

System Design for Measuring Microstructure Changes During Thermal Treatment

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1 Revision History

Table 1: Revision History

Date	Developer(s)	Change
Jan 17, 2023	Abdul Nour	Added Intro, Purpose, and Scope (3,4,5)
Jan 17, 2023	Abdul Nour	Added Project Overview (6)
Jan 17, 2023	Abdul Nour	Added Design of Hardware (9)
Jan 18, 2023	Joseph Braun	Added System Variables (7)
Jan 18, 2023	Joseph Braun	Added Timeline (12)
Jan 18, 2023	Joseph Braun	Added User Interfaces (8)
Jan 18, 2023	Joseph Braun	Added Communication Protocols (11)
Jan 18, 2023	Joseph Braun	Added Reflection answers
...

2 Reference Material

This section records information for easy reference.

2.1 Abbreviations and Acronyms

Table 2: Abbreviations and Acronyms

symbol	description
FR	Functional Requirement
NFR	Non-functional Requirement
NFR-L	Non-functional Requirement: Look and Feel Requirement
NFR-U	Non-functional Requirement: Usability and Humanity Requirement
NFR-P	Non-functional Requirement: Performance Requirement
NFR-O	Non-functional Requirement: Operational and Environmental Requirement
NFR-M	Non-functional Requirement: Maintainability and Support Requirement
NFR-S	Non-functional Requirement: Security Requirement
NFR-C	Non-functional Requirement: Cultural Requirement
NFR-H	Non-functional Requirement: Health and Safety Requirement
NFR-I	Non-functional Requirement: Installability Requirement
Measuring Microstructure Changes During Thermal Treatment	Explanation of program name

Contents

1 Revision History	i
2 Reference Material	ii
2.1 Abbreviations and Acronyms	ii
3 Introduction	1
4 Purpose	1
5 Scope	1
6 Project Overview	3
6.1 Normal Behaviour	3
6.2 Undesired Event Handling	3
6.3 Component Diagram	4
6.4 Connection Between Requirements and Design	5
7 System Variables	7
7.1 Monitored Variables	7
7.2 Controlled Variables	7
7.3 Constants Variables	7
8 User Interfaces	7
9 Design of Hardware	7
10 Design of Electrical Components	7
11 Design of Communication Protocols	8
12 Timeline	9
A Interface	10
B Mechanical Hardware	10
C Electrical Components	11
D Communication Protocols	13
E Reflection	13

List of Tables

1	Revision History	i
2	Abbreviations and Acronyms	ii
3	Connection Between Requirements and Design	5
4	Connection Between Requirements and Design Continued	6

List of Figures

1	System Context Diagram	2
2	Component Diagram	4
3	Project Timeline	9
4	Previous software user interface design	10
5	Nano-Voltmeter: Keithley 2182A	11
6	Multimeter: Hewlett-Packard 3478A	11
7	Precision Current Source: Keithley 6220	12
8	National Instruments PCI-GPIB IEEE 488.2 Instrument Control Device	12
9	PCI-GPIB Card Specifications	13

3 Introduction

This document outlines the design and implementation plan for ReSprint's system that would be measuring and analyzing data from thermally treated samples. The main risks identified for the project include insufficient data sampling rates from existing measurement hardware and compatibility issues with the outdated operating system on the control computer. To mitigate these risks, the system will aim to be compatible with newer versions of Windows, be able to read and parse data files, perform extensive calculations, and handle real-time data processing. The project will be developed using C# and the Microsoft Visual Studio environment, with ESLint as the linting tool and MochaJS as the unit testing framework as found in the [Verification & Validation Plan](#). The system boundaries and components found in the [Hazard Analysis](#) document include thermally treated samples, a current source, a temperature sensor, a nanovoltmeter, interfaces between the devices and control computer, the control computer, and the software application installed on the control computer.

