### 5.2.49

#### RAVULA SHASHANK REDDY - EE25BTECH11047

September 30, 2025

### Question

Solve the system of equations using matrices:

$$3x - y - 2z = 2,$$
  

$$2y - z = -1,$$
  

$$3x - 5y = 3.$$

#### Solution

Given:

$$\begin{pmatrix} 3 \\ -1 \\ -2 \end{pmatrix}^T \mathbf{x} = 2,\tag{1}$$

$$\begin{pmatrix} 0 \\ 2 \\ -1 \end{pmatrix}^T \mathbf{x} = -1, \tag{2}$$

$$\begin{pmatrix} 3 \\ -5 \\ 0 \end{pmatrix}^T \mathbf{x} = 3 \tag{3}$$

$$\begin{pmatrix} 3 & -1 & -2 \\ 0 & 2 & -1 \\ 3 & -5 & 0 \end{pmatrix} \mathbf{x} = \begin{pmatrix} 2 \\ -1 \\ 3 \end{pmatrix} \tag{4}$$

#### Solution

$$R_3 \to R_3 - R_1 \Rightarrow \begin{pmatrix} 3 & -1 & -2 & 2 \\ 0 & 2 & -1 & -1 \\ 0 & -4 & 2 & 1 \end{pmatrix}$$
 (5)

$$R_2 \to \frac{1}{2}R_2 \Rightarrow \begin{pmatrix} 3 & -1 & -2 & 2\\ 0 & 1 & -\frac{1}{2} & -\frac{1}{2}\\ 0 & -4 & 2 & 1 \end{pmatrix}$$
 (6)

$$R_1 \to R_1 + R_2, \quad R_3 \to R_3 + 4R_2 \Rightarrow \begin{pmatrix} 3 & 0 & -\frac{5}{2} & \frac{3}{2} \\ 0 & 1 & -\frac{1}{2} & -\frac{1}{2} \\ 0 & 0 & 0 & -1 \end{pmatrix}$$
 (7)

$$\implies 0 = -1 \tag{8}$$

System inconsistent  $\Rightarrow$  No s



```
#include <stdio.h>
#include <math.h>
#define N 3
int main() {
    int i, j, k;
   double A[N][N+1] = {
        \{3, -1, -2, 2\},\
       \{0, 2, -1, -1\},\
       \{3, -5, 0, 3\}
   };
    // Forward elimination
   for (i = 0; i < N; i++) {</pre>
        // Pivot should not be zero (no pivoting added here for
            simplicity)
        if (fabs(A[i][i]) < 1e-9) continue;</pre>
```

```
// Normalize row
   double div = A[i][i];
   for (j = i; j <= N; j++) {</pre>
       A[i][j] /= div;
   // Eliminate other rows
   for (k = 0; k < N; k++) {
       if (k == i) continue;
       double factor = A[k][i];
       for (j = i; j <= N; j++) {
           A[k][j] -= factor * A[i][j];
// Check for inconsistency
int inconsistent = 0;
```

```
for (i = 0; i < N; i++) {
   int allZero = 1;
   for (j = 0; j < N; j++) {
       if (fabs(A[i][j]) > 1e-9) {
           allZero = 0;
           break;
   if (allZero && fabs(A[i][N]) > 1e-9) {
       inconsistent = 1;
       break;
```

```
if (inconsistent) {
    printf(System is inconsistent -> No solution\\n);
} else {
    printf(Solution:\\n);
    for (i = 0; i < N; i++) {</pre>
        printf(x\%d = \%lf \setminus n, i+1, A[i][N]);
return 0;
```

```
import numpy as np
import matplotlib.pyplot as plt
# local imports as you asked
import libs.line.funcs as linefuncs
import libs.triangle.funcs as trifuncs
# Coefficients of the system Ax=b
A = np.array([
  [3, -1, -2],
 [0, 2, -1].
  [3, -5, 0]
], dtype=float)
b = np.array([2, -1, 3], dtype=float)
# Check consistency via rank
rankA = np.linalg.matrix rank(A)
```

```
rankAb = np.linalg.matrix rank(np.c [A, b])
print(Rank(A) = , rankA)
print(Rank([A|b]) =, rankAb)
if rankA != rankAb:
    print(System is inconsistent -> No solution)
# --- Plot the planes ---
fig = plt.figure()
ax = fig.add_subplot(111, projection='3d')
```

```
# Create a meshgrid for x,y
 |x \text{ vals} = \text{np.linspace}(-5, 5, 50)|
y vals = np.linspace(-5, 5, 50)
 X, Y = np.meshgrid(x vals, y vals)
 # Equation 1: 3x - y - 2z = 2 \rightarrow z = (3x - y - 2)/2
 Z1 = (3*X - Y - 2)/2
 # Equation 2: 2y - z = -1 -> z = 2y + 1
 Z2 = 2*Y + 1
 # Equation 3: 3x - 5y = 3 -> (no z term, it's a vertical plane)
 # So plot separately
 Z3 = np.linspace(-5, 5, 50)
 X3, Z3m = np.meshgrid(x_vals, Z3)
 Y3 = (3*X3 - 3)/5
```

```
# Plot the planes
ax.plot_surface(X, Y, Z1, alpha=0.5, color='red', label='Plane 1'
ax.plot_surface(X, Y, Z2, alpha=0.5, color='blue', label='Plane 2
ax.plot_surface(X3, Y3, Z3m, alpha=0.5, color='green', label='
    Plane 3')
# Labels
ax.set xlabel(x)
ax.set ylabel(y)
ax.set zlabel(z)
ax.set title(Three Planes (Inconsistent System))
plt.show()
```

## Python Shared

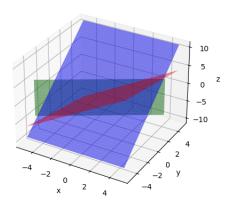
```
import ctypes
import numpy as np
# Load the shared library
lib = ctypes.CDLL(./libgauss.so)
# Function signature: int solve_system(double *A_in, double *
    x out)
lib.solve_system.argtypes = [ctypes.POINTER(ctypes.c double),
                           ctypes.POINTER(ctypes.c_double)]
lib.solve system.restype = ctypes.c int
# Input augmented matrix [A|b]
A = np.array([
    [3, -1, -2, 2], # 3x - y - 2z = 2
   [0, 2, -1, -1], # 2y - z = -1
    [3, -5, 0, 3] # 3x - 5y = 3
], dtype=np.float64)
```

# Python Shared

```
A flat = A.flatten()
x out = np.zeros(3, dtype=np.float64)
# Call the C function
status = lib.solve system(A flat.ctypes.data as(ctypes.POINTER(
   ctypes.c double)),
                        x out.ctypes.data as(ctypes.POINTER(
                            ctypes.c double)))
if status == 1:
   print(System is inconsistent -> No solution)
else:
   print(Solution:, x_out)
```

## Plot

#### Three Planes (Inconsistent System)



### Figure: