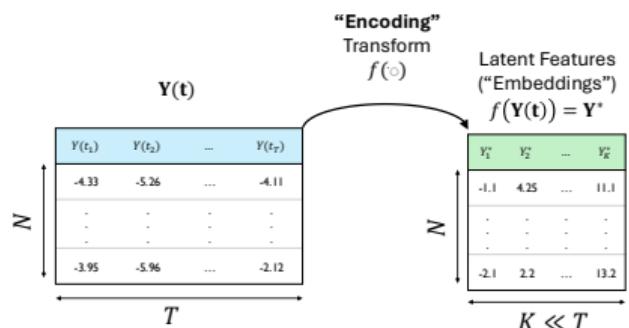
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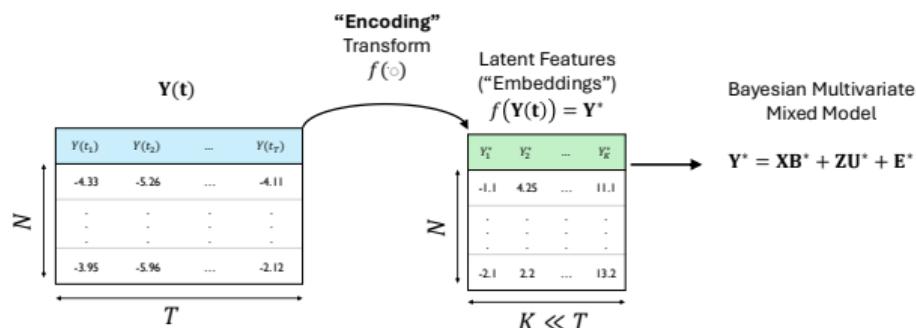
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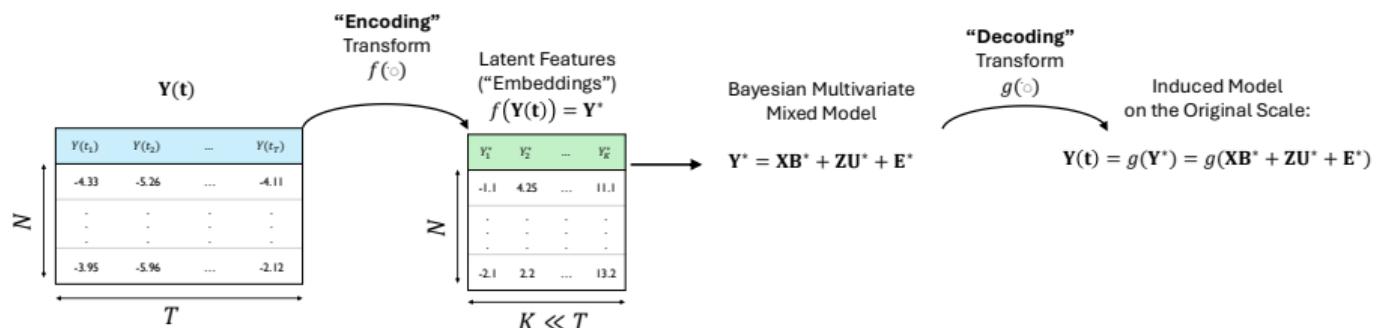
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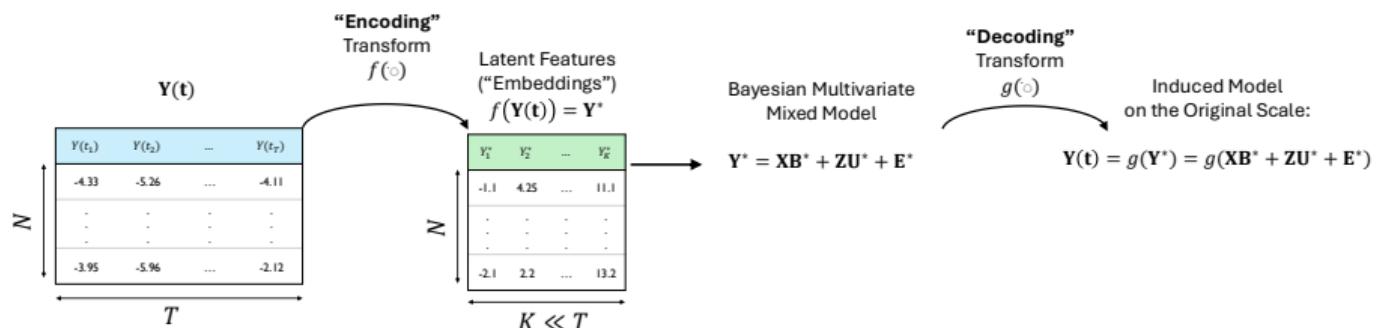
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→ We will demonstrate our methodology in an application to the MNIST digits dataset.

Example: MNIST Digits Data

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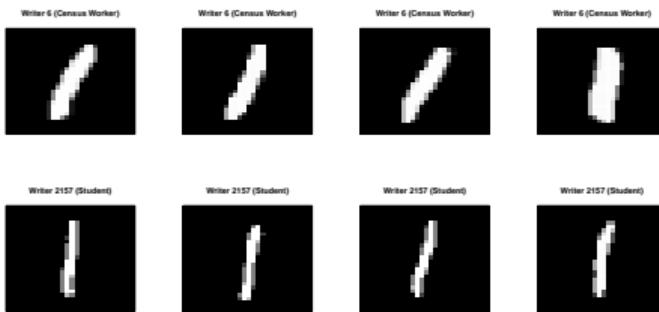
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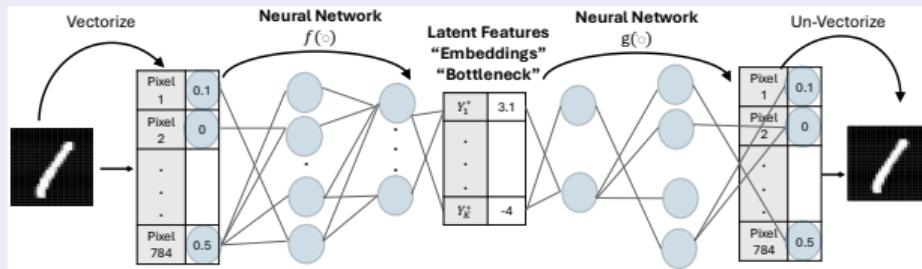


Goal

Regress the 28×28 images on group labels (census vs high-school) while accounting for the multilevel data structure.