4 Purpose

The purpose of the system design document for this project is to provide a detailed and comprehensive plan for the design and implementation of the hardware and electrical components of the project, following the successful completion of the proof of concept demonstration. As outlined in the [Software Requirements and Specification](#) document, this document will add details to the technical requirements and constraints of the system, including any necessary measurements and interfaces as mentioned in the [Hazard Analysis](#) document. The document will serve as a guide for the development team in terms of the technical aspects of the project, including the necessary hardware and electrical components, and also acts as a reference for stakeholders, including any regulatory bodies, to understand the technical details of the project and ensure compliance with the [Development Plan](#) documentation. This document will be essential for the proper planning, development, and implementation of the hardware and electrical components of the project.

5 Scope

The scope of this document includes a comprehensive design plan for the hardware and electrical components of the project. It covers the purpose and scope of the project, an overview of the normal behavior and handling of undesired events, a component diagram, and a connection between requirements and design. The document also includes details on the system variables, including monitored, controlled, and constant variables, as well as the design of the user interfaces. Additionally, the document covers the design of the hardware, electrical components, and communication protocols, with a timeline for the project, and appendices on the interface, hardware, electrical components, communication protocols, and reflection

on the project. Overall, the scope of the document is to provide a detailed and technical guide for the development team and a reference for stakeholders to understand the technical aspects of the project and ensure proper planning, development and implementation of the hardware and electrical components of the project.

