

## Lab 5: Vector Spaces, Subspaces, and Bases

EECS 245, Fall 2025 at the University of Michigan

**due** by the end of your lab section on Wednesday, September 24th, 2025

**Name:** \_\_\_\_\_

**uniqname:** \_\_\_\_\_

Each lab worksheet will contain several activities, some of which will involve writing code and others that will involve writing math on paper. To receive credit for a lab, you must complete all activities and show your lab TA by the end of the lab section.

While you must get checked off by your lab TA **individually**, we encourage you to form groups with 1-2 other students to complete the activities together.

Acknowledgements: Activities 1, 3, and 6 are taken from [here](#), and Activity 4 is taken from *Linear Algebra* by Gilbert Strang. Consider looking at these sources for more practice problems.

## Activity 1: Linear Independence

Let  $\vec{w} = \begin{bmatrix} 1 \\ 1 \\ 0 \\ 0 \end{bmatrix}$ ,  $\vec{x} = \begin{bmatrix} 1 \\ 0 \\ 1 \\ 0 \end{bmatrix}$ ,  $\vec{y} = \begin{bmatrix} 0 \\ 0 \\ 1 \\ 1 \end{bmatrix}$ , and  $\vec{z} = \begin{bmatrix} 0 \\ 1 \\ 0 \\ 1 \end{bmatrix}$ .

- a) Find scalars  $a, b, c$ , and  $d$  such that  $a\vec{w} + b\vec{x} + c\vec{y} + d\vec{z} = \vec{0}$ , and at least one of the scalars is non-zero. By doing so, you're showing that  $\vec{w}, \vec{x}, \vec{y}, \vec{z}$  are linearly dependent.

- b) Find scalars  $A, B$ , and  $C$  such that  $\vec{z} = A\vec{w} + B\vec{x} + C\vec{y}$ . This is another way of showing that  $\vec{w}, \vec{x}, \vec{y}, \vec{z}$  are linearly dependent.

- c) Show that  $\text{span}(\{\vec{w}, \vec{x}, \vec{y}, \vec{z}\}) \neq \mathbb{R}^4$  by finding a vector  $\vec{v} \in \mathbb{R}^4$  such that  $\vec{v} \notin \text{span}\{\vec{w}, \vec{x}, \vec{y}, \vec{z}\}$ .

- d) Why is the fact that  $\text{span}(\{\vec{w}, \vec{x}, \vec{y}, \vec{z}\}) \neq \mathbb{R}^4$  enough to conclude that  $\vec{w}, \vec{x}, \vec{y}, \vec{z}$  are linearly dependent?

## Activity 2: Formal Definition of Linear Independence

Suppose  $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_d \in \mathbb{R}^n$ , and that  $\vec{b} \in \text{span}(\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_d\})$ .

- a) Give a one sentence English explanation of what it means for  $\vec{b} \in \text{span}(\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_d\})$ .

- b) Suppose that  $a_1\vec{v}_1 + a_2\vec{v}_2 + \dots + a_d\vec{v}_d = \vec{b}$  **and**  $c_1\vec{v}_1 + c_2\vec{v}_2 + \dots + c_d\vec{v}_d = \vec{b}$ , where at least one of the  $a_i$ 's is different from its corresponding  $c_i$ .

Using the formal definition of linear independence from [Chapter 2.4](#), determine whether or not  $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_d$  are linearly independent, and prove your answer.

- c) Find another set of coefficients  $k_1, k_2, \dots, k_d$  such that

$$k_1\vec{v}_1 + k_2\vec{v}_2 + \dots + k_d\vec{v}_d = \vec{b}$$

and at least one of the  $k_i$ 's is different from its corresponding  $a_i$  or  $c_i$ .

By doing this, you're showing that if there is at least one way to write  $\vec{b}$  as a linear combination of a set of vectors, then there are infinitely many ways to write  $\vec{b}$  as a linear combination of those vectors; there can't just be two or three ways to do it.

### Activity 3: Introduction to Subspaces

As discussed in [Chapter 2.6](#), a **subspace**  $S$  of a vector space  $V$  is a subset of  $V$  that itself is a vector space, contains the zero vector, and is **closed** under addition and scalar multiplication. That is, if you take any two vectors in  $S$ , any of their linear combinations must also be in  $S$ .

