Documentation for mean-field model (Matlab)

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1 Overview of functions

The following Matlab functions constitute the mean-field model of mitotic spindle rotation in *C. elegans* embryos.

Main.m: This is the function that implements the full model. That is, it calculates the potential energy $W(\alpha)$ at angles α from 0 and π . See §1.1 for more information about the step size of α . This function takes inputs on both the cell geometry (a and b) and the setup of the spindle (ctr, phi_1, phi_2, push, AP, LD, elas; see §1.1). The output of Main.m is the energy landscape W over the range of angles $A = [0, \pi]$ in vector form. It also plots W against A.

MainWithFilter.m: This function is the exact same as Main.m, except that it puts the output W through a high-pass filter (to clean up the curve) before plotting. Note that this file is **only useful for the symmetric well case**: the high-pass filter loses all information about asymmetry in the wells.

parameters.m: This script contains all the fixed parameters in the model (see §1.1). It is called by Main.m at the beginning of the file; it is also called by work.m, torque.m, and find_prob.m. It does not take any inputs and its output is to load the fixed parameters onto the workspace.

alpha_halfplane.m: This function is called by Main.m before calculating W. Its inputs are a, r_N, ctr, phi_1, and phi_2 (§1.1). The purpose of this function is to calculate the angles at which the leading and lagging ends of each MT aster are above or below the x-axis (for ease of future calculations in torque.m). It saves these angles to two .mat files, halfplane1.mat and halfplane2.mat, which are later loaded by torque.m.

equal_arcsCircle.m: This function is called by Main.m in the case that the cell is perfectly circular (i.e. aspect ratio = 1 or a = b). It calculates the locations of the cortical dyneins in terms of the parameter t that parameterizes the boundary of the cell. The output of this function is a vector of these positions.

equal_arcsHannah.m: This function is called by Main.m in the case that the cell is perfectly circular (i.e. aspect ratio $\neq 1$ or $a \neq b$). It calculates the locations of the cortical dyneins in terms of the parameter t that parameterizes the boundary of the cell. The output of this function is a vector of these positions.

let99.m: This function calculates the beginning and end positions of the Let-99 push band in the case that the band is present (i.e. push = 'on', see $\S1.1$). Again, these positions are in terms of the parameter t that parameterizes the boundary of the cell. Given the cell resolution (a and b) and a fixed arc-length arc, it outputs a vector tvec that contains the beginning and end positions of the push band. In the case that there is no push band present (i.e. push = 'off', see $\S1.1$), tvec is an empty vector.

work.m: This is the function called by Main.m that actually calculates the energy landscape. It has the same inputs as Main.m plus an additional input alpha, which is the current angular orientation of the spindle. It calculates the potential energy of the spindle at alpha by approximating the integral of the torque function from angle 0 to angle alpha. This integral is approximated numerically by a Riemann sum of step size d_alpha (see §1.1) that calls torque.m.

torque.m: This function, which has all the same inputs as work.m, calculates the total torque on the spindle at a given angular orientation alpha; this value is its output. The following seven functions (find_env_pi.m to find_pull.m) are the helper functions that allow it to do so.

find_env_pi.m: This function finds the beginning and end positions of the MT aster along the cell boundary (in terms of the boundary parameter t) given that the aster's angular spread phi_i is equal to π . Its inputs are a, b, r_N, and ctr, and its output are the beginning and end points of the aster. It finds these points by selecting the correct roots from symbolic solutions for the intersection of the line defined by the aster spread and the cell boundary (Figure 1). This function is called separately for each of the upper and lower (or "mother" and "daughter") asters.

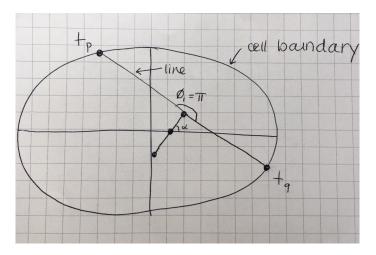


Figure 1: Geometric setup for the function find_env_pi.m.

find_env_notpi.m: This function finds the beginning and end positions of the MT aster along the cell boundary (in terms of the boundary parameter t) given that the aster's angular spread phi_i is less than π . It takes the same inputs as find_env_pi.m plus the aster spread phi_i . It also takes the angles from alpha_hlafplane as inputs. It makes calls to find_env_pi.m and find_end.m, and uses the following geometric setup to compute the beginning and end of the MT aster with correct spread phi_i (Figure 2). This function is also called separately for each of the upper and lower (or "mother" and "daughter") asters.