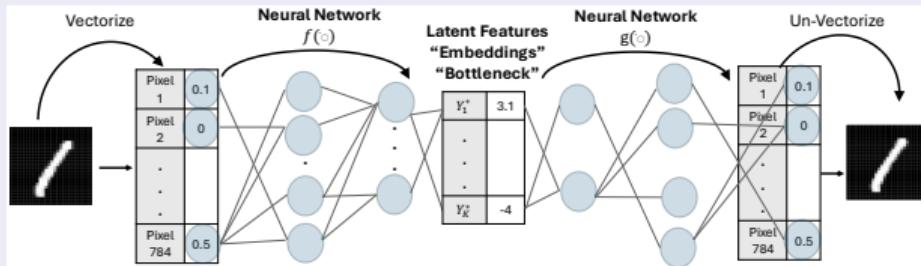
Transformation

Autoencoder

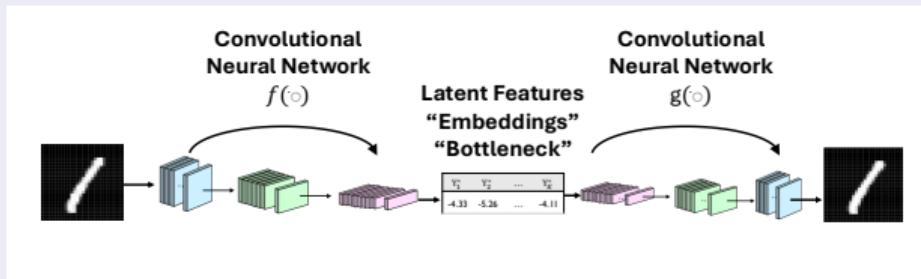


Transformation

Autoencoder



Convolutional Autoencoder



Transformation

Attain reconstruction error < 0.05 for 95th percentile (nearly worst case!):

Figures/compactness-near-losslessness_early_stopping_d

What about the underlying geometry

→ Latent model assumes $\mathbf{Y}^* = \mathbf{X}\mathbf{B}^* + \mathbf{Z}\mathbf{U}^* + \mathbf{E}^*$, with \mathbf{U}^* and \mathbf{E}^* multivariate Gaussian.

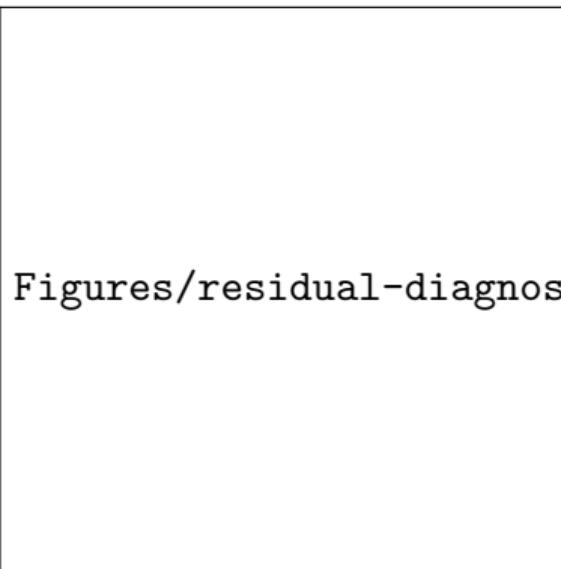
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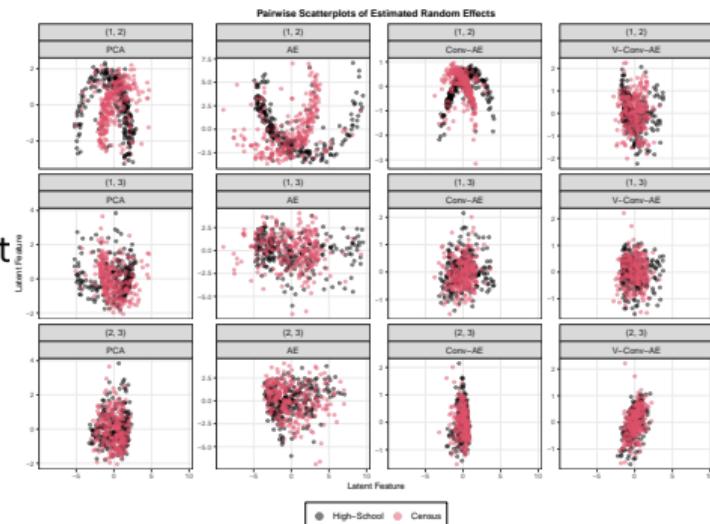
Figures/residual-diagnostics.pdf

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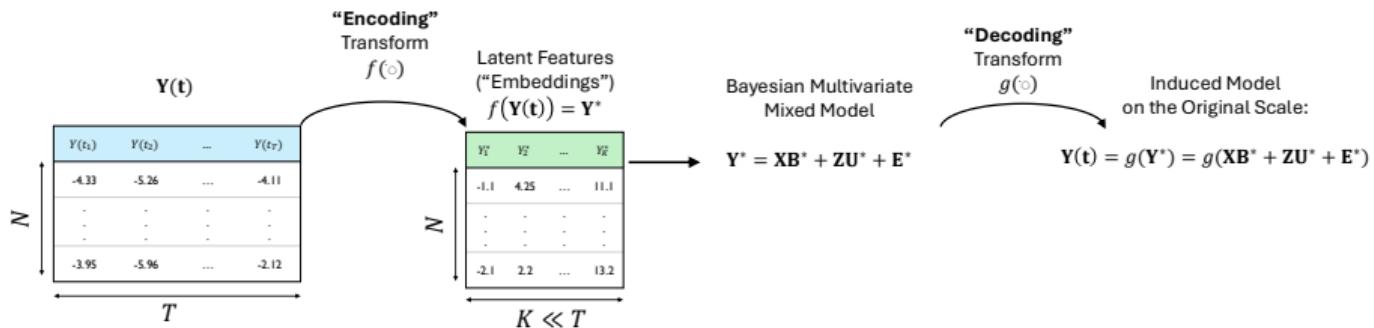
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→ Choose **Variational** Convolutional AE (V-Conv-AE) to enforce regularity of latent space!

