



EECS 245 Fall 2025

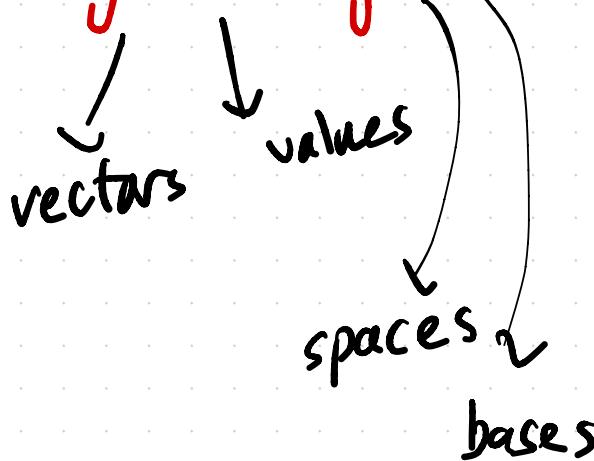
Math for ML

Lecture 20: Eigenvalues and Eigenvectors, Continued
Read Chapter 5.1!

Agenda

all about

eigen-things



Announcements

- MT 2 scores on Gradescope
- 1 on 1 check-ins available
- HW 10 coming Saturday

$$X^T X + \lambda I$$

why is this always invertible?

square, $n \times n$ matrix A

think about linear transformations
from $\mathbb{R}^n \rightarrow \mathbb{R}^n$

(non-zero)

eigenvector \vec{v} :

$$A\vec{v} = \lambda\vec{v}$$

when multiplied by A, \vec{v} 's direction
didn't change; it was just
scaled by a factor of

eigenvalue

$$A = \begin{bmatrix} 1 & 2 \\ 2 & 1 \end{bmatrix}$$

if \vec{v} is an eigenvector of A ,
so is $c\vec{v}$, for any $c \neq 0$

Let $\vec{v} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$

$$A\vec{v} = \begin{bmatrix} 3 \\ 3 \end{bmatrix} = 3 \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$\Rightarrow \vec{v}_1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$ eigenvector of A

with $\lambda_1 = 3$

$$\begin{aligned} A \begin{bmatrix} -1 \\ -1 \end{bmatrix} &= \begin{bmatrix} -3 \\ -3 \end{bmatrix} \\ &= 3 \begin{bmatrix} -1 \\ -1 \end{bmatrix} \end{aligned}$$

