



EECS 245 Fall 2025

Math for ML

Lecture 14: Inverses, Projections

→ Read : Ch 2.9 (new examples added!)
Ch 2.10 (in progress)

Agenda

- ① Recap : Inverses (review of last lecture and lab)
- ② Projecting onto the span of multiple vectors

↓ final idea before we go
back to "core"
machine learning!

Announcements :

- ① HW 6 due **Monday** → do it, don't drop it!
- ② Check the "Grade Report" on Gradescope

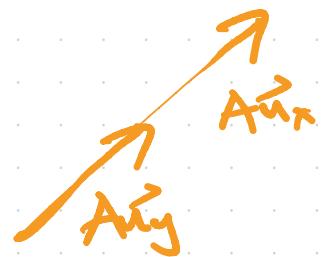
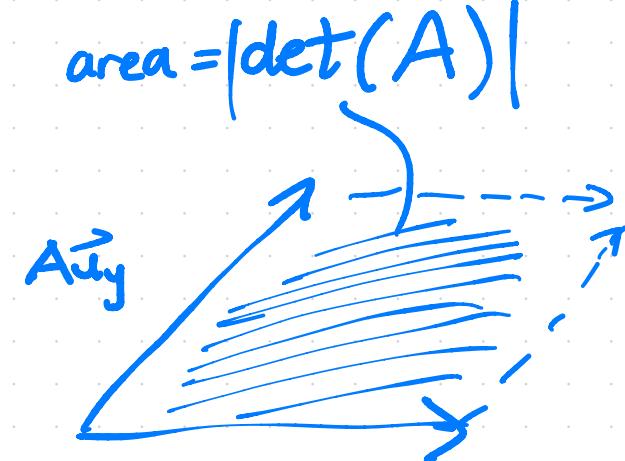
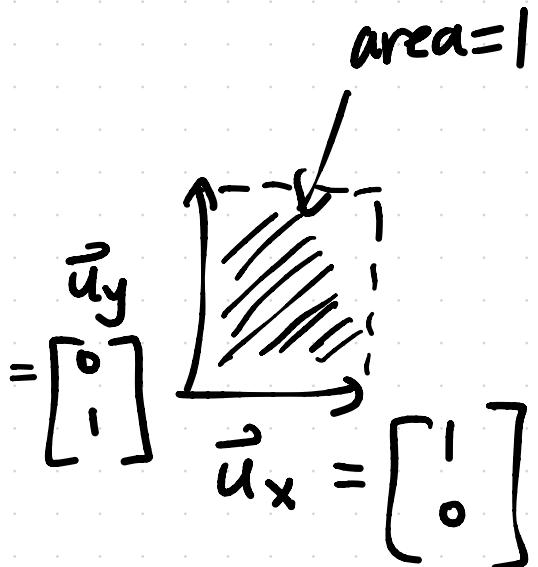
Inverses

Suppose A is an $n \times n$ matrix
that is invertible

\Rightarrow this means there exists another ^{$n \times n$} matrix
 B such that

$$\underbrace{AB = BA}_{B \text{ is } A\text{'s}} = I = \begin{bmatrix} 1 & & 0 \\ 0 & \ddots & \vdots \end{bmatrix}$$

"right inverse"



$\det(A) = 0 \Rightarrow A'$'s columns
are dependent $\Rightarrow A$ not invertible

If A^2 is invertible, prove A is invertible

Three approaches : ① Constructing A 's inverse
② Null spaces
③ Determinant

① Constructing A's inverse

given A^2 invertible : what does that mean?

means there exists matrix B where

$$A^2 B = B A^2 = I$$

$$\begin{aligned} AAB &= I \quad ① \\ BAA &= I \quad ② \end{aligned}$$

can we use this to find A's inverse?

$$\text{In } ①, \quad A(AB) = I \rightarrow A^{-1} = AB$$

$$\text{in } ②, \quad (BA)A = I \rightarrow A^{-1} = BA$$

→ which is it? AB or BA ?

→ in general, they are different, but here, $AB = BA$

proof that here, $AB = BA$

start with BA

$$I^{-1} = I$$

$$\begin{aligned} BA &= BAI = \underbrace{BAA}_{=I, \text{ from last slide}} AB = \underbrace{(BAA)}_{\text{also } I!} AB = IAB \\ &= AB \end{aligned}$$

so, $A^{-1} = AB = BA$

② Null spaces

if A^2 invertible, then A is invertible

start by assuming the statement isn't true,

assume A^2 invertible but A isn't

→ if A isn't invertible, then

there exists some $\vec{x} \neq \vec{0}$ where

$$A\vec{x} = \vec{0}$$

$$\rightarrow \text{but then } AA\vec{x} = A\vec{0} = \vec{0} \rightarrow A^2\vec{x} = \vec{0}$$

→ contradiction since we assumed A^2 inv.

