4.3.56

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Question

Find the equation of the plane with intercepts 2, 3 and 4 on the x, y and z - axis respectively.

The intercepts define three points on the plane, which we can label A, B, and C.

Point	Vector
А	$\begin{pmatrix} 2 \\ 0 \\ 0 \end{pmatrix}$
В	$\begin{pmatrix} 0\\3\\0 \end{pmatrix}$
С	$\begin{pmatrix} 0 \\ 0 \\ 4 \end{pmatrix}$

Table: Answers

We can find two direction vectors, m_1 and m_2 , that lie in the plane:

$$\mathbf{m_1} = \mathbf{B} - \mathbf{A} = \begin{pmatrix} 0 - 2 \\ 3 - 0 \\ 0 - 0 \end{pmatrix} = \begin{pmatrix} -2 \\ 3 \\ 0 \end{pmatrix}$$
$$\mathbf{m_2} = \mathbf{C} - \mathbf{A} = \begin{pmatrix} 0 - 2 \\ 0 - 0 \\ 4 - 0 \end{pmatrix} = \begin{pmatrix} -2 \\ 0 \\ 4 \end{pmatrix}$$

The normal vector to the plane, \mathbf{n} , is found by the cross product of these two vectors.

$$\mathbf{n} = \mathbf{m_1} \times \mathbf{m_2} = \begin{pmatrix} -2 \\ 3 \\ 0 \end{pmatrix} \times \begin{pmatrix} -2 \\ 0 \\ 4 \end{pmatrix}$$
$$= \begin{pmatrix} (3)(4) - (0)(0) \\ (0)(-2) - (-2)(4) \\ (-2)(0) - (3)(-2) \end{pmatrix} = \begin{pmatrix} 12 \\ 8 \\ 6 \end{pmatrix}$$

We can simplify the normal vector to $\mathbf{n} = \begin{pmatrix} 6 \\ 4 \\ 3 \end{pmatrix}$. The equation of the plane

is then given by:

$$\mathbf{n}^T(\mathbf{x} - \mathbf{A}) = 0$$

Substituting the numerical values, where $\mathbf{x} = [x, y, z]^T$:

$$\begin{pmatrix} 6 & 4 & 3 \end{pmatrix} \begin{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} - \begin{pmatrix} 2 \\ 0 \\ 0 \end{pmatrix} \end{pmatrix} = 0$$

$$\implies \begin{pmatrix} 6 & 4 & 3 \end{pmatrix} \begin{pmatrix} x - 2 \\ y \\ z \end{pmatrix} = 0$$

$$\implies 6(x - 2) + 4y + 3z = 0$$

$$\implies 6x - 12 + 4y + 3z = 0$$

$$\implies 6x + 4y + 3z = 12$$

C Code

```
#include <stdio.h>
typedef struct {
   double x, y, z;
} Vector;
typedef struct {
   double a, b, c, d;
} Plane;
Vector subtract vectors(Vector v1, Vector v2) {
   Vector result;
   result.x = v1.x - v2.x;
   result.y = v1.y - v2.y;
   result.z = v1.z - v2.z;
   return result;
```

C Code

```
Vector cross product(Vector v1, Vector v2) {
   Vector result;
   result.x = v1.y * v2.z - v1.z * v2.y;
   result.y = v1.z * v2.x - v1.x * v2.z;
   result.z = v1.x * v2.y - v1.y * v2.x;
   return result;
double dot_product(Vector v1, Vector v2) {
   return v1.x * v2.x + v1.y * v2.y + v1.z * v2.z;
```

C Code

```
Plane find_plane_equation(Vector p1, Vector p2, Vector p3) {
   Vector m1 = subtract vectors(p2, p1);
   Vector m2 = subtract vectors(p3, p1);
   Vector normal = cross product(m1, m2);
   double d = dot product(normal, p1);
   Plane result;
   result.a = normal.x:
   result.b = normal.y;
   result.c = normal.z:
   result.d = d;
   return result;
```

Python Code

```
import numpy as np
 import matplotlib.pyplot as plt
 def get z(x, y):
     return (12 - 6*x - 4*y) / 3
 x vals = np.linspace(0, 4, 10)
 y_{vals} = np.linspace(0, 5, 10)
|x_grid, y_grid = np.meshgrid(x_vals, y_vals)
 z_grid = get_z(x_grid, y_grid)
 fig = plt.figure(figsize=(8, 6))
 ax = fig.add_subplot(111, projection='3d')
 ax.plot_surface(x_grid, y_grid, z_grid, alpha=0.7, cmap='viridis'
```

Python Code

```
ax.scatter(2, 0, 0, color='red', s=100, label='Intercept
      (2.0.0)'
ax.scatter(0, 3, 0, color='green', s=100, label='Intercept
    (0,3,0))
ax.scatter(0, 0, 4, color='blue', s=100, label='Intercept (0,0,4)
ax.set xlabel('X-axis')
ax.set_ylabel('Y-axis')
ax.set zlabel('Z-axis')
ax.set title('Plane: 6x + 4y + 3z = 12')
ax.legend()
plt.grid(True)
plt.show()
```

Plot