\Rightarrow so $\vec{v} = \begin{bmatrix} -1 \\ -1 \end{bmatrix}$

is also

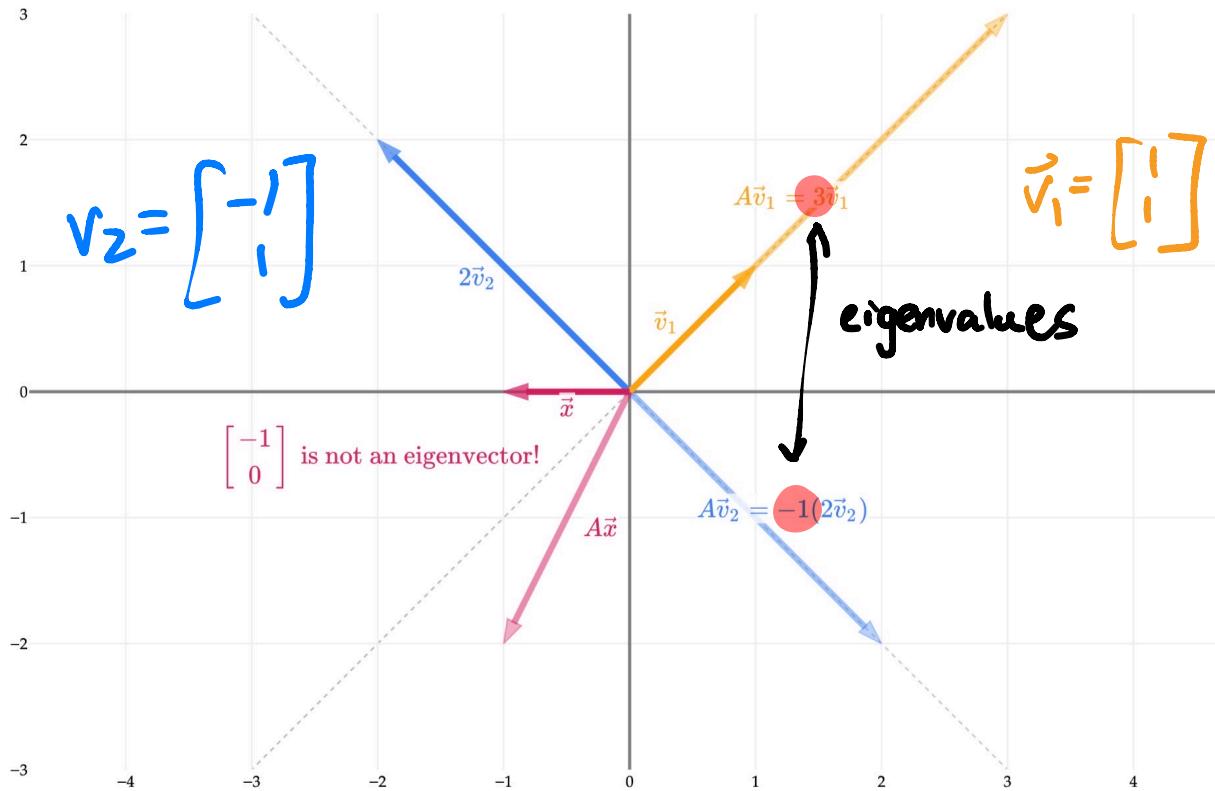
eigvec of A
with $\lambda = 3$

$$\underbrace{\begin{bmatrix} 1 & 2 \\ 2 & 1 \end{bmatrix}}_A \begin{bmatrix} -1 \\ 1 \end{bmatrix} = \begin{bmatrix} -1+2 \\ -2+1 \end{bmatrix} = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