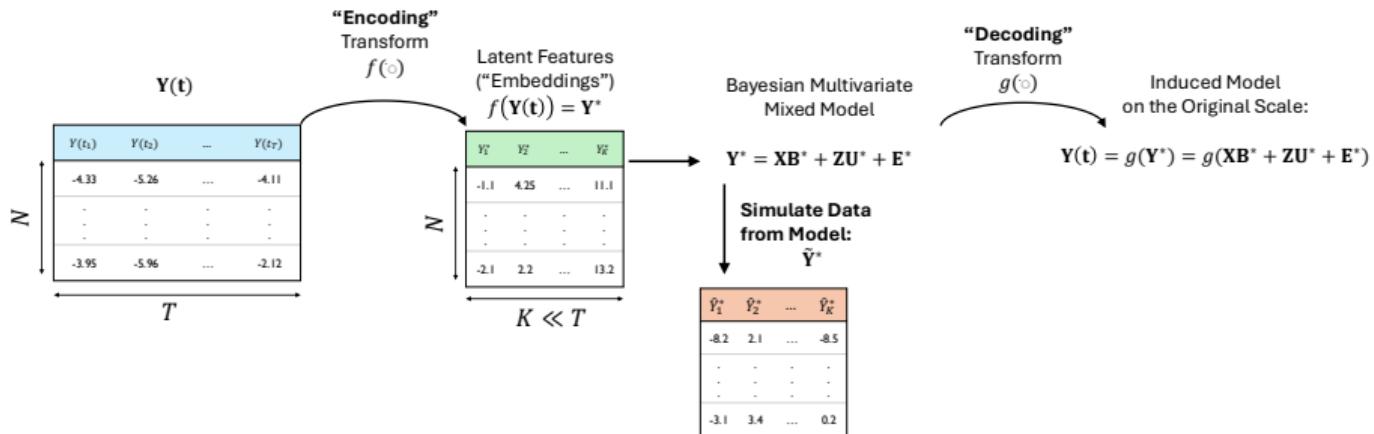
Data-Generative Properties

If encoding and decoding transformations preserve the objects' inherent structure and our latent model is appropriate, then simulations from the model should capture key features of the observed data.



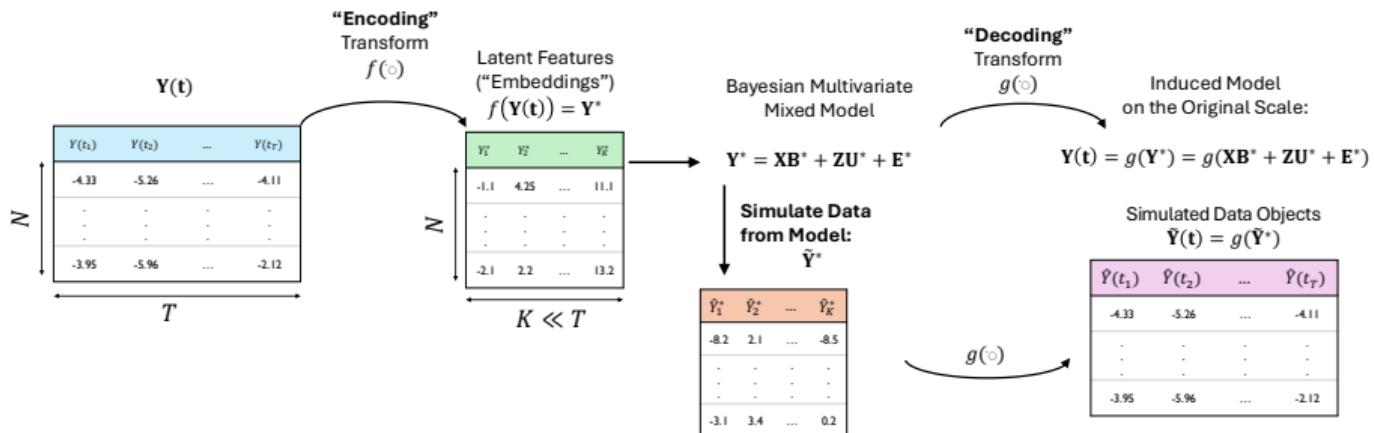
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Bayesian approach allows uncertainty in parameter estimates to be propagated through to the generated data.

Simulated Data

Simulated New Digits from an Existing Census Writer

Simulated Observation 1
V-Conv-AE



Simulated Observation 2
V-Conv-AE



Simulated Observation 3
V-Conv-AE



Simulated Observation 4
V-Conv-AE



Simulated Observation 5
V-Conv-AE



Simulated Observation 1
PCA



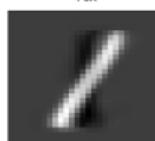
Simulated Observation 2
PCA



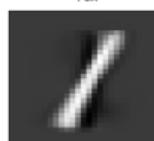
Simulated Observation 3
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Simulated Observation 5
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Real Observation 1



Real Observation 2



Real Observation 3



Real Observation 4

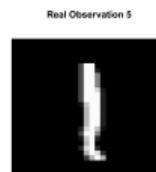
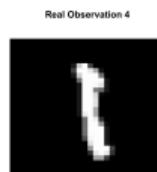
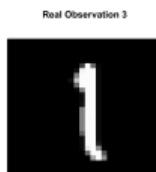
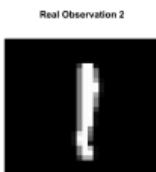
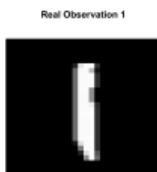
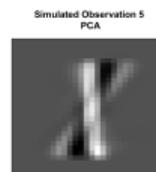
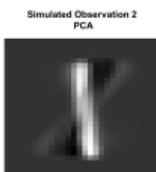
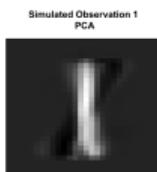
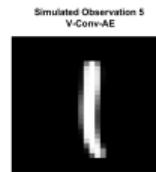
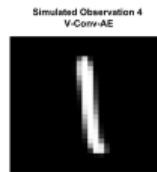
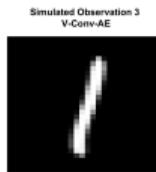
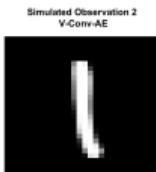
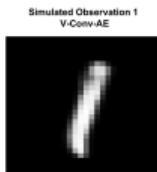


