

CHAPTER 1

INTRODUCTION

Wind power is a leading sustainable and eco-friendly energy solution, providing clean and renewable electricity. Vertical Axis Wind Turbines (VAWTs) are notable in the realm of wind energy technology for their adaptability to various wind conditions and smaller size. Yet, the whole capabilities of VAWTs can be realized by incorporating sophisticated control systems. This study presents a sophisticated wind energy system that utilizes microcontroller-based control, real-time voltage monitoring with an LCD display, and seamless connection with the Internet of Things (IoT).

With increasing global energy demands, it is crucial to improve the efficiency and intelligence of renewable energy sources. Conventional VAWTs are efficient but frequently do not have real-time monitoring and adaptive control systems. The system we suggest fills this need by integrating a microcontroller as the primary intelligence hub. The microcontroller controls the turbine's speed and makes dynamic adjustments using real-time data from an anemometer to ensure optimal performance in changing wind conditions.

An LCD display functions as the interface between the system and its operators, offering instant feedback on the generated voltage. Real-time monitoring is essential for analysing and debugging on-site, improving the system's accessibility and usability. Nevertheless, the invention does not cease at that point. Our solution overcomes geographical limitations by incorporating an Internet of Things (IoT) module, allowing for remote monitoring and control via cloud connectivity. Users can remotely access

vital turbine data, monitor performance patterns, and make necessary modifications from any place with internet connectivity.

The microcontroller's control logic serves as the system's central processing unit. This algorithm controls the turbine's rotating speed to ensure a smooth response to changes in wind speed. The objective is to increase voltage production to enhance the reliability and consistency of power output.

This fusion of hardware, software, and IoT connectivity marks the beginning of a new age in wind energy systems, turning them into smart and flexible entities. Stringent testing and calibration procedures have been put in place to ensure the precision and dependability of the voltage monitoring system, making it appropriate for use in various environments. Our proposed system offers a diverse and effective alternative for sustainable power generation, suitable for residential, commercial, and industrial installations.

1.1BACKGROUND

The escalating global demand for energy, coupled with growing environmental concerns, has intensified the exploration of sustainable and renewable energy sources. Among these sources, wind power has established itself as a key contributor to the transition towards cleaner electricity generation. Vertical Axis Wind Turbines (VAWTs) have garnered attention due to their unique design features, such as adaptability to turbulent wind conditions, reduced noise levels, and a smaller physical footprint compared to traditional horizontal axis counterparts.

While the inherent advantages of VAWTs make them a promising solution for harnessing wind energy, their performance can be significantly enhanced through the integration of advanced control systems. Conventional wind turbine systems often lack real-time monitoring and

adaptive control mechanisms, which are crucial for optimizing power output in varying wind conditions. Recognizing this gap, our research aims to bridge the divide between mechanical robustness and electronic intelligence in the context of VAWTs.

Microcontroller-based control systems offer a viable solution to address the limitations of traditional wind turbines. By incorporating a microcontroller as the central processing unit, we can implement sophisticated control algorithms that dynamically adjust the turbine's rotational speed based on real-time environmental data. This not only maximizes power generation efficiency but also ensures the longevity of the turbine by preventing undue stress on the mechanical components.

Moreover, real-time monitoring of crucial parameters, such as voltage output, is essential for assessing the performance and health of the wind turbine system. An LCD display integrated into the system provides a user-friendly interface for on-site monitoring, allowing operators to make informed decisions and promptly address any issues that may arise.

To further elevate the capabilities of our wind energy system, we propose the integration of the Internet of Things (IoT). The IoT module enables seamless communication between the wind turbine system and cloud-based platforms, facilitating remote monitoring and control. This not only expands the system's reach beyond physical boundaries but also opens avenues for data analytics, predictive maintenance, and continuous optimization.

In essence, the background of this research is rooted in the need to enhance the efficiency, intelligence, and accessibility of wind energy systems. By combining the mechanical prowess of VAWTs with the precision of microcontroller-based control, real-time monitoring through LCD displays, and the connectivity afforded by IoT, we aspire to contribute to a sustainable

and intelligent energy landscape. This background sets the stage for the detailed exploration and implementation of our proposed smart wind turbine system.

1.2 AIM

The primary aim of this research is to design, implement, and evaluate a smart Vertical Axis Wind Turbine (VAWT) system that integrates microcontroller-based control, real-time voltage monitoring through an LCD display, and Internet of Things (IoT) connectivity. The overarching goal is to enhance the efficiency, adaptability, and intelligence of the wind energy system for sustainable power generation.

1.3 OBJECTIVES

- Design and implement a microcontroller-based control system for the VAWT.
- Integrate an LCD display into the system to provide on-site real-time monitoring of the voltage generated by the wind turbine.
- Integrate an IoT module into the wind turbine system to establish connectivity with cloud-based platforms.

1.2 METHODOLOGY

We made the vertical axis wind turbine specifically for the center median of the highway. For the wind turbine to rotate easily in low wind, light metal is utilized. The aluminum sheets are fastened directly to the 12-volt dynamo setup's axil, which was previously connected to the spur gear layout. This circuit has a battery attached to it, which stores the energy that is produced. Connected to the circuit is an inverter module that will convert DC to AC.

CHAPTER 2

LITERATURE SURVEY

LITERATURE SURVEY

Firas Basim Ismail Alnaimi, et.al, 2024, “Design and implementation of smart integrated hybrid Solar-Darrius wind turbine system for in-house power generation”, Rees.

This paper outlines the development of an integrated hybrid Solar-Darrius wind turbine system for renewable power generation. It identifies the SG6043 air foil as optimal, validated through Q-blade and CFD simulations, yielding specific power and moment coefficients. The study also introduces a hybrid prototype with improved turbine performance and IoT integration for remote monitoring. Blade shape optimizations and an IoT-based solution using the ESP32 Wi-Fi module are discussed. Theoretical energy generation ranges from 0.06 kW to 0.88 kW, addressing weather challenges and affirming reasonable assumptions.

Ashar Iqbal, et.al, 2019, “A Novel Vertical Axis Wind Turbine for Energy Harvesting on the Highways”, Research Gate.

This paper presents a VAWT cascaded along a highway to harness wind gusts from passing vehicles for generating electrical energy. The turbine's design features a low tip speed ratio and starting torque, proving efficient even at low wind speeds. The system's performance is tested indoors and outdoors, demonstrating accuracy and effectiveness compared to other techniques in the literature.

Sudip Baack, et.al,2022, “Installation and Performance Study of a Vertical-Axis Wind Turbine Prototype Model”, MDPI.

A study was conducted on a small-scale vertical-axis wind turbine in a laboratory setting, using artificial wind from a pedestal fan and blower. The research

analysed critical parameters like output power, voltage, and bearing shaft vibration at different wind speeds. Output power and voltage showed linear and curvilinear patterns with average shaft speed, respectively. Vibration parameters varied curvilinearly with speed. An automatic drip irrigation system was powered by the turbine, and theoretical analyses of wind flow and power generation were also performed.

Samir J. Deshmukh, et.al, 2017, “Design and Development of Vertical Axis Wind Turbine”, Research Gate.

The study focuses on utilizing low-velocity wind below 4m/s for power generation using a Maglev vertical axis wind turbine (VAWT). This Maglev turbine, employing magnetic levitation, outperforms conventional horizontal axis wind turbines (HAWTs) in output. Its design ensures stability and increased efficiency by using magnets for levitation instead of traditional bearings, reducing stress on the shaft and allowing for faster spinning. Safety is enhanced by placing Components.

C. Kothai Andal, et.al, 2022, “Design and implementation of IoT based intelligent energy management controller for PV/wind/battery system with cost minimization”, Science Direct

This work focuses on energy management in a distant hybrid renewable system (HRS) comprising wind turbines, solar modules, the grid, and battery storage. An energy management system integrated with IoT enables real-time monitoring and control of power flow, optimizing efficiency. The project uses IoT for remote monitoring of power generation and consumption across multiple Nano grids, with multi-function sensors wirelessly transmitting data to cloud servers. A micro grid with slave nodes (SN) connected to a master node controls power transmission between renewable energy sources like solar and wind, regulated by an ARDUINO microcontroller and MATLAB algorithm. The real-life results matched simulations, showcasing the effectiveness of the setup.

J.Mohammed Aashif, et.al,2023, “IoT Based Vertical Axis Wind Turbine Monitoring and Power Generating System”, IJRPR.

This project involves designing and remotely monitoring a small wind turbine using the Internet of Things (IoT). The IoT system enables remote supervision, energy management, and data collection for meteorological and performance analysis. Users can access operational parameters, energy performance data, and conduct energy management tasks seamlessly. The smooth remote control and successful operation of the wind turbine demonstrate the potential for onsite observation and data gathering. The IoT-based setup will be used for long-term monitoring to confirm power curves, optimize performance, and create a database for future studies on larger-scale wind turbines and renewable energy systems.