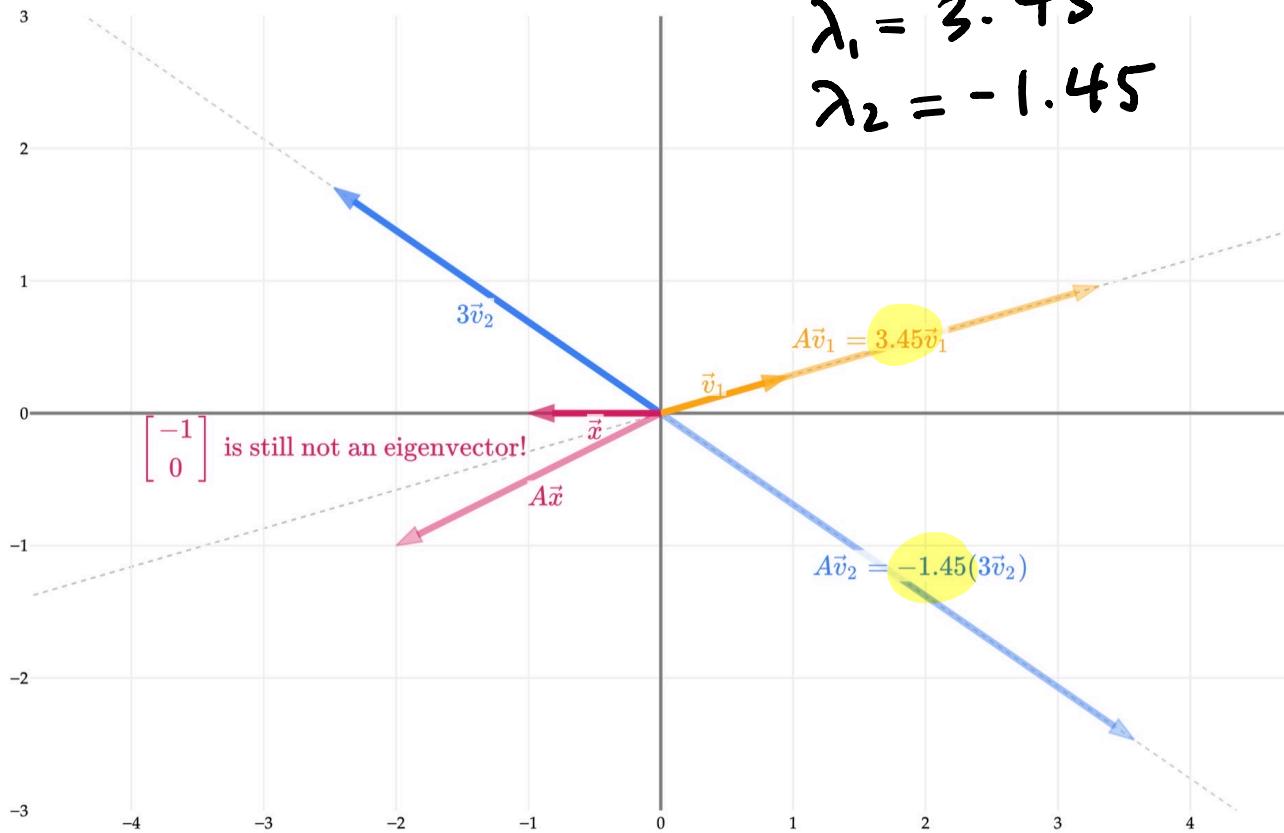
$$= (-1) \begin{bmatrix} -1 \\ 1 \end{bmatrix}$$

so, $\vec{v}_2 = \begin{bmatrix} -1 \\ 1 \end{bmatrix}$ is an eigenvector
corresponding to $\lambda_2 = -1$

Visualizing the eigenvectors of $A = \begin{bmatrix} 1 & 2 \\ 2 & 1 \end{bmatrix}$



Visualizing the eigenvectors of $B = \begin{bmatrix} 2 & 5 \\ 1 & 0 \end{bmatrix}$



Here,
 $\lambda_1 = 3.45$
 $\lambda_2 = -1.45$

```
B = np.array([[2, 5],  
             [1, 0]])  
  
np.linalg.eig(B)
```

```
EigResult(eigenvalues=array([ 3.44948974, -1.44948974]), eigenvectors=array([[  
    0.96045535, -0.82311938],  
    [ 0.27843404,  0.56786837]]))
```

\vec{v}_1

\vec{v}_2

cols are the eigvecs

observe: $\lambda_1 + \lambda_2 = 2$,

which is sum of diagonal!

True in general: sum of λ_i 's = sum of diagonal

$$A = \begin{bmatrix} 1 & 4 \\ 3 & 12 \end{bmatrix}$$

notice: $\text{rank}(A) = 1$

$$\lambda_1 = 13, \quad \lambda_2 = \frac{0}{?}$$

$$\vec{v}_1 = \begin{bmatrix} 1 \\ 3 \end{bmatrix}, \quad \vec{v}_2 = \begin{bmatrix} 4 \\ -1 \end{bmatrix}$$

\uparrow
basis for $\text{nullsp}(A)$!

$$\lambda_1 = 13 \quad / \quad \begin{bmatrix} 1 & 4 \\ 3 & 12 \end{bmatrix} \begin{bmatrix} x \\ z \end{bmatrix} = \begin{bmatrix} 13x \\ 13y \end{bmatrix}$$

$$x + 4y = 13x \Rightarrow 4y = 12x \\ \Rightarrow y = 3x$$

$$3x + 12y = 13y \quad \Downarrow \quad 3x = y$$

both same,
since any vector
on that line
works!