recall,

rank

+

dim nullsp

=

cols

③ Determinants

A^2 invertible $\rightarrow A$ invertible

if A^2 invertible, $\det(A^2) \neq 0$

$$\det(A^2) \neq 0$$

$$\det(AA) \neq 0$$

$$\det(A) \det(A) \neq 0$$

$$[\det(A)]^2 \neq 0$$

$\det(A) \neq 0 \rightarrow A$ is invertible

$$\left\{ \begin{array}{l} \det(AB) \\ = \det(A)\det(B) \\ \det(A+B) \\ \neq \det(A)+\det(B) \end{array} \right.$$

If $A \begin{bmatrix} 3 \\ 1 \\ -1 \end{bmatrix} = \begin{bmatrix} 9 \\ 4 \\ 3 \end{bmatrix}$ and $A \begin{bmatrix} 4 \\ 0 \\ 2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$,

lin comb of
A's cols

is A invertible?

No! $\begin{bmatrix} 4 \\ 0 \\ 2 \end{bmatrix} \in \text{nullsp}(A)$, which
means $\dim(\text{nullsp}(A)) \geq 1$,
means $\text{rank}(A) \leq 2$

Unit vector \vec{u}

consider the equation

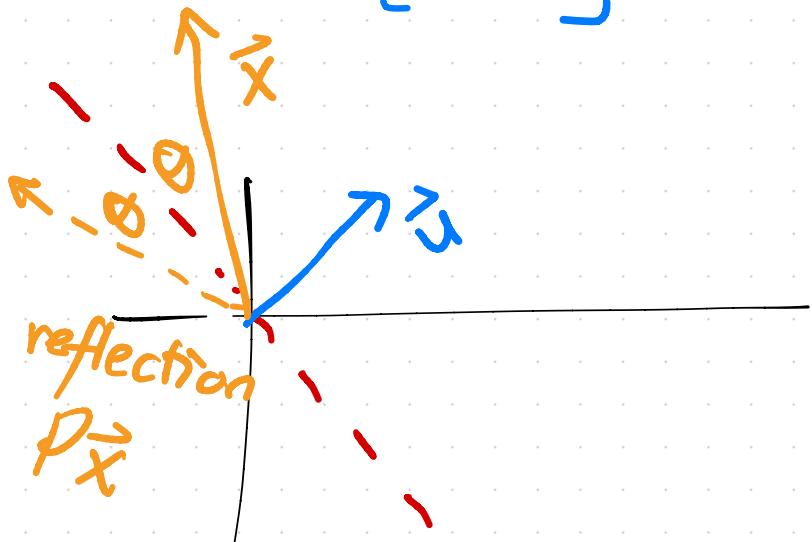
e.g. $\vec{u} = \begin{bmatrix} 3/5 \\ 4/5 \end{bmatrix}$

$$\vec{u} \cdot \vec{x} = 0$$

= line
 $y = -\frac{3}{4}x$

$$\frac{3}{5}x + \frac{4}{5}y = 0$$

$$y = -\frac{3}{4}x$$



$$P = I - 2 \underbrace{\vec{u} \vec{u}^T}_{n \times n \text{ matrix}}$$

Householder
"reflection
matrix"

$P\vec{x}$ is the reflection of \vec{x} across the line/plane!

$$\vec{u} \cdot \vec{x} = 0$$

P is orthogonal!

$$\underbrace{PP^T = P^T P = I}_{\text{equivalent to}}$$

equivalent to

$$P^{-1} = P^T$$

also, $P^T = P \Rightarrow P^{-1} = P^T = P \Rightarrow P$ is its own inverse!

$$P^T P = \underbrace{(I - 2\vec{u}\vec{u}^T)}_{P^T}^T (I - 2\vec{u}\vec{u}^T)$$

$$= (I^T - 2(\vec{u}\vec{u}^T)^T) (I - 2\vec{u}\vec{u}^T)$$

$$= \underbrace{(I - 2\vec{u}\vec{u}^T)}_P (I - 2\vec{u}\vec{u}^T)$$

$$= I - 2\vec{u}\vec{u}^T - 2\vec{u}\vec{u}^T + 4\vec{u}\underbrace{\vec{u}^T}_{=I^2}\vec{u}\vec{u}^T$$

$$= I \quad \checkmark$$

$$(AB)^T$$

$$= B^T A^T$$

$$(\vec{u}\vec{u}^T)^T$$

$$= (\vec{u}^T)^T \vec{u}^T$$

$$= \vec{u}\vec{u}^T$$

orthogonal matrix $Q \in \mathbb{R}^{n \times n}$

$$\|Q\vec{x}\| = \|\vec{x}\|$$

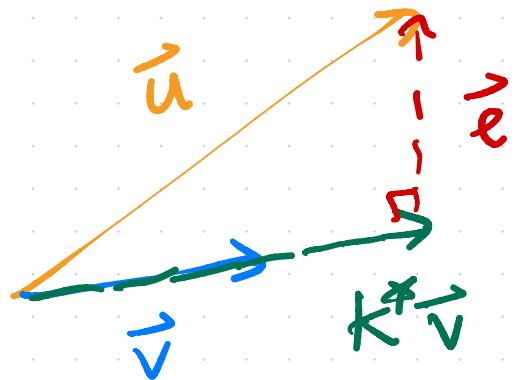
orthogonal matrices preserve length!
only change direction