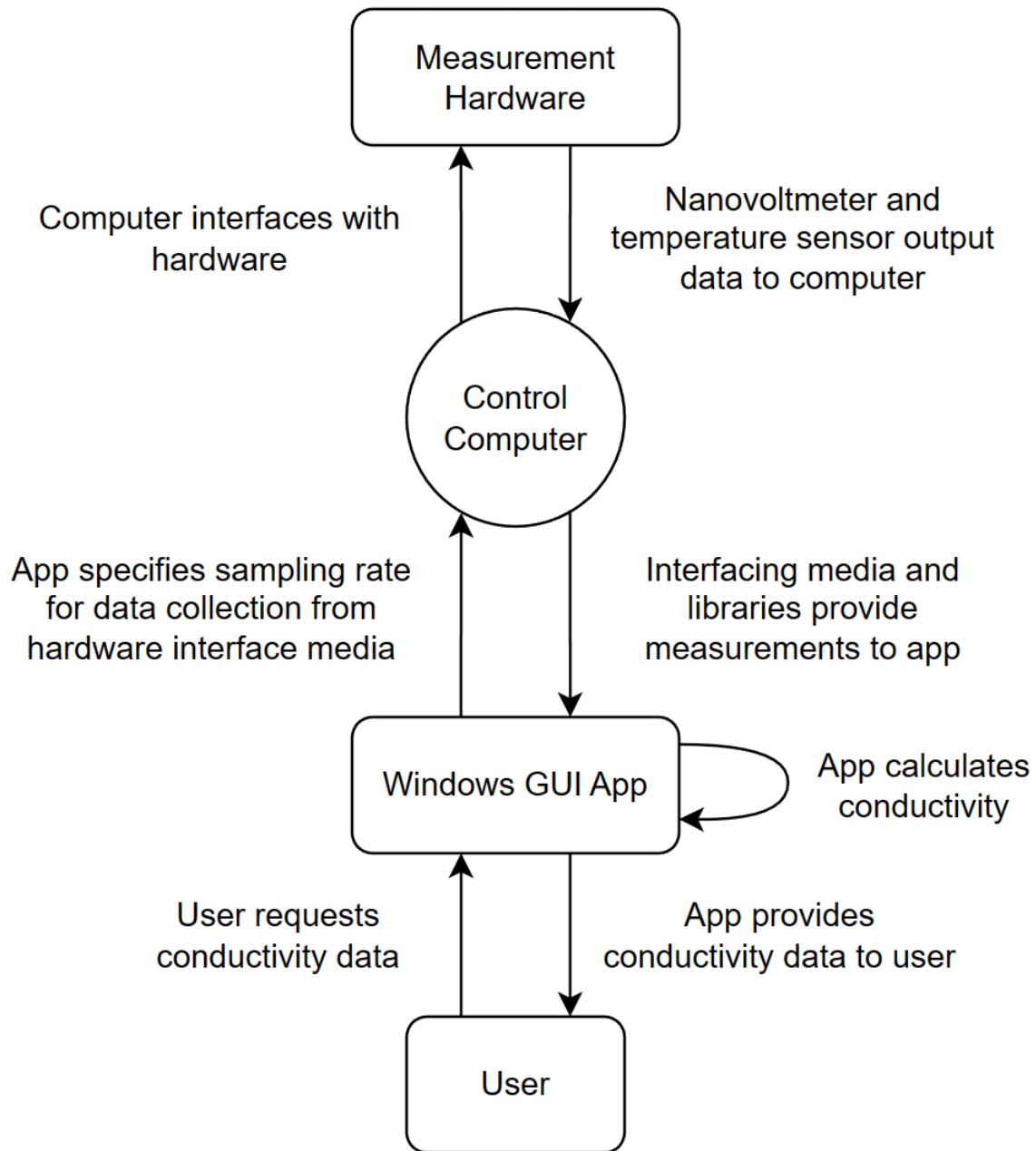


Figure 1: System Context Diagram

6 Project Overview

6.1 Normal Behaviour

The normal behavior and operation of the system refers to how the system is expected to function under normal operating conditions. This includes the system's ability to collect, process, and analyze data from thermally treated samples using the existing hardware, such as the nanovoltmeter, current source, and temperature sensor. The system should also be able to communicate with these devices using the appropriate communication protocols and interfaces, and handle any data synchronization issues. Additionally, the system should be able to perform basic calculations on the data and display it in an easy-to-understand format for the user. The system should also be able to handle real-time data processing, allowing for real-time monitoring of the samples. Overall, the normal behavior of the system is to provide accurate and reliable data analysis of thermally treated samples in real-time, allowing the user to make informed decisions based on the data provided.

6.2 Undesired Event Handling

In the event of an unexpected occurrence, the application should quickly transition to a safe state to prevent the acceptance of any invalid data by the system. This will avoid additional errors when the user accesses or alters corrupted or incorrect data. To ensure that all of the measurements expected are retrieved, the system shall make sure to notify the user to double-check the measurement devices and connectivity in case of failure. This approach will ensure that the system remains reliable and provides accurate data to the user.