Real Observation 5



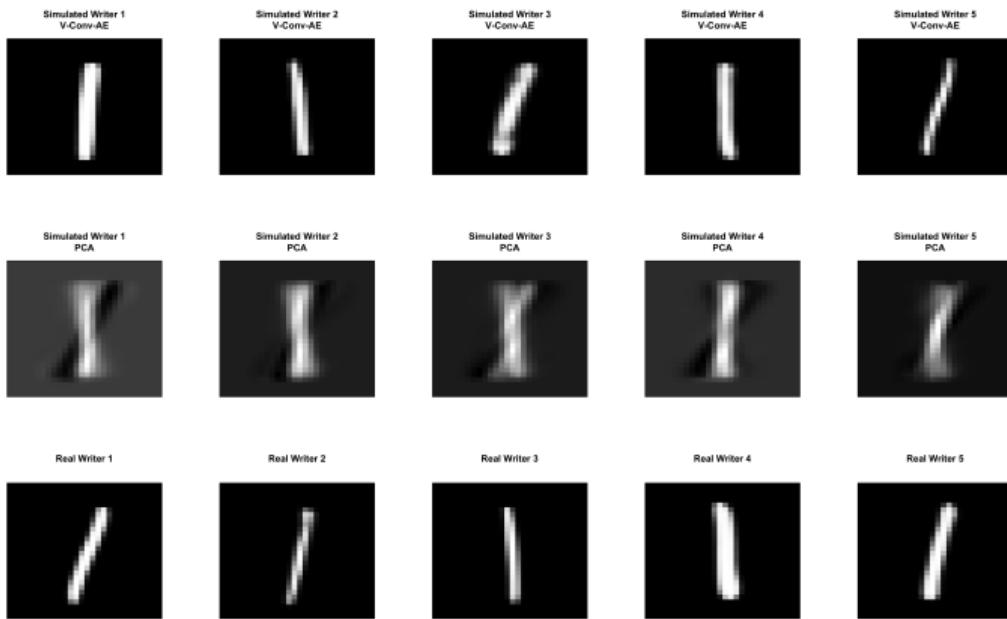
Simulated Data

Simulated New Digits from an Existing High-School Writer



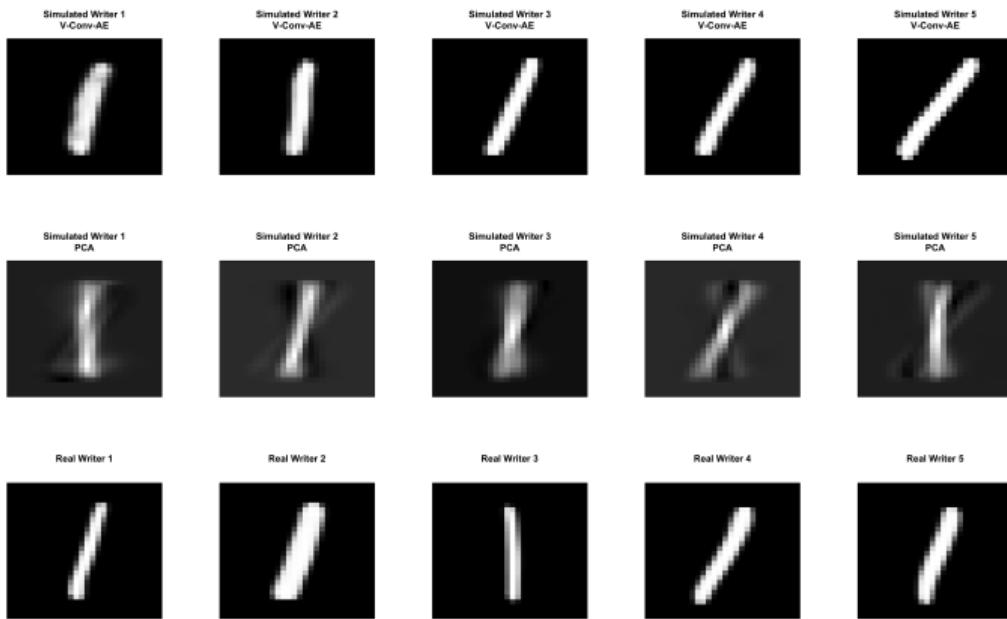
Simulated Data

Typical Digits from New Simulated High-School Writers



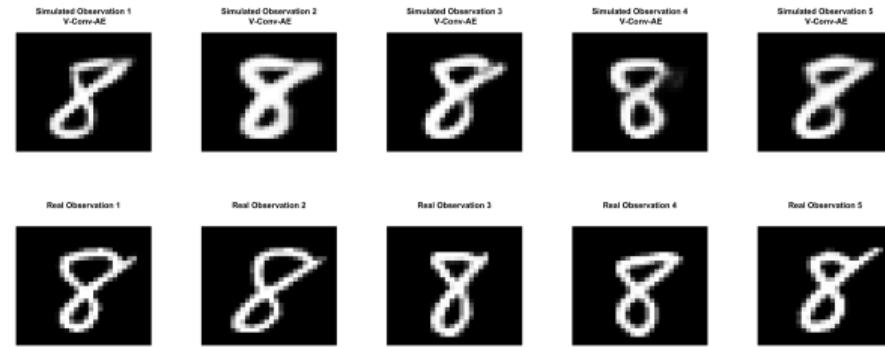
Simulated Data

Typical Digits from New Simulated Census Writers



Simulated Data

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Real Observation 1 Real Observation 2 Real Observation 3 Real Observation 4 Real Observation 5