Swarupa Pinninti, et.al, 2019, “Design and Modelling of Vertical axis wind turbine and Solar PV Hybrid Power Generation System”, IJERT.

The increasing demand for electricity globally has led to a renewed focus on alternative energy sources due to rising fossil fuel prices and environmental concerns. A hybrid electric power generation system combining wind and solar energy is crucial for remote areas. Wind power is clean, renewable, and widely distributed, making it an excellent alternative to fossil fuels. The system utilizes solar energy throughout the year and supplements it with wind power using a vertical axis turbine, ensuring a reliable and sustainable energy source for the future.

Hussein Al-Zoubi, et.al, 2019, “IoT Applications in Wind Energy Conversion Systems”, DEGRUYTER.

This paper delves into the integration of IoT in wind energy systems to enhance reliability and performance assessment. It focuses on wind resource assessment and lifetime estimation of wind power modules using IoT technologies. The model includes sub-models of an aerodynamic rotor, a variable speed permanent magnet synchronous generator (PMSG), and various sensors for real-time data measurement. Through simulations with MATLAB/Simulink and IoT 'Thing

Speak,' IoT is shown to improve measurement reliability, monitoring accuracy, and quality assurance in wind energy systems.

Jazuli Fadil, et.al, 2020, “Novel of Vertical Axis Wind Turbine with Variable Swept Area Using Fuzzy Logic Controller”, INASS.

This paper introduces a novel approach to wind turbine power generation using a vertical axis wind turbine (VAWT) with variable swept area (VSA) smart rotors controlled by a fuzzy logic controller (FLC). The VSA adjusts its size based on wind speed to maintain a constant power output at the permanent magnet synchronous generator (PMSG). Experimental testing shows that the VSA system achieves significantly higher efficiency than fixed swept area (FSA), with a 33% increase in power output at lower wind speeds and operation across a wider range of wind speeds.

D Nayan, et.al, 2023, “Power generation on highway by using Vertical windmill and Solar System”, IARJSET.

The proposed hybrid power generation system combines wind and solar resources to address the increasing demand for electricity. Utilizing a vertical axis wind turbine placed on highway dividers, the system harnesses the air produced by passing vehicles to generate rotational energy. This complements the electrical energy generated by the solar system. The combined output is stored in a battery for applications like automatic street lighting and toll gates, offering a sustainable solution to energy needs.

2.2 PROBLEM STATEMENT

Despite the advancements in wind energy technology, traditional Vertical Axis Wind Turbines (VAWTs) often face challenges related to suboptimal power generation efficiency and a lack of real-time monitoring and control mechanisms. Conventional VAWTs may struggle to adapt to varying wind conditions, leading to inefficient power output and potential mechanical stress. Additionally, the absence of comprehensive monitoring tools limits the ability to diagnose and address issues promptly.

In addressing these challenges, our research identifies the need for an intelligent and adaptive wind energy system that combines mechanical robustness with electronic intelligence. The lack of real-time monitoring and control features in existing VAWT systems inhibits their optimal performance and hinders their integration into a more dynamic and responsive energy grid.

The problem can be summarized as follows:

- Traditional VAWTs often operate at suboptimal efficiency due to a lack of adaptive control mechanisms, leading to missed opportunities for harnessing wind energy effectively.
- The absence of real-time monitoring tools impedes the ability to assess the turbine's performance, detect anomalies, and promptly address issues, ultimately affecting the overall reliability of the system.
- Many VAWTs struggle to dynamically adjust to changing wind speeds and directions, resulting in inconsistent power generation and potential wear and tear on mechanical components.
- Existing wind turbine systems often lack integration with advanced technologies such as microcontroller-based control, real-time data display through LCD, and connectivity to the Internet of Things (IoT), which can contribute to a more intelligent and efficient power generation system.

2.3 EXISTING SYSTEM

The current landscape of Vertical Axis Wind Turbine (VAWT) systems predominantly relies on traditional designs marked by fixed-speed operation and limited control mechanisms. These conventional systems often operate at a constant speed, leading to inefficiencies in capturing wind energy, especially in dynamic wind conditions. With minimal adaptive control mechanisms, these VAWTs struggle to optimize power generation across varying wind speeds and directions. Moreover, the absence of comprehensive real-time monitoring tools hampers the system's ability to promptly detect and address performance issues.

In the existing paradigm, the integration of advanced technologies such as microcontroller-based control, real-time data display through LCD interfaces, and connectivity to the Internet of Things (IoT) is notably lacking. This shortfall in modern features limits the intelligence, adaptability, and remote accessibility of current VAWT systems. As a result, there exists a pressing need for an advanced wind energy solution that overcomes these limitations and integrates cutting-edge technologies to enhance efficiency, adaptability, and overall performance in the context of sustainable power generation.

2.3.1 DISADVANTAGES

- Lack of advanced control mechanisms and real-time monitoring tools leads to suboptimal power generation and reduced overall efficiency.
- Absence of modern technologies such as microcontroller-based control and IoT connectivity further hinders intelligence, data-driven optimization, and remote accessibility.

2.4 PROPOSED SYSEM

The proposed system represents a transformative approach to Vertical Axis Wind Turbines (VAWTs) by integrating advanced technologies to overcome the limitations inherent in conventional designs. At its core, the system incorporates a microcontroller as the central control unit. A crucial addition is the integration of an LCD display, providing immediate feedback on the generated voltage for on-site analysis. The inclusion of an Internet of Things (IoT) module facilitates seamless connectivity to cloud-based platforms, enabling remote monitoring and control. Safety features and mechanical enhancements ensure resilience in extreme weather conditions, addressing concerns about system reliability.

2.4.1 ADVANTGAES

- LCD display provides immediate feedback on voltage, allowing quick on-site analysis.
- IoT integration enables remote monitoring.