6.3 Component Diagram

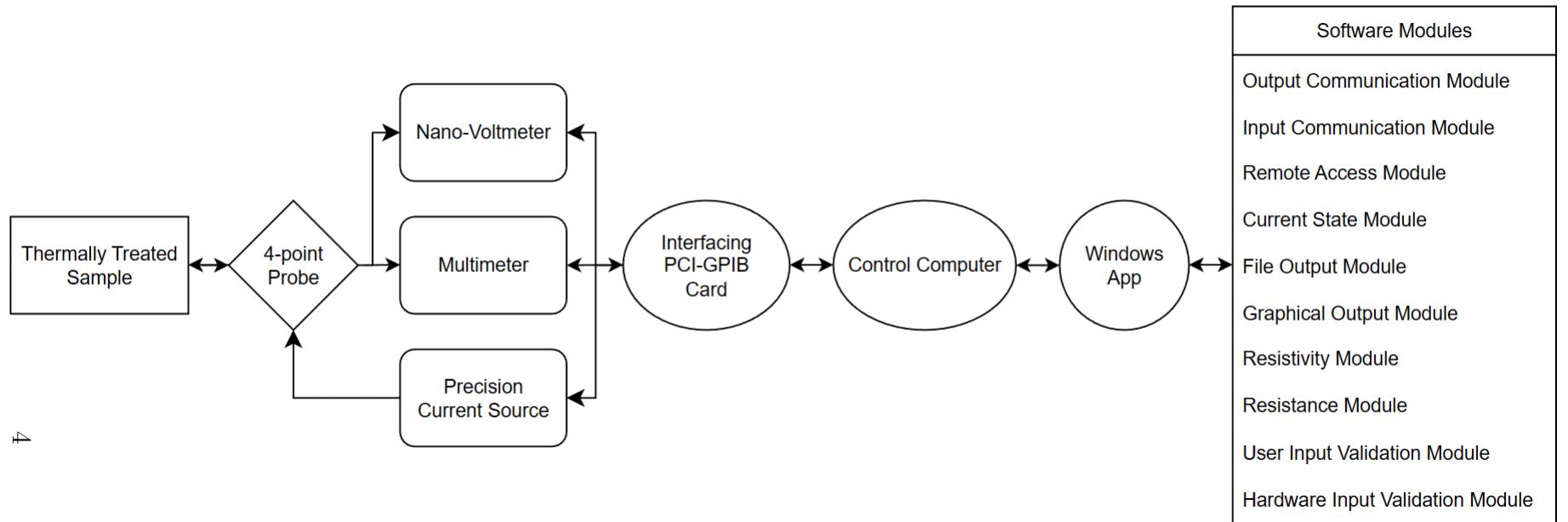


Figure 2: Component Diagram

6.4 Connection Between Requirements and Design

Table 3: Connection Between Requirements and Design

Requirements	Design Decisions
FR1	All software modules except the Remote Access module are used to satisfy this requirement along with the use of all hardware components
FR2	Current State, and Output Communication modules contribute to this requirement
FR3	Input Communication module and the use of a GPIB serial communication device shall control the sampling rate
FR4	In addition to the modules mentioned for FR2, the Graphical Output module would contribute to this requirement
FR5	The Remote Access module is responsible for satisfying this requirement
NFR-L1	NF-AT1
NFR-L2	NF-AT2
NFR-U1	NF-UT1
NFR-U2	NF-UT2
NFR-U3	NF-UT3
NFR-U4	NF-UT4
NFR-U5	NF-UT5
NFR-U6	NF-UT6
NFR-U7	NF-UT7
NFR-P1	NF-PT1
NFR-P2	NF-PT2
NFR-P3	NF-PT3
NFR-P4	NF-PT4
NFR-P5	NF-PT5
NFR-O1	NF-OT1
NFR-O2	NF-OT2
NFR-O3	N/A

Table 4: Connection Between Requirements and Design Continued

Requirements	Design Decisions
NFR-M1	N/A
NFR-M2	NF-MT1
NFR-M3	NF-MT1
NFR-S1	NF-ST1
NFR-S2	NF-ST2
NFR-C1	NF-CT1
NFR-H1	NF-HT1
NFR-H2	NF-HT1
NFR-I1	NF-MT1

7 System Variables

Our system contains three main variables: the current being provided from the Current Source, the voltage measured across the sample with the Nano-Voltmeter, and the temperature measured from the sample.

7.1 Monitored Variables

- *m_voltage*: sample voltage
- *m_temp*: sample temperature

7.2 Controlled Variables

- *c_current*: current source output

7.3 Constants Variables

No constant variables used in this project.

8 User Interfaces

A user interface will be designed for the Windows application. Dr. Zurob has provided the team with the previous version of the application, which can be seen in [Appendix A](#). We will design our user interface with the same basic layout as the previous version in order to keep the design familiar to the user. Updates from the previous design will include changes to the colour scheme, font, and graphics.

9 Design of Hardware

There are no mechanical hardware components used in this design.

10 Design of Electrical Components

For this project, we are provided with all of the hardware. Starting with the thermally treated samples, these will be provided by the user and/or Dr. Zurob. The lab is responsible for providing them as they are specific materials that are treated with equipment outside of the scope of our project. The measurement devices along with the current source and the serial communication module are also provided by the lab as the following:

- Nano-Voltmeter: Keithley 2182A

- Multimeter: Hewlett-Packard 3478A
- Precision Current Source: Keithley 6220
- Serial Communication Module: National Instruments PCI-GPIB IEEE 488.2 Instrument Control Device

Reference photos of listed components can be found in [Appendix C](#).