Only one of the following is a subspace of  $\mathbb{R}^3$ . Which one? Explain why the others are not subspaces.

The set of vectors  $\vec{v} = \begin{bmatrix} x \\ y \\ z \end{bmatrix}$  in  $\mathbb{R}^3$  such that

- (i)  $x + 2y - 3z = 4$
- (ii)  $\vec{v}$  is on the line  $L = \begin{bmatrix} 1 \\ -2 \\ 0 \end{bmatrix} + t \begin{bmatrix} 2 \\ 3 \\ 4 \end{bmatrix}, t \in \mathbb{R}$
- (iii)  $x + y + z = 0$  and  $x - y + z = 1$
- (iv)  $x = -z$  and  $x = z$
- (v)  $x^2 + y^2 = z$

### Activity 4: Finding Non-Examples of Subspaces

In this activity, you'll find sets of vectors in  $\mathbb{R}^2$  that satisfy some, but not all, of the requirements for a subspace. Think creatively, and since we're working in  $\mathbb{R}^2$ , visualize the vectors!

- a) Find a set of vectors in  $\mathbb{R}^2$  such that the sum of any two vectors  $\vec{u}$  and  $\vec{v}$  in the set is also in the set, but  $\frac{1}{2}\vec{v}$  is possibly not in the set.

- b) Find a set of vectors in  $\mathbb{R}^2$  such that  $c\vec{v}$  is in the set for any vector  $\vec{v}$  in the set and any scalar  $c$ , but the sum of any two vectors  $\vec{u}$  and  $\vec{v}$  in the set is possibly not in the set.

## Activity 5: Bases

Recall from Chapter 2.6 that a **basis** for a subspace  $S$  is a set of vectors that

1. span all of  $S$ , **and**
2. are linearly independent

In each part below, find **two different possible bases** for the given vector space, and state the **dimension** of the vector space. (Note that this is effectively what you're doing in [Problems 4 and 5 of Homework 4](#), we just hadn't introduced the term "basis" at that point.)

a)  $S = \text{span} \left( \left\{ \begin{bmatrix} 1 \\ 3 \\ 3 \end{bmatrix}, \begin{bmatrix} -3 \\ -9 \\ -9 \end{bmatrix}, \begin{bmatrix} 1 \\ 5 \\ -1 \end{bmatrix}, \begin{bmatrix} 2 \\ 7 \\ 4 \end{bmatrix}, \begin{bmatrix} 1 \\ 4 \\ 1 \end{bmatrix} \right\} \right)$

b)  $S = \left\{ \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} \mid v_1 = -v_2; v_1, v_2 \in \mathbb{R} \right\}$

c)  $S = \left\{ \begin{bmatrix} v_1 \\ v_2 \\ v_3 \\ v_4 \end{bmatrix} \mid v_4 = 0; v_1, v_2, v_3 \in \mathbb{R} \right\}$

## Activity 6: Intersections of Subspaces

Let:

- $M$  be the subspace of  $\mathbb{R}^4$  spanned by  $\begin{bmatrix} 1 \\ 1 \\ 1 \\ 0 \end{bmatrix}$  and  $\begin{bmatrix} 0 \\ -4 \\ 1 \\ 5 \end{bmatrix}$
- $N$  be the subspace of  $\mathbb{R}^4$  spanned by  $\begin{bmatrix} 0 \\ -2 \\ 1 \\ 2 \end{bmatrix}$  and  $\begin{bmatrix} 1 \\ -1 \\ 1 \\ 3 \end{bmatrix}$

- a) Find a vector that belongs to both  $M$  and  $N$ . (In other words, find a vector  $\vec{v}$  such that  $\vec{v} \in M$  and  $\vec{v} \in N$ .)

There are infinitely many answers; pick the answer with a first component of 1.

- b) Fill in the blanks: the set of all vectors that belong to both  $M$  and  $N$  is a subspace of  $\mathbb{R}^4$  with dimension \_\_\_\_\_.

Use the space below for scratch work.