

# Matgeo Presentation - Bonus Problem

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## Question

Given 3 vectors  $\mathbf{A}, \mathbf{B}, \mathbf{C}$  are coplanar then show  $\det(\mathbf{M}) = 0$  where  $\mathbf{M} = (\mathbf{A} \ \mathbf{B} \ \mathbf{C})$

## Solution

Equation of plane through 3 coplanar points is

$$\mathbf{n}^T \mathbf{x} = 0 \quad (0.1)$$

$$\implies \mathbf{n}^T \mathbf{A} = \mathbf{n}^T \mathbf{B} = \mathbf{n}^T \mathbf{C} = 0 \quad (0.2)$$

$$\mathbf{M} = (\mathbf{A} \quad \mathbf{B} \quad \mathbf{C}) \quad (0.3)$$

$$\implies \mathbf{n}^T \mathbf{M} = (\mathbf{n}^T \mathbf{A} \quad \mathbf{n}^T \mathbf{B} \quad \mathbf{n}^T \mathbf{C}) \quad (0.4)$$

$$\implies \mathbf{n}^T \mathbf{M} = (0 \quad 0 \quad 0) \quad (0.5)$$

$$\implies \mathbf{n}^T \mathbf{M} = \mathbf{0} \quad (0.6)$$

From (0.6) it means  $\mathbf{M}$  has a non trivial vector in it's null space

$$\implies \text{rank}(\mathbf{M}) < 3. \quad (0.7)$$

For a  $3 \times 3$  square matrix like  $\mathbf{M}$  if  $\det(\mathbf{M}) \neq 0$  means  $\mathbf{M}$  is invertible which means  $\mathbf{M}$  is a full rank matrix

$$\implies \text{rank}(\mathbf{M}) = 3. (\text{if } \det(\mathbf{M}) \neq 0)$$

## Solution

From (0.7)  $\text{rank}(\mathbf{M}) < 3$

$\implies \mathbf{M}$  is not invertible

$\implies \det(\mathbf{M}) = 0$

**proof 2:**

3 vectors  $\mathbf{A}, \mathbf{B}, \mathbf{C}$  are coplanar means they are linearly dependent.

let's assume

$$\mathbf{C} = \alpha \mathbf{A} + \beta \mathbf{B}. \quad (0.8)$$

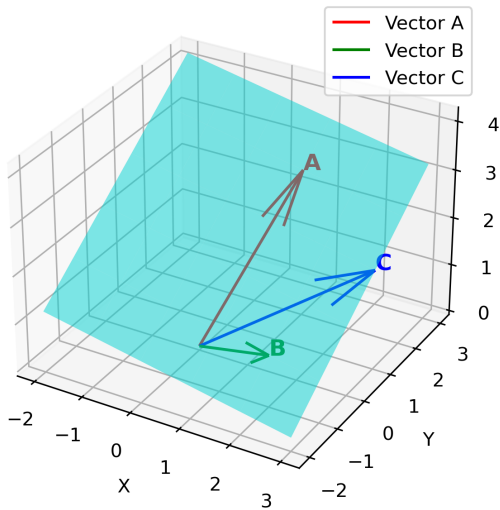
$$\det(\mathbf{M}) = \det((\mathbf{A} \quad \mathbf{B} \quad \mathbf{C})) \quad (0.9)$$

$$= \det((\mathbf{A} \quad \mathbf{B} \quad \alpha \mathbf{A} + \beta \mathbf{B})) \quad (0.10)$$

$$= \alpha \det((\mathbf{A} \quad \mathbf{B} \quad \mathbf{A})) + \beta \det((\mathbf{A} \quad \mathbf{B} \quad \mathbf{B})) = 0 \quad (0.11)$$

$$\implies \det(\mathbf{M}) = 0 \quad (0.12)$$

## Coplanar Vectors and Enclosing Plane



# C Code: coplanar.c

```
#include <stdio.h>

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// Function to compute scalar triple product (box product)
float boxProduct(float A[3], float B[3], float C[3]) {
    return A[0] * (B[1]*C[2] - B[2]*C[1])
        - A[1] * (B[0]*C[2] - B[2]*C[0])
        + A[2] * (B[0]*C[1] - B[1]*C[0]);
}

int main() {
    FILE *fp;
    float A[3], B[3], C[3];
    float box;

    // Input 3 vectors
    printf("Enter vector A(x y z): ");
    scanf("%f%f%f", &A[0], &A[1], &A[2]);

    printf("Enter vector B(x y z): ");
    scanf("%f%f%f", &B[0], &B[1], &B[2]);

    printf("Enter vector C(x y z): ");
    scanf("%f%f%f", &C[0], &C[1], &C[2]);

    // Compute box product
    box = boxProduct(A, B, C);

    // Open file coplanar.dat for writing
    fp = fopen("coplanar.dat", "w");
    if (fp == NULL) {
        printf("Error opening file!\n");
    }
}
```

## C Code: coplanar.c

```
        return 1;
    }

    fprintf(fp, "Scalar_triple_product_(Box_Product)_= %.2f\n", box);

    if (box == 0)
        fprintf(fp, "Vectors_are_coplanar.\n");
    else
        fprintf(fp, "Vectors_are_NOT_coplanar.\n");

    fclose(fp);

    printf("Result_written_to_coplanar.dat\n");

    return 0;
}
```

# Python: plot.py

```
import numpy as np
import matplotlib.pyplot as plt
from mpl_toolkits.mplot3d import Axes3D

# ==== Define the vectors ====
A = np.array([1, 2, 3]) # example vector A
B = np.array([2, -1, 1]) # example vector B
C = np.array([3, 1, 2]) # example vector C

# Compute normal to the plane (B-A) (C-A)
normal = np.cross(B - A, C - A)

# Equation of plane:  $n(X - A) = 0$   $nX = nA$ 
d = np.dot(normal, A)

# ==== Plotting ====
fig = plt.figure()
ax = fig.add_subplot(111, projection='3d')

# Plot vectors A,B,C from origin (with labels for legend)
ax.quiver(0, 0, 0, A[0], A[1], A[2], color='r', label='Vector_A')
ax.quiver(0, 0, 0, B[0], B[1], B[2], color='g', label='Vector_B')
ax.quiver(0, 0, 0, C[0], C[1], C[2], color='b', label='Vector_C')

# Add labels at arrow tips
ax.text(A[0], A[1], A[2], "A", color='r', fontsize=12, weight='bold')
ax.text(B[0], B[1], B[2], "B", color='g', fontsize=12, weight='bold')
ax.text(C[0], C[1], C[2], "C", color='b', fontsize=12, weight='bold')

# Create grid for the plane
xx, yy = np.meshgrid(range(-2, 4), range(-2, 4))
zz = (d - normal[0]*xx - normal[1]*yy) / normal[2]
```



# Python: plot.py

```
# Plot plane
ax.plot_surface(xx, yy, zz, alpha=0.5, color='cyan')

# Labels
ax.set_xlabel('X')
ax.set_ylabel('Y')
ax.set_zlabel('Z')
ax.set_title("Coplanar Vectors and Enclosing Plane")

# Show legend box
ax.legend()

# ==== Save the figure ====
plt.savefig("coplanar_vectors_plane.png", dpi=300, bbox_inches='tight')

plt.show()
```