We are also provided with the control (lab) computer, which has the PCI-GPIB communication card built in. This computer was upgraded with additional RAM memory and an SSD storage by our mechatronics engineers. Further upgrades would be possible, such as the addition of a Wi-Fi card in case the lab does not provide continuous Ethernet connection to the internet.

11 Design of Communication Protocols

The hardware will communicate with the application through the PCI-GPIB card. The protocol used by the card is IEEE 488.2. This is an extension of the IEEE 488 protocol, also known as GPIB, which is a short-range digital communications 8-bit parallel multi-master interface bus specification developed by Hewlett-Packard. Some key features of GPIB are:

- One bus can support up to 15 devices
- Message transactions are hardware handshaked
- Data rates may be up to 1 MB/s

The specifications for the particular PCI-GPIB card used in this system (installed on the lab computer) are shown in [Appendix D](#). The specifications include information about IEEE 488 compatibility and bus transfer rates.

12 Timeline

Start	End	Task	Description	Assigned Team Member(s)	Duration
19-Jan	20-Jan	Finalise Hardware Setup	Ensure that all devices are working properly, install appropriate drivers on computer to communicate with devices	Abdul, Joseph	2
21-Jan	27-Jan	Implement Module 2 (M2)	M2 is the Input Communication Module. It will convert input data from the devices into the data structure used by the application.	Abdul, Joseph	7
21-Jan	27-Jan	Implement Module 4 (M4)	M4 is the Current State Module. It will obtain and display the current system state, such as current temperature, voltage, and sampling rate.	Edwin	7
21-Jan	27-Jan	Implement Module 6 (M6)	M6 is the Graphical Output Module. It will display the relevant data in a graphical format.	Tyler	7
21-Jan	27-Jan	Implement Module 7 (M7)	M7 is the Calculation Module. It will compute the resistance and resistivity of the sample and return the result.	Timothy	7
28-Jan	30-Jan	Module Testing	This time is reserved for each team member to individually test the module they were assigned to complete and ensure it is working properly. After unit tests are complete, the group will perform integration testing with all currently completed modules.	All	3
31-Jan	03-Feb	Implement Module 5 (M5)	M5 is the File Output Module. It will output a file with the appropriate data to the screen for the user.	Timothy	4
31-Jan	03-Feb	Implement Module 8 (M8)	M8 is the User Input Validation Module. It will validate the input from the user.	Tyler	4
31-Jan	03-Feb	Implement Module 9 (M9)	M9 is the Hardware Input Validation Module. It will validate the input from the hardware devices.	Joseph	4
31-Jan	03-Feb	Implement Module 3 (M3)	M3 is the Remote Access Module. It will implement remote access to the application for the user.	Abdul, Edwin	4
04-Feb	05-Feb	Final Testing	This time is reserved for unit testing of each additional module. After all modules have been tested, final integrations tests will be performed to ensure the addition of the new modules does not cause issues with the system. When integration testing is done, the system will be ready for demo.	All	2