CHAPTER 3

REQUIREMENTS

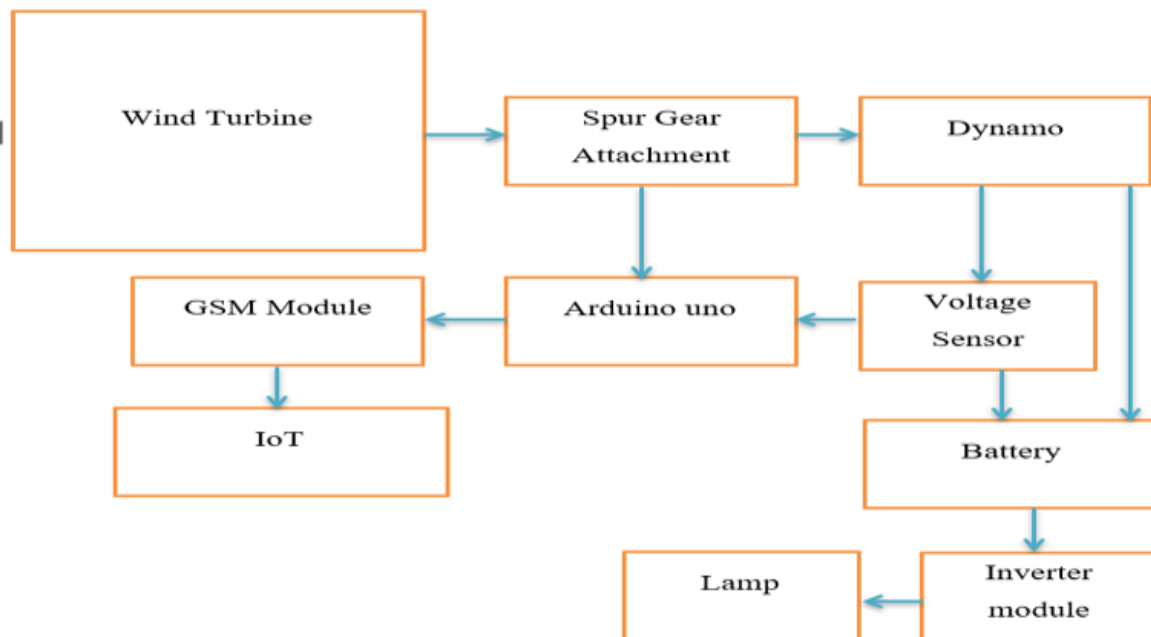


Fig 3 BLOCK DIAGRAM

REQUIREMENTS

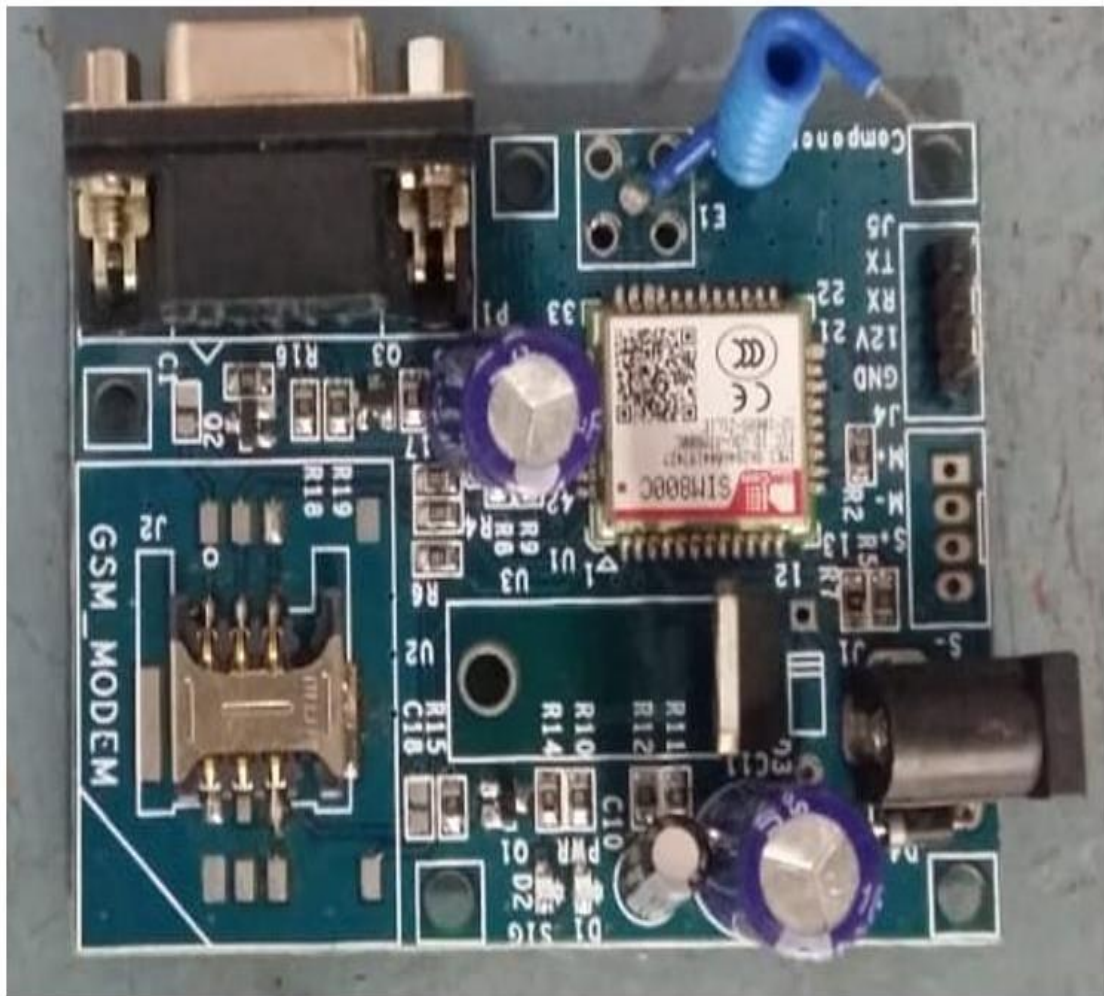
- FRAME
- GSM MODULE
- SPUR GEAR
- ARDUINO UNO
- DYNAMO
- VOLTAGE SENSOR
- BATTERY
- INVERTER MODULE
- LOAD
- ARDUINO – IDE
- EMBEDDED C - LANGUAGE

3.1 FRAME



A frame is a structural system that supports other components of a physical construction. Frame is used to carry the total setup of arrangement. It must be able to sustain the total weight of arrangement. It would be joined by arc welding to get permanent joint. So, frame is very important to our project.

3.2 GSM MODULE



SIM Com Wireless Solutions is a subsidiary of SIM Technology Group Ltd (stock code: 2000. H.K). It is a fast-growing wireless M2M company, designing and offering a variety of wireless modules based on GSM/GPRS/EDGE, WCDMA/HSDPA and TD-SCDMA technical platforms By partnering with third parties, SIM Com Wireless provides customized design solutions in M2M, WLL, Mobile Computing, GPS and other applications. SIM Com Wireless also provides ODM services for customers. According to ABI Insight report, SIM Com Cellular Module was number two provider of wireless modules worldwide in 2008 with 20% acquisition of global market share.

3.2.1 Product Description

This GSM Modem can accept any GSM network act as SIM card and just like a mobile phone with its own unique phone number. Advantage of using this modem will be that you can use its RS232 port to communicate and develop embedded applications. The SIM900A is a complete Dual-band GSM/GPRS solution in a SMT module featuring an industry-standard interface; the SIM800 delivers GSM/GPRS 900/1800MHz performance for voice, SMS, Data, and Fax in a small form factor and with low power consumption. With a tiny configuration of 24mm x 24mm x 3 mm, SIM800 can fit almost all the space requirements in your applications, especially for slim and compact demand of design.

3.2.2 Features

- High Quality Product
- RS232 interface @ RMC Connector for direct communication with computer or MCU kit
- Configurable baud rate
- SMA connector with GSM Antenna.
- SIM Card holder.
- Built in Network Status LED
- Inbuilt Powerful TCP/IP protocol stack for internet data transfer over GPRS.
- Audio interface Connector
- Normal operation temperature: -20 °C to +55 °C
- Input Voltage: 4.5V-12V DC

3.2.3 Application

- Short Message Service(SMS)
- Internet
- Incoming /outgoing calls

3.3 SPUR GEAR

A spur gear is a type of cylindrical gear with straight teeth that are parallel to the gear's axis of rotation. It is one of the most common types of gears used in mechanical systems for transmitting motion and power between shafts. Spur gears mesh with other gears of the same type or with mating teeth on other machine elements to transfer rotational motion and torque. They are characterized by their simplicity, efficiency, and ease of manufacture, making them widely used in various applications such as automotive transmissions, machinery, industrial equipment, and consumer appliances.



Fig 3.3 SPUR GEAR

3.3.1 Features

1. **Straight Teeth:** Spur gears have straight teeth that are cut parallel to the gear's axis of rotation, making them relatively easy to manufacture and mesh with other gears.
2. **Constant Gear Ratio:** The gear ratio between two meshing spur gears remains constant throughout their operation, providing consistent speed and torque transmission.
3. **Efficiency:** Spur gears are known for their high efficiency due to minimal sliding friction between the teeth during meshing, resulting in efficient power transmission.
4. **Simple Design:** The design of spur gears is straightforward, consisting of a cylindrical gear with straight teeth, making them easy to understand, manufacture, and maintain.
5. **Parallel Shaft Configuration:** Spur gears are typically used to transmit motion and power between parallel shafts, as their teeth are cut parallel to the gear's axis.
6. **Direction of Rotation:** Spur gears can rotate either clockwise or counterclockwise depending on the arrangement of the gear teeth.
7. **Noise and Vibration:** Spur gears can produce noise and vibration, especially at high speeds, due to the impact of the gear teeth during meshing. Proper design and lubrication can help minimize these effects.
8. **Load Distribution:** The load is distributed evenly across the teeth of spur gears, resulting in uniform wear and extended gear life.

3.3.2 Applications

- Automotive
- Machinery

- Industrial Equipment
- Consumer Appliances
- Robotics
- Aerospace
- Marine
- Power Generation
- Medical Equipment