e.g. $x=1$, so $y=3$,
 $\text{so } \vec{v}_1 = \begin{bmatrix} 1 \\ 3 \end{bmatrix}$

A has an
eigenvalue of 0



A is not invertible

$$A = \begin{bmatrix} 1 & 2 \\ 2 & 1 \end{bmatrix} \quad \text{had}$$

$$\lambda_1 = 3 \text{ with } \vec{v}_1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$\lambda_2 = -1 \text{ with } \vec{v}_2 = \begin{bmatrix} -1 \\ 1 \end{bmatrix}$$

$$\begin{aligned} A^2 &= \begin{bmatrix} 1 & 2 \\ 2 & 1 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 2 & 1 \end{bmatrix} \\ &= \begin{bmatrix} 5 & 4 \\ 4 & 5 \end{bmatrix} \end{aligned}$$

What are the eigenvalues of

$$A^2 ?$$

What eigenvectors?

if \vec{v} is an eigenvector with eigenvalue λ
of A , then

$$\begin{aligned} A^2 \vec{v} &= AA\vec{v} = A(\lambda\vec{v}) = \lambda(A\vec{v}) \\ &= \lambda(\lambda\vec{v}) \\ &= \lambda^2 \vec{v} \end{aligned}$$

only one direction!

then, \vec{v} is an eigenvector
of A^2 with eigenvalue λ^2 .