Figure 3: Project Timeline

A Interface

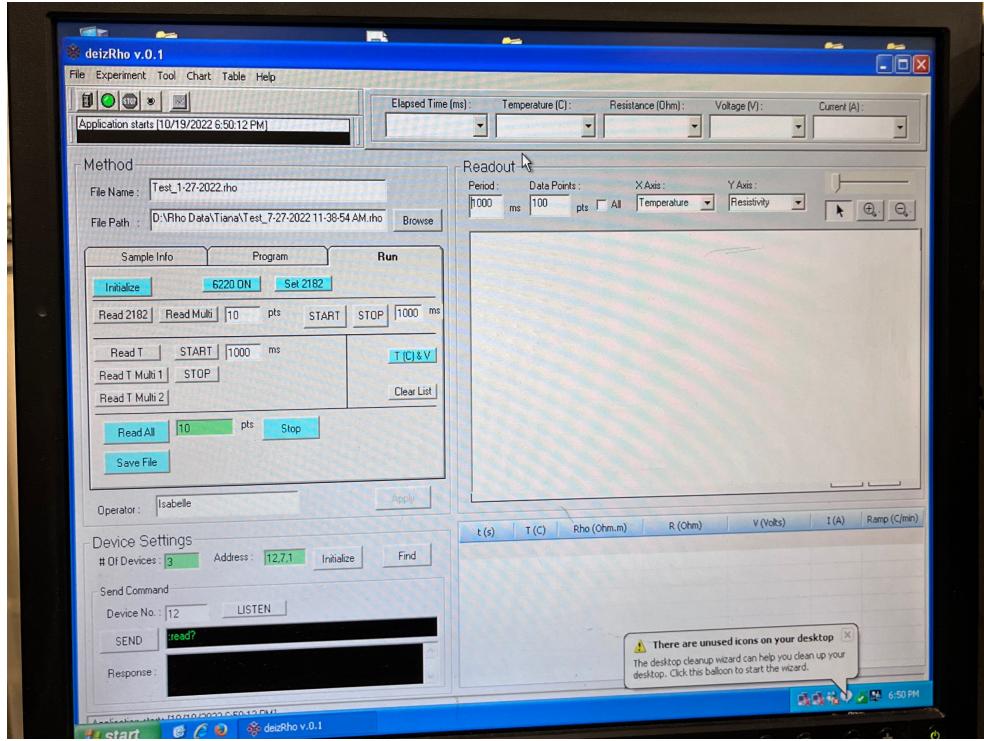


Figure 4: Previous software user interface design

B Mechanical Hardware

C Electrical Components



Figure 5: Nano-Voltmeter: Keithley 2182A



Figure 6: Multimeter: Hewlett-Packard 3478A



Figure 7: Precision Current Source: Keithley 6220

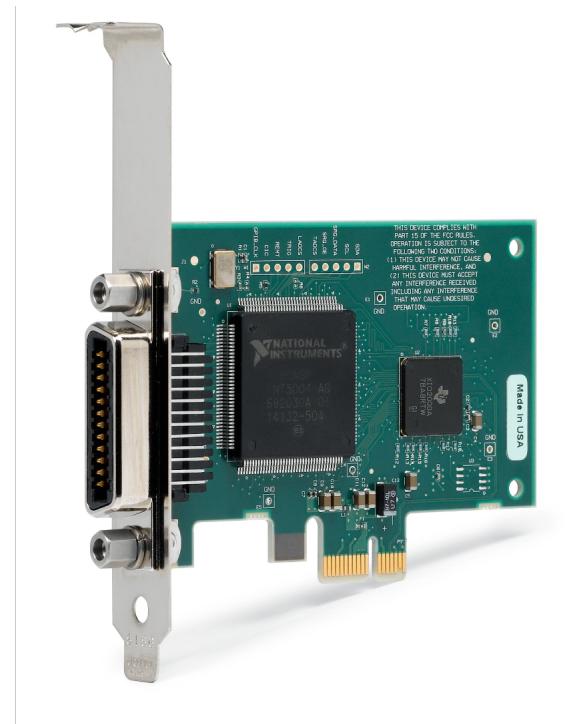


Figure 8: National Instruments PCI-GPIB IEEE 488.2 Instrument Control Device

D Communication Protocols

Specifications	
IEEE 488 Compatibility	
IEEE 488.1 and IEEE 488.2 compatible	
Capability Code	Description
SH1	Source Handshake
AH1	Acceptor Handshake
T5, T65	Talker, Extender Talker
L3, L63	Listener, Extender Listener
SR1	Service Request
PPI, PP2	Local/Remote Parallel Poll
RL1	Remote/Local
C1, C2, C3, C4, C5	Controller
E1, E2	Three-state bus drivers with automatic switch to open collector during parallel poll
Maximum IEEE 488 Bus Transfer Rates	
IEEE 488 interlocked handshake.....	1.5 MB/s
IEEE 488 noninterlocked (HS488) handshake.....	7.7 MB/s
(actual rates depend on system configuration and instrument capabilities)	
GPIB Analyzer Performance	
Sampling rate.....	20 MHz
Timestamp resolution	50 ns
Ethernet Performance	
10BaseT.....	10 Mb/s, full-duplex
100BaseTX.....	100 Mb/s, full-duplex
1000BaseT.....	1000 Mb/s, full-duplex
Power Requirements	
PCI-GPIB, PXI-GPIB, PCI-GPIB/LP (183617x-01-based board) +5 VDC	1.5 W typical, 2.25 W maximum
PCI-GPIB, PXI-GPIB (188513x-01-based board) +3.3 VDC	0.4 W typical, 0.6 W maximum
PCI-GPIB+ +3.3 VDC.....	0.6 W typical, 1.9 W maximum
PCI-8232 +5 VDC	4.4 W typical, 5.8 W maximum
PXI-8232 +3.3 VDC	3.0 W typical, 4.0 W maximum
PCI signaling level.....	Universal
Physical Dimensions	
PCI (183617x-01-based board).....	13.3 by 10.7 cm (5.3 by 4.2 in.)
PCI (188513x-01-based board).....	12.0 by 6.44 cm (4.72 by 2.54 in.)
PCI (low-profile).....	12.0 by 6.44 cm (4.72 by 2.54 in.)
PXI	16 by 10 cm (6.3 by 3.9 in.)
I/O Connectors	
GPIB.....	IEEE 488 standard 24-pin
Ethernet.....	RJ-45
Operating Environment	
Ambient temperature.....	0 to 55 °C
Relative humidity	10 to 90%, noncondensing
(tested in accordance with IEC-60068-2-1, IEC-60068-2-2, and IEC-60068-2-56)	
Storage Environment	
Ambient temperature.....	-20 to 70 °C
Relative humidity	5 to 95%, noncondensing
(tested in accordance with IEC-60068-2-1, IEC-60068-2-2, and IEC-60068-2-56)	
Shock and Vibration	
PCI-GPIB, PXI-8232	