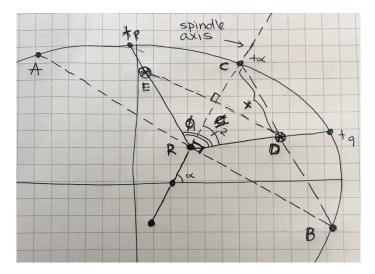


Figure 2: Geometric setup for the function find_env_notpi.m.

find_end.m: This function finds the point D in the above configuration (Figure 2). It does so by finding the line segment with length x (found by the law of sines as we know |CR|, |CB|, \(\text{RCD}, \) and \(\text{DCR} = \text{phi_i/2} \)) in the direction of the line segment CB (Figure 2). Call this segment CD (Figure 2). Using geometric properties of vector addition, we obtain the point (i.e. vector) D by adding the vector C to the vector CD (Figure 2). This point D is crucial for finding the lagging endpoint of the MT aster because it allows the function find_env_notpi.m to define a line from the MTOC (point R) to the cell boundary that makes angle phi_i/2 with the spindle axis (Figure 2). The function find_env_notpi.m then reflects D across the spindle axis to the point E, and similarly finds the leading endpoint of the aster (Figure 2).

find_dyneins.m: Given the endpoints t_p and t_q of the MT aster (along with the vector of all dynein positions set_psi and some other inputs), this function finds the dynein positions that are within the MT aster. It stores these dyneins in the output vector env_d It also takes the Let-99 band positions tvec, and places the dynein positions in the Let-99 band that overlap with the aster in a separate vector let (so these positions are NOT included in env_d). This output vector now contains the positions along the boundary in the Let-99 band where MTs will grow up against the boundary (i.e. no dyneins) and create pushing forces.

find_sintheta.m: This function finds the sine of the angle theta_i made by each MT in the aster and the spindle axis. We need the sines of these angles in order to calculate the torque on the spindle center (i.e. the pronucleus). This function is called separately for each MT aster, as well as for the MTs making contact with dyneins (env_d) versus those in the push band (let). This function also implements MT sliding and elasticity. If this feature is present (i.e. elas = 'on'), then this function perturbs each angle theta_i with a random angle omega (uniformly sampled from the angle between the two adjacent dynein locations) before calculating the sines.

find_prob.m: This function is for implementing the anterior-to-posterior difference in MT-dynein binding probabilities (which itself is for scaling down the anterior forces). If this difference is present (i.e. AP = 'on'), it loops through the vector of dynein positions env_d and builds a vector myProbs of corresponding binding probabilities depending on if the dynein is in the anterior region or the posterior region. The anterior-to-posterior split is defined at the 60:40 egglength mark (0.2*a), and should be kept as such unless we get new experimental findings. Similarly, we want to fix the posterior and anterior binding probabilities (P-p and P-a, respectively) fixed, as these are taken from the original study by Coffman et al. Otherwise, if there is no anterior-to-posterior difference in place (i.e. AP = 'off'), then the vector of probabilities contains all ones. This function is called separately for each MT aster.

find_pull.m: This function is for implementing length dependent pulling forces. If length dependence is in place (i.e. LD = 'on'), then it loops through the vector of dynein positions env_d and builds a vector myForces of corresponding pulling forces. If not (i.e. LD = 'off'), then the vector of pulling forces contains all ones (i.e. pulling force is constant and equal to 1).

ellipse.m: This function is not used in calculating the energy landscape, but is used for plotting purposes. Specifically, it plots the boundary of the cell given the dimensions a and b. There is a commented out section of code in torque.m that calls this function as part of a plot of the complete spindle setup (dynein locations, MT asters, etc.). This function is called separately for each MT aster.

PDFplotCTRL.m: Given the ellipse major axis a, this function plots the steady state p.d.f. $p(\alpha)$ corresponding to $W(\alpha)$, for the case that b = 15 and the asters are symmetric (control case, i.e. no push no AP, no LD, no elas). It does so by loading the .mat file of scale factors (k = k_1*Wmax, where Wmax is the maximum value of W, and k_1 is a pre-fit parameter; see §2) and plotting the function $p(\alpha) = Ne^{-kW(\alpha)}$ (N is a normalization constant).