Simulated New Digits from an Existing High-School Writer

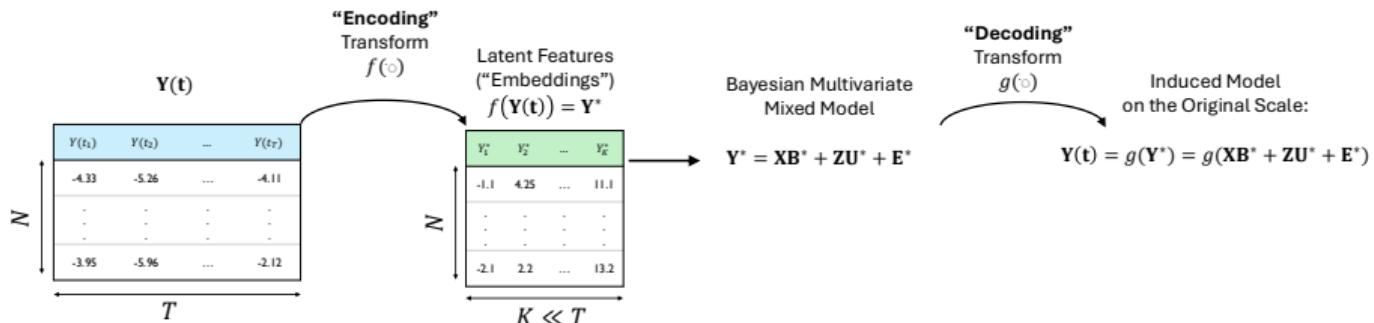


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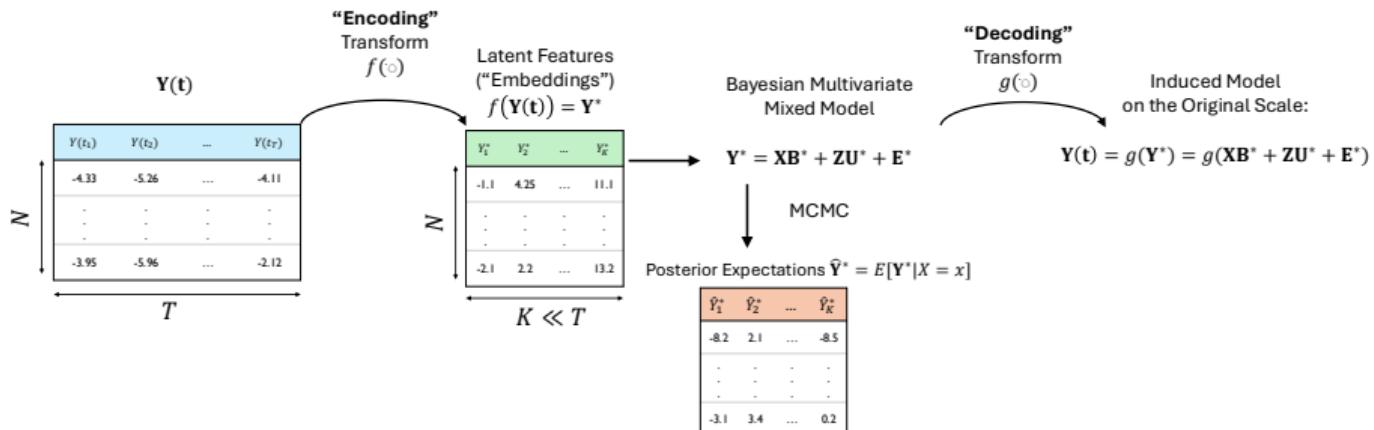
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Since in general $\mathbb{E}[g(\mathbf{Y}^*)] \neq g(\mathbb{E}[\mathbf{Y}^*])$, we need to think carefully about inference and interpretation:



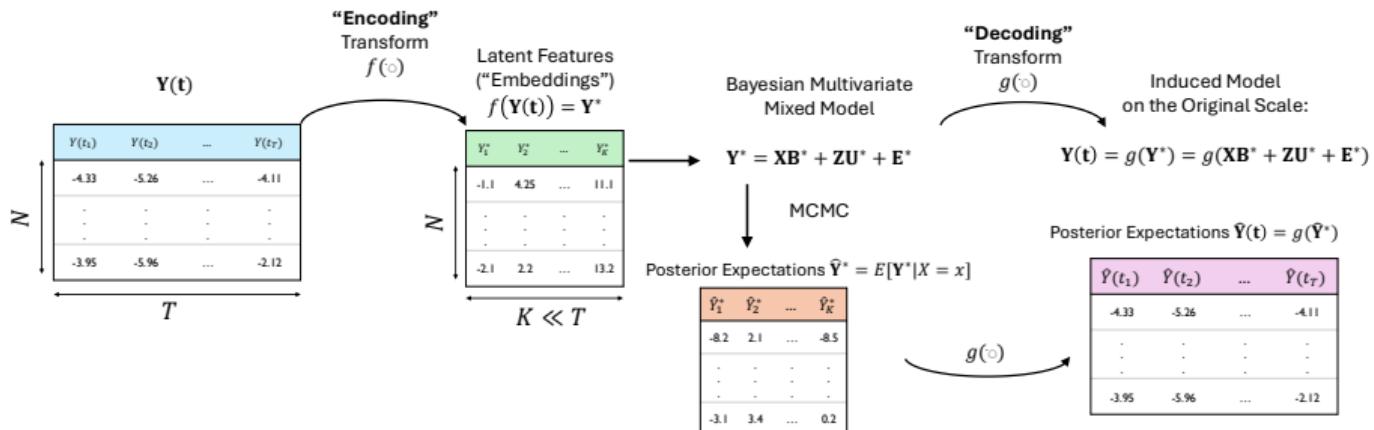
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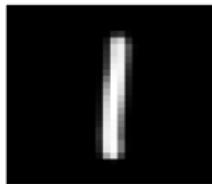
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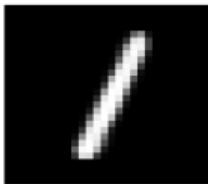


Estimates

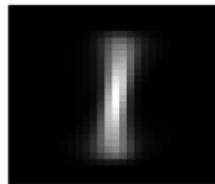
(a) High-School (V-Conv-AE)



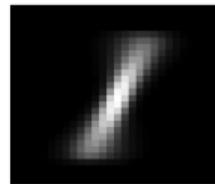
(b) Census Worker (V-Conv-AE)



(c) High-School (PCA)

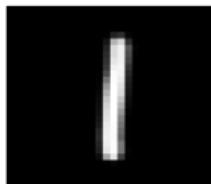


(d) Census Worker (PCA)

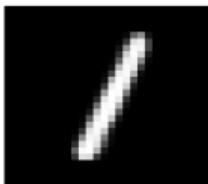


Estimates

(a) High-School (V-Conv-AE)



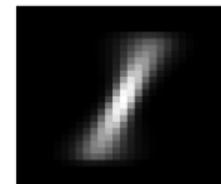
(b) Census Worker (V-Conv-AE)



(c) High-School (PCA)



(d) Census Worker (PCA)



(a) High-School (V-Conv-AE)



(b) Census Worker (V-Conv-AE)



Estimates

(a) High-School (V-Conv-AE)



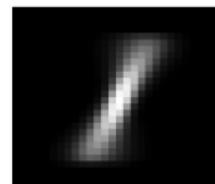
(b) Census Worker (V-Conv-AE)



(c) High-School (PCA)



(d) Census Worker (PCA)



(a) High-School (V-Conv-AE)



(b) Census Worker (V-Conv-AE)



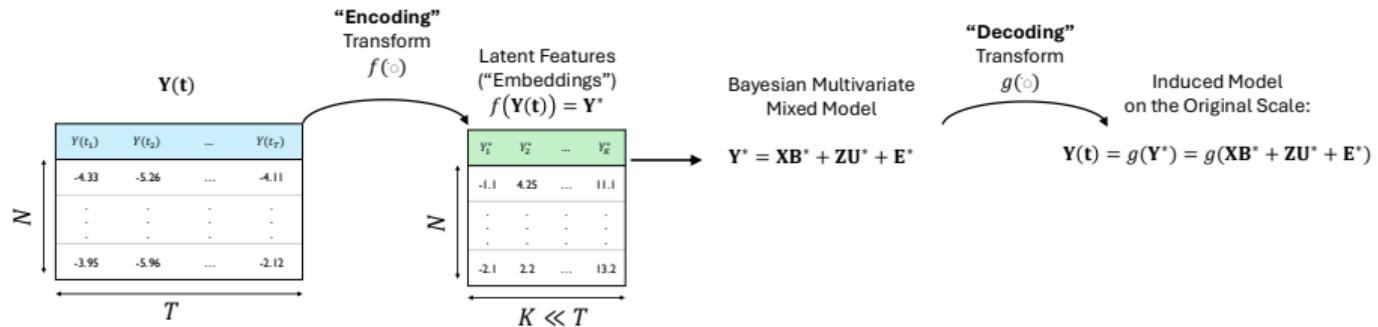
(a) High-School (V-Conv-AE)