possible for A^2 to have an
eigenvector

that A doesn't have

think: rotations

Characteristic
polynomial

$$p(\lambda) = \det(A - \lambda I)$$

degree n
polynomial

eigenvalues are solutions to

$$p(\lambda) = \det(A - \lambda I) = 0$$

$$A = \begin{bmatrix} 1 & 2 \\ 2 & 1 \end{bmatrix}$$

$$\det(A - \lambda I) = \det$$

$$\begin{bmatrix} 1-\lambda & 2 \\ 2 & 1-\lambda \end{bmatrix}$$

$$= (1-\lambda)^2 - 4$$

$$= \lambda^2 - 2\lambda + 1 - 4$$

$$= \lambda^2 - 2\lambda - 3 = (\lambda+1)(\lambda-3) = 0$$

$$\lambda = -1, \quad \lambda = 3$$

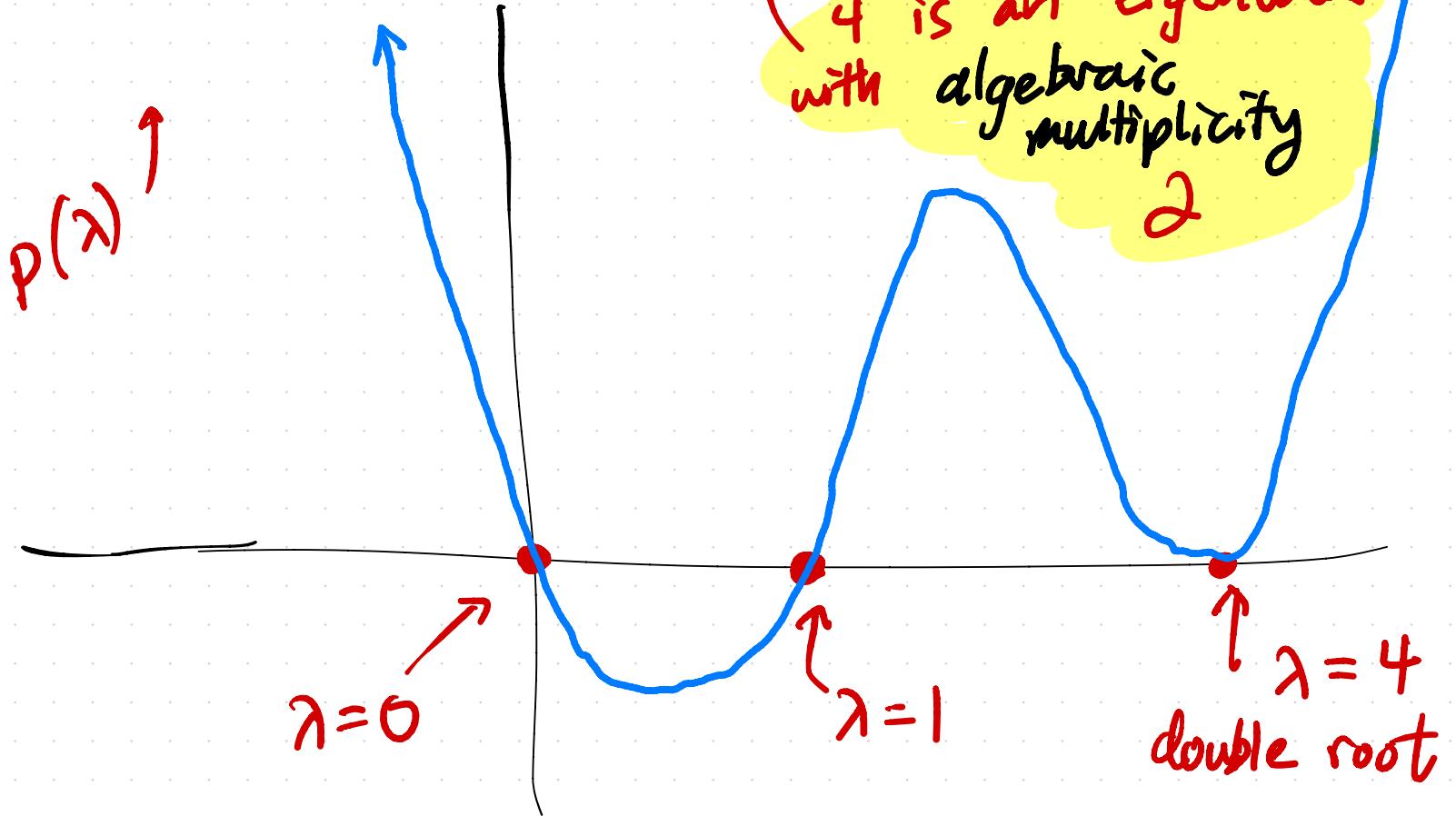
$$A = \begin{bmatrix} 4 & 0 \\ 1 & 4 \end{bmatrix}$$

$$P(\lambda) = \det(A - \lambda I) = \det \begin{pmatrix} 4-\lambda & 0 & 0 & 0 \\ 1-\lambda & 4-\lambda & 0 & 0 \\ 0 & 0 & 0-\lambda & 0 \\ 0 & 0 & 0 & 4-\lambda \end{pmatrix}$$

$$= (4-\lambda)(1-\lambda)(0-\lambda)(4-\lambda)$$

$$= \lambda(\lambda-1)(\lambda-4)^2$$

$$p(\lambda) = \lambda(\lambda-1)(\lambda-4)^2$$



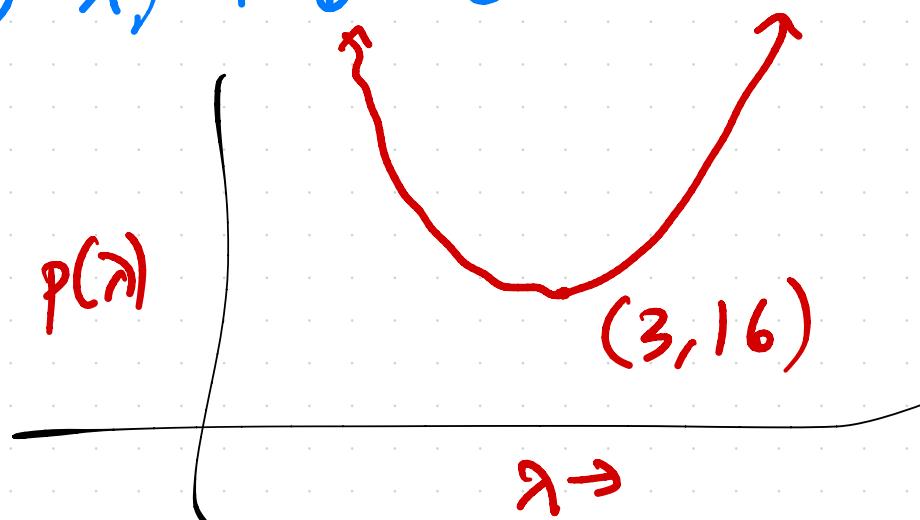
$$A = \begin{bmatrix} 3 & -4 \\ 4 & 3 \end{bmatrix} = 5 \begin{bmatrix} 3/5 & -4/5 \\ 4/5 & 3/5 \end{bmatrix}$$

