EDWIN GOH

DATA SCIENTIST @ NASA JET PROPULSION LABORATORY (JPL)

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Personal Profile

Data Scientist with a unique blend of expertise in deep learning, aerospace engineering (reacting fluid dynamics), and Earth science (oceanography). Demonstrated success at NASA JPL formulating and leading projects that leverage deep learning to solve complex scientific and engineering challenges in various domains such as planetary science, Earth science, and robotics. Proficient in large-scale, multi-node deep learning using PyTorch and TensorFlow. Eager to drive advancements in NVIDIA Modulus for high-throughput predictive simulations and digital twins.

Work Experience

NASA Jet Propulsion Laboratory — California Institute of Technology **Data Scientist**

Pasadena, CA

Feb 2020 - Present

Semi-supervised Learning from Images of a Changing Earth (SLICE; Principal Investigator):

- PI on a \$1M NASA research program to develop self-supervised Earth science foundation models
- Attained breakthrough 0.1°C accuracy in reconstructing satellite sea surface temperature measurements under cloud obstruction by applying large-scale, physics-informed masked image modeling on a 25PB dataset
- Leveraging neural operator learning with NVIDIA Modulus (Makani) to develop an ocean digital twin
- Contrastive Learning for Onboard Vision-Enabled Robotics (CLOVER; Principal Investigator)
- Won a competed proposal to investigate self-supervised learning for planetary science and robotic exploration
- Managed a team of 7 researchers to execute multi-node contrastive pretraining experiments on Mars imagery
- Reduced required labels by 10x and doubled inference throughput on Mars terrain segmentation

Automated Scheduling of NASA's Deep Space Network (DSN):

- Pioneered automated DSN communications scheduling with deep reinforcement learning (RL)
- Implemented OR-inspired RL baselines and published a benchmark dataset for satellite scheduling (SatNet)
- Developed benchmark problem set used by Microsoft collaborators for quantum annealing-based scheduling
- ShadowNav (Co-Investigator):
- Developed a stereo perception pipeline for absolute rover localization on the far/dark side of the Moon
- Compared stereo and edge-detection algorithms and quantified their impact on localization accuracy

Business Development

- Served 14 stakeholders across JPL, NASA, USGS, DHS, and DARPA
- Co-authored proposal with Prof. Anima Anandkumar (Caltech) on Fourier Neural Operators for oceanography

Ben T. Zinn Combustion Lab - Georgia Tech

Atlanta, GA

Graduate Research Assistant - DOE Optimized Low-NOx Staged Combustor Development

2016 - 2020

- Developed simulation suite in Python and MATLAB for preliminary combustor design and optimization
- Elucidated key effects of non-ideal flow conditions on NOx formation and combustor design
- Investigated recurrent neural networks to develop surrogate models for compute-intensive chemical kinetics
- Implemented a CUDA-based Lattice Boltzmann Method (LBM) for fluid dynamics simulations as part of a Parallel Computing course, improving throughput by over 90% compared to a CPU-based simulation

United Parcel Service (UPS)

Atlanta, GA

Formulated MILP problems to optimize UPS' last-mile delivery network in the EU

May 2019 - Nov 2019

- Enabled 2X speedup of a shortest-path network optimization subroutine through parallelization in the cloud

Education

Data Science Co-op

Skills _____

Programming Python (Distributed PyTorch, Scikit-learn, Ray, OpenCV, etc.), Java, C/C++

Computing Linux, shell scripting (bash, zsh), high performance computing (Slurm, PBS), ROS

Communication Proficient in conveying complex AI concepts to technical and non-technical audiences

Professional Service/Activities

• American Institute of Aeronautics and Astronautics (AIAA), senior member

- Elected AIAA Intelligent Systems Technical Committee (ISTC) member
- Intelligent Systems Technical Discipline Lead (TDL) for the AIAA ASCEND 2024 Conference

Book Chapters_____

[B1] **Goh, E.**, Didier, A., Wang, J. (2023) Deep Learning for Ocean Mesoscale Eddy Detection. Artificial Intelligence in Earth Science: Best Practices and Fundamental Challenges.