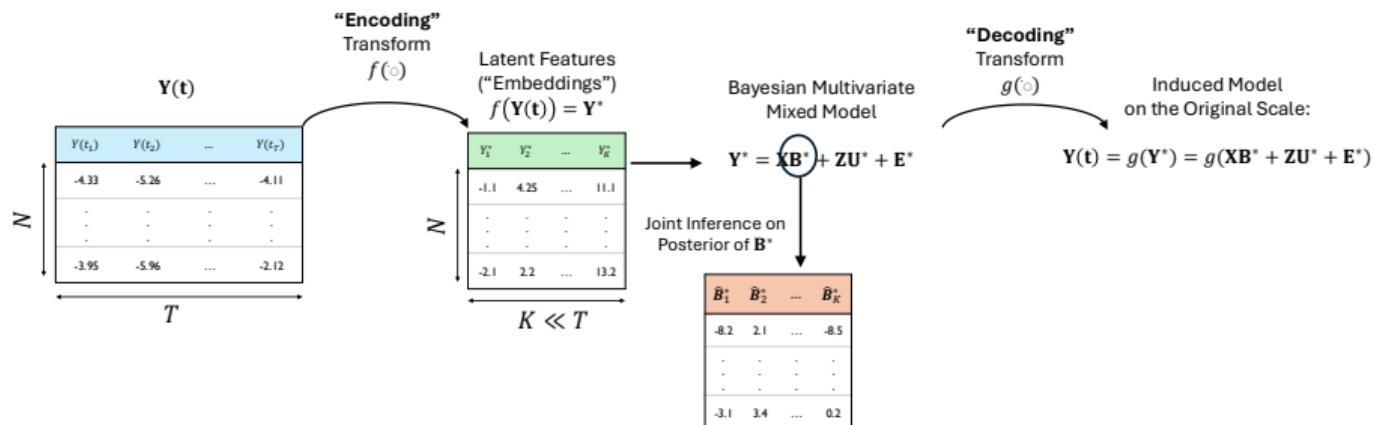
(b) Census Worker (V-Conv-AE)