1.1 Inputs & parameters

```
a: Ellipse/cell major axis (i.e. half-length of x-axis, values between 15-30)
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b: Ellipse/cell minor axis (i.e. half-length of y-axis, values between 15-25)

ctr: Spindle-center position x-coordinate

phi_1: Upper MT aster spread, between 0 and π

phi_2: Lower MT aster spread, between 0 and π

push: String ('on' or 'off'), for push band

AP: String ('on' or 'off'), for anterior-to-posterior difference

LD: String ('on' or 'off'), for length-dependent pulling forces

elas: String ('on' or 'off'), for MT slipping and elasticity

r_N: Nuclear/spindle radius

b_basal: Set equal to 15 (wild type = 15, where a = 25)

a_basal: Set equal to 15 (for wild type when elongating y-axis)

a_WTscale: Wild type dimension (= 40) for scaling up volume

b_WTscale: Wild type dimension (= 24) for scaling up volume

N_d_basal: Number of cortical dyneins in control case (= 128)

arc: Full arc length of Let-99 band

d_alpha: Step size for computing energy landscape

end_alpha: Maximum value of alpha for energy landscape

A: Range of alpha values from 0 to end_alpha with step size d_alpha

phi_pi: For when MT aster spread is equal to π (set = π)

rho_asymm: Angular MT density for asymmetric envelope (from compt. model)

rho_symm: Angular MT density for symmetric envelope (from compt. model)

myCutoff: Cutoff (x-coordinate) for 60:40 egg-length mark (= 0.2*a)

 P_p : Posterior binding probability (=1)

P_a: Anterior binding probability (= 0.65, from compt. model)

For asymmetric MT asters, specifically for a leading upper aster, the standard values are $\phi_1 = 2.324$ and $\phi_2 = 2\pi/3$. Below are examples of sample commands with different inputs.

```
>> Main(25, 15, 0, 2*pi/3, 2*pi/3, 'off','off','off','off')
```

Figure 3: Command for a cell with aspect ratio 25:15, on-center spindle, symmetric MT asters (spread of $2\pi/3$), no push bands, no anterior-to-posterior asymmetry, no length dependent pulling forces, and no MT elasticity.

```
>> Main(28, 15, 8, 2.324, 2*pi/3, 'off', 'on', 'off', 'off')
```

Figure 4: Command for a cell with aspect ratio 28:15, off-center spindle (shifted right by 8 units), asymmetric MT asters ($\phi_1 = 2.324$, $\phi_2 = 2\pi/3$), no push bands, anterior-to-posterior asymmetry, no length dependent pulling forces, and no MT elasticity.

```
>> Main(30, 15, 10, 2.324, 2*pi/3, 'off', 'off', 'on', 'on')
```

Figure 5: Command for a cell with aspect ratio 30:15, off-center spindle (shifted right by 10 units), asymmetric MT asters ($\phi_1 = 2.324$, $\phi_2 = 2\pi/3$), no push bands, no anterior-to-posterior asymmetry, length dependent pulling forces, and no MT elasticity.

1.2 .mat files

dyneins16to30.mat: Contains a cell of vectors, where cell index a corresponds to the vector of dynein locations for given input a to Main.m (b is fixed at 15).

dyneins_b16to35.mat: Contains a cell of vectors, where cell index b corresponds to the vector of dynein locations for given input b to Main.m (a is fixed at 15).

dyneinsAR1p67VolScaleBy1p6.mat: Contains two different vectors of dynein locations specific to a cell with a = 40 and b = 24. These dimensions give us wild type aspect ratio (AR = 1.67) but with cell volume scaled up (from the usual a = 25 and b = 15) by a factor of 1.6. The first vector of dynein positions, scaleDynWithVol, is for when we scale the number of dyneins with total arc length so that the arc length between dyneins remains a constant 1. The second vector of dynein positions, fixDynAt128, is for when we fix the number of dyneins to be 128, which is the same number of dyneins as when a = 25 and b = 15.

kValsCtrlAR1p06to2.mat: Contains vector kvec of scale factors k for PDFplotCTRL.m.

2 Fitting the parameter k_1

Earlier work with this model included fitting the unknown parameter k_1, where

$$k_1 = \frac{1}{\eta D}$$
, $\eta = \text{drag coefficient}$, and $D = \text{diffusion coefficient}$.

This fitting was done using the file plotPDF.m. This function takes as input a vector of final angles psi from the computational model and the maximum value of the energy landscape Wmax. It calls the function nhist (written by Johnathan Lansey, open source) to plot a normalized histogram of final angles. Finally, it fits the steady-state p.d.f,

$$p(\alpha) = e^{-\mathbf{k} \cdot \mathbf{1} W(\alpha)},$$

to this histogram using a least-squares method (Matlab's lsqcurvefit function) with respect to the unknown parameter $k_{-}1$.