$$\vec{A}\vec{x} = \vec{b}$$

$$\vec{x} = \vec{A}^{-1}\vec{b}$$

Projections

"the approximation problem"



choose k^* such that

$$\vec{e} = \vec{u} - k\vec{v}$$

orthogonal to \vec{v}

Consider the vectors

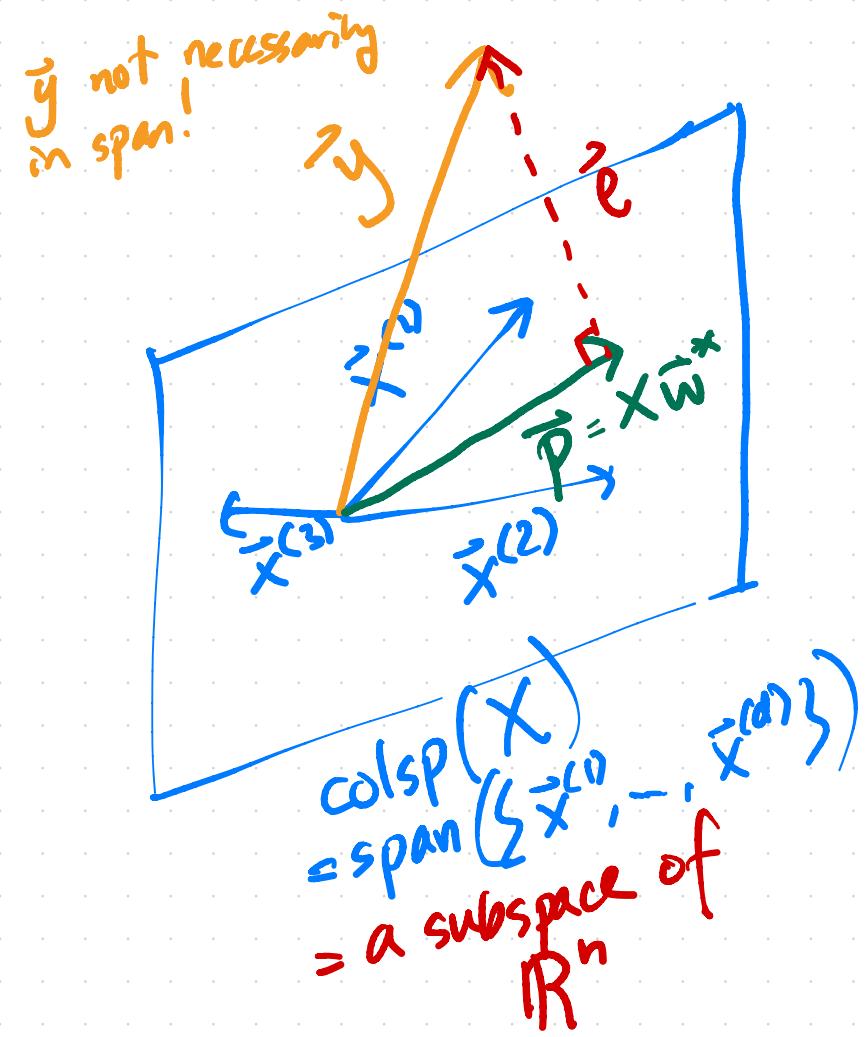
$$\vec{x}^{(1)}, \vec{x}^{(2)}, \dots, \vec{x}^{(d)} \in \mathbb{R}^n$$

Among all vectors in

$$\underbrace{\text{span}(\vec{x}^{(1)}, \dots, \vec{x}^{(d)})}$$

which is closest to \vec{y} ?

this  span is a subspace
of \mathbb{R}^n



$$X = \begin{bmatrix} 1 & 1 & \dots & 1 \\ \vec{x}^{(1)} & \vec{x}^{(2)} & \dots & \vec{x}^{(d)} \\ 1 & 1 & \dots & 1 \end{bmatrix}_{n \times d}$$

vectors in $\text{colsp}(X)$ are of the form

$X\vec{w}$, where $\vec{w} \in \mathbb{R}^d$
of all $X\vec{w}$'s, which is closest to \vec{y} ?

choose \vec{w}^* so that

$$\vec{e} = \vec{y} - X\vec{w}^*$$

is orthogonal to

$\text{colsp}(X)$

(equivalent to being orthogonal to
each of X 's columns)

choose
 \vec{w}
so that

$$\vec{X}^{(1)} \cdot (\vec{y} - \vec{X}\vec{w}) = 0$$

$$\vdots$$

$$\vec{X}^{(d)} \cdot (\vec{y} - \vec{X}\vec{w}) = 0$$

$$\vec{X}^T (\vec{y} - \vec{X}\vec{w}) = \vec{0} = \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix}$$