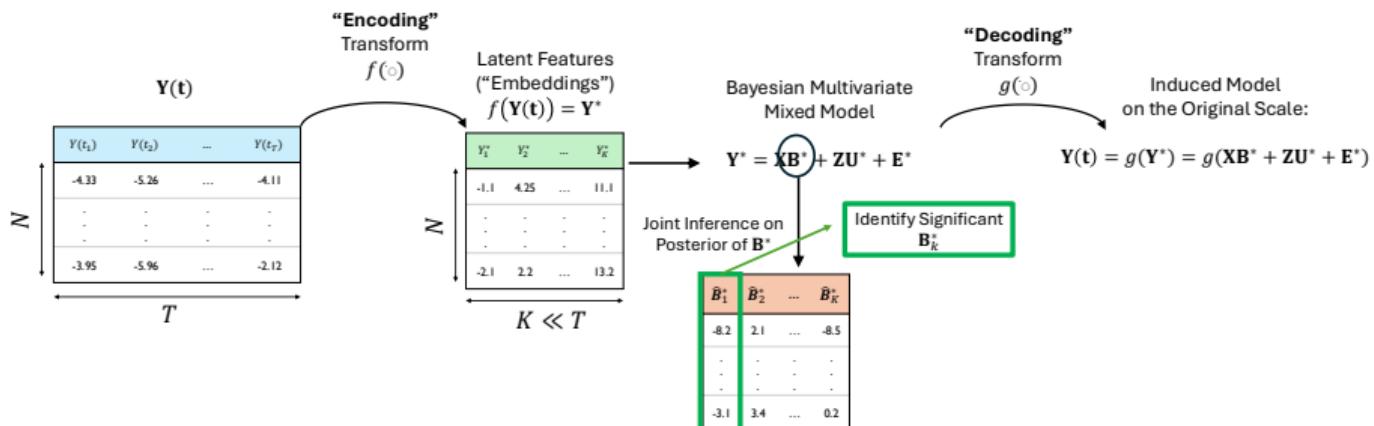
Inference



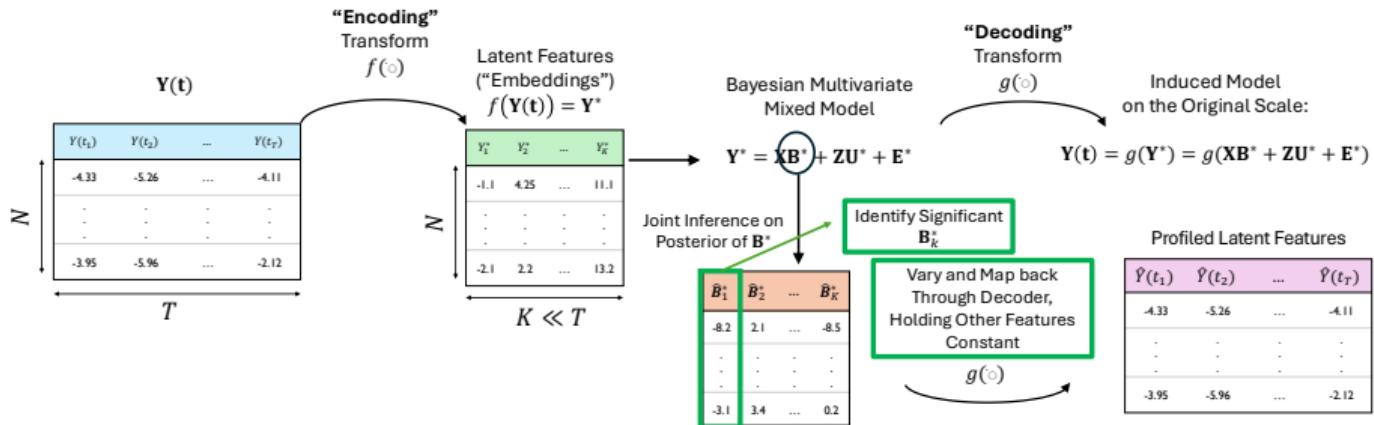
Inference



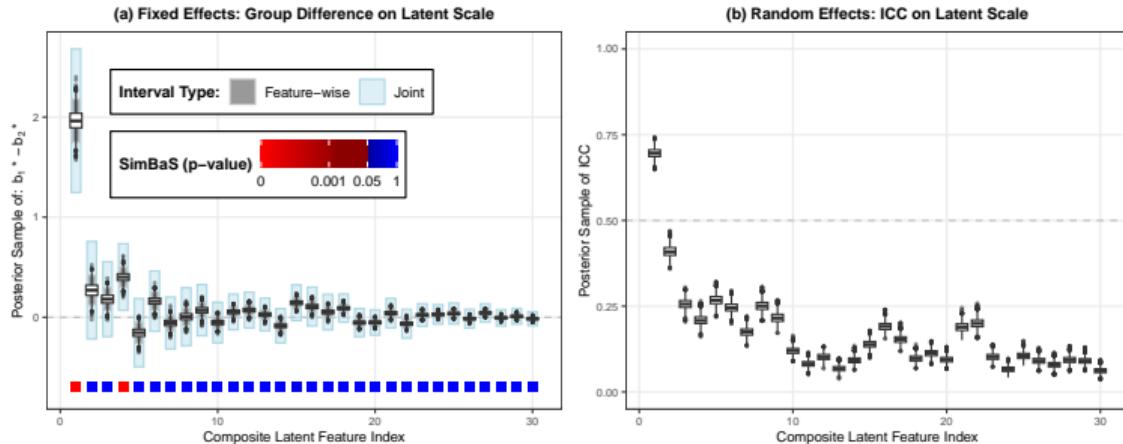
Inference



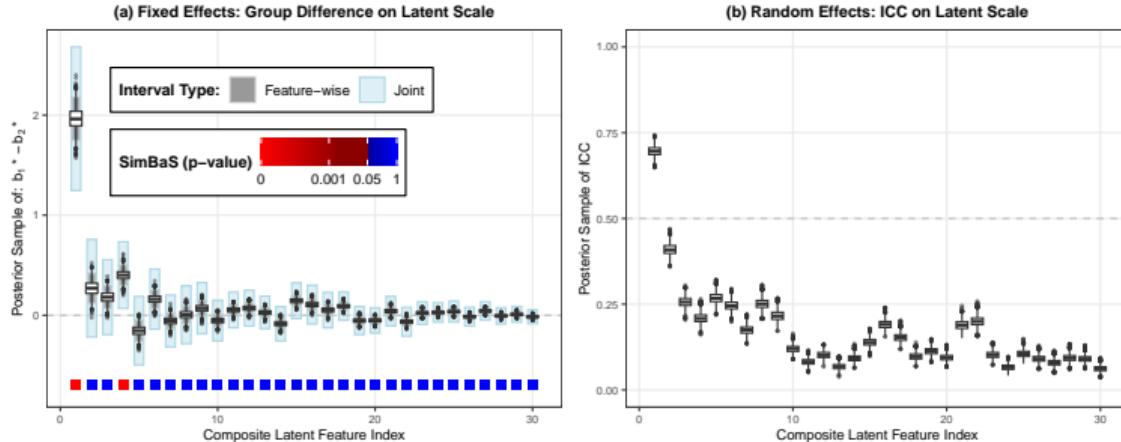
Inference



Inference

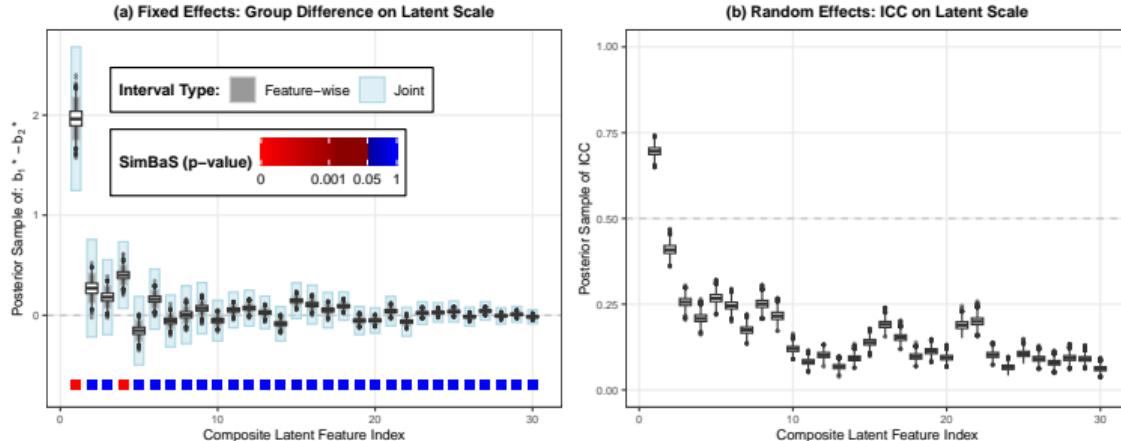


Inference



→ Identify Feature 1 as a driver of **between-group** differences.

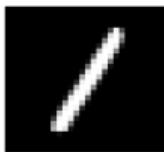
Inference



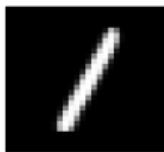
- Identify Feature 1 as a driver of **between-group** differences.
- Higher-order features important for **between-subject** variation.

Inference

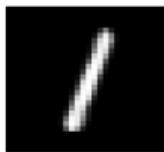
Typical Digit, y_1 , Quantile = 0.05



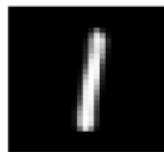
Typical Digit, y_1 , Quantile = 0.23



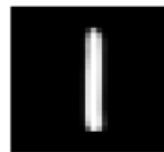
Typical Digit, y_1 , Quantile = 0.41



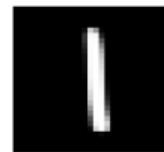
Typical Digit, y_1 , Quantile = 0.59



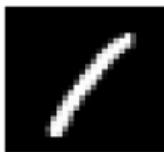
Typical Digit, y_1 , Quantile = 0.77



Typical Digit, y_1 , Quantile = 0.95



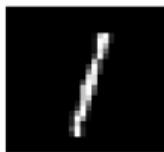
Real Observation, y_1 , Quantile = 0.05



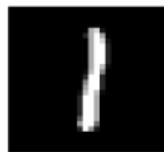
Real Observation, y_1 , Quantile = 0.23



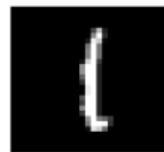
Real Observation, y_1 , Quantile = 0.41



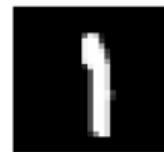
Real Observation, y_1 , Quantile = 0.59



Real Observation, y_1 , Quantile = 0.77



Real Observation, y_1 , Quantile = 0.95



Inference

Figures/combined-profile-features-2-3-digit_1.png

Inference

Typical Digit, y_2 Quantile = 0.06



Typical Digit, y_2 Quantile = 0.23



Typical Digit, y_2 Quantile = 0.41



Typical Digit, y_2 Quantile = 0.59



Typical Digit, y_2 Quantile = 0.77



Typical Digit, y_2 Quantile = 0.95



Real Observation, y_2 Quantile = 0.06



Real Observation, y_2 Quantile = 0.23



Real Observation, y_2 Quantile = 0.41



Real Observation, y_2 Quantile = 0.59



Real Observation, y_2 Quantile = 0.77



Real Observation, y_2 Quantile = 0.95



Typical Digit, y_2 Quantile = 0.06



Typical Digit, y_2 Quantile = 0.23



Typical Digit, y_2 Quantile = 0.41



Typical Digit, y_2 Quantile = 0.59



Typical Digit, y_2 Quantile = 0.77



Typical Digit, y_2 Quantile = 0.95



Real Observation, y_2 Quantile = 0.06



Real Observation, y_2 Quantile = 0.23



Real Observation, y_2 Quantile = 0.41



Real Observation, y_2 Quantile = 0.59



Real Observation, y_2 Quantile = 0.77

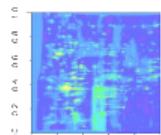
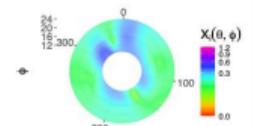