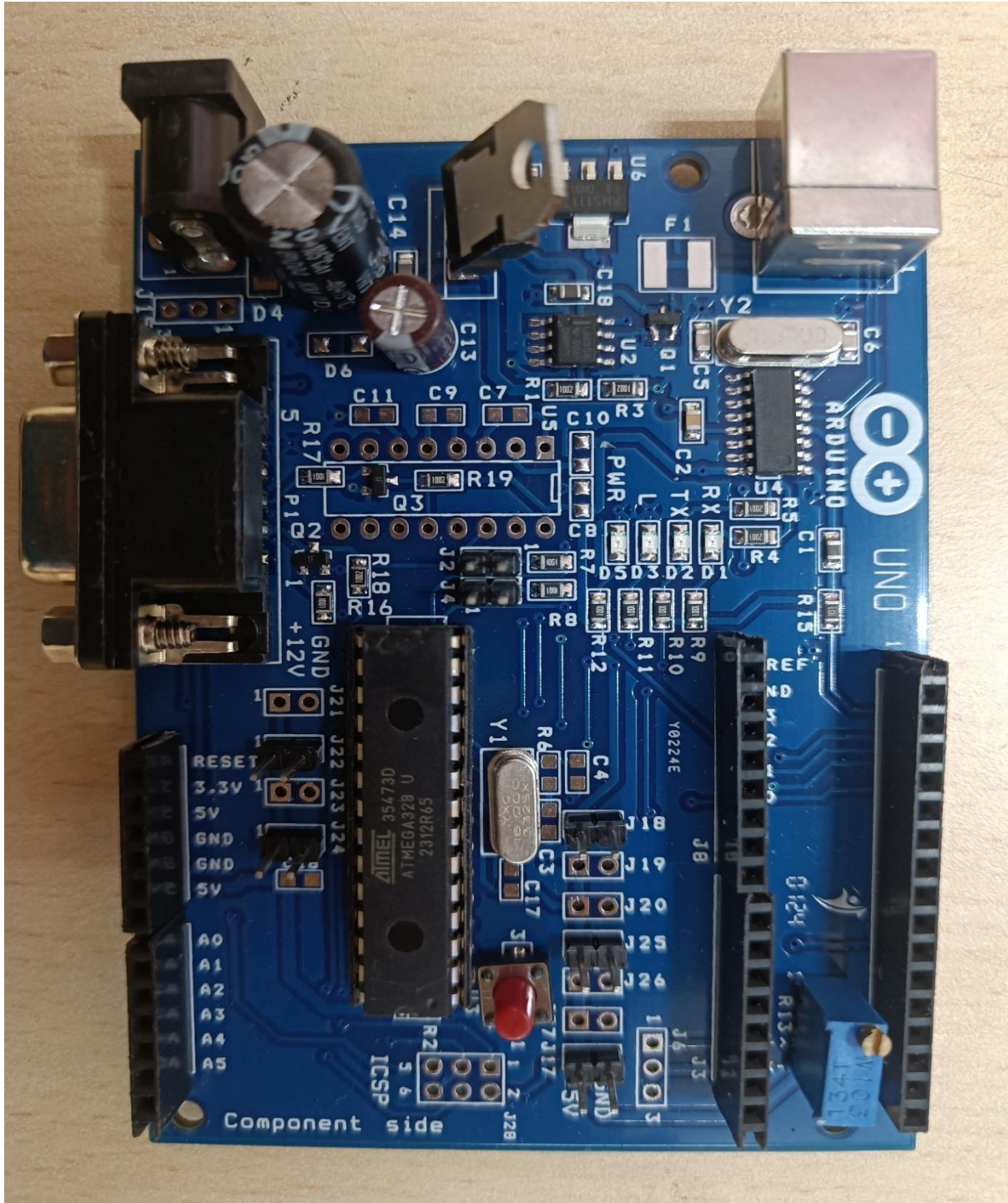
3.4 ARDUINO UNO

Arduino is an open-source project that created microcontroller-based kits for building digital devices and interactive objects that can sense and control physical devices. The project is based on microcontroller board designs, produced by several vendors, using various microcontrollers. These systems provide sets of digital and analog input/output (I/O) pins that can interface to various expansion boards (termed shields) and other circuits. The boards feature serial communication interfaces, including Universal Serial Bus (USB) on some models, for loading programs from personal computers. For programming the microcontrollers, the Arduino project provides an integrated development environment (IDE) based on a programming language named Processing, which also supports the languages C and C++.

3.4.1 Product Description

Arduino Uno is a microcontroller board based on the ATmega328P. It has 14 digital input/output pins (of which 6 can be used as PWM outputs), 6 analog inputs, a 16 MHz quartz crystal, a USB connection, a power jack, an ICSP header and a reset button. It contains everything needed to support the microcontroller; simply connect it to a computer with a USB cable or power it with a AC-to-DC adapter. Arduino Uno has a number of facilities for

communicating with a computer, another Arduino board, or other microcontrollers.



3.4 ARDUINO UNO

3.4.2 ATMEGA328P-PU microcontroller

The most important element in Arduino Uno R3 is ATMEGA328P-PU is an 8-bit Microcontroller with flash memory reach to 32k bytes. It's features as follow:

- High Performance, Low Power AVR
- Advanced RISC Architecture
 - 131 Powerful Instructions – Most Single Clock Cycle Execution
 - 32 x 8 General Purpose Working Registers
 - Up to 20 MIPS Throughput at 20 MHz
 - On-chip 2-cycle Multiplier
- High Endurance Non-volatile Memory Segments
 - 4/8/16/32K Bytes of In-System Self-Programmable Flash program memory
 - 256/512/512/1K Bytes EEPROM
 - 512/1K/1K/2K Bytes Internal SRAM
 - Write/Erase Cycles: 10,000 Flash/100,000 EEPROM
 - Data retention: 20 years at 85°C/100 years at 25°C
 - Optional Boot Code Section with Independent Lock Bits
 - In-System Programming by On-chip Boot Program
 - True Read-While-Write Operation
 - Programming Lock for Software Security
- Peripheral Features
 - Two 8-bit Timer/Counters with Separate Prescale and Compare Mode
 - One 16-bit Timer/Counter with Separate Prescale, Compare Mode, and Capture Mode

- Real Time Counter with Separate Oscillator
- Six PWM Channels
- 8-channel 10-bit ADC in TQFP and QFN/MLF package
- Temperature Measurement
- 6-channel 10-bit ADC in PDIP Package
- Temperature Measurement
- Programmable Serial USART
- Master/Slave SPI Serial Interface
- Byte-oriented 2-wire Serial Interface (Philips I2C compatible)
- Programmable Watchdog Timer with Separate On-chip Oscillator
- On-chip Analog Comparator
- Interrupt and Wake-up on Pin Change
- Special Microcontroller Features
 - Power-on Reset and Programmable Brown-out Detection
 - Internal Calibrated Oscillator
 - External and Internal Interrupt Sources
 - Six Sleep Modes: Idle, ADC Noise Reduction, Power-save, Power-down, Standby, and Extended Standby
- I/O and Packages
 - 23 Programmable I/O Lines
 - 28-pin PDIP, 32-lead TQFP, 28-pad QFN/MLF and 32-pad QFN/MLF
- Operating Voltage
 - 1.8 - 5.5V
- Temperature Range
 - -40°C to 85°C
- Speed Grade

- 0 - 4 MHz@1.8 - 5.5V, 0 - 10 MHz@2.7 - 5.5.V, 0 - 20 MHz @ 4.5 - 5.5V
- Power Consumption at 1 MHz, 1.8V, 25°C
 - Active Mode: 0.2 mA
 - Power-down Mode: 0.1 μ A
 - Power-save Mode: 0.75 μ A (Including 32 kHz RTC)

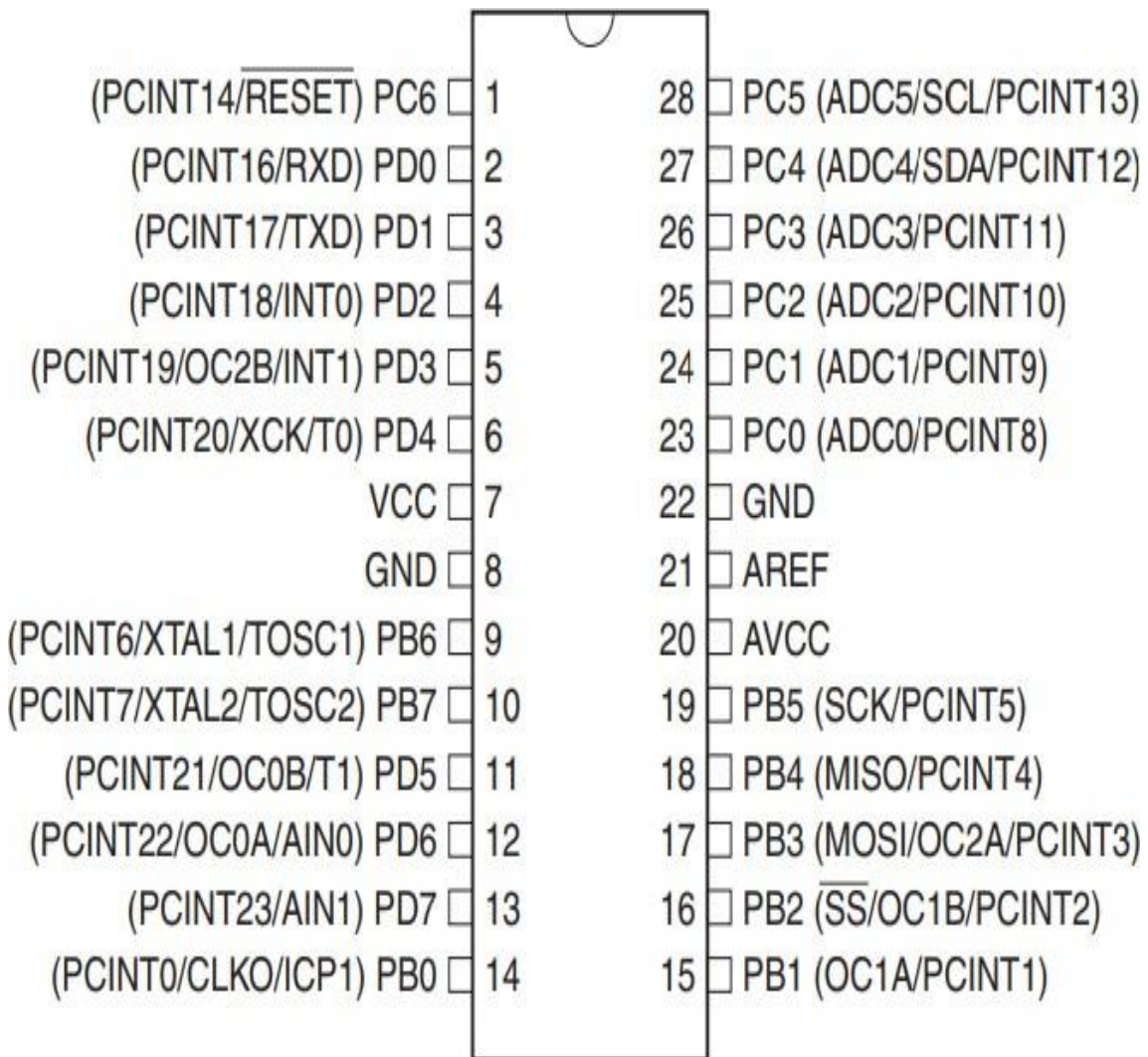


Fig 3.4.2 pin diagram of ATMEGA328P-PU

3.4.3 Features

- Microcontroller: ATmega328P
- Operating voltage: 5V
- Input voltage: 7-12V
- Flash memory: 32KB
- SRAM: 2KB
- EEPROM: 1KB

3.4.4 Applications

- Real time biometrics
- Robotic applications
- Academic applications

3.5 DYNAMO

A dynamo is an electrical generator that creates direct current using a commutator. Dynamos were the first electrical generators capable of delivering power for industry, and the foundation upon which many other later electric-power conversion devices were based, including the electric motor, the alternating-current alternator, and the rotary converter.