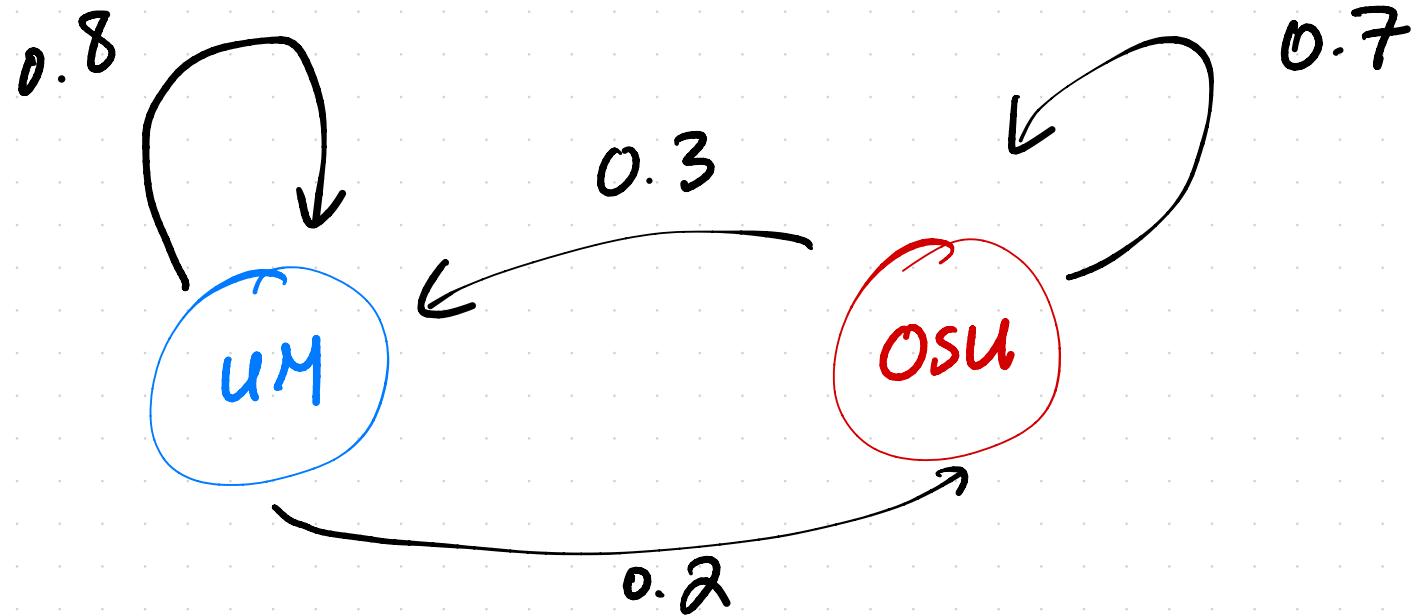
$$5e^{i\theta} \quad 5e^{-i\theta}$$

$$\theta = \cos^{-1}(3/5)$$

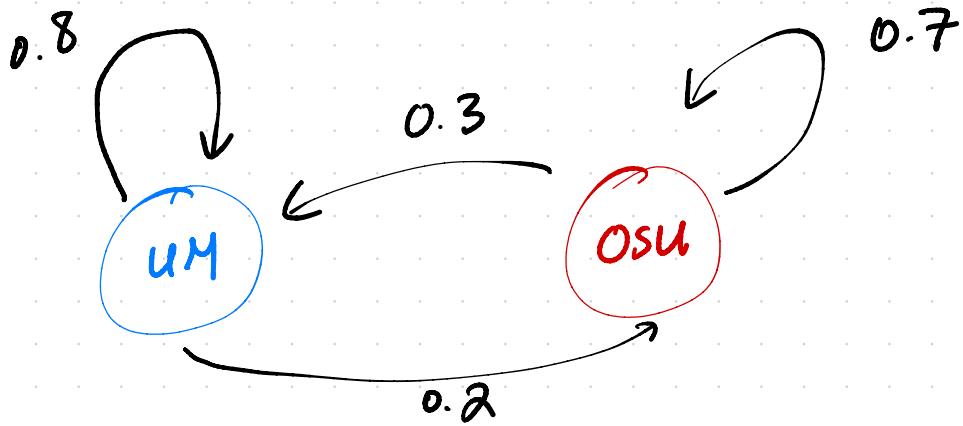
$$P(\lambda) = (3-\lambda)^2 + 16 = 0$$

rotation, then stretch





in the long run, what %
of games does Michigan win?



$$A = \begin{bmatrix} 0.8 & 0.3 \\ 0.2 & 0.7 \end{bmatrix}$$

$\rightarrow \text{UM}$
 $\rightarrow \text{OSU}$

$\text{UM} \rightarrow$ $\text{OSU} \rightarrow$

$$A = \begin{bmatrix} 0.8 & 0.3 \\ 0.2 & 0.7 \end{bmatrix}$$

$$\vec{x}_k = \begin{bmatrix} p(\text{Michigan})_k \\ p(\text{OSU})_k \end{bmatrix}$$

simulate!

$$\vec{x}_0 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$\vec{x}_1 = A \vec{x}_0 = \begin{bmatrix} 0.8 & 0.3 \\ 0.2 & 0.7 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 0.8 \\ 0.2 \end{bmatrix}$$

$$\vec{x}_2 = A \vec{x}_1 = \begin{bmatrix} 0.7 \\ 0.3 \end{bmatrix} = A^2 \vec{x}_0$$

in general,

$$\vec{x}_k = A^k \vec{x}_0$$

multiplying by A steps
one iteration

into the future !

dig idea

(see notes for
code) :

```
x_1 = [0.8 0.2]  
x_2 = [0.7 0.3]  
x_3 = [0.65 0.35]  
x_4 = [0.625 0.375]  
x_5 = [0.6125 0.3875]  
x_6 = [0.60625 0.39375]  
x_7 = [0.603125 0.396875]  
x_8 = [0.6015625 0.3984375]  
x_9 = [0.60078125 0.39921875]  
x_10 = [0.60039063 0.39960938]  
x_11 = [0.60019531 0.39980469]  
x_12 = [0.60009766 0.39990234]  
x_13 = [0.60004883 0.39995117]  
x_14 = [0.60002441 0.39997559]
```

$\vec{x}_k \rightarrow$ an eigen
vec



of A

(corresponding
to $\lambda = 1$)

$$A\vec{x} = \underline{1}\vec{x}$$

$$\vec{x} = \begin{bmatrix} 3/5 \\ 2/5 \end{bmatrix}$$

$$\begin{bmatrix} 0.8 & 0.3 \\ 0.2 & 0.7 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

$$0.8x_1 + 0.3x_2 = x_1$$

$$0.2x_1 + 0.7x_2 = x_2$$

$\vec{x} = c \begin{bmatrix} 3 \\ 2 \end{bmatrix}$,
 add cond
 that
 $x_1 + x_2 = 1$