Real Observation, y_2 Quantile = 0.95

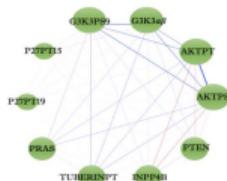


A General Framework

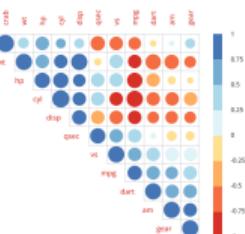
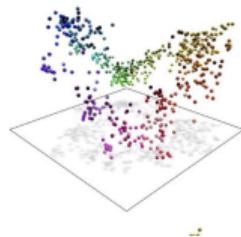
Data Objects



Protein-Protein Network for PI3K-AKT Pathway



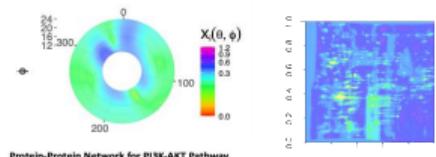
English names for colours
text-embedding-large-3



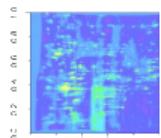
-2

A General Framework

Data Objects



Protein-Protein Network for PI3K-AKT Pathway



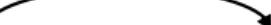
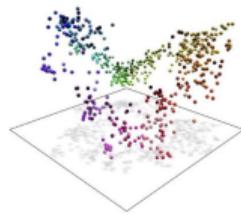
Encoding
 $f(\cdot)$

Lower-Dimensional
Space of Latent
Features

Y_1^*	Y_2^*	\dots	Y_K^*
-4.33	-5.26	\dots	-4.11

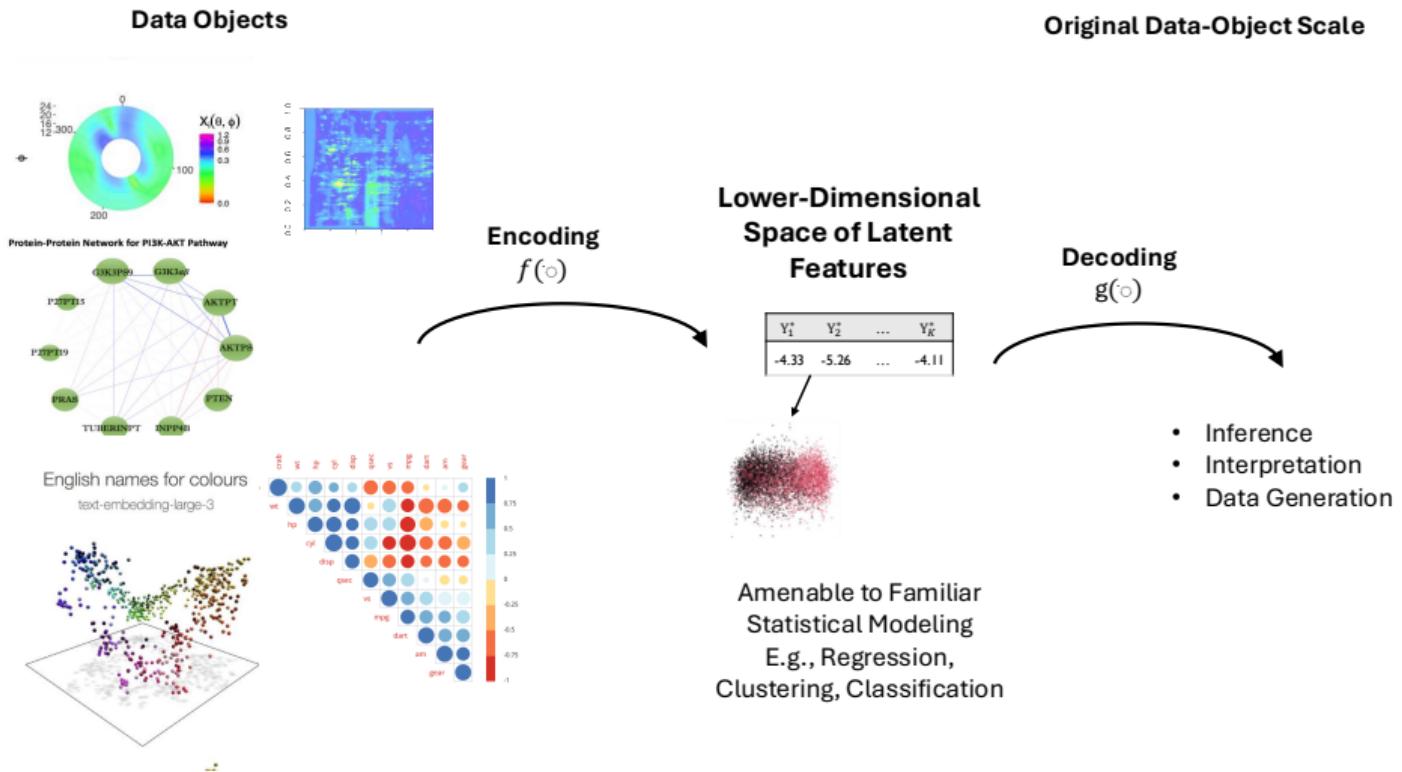


English names for colours
text-embedding-large-3



Amenable to Familiar
Statistical Modeling
E.g., Regression,
Clustering, Classification

A General Framework



A General Framework

- Transformation functions $f(\cdot)$ and $g(\cdot)$ can:
 - Utilize modern machine-learning tools.
 - Incorporate analytic transformations that respect the objects' geometry.
 - Induce favorable latent space geometry.
 - Use compositions, e.g., $f(\cdot) = f_2 \circ f_1(\cdot)$
- Framework allows us to:

A General Framework

- Transformation functions $f(\cdot)$ and $g(\cdot)$ can:
 - Utilize modern machine-learning tools.
 - Incorporate analytic transformations that respect the objects' geometry.
 - Induce favorable latent space geometry.
 - Use compositions, e.g., $f(\cdot) = f_2 \circ f_1(\cdot)$
- Framework allows us to:
 - Model modern data objects using familiar statistical tools → principled approaches to estimation, inference, hypothesis testing etc.,
 - Leverage the power of contemporary approaches for data representation within familiar and well-tested statistical modeling frameworks.

Thank You For Listening