3.5.1 Working Of Dynamo

1. A dynamo is created by placing a conducting wire between the north and south poles of a permanent magnet.
2. According to the laws of electromagnetism, when a current-carrying conductor is placed in a changing magnetic field, a current flow is induced inside the conductor.
3. Therefore, a changing magnetic field is produced by rotating the coil.
4. According to the laws of electromagnetism, this changing magnetic field induces a current flow inside the coil.

5. During these rotations, two possible polarities are generated, positive polarity or negative polarity.
6. We know that for alternating current a positive polarity and a negative polarity must be present.
7. Hence, this change in the magnetic field generates an alternating current.

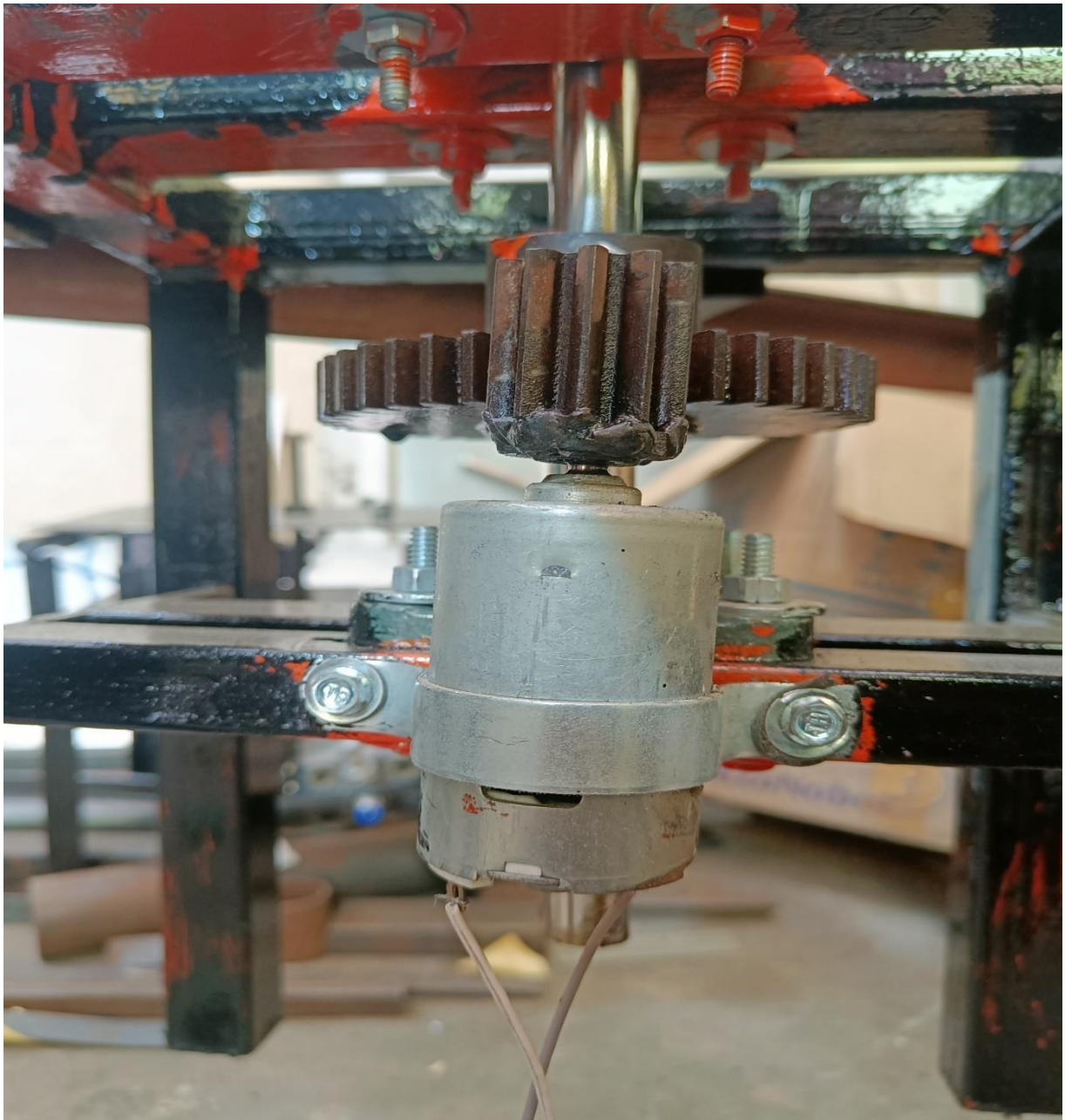


Fig 3.5 DYNAMO

3.5.2 Features

1. **Mechanical Input:** Dynamo motors require a mechanical input, typically in the form of rotational motion, to generate electricity. This mechanical input could come from various sources such as turbines, engines, wind turbines, or hand-cranking mechanisms.
2. **Electromagnetic Induction:** Dynamo motors operate based on the principle of electromagnetic induction. When a conductor moves within a magnetic field or when the magnetic field around a conductor changes, it induces an electromotive force (EMF) in the conductor, which generates an electric current.
3. **Field Magnet:** Dynamo motors have a magnetic field, usually created by permanent magnets or electromagnets. This magnetic field is essential for inducing the electric current in the rotating conductors.
4. **Armature:** The armature is the part of the dynamo motor where the electrical current is induced. It typically consists of coils of wire wound around a core, which rotates within the magnetic field. As the armature rotates, it cuts through magnetic lines of force, generating an EMF.
5. **Commutator:** In DC (Direct Current) dynamo motors, the commutator is a crucial component. It consists of segments of conducting material attached to the armature shaft. The commutator reverses the direction of the current in the armature coils as they rotate, ensuring that the generated electricity flows in a consistent direction.
6. **Brushes:** Brushes are conductive contacts that maintain electrical contact with the commutator segments as the armature rotates. They conduct the electric current between the rotating armature and the stationary external circuit.
7. **Output Terminals:** Dynamo motors have output terminals where the generated electrical energy is collected and delivered to an external circuit or load.

8. **Voltage and Current Regulation:** Depending on the design and application, dynamo motors may incorporate mechanisms for regulating the voltage and current output to meet specific requirements.
9. **Efficiency and Power Rating:** Dynamo motors vary in efficiency and power rating depending on their size, design, and intended application. Efficiency refers to how effectively the motor converts mechanical energy into electrical energy, while the power rating indicates the maximum amount of electrical power it can generate or handle.

3.5.3 Applications

- Power Generation
- Bicycle Dynamo Lights
- Emergency Power Generation
- Portable Electronics
- Hand-cranked Generators

3.6 VOLTAGE SENSOR

A voltage sensor is a device designed to measure the electrical potential difference (voltage) between two points in an electrical circuit. It detects and quantifies the voltage level, typically converting it into an output signal that can be read and interpreted by other electronic systems or devices. Voltage sensors are crucial components in various applications, including electrical power systems, electronic instrumentation, control systems, and automation, where accurate voltage monitoring is essential for ensuring proper operation, safety, and efficiency.

3.6.1 Working Principle

A voltage sensor operates by detecting the voltage levels present in an electrical circuit and converting this information into a usable output. Typically, it consists of a sensing element that interacts with the voltage, signal conditioning

circuitry to process the voltage signal, and measurement electronics to quantify the voltage. The output can be in analog or digital form, depending on the sensor's design and application. Calibration ensures accuracy within specified tolerances, while protective measures such as isolation are often employed to safeguard both the sensor and connected equipment. Overall, the voltage sensor's working principle revolves around accurately detecting and translating voltage levels for various applications, ensuring reliable performance and safety in electrical systems.