Journal Publications

- [J1] **Goh, E.**, Yepremyan, A., Wang, J., Wilson, B. (2024). MAESSTRO: Masked Autoencoders for Sea Surface Temperature Reconstruction under Occlusion. Ocean Science, 20(5), 1309-1323.
- [J2] Atha, D., Swan, R. M., Cauligi, A., Bettens, A., **Goh, E.**, Kogan, D., Matthies, L., Ono, M. (2024). ShadowNav: Autonomous Global Localization for Lunar Navigation in Darkness. IEEE Transactions on Field Robotics.
- [J3] Vincent, G., Ward, I., Moore, C., Chen, J., Pak, K., Yepremyan, A., Wilson, B., **Goh, E.** (2023). CLOVER: Contrastive Learning for Onboard Vision-Enabled Robotics. AIAA Journal of Spacecraft and Rockets.
- [J4] Guillaume, A., Goh, E., Johnston, M.D., Wilson, B.D., Ramanan, A., Tibble, F., Lackey, B. (2022). Deep Space Network Scheduling using Quantum Annealing. IEEE Transactions on Quantum Engineering, 3, 1-13
- [J5] Claudet, T., Alimo, R., **Goh, E.**, Johnston, M.D., Madani, R., Wilson, B. (2022). *A*-MILP: Deep Space Network Scheduling via Mixed-Integer Linear Programming. IEEE access, 10, 41330-41340.
- [J6] **Goh, E.**, Li, J., Kim, N.Y., Lieuwen, T. and Seitzman, J. (2021). Finite-rate entrainment effects on nitrogen oxide (NOx) emissions in staged combustors. Combustion and Flame, 230, 111-434.
- [J7] **Goh, E.**, Sirignano, M., Li, J., Nair, V., Emerson, B., Lieuwen, T. and Seitzman, J. (2019). Prediction of minimum achievable NOx levels for fuel-staged combustors. Combustion and Flame, 200, 276-285.

Conference Publications

- [C1] **Goh, E.**, Ward, I.R., Vincent, G.M., Pak, K., Chen, J. (2023). Self-Supervised Distillation for Computer Vision Onboard Planetary Robots. 2023 IEEE Aerospace Conference. IEEE.
- [C2] Vincent, G.M., **Goh, E.**, Pak, K., Wilson, B., Wang, J., Holt, B. (2023). Unsupervised SAR Images for Submesoscale Oceanic Eddy Detection. IEEE IGARSS.
- [C3] **Goh, E.,** Yepremyan, A., Wilson, B., Wang, J. (2023). Reconstruction of Sea Surface Temperature Under Clouds Using Masked Autoencoders. IEEE IGARSS.
- [C4] Ward, I.R., Moore, C., Pak, K., Chen, J., **Goh, E.** (2022). Improving Contrastive Learning on Visually Homogeneous Mars Rover Images. European Conference on Computer Vision (ECCV) Workshop on Al4Space.
- [C5] Vincent, G.M., Yepremyan, A., Chen, J., **Goh, E.** (2022). Mixed-domain Training Improves Multi-Mission Terrain Segmentation. European Conference on Computer Vision (ECCV) Workshop on Al4Space.
- [C6] **Goh, E.**, Chen, J., Wilson, B. (2022). Mars Terrain Segmentation with Less Labels. 2022 IEEE Aerospace Conference. IEEE.
- [C7] **Goh, E.**, Venkataram, H.S., Hoffmann, M., Johnston, M. and Wilson, B. (2021). Scheduling the NASA Deep Space Network with Deep Reinforcement Learning. 2021 IEEE Aerospace Conference. IEEE.
- [C8] **Goh, E.**, Sirignano, M., Nair, V., Emerson, B., Lieuwen, T. and Seitzman, J. (2017). Modeling of Minimum NOx in Staged-Combustion Architectures at Elevated Temperatures. In ASME Turbo Expo 2017: Turbomachinery Technical Conference and Exposition. American Society of Mechanical Engineers Digital Collection.