Functional shock	30 g peak, half-sine, 11 ms pulse
(tested in accordance with IEC-60068-2-27; test profile developed in accordance with MIL-PRF-28800F)	
Random vibration	
Operating.....	5 to 500 Hz, 0.3 g _{rms}
Nonoperating.....	5 to 500 Hz, 2.4 g _{rms}
(tested in accordance with IEC-60068-2-64; nonoperating test profile exceeds the requirements of MIL-PRF-28800E, Class 3)	
Compliance and Safety	
Visit ni.com/certification .	

Figure 9: PCI-GPIB Card Specifications

E Reflection

The information in this section will be used to evaluate the team members on the graduate attribute of Problem Analysis and Design. Please answer the following questions:

1. What are the limitations of your solution? Put another way, given unlimited resources, what could you do to make the project better? (LO_ProbSolutions)
2. Give a brief overview of other design solutions you considered. What are the benefits and tradeoffs of those other designs compared with the chosen design? From all the potential options, why did you select documented design? (LO_Explores)

Answers:

1. The main limitations of this project are due to the hardware. We are working with a fairly old desktop computer which was provided for the project. Though we have made some upgrades so that Windows 10 can be run on the computer, we have stopped short of building a new computer. Given unlimited resources, we would purchase all new hardware for the project, including building a new computer and replacing all the devices.
2. There were primarily two design solutions which our team considered for this project. The first solution was to troubleshoot what went wrong with the old program and fix it so that it could be used again. This solution was proposed due to the low implementation time, as it would be easier to fix the old program than write a new one. The issue with this solution is that ultimately Dr. Zurob is left with the same application he originally had, so there is not much added value. In addition, since the old program runs on Windows XP, there is no possibility of adding a remote connection, which is one of the stretch goals of this project. For these reasons, our team decided to choose our second solution of writing a new program on an updated Windows 10/11 system. The application will have updated graphics and will likely run faster on the updated hardware, and there is the option of adding a remote connection to the application.