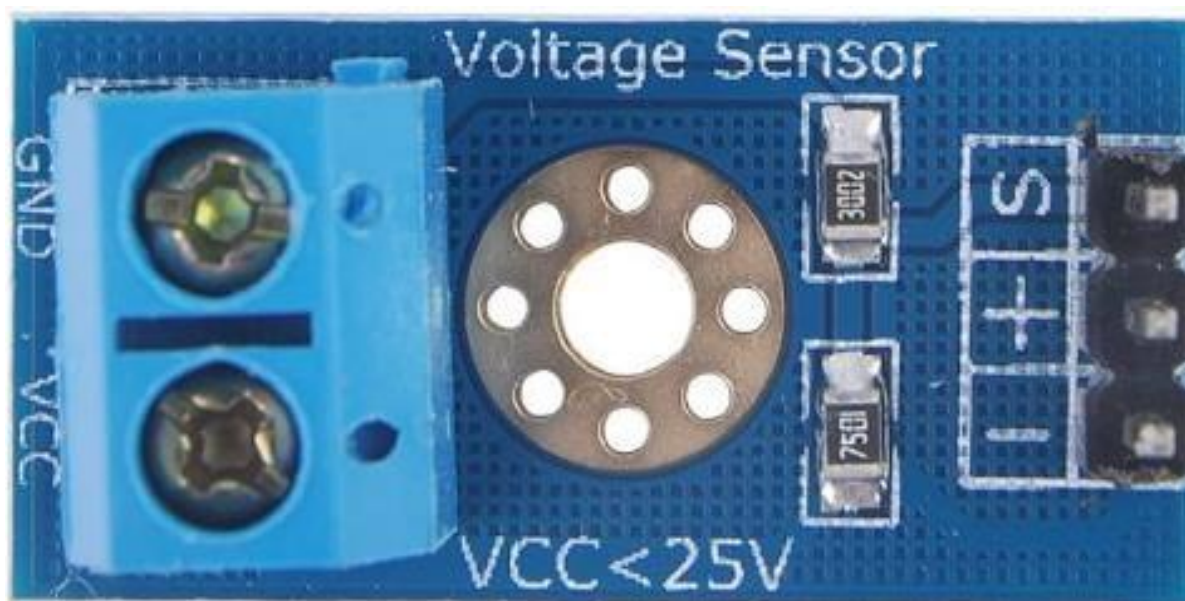


Fig 3.6 VOLTAGE SENSOR

3.6.2 Features

1. **Voltage Range:** Voltage sensors may support a wide range of voltage levels, allowing them to be used in various electrical systems, from low-voltage circuits to high-voltage power lines.
2. **Accuracy:** High accuracy is crucial for precise voltage measurement. Voltage sensors may offer different levels of accuracy to suit different applications, with some providing precise measurements down to millivolt levels.

3. **Response Time:** The speed at which a voltage sensor responds to changes in voltage is important, especially in dynamic systems. Sensors with fast response times ensure timely detection of voltage fluctuations.
4. **Isolation:** Many voltage sensors provide galvanic isolation between the measured circuit and the measurement electronics, protecting sensitive equipment and operators from potential hazards such as electric shocks and ground loops.
5. **Output Interface:** Voltage sensors may feature various output interfaces, including analog voltage outputs, digital outputs (such as I2C, SPI, or UART), or relay outputs, facilitating integration with different control and monitoring systems.
6. **Temperature Stability:** Some voltage sensors are designed to maintain accuracy over a wide temperature range, ensuring reliable performance in diverse environmental conditions.
7. **Overvoltage Protection:** Built-in protection mechanisms safeguard the sensor and connected equipment from voltage spikes or overvoltage conditions, prolonging the sensor's lifespan and preventing damage.
8. **Compact Size and Mounting Options:** Voltage sensors come in various form factors and mounting options, allowing for easy integration into different devices and installations, from compact PCB-mounted sensors to panel-mounted or DIN rail-mounted units.
9. **Configurability and Customization:** Advanced voltage sensors may offer configurable settings or programmable features, allowing users to tailor the sensor's behaviour to specific application requirements.
10. **Diagnostic Features:** Some voltage sensors incorporate diagnostic capabilities, such as self-test functions or fault detection algorithms, to ensure continued reliability and facilitate troubleshooting.

3.6.3 Applications

- Power Distribution Systems
- Renewable Energy Integration
- Industrial Automation
- Automotive Electronics
- Home Appliances
- Smart Grid Technologies

3.7 BATTERY

In isolated systems away from the grid, batteries are used for storage of excess solar energy converted into electrical energy. The only exceptions are isolated sunshine load such as irrigation pumps or drinking water supplies for storage. In fact for small units with output less than one kilowatt. Batteries seem to be the only technically and economically available storage means. Since both the photovoltaic system and batteries are high in capital costs. It is necessary that the overall system be optimized with respect to available energy and local demand pattern. To be economically attractive the storage of solar electricity requires a battery with a particular combination of properties:

- (1) Low cost
- (2) Long life
- (3) High reliability
- (4) High overall efficiency
- (5) Low discharge
- (6) Minimum maintenance
 - (A) Ampere hour efficiency
 - (B) Watt hour efficiency

We use lead acid battery for storing the electrical energy from the solar panel for lighting the street and so about the lead acid cells are explained below.



Fig 3.7 BATTERY

Inside a lead-acid battery, the positive and negative electrodes consist of a group of plates welded to a connecting strap. The plates are immersed in the electrolyte, consisting of 8 parts of water to 3 parts of concentrated sulfuric acid. Each plate is a grid or framework, made of a lead-antimony alloy. This construction enables the active material, which is lead oxide, to be pasted into the grid.

3.8 INVERTER MODULE

An inverter module is an electronic device that converts direct current (DC) power into alternating current (AC) power. It accomplishes this by employing electronic switching circuits to manipulate the DC input, producing an AC output that mimics the characteristics of grid-supplied electricity. Inverter modules are essential components in various applications, including solar power systems, uninterruptible power supplies (UPS), electric vehicles, and industrial machinery, enabling the efficient and reliable conversion of power between different electrical formats.



Fig 3.8 INVERTER MODULE

3.8.1 Working Principle

An inverter module serves as a crucial link between direct current (DC) power sources, like batteries or solar panels, and alternating current (AC) electrical devices. Operating on the principle of electronic switching, inverter

modules convert the steady DC voltage into a variable-frequency AC waveform, mimicking the characteristics of utility grid power. Through rapid transistor switching and filtering techniques, the inverter produces a smooth AC output suitable for powering a wide range of devices. Additionally, these modules often incorporate advanced control systems to regulate output voltage, frequency, and protect against overload or short-circuit conditions. This ensures compatibility with various loads while maintaining efficiency and reliability.

Moreover, inverter modules play a pivotal role in renewable energy systems, providing the means to harness and utilize DC power generated from sources like solar panels or wind turbines. They enable the integration of renewable energy into existing electrical grids or standalone off-grid systems, facilitating energy independence and sustainability. With features such as grid synchronization and battery charging capabilities, inverter modules contribute to the efficient utilization of renewable resources, reducing reliance on fossil fuels and mitigating environmental impact. Overall, inverter modules play a vital role in modern energy infrastructure, enabling the seamless conversion and utilization of power from diverse sources for a multitude of applications.

3.8.2 Features

1. Input voltage range
2. Output power rating
3. Efficiency
4. Protection features (e.g., overvoltage protection, short-circuit protection)
5. Control interfaces (e.g., PWM control, digital control)
6. Size and form factor
7. Cooling mechanisms (e.g., fans, heat sinks)
8. Compatibility with various loads and applications

3.8.3 Applications

- Residential and commercial power backup systems
- Off-grid renewable energy systems (such as solar or wind power)
- Uninterruptible Power Supplies (UPS)
- Electric vehicle powertrains
- Industrial machinery and equipment
- Telecommunications infrastructure
- RV (Recreational Vehicle) and marine power systems
- Portable power solutions (e.g., camping, outdoor activities)
- Grid-tied solar PV systems with battery storage

3.9 LOAD

A lamp is a device that produces light through the emission of electromagnetic radiation, typically in the visible spectrum. It consists of a light source, such as an incandescent bulb, fluorescent tube, LED (light-emitting diode), or gas-discharge lamp, enclosed within a housing or fixture. Lamps are utilized for various purposes, including illumination in indoor and outdoor settings, decorative lighting, task lighting, and signalling. They come in diverse shapes, sizes, and designs to suit different applications and preferences. Lamps may be powered by electricity, battery, or fuel, and they play a fundamental role in providing illumination for residential, commercial, industrial, and public spaces.

3.9.1 Features

1. **Light Source:** Lamps can utilize various light sources, including incandescent bulbs, fluorescent tubes, LEDs, halogen bulbs, or gas-discharge lamps. The choice of light source impacts factors such as brightness, color temperature, and energy efficiency.

2. **Fixture Design:** Lamps come in a wide range of designs and styles to suit different aesthetic preferences and functional requirements. These designs may include desk lamps, floor lamps, pendant lights, chandeliers, wall sconces, and more.
3. **Brightness and Colour Temperature:** Different lamps offer varying levels of brightness and colour temperature, allowing users to adjust the lighting to suit specific tasks, moods, or environments.
4. **Energy Efficiency:** With increasing emphasis on sustainability, many lamps now feature energy-efficient technologies such as LEDs or CFLs (compact fluorescent lamps), which consume less energy and have longer lifespans compared to traditional incandescent bulbs.
5. **Dimming Capability:** Some lamps are equipped with dimming features, allowing users to adjust the brightness level according to their needs. This adds versatility and control over the lighting atmosphere.



Fig 3.9 LAMP LOAD

3.9.2 Application

- Residential Lighting
- Commercial Spaces
- Industrial Environments
- Public Spaces
- Specialized Applications
- Outdoor Lighting
- Emergency Lighting

3.10 ARDUINO IDE

The Arduino integrated development environment (IDE) is a cross-platform application (for Windows, macOS, Linux) that is written in the programming language Java. It is used to write and upload programs to Arduino board.

The source code for the IDE is released under the GNU General Public License, version 2. The Arduino IDE supports the languages C and C++ using special rules of code structuring. The Arduino IDE supplies a software library from the Wiring project, which provides many common input and output procedures. User-written code only requires two basic functions, for starting the sketch and the main program loop, that are compiled and linked with a program stub `main ()` into an executable cyclic executive program with the GNU toolchain, also included with the IDE distribution. The Arduino IDE employs the program `avrdude` to convert the executable code into a text file in hexadecimal encoding that is loaded into the Arduino board by a loader program in the board's firmware.

The name Arduino comes from a bar in Ivrea, Italy, where some of the founders of the project used to meet. The bar was named after Arduin

of Ivrea, who was the margrave of the March of Ivrea and King of Italy from 1002 to 1014.

3.11 EMBEDDED C

Embedded C is a set of language extensions for the C programming language by the C Standards Committee to address commonality issues that exist between C extensions for different embedded systems.

Historically, embedded C programming requires nonstandard extensions to the C language in order to support exotic features such as fixed-point arithmetic, multiple distinct memory banks, and basic I/O operations. In 2008, the C Standards Committee extended the C language to address these issues by providing a common standard for all implementations to adhere to. It includes a number of features not available in normal C, such as fixed-point arithmetic, named address spaces and basic I/O hardware addressing. Embedded C uses most of the syntax and semantics of standard C, e.g., `main()` function, variable definition, data type declaration, conditional statements (`if`, `switch case`), loops (`while`, `for`), functions, arrays and strings, structures and union, bit operations, macros, etc.

CHAPTER 4

TYPES OF WINDMILL

TYPES OF WINDMILL:

- Horizontal Axis Wind Turbines (HAWT)
- Vertical Axis Wind Turbines (VAWT)

4.1 HORIZONTAL AXIS WIND TURBINES (HAWT)

Horizontal axis wind mills, also known as horizontal axis wind turbines (HAWTs), are devices that convert wind energy into mechanical energy, which is then used to generate electricity. Here are some key features and components of horizontal axis wind mills:

Blades: HAWTs have two or more blades attached to a rotor. These blades are typically made of lightweight and durable materials such as fiberglass or carbon Fiber. The shape and design of the blades are crucial for efficient energy capture from the wind.

Rotor: The rotor is the central part of the wind mill that includes the blades. It rotates when wind energy is applied to the blades, converting the kinetic energy of the wind into rotational mechanical energy.

Nacelle: The rotor is connected to a nacelle, which is a housing that contains the gearbox, generator, and other components. The nacelle is usually mounted on top of a tall tower to capture higher wind speeds and reduce turbulence.

Yaw System: Horizontal axis wind mills have a yaw system that allows the turbine to rotate horizontally to face the direction of the wind. This helps maximize energy capture by ensuring that the blades are always facing into the wind.

Tower: The tower provides height for the wind mill, allowing it to reach higher wind speeds where the energy potential is greater. Towers for HAWTs can vary in height depending on the turbine size and site conditions.

Generator: The mechanical energy produced by the rotor is transferred to a generator inside the nacelle, where it is converted into electrical energy. The generator is often a synchronous or asynchronous type designed to produce alternating current (AC) electricity.

Control Systems: Modern HAWTs are equipped with advanced control systems that monitor wind conditions, adjust blade pitch and rotor speed for optimal performance, and ensure safe operation of the turbine.

Horizontal axis wind mills are widely used for utility-scale wind power generation in wind farms as well as for smaller applications such as residential and commercial installations. They are a key technology in the renewable energy sector, contributing to the transition towards cleaner and more sustainable electricity generation.



Fig 4.1 HAWT

4.1.1 Advantages

- **Efficiency:** HAWTs are known for high efficiency in converting wind energy into electrical power.
- **Scalability:** They can be built in various sizes, suitable for different applications from residential to utility-scale.
- **Stability:** HAWTs are generally more stable than vertical axis turbines due to their design and tall towers.
- **Technological Advancements:** Modern HAWTs incorporate advanced features for optimal performance and reliability.
- **Grid Integration:** They are well-integrated with existing electrical grids, making connection and power distribution efficient.
- **Adaptability:** HAWTs can operate in various wind conditions, making them suitable for different geographical locations.
- **Cost-Effectiveness:** Advancements in manufacturing and installation have reduced costs, making wind energy competitive with conventional sources.

4.2 VERTICAL AXIS WIND TURBINE(VAWT)

Vertical axis wind mills, also known as vertical axis wind turbines (VAWTs), are a type of wind turbine where the main rotor shaft is arranged vertically. Unlike horizontal axis wind turbines (HAWTs) where the rotor shaft is horizontal and perpendicular to the ground, VAWTs have their blades rotating around a vertical axis. Here are some key points about vertical axis wind mills:

Blade Design: VAWTs can have various blade designs, such as Darrieus, Savonius, or helical blades. These blades capture wind energy and convert it into rotational motion around the vertical axis.

Low Wind Speed Performance: VAWTs are often designed to perform well in low wind speeds and turbulent conditions, making them suitable for urban and residential areas where wind conditions may not be ideal for HAWTs.

Height Requirement: While VAWTs generally have lower height requirements compared to HAWTs, they may still benefit from being mounted on taller structures to access stronger winds and improve efficiency.

Less Sensitive to Wind Direction: Unlike HAWTs that require a yaw system to align with the wind direction, VAWTs are less sensitive to wind direction changes due to their omnidirectional blade design.

Noise and Vibration: VAWTs tend to produce less noise and vibration compared to HAWTs, making them potentially more suitable for locations where noise pollution is a concern.

Less Common for Large-Scale Power Generation: While VAWTs have advantages in certain scenarios, they are less common for large-scale power generation compared to HAWTs. However, they are used in smaller installations, experimental projects, and applications where their specific advantages are beneficial.

Aesthetic Considerations: Some VAWT designs are visually appealing and may be preferred in locations where aesthetics are important, such as near residential areas or tourist sites.

Overall, vertical axis wind mills offer unique advantages and are suitable for specific applications and environments, complementing the more widespread use of horizontal axis wind turbines in the wind energy industry.

4.2.1 Advantages

- **Low Wind Speed Performance:** VAWTs are generally more efficient in low wind speeds compared to horizontal axis wind turbines (HAWTs). They can start generating electricity at lower wind speeds, making them suitable for areas with variable or lower wind speeds.
- **Omnidirectional:** VAWTs are omnidirectional, meaning they can capture wind from any direction without the need for a yaw mechanism to orient

themselves into the wind. This feature makes them more adaptable to changing wind directions and turbulent wind conditions.

- **Less Sensitive to Wind Turbulence:** VAWTs are less affected by turbulent winds, which can occur in built-up or urban areas. Their design allows them to operate effectively even in turbulent airflow.
- **Compact Design:** Vertical axis wind turbines have a compact design compared to horizontal axis turbines, which may make them more suitable for installations where space is limited, such as rooftops or urban environments.
- **Ease of Maintenance:** VAWTs often have simpler designs and fewer moving parts compared to HAWTs, leading to easier maintenance and potentially lower maintenance costs over time.
- **Less Noise and Vibration:** Due to their design and operation, VAWTs tend to produce less noise and vibration, which can be beneficial for installations near residential areas or sensitive environments.
- **Aesthetic Appeal:** Some VAWT designs are aesthetically pleasing and may be preferred in locations where visual impact is a concern, such as tourist areas or scenic landscapes.
- **Experimental Applications:** VAWTs are sometimes used in experimental or research projects to explore new design concepts and technologies in wind energy generation.
- **Safety:** VAWTs may have a safety advantage over HAWTs in certain situations. Since the rotor and blades of VAWTs are located closer to the ground, maintenance and repair tasks can be safer and more accessible compared to tall HAWTs mounted on high towers.
- **Less Complex Foundation:** VAWTs typically require simpler and less complex foundations compared to HAWTs. This can result in lower

installation costs, especially in areas with challenging soil conditions or restricted access for heavy machinery.



Fig 4.2 VAWT

4.3 POINT THAT SURPASS VAWT COMPARED TO HAWT

- **Low Wind Speed Performance:** VAWTs are generally more efficient at capturing energy from low wind speeds compared to HAWTs. This makes them suitable for areas with lower average wind speeds or variable wind conditions.
- **Omnidirectional Capability:** VAWTs can capture wind from any direction without the need for a yaw mechanism to orient themselves into the wind. This feature makes them more adaptable to changing wind directions and turbulent wind conditions.
- **Less Sensitive to Wind Turbulence:** VAWTs are less affected by turbulent winds, which can occur in built-up or urban areas. Their design allows them to operate effectively even in turbulent airflow, making
- **Less Complex Foundation:** VAWTs typically require simpler and less complex foundations compared to HAWTs. This can result in lower installation costs, especially in areas with challenging soil conditions or restricted access for heavy machinery.
- **Safety Considerations in Urban Environments:** VAWTs may have safety advantages in urban environments or areas with close proximity to buildings and infrastructure. Their lower height and compact design make them potentially safer in densely populated areas where space is limited.
- **Less Noise Pollution:** VAWTs tend to produce less noise compared to HAWTs due to their design and operation. This can be advantageous in residential areas or locations where noise pollution is a concern.
- **Ease of Maintenance:** VAWTs can be easier to maintain and service because their components, such as the generator and gearbox, are often located at ground level or within easy reach. This can reduce maintenance costs and downtime.
- **Scalability:** VAWTs are often more scalable than HAWTs, meaning they can be effectively used in both small-scale applications (such as residential

or commercial buildings) and larger installations (such as wind farms). This versatility makes them suitable for a wide range of projects.

- **Visual Appeal:** Some people find VAWTs visually appealing and less intrusive compared to the large blades of HAWTs. This can be a consideration in areas where aesthetics are important, such as tourist destinations or scenic locations.
- **Bird and Bat Safety:** VAWTs may pose less risk to birds and bats compared to HAWTs, as they operate at lower speeds and have a different blade configuration that may reduce the likelihood of wildlife collisions.

CHAPTER 5

GENERATED VOLATAGE CALCULATION

5.1 AT SLOW ROTATION



Fig 5.1 AT SLOW ROTATION

While moving slowly, it can generate up to 4 volts in a single rotation and it is displayed in the LCD screen. VAWTs operating at slow speeds in highway environments may generate less energy compared to those in locations with higher wind speeds. This is because the kinetic energy available for the turbine to capture and convert into electricity is reduced. VAWTs in low-speed environments may utilize specific blade designs optimized for slower wind conditions. These designs focus on maximizing energy capture efficiency at lower speeds by adjusting blade curvature, air foil shape, and pitch angle. Some VAWTs incorporate variable pitch control mechanisms that allow the blades to adjust their angle based on wind conditions. This feature can optimize energy capture even at slower speeds by maintaining an optimal angle of attack for the wind. VAWTs in highway environments with slow wind speeds may have different start-up characteristics compared to those in higher wind speed areas. Ensuring reliable start-up mechanisms and control systems is crucial for efficient operation. Operating at slow speeds can reduce wear and tear on turbine components, leading to potentially lower maintenance requirements and longer operational lifespan. However, regular inspections and maintenance tasks are still essential to ensure optimal performance and safety. VAWTs in low-speed environments can benefit from integration with energy storage systems, such as batteries or flywheels. These systems can store excess energy generated during periods of higher wind speeds for use during low wind periods, enhancing overall energy efficiency. VAWTs operating at slow speeds in highway environments typically have minimal environmental impact, including reduced noise levels and lower disturbance to wildlife compared to turbines in higher wind speed areas. When VAWTs generate less energy due to slow wind speeds, grid integration strategies may need to be adjusted to balance energy supply and demand effectively. This may include backup power sources or grid connection upgrades.

5.2 AT FAST ROTATION



Fig 5.2 AT FAST MOVE

It may reach a maximum voltage of 20 volts in a single turn when moving quickly and it is displayed in LCD screen. Increased Energy Generation: VAWTs placed in highways or locations with higher wind speeds can generate more energy compared to those in lower wind speed areas. The higher wind speeds provide greater kinetic energy for the turbine to capture and convert into electricity.

Optimized Blade Design: VAWTs installed in high-speed environments may use specialized blade designs to efficiently harness the increased wind energy. These designs may include aerodynamic profiles that reduce drag and enhance energy capture.

Safety Measures: Turbines in high-speed locations require robust safety measures to withstand strong winds and potential extreme weather conditions. This includes sturdy tower construction, secure foundation anchoring, and reliable braking systems to control turbine speed during high winds.

Grid Integration: VAWTs in highways can contribute to grid stability and renewable energy generation. They can be integrated into smart grid systems to manage energy production based on demand and grid conditions.

Monitoring and Maintenance: Turbines in high-speed environments require regular monitoring and maintenance to ensure optimal performance and safety. This includes inspections for wear and tear, lubrication of moving parts, and proactive measures to prevent damage from strong winds.

Noise Considerations: VAWTs operating at higher speeds may produce more noise than those in lower wind speed areas. Noise mitigation measures such as sound barriers or distance from residential areas may be necessary to address potential noise concerns.

Environmental Impact: While VAWTs on highways can contribute to renewable energy production, their impact on the surrounding environment, including wildlife and landscape aesthetics, should be carefully considered and mitigated as needed.

CHAPTER 6

CONCLUSION AND FUTURE SCOPE

6.1 CONCLUSION

An important step towards intelligent and sustainable power generation has been made with the design and deployment of a microcontroller-integrated vertical axis wind turbine system. In this work, we have discussed the features and components of the system we have designed, with a focus on how monitoring and adaptive control are crucial.

We were able to implement real-time speed modifications for the turbine in response to outside data by using a microcontroller as the brains of the operation. This not only makes the turbine last longer by avoiding wear and tear on its mechanical parts, but it also maximizes the efficiency with which it generates power. The addition of an LCD screen allows operators to see the voltage output in real-time.

New opportunities for remote monitoring and control arise with the inclusion of IoT connectivity. Users can access critical turbine data from any internet-connected device on a cloud-based platform, which allows for preventive maintenance, data analytics, and optimization in real-time. Users are able to make well-informed decisions that optimize the system's performance and dependability because to this seamless connectivity, which overcomes geographical constraints.

Wind energy's pinnacle system, our Vertical Axis Wind Turbine integrates hardware, software, and Internet of Things connectivity. It helps build a more intelligent and long-lasting energy system while also meeting the increasing worldwide demand for renewable power. A cleaner, greener world will be shaped

in large part by intelligent wind turbine systems like ours as we transition to a renewable energy-powered future.



Fig 6.1 FINAL OUTPUT

6.2 FUTURE SCOPE

Turbine Design: Begin by designing the VAWT system, including selecting the appropriate blade design, rotor diameter, and generator specifications based on the expected wind conditions and power generation requirements.

Microcontroller Selection: Choose a suitable microcontroller platform for controlling and monitoring the VAWT system. Popular options include Arduino boards, Raspberry Pi, or specialized microcontrollers with features like PWM (Pulse Width Modulation) for motor control.

Sensor Integration: Integrate sensors such as an anemometer (to measure wind speed), wind direction sensor, and load sensors to gather real-time data about the wind conditions and turbine performance.

Control Algorithms: Develop control algorithms using the microcontroller to optimize the VAWT's operation based on the collected data. This may include adjusting blade pitch, rotor speed, and power output for maximum efficiency.

IoT Connectivity: Incorporate IoT (Internet of Things) connectivity using Wi-Fi, GSM, or LoRa modules to enable remote monitoring and control of the VAWT system. This allows for real-time data transmission, status updates, and control commands from a central dashboard or mobile app.

Data Logging and Analytics: Implement data logging capabilities to store historical performance data such as power output, wind speed, and energy generated. Use analytics tools to analyse this data for performance optimization and predictive maintenance.

Safety Features: Include safety features such as over-speed protection, emergency stop mechanisms, and fault detection algorithms to ensure safe operation of the VAWT system.

Energy Storage Integration: Consider integrating energy storage systems such as batteries or capacitors to store excess energy generated by the VAWT for use during periods of low wind or high demand.

Testing and Validation: Conduct thorough testing and validation of the VAWT system under various wind conditions to ensure reliability, efficiency, and performance consistency.

Regulatory Compliance: Ensure compliance with relevant regulations and standards for renewable energy systems, electrical safety, and environmental impact.

Remote Monitoring and Maintenance: Implement remote monitoring capabilities using IoT connectivity to remotely monitor the VAWT system's performance, health status, and energy production metrics. This enables proactive maintenance scheduling, troubleshooting, and remote firmware updates to optimize system efficiency and reliability.

Energy Management and Optimization: Incorporate energy management algorithms into the microcontroller software to optimize energy usage, storage, and distribution within the VAWT system. This includes prioritizing energy consumption based on demand, charging and discharging strategies for energy storage systems, and grid interaction protocols for excess energy